

**Math 31AH: Fall 2021**  
**Midterm Solutions**  
**Wednesday, 10/27/2021**

**Instructions:** This is a 50 minute closed notes, closed books exam. Consultation with other humans is prohibited, including humans acting via websites such as Chegg. You need to clearly prove your claims; unsupported claims will get little credit. Please upload your exam to Gradescope after you are finished. You will have 10 additional minutes to upload your solutions to Gradescope.

**Problem 1:** [20] Let  $\mathbb{F}$  be a field. Endow  $\mathbb{F}^2$  with binary operations

$$(a, b) + (a', b') := (a + a', b + b') \quad (a, b) \cdot (a', b') := (a \cdot a', b \cdot b')$$

Prove that these operations do **not** turn  $\mathbb{F}^2$  into a field.

**Solution:** Suppose  $\mathbb{F}^2$  were a field under these operations. Since  $(0, 0) + (a, b) = (a, b)$  for all  $(a, b) \in \mathbb{F}^2$ , the element  $(0, 0)$  must be the 0 (i.e. additive identity) of  $\mathbb{F}^2$ . However, we have

$$(1, 0) \cdot (0, 1) = (0, 0)$$

so that a product of two nonzero elements of  $\mathbb{F}^2$  is zero. We proved in class that this cannot happen in any field.

**Comments:** This was a problem on the homework. Students did well here in general. Some students showed that elements of the form  $(a, 0)$  do not have multiplicative inverses. There was some slight issue with not specifying that  $a \neq 0$  using this approach.

**Problem 2:** [10+10] Consider the two bases of  $\mathbb{R}^2$  given by  $\mathcal{B} = \{\mathbf{e}_1, \mathbf{e}_2\}$ ,  $\mathcal{C} = \{\mathbf{v}_1, \mathbf{v}_2\}$  where

$$\mathbf{e}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \mathbf{e}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad \mathbf{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \mathbf{v}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be reflection across the line  $y = x$  and let  $A, B \in \text{Mat}_{2 \times 2}(\mathbb{R})$  be the matrices

$$A := [T]_{\mathcal{B}}^{\mathcal{B}} \quad B := [T]_{\mathcal{C}}^{\mathcal{C}}$$

(1) Calculate  $A$ .

(2) Find an invertible matrix  $P$  such that  $B = PAP^{-1}$ .

**Solution:** (1) We calculate

$$T(\mathbf{e}_1) = T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \mathbf{e}_2$$

and

$$T(\mathbf{e}_2) = T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \mathbf{e}_1$$

and conclude

$$A = [T]_{\mathcal{B}}^{\mathcal{B}} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

(2) Let  $i : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the identity map. We have

$$B = [T]_{\mathcal{C}}^{\mathcal{C}} = [i \circ T \circ i]_{\mathcal{C}}^{\mathcal{C}} = [i]_{\mathcal{C}}^{\mathcal{B}} [T]_{\mathcal{B}}^{\mathcal{B}} [i]_{\mathcal{B}}^{\mathcal{C}} = PAP^{-1}$$

where  $P = [i]_{\mathcal{C}}^{\mathcal{B}}$ . Since

$$\mathbf{e}_1 = \frac{1}{2}\mathbf{v}_1 + \frac{1}{2}\mathbf{v}_2 \quad \text{and} \quad \mathbf{e}_2 = \frac{1}{2}\mathbf{v}_1 - \frac{1}{2}\mathbf{v}_2$$

we have

$$P = [i]_{\mathcal{C}}^{\mathcal{B}} = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{pmatrix}$$

**Comments:** This was an example from class. Students also did well here overall. Points lost tended to come from not having enough detail. There was some confusion here regarding  $P$  vs.  $P^{-1}$ . In this particular case,  $PAP^{-1} = P^{-1}AP$ , but this is **not always true** in general. So, some people ‘got lucky’.

**Problem 3:** [15] For a positive integer  $n$ , let  $V_n$  be the  $\mathbb{R}$ -vector space of polynomials  $f(t)$  of degree  $\leq n$  in the variable  $t$  with real coefficients. What is the dimension of the  $\mathbb{R}$ -vector space  $\text{Hom}(V_5, V_3) = \{T : V_5 \rightarrow V_3 : T \text{ is a linear transformation}\}$ ?

**Solution:** The vector space  $V_n$  has basis  $\{1, t, t^2, \dots, t^n\}$  and so  $\dim V_n = n + 1$ . Furthermore, we proved in class that  $\text{Hom}(V, W) \cong \text{Mat}_{r \times s}(\mathbb{R})$  whenever  $V$  and  $W$  are  $\mathbb{R}$ -vector spaces of dimensions  $\dim V = s$  and  $\dim W = r$  which implies  $\dim \text{Hom}(V, W) = \dim V \cdot \dim W$ . We conclude that

$$\dim \text{Hom}(V_5, V_3) = \dim V_5 \cdot \dim V_3 = 6 \cdot 4 = 24.$$

**Comments:** There was a fair amount of confusion about how to calculate  $\dim \text{Hom}(V, W)$  for finite-dimensional vector spaces  $V$  and  $W$ . Some students felt that it was  $\dim V$  or  $\dim W$ . Be sure you understand why it is neither of these. There were also some points lost for thinking that  $\dim V_n = n$  rather than  $n + 1$ .

**Problem 4:** [25] If  $T : V \rightarrow V$  is a linear transformation, a subspace  $W \subseteq V$  is *T-invariant* if  $T(\mathbf{w}) \in W$  for all  $\mathbf{w} \in W$ . If  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  is given by

$$T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x + y + z \\ 2x + 2y + 2z \\ -x - y - z \end{pmatrix}$$

find **all**  $T$ -invariant subspaces  $W \subseteq \mathbb{R}^3$ .

**Solution:** The linear transformation  $T$  has image

$$\text{Image}(T) = \left\{ \begin{pmatrix} x + y + z \\ 2x + 2y + 2z \\ -x - y - z \end{pmatrix} : x, y, z \in \mathbb{R} \right\} = \text{span} \left\{ \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} \right\}$$

which is a line in  $\mathbb{R}^3$  through the origin. Any subspace  $W \subseteq \mathbb{R}^3$  containing this line will be  $T$ -invariant. This includes

- $W = \text{Image}(T)$ ,
- $W =$  any plane containing the line  $\text{Image}(T)$ , and
- $W = \mathbb{R}^3$ .

Furthermore, any subspace of  $\text{Ker}(T)$  is  $W$ -invariant. We calculate

$$\text{Ker}(T) = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x + y + z = 0 \right\}$$

Any other subspace  $W$  is *not*  $T$ -invariant. Indeed, given such a  $W$  choose  $\mathbf{w} \in W$  such that  $T(\mathbf{w}) \neq \mathbf{0}$ . Since  $W$  does not contain  $\text{Image}(T)$  and  $\text{Image}(T)$  is 1-dimensional, we have  $T(\mathbf{w}) \notin W$ .

**Comments:** This was the most difficult problem on the exam and people struggled in general. The main idea is to realize that  $T$  is sending all of  $\mathbb{R}^3$  to a certain line  $L$ . Quite a few people got a bit lost in formulas, matrices, row reduction, etc. I deducted a couple points for students who forgot about the ‘silly’ invariant spaces  $0$  and  $\mathbb{R}^3$ .

**Problem 5:** [20] Give an example of a vector space  $V$  and a linear map  $T : V \rightarrow V$  which is injective but not surjective.

**Solution:** Let  $V$  be the vector space of all polynomials  $f(t)$  in the variable  $t$  with real coefficients. Define  $T : V \rightarrow V$  by  $T(f(t)) = t \cdot f(t)$ . Then  $T$  is linear.  $T$  is not surjective since  $1 \notin \text{Image}(T)$ . However,  $T$  is injective since  $t \cdot f(t) = t \cdot g(t)$  implies  $f(t) = g(t)$ .

**Comments:** The main issues here were caused by students who assumed that we were working with  $\mathbb{F}^n$ . Indeed, there is no such example when  $V$  is finite-dimensional. So, saying things about pivot 1’s in RREF isn’t relevant here. The hope was that you would recall the infinite-dimensional examples we have been working with. (In fact, we can find such a  $T$  whenever  $V$  is an infinite-dimensional vector space.)