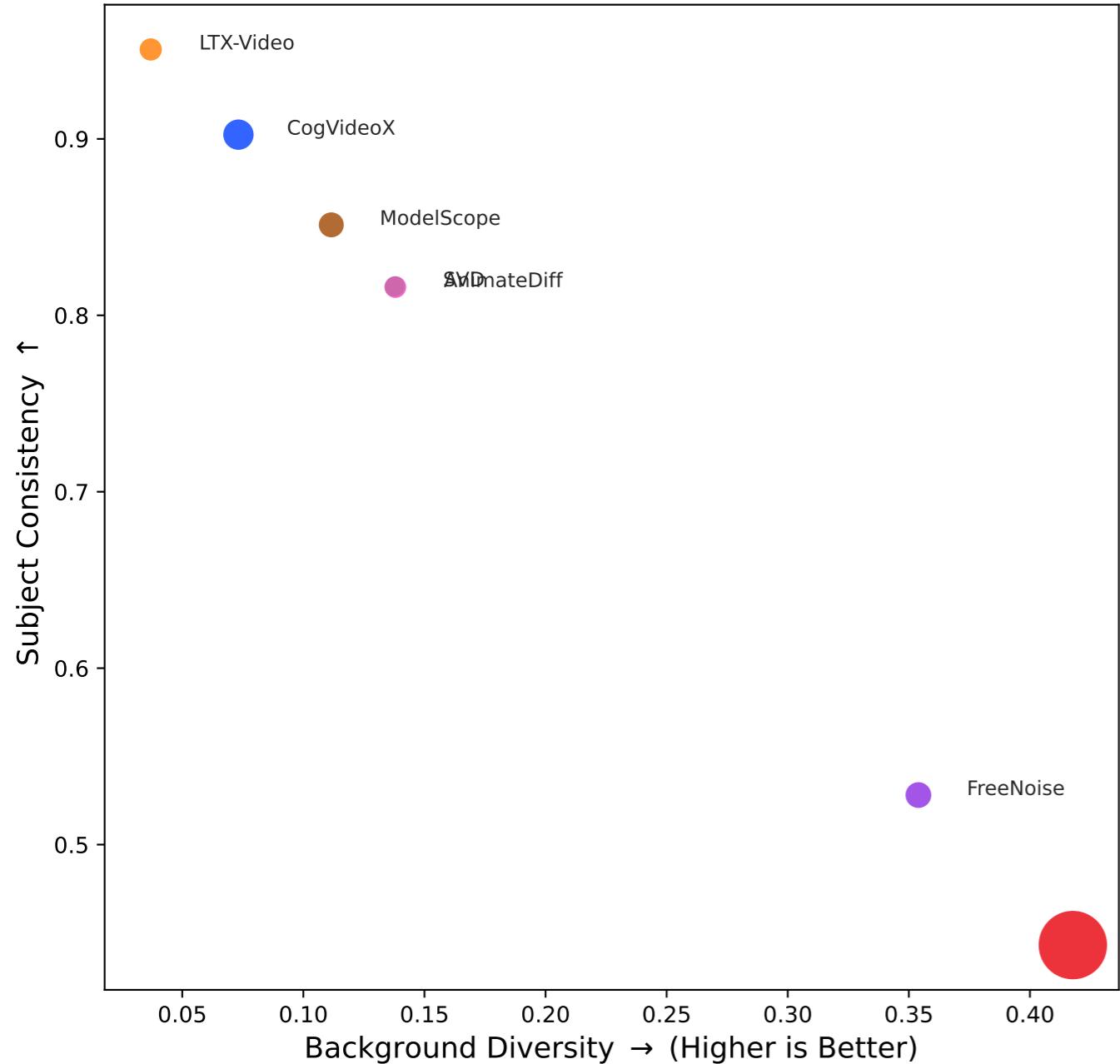


### Track S: Semantic Leap (Dynamics Goal)



### Track M: Motion Continuity (Stability Goal)

