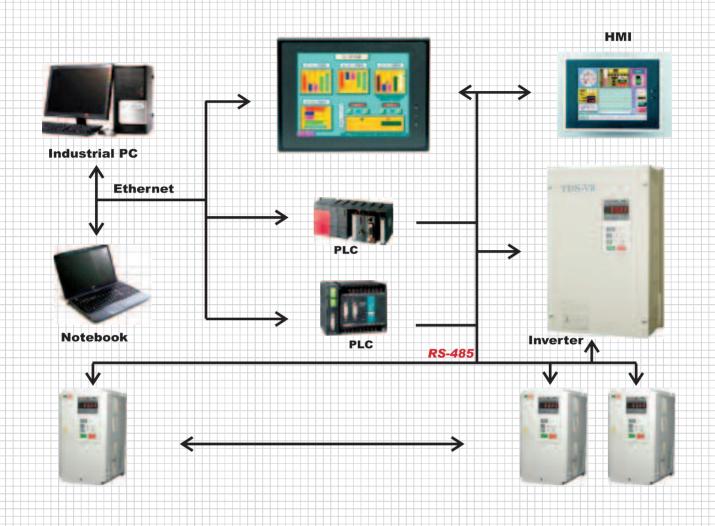
# AC MOTOR DIVE

## Modbus RS-485 can control at most 31 inverters at the same time.





**Powerful** 

TDS-F8 **Easy for Operation** Single-Phase **AC 220 V Cost Efficency** 3-Phase **AC 220 V** Capacity(KW) 0.4 0.75

**Peripherals: Extension cable wire LED** operator LCD operator (TDS-V8 only) **Brake unit EMC** compliant filter **Ferrite ring** 

### Inverter model number

# TDS-V8-L OP7 E

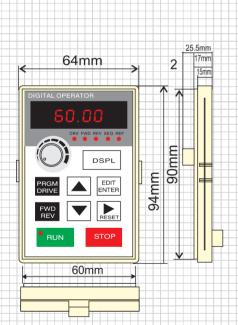
TDS-V8
TekDrive Inverter series

Rated Voltage L:220V, 60Hz(200V, 50Hz) H:440V, 60Hz(400V, 50Hz)

Max. Applicable Motor Output(KW)

Operator Types C:LCD operator E:LED operator F:LED with VR

F:



Standard for 3.7KW & below

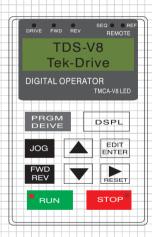
73mm
2mm
2mm
65mm

DIGITAL OPERATOR
TMCA-V8 LED
TENTER
TWD
REV
RESET
RUN
STOP

68mm

Standard for 5.5KW & above

C:



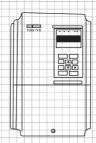
Optional LCD
The same size as
LED Operator

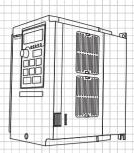
# TDS Series

Series	Model	Capacity	Feature
F8	Economical	1Ø 220V: 0.4~1.5kW 3Ø 220V: 0.4~1.5kW	
V8	Standard	3Ø 220V: 0.75~75kW 3Ø 440V: 0.75~160kW	

# TDS-V8 Series (Sensorless Vector Control)







## **Feature**

- Sensorless Vector control with auto tuning system.
  - -The Autotune feature can be used to identify and store the important motor parameters for the sensorless Vector Control Mode.
- Standard LED operator.
  - -Dialogic LCD operator (English/Chinese) with the function of parameters copying is optional.
- Communication function: RS-485 installed (MODBUS protocol).
- Frequency control ranges from 0.1 Hz to 400Hz with resolution of 0.01Hz.
  - -frequency setting signal DC:0~10V / 4~20mA
- ♦ Two set of analogical output interface. Each provides 11 individual analogical signals setting.
- PID Control, Simple PLC function, Energy saving, Multiple Frequency Pulse Output.
- Auto torque boost, slip compensation.

### **Control Characteristics**

Operation Mode	LED operator or LCD operator	
Control Mode	Sine PWM	
Frequency Control Ranges	0.1Hz~400Hz	-
Frequency Accuracy	Digital Command:±0.01%(-10~+40°C), Analog Command:±0.1% (25°C~±10°C)	
Frequency Command Resolution	Digital Command:0.01Hz, Analog Command:0.06Hz/60Hz	
Frequency Output Resolution	0.01Hz	
Overload Resistibility	150% Rated Current for 1 Minute (CT)	
Frequency Setting Signal	DC 0~10V/4 ~ 20mA	
Acc./Dec. Time	0.1~6000.0 Sec. (Accel/Decel Time Con be Set Independent)	
Voltage-Frequency Characteristics	V/F Curve Can be Set Through Parameter Setting (15 Types Fixed, 1 Type Flexible)	
Regeneration Torque	100%, 2%ED, 5 Seconds	
Basic Control Function	Auto torque Boost, Slip Compensation, Restart After Momentary Power Loss, Energy Saving,	
	PID Control, Simple PLC function, Sersorless Vector Control	
	Up/Down Operation, Cumulative Power on & Operation Hour Memory, 4 Different Sets of Fault	
Extra Function	Status Record(Including Latest one), RS-485 (MODBUS Protocol), Multiple-Pulse Output Port,	
	2 Analog Output Ports etc.	

### Protection Function

	Stall Prevention	Current Level Can be Selected During Acceleration and Constant Speed Running.  During Deceleration, Stall Prevention Can be Enabled or Disabled.	
F	Instantaneous overcurrent (OC)	Stopped if above 200% Rated Current	-
	Inverter Overload Protection (OL2)	Stopped if above 150% Rated Current for 1 Minute	
	Motor OverloadProtection (OL1)	Electronic Overload Curve Protection	
F	Overvoltage (OV)	Stop if VDC ≥ 410V(220 Class) or VDC ≥ 820V (440 Class)	-
	Undervoltage (UV)	Stop if VDC ≤ 200V(220 Class) or VDC ≤ 400V (440 Class)	
	Momentary Power	≥ 15ms, stop otherwise	
	Loss Ride-Though time		
	Overheat Protection (OH)	Protection by Thermistor	
	Grounding Protection (GF)	Protection by DC Current Sensor	

# TDS-V8 Specification

Self

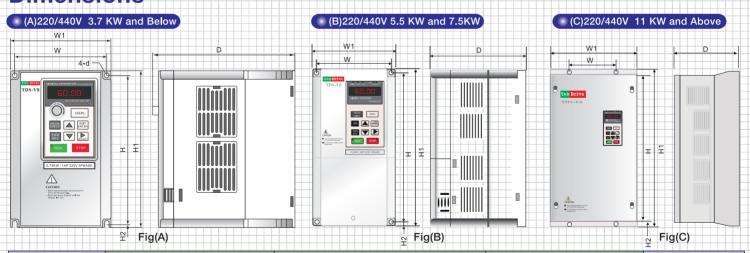
2.2

-		<del></del>			$\rightarrow$																	+
	Ir	put Voltage class								220'	VCla	ass 3	-Phas	se								F
		Model	0P7	1P:	5 2F	2	3P7	5P5	7P5	0	11	015	018	02	2 (	030	037	04	5 0	55	075	E
Max Applicable Motor HP		1	2	3	}	5	7.5	10	1	15	20	25	30	)	40	50	60	) 7	5	100	E	
(CT)* kw			0.75	1.5	5 2.	2	3.7	5.5	7.5	1	11	15	18.5	22	2	30	37	45	5 5	5	75	E
	ver	Rated Output Capacity (kVA)	2	2.7	7 4	ŀ	7.5	10.1	13.7	20	0.6	27.4	34	41		54	68	78	3 9	5	128	F
H	Output Power	Rated Output Current (A)*	4.8	6.4			17.5	24	32		18	64	80	96	} '	130	160	18	3 2	24	300	F
$\blacksquare$	thatr	Max. Output Voltage (V)	3-Ph	ase	200V	/~23	30VA	C(Pro	oport	ona	ıl to	input	volta	ge)								Ε
	ō	Max. Output Frequency(Hz)	Thro	ugh	para	met	er se	tting	(Max	. 40	0Hz	.)										E
	acun	Rated Voltage Frequency	3-Ph	ase	200\	/~23	30V, :	50/60	Hz													F
H	Power Source	Allowable Voltage Fluctuation	-15%		0%																	F
H	Po	Allowable Frequency Fluctuation																				E
		Medchanical Construction	Encl	osec	I, Wa	II-M	ount	ed Ty	pe(N	EΜ	A-1)	IP20						I	P00			E
Cooling				Self Forced																		
H	App	rox mass(kg)	2	.2		2.8	3	ţ	5.5		13	.1		24.	5		4	47	6	9	73	Ė
H	100	vout Voltage alege								4.40	\	\	2 Dk						1111			t
$\blacksquare$	П	put Voltage class		4					0.1.1	440			3-Ph					000	440	400	400	-
		Model	0P7	1P5		3P7	5P5	7P5	•	015	018	022		037	045	055	075	090	110	132		-
		x Applicable Motor HP	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100	125	150	175		-
Ħ	(C		0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90	110	132		
H	Output Power	Rated Output Capacity (kVA)	2.1	2.7	4	7.5	10.1			27.4	34	41	54	68	82	110	138	180	195	210		Ξ
	Jt Po	Rated Output Current (A)*	2.6	4.0	4.8	8	12	16	24	32	40	48	64	80	96	128	165	192	224	270	300	-
	of the	Max. Output Voltage (V)						•	•			•	volta	ige)								-
		Max. Output Frequency(Hz)						etting	•	. 40	0Hz	:)										-
H	Power Source	Rated Voltage Frequency	3-Pr			/~4t	5UV,	50/60	)HZ													
	Wer S	Allowable Voltage Fluctuation																				
H	2	Allowable Frequency Fluctuation							/>	_, .	A 41	IDCC							00			-
Medchanical Construction Enclosed, Wall-Mounted Type(N									/pe(N	(NEMA-1) IP20 IP00								-				

# **Dimensions**

Cooling

Approx mass(kg)



Forced

24.5

69

Voltage	Application Motor	Mounting Dimension (mm)			Extern	nal Dime (mm)	Fig			
-	Output(HP) / KW	W	H1	H2	d	W1	H1	D		
	1HP / 0.75KW 2HP / 1.5KW	108	173	5.5	5	118	184	168	Fig(A)	
	3HP / 2.2KW 5HP / 3.7KW	124	214	5.5	6	137.5	225	161	i ig(A)	
220V/ 440V	7.5HP / 5.5KW 10HP / 7.5KW	174	281	8	8	191	297	197	Fig(B)	
4400	15HP / 11KW 20HP / 15KW	140	394	8	8	244	410	202		
	25HP / 18.5KW 30HP / 22KW 40HP / 30KW	170	479	12.5	10	287	504	273		
440V	50HP / 37KW 60HP / 45KW									
220V	50HP / 37KW 60HP / 45KW	-							Fig(C)	
440V	75HP / 37KW 100HP / 75KW 125HP / 90KW	250	709	12.5	12	376	734	280		
220V	75HP / 55KW 100HP / 75KW						·			
440V	100HP / 110KW 175HP / 132KW 215HP / 160KW	430	843	13	15	533	870	280		

<sup>\*</sup>Tek-Drive reserves the rights of changing the spec. For bigger capacity, please contact with Tek-Drive

# Description of Inverter model number

# **TDS-F8-L 0P7 E3**

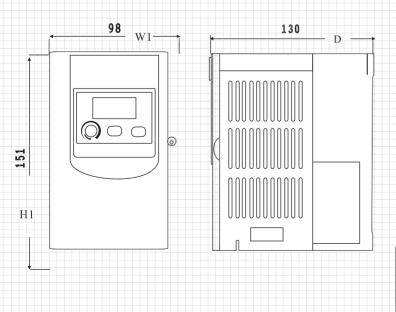
TDS-F8
TekDrive Inverter series

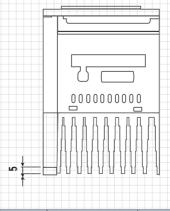
Inverter Output Capacity (KW) 0P4: 0.4 KW 0P7: 0.75 KW 1P5: 1.5 KW blank: single phase 3:3 phase

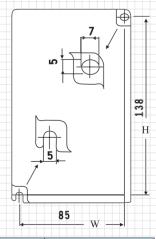


	nput Voltage class	220V Single phase / 3-Phase						
_	NA - del	TDS-F8-L						
	Model	0P4 0P7	1P5					
Max	Applicable Motor HP	1/2 1	2					
(CT	)* kw	0.4 0.75	1.5					
ي پ	Rated Output Capacity (kVA)	1.4 2	2.7					
Output	Rated Output Current (A)*	3.2 4.8	6.4					
D C	Max. Output Voltage (V)	3-Phase 200V~230VAC(Proportional to input voltage)						
	Max. Output Frequency(nz)	Through parameter setting (Max. 400Hz)						
er.	Rated Voltage Frequency	Single Phase 200V~230V, 50	)/60Hz					
Power	Allowable Voltage Fluctuation	-15%~+10%						
<u> </u>	•	±5%						
	Medchanical Construction	Enclosed, Wall-Mounted Type(NEMA-1) IP20						
	Cooling	Self	Forced					
	Weight(kg)	1.2						
	Operation Mode	LED operator						
	Control Mode	Sine PW/M						
<u>SS</u>	Frequency Control Ranges	0.1 Hz~400 Hz						
rist	Frequency Accuracy	Digital Command:±0.01%(-10~+40°C), Analog Command:±1% (25°C~±10°C)						
cte	Frequency Command Resolution	Digital Command:0.01Hz, Analog Command:0.06Hz/60Hz						
ğ	Frequency Output Resolution	0.1Hz						
2	Frequency Setting Signal	DC 0~10V/4 ~ 20mA						
	Acc./Dec. Time	0~999.9 Sec. (Accel/Decel Time Can be Set Individually)						
差			V/F Curve Can be Set Through Paramenter Setting					
Control Characteristics	Basic Control Function	Auto torque Boost, Slip Compensation, Restart After Momentary Power Loss, Energy Sav						
	Entre Engelier	Up/Down Operation, Cumulative Power on & Operation Hour Memory, 4 Different Sets of	Fault Status Record					
	Extra Funation	(Including Latest one), RS-485 (MODBUS Protocol), Multiple-Pulse Output Ports, 1 Analog Output.						

# **Dimension**







	\/altaga	Applicable Motor		unting	(mm)	External(mm)			
	Voltage	Output (HP/KW)	W	Н	D	W1	H1	D	
220V 1ø/3ø	0.5HP/0.4KW		138	130	98	151	130		
	1HP/0.75KW	85							
	2HP/1.5KW								

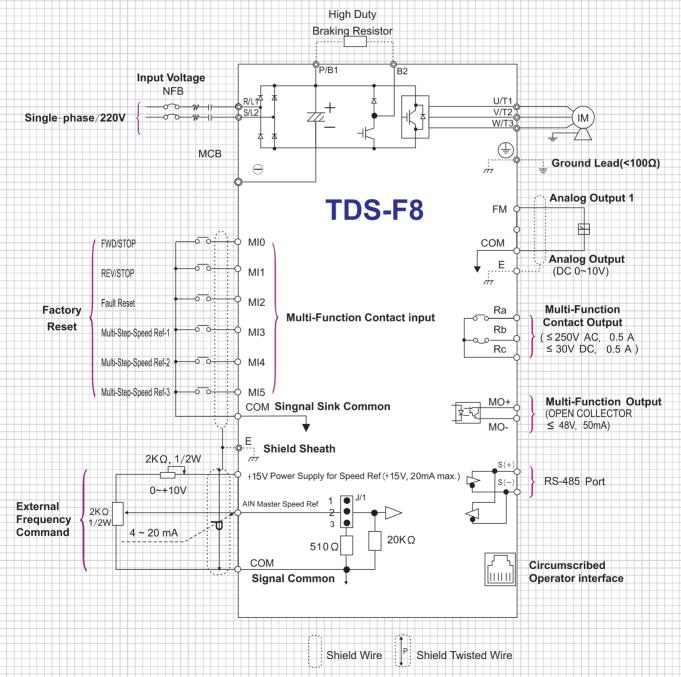
# **TDS-F8 Series**

**Feature** 

# **Wide Applications High Performance**

- PWM control
- Built-in MODBUS RS-485
- Built-in PID Function
- 3 skip-Frequency setting
- 2 ACC/DEC Time S curve setting
- Simple PLC function remote control
- Pump control automatic energy saving
- Pressure setting & constant pressure control.

# **Basic Connection Diagram**



Inverter Standard Connection Diagram ( indicates the main circuit terminals and the sign, Indicates control circuit terminals)

# TDS-V8 Inverter Standard Connection Diagram

(⊚ indicates the main circuit terminals and the sign, ○ indicates control circuit terminals) ∘

