



**HOCHSCHULE
MITTWEIDA**
University of Applied Sciences

EINN: Epidemic Prediction using ML

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Agenda

- ① What is EINN?
- ② Background
- ③ EINN Model
- ④ Results

What is EINN?

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Introduction

- EINN is a (**Neural Network**) machine learning model to predict epidemic dynamics [1]
- Mechanistic models (ODE models e.g SIR/SEIRM) good at trend approximation [1]
- RNN powered epidemic models good at short and long term epidemic prediction [1]
- EINN combines the knowledge of PINN, RNN, and ODE [1]

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Background

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Mechanistic epidemic models

- Uses ODE to predict
- Have many models: SIR, SEIR, SEIRM etc.
- Susceptible (S): $\frac{dS_t}{dt} = -\beta_t \frac{S_t I_t}{N}$
- Exposed (E): $\frac{dE_t}{dt} = \beta_t \frac{S_t I_t}{N} - \alpha_t E_t$
- Infected (I): $\frac{dI_t}{dt} = \alpha_t E_t - \gamma_t I_t - \mu_t I_t$
- Recovered (R): $\frac{dR_t}{dt} = \gamma_t I_t$
- Mortality (M): $\frac{dM_t}{dt} = \mu_t I_t$

Note: $\Omega_t = \{\alpha_t, \beta_t, \gamma_t, \mu_t\}$ are parameters, N is the population number, and t is time.

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RNN

- RNN is a neural network model
- Uses the previous state as an input to predict the next state
- Used in object detection and NLP

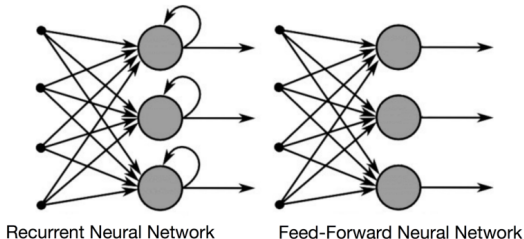


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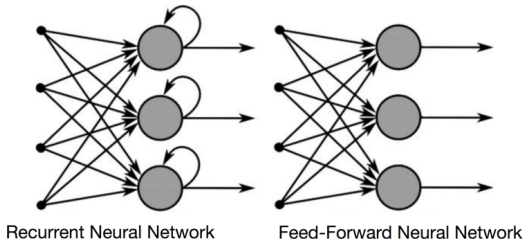


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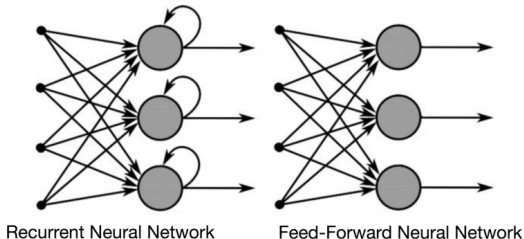


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Background

PINN

- Uses physics laws to predict the next state
- Uses PDE (partial differential equation) and ODE (ordinary differential equation) as a loss estimator
- L_{data} : loss from data fitting
- L_{physics} : loss from physics laws

$$\text{e.g. } \vec{a} = -\mu \|\vec{v}\| \vec{v} - \vec{g}, \vec{v} = \frac{df}{dt}, \vec{a} = \frac{d^2f}{dt^2}$$

$$L_{\text{physics}} = \frac{1}{N} \sum_{i=0}^{N-1} \left(-\mu \left\| \frac{df_i}{dt_i} \right\| \frac{df_i}{dt_i} - \vec{g} - \left(\frac{d^2f_i}{dt_i^2} \right) \right)^2$$

- $L_{\text{total}} = L_{\text{data}} + L_{\text{physics}}$

Note: \vec{a} is acceleration, \vec{v} is velocity, \vec{g} is gravity, μ is friction, f is position, t is time, and N is the number of data points.

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PINN for Systems Biology

- Recent works with PINN for Systems Biology [3, 4]: better PINN for SIR mechanics
- Uses time t as input for Neural Network $N(t)$ and rate of change in ODE systems $f_{\text{ODE}}(t)$
- Uses $(\frac{dN(t)}{dt} - f_{\text{ODE}}(t))$ as a loss

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EINN Model

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Model summary

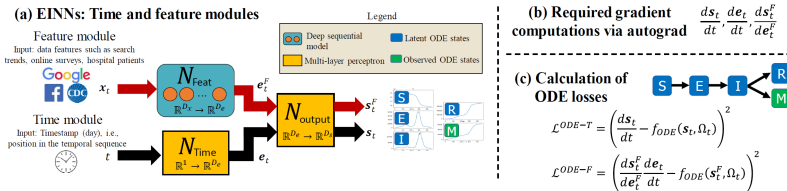


Figure: EINN Model. (a) The training model. (b) Needed gradients to train the model using autograd. (c) ODE losses of feature module and time module. Taken from: [1]

EINN Model

Source model (Time module)

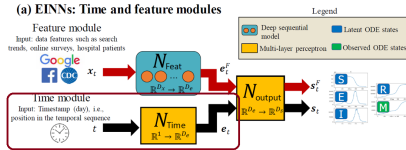


Figure: Cropped model summary showing the training summary. Cropped from: [1]

- Source model is a PINN for Systems Biology
- Input: time
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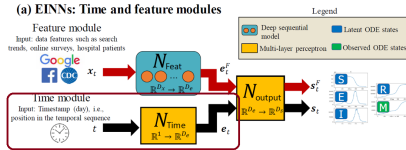


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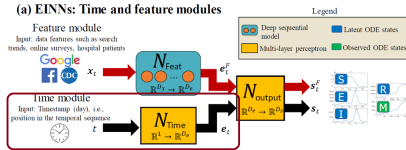


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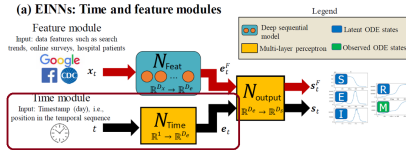


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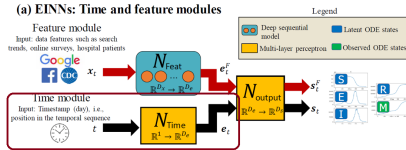


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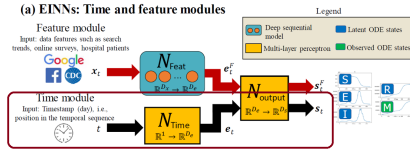


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- ODE loss for time module ($L^{\text{ODE-T}}$) [1]:

$$\frac{1}{N+1} \sum_{t=t_0}^{t_N} \left[\frac{ds_t}{dt} - f_{\text{ODE}}(s_t, \Omega_t) \right]^2$$

s_t : predicted ODE states at time t using time module path

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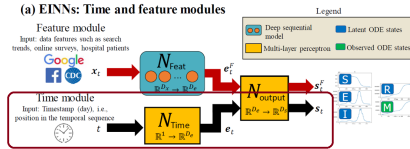


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- In the ODE states, Mortality (M) is observed and other states are latent [5]

- $L^{\text{Data-T}} [1]: \frac{1}{N+1} \sum_{t=t_0}^{t_N} [\hat{M}_t - M_t]^2$
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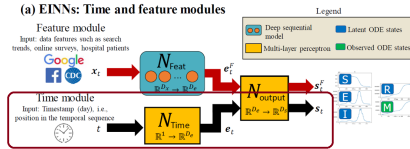


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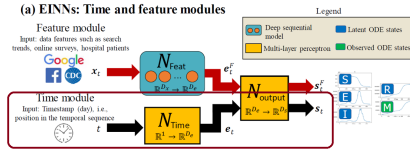


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- Adding monotonicity loss (loss from latent states) to make learning less challenging using domain knowledge [1, 6]
- S is monotonically decreasing and R is monotonically increasing [1]
- $$\mathcal{L}^{\text{Mono}} = \frac{1}{N+1} \left(\sum_{t=t_0}^{t_N} \frac{dS_t}{dt} \text{ReLU}\left(\frac{dS_t}{dt}\right) + \sum_{t=t_0}^{t_N} -1 \frac{dR_t}{dt} \text{ReLU}\left(-\frac{dR_t}{dt}\right) \right)$$

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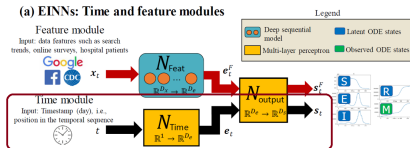
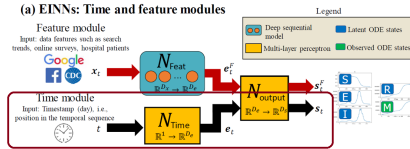


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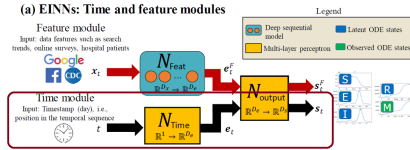


- Adding parameter to loss to track parameter change with time
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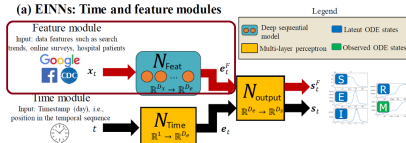


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- Input (x_t): Features relevant to the problem
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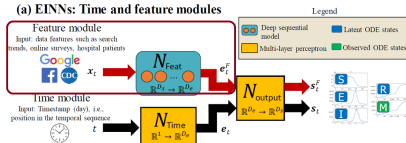


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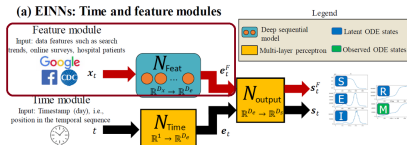


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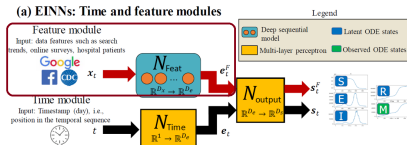


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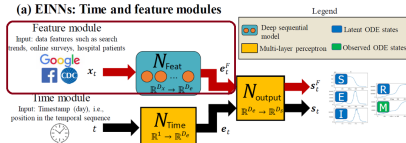


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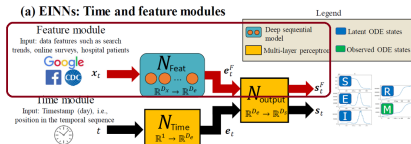


Figure: Cropped model summary showing the training summary. Cropped from: [1]

- $e_t \approx e_t^F$ required for gradient trick for ODE loss from feature module

- $e_t \approx e_t^F \Rightarrow \frac{ds_t^F}{dt} = \frac{ds_t^F}{de_t^F} \frac{de_t^F}{dt} \approx \frac{ds_t^F}{de_t^F} \frac{de_t}{dt}$

- Loss ODE from feature module (L^{ODE-F}) [1]:

$$\frac{1}{N+1} \sum_{t=t_0}^{t_N} \left[\frac{ds_t^F}{de_t^F} \frac{de_t}{dt} - f_{ODE}(s_t^F, \Omega_t) \right]^2$$

EINN Model

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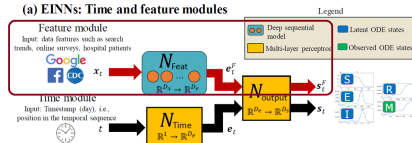


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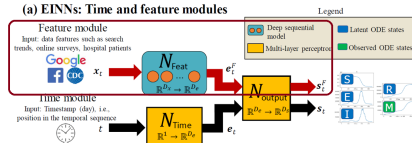


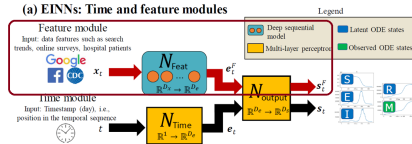
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EINN Model

Target module losses



- \hat{M}_t^F : predicted mortality using feature module path

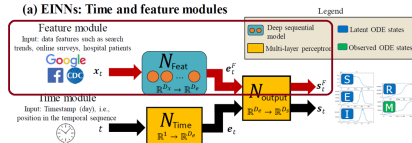
- Loss from data (L^{Data-F}):

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EINN Model

Target module losses



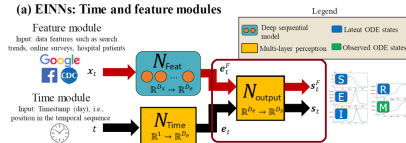
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EINN Model

Target module losses



- N_{output} feed-forward Neural Network

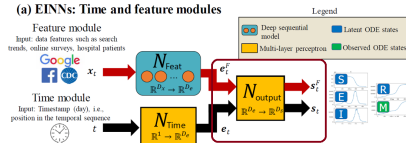
- Aligning findings from both paths

- $$L_{Output} = \frac{1}{N+1} \sum_{t=t_0}^{t_N} [s_t - s_t^F]^2$$

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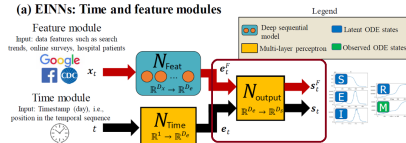


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Results

Results

- Generation: The NN learns directly from ODE generated data [1, 7, 8]
- Regularization: The NN predicts states and parameters of an ODE and learns from the parameters [1, 9, 10]
- Ensembling: Combines predictions of RNN and SEIRM/SIR outputs in one NN for a final prediction [1, 11, 12]
- EINNs-NoGradMatching: skipping $e_t \approx e_t^F$ part [1]

Results

Model	Short-term (1-4 wks)			Long-term (5-8 wks)			Trend correlation
	NR1	NR2	ND	NR1	NR2	ND	PC
Task 1: COVID-19 Forecasting (US National + 47 states)							
RNN (GRU+Atten)	1.09	0.50	0.86	1.19	0.53	0.96	0.08
Mechanistic model (SEIRM)	2.35	1.13	1.36	7.14	2.99	3.11	0.53
GENERATION	0.79	0.35	0.60	0.93	0.40	0.74	-0.01
REGULARIZATION	1.05	0.48	0.81	1.19	0.53	0.97	0.09
ENSEMBLING	0.91	0.41	0.68	0.93	0.40	0.69	-0.01
EINNs (ours)	0.54	0.24	0.38	0.85	0.37	0.66	0.46
PINN (time module standalone)	0.84	0.38	0.64	0.93	0.40	0.72	0.24
EINNs-NoGradMatching	0.64	0.29	0.49	0.98	0.43	0.79	0.03
Task 2: Influenza Forecasting (10 HHS regions)							
RNN (GRU+Atten)	0.72	0.38	0.67	1.19	0.51	1.14	-0.03
Mechanistic model (SIRS)	0.72	0.38	0.51	1.16	0.55	0.81	0.71
GENERATION	0.76	0.4	0.71	1.21	0.52	1.15	-0.14
REGULARIZATION	1.19	0.64	1.00	1.22	0.54	0.9	-0.45
ENSEMBLING	0.89	0.47	0.77	0.83	0.35	0.73	-0.69
EINNs (ours)	0.53	0.27	0.37	1.01	0.42	0.73	0.68
PINN (time module standalone)	0.55	0.29	0.44	1.13	0.48	1.02	-0.47
EINNs-NoGradMatching	0.53	0.27	0.38	1.02	0.42	0.76	0.50

Figure: Short-term, Long-term, and Trend results. NR: Normalized RMSE (Lower is better), ND: Normal Deviation (Lower is better) PC: Pearson Correlation (Higher is better). Image taken from: [1]

Results

- Better short and long term prediction than RNN and Mechanistic model (SEIRM)
- Better trend correlation than RNN and slightly less trend correlation than Mechanistic model
- Not sensitive to parameter change [1]
- only L^{output} effectively contributes to EINN-NoGrad [1]
- Even PINN learns from ODE, they still generate different outputs [1]

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Thank You



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