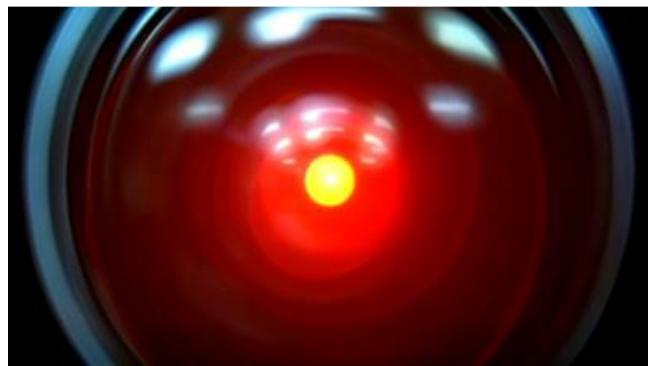


Introduction to Computer Vision

Introduction

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Welcome!



Introductory course for computer vision

- :
 - Enthusiastic undergrads
 - Want to get to know this exciting technology
 - Covers “DL for vision”, in a semi-applied way
- CENG 783: Deep Learning
- CENG 793: Advanced Deep Learning
- CENG 796: Deep Generative Models

Bioloa

Psycholog

Phys ics

Compute r Science

Engineerin g

Mathematic s

Compu ter Vision

Machine
learning

Robotics

Speech,
NLP

Image
processing

optics

Neuroscie
nce

Cognitive
sciences

Algorithms,
theory,...

Systems,
architecture,
...

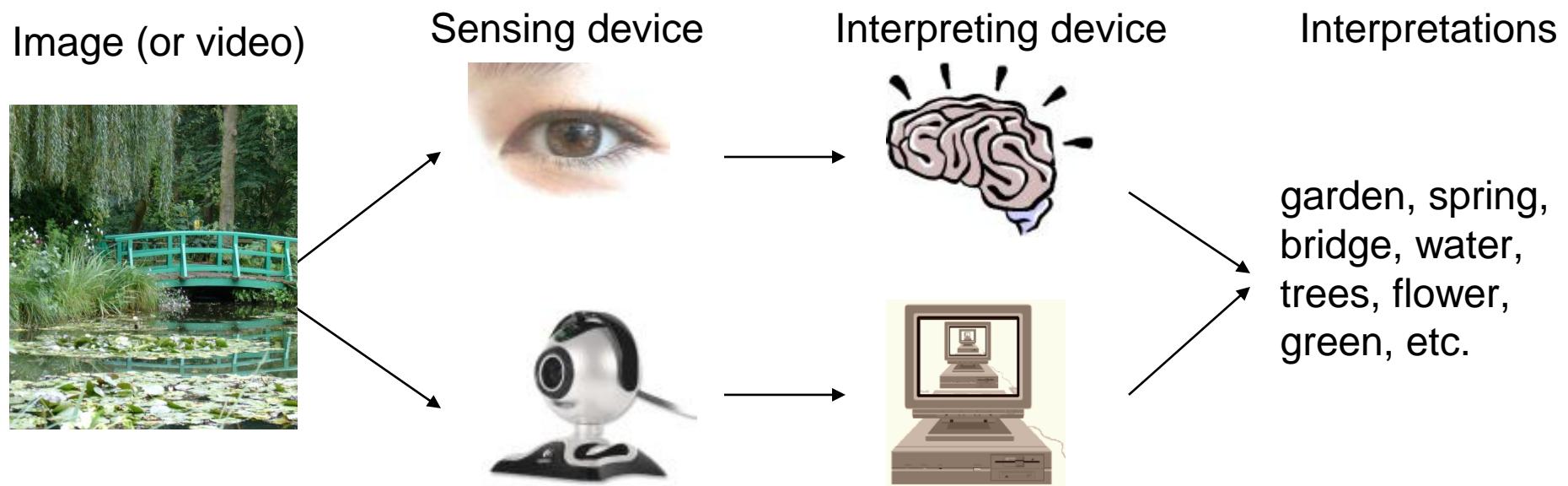
Information
retrieval

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

This week's agenda

- Course overview
- Introduction to computer vision

What is (computer) vision?



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

The goal of computer vision

- To bridge the gap between pixels and “meaning”



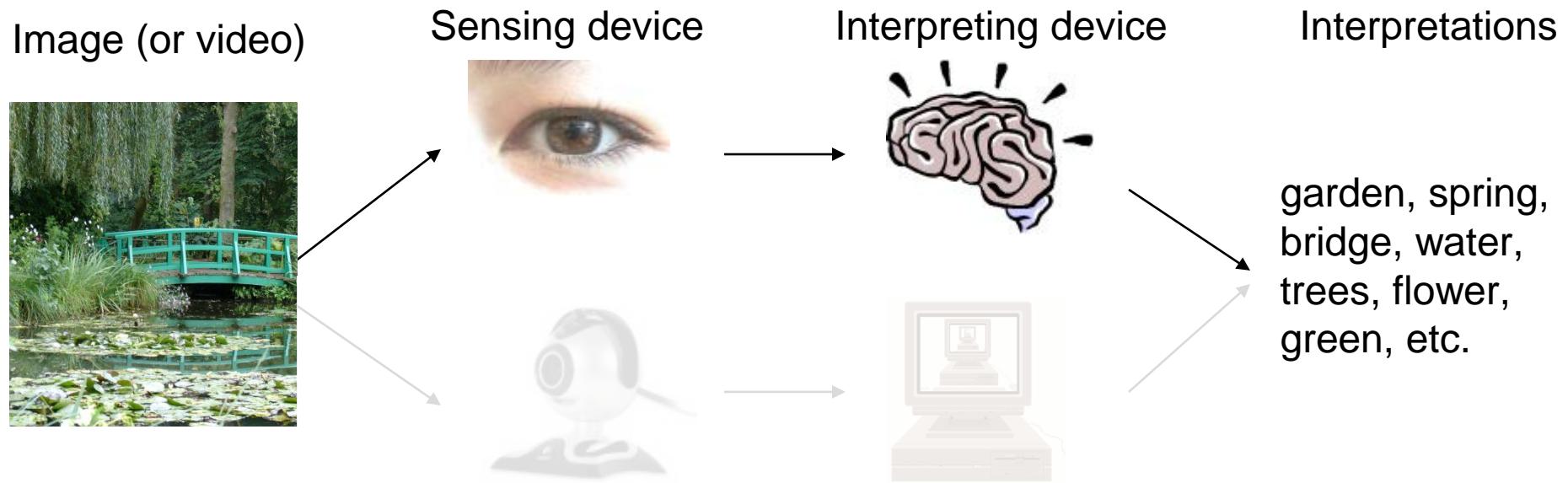
0	3	2	5	4	7	6	9	8
3	0	1	2	3	4	5	6	7
2	1	0	3	2	5	4	7	6
5	2	3	0	1	2	3	4	5
4	3	2	1	0	3	2	5	4
7	4	5	2	3	0	1	2	3
6	5	4	3	2	1	0	3	2
9	6	7	4	5	2	3	0	1
8	7	6	5	4	3	2	1	0

What we see

Adapted from slides by Quoc Le, Daphne Koller, and Ranjay Krishna

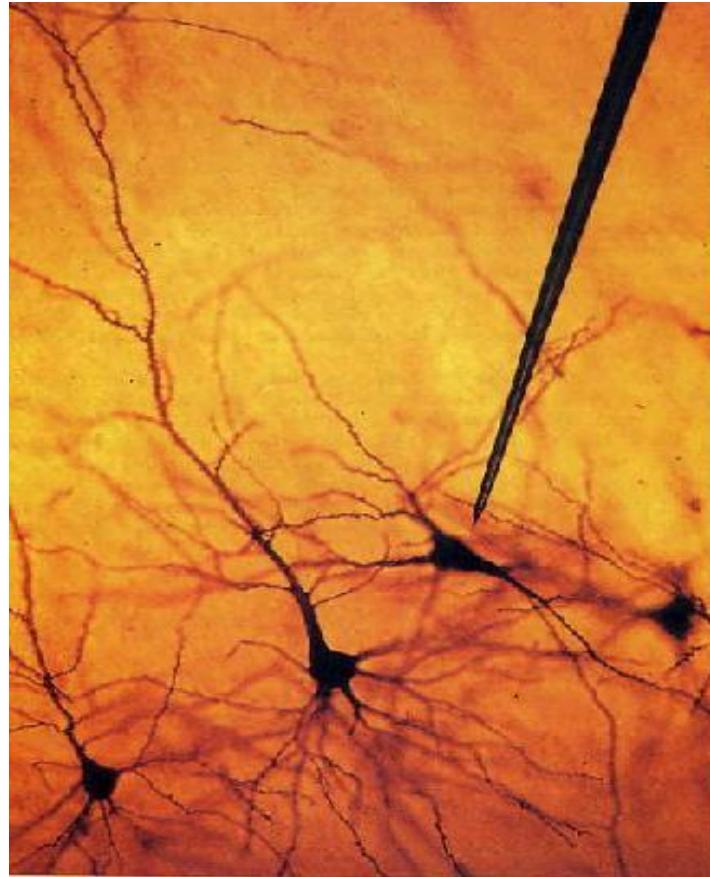
What a computer sees

What is (computer) vision?



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

1981: Nobel Prize in medicine



Hubel & Wiesel

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Human vision is superbly efficient

Can you detect a person?



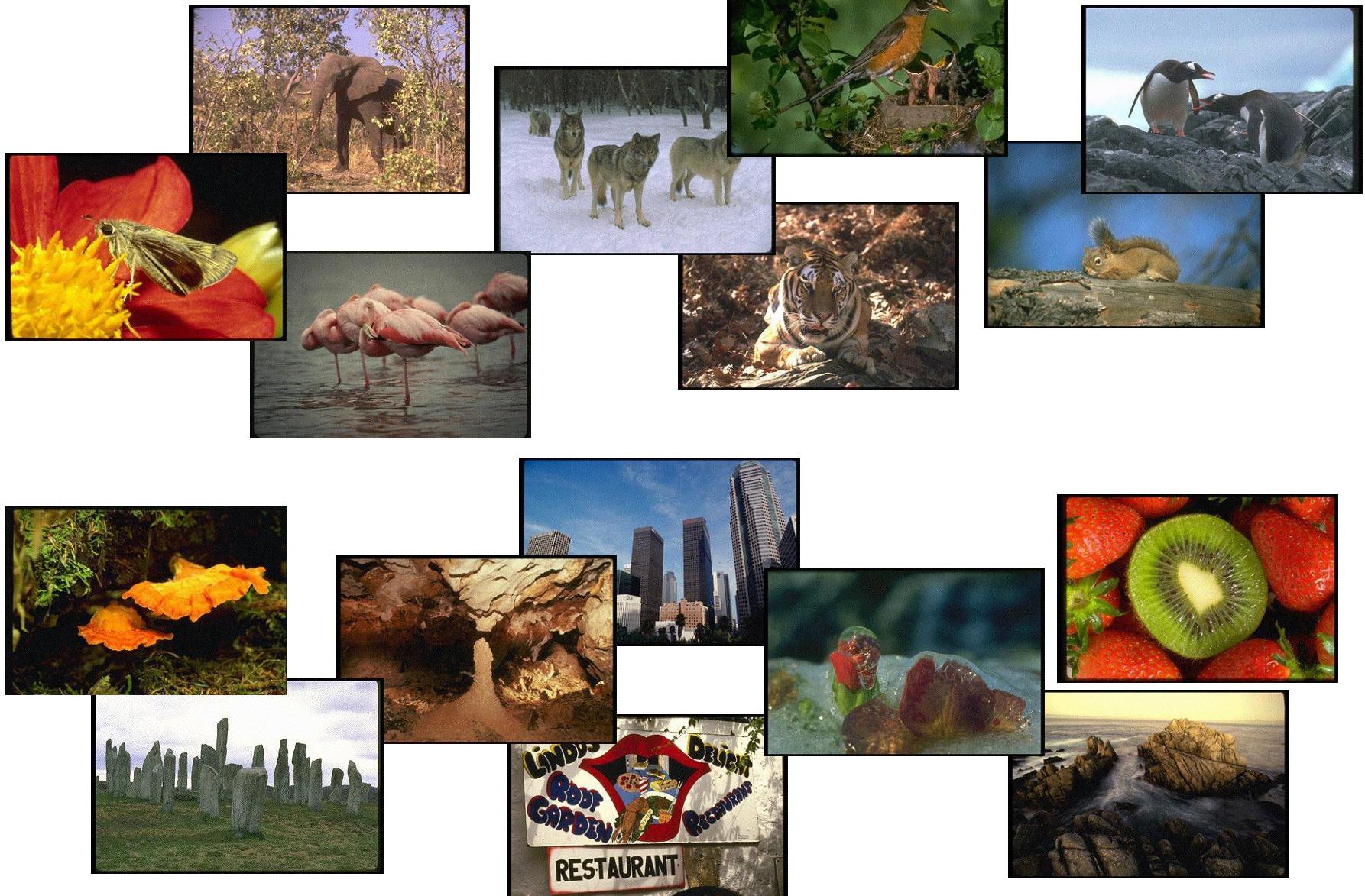
100 ms per frame,

Never seen the picture, do not know the person

Potter, Biederman, etc. 1970s

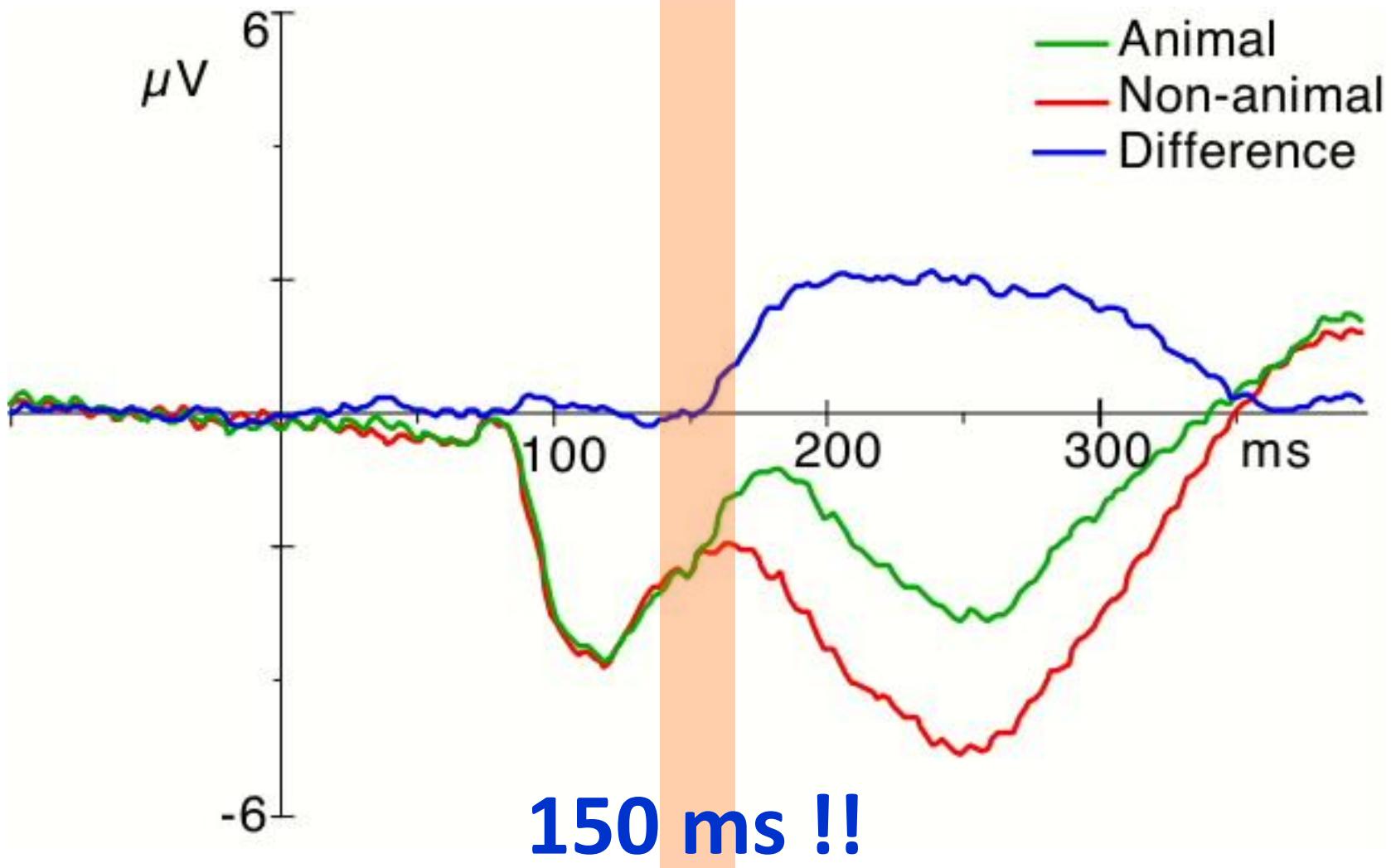
Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Animal vs non-animal



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Thorpe, et al. *Nature*, 1996



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Thorpe, et al. *Nature*, 1996

Change blindness

Raise hand when you spot a difference

Change blindness



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Rensink, O'regan, Simon, etc.

Change blindness



This is why spot-the-difference is a game 😊

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Rensink, O'regan, Simon, etc.

Segmentation



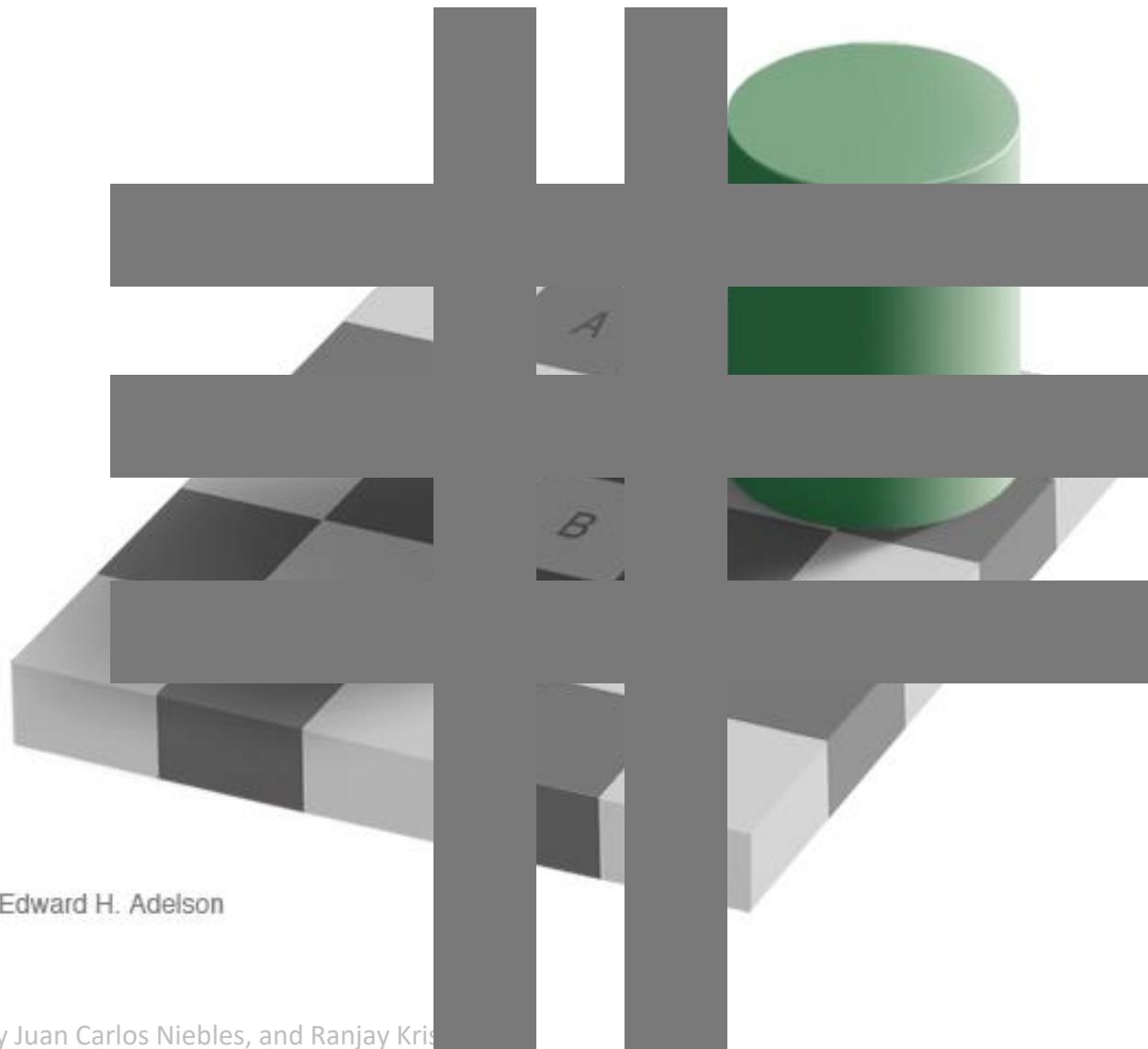
Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Perception

Same face but the one behind looks like Al Gore due to feats of human face perception



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna



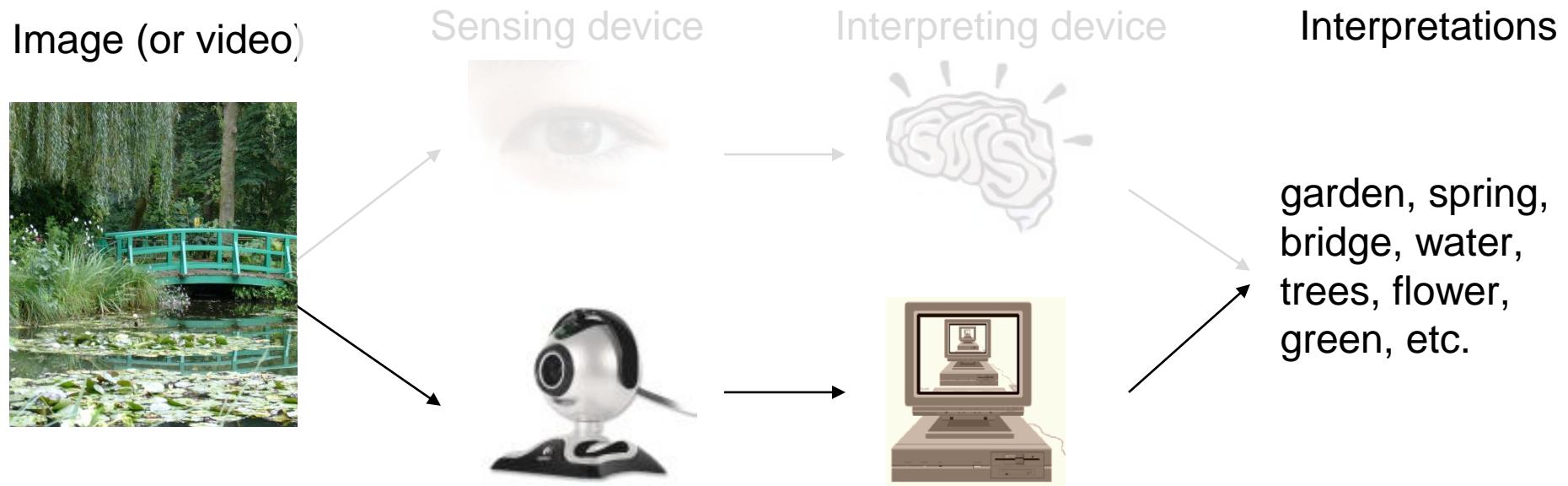
Adapted from slides by Juan Carlos Niebles, and Ranjay Kris

Human vision is GREAT, but its (mostly unknown) approach is not necessarily *the best* on for *computer* vision



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

What is (computer) vision?



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

The goal of computer vision

- To bridge the gap between pixels and “meaning”



La Gare Montparnasse, 1895

0	3	2	5	4	7	6	9	8
3	0	1	2	3	4	5	6	7
2	1	0	3	2	5	4	7	6
5	2	3	0	1	2	3	4	5
4	3	2	1	0	3	2	5	4
7	4	5	2	3	0	1	2	3
6	5	4	3	2	1	0	3	2
9	6	7	4	5	2	3	0	1
8	7	6	5	4	3	2	1	0

What we see

Adapted from slides by Quoc Le, Daphne Koller, and Ranjay Krishna

What a computer sees

Course Logistics

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Contacting instructor and TAs

- Instructor: Gokberk Cinbis
 - Website: <http://user.ceng.metu.edu.tr/~gcinbis>
 - Primary Research Area: Data-efficient ML/DL, primarily on visual data
 - Office hours: please email to get appointment
- Teaching Assistant: İlker İşik

Contacting instructor and TAs

- All announcements, Q&A will be made on ODTUCLASS
 - <https://odtuclass.metu.edu.tr>
- Please post your questions on ODTUCLASS
- Please email us if you encounter problems with forums

Overall philosophy

- Breadth
 - Computer vision is a huge field, now tightly integrated with deep learning research
 - It can impact every aspect of life and society
 - It will drive the next information and AI revolution
 - Pixels are everywhere in our lives and cyber space
 - This is an introductory course, we will not cover all topics of CV
 - Lectures are mixture of details techniques and high level ideas
 - Speak our “language”

Overall philosophy

- Depth
 - Master bread-and-butter techniques: eg. edges, corners, feature extraction, image classification
 - Programming assignments: be a good coder AND a good writer
 - Gather hands-on experience on using & developing basic deep learning approaches

Lecture hours

- Lectures will start at **8:40** on both Tue & Fri.
- We'll effectively have 4 lectures per week (instead of 3), therefore, we skip some lecture days. This will help us to make faster progress in terms of theoretical discussions so that homeworks are not delayed in the semester, also makes it easy to make-up cancelled classes.

Office hours: after class / appointment by email.

Lecture recordings?

Probably not, for your own sake. Your primary resource for the classes are slides + lectures themselves.

Great lectures notes for a related course can be found here:

[https://github.com/StanfordVL/CS131 notes](https://github.com/StanfordVL/CS131_notes)

See syllabus for the textbook recommendations

Zoom?

Again, probably not, for your own sake. Hybrid lectures, in my experience, greatly reduce the in-class discussion quality.

Grading policy

- Homeworks: 55% (Tentatively 3 HWs)
- Midterm: 20%
- Final: 25%

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Homework - late day policy

- Late day policy (important!)
 - Each student has 3 free calendar days to turn in late **in total (throughout the semester)**. Use them wisely.
 - Example: if a student submits hw1 5 hours late, he/she will consume 1 full day, and will have 2 remaining late days.
 - Once late days are exhausted, 100% penalty will be applied to late submissions.

Homework policies

- Homeworks must be turned in on ODTUClass, unless otherwise specified.

Exception: if you encounter an issue when submitting the ODTUClass, please let us know. If deadline is about to pass, email TA your solution immediately! If the file is too large, email link to the dropbox/google drive/etc directory containing your solution. (We must see the solution date.)

Collaboration policy

- Collaboration policy
 - Plagiarism will not be tolerated
 - Self-plagiarism will not be tolerated
 - METU Guidelines:
<http://oidb.metu.edu.tr/en/system/files/Academic%20Integrity%20Guide%20for%20Students.pdf>
 - Ask ahead of time whenever you are in doubt.

Midterm/Final Exams

- Will contain written questions from the concept covered in class or any questions in the homeworks.
- Can require you to solve technical math problems.
- Midterm/Final maybe done in a lab environment.

More details

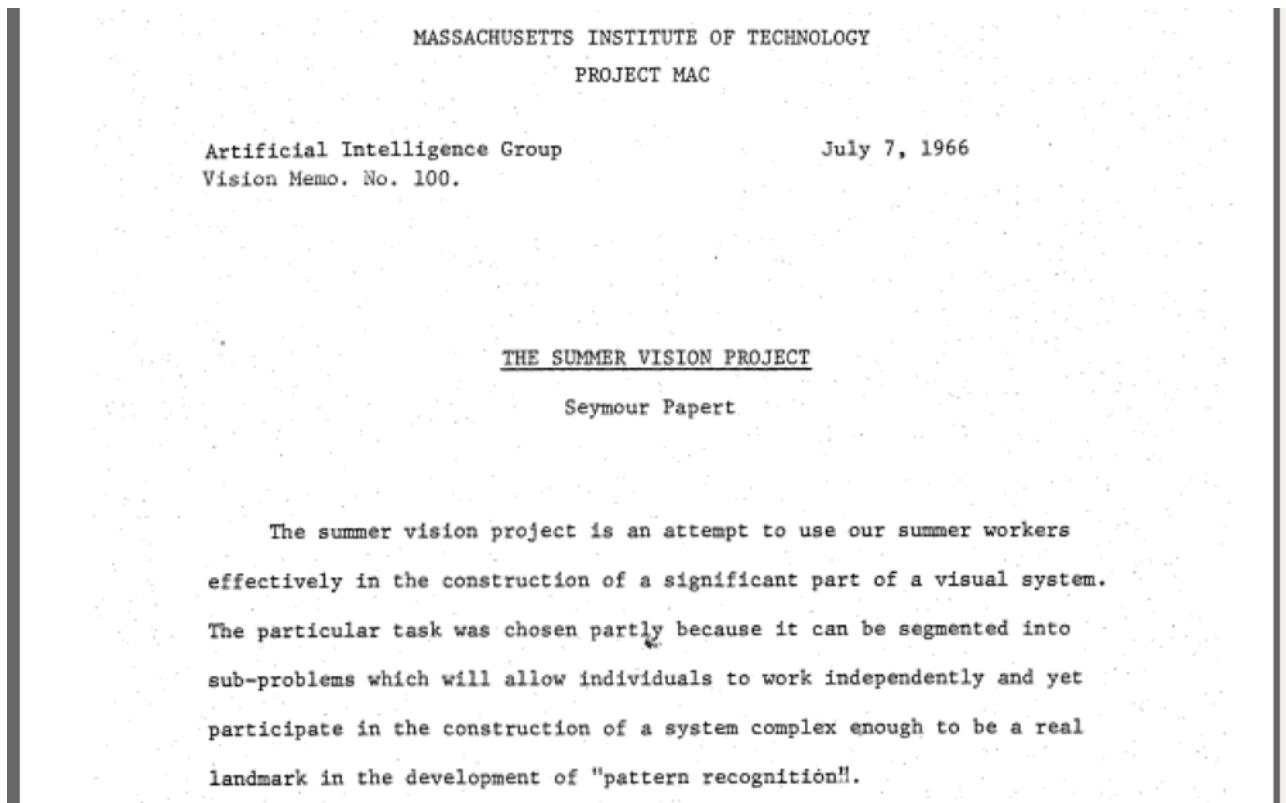
- Course webpage, syllabus:

[http://user.ceng.metu.edu.tr/~gcinbis/courses/
Fall23/CENG483/](http://user.ceng.metu.edu.tr/~gcinbis/courses/Fall23/CENG483/)

Also, if interested in, about my research:

<http://user.ceng.metu.edu.tr/~gcinbis>

Origins of computer vision: an MIT undergraduate summer project

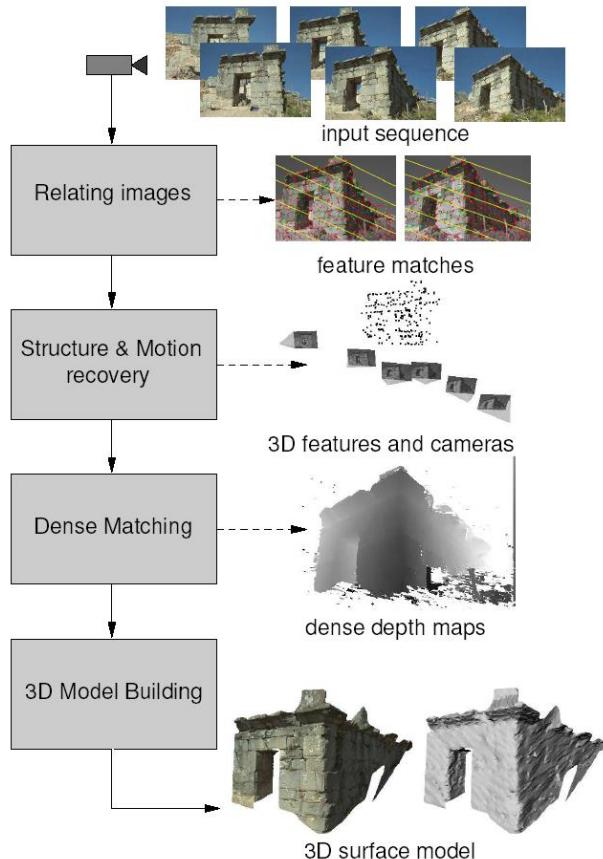
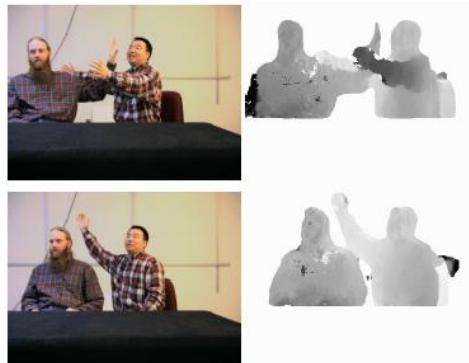


Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

What kind of information can we extract from an image?

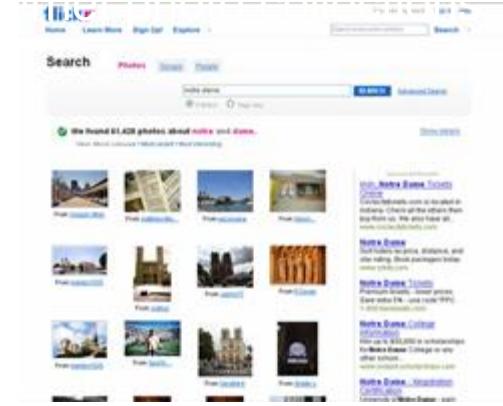
- (Geo)metric information
- Semantic information

Vision as measurement device



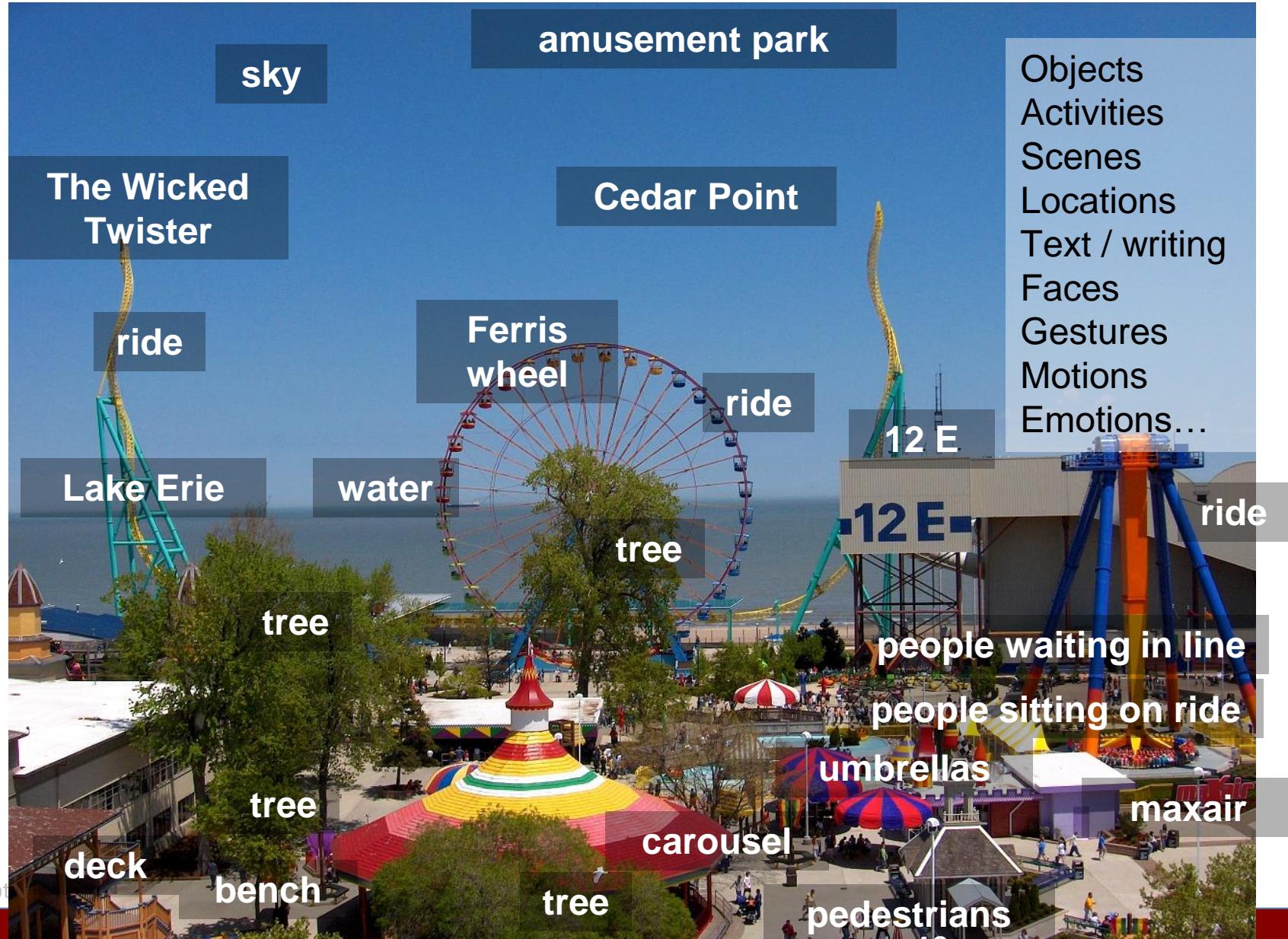
Pollefeys et al.

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna



Goesele et al.

Vision as a source of semantic information

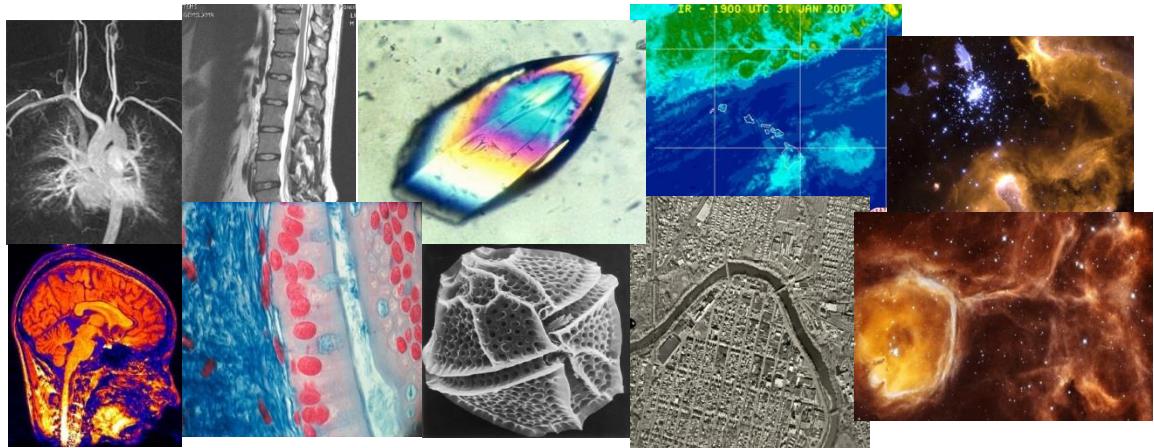


Slide credit: Kristen Grauman

Adapted

Why study computer vision?

- Vision is useful: Images and video are everywhere!



Surveillance and security

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Medical and scientific images

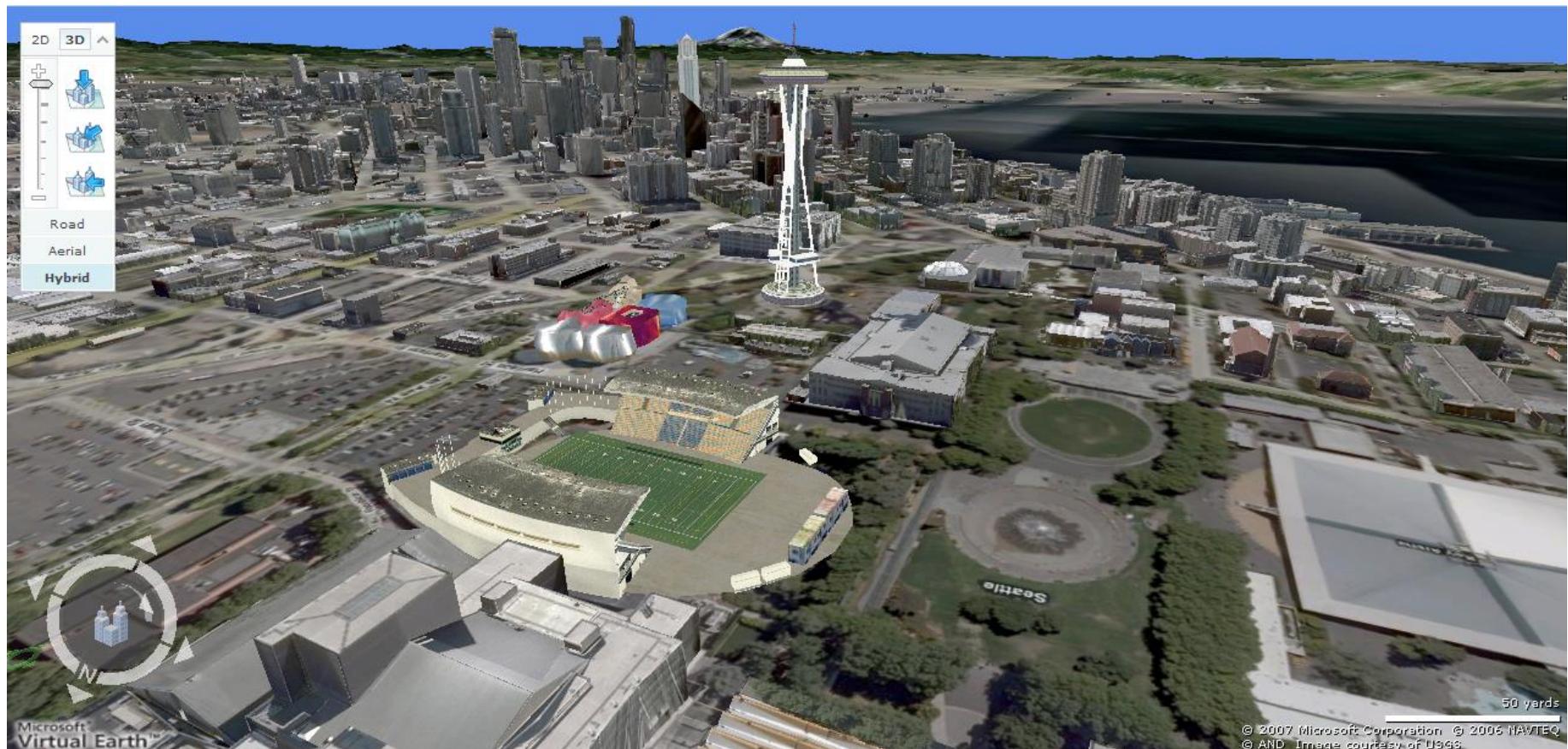
Special effects: shape and motion capture



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Source: S. Seitz

3D urban modeling



Bing maps, Google Streetview

Source: S. Seitz

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

3D urban modeling: Microsoft Photosynth



<http://photosynth.net> (defunct)

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Source: S. Seitz

Face detection



- Many digital cameras now detect faces
 - Canon, Sony, Fuji, ...

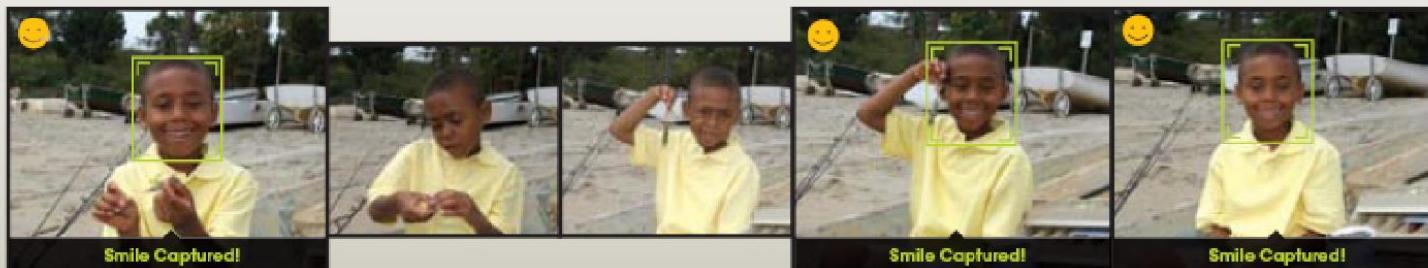
Source: S. Seitz

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Smile detection

The Smile Shutter flow

Imagine a camera smart enough to catch every smile! In Smile Shutter Mode, your Cyber-shot® camera can automatically trip the shutter at just the right instant to catch the perfect expression.



[Sony Cyber-shot® T70 Digital Still Camera](#)

Source: S. Seitz

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Face recognition: Apple, Facebook, etc.



<http://www.apple.com/ilife/iphoto/>

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

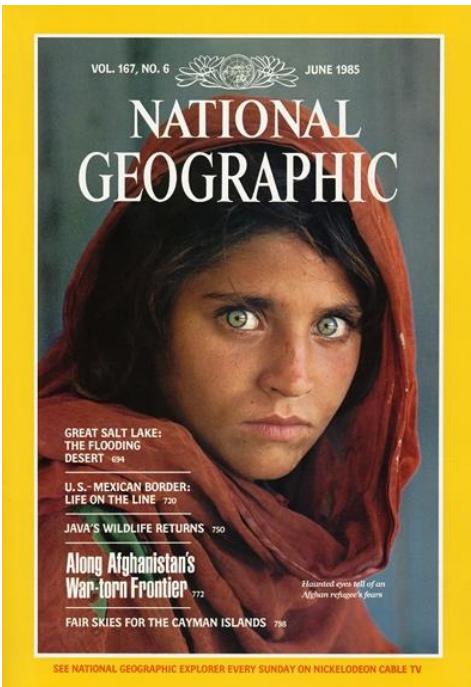
Portrait Focus



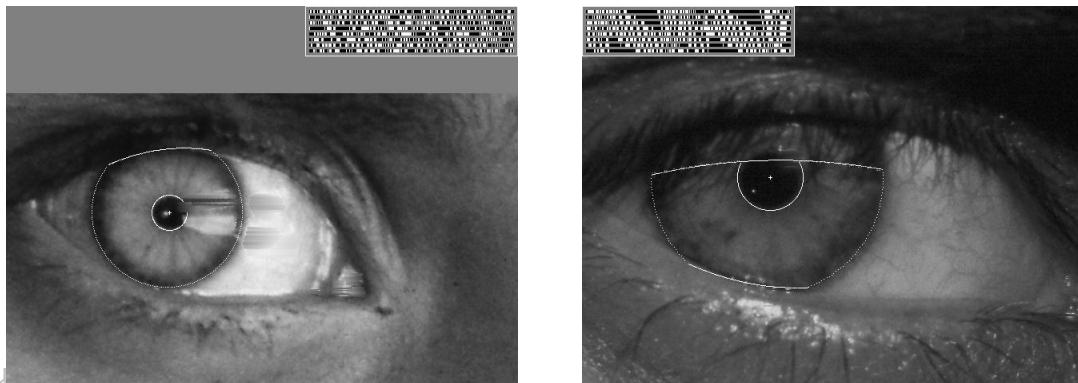
<https://www.engadget.com/2016/10/24/apple-releases-ios-10-1-adds-portrait-mode-to-the-iphone-7-plus/>

Ad:

Biometrics



How the Afghan Girl was Identified by Her Iris Patterns



Adapted from slides by Ju

Source: S. Seitz

Biometrics



Fingerprint scanners on
many new laptops,
other devices

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

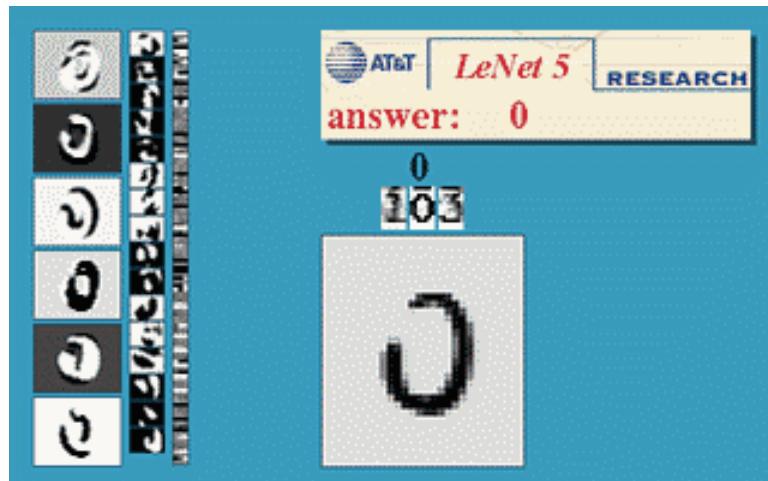


Face recognition systems now beginning
to appear more widely
iphone X just introduced face recognition

Optical character recognition (OCR)

Technology to convert scanned docs to text

- If you have a scanner, it probably came with OCR software



Digit recognition, AT&T
labs



License plate readers
http://en.wikipedia.org/wiki/Automatic_number_plate_recognition

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Source: S. Seitz

Toys and Robots



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Mobile visual search: Google Goggles

Google Goggles in Action

Click the icons below to see the different ways Google Goggles can be used.



Mobile visual search: iPhone Apps



kooaba

Matched Image



Adapt

Automotive safety

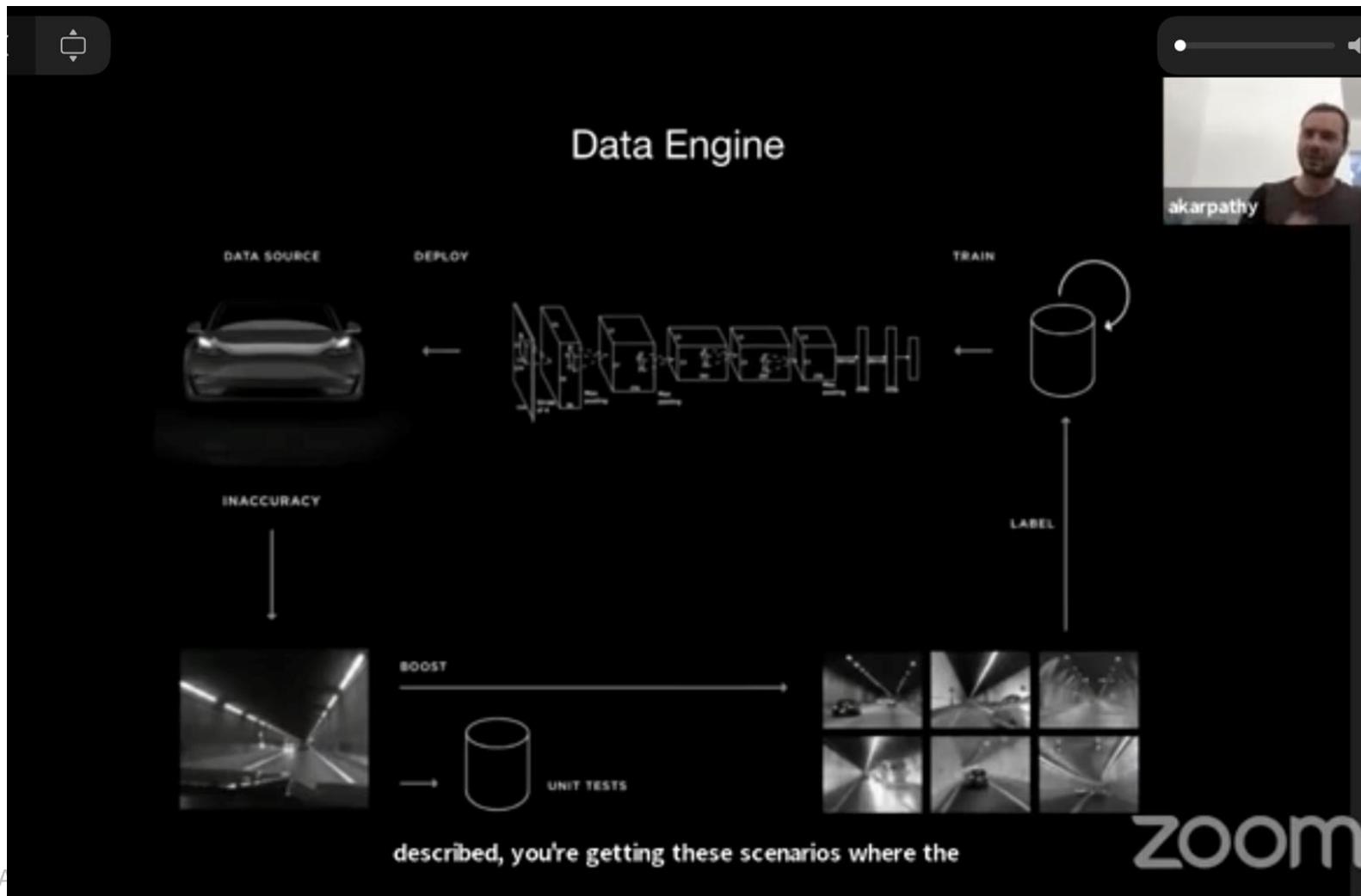
The screenshot shows the Mobileye website's consumer products page. At the top, there are navigation buttons for 'manufacturer products' and 'consumer products'. The main headline is 'Our Vision. Your Safety.' Below it, a diagram illustrates three camera systems: a 'rear looking camera' at the back of a car, a 'forward looking camera' at the front, and a 'side looking camera' on the side. In the bottom left, a section titled 'EyeQ Vision on a Chip' features an image of a chip labeled 'EyeQ' and a link to 'read more'. In the center, a section titled 'Vision Applications' shows a person walking across a crosswalk with a bounding box around them, and a link to 'read more'. In the bottom right, a section titled 'AWS Advance Warning System' shows a circular display with a car icon and a speed limit of '08', with a link to 'read more'. To the right, a sidebar titled 'News' lists two articles: 'Mobileye Advanced Technologies Power Volvo Cars World First Collision Warning With Auto Brake System' and 'Volvo: New Collision Warning with Auto Brake Helps Prevent Rear-end'. Below the news is a thumbnail of a driver's view from inside a car. A sidebar titled 'Events' lists 'Mobileye at Equip Auto, Paris, France' and 'Mobileye at SEMA, Las Vegas, NV', each with a 'read more' link.

- Mobileye: Vision systems in high-end BMW, GM, Volvo models
 - “In mid 2010 Mobileye will launch a world's first application of full emergency braking for collision mitigation for pedestrians where vision is the key technology for detecting pedestrians.”

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Source: A. Shashua, S. Seitz

Towards fully autonomous driving



Vision in supermarkets



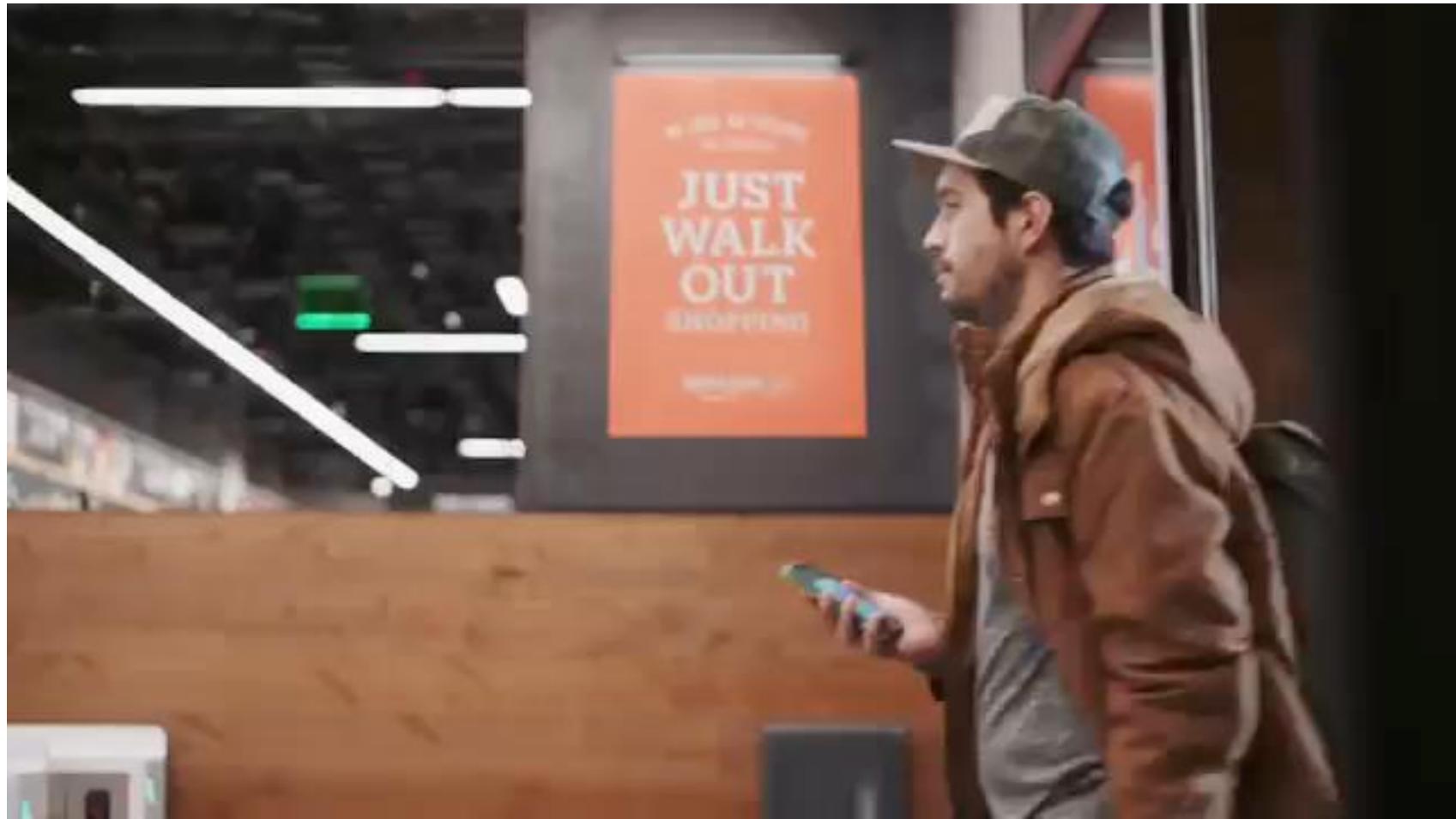
LaneHawk by EvolutionRobotics

“A smart camera is flush-mounted in the checout lane, continuously watching for items. When an item is detected and recognized, the cashier verifies the quantity of items that were found under the basket, and continues to close the transaction. The item can remain under the basket, and with LaneHawk, you are assured to get paid for it... “

Source: S. Seitz

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Amazon Go



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Vision-based interaction (and games)



Microsoft's Kinect



Sony EyeToy



Assistive technologies

Source: S. Seitz

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Augmented Reality



Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Vision for robotics, space exploration



[NASA's Mars Exploration Rover Spirit](#) captured this westward view from atop a low plateau where Spirit spent the closing months of 2007.

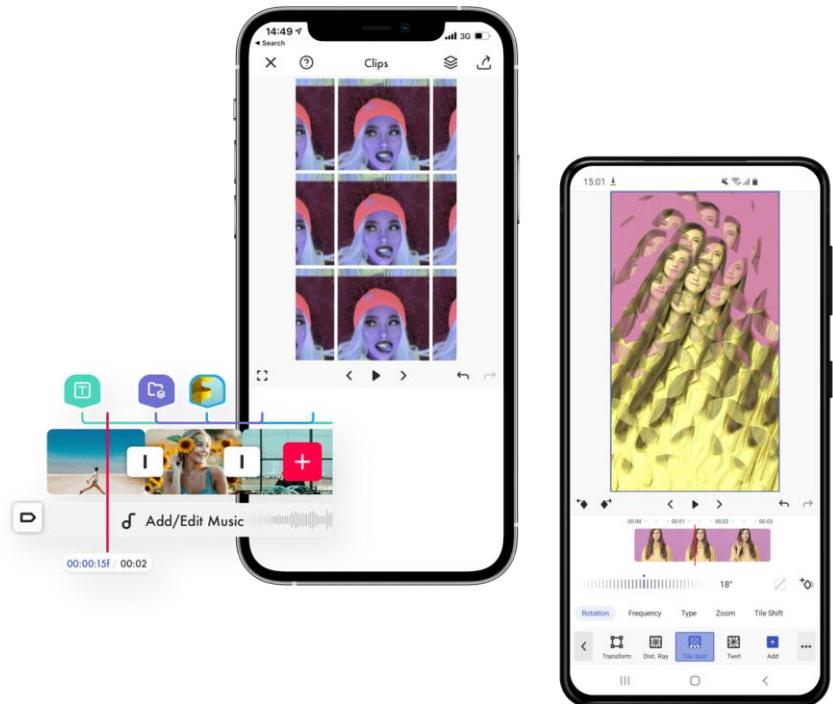
Vision systems (JPL) used for several tasks

- Panorama stitching
- 3D terrain modeling
- Obstacle detection, position tracking
- For more, read “[Computer Vision on Mars](#)” by Matthies et al.

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Source: S. Seitz

Creative content editing



NVidia

Adapted from slides by Juan Carlos Niebla, and Ranjay Krishna

<https://www.pixerylabs.com>

Content creation



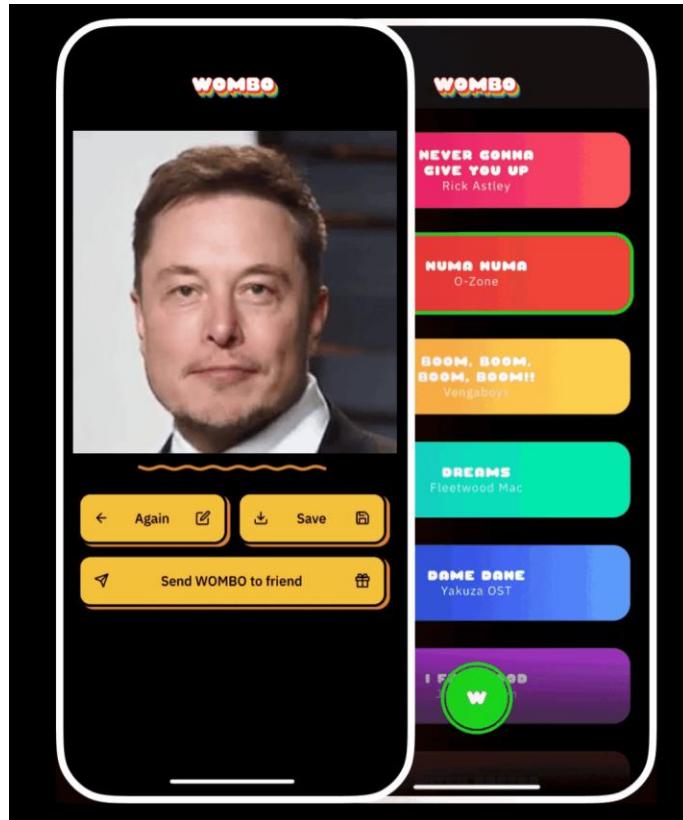
<https://ai.facebook.com/blog/generative-ai-text-to-video/>

<https://makeavideo.studio/>

September 29, 2022

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

And just for fun :)

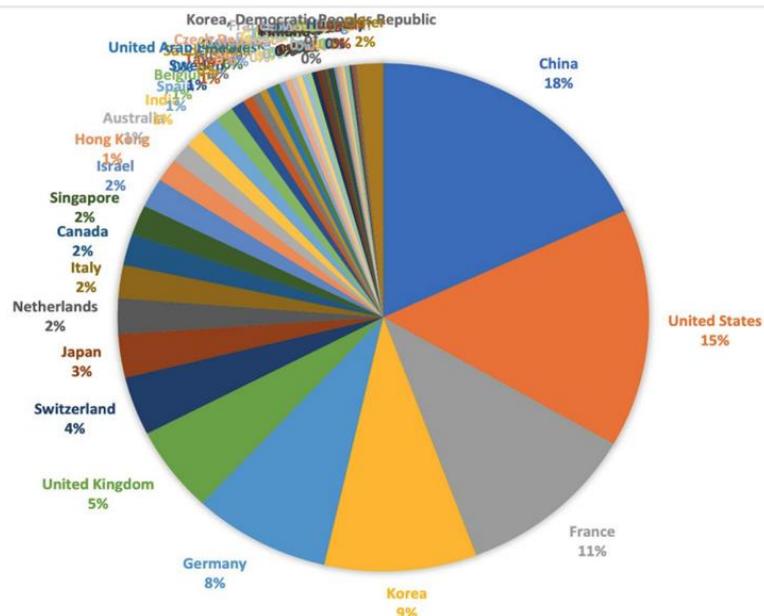


<https://www.wombo.ai>

Adapted from slides by Juan Carlos Niebles, and Ranjay Krishna

Computer Vision as a Research Field

Attendance

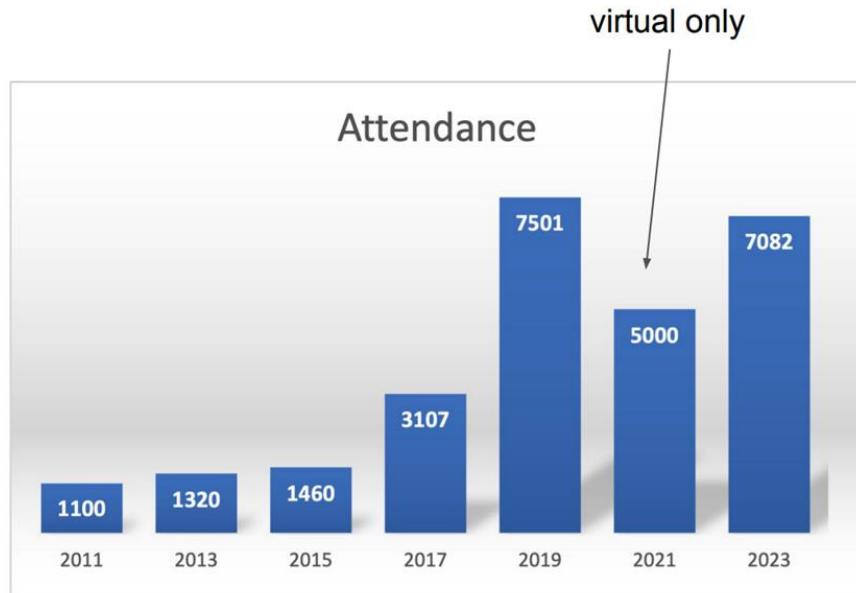


Attendees from 84 countries/regions

China	1233	Denmark	29
United States	1034	Colombia	26
France	749	Czech Republic	26
Korea	630	Poland	23
Germany	569	Greece	22
UK	374	Turkey	21
Switzerland	255	Mexico	21
Japan	188	Finland	21
Netherlands	155	Romania	19
Italy	143	Croatia	17
Canada	136	Armenia	12
Singapore	130	Slovenia	12
Israel	128	Ethiopia	12
Hong Kong	102	Luxembourg	11
Australia	87	Vietnam	11
India	81	Norway	10
Spain	79	Brazil	10
Belgium	75	Hungary	10
Sweden	57	Cyprus	10
Taiwan	41	Korea Dem	10
Austria	37	Other 37 countries < 10	
Saudi Arabia	30		
United Arab Emirates			

Computer Vision as a Research Field

Attendance in numbers



As of yesterday: 7335 registrations incl. 6761 in-person

