

# Sparsification Techniques Preserving Temporal Connectivity

Arnaud Casteigts<sup>1</sup>

(Joint work with Joseph G. Peters<sup>2</sup> and Jason Schoeters<sup>1</sup>)

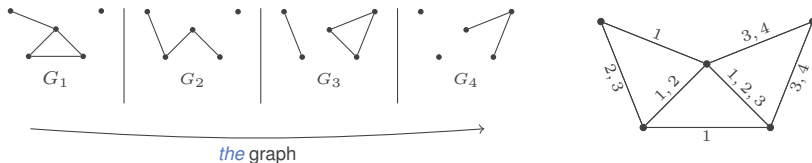
<sup>1</sup>LaBRI, U. Bordeaux, <sup>2</sup>SFU, Vancouver

Algorithmic Aspects of Temporal Graphs II  
(@ICALP'2019)

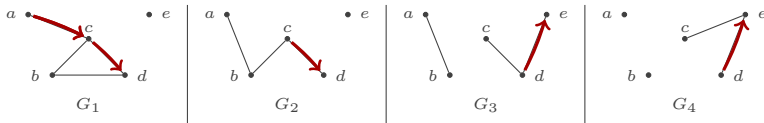
([arxiv.org/abs/1810.00104](https://arxiv.org/abs/1810.00104))

# Temporal graphs

(a.k.a. Time-varying graphs, Evolving graphs, Dynamic graphs)



## Paths and connectivity:



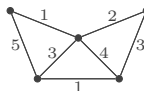
→ Temporal paths (*journey*): path labeled with non-decreasing times

→ *Strict* vs. *non-strict* journeys: allow (or not) consecutive hops in same time step?

→ *Temporal connectivity*:  $\forall u, \forall v, \exists \text{ journey}(u, v)$ .

## Simple temporal graph:

- ▶ Single presence time per edge
- ▶ Times are locally distinct (strict = non-strict)



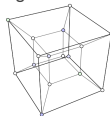
# Temporal spanners

## Original question

[Kempe, Kleinberg, Kumar, STOC'00]

“Given a temporally connected graph, is there always a subset of  $O(n)$  edges that preserves temporal connectivity”? Followed by preliminary answers:

- If journeys are required to be strict  $\rightarrow$  No, e.g.



- More generally?  $\rightarrow$  No, e.g.



$O(n \log n)$  edges, but unsparisifiable.

$\rightarrow$  *Relaxation*: How about a **sparse** (i.e.  $o(n^2)$ ) subset of edges?

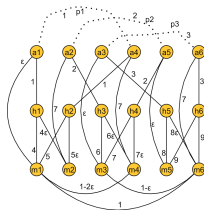
## Theorem

[Axiotis, Fotakis, ICALP'16]

$\rightarrow$  **No!**  $\exists$  non-sparsifiable graphs with  $\Theta(n^2)$  many edges  
(can be adapted to both strict and non-strict journeys)

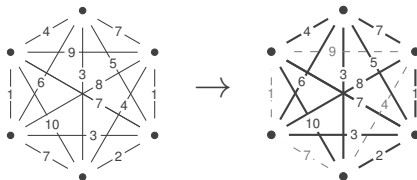
$\rightarrow$  **More assumptions needed!**

E.g. complete graphs?



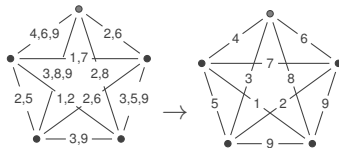
# Temporal cliques

The model: Simple temporal cliques

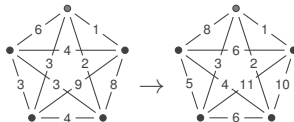


Applicability to more general cliques (by reduction):

- If the clique admits a simple sub-schedule ✓



- If non-strict journeys are allowed ✓

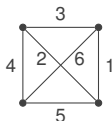


## List of techniques:

- The  $K_4$  technique  $\approx 5 \binom{n}{2} / 6$
- Pivotability  $2n - 3$  (but not general)
- Delegation and dismountability  $2n - 3$  (but not general)
- Fireworks (transitive delegations)  $\approx 3 \binom{n}{2} / 4$
- Bidirectional fireworks  $\approx \binom{n}{2} / 2$
- Bidirectional fireworks + Dismountability + Partial delegation  $O(n \log n)$

## The $K_4$ Lemma

Whatever the labeling, one can find an edge  $e$  such that  $K_4 \setminus \{e\}$  is temporally connected.



Then...

Partition  $K_n$  into  $K_4$ 's, remove an edge in each  $K_4 \rightarrow$  removes  $\lfloor n/4 \rfloor = \Theta(n)$  edges

Remark

[C. Peters, Schoeters, ICALP'19]

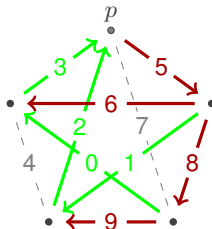
Can be improved by considering **edge**-disjoint  $K_4$ 's

$\rightarrow \binom{n}{2}/6 = \Theta(n^2)$  edges can be removed, resulting in spanner of size  $5\binom{n}{2}/6$

(but still far from sparse...)

# First attempt: Pivotability

A simple way to build linear spanners!



**Motivation:** Kosaraju's principle in directed graphs

$\rightarrow \exists v$  s.t.  $v$  can be reached by all others and  $v$  can reach all others  $\Rightarrow$  strong connectivity

**Temporal version:**

$\rightarrow v$  reached by all others before  $t$  and reaching all others after  $t$  (for some  $t$ )  $\Rightarrow$  temporal connectivity

**Unfortunately:**  $\exists$  arbitrarily large **non pivotable** cliques

we need something else...

# Delegation and dismountability

## Delegation

If  $uv = e^-(u)$ , then  $v$  can reach all the vertices through  $u$ .

→ We say that  $v$  can **delegate** its emissions to  $u$

If  $uv = e^+(u)$ , then  $v$  can be reached by all the vertices through  $v$ .

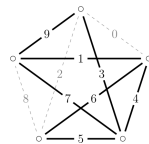
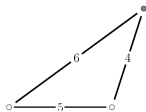
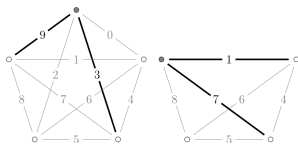
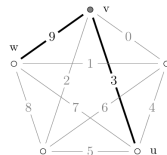
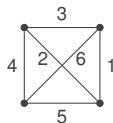
→ We say that  $v$  can **delegate** its receptions to  $u$

## Dismountability

If  $v$  shares both the min edge of a neighbor  $u$  and the max edge of another neighbors  $w$ , then  $v$  is **dismountable**.

→ a spanner for  $K \setminus v + uv + vw$  is a spanner for  $K$  (self-reduction)

→ Suggests recursion & a concept of *full-dismountability* (= recursively dismountable)



## Relaxation

$k$ -hop delegation,  $k$ -hop dismountability

## Unfortunately (again!)

$\exists$  arbitrary large **non ( $k$ -hop) dismountable** cliques



# Transitive delegations (“fireworks”)

## Principle:

- ▶ Min edges  $\rightarrow$  “directed” forest
- ▶ Transitive delegations towards **emitters** (sinks)
- ▶ Spanner = min edges + all edges of emitters

*Wait a minute... possibly too many emitters!*

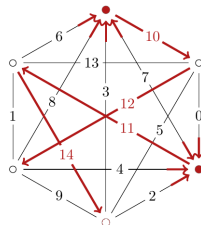
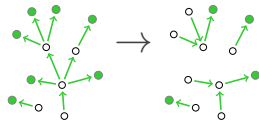
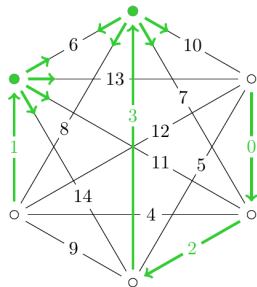
$\rightarrow$  Transformation of the forest:

- ▶ At most  $n/2$  emitters

**Theorem:**  $\exists$  spanners of size  $\frac{3}{4} \binom{n}{2} + O(n)$

**Note:** also works for receptions (“backward fireworks”):

$\rightarrow$  Spanner = max edges + all edges of **collectors**

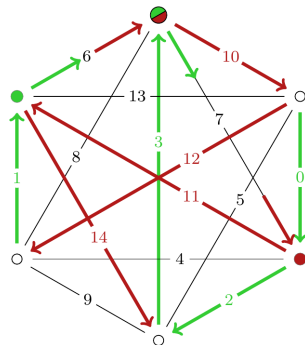


# Combining both directions

## Principle

- ▶ Every vertex can reach at least one emitter  $u$  through  $u$ 's min edge
- ▶ Every vertex can be reached by a collector  $v$  through  $v$ 's max edge
- ▶ Every emitter can reach all collectors through direct edges

→ Spanner = min edges + max edges  
+ edges between **emitters** and **collectors**



## Theorem:

At most  $n/2$  **emitters** and  $n/2$  **collectors**  $\Rightarrow \exists$  Spanners of size  $\binom{n}{2}/2 + O(n)$

$\approx$  half of the edges

Recurse or iterate  
(down to  $O(n \log n)$ )

# Recurse or sparsify?

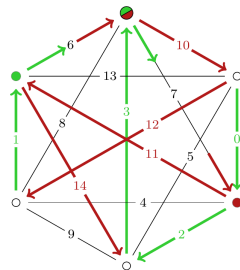
Two options:

- ▶ Case 1:  $\text{emitters} \cup \text{collectors} \subsetneq V$
- ▶ Case 2:  $\text{emitters} \cup \text{collectors} = V$

**Case 1:** One vertex  $v$  is neither emitter nor collector.

→  $\exists$  2-hop dismantlable vertex

(select 4 edges selected, then recursion)

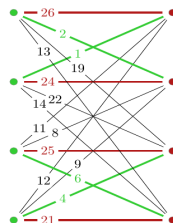


**Case 2:**  $\text{emitters} \cup \text{collectors} = V$

→ All vertices are either emitters or collectors (not both)!

A lot of structure to work with:

- ▶ Complete bipartite graph  $\mathcal{H}$  between emitters and collectors
- ▶ Min edges and max edges form two perfect matchings
- ▶ W.l.o.g. min edges (max edges) are *reciprocal* in  $\mathcal{H}$



New objective:

→ Sparsify  $\mathcal{H}$  while preserving journeys from each **emitter** to all **collectors**

# Sparsification of the bipartite graph

Technique: Partial delegations among emitters

- ▶ Find a 2-hop journey from one emitter to another, arriving through a “locally small” edge
- ▶ Pay extra edges to reach the missed collectors

Iterative procedure:

In each step  $i$ :

- ▶ Half of the **emitters** delegate to other half
- ▶ Some collectors are missed  $\rightarrow$  pay extra edges (penalty)
- ▶ Penalty doubles in each iteration, but number of emitters halves

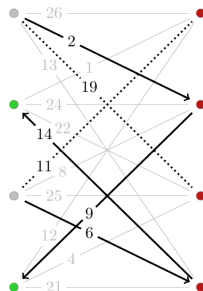
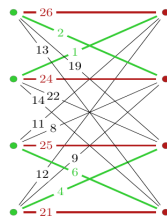
Cost:

$O(n)$  edges over  $O(\log n)$  iterations  $\rightarrow O(n \log n)$  edges.

Conclusion (entire algorithm):

- ▶  $n_1$  recursions due to 2-hop dismantability
- ▶  $n_2 = n - n_1$  vertices when meeting Case 2

$\rightarrow \exists$  spanner of size  $\Theta(n_1) + \Theta(n_2 \log n_2) = O(n \log n)$ .



□

Open questions

# Open questions

## Relaxing the complete graph assumption

- Can more general classes of dense graphs be sparsified?
  - Recall that  $\exists$  unsparsifiable graphs of density  $\Theta(n^2)$
  - Yes if  $\Theta(1)$  edges are missing, can we do better?

## Better spanners for temporal cliques

- Is  $O(n \log n)$  optimal for cliques?

Experiments:	$n$	sparsest spanner (# edges)	
	4	4 or 5	exhaustive search
	5	6 or 7	exhaustive search
	6	8 or 9	exhaustive search
	7	10 or 11	millions random instances
	...	...	
	20	36 or 37	dozens random instances

→  $2n - 4 \leq OPT \leq 2n - 3$  ?

Thank you!