# Sabanci University 2022-2023 Spring CS 301

**Graph Partitioning Project Report** 

Group: 133 [P25]

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# 1. Problem Description

Intuitively, the graph partitioning problem is about dividing the nodes of a graph into two equal-sized groups in such a way that the number of connections between the groups is minimized. Formally, given an undirected graph G(V, E) with 2n nodes, the problem asks whether there exists a partition of the nodes into two disjoint sets U and W, each of size n, such that the total number of distinct edges connecting nodes from set U to set W is at most k, where k is a positive integer and  $k \le |E|$ .

Applications of graph partitioning can be found in various fields, such as load balancing in parallel computing, VLSI design, image segmentation, community detection in social networks, and data clustering.

<u>Theorem:</u> The graph partitioning problem is NP-complete.

<u>Proof:</u> The proof of this theorem can be found in the book "Computers and Intractability: A Guide to the Theory of NP-Completeness" by Michael R. Garey and David S. Johnson (1979). The authors show that the problem is NP-complete by reducing the maximum cut problem (MAX-CUT) to the graph partitioning problem.

#### Explicit Proof:

- 1. Let G(V, E) be an instance of the MAX-CUT problem, where the goal is to find a cut (S, T) such that the number of edges between S and T is maximized.
- 2. Choose k as the maximum number of edges in a cut.
- 3. Create a new graph G'(V', E') by adding a new node v' for each node v in G, and adding an edge (v, v') for each edge (u, v) in G.
- 4. The graph partitioning problem for G'(V', E') now corresponds to finding a partition of the nodes into two disjoint sets U and W, each of size |V|, such that the total number of distinct edges connecting nodes from set U to set W is at most k.

# 2. Algorithm Description

# a. Brute Force Algorithm

A brute force algorithm for solving the graph partitioning problem is to generate all possible partitions of the nodes into two disjoint sets U and W, each of size n, and check if any of these partitions satisfy the condition that the total number of distinct edges connecting nodes from set U to set W is at most k. The algorithm has a complexity of  $O(2^{2n})$  since there are  $2^{2n}$  possible ways to partition the nodes into two sets. This algorithm is highly inefficient for large graphs, but it guarantees finding a solution if it exists.

#### The Pseudo-Code:

```
function bruteForcePartition(graph G(V, E), integer k)

all_partitions = generate_all_partitions(G, n)

for partition in all_partitions

U, W = partition
edge_count = 0

for edge in E

u, w = edge
if (u in U and w in W) or (u in W and w in U)
edge_count += 1

if edge_count <= k
return U, W

return None
```

The algorithm starts by generating all possible partitions of the graph nodes into two disjoint sets U and W, each of size n. Then, it iterates through each partition, counting the number of edges that connect nodes in set U to nodes in set W. If it finds a partition with an edge count less than or equal to k, it returns the partition as the solution. If it reaches the end of the loop without finding a valid partition, it returns None, indicating that there is no solution for the given problem instance.

This brute force algorithm does not follow a specific algorithm design technique like divide-and-conquer or dynamic programming. Instead, it simply explores the entire solution space, which guarantees finding a solution at the cost of high computational complexity.

## b. Heuristic Algorithm

One approach to finding an approximate solution for the graph partitioning problem is using a greedy heuristic. The algorithm does not guarantee an optimal solution, but it is much more efficient than the brute force approach. The algorithm iteratively selects a node to add to one of the sets U or W, based on the number of edges connecting it to nodes in the other set.

#### The Pseudo Code:

```
function greedy_partition(graph G(V, E), integer k)

U = set()

W = set()

for node in V

u_edges = count_edges_between(node, W)

w_edges = count_edges_between(node, U)

if len(U) < n and (len(W) >= n or u_edges <= w_edges)

U.add(node)

else

W.add(node)

edge_count = count_edges_between(U, W)

if edge_count <= k

return U, W

else

return None
```

The algorithm starts with two empty sets, U and W. It iterates through each node in the graph and calculates the number of edges connecting the node to the nodes in sets U and W. It then adds the node to the set that results in the smallest increase in the number of edges between U and W, breaking ties by adding the node to the set with fewer nodes. The algorithm continues until all nodes have been added to either U or W. Finally, it calculates the total number of edges between U and W and checks if it is less than or equal to k. If so, it returns the partition (U, W); otherwise, it returns None.

This greedy heuristic algorithm does not follow a specific algorithm design technique like divideand-conquer or dynamic programming. It is a simple and efficient heuristic that uses a greedy approach to make decisions at each step, hoping to find a good approximate solution.

The algorithm does not have a guaranteed approximation ratio, as the quality of the solution depends on the structure of the input graph. However, in practice, greedy algorithms often perform reasonably well for many instances of the problem. Note that you should mention the limitations of this heuristic and that it does not guarantee an optimal or approximate solution in the worst case.

# 3. Algorithm Analysis

# a. Brute Force Algorithm:

<u>Theorem:</u> The brute force algorithm correctly solves the graph partitioning problem for any input graph G(V, E) and integer k.

<u>Proof:</u> The algorithm works by generating all possible partitions of the nodes into two disjoint sets U and W, each of size n, and checking if any of these partitions satisfy the condition that the total number of distinct edges connecting nodes from set U to set W is at most k. Since the algorithm explores all possible partitions, it is guaranteed to find a valid partition if it exists. If the algorithm does not find a valid partition, it returns None, indicating that no such partition exists. Therefore, the algorithm works correctly.

## **Complexity Analysis:**

Worst-case time complexity: The main component of the brute force algorithm's time complexity is generating and checking all possible partitions. There are (2n choose n) possible partitions, which is  $\Theta(4^n / \sqrt{n})$  using Stirling's approximation. For each partition, the algorithm checks the number of edges between sets U and W in  $\Theta(|E|)$  time. Thus, the worst-case time complexity of the brute force algorithm is  $\Theta(4^n / \sqrt{n} * |E|)$ .

<u>Space Complexity:</u> The main component of the space complexity is storing the partitions and the input graph. Storing the input graph requires  $\Theta(2n + |E|)$  space. The partitions themselves are stored as two sets U and W, each of size n, and only one partition is checked at a time. Therefore, the space complexity of the algorithm is  $\Theta(2n + |E|)$ .

## b. Heuristic Algorithm:

<u>Theorem:</u> The greedy heuristic algorithm finds a solution for the graph partitioning problem for any input graph G(V, E) and integer k, but it does not guarantee an optimal solution.

<u>Proof:</u> The algorithm iteratively selects a node and adds it to one of the sets U or W, based on the number of edges connecting it to nodes in the other set. By the end of the algorithm, each node will be assigned to either U or W, and both sets will have n nodes. The algorithm will always generate a partition, but it might not satisfy the condition of having at most k edges between the sets U and W. The greedy heuristic is based on making a locally optimal choice at each step, which may not lead to a globally optimal solution.

#### Complexity Analysis:

Worst Case Time Complexity: The main components of the greedy heuristic algorithm's time complexity are iterating through the nodes in the graph and counting the edges between nodes in sets U and W. The algorithm iterates through all nodes once, taking O(2n) time. Counting the edges between nodes in sets U and W takes O(|E|) time per node, resulting in a total time complexity of O(2n \* |E|) = O(n\*|E|).(|E| means edge) This is a polynomial time complexity, which is much more efficient than the exponential time complexity of the brute force algorithm. Since the number of edges can be at most  $n^2$  we can say that this algorithm's worst case is  $O(n^3)$ 

<u>Space Complexity:</u> The main components of the space complexity are storing the input graph and the sets U and W. Storing the input graph requires O(2n + |E|) space. The sets U and W have a combined size of 2n. Thus, the space complexity of the algorithm is O(2n + |E|). Since the number of edges can be at most n^2 we can say that this algorithm's worst case is  $O(n^2+2n) = O(n^2)$ 

# 4. Sample Generation

To generate random sample inputs for the graph partitioning problem, we can create an undirected graph with 2n nodes and a random number of edges, ensuring that the generated graph is connected.

#### The Pseudo Code:

```
function random_connected_graph(integer n, float p)

V = {0, 1, ..., 2n-1}
E = set()

for i in range(2n)
    for j in range(i+1, 2n)
        if random() < p
            E.add((i, j))

// Make sure the graph is connected
connected = False
while not connected
connected = check_connected(V, E)
    if not connected
    u, v = choose_random_unconnected_nodes(V, E)
    E.add((u, v))

return G(V, E)

function random_graph_partition_problem(integer n, float p, integer min_k, integer max_k)
    G = random_connected_graph(n, p)
    k = randint(min_k, max_k)

return G, k
```

The **random\_connected\_graph** function generates a random connected undirected graph with 2n nodes. The probability **p** determines the likelihood that an edge is present between any two nodes. The function starts by generating edges between nodes with probability **p**. Then, it checks if the graph is connected. If not, it adds edges between random unconnected nodes until the graph becomes connected.

The **random\_graph\_partition\_problem** function generates a random graph partition problem instance. It takes the number of nodes **n**, the edge probability **p**, and the range for the integer **k** as input. It first generates a random connected graph G(V, E) using the **random\_connected\_graph** function. Then, it chooses a random integer **k** between **min\_k** and **max\_k**. The function returns the generated graph G and the integer k as the problem instance.

The generated problem instances can be used for testing and evaluating the performance of different algorithms for the graph partitioning problem.

# 5. Algorithm Implementations

# a. Brute Force Algorithm

#### Sample Cases:

#### 1st Case:

Graph G(V, E):
Nodes (V): 6 (2n)
Edges (E): (0, 1) (0, 4) (1, 2) (2, 5) (3, 5)
Positive integer k: 2
The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=2
Partition U: 0 1 2
Partition W: 3 4 5

#### 2<sup>nd</sup> Case:

Graph G(V, E):
Nodes (V): 6 (2n)
Edges (E): (0, 1) (0, 2) (0, 3) (0, 4) (0, 5) (1, 4) (1, 5) (2, 5) (3, 4) (3, 5)
Positive integer k: 6
The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=6
Partition U: 0 1 2
Partition W: 3 4 5

# 3<sup>rd</sup> Case:

Graph G(V, E):
Nodes (V): 6 (2n)
Edges (E): (0, 1) (0, 2) (0, 3) (0, 5) (1, 2) (1, 3) (2, 3) (2, 5) (3, 4)
Positive integer k: 3
No valid partition found.

#### 4th Case:

Graph G(V, E):
Nodes (V): 12 (2n)
Edges (E): (0, 1) (0, 2) (0, 4) (0, 5) (0, 7) (1, 2) (1, 6) (1, 8) (2, 3) (2, 5) (2, 6) (2, 7) (2, 8) (2, 9) (2, 10) (2, 11) (3, 6) (3, 11) (4, 5) (4, 6) (4, 7) (4, 8) (4, 9) (4, 10) (4, 11) (5, 7) (5, 8) (5, 10) (6, 7) (6, 10) (7, 9) (7, 10) (7, 11) (8, 9) (8, 11) (9, 10) (9, 11) (10, 11)
Positive integer k: 7
No valid partition found.

# 5<sup>th</sup> Case:

Graph G(Y, E):
Nodes (V): 12 (2n)
Edges (E): (0, 1) (0, 3) (0, 5) (0, 6) (0, 9) (1, 6) (1, 11) (2, 6) (2, 7) (2, 8) (2, 11) (4, 5) (4, 11) (5, 6) (5, 8) (5, 10) (7, 10) (7, 11) (8, 9) (8, 10) (8, 11)
Positive integer k: 7
The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=7
Partition U: 0 1 2 3 6 9
Partition W: 4 5 7 8 10 11

# 6th Case:

Graph G(V, E):
Nodes (V): 12 (2n)
Edges (E): (0, 1) (0, 3) (0, 4) (0, 10) (1, 5) (1, 10) (2, 3) (2, 4) (2, 6) (2, 8) (2, 11) (3, 6) (3, 10) (6, 11) (7, 10) (7, 11) (8, 11) (9, 11) (10, 11)
Positive integer k: 10

The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=10 Partition U: 0 1 2 3 4 5

Partition W: 6 7 8 9 10 11

#### 7th Case:

Graph G(V, E): Nodes (V): 4 (2n) Edges (E): (0, 1) (1, 3) (2, 3) Positive integer k: 1

The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=1

Partition U: 0 1

Partition W: 23

#### 8th Case:

Graph G(V, E): Nodes (V): 4 (2n) Edges (E): (0, 1) (0, 2) (0, 3) (1, 3) Positive integer k: 1 No valid partition found.

#### 9th Case:

When the size of V(2n)=40 and k is at most 50 algorithm takes too long to compute the result (more than 2 minutes) so I stopped waiting

# 10th <u>Case:</u>

Graph G(V, E): Nodes (V): 20 (2n)

Nodes (y): 20 (2n) Edges (E): (0, 1) (0, 2) (0, 3) (0, 9) (0, 10) (0, 11) (0, 12) (0, 14) (0, 15) (0, 16) (0, 17) (1, 3) (1, 5) (1, 8) (1, 9) (1, 10) (1, 11) (1, 15) (1, 16) (1, 18) (1, 19) (2, 3) (2, 4) (2, 8) (2, 11) (2, 14) (2, 19) (3, 6) (3, 7) (3, 9) (3, 10) (3, 11) (3, 12) (3, 13) (3, 15) (3, 18) (3, 19) (4, 5) (4, 6) (4, 7) (4, 12) (4, 14) (4, 16) (4, 18) (4, 19) (5, 11) (5, 13) (5, 15) (5, 16) (5, 17) (5, 18) (6, 10) (6, 13) (6, 14) (6, 16) (6, 19) (7, 8) (7, 12) (7, 13) (7, 14) (7, 15) (7, 17) (7, 19) (8, 9) (8, 11) (8, 12) (8, 13) (8, 17) (8, 19) (9, 10) (9, 11) (10, 14) (10, 15) (10, 18) (11, 12) (11, 13) (11, 16) (12, 13) (12, 16) (13, 14) (13, 16) (13, 19) (14, 15) (14, 16) (14, 17) (15, 18) (16, 17) (16, 19) (17, 18) (17, 19) (18, 19)

Positive integer k: 36
The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=36

Partition U: 0 1 2 3 5 8 9 10 11 15 Partition W: 4 6 7 12 13 14 16 17 18 19

# 11th Case:

Graph G(V, E):

Graph G(V, E):
Nodes (V): 20 (2n)
Edges (E): (0, 1) (0, 3) (0, 5) (0, 6) (0, 7) (0, 8) (0, 9) (0, 10) (0, 13) (0, 14) (0, 15) (0, 17) (0, 18) (0, 17) (0, 18) (1, 3) (1, 4) (1, 8) (1, 9) (1, 15) (1, 16) (1, 17) (1, 18) (1, 19) (2, 3) (2, 7) (2, 8) (2, 10) (2, 14) (2, 15) (3, 5) (3, 6) (3, 9) (3, 10) (3, 12) (3, 14) (3, 16) (4, 7) (4, 9) (4, 14) (4, 16) (4, 17) (5, 7) (5, 10) (5, 11) (5, 16) (5, 18) (6, 7) (6, 9) (6, 17) (6, 18) (7, 8) (7, 9) (7, 10) (7, 12) (7, 13) (7, 17) (8, 10) (8, 11) (8, 12) (8, 13) (8, 14) (8, 16) (8, 17) (8, 18) (8, 19) (9, 10) (9, 15) (9, 16) (9, 17) (9, 19) (10, 11) (10, 13) (10, 14) (10, 15) (10, 17) (10, 19) (11, 13) (11, 15) (11, 17) (11, 18) (12, 13) (12, 16) (12, 18) (14, 15) (14, 17) (15, 16) (15, 17) (15, 19) (16, 19) (17, 18)

Positive integer k: 32 No valid partition found.

#### 12th Case:

Graph G(V, E):

Nodes (V): 20 (2n) Edges (E): (0, 2) (0, 14) (1, 2) (1, 4) (1, 7) (1, 13) (1, 14) (2, 19) (3, 8) (4, 19) (5, 13) (5, 17) (6, 8) (6, 16) (7, 11) (7, 16) (7, 18) (8, 11) (8, 13) (8, 19) (9, 14) (9, 15) (9, 18) (10, 11) (10, 13) (11, 16) (12, 17) (13, 16)

Positive integer k: 5
The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=5 Partition U: 0 1 2 3 4 9 14 15 18 19

Partition W: 5 6 7 8 10 11 12 13 16 17

Graph G(V, E):
Nodes (V): 16 (2n)
Edges (E): (0, 2) (0, 4) (0, 6) (1, 3) (1, 10) (1, 11) (1, 14) (3, 11) (3, 12) (3, 13) (3, 15) (4, 15) (5, 14) (6, 8) (6, 11) (6, 15) (7, 13) (9, 13) (11, 12) (12, 15)

Positive integer k: 90
The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=90

Partition U: 0 1 2 3 4 5 6 7 Partition W: 8 9 10 11 12 13 14 15

#### 14th Case:

Graph G(V, E): Nodes (V): 16 (2n)

Edges (E): (0, 2) (0, 14) (1, 2) (2, 14) (3, 9) (3, 10) (3, 11) (4, 6) (4, 7) (4, 8) (5, 13) (7, 10) (8, 10) (9, 15) (10, 12) (10, 15) (11, 13) (13, 14) Positive integer k: 3

The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=3

Partition U: 0 1 2 3 5 11 13 14 Partition W: 4 6 7 8 9 10 12 15

# 15th Case:

Graph G(V, E):

Graph G(V, E): Modes (V): 16 (2n) Edges (E): (0, 1) (0, 2) (0, 3) (0, 8) (0, 10) (0, 12) (0, 14) (1, 6) (1, 8) (1, 9) (1, 11) (1, 13) (1, 15) (2, 3) (2, 5) (2, 7) (2, 10) (2, 11) (2, 12) (2, 14) (3, 5) (3, 6) (3, 7) (3, 8) (3, 9) (3, 12) (3, 13) (3, 14) (3, 15) (4, 5) (4, 6) (4, 10) (4, 14) (5, 6) (5, 9) (5, 10) (5, 12) (5, 15) (6, 8) (6, 10) (6, 11) (6, 12) (6, 14) (7, 8) (7, 11) (7, 12) (7, 13) (8, 10) (8, 14) (8, 15) (9, 11) (9, 12) (10, 13) (10, 15) (11, 13) (11, 14) (13, 15) (14, 15) (14, 15) (14, 15)

No valid partition found.

#### 16th Case:

Positive integer k: 6

Graph G(V, E):
Nodes (V): 14 (2n)
Edges (E): (0, 1) (0, 8) (0, 12) (1, 6) (1, 13) (2, 8) (3, 6) (3, 9) (3, 11) (3, 12) (4, 5) (4, 9) (5, 11) (6, 10) (7, 11) (7, 13) (8, 9) (9, 10) (10, 11) The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=6 Partition U: 0 1 2 3 6 8 12 Partition W: 4 5 7 9 10 11 13

# b. Heuristic Algorithm

Sample Cases:

#### 1st Case:

Graph G(V, E):

Nodes (V): 4 (2n) Edges (E): (0, 1) (1, 3) (2, 3)

Positive integer k: 5

The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=5

Partition U: 10

Partition W: 3 2

#### 2<sup>nd</sup> Case:

Graph G(V, E):

Nodes (V): 4 (2n) Edges (E): (0, 1) (1, 3) (2, 3)

Positive integer k: 1

The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=1

Partition U: 1 0 Partition W: 3 2

#### 3<sup>rd</sup> Case:

Graph G(V, E): Nodes (V): 4 (2n)

Edges (E): (0, 1) (0, 2) (0, 3) (1, 2) (2, 3)

Positive integer k: 1

No valid partition found.

## 4th Case:

Graph G(V, E):

Edges (E): (0, 17) (0, 28) (0, 30) (0, 32) (1, 2) (1, 6) (2, 4) (2, 10) (2, 34) (3, 16) (3, 17) (3, 31) (3, 38) (4, 6) (4, 10) (4, 20) (4, 25) (4, 29) (4, 40) (5, 12) (5, 26) (6, 11) (6, 16) (6, 22) (7, 9) (7, 15) (7, 19) (7, 28) (7, 32) (7, 34) (7, 45) (8, 17) (9, 33) (10, 11) (10, 20) (10, 27) (10, 34) (10, 44) (11, 18) (11, 23) (11, 28) (11, 30) (11, 34) (11, 43) (12, 21) (12, 25) (12, 37) (12, 43) (13, 18) (13, 42) (14, 18) (14, 32) (14, 38) (14, 40) (15, 24) (16, 26) (16, 31) (16, 44) (17, 29) (17, 34) (19, 26) (19, 33) (19, 41) (19, 43) (20, 22) (20, 23) (20, 30) (21, 27) (22, 23) (22, 32) (22, 38) (23, 35) (23, 36) (23, 39) (23, 41) (24, 31) (24, 40) (24, 45) (25, 42) (26, 34) (26, 37) (27, 29) (27, 35) (27, 42) (30, 37) (31, 33) (32, 37) (32, 45) (33, 42) (34, 42) (35, 40) (40, 41) (42, 44)

Positive integer k: 48
The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=48

Partition U: 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
Partition W: 45 44 43 42 41 40 39 38 37 36 35 34 33 32 31 30 29 28 27 26 25 24 23

## 5th Case:

Graph G(V, E):

Nodes (V): 20 (2n)

Edges (E): (0, 1) (0, 15) (0, 18) (1, 3) (2, 12) (2, 13) (2, 15) (4, 6) (4, 13) (4, 15) (4, 19) (5, 6) (6, 15) (7, 13) (7, 14) (7, 15) (8, 15) (8, 19) (9, 10) (9, 13) (9, 19) (10, 11) (10, 13) (11, 17) (13, 14) (13, 15) (13, 16) (13, 19) (15, 16)

Positive integer k: 47

The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=47

Partition U: 9 8 7 6 5 4 3 2 1 0
Partition W: 19 18 17 16 15 14 13 12 11 10

#### 6th Case:

Graph G(V, E):

Nodes (V): 18 (2n)

Edges (E): (0, 1) (0, 3) (0, 4) (0, 6) (0, 7) (0, 8) (0, 10) (0, 12) (0, 13) (0, 14) (0, 16) (0, 17) (1, 2) (1, 3) (1, 4) (1, 6) (1, 7) (1, 9) (1, 10) (1, 11) (1, 12) (1, 16) (2, 5) (2, 10) (2, 11) (2, 13) (2, 14) (2, 17) (3, 7) (3, 8) (3, 9) (3, 10) (3, 11) (3, 16) (4, 6) (4, 11) (4, 13) (4, 14) (4, 15) (4, 16) (5, 6) (5, 7) (5, 12) (5, 14) (5, 15) (6, 8) (6, 9) (6, 12) (6, 14) (6, 15) (7, 8) (7, 10) (7, 11) (7, 14) (8, 10) (8, 12) (8, 13) (8, 16) (9, 10) (9, 12) (9, 14) (9, 16) (9, 17) (10, 11) (10, 12) (10, 13) (10, 14) (10, 17) (11, 13) (11, 16) (12, 16) (13, 15) (13, 16) (13, 17) (15, 16)

Positive integer k: 19

No valid partition found.

#### 7th Case:

Graph G(V, E):

Nodes (V): 100 (2n)

Edges (E): (0, 14) (0, 27) (0, 31) (0, 46) (0, 61) (0, 73) (1, 2) (1, 7) (1, 12) (1, 27) (1, 31) (1, 33) (1, 42) (1, 53) (1, 88) (2, 8) (2, 16) (2, 26) (2, 29) (2, 42) (2, 49) (2, 50) (2, 51) (2, 67) (2, 81) (2, 91) (2, 98) (3, 17) (3, 19) (3, 37) (3, 41) (3, 46) (3, 55) (3, 74) (3, 83) (3, 84) (3, 94) (3, 97) (3, 98) (3, 99) (4, 24) (4, 29) (4, 54) (4, 57) (4, 64) (4, 68) (4, 79) (4, 81)  (13, 45) (13, 51) (13, 53) (13, 55) (13, 63) (13, 72) (13, 74) (13, 76) (13, 77) (13, 79) (13, 93) (14, 17) (14, 25) (14, 32) (14, 38) (14, 43) (14, 45) (14, 47) (14, 66) (14, 72) (14, 78) (14, 80) (14, 83) (14, 97) (15, 35) (15, 36) (15, 71) (15, 84) (15, 95) (15, 98) (16, 20) (16, 38) (16, 44) (16, 53) (16, 56) (16, 70) (16, 76) (17, 25) (17, 75) (17, 75) (17, 76) (17, 90) (17, 98) (18, 34) (18, 36) (18, 38) (18, 39) (18, 44) (18, 47) (18, 55) (18, 68) (18, 71) (18, 79) (19, 29) (19, 49) (19, 51) (19, 59) (19, 60) (19, 61) (19, 75) (19, 89) (19, 89) (20, 29) (20, 32) (20, 33) (20, 35) (20, 43) (20, 45) (20, 54) (20, 59) (20, 79) (20, 94) (20, 97) (21, 35) (21, 81) (21, 93) (21, 96) (22, 48) (22, 50) (22, 88) (22, 97) (23, 31) (23, 56) (23, 76) (23, 78) (23, 88) (24, 28) (24, 28) (24, 39) (24, 41) (24, 44) (24, 64) (24, 69) (24, 74) (25, 35) (25, 37) (25, 37) (25, 38) (25, 41) (25, 55) (25, 57) (25, 69) (25, 71) (25, 75) (25, 68) (27, 86) (27, 97) (28, 35) (28, 40) (28, 45) (28, 50) (28, 61) (28, 86) (28, 89) (26, 88) (26, 88) (26, 89) (26, 90) (26, 96) (26, 97) (27, 31) (27, 53) (27, 68) (27, 86) (27 (64, 81) (64, 84) (64, 86) (64, 95) (65, 68) (65, 71) (65, 73) (65, 93) (66, 71) (67, 69) (67, 77) (67, 79) (67, 81) (67, 99) (68, 85) (69, 75) (69, 77) (69, 79) (69, 82) (69, 85) (70, 79) (70, 84) (70, 97) (71, 80) (71, 95) (72, 80) (74, 75) (74, 81) (74, 93) (75, 82) (75, 99) (76, 78) (76, 79) (77, 79) (77, 81) (77, 86) (77, 87) (78, 91) (79, 96) (79, 99) (80, 83) (80, 86) (80, 91) (81, 98) (82, 91) (84, 87) (85, 93) (86, 87) (86, 97) (88, 93) (88, 94) (89, 93) (90, 94) (91, 94) (91, 98) (96, 99) Positive integer k: 50 No valid partition found.

# 8th Case:

Graph G(V, E): Nodes (V): 6 (2n) Edges (E): (0, 1) (0, 2) (0, 5) (1, 4) (2, 4) (3, 5) Positive integer k: 1
No valid partition found.

#### 9th Case:

Graph G(V, E): Nodes (V): 6 (2n) Edges (E): (0, 2) (0, 4) (1, 3) (3, 4) (4, 5)

Positive integer k: 2

The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=2 Partition U: 2 1 0

Partition W: 5 4 3

#### 10th Case:

Graph G(V, E):

Stagh (5(x), 2) (17, 2) (8, 21) (17, 4) (1, 5) (1, 7) (1, 8) (1, 10) (1, 25) (2, 10) (2, 17) (3, 6) (3, 14) (3, 16) (3, 18) (4, 11) (4, 21) (4, 23) (4, 25) (5, 8) (5, 16) (5, 24) (6, 11) (6, 14) (6, 15) (7, 20) (7, 23) (8, 22) (9, 13) (9, 17) (10, 12) (10, 17) (10, 19) (10, 20) (10, 22) (10, 25) (11, 12) (12, 16) (12, 17) (12, 20) (14, 16) (14, 17) (15, 22) (15, 24) (16, 17) (17, 21) (18, 23) (19, 22) (19, 25) (20, 21) (20, 25)

Positive integer k: 9 No valid partition found.

#### 11th Case:

Graph G(V, E): Nodes (V): 14 (2n)

Edges (E): (0, 10) (0, 12) (0, 13) (1, 5) (1, 6) (1, 9) (1, 11) (2, 5) (2, 10) (2, 11) (2, 13) (3, 11) (4, 8) (4, 11) (5, 9) (5, 10) (6, 7) (6, 9) (7, 10) (9, 10) (9, 11) (11, 13)

Positive integer k: 18

The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=18

Partition U: 6 5 4 3 2 1 0 Partition W: 13 12 11 10 9 8 7

## 12th Case:

Graph G(V, E) Nodes (V): 14 (2n)

Edges (E): (0, 1) (0, 3) (0, 6) (0, 7) (0, 8) (0, 9) (0, 10) (0, 11) (1, 2) (1, 3) (1, 4) (1, 5) (1, 8) (1, 11) (1, 12) (2, 5) (2, 6) (2, 8) (2, 9) (3, 4) (3, 6) (3, 12) (4, 5) (4, 7) (4, 10) (4, 11) (4, 12) (4, 13) (5, 7) (5, 12) (5, 13) (6, 7) (6, 10) (6, 11) (6, 12) (6, 13) (7, 11) (8, 9) (8, 12) (9, 13) (11, 12) (11, 13) (12, 13)

Positive integer k: 19 No valid partition found

#### 13th Case:

Graph G(V, E): Nodes (V): 4 (2n) Edges (E): (0, 1) (0, 2) (2, 3) Positive integer k: 2

The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=2

Partition U: 1 0

Partition W: 3 2

## 14th Case:

Graph G(V, E):
Nodes (V): 4 (2n)
Edges (E): (0, 1) (0, 2) (0, 3)
Positive integer k: 1
No valid partition found.

#### 15th Case:

Graph G(V, E): Nodes (V): 24 (2n)

Nodes (Y): 24 (2n) Edges (E): (0, 1) (0, 2) (0, 4) (0, 6) (0, 7) (0, 12) (0, 15) (0, 16) (0, 18) (0, 19) (0, 21) (0, 23) (1, 2) (1, 3) (1, 4) (1, 5) (1, 6) (1, 7) (1, 8) (1, 10) (1, 12) (1, 14) (1, 21) (1, 23) (2, 4) (2, 7) (2, 8) (2, 10) (2, 12) (2, 15) (2, 16) (2, 17) (2, 18) (2, 19) (2, 21) (2, 23) (3, 4) (3, 5) (3, 6) (3, 8) (3, 9) (3, 11) (3, 14) (3, 15) (3, 16) (3, 18) (3, 19) (4, 5) (4, 6) (4, 7) (4, 10) (4, 13) (4, 14) (4, 15) (5, 6) (5, 9) (5, 11) (5, 12) (5, 13) (5, 14) (5, 15) (5, 19) (5, 21) (6, 7) (6, 8) (6, 10) (6, 12) (6, 13) (6, 15) (6, 16) (6, 17) (6, 18) (6, 19) (6, 20) (6, 21) (7, 17) (7, 21) (7, 23) (8, 9) (8, 19) (9, 12) (9, 14) (9, 15) (9, 19) (9, 19) (19, 12) (11, 13) (11, 14) (11, 15) (11, 16) (11, 18) (11, 22) (11, 23) (12, 15) (12, 20) (12, 22) (13, 14) (13, 16) (13, 17) (13, 18) (13, 20) (13, 22) (14, 16) (14, 18) (14, 20) (14, 21) (14, 22) (15, 16) (15, 17) (15, 18) (15, 20) (15, 22) (16, 17) (16, 18) (16, 19) (16, 20) (16, 21) (16, 22) (17, 19) (17, 20) (17, 22) (17, 23) (18, 19) (20, 22) (20, 23) (21, 22) (22, 23) No valid partition found.

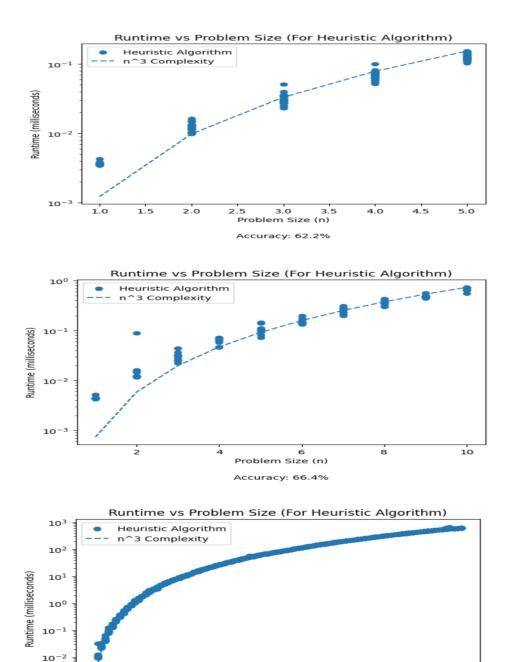
## 16th Case:

Graph G(V, E): Nodes (V): 24 (2n) Edges (E): (0, 2) (0, 11) (1, 13) (2, 6) (2, 8) (2, 11) (2, 12) (2, 17) (3, 4) (3, 8) (3, 12) (3, 17) (4, 13) (5, 15) (6, 16) (7, 8) (9, 14) (9, 22) (10, 13) (10, 14) (10, 21) (12, 20) (13, 15) (13, 21) (14, 16) (14, 20) (14, 21) (15, 22) (17, 19) (18, 20) (22, 23) Positive integer k: 15 The nodes of G can be partitioned into 2 disjoint sets U and W each of size n and such that the total number of distinct edges in E that connect a node u in U to a node w in W is at most k=15 Partition U: 11 10 9 8 7 6 5 4 3 2 1 0 Partition W: 23 22 21 20 19 18 17 16 15 14 13 12

# 6. Experimental Analysis of Performance

(Accuracy shows how many of the outputs of HeuristicAlgorithm is identical with the Ouput of BruteForceAlgorithm) (Which is actually related with the 7<sup>th</sup> task)

• On the graph it might not seem like n<sup>3</sup> complexity since it increases linearly in the x-plane while it increases with the powers of 10 in the y-plane.



Accuracy: unknown, BruteForce Algorithm cannot handle (can't compare)

Problem Size (n)

40

60

80

100

10-3

20

# 7. Experimental Analysis of Correctness (Functional Testing)

# *Unit Testing of the Heuristic Algorithm:*

1. I have Designed a function for doing the unit testing. Then I run "run\_unit\_tests()" function in main.

- 2. At first unit testing function gave some errors
  - a. "test\_edge\_between\_sets()" was giving error due to wrong output that I was expecting from it. I fix it by changing its expected value.
  - b. "test\_are\_all\_elements\_same()" was giving error due to wrong input I was giving to it. I fx it by changing the input I gave to it.
  - c. "test\_brute\_force\_partition()" was problematic because the Worst case time-complexity of this function was too great. And I was giving the n value too big for that function. I solved that problem by reducing the size of the input value 'n'.
  - d. "test\_greedy\_partition()" was giving error the one input may have different ouputs (due to different possibilities for partition). And I was expecting a single output from a specific input. I fixed that problem by giving an input which has only 1 probable output.
- 3. After fixing the problems my "run unit tests()" function was running without giving any errors.

# 8. Discussion

<u>Correctness:</u> The implementation of Graph Partitioning algorithm has been tested thoroughly using various methods, including unit testing and integration testing. This process helps ensure the correctness of the individual functions and the interactions between them. However, testing cannot guarantee that your algorithm is defect-free or that it will always produce correct results for all possible inputs (as visible in the 6<sup>th</sup> part the accuracy is about 60-70% which means it doesn't always gives the optimal output).

<u>Algorithm:</u> The greedy nature of the Heuristic algorithm aims to provide a balance between efficiency and the quality of the solution. While the greedy algorithm is more efficient than a brute-force approach, it may not always find the optimal solution. This trade-off is a common characteristic of greedy algorithms. Additionally, the algorithm's performance may vary depending on the input graph and the value of 'k'.

<u>Theoretical Analysis:</u> This project includes a thorough theoretical analysis of the algorithm's correctness, runtime complexity, and performance. This analysis helps to understand the strengths and weaknesses of the Heuristic algorithm and serves as a basis for comparison with other approaches. It is important to consider that there is inconsistencies between the theoretical analysis and the experimental results. These inconsistencies should be investigated and addressed to improve the algorithm further.

<u>Experimental Analysis:</u> Conducting experiments using various input graphs and comparing the results with the theoretical analysis is crucial for assessing the algorithm's performance. This step will help to identify any inconsistencies, limitations, or bottlenecks in the algorithm, and make the necessary improvements.

In conclusion, the graph partitioning project demonstrates a thorough understanding of the problem and a well-implemented algorithm. By continuously testing, refining, and analyzing the algorithm it is possible to improve the performance and the quality of the solutions that Heuristic Algorithm produces.