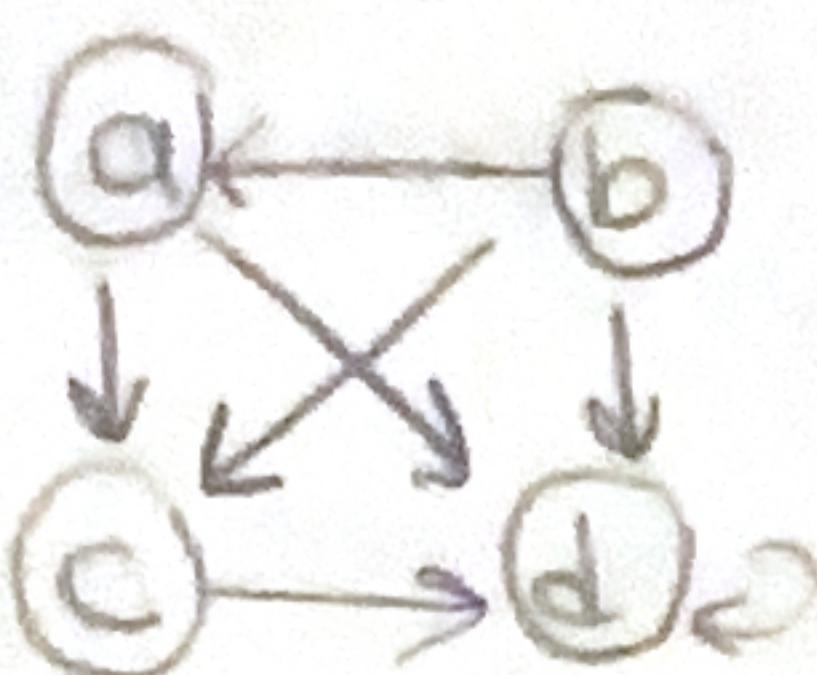


Adjacency List (Contd.)

Time Complexity



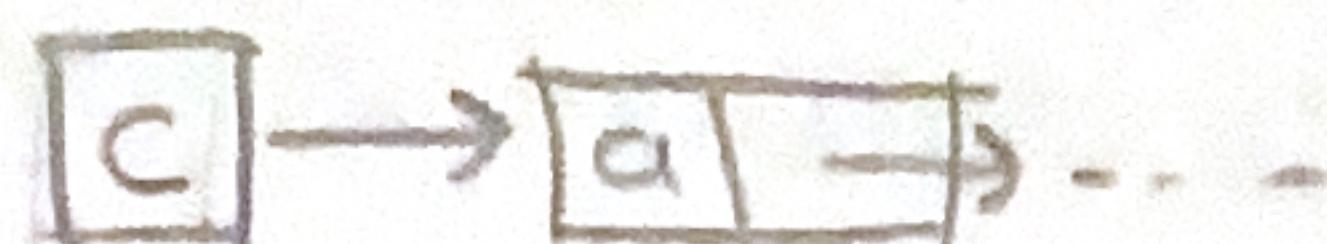
$O(|V|)$ for directed graphs

Check if there's an edge between c & a:

- 1) Go through the array part first. $O(1)$

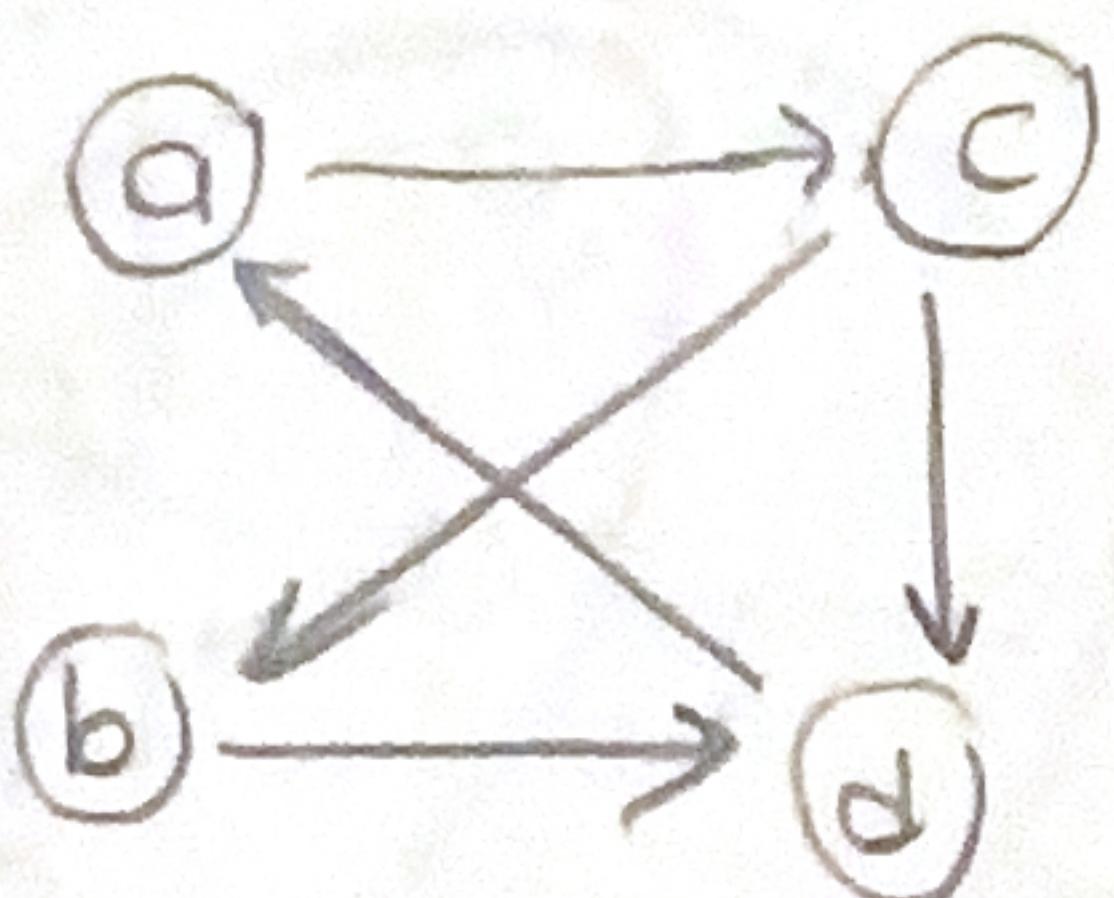
a
b
c

- 2) Check if linked list contains a.



there can be at most $|V|$ items.
 $(O(|V|))$

Adjacency Matrix



Space Complexity = $O(|V|^2)$

	a	b	c	d
a	0	0	1	0
b	0	0	0	1
c	0	1	0	0
d	1	0	0	0

Growth Rate (Time Comp)
of Drawing the Graph = $O(|V|^2)$

↳ list was better

Checking the Edge = $O(1)$

↳ matrix is better

* But it's not wise to compare $|V|^2$ to $|V| + |E|$ we need to know how V relates to E.

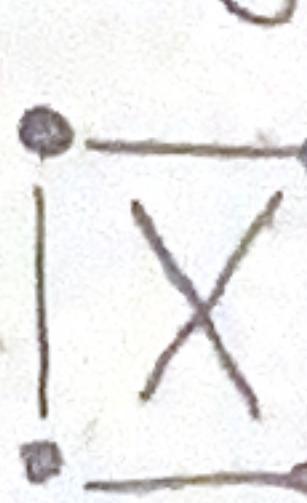
Sparse Graphs

- Vertices & edges are linearly related
- $|V| \approx |E|$
- Number of edges can be at most $|V|-1$



Dense Graphs

- Edges are related to $(\text{vertices})^2$
- $|E| = \frac{|V|(|V|-1)}{2}$ ↳ at most
- $|E| \approx O(|V|^2)$
- worse case (2)



↳ 6