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MODULE pluscal_squareroot
EXTENDS Integers, TLC
CONSTANTS x  x is the input

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-wfNext
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--algorithm squareroot{
variables y1, y2, y3, z;
{
l0: y1 := 0; y2 := 1; y3 := 1;
l1: while ( y2 ≤ x ) {
    l2: y1 := y1 + 1; y2 := y2 + y3 + 2; y3 := y3 + 2;
    } ;
l3: z := y1;
l4: print ⟨x, z, y1, y2, y3⟩;
}
}

```

```
BEGIN TRANSLATION
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CONSTANT defaultInitValue
VARIABLES y1, y2, y3, z, pc

```

```
vars ≜ ⟨y1, y2, y3, z, pc⟩
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Init ≜  Global variables
        ∧ y1 = defaultInitValue
        ∧ y2 = defaultInitValue
        ∧ y3 = defaultInitValue
        ∧ z = defaultInitValue
        ∧ pc = "l0"

```

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l0 ≜  ∧ pc = "l0"
      ∧ y1' = 0
      ∧ y2' = 1
      ∧ y3' = 1
      ∧ pc' = "l1"
      ∧ z' = z

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l1 ≜  ∧ pc = "l1"
      ∧ IF y2 ≤ x
        THEN  ∧ pc' = "l2"
        ELSE  ∧ pc' = "l3"
      ∧ UNCHANGED ⟨y1, y2, y3, z⟩

```

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l2 ≜  ∧ pc = "l2"
      ∧ y1' = y1 + 1
      ∧ y2' = y2 + y3 + 2
      ∧ y3' = y3 + 2

```

$$\begin{aligned}
& \wedge pc' = \text{"l1"} \\
& \wedge z' = z \\
l3 & \triangleq \wedge pc = \text{"l3"} \\
& \wedge z' = y1 \\
& \wedge pc' = \text{"l4"} \\
& \wedge \text{UNCHANGED } \langle y1, y2, y3 \rangle \\
l4 & \triangleq \wedge pc = \text{"l4"} \\
& \wedge \text{PrintT}(\langle x, z, y1, y2, y3 \rangle) \\
& \wedge pc' = \text{"Done"} \\
& \wedge \text{UNCHANGED } \langle y1, y2, y3, z \rangle \\
Next & \triangleq l0 \vee l1 \vee l2 \vee l3 \vee l4 \\
& \vee \text{Disjunct to prevent deadlock on termination} \\
& (pc = \text{"Done"} \wedge \text{UNCHANGED } vars) \\
Spec & \triangleq Init \wedge \Box[Next]_{vars} \\
Termination & \triangleq \Diamond(pc = \text{"Done"}) \\
& \text{END TRANSLATION}
\end{aligned}$$

$$\begin{aligned}
MAX & \triangleq 32768 \quad \text{16 bits} \\
D & \triangleq 0 \dots 32768 \\
& x \leq 32760
\end{aligned}$$

$$Safety_absence \triangleq (y1 \in D) \wedge (y2 \in D) \wedge (y3 \in D) \wedge (z \in D)$$

$$i \triangleq$$

$$\begin{aligned}
& \wedge pc = \text{"l0"} \Rightarrow y1 \in D \wedge y2 \in D \wedge y3 \in D \wedge z \in D \\
& \wedge pc = \text{"l1"} \Rightarrow y2 = (y1 + 1) * (y1 + 1) \wedge y3 = 2 * y1 + 1 \wedge y1 * y1 \leq x \wedge Safety_absence \\
& \wedge pc = \text{"l2"} \Rightarrow y2 = (y1 + 1) * (y1 + 1) \wedge y3 = 2 * y1 + 1 \wedge y1 * y1 \leq x \wedge y2 \leq x \wedge Safety_absence \\
& \wedge pc = \text{"l3"} \Rightarrow y2 = (y1 + 1) * (y1 + 1) \wedge y3 = 2 * y1 + 1 \wedge y1 * y1 \leq x \wedge Safety_absence \\
& \wedge pc = \text{"l4"} \Rightarrow y2 = (y1 + 1) * (y1 + 1) \wedge y3 = 2 * y1 + 1 \wedge y1 * y1 \leq x \wedge x < y2 \wedge Safety_absence \\
& \wedge pc = \text{"l5"} \Rightarrow y2 = (y1 + 1) * (y1 + 1) \wedge y3 = 2 * y1 + 1 \wedge z * z \leq x \wedge x < (z + 1) * (z + 1) \wedge Safety_absence
\end{aligned}$$

$$\begin{aligned}
Safety_partialcorrectness & \triangleq pc = \text{"l5"} \Rightarrow \wedge y2 = (y1 + 1) * (y1 + 1) \\
& \wedge y3 = 2 * y1 + 1 \\
& \wedge z * z \leq x \wedge x < (z + 1) * (z + 1)
\end{aligned}$$