



# Correct by Construction Algorithms by Refinement

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Visit of the Dishui Lake International Software Engineering Institute
at East China Normal University (ECNU) from. 27th October 2025 to 31st October 2025.

## Summary

- Introduction of Correct by Construction by Example
   Detecting overflows in computations
   Computing the velocity of an aircraft on the ground
   Tracking bugs in C codes
- 2 Programming by contract
- 3 Short Summary on Event-B
- 4 Analysis and then Synthesis Analysis using Refinement Synthesis by Merging
- **5** Conclusion

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## Detecting overflows of computations

Listing 1: Function average

```
#include <stdio.h>
#include <limits.h>
int average(int a, int b)
  return ((a+b)/2);
int main()
  int x, y;
  x=INT\_MAX; y=INT\_MAX;
   printf("Average - - for -%d - and -%d - is -%d\n", x, y,
          average(x, v)):
  return 0:
```

#### Execution

## Execution produces a result

Average for 2147483647 and 2147483647 is -1

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## Using frama-c produces a required annotation

```
int average(int a, int b)
{
  int __retres;
  /*@ assert rte: signed_overflow: -2147483648 <= a + b; */
  /*@ assert rte: signed_overflow: a + b <= 2147483647; */
  __retres = (a + b) / 2;
  return __retres;
}</pre>
```

## Annotated Example 1

Listing 2: Function average.....

```
#include <stdio.h>
#include <limits.h>
/*@ requires 0 <= a;
     requires a <= INT_MAX ;
     requires 0 \le b;
     requires b <= INT_MAX ;
     requires 0 \le a+b;
     requires a+b <= INT_MAX ;
     ensures \result <= INT MAX:
*/
int average (int a, int b)
 return((a+b)/2);
int main()
 int x,y;
 x=INT_MAX / 2; y=INT_MAX / 2;
  // printf("Average for %d and %d is %d\n",x,y,
  //
     ):
  return average(x,y);
```

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# Nose Gear Velocity



Estimated ground velocity of the aircraft should be available only if it is within 3 km/hr of the true velocity at some moment within Visit of the Dishui Lake International Software Engineering Institute at East Crime from a Lorent (ESNU) from. 27th October 2025 to 31st October 2025. (Dominique Méry)

# Characterization of a System (I)

- NG velocity system:
  - Hardware:
    - Electro-mechanical sensor: detects rotations
    - Two 16-bit counters: Rotation counter, Milliseconds counter
    - Interrupt service routine: updates rotation counter and stores current time.
  - Software:
    - Real-time operating system: invokes update function every 500 ms
    - 16-bit global variable: for recording rotation counter update time
    - An update function: estimates ground velocity of the aircraft.
- Input data available to the system:
  - time: in milliseconds
    distance: in inches
  - rotation angle: in degrees
- Specified system performs velocity estimations in imperial unit system
- Note: expressed functional requirement is in SI unit system (km/hr).

## Characterization of a System (II) cont

#### What are the main properties to consider for formalization?

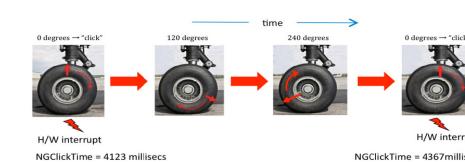
- Two different types of data:
  - counters with modulo semantics
  - non-negative values for time, distance, and velocity
- Two dimensions: distance and time
- Many units: distance (inches, kilometers, miles), time (milliseconds, hours), velocity (kph, mph)
- And interaction among components

#### How should we model?

- Designer needs to consider units and conversions between them to manipulate the model
- One approach: Model units as sets, and conversions as constructed types projections.
- Example:
  - 1  $estimateVelocitu \in \texttt{MILES} \times \texttt{HOURS} \rightarrow \texttt{MPH}$
  - 2  $mphTokph ∈ MPH \longrightarrow KPH$

## Sample Velocity Estimation

NGRotations = 8954



WHEEL\_DIAMETER = 22 inches PI = 3.14

12 inches/foot 5280 feet/mile

estimatedGroundVelocity = distance travel/elapsed time = ((3.14 \* 22)/(12\*5280))/((4367-4123)/(1000\*3600 = 16 mph

NGRotations = 8955

## Safety Property

## Safety Property

- Storing the number of NGClick in a n-bit variable VNGClick
- Integers are denoted by the set Int and is simply defined by the interval Int=INT\_MIN..INT\_MAX.
- lacktriangleright Safety requirement: The value of VNGClick is always in the range of implementation Int or equivalently  $VNGClick \in Int$

## Safety Property

- Storing the number of NGClick in a n-bit variable VNGClick
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- Safety requirement: The value of VNGClick is always in the range of implementation Int or equivalently  $VNGClick \in Int$
- $Length = \pi * diameter * VNGClick$  (mathematical property)
- $Length \le 6000$  (domain property)
- $\pi*diameter*VNGClick \leq 6000$
- $VNGClick \leq 6000/(\pi*diameter)$
- if n=8, then  $2^7-1=127$  and  $6000/(\pi*[22,inch])=6000/(\pi*55,88)=6000/(3,24*[55,88,cm])=6000/(3,24*0.5588) \approx 3419$  and the condition of safety can not be satisfied in any situation.
- if n=16, then  $2^{15}-1=65535$  and  $6000/(\pi*[22,inch])\approx 3419$  and the condition of safety can be satisfied in any situation since  $3419\leq=65535$ .

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$$RTE\_VNGClick : 0 \le vNGClick \le INT\_MAX$$
 (1)

The current value of VNGClick is always bounded by the two values 0 and INT\_MAX.

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## bug0.c

#### Listing 3: Bug bug0

```
#include <stdio.h>
#include <stdiib.h>
#include <stdiib.h>
#include <time.h>

int main() {
    int x, y;
    // Seed the random number generator with the current time
    srand(time(NULL));
    // Generate a random number between 1 and 100
    x = rand() % 100 + 1;
    // Perform some calculations
    y = x / (100 - x);
    printf("Result: %d\n", y);
    return 0;
}
```

#### Listing 4: Bug bug00

```
// Heisenbug
#include <stdio.h>
#include < stdlib . h>
#include <time.h>
int main() {
 int x, y, i=0;
    for (i = 0; i \le 100000; i++) {
    // Seed the random number generator with the current time
    srand(time(NULL));
    // Generate a random number between 1 and 100
   x = rand() \% 100 + 1;
        printf("Result: x= %d\n",x);
    // Perform some calculations
   y = x / (100 - x);
    printf("Result: i=%d and y=%d\n",i, y);
    return 0:
```

#### Listing 5: Bug bug000

```
// Heisenbug
#include <stdio.h>
#include < stdlib . h>
#include <time.h>
int main() {
  int x, y, i=0;
    for (i = 0; i \le 200000; i++) {
    // Seed the random number generator with the current time
    srand(time(NULL)+i):
    // Generate a random number between 1 and 100
   x = rand() \% 100 + 1;
        printf("Result: x= %d\n",x);
    // Perform some calculations
   y = x / (100 - x);
    printf("Result: i=%d %d\n",i, y);
    return 0:
```

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# Verifying program correctness (Run Time Errors, ...)

A program P satisfies a (pre,post) contract:

- P transforms a variable v from initial values  $v_0$  and produces a final value  $v_f \colon v_0 \stackrel{\mathsf{P}}{\longrightarrow} v_f$
- $lackbox{ } {\sf v}_0$  satisfies pre:  ${\sf pre}(v_0)$  and  ${\sf v}_f$  satisfies post :  ${\sf post}(v_0,v_f)$
- D est le domaine RTE de V

# Verifying program correctness (Run Time Errors, ...)

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```
requires pre(v_0) ensures post(v_0, v_f) variables X
\begin{array}{|c|c|c|c|c|c|}\hline & begin & \\ & 0: P_0(v_0, v) & \\ & & instruction_0 & \\ & & \ddots & \\ & & i: P_i(v_0, v) & \\ & & \ddots & \\ & & & instruction_{f-1} & \\ & & f: P_f(v_0, v) & \\ & & end & \end{array}
```

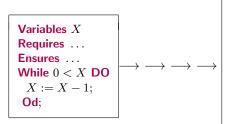
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- $pre(v_0) \wedge v = v_0 \Rightarrow P_0(v_0, v)$
- $pre(v_0) \land P_f(v_0, v) \Rightarrow post(v_0, v)$
- For any pair of labels  $\ell, \ell'$  such that  $\ell \longrightarrow \ell'$ , one verifies that, pour any values  $v, v' \in \text{MEMORY}$   $\left( \begin{array}{c} pre(v_0) \wedge P_\ell(v_0, v)) \\ \wedge cond_{\ell, \ell'}(v) \wedge v' = f_{\ell, \ell'}(v) \\ \Rightarrow P_{\ell'}(v_0, v') \end{array} \right),$
- For any pair of labels m,n such taht  $m \longrightarrow n$ , one verifies that,  $\forall v,v' \in \text{MEMORY}$ :

```
 \begin{tabular}{lll} \textbf{Variables} & X \\ \textbf{Requires} & \dots \\ \textbf{Ensures} & \dots \\ \textbf{While} & 0 < X \ \textbf{DO} \\ & X := X - 1; \\ \textbf{Od}; \\ \end{tabular}
```

```
 \begin{array}{c|c} \textbf{Variables} \ X \\ \textbf{Requires} \ \dots \\ \textbf{Ensures} \ \dots \\ \textbf{While} \ 0 < X \ \textbf{DO} \\ X := X - 1; \\ \textbf{Od}; \end{array} \longrightarrow \longrightarrow
```

```
 \begin{array}{c} \textbf{Variables } X \\ \textbf{Requires } \dots \\ \textbf{Ensures } \dots \\ \textbf{While } 0 < X \ \textbf{DO} \\ X := X - 1; \\ \textbf{Od}; \end{array} \longrightarrow \longrightarrow \longrightarrow \longrightarrow
```



```
 \begin{array}{l} \textbf{Contract} \ EX \\ \textbf{Variables} \ X(int) \\ \textbf{Requires} \ x_0 \in \mathbb{N} \\ \textbf{Ensures} \ x_f = 0 \\ \ell_0 : \{ \ x = x_0 \wedge x_0 \in \mathbb{N} \} \\ \textbf{While} \ 0 < X \ \textbf{DO} \\ \ell_1 : \{ 0 < x \leq x_0 \wedge x_0 \in \mathbb{N} \} \\ X := X - 1; \\ \ell_2 : \{ 0 \leq x \leq x_0 \wedge x_0 \in \mathbb{N} \} \\ \textbf{Od}; \\ \ell_3 : \{ x = 0 \} \end{array}
```

## A Simple C Function

Listing 6: Simple contract

```
/*@ requires \false ;
    @ ensures \false ; */
int f1(int x)
{ if (f1(x) <= 0)
        { return(1);
        }
    else
        { return(0);
        }
}</pre>
```

## A Simple C Function

Listing 7: Simple contract

```
#include <stdio.h>
#include <math.h>
/*@ requires \false;
   @ ensures \false ; */
int f1(int x)
\{ \text{ if } (f1(x) \le 0) \}
     { return (1);
  else
      return(0);
```

## A Simple C Function

Listing 8: Simple contract

```
#include <stdio.h>
#include <math.h>
/*@ requires \false;
   @ ensures \false ; */
int f1(int x)
\{ \text{ if } (f1(x) \le 0) \}
     { return (1);
  else
      return(0);
```

## Correct by Construction

■ Finding or computing annotations is difficult and even undecidable!

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Contract EXVariables X(int)Requires  $pre(x_0)$ 

Given Requires  $pre(x_0)$  Ensures  $post(x_0, x_f)$ 

## Correct by Construction

■ Finding or computing annotations is difficult and even undecidable!

Design of the algorithm ALG fulfiling the contract

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- Design of the algorithm ALG fulfiling the contract
- HOARE triple:

$$\{\mathbf{prex_0}) \land \mathbf{x} = \mathbf{x_0}\}\mathsf{ALG}\{\mathbf{post}(\mathbf{x_0}, \mathbf{x})\}$$

# Correct by Construction

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- Design of the algorithm ALG fulfiling the contract
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## Idea?

From Cntract EX, using a step by step approach to find an algorithm ALG satisfying it using refinement and Event-B models.

Applying the CLEANROOM model but with tooml support (Thanks to Dr Wu!)

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## Short Summary on Event-B (context)

- Context: static properties of Event-B models
  - Sets: user-defined types
  - Constants: static object in development
  - Axioms: presumed properties about sets and constants
  - ▶ Theorems: derived properties about sets and constants

```
SETS A
CONSTANTS B, C, f
AXIOMS ax1: B \subseteq A
ax2: C \subseteq A
ax3: g \in B \rightarrow C
ax4: \forall A.A \subseteq \mathbb{N} \land 0 \in A \land suc[A] \subseteq A \Rightarrow \mathbb{N} \subseteq A
...
```

# Short Summary on Event-B (discrete)

- Machine: behavioral properties of Event-B models
  - Variables: states
  - Invariants: properties of variables that always need to hold
  - ▶ Theorems: derived properties about variables
  - Events: possible state changes

 $\begin{array}{l} \textbf{EVENT e} \\ \textbf{ANY } t \\ \textbf{WHERE} \\ G(c,s,t,x) \\ \textbf{THEN} \\ x: |(P(c,s,t,x,x')) \\ \textbf{END} \end{array}$ 

 $lackbox{ } c$  et s are constantes and visible sets by

- x is a state variable or a list of variabless
- G(c, s, t, x) is the condition for observing e.
- P(c, s, t, x, x') is the assertion for the relation over x and x'.
- BA(e)(c, s, x, x') is the before-after relationship for e and is defined by  $\exists t.G(c, s, t, x) \land P(c, s, t, x, x')$ .

# Short Summary on Event-B (refinement)

- Given an abstract and a corresponding concrete event

EVENT ae  $\ \widehat{=}$  any v where G(x,v) then x:=E(x,v) end

 $\begin{array}{ll} \textbf{EVENT ce} & \widehat{=} \\ \textbf{any } w \textbf{ where} \\ H(y,w) \\ \textbf{then} \\ y := F(y,w) \\ \textbf{end} \end{array}$ 

$$\begin{array}{ccc} I(x) & \wedge & J(x,y) & \wedge & H(y,w) \\ \Longrightarrow & \\ \exists v \cdot (G(x,v) & \wedge & J(E(x,v),F(y,w))) \end{array}$$

- $BA(ae)(x, x') = \exists v. G(x, v) \land x' = E(x)$
- $BA(ce)(y, y') \stackrel{\triangle}{=} \exists w. H(y, w) \land y' = F(y)$

```
MACHINE
 m
SEES
 c
VARIABLES
 x
INVARIANT
 I(x)
THEOREMS
 Q(x)
INITIALISATION
 Init(x)
EVENTS
 ...e
END
```

**MACHINE** mSEES CVARIABLES xINVARIANT I(x)THEOREMS Q(x)INITIALISATION Init(x)EVENTS ...e **END** 

 ${\it c}$  defines the static environment for the proofs related to m: sets, constants, axioms, theorems  $\Gamma(m)$ .

# mSEES cVARIABLES

INVARIANT

I(x)

x

THEOREMS

Q(x)

INITIALISATION

Init(x)

EVENTS

 $\dots e$ 

**END** 

c defines the static environment for the proofs related to m: sets, constants, axioms, theorems  $\Gamma(m)$ .  $\Gamma(m) \vdash \forall x \in Values : \mathrm{INIT}(x) \Rightarrow \mathrm{I}(x)$ 

#### **MACHINE**

m

#### SEES

c

#### VARIABLES

x

#### INVARIANT

I(x)

#### THEOREMS

Q(x)

## INITIALISATION

Init(x)

## EVENTS

 $\dots e$ 

**END** 

 ${\it c}$  defines the static environment for the proofs related to m: sets, constants, axioms, theorems  $\Gamma(m)$ .

$$\Gamma(m) \vdash \forall x \in Values : Init(x) \Rightarrow I(x)$$

 $\forall e:$ 

$$\Gamma(m) \vdash \forall x, x', u \in Values : \mathcal{I}(x) \land R(u, x, x') \Rightarrow \mathcal{I}(x')$$

#### **MACHINE**

m

#### SEES

c

#### VARIABLES

 $\boldsymbol{x}$ 

## INVARIANT

I(x)

## THEOREMS

Q(x)

## INITIALISATION

Init(x)

## EVENTS

 $\dots e$ 

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$$\Gamma(m) \vdash \forall x \in Values : I(x) \Rightarrow Q(x)$$

## MACHINE mSEES CVARIABLES xINVARIANT I(x)THEOREMS Q(x)INITIALISATION Init(x)EVENTS ...e

END

```
{\color{blue}c} defines the static environment for the proofs related to m: sets, constants, axioms, theorems \Gamma(m). \Gamma(m) \vdash \forall x \in Values : \mathrm{INIT}(x) \Rightarrow \mathrm{I}(x) \forall e : \\ \Gamma(m) \vdash \forall x, x', u \in Values : \mathrm{I}(x) \land R(u, x, x') \Rightarrow \mathrm{I}(x') \Gamma(m) \vdash \forall x \in Values : \mathrm{I}(x) \Rightarrow \mathrm{Q}(x)
```

```
ANY u WHERE G(x,u) THEN x:|(R(u,x,x')) END
```

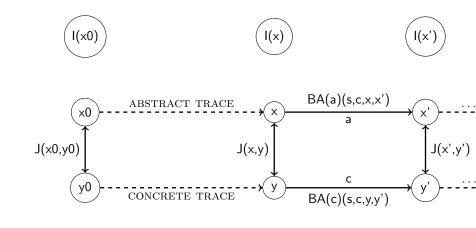
or e is observed  $x \stackrel{e}{\longrightarrow} x'$ 

## **Event B Structure and Proofs**

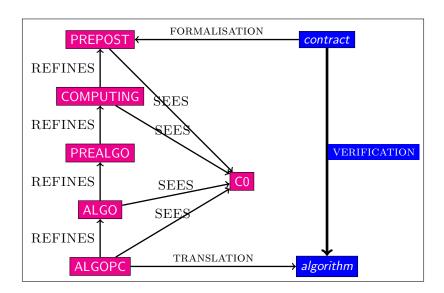
CONTEXT	MACHINE
ctxt_id_2	machine_id_2
EXTENDS	REFINES
ctxt_id_1	machine_id_1
SETS	SEES
s	ctxt_id_2
CONSTANTS	VARIABLES
c	v
AXIOMS	INVARIANTS
A(s,c)	I(s,c,v)
THEOREMS	THEOREMS
$T_c(s,c)$	$T_m(s,c,v)$
END	VARIANT
	V(s,c,v)
	EVENTS
	EVENT e
	any x
	where $G(s, c, v, x)$
	then
	v:  BA(s, c, v, x, v')
	end
	END

Invariant	$A(s,c) \wedge I(s,c,v)$
preservation	$\wedge G(s, c, v, x)$
	$\wedge BA(s,c,v,x,v')$
	$\Rightarrow I(s, c, v')$
Event	$A(s,c) \wedge I(s,c,v)$
feasibility	$\wedge G(s, c, v, x)$
	$\Rightarrow \exists v'.BA(s,c,v,x,v')$
Variant	$A(s,c) \wedge I(s,c,v)$
modelling	$\wedge G(s, c, v, x)$
progress	$\wedge BA(s, c, v, x, v')$
	$\Rightarrow V(s, c, v') < V(s, c, v)$
Theorems	$A(s,c) \Rightarrow T_c(s,c)$
	$A(s,c) \wedge I(s,c,v)$
	$\Rightarrow T_m(s,c,v)$

## Refinement between two machines



## The Iterative Pattern



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## Computing two sums

## First n numbers and first odd/even numbers

- First the **pre/post specification** . . .
- Possibility to use a programming language with contracts too

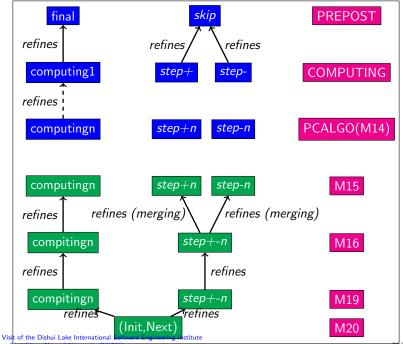
## Computing two sums

## First n numbers and first odd/even numbers

- First the **pre/post specification** ...
- Possibility to use a programming language with contracts too

$$\begin{array}{l} \text{requires } input_0 \geq 0 \wedge rs_0, re_0 \in \mathbb{Z} \\ \text{ensures } \left\{ \begin{array}{l} rs_f = s(input_0) \\ re_f = es(input_0) \\ input_f = input_0 \end{array} \right. \\ \text{variables input, re, rs} \end{array}$$

- Find two sequences s and es computing the sum of first n natural numbers and first even numbers smaller than n
- Prove that:
  - $\forall n.n \in \mathbb{N} \Rightarrow s(n) = \sum_{i=0}^{i=n} i.$
  - $\forall n.n \in \mathbb{N} \Rightarrow es(n) = \sum_{i=0}^{i=n/2} 2 * i.$



# Defining the sequences and proving

# First n numbers and first odd/even numbers

```
axm1: n \in \mathbb{N}
axm2: s \in \mathbb{N} \to \mathbb{N} \land os \in \mathbb{N} \to \mathbb{N} \land es \in \mathbb{N} \to \mathbb{N}
axm3 : es(0) = 0 \land os(0) = 0 \land s(0) = 0
axm6: suc \in \mathbb{N} \to \mathbb{N} \land (\forall i \cdot i \in \mathbb{N} \Rightarrow suc(i) = i+1)
axm7: \forall A \cdot A \subseteq \mathbb{N} \land 0 \in A \land suc[A] \subseteq A \Rightarrow \mathbb{N} \subseteq A
th1: \forall i \cdot i \in \mathbb{N} \Rightarrow s(i+1) = s(i) + i + 1
th2: \forall u, v \cdot u \in \mathbb{N} \land v \in \mathbb{N} \land 2 * u = v \Rightarrow u = v/2
th3: \forall k \cdot k \in \mathbb{N} \Rightarrow 2 * s(k) = k * k + k
th4: \forall k \cdot k \in \mathbb{N} \Rightarrow s(k) = (k * k + k)/2
th5: \forall k \cdot k \in \mathbb{N} \Rightarrow es(2 * k) = 2 * s(k)
th6: \forall k \cdot k \in \mathbb{N} \Rightarrow es(2 * k + 1) = 2 * s(k)
th7: \forall k \cdot k \in \mathbb{N} \land k \neq 0 \Rightarrow os(2 * k) = k * k
```

 $th8: \forall k \cdot k \in \mathbb{N} \Rightarrow os(2 * k + 1) = (k + 1) * (k + 1)$ 

# Stating the pre/post specification in Event-B

#### INVARIANTS

```
\begin{array}{l} inv1: input \in \mathbb{Z} \\ inv6: input = n \end{array}
```

 $inv2: rs \in \mathbb{Z} \land re \in \mathbb{Z}$  $inv3: ok \in BOOL$ 

 $inv4: ok = TRUE \Rightarrow rs = s(input) \land re = es(input)$ 

# Stating the pre/post specification in Event-B

## then

```
 \begin{aligned} &act1:ok:=FALSE\\ &act2:rs:\in\mathbb{Z}\\ &act3:re:\in\mathbb{Z}\\ &act4:input:=n \end{aligned}
```

## **EVENT** computing

#### when

```
grd1:ok=FALSE
```

#### then

```
\begin{split} &act1:rs:=s(input)\\ &act2:ok:=TRUE\\ &act3:re:=es(input) \end{split}
```

# Refining for computing (1)

#### INVARIANTS

```
\begin{split} &inv1: cur \in 0 \dots n \\ &inv2: ee \in 0 \dots n \to \mathbb{N} \\ &inv3: ss \in 0 \dots n \to \mathbb{N} \\ &inv5: dom(ss) = 0 \dots cur \wedge dom(ee) = dom(ss) \wedge dom(ss) \subseteq \mathbb{N} \\ &inv6: \forall i \cdot i \in 0 \dots cur \Rightarrow ee(i) = es(i) \wedge ss(i) = s(i) \end{split}
```

## Variant

## then

```
 \begin{aligned} &act1:ok := FALSE \\ &act2:rs : \in \mathbb{Z} \\ &act3:re : \in \mathbb{Z} \\ &act4:input := n \\ &act5:ee := \{0 \mapsto 0\} \\ &act6:ss := \{0 \mapsto 0\} \\ &act7:cur := 0 \end{aligned}
```

# Refining for computing (2)

## **EVENT** computing11

## when

```
grd1: ok = FALSE

grd2: cur = n
```

#### then

```
 \begin{aligned} &act1:rs:=ss(input)\\ &act2:ok:=TRUE\\ &act3:re:=ee(input) \end{aligned}
```

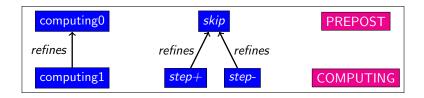
# Refining for computing (3)

```
EVENT step11+
Any
 k
when
 qrd1: ok = FALSE
 qrd2: k \in \mathbb{N} \wedge cur = 2 * k + 1
 qrd3: cur < n
 qrd4: cur < n
then
 act1: ss(cur + 1) := ss(cur) + cur + 1
 act2: ee(cur + 1) := ee(cur) + cur + 1
 act3: cur := cur + 1
```

# Refining for computing (4)

```
EVENT step11=
Any
 k.
when
 qrd1: ok = FALSE
 grd2: k \in \mathbb{N} \wedge cur = 2 * k
 qrd3: cur < n
then
 act1: ss(cur + 1) := ss(cur) + cur + 1
 act2: ee(cur + 1) := ee(cur)
 act3: cur := cur + 1
```

# Diagram of events



```
MACHINE M1 SEES C0
```

#### **VARIABLES**

input, rs, re, ok,

#### **INVARIANTS**

 $inv1: input \in \mathbb{Z}$ inv6: input = n

 $inv2: rs \in \mathbb{Z} \wedge re \in \mathbb{Z}$   $inv3: ok \in BOOL$ 

 $inv4:ok=TRUE\Rightarrow rs=s(input)\land re=es(input)$ 

#### MACHINE M11 SEES C0

#### VARIABLES

input, rs, re, ok, ee, ss, cur,

#### INVARIANTS

 $inv1 : cur \in 0 ... n$   $inv2 : ee \in 0 ... n \rightarrow \mathbb{N}$  $inv3 : ss \in 0 ... n \rightarrow \mathbb{N}$ 

 $inv5: dom(ss) = 0 \ldots cur \wedge dom(ee) = dom(ss) \wedge dom(ss) \subseteq \mathbb{N}$ 

 $inv6: \forall i \cdot i \in 0 ... cur \Rightarrow ee(i) = es(i) \land ss(i) = s(i)$ 

## MACHINE M12 SEES C0

#### VARIABLES

input, rs, re, ok, ee, ss, cur, cs, ce,

#### INVARIANTS

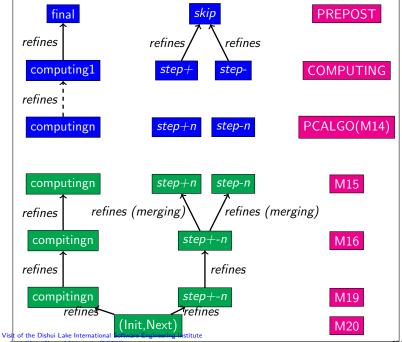
inv1: cs = ss(cur)inv2: ce = ee(cur)

# MACHINE M13 SEES C0 VARIABLES

input, rs, re, ok, ee, ss, cur, cs, ce,INVARIANTS

inv1: cs = ss(cur) inv2: ce = ee(cur) inv4: ce = es(cur)inv3: cs = s(cur)

```
MACHINE M14 SEES C0,C1 VARIABLES input, rs, re, cur, cs, ce, l, INVARIANTS inv1: cs = s(cur) inv5: l = start \Leftrightarrow ok = FALSE inv6: l = end \Leftrightarrow ok = TRUE inv2: cs = s(cur) inv3: l \in L inv4: l = end \Rightarrow re = es(n) \land rs = s(n)
```



# Generation of an algorithm from M14

## Translation from Evenrts

```
struct sums codesum(int n)
{int k,ce,cs; struct sums r;
  r.s=0:r.se=0:k=0:ce=0:cs=0:
  while (k<n)
      if (k \% 2 != 0)
       \{ ce = ce + k + 1; cs = cs + k + 1; k = k + 1; \}
      else
       \{ ce = ce ; cs = cs +k+1; k = k +1; \}
  r.s=cs; r.se=ce;
  return(r);
```

#### Generation of an algorithm from M14

Improving and checking with Frama-c

```
#include "structure.h"
#include "trans-even.h"
struct sums codesum(int n)
{int k,ce,cs; struct sums r;
  r.s=0; r.se=0; k=0; ce=0; cs=0;
  /*@ loop invariant k \ge 0 && k \le n && mathsum(k) == cs;
    @ loop invariant ((k \% 2 = 0) \Longrightarrow (mathse(k) = ce));
    \emptyset loop invariant ((k \% 2 != 0) \Longrightarrow (mathse(k) == ce));
    loop assigns k, ce, cs;
    loop variant n-k:
   */
  while (k<n)
       if (k \% 2 != 0)
        \{ ce = ce + k + 1; cs = cs + k + 1; k = k + 1; \}
      else
        \{ ce = ce ; cs = cs + k+1; k = k +1; \}
```

#### Generation of an algorithm from M14

flom. 27th October 2025 to 31st October 2025. (Dominique Méry)

Improving and checking with Frama-c

```
#include "structure.h"
#include "trans-even.h"
struct sums codesum(int n)
{int k,ce,cs; struct sums r;
   r.s=0; r.se=0; k=0; ce=0; cs=0;
  /*@ loop invariant k \ge 0 && k \le n && mathsum(k) == cs;
     @ loop invariant ((k \% 2 = 0) \Longrightarrow (mathse(k) = ce));
     \emptyset loop invariant ((k \% 2 != 0) \Longrightarrow (mathse(k) == ce));
     loop assigns k, ce, cs;
     loop variant n-k;
    */
   while (k<n)
        if (k \% 2 != 0)
          \{ ce = ce + k + 1; \}
        cs = cs + k+1; k = k +1;
 cp trabs-e* }
   r.s=cs;r.se=ce;
Visit of the Disbui Lake International Software Engineering Institute at East China Normal University (ECNU)
```

# Generation of an algorithm from M14

Using the Plugin EB2Algo

```
rs :∈ Z | |
re :∈ Z ||
input = n | I |
cur = 0 II
ce = 0 II
cs = 0
while cur≠n do
    if cur mod 2≠0 then
         cur = cur + 1 | I |
         cs = cs + cur + 1 | I |
         ce = ce+cur+1
    else
         cur = cur + 1 | I |
         cs = cs + cur + 1 | I |
```

## **Current Summary**

- Introduction of Correct by Construction by Example
   Detecting overflows in computations
   Computing the velocity of an aircraft on the ground
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- 2 Programming by contract
- **3** Short Summary on Event-B
- 4 Analysis and then Synthesis
  Analysis using Refinement
  Synthesis by Merging
- **6** Conclusion

## Merging events

# $\begin{aligned} & \textbf{EVENT e1} \\ & \textbf{any} \\ & x \\ & \textbf{where} \\ & G1(s,c,x,u) \\ & \textbf{then} \\ & u: |(R(s,c,x,u,u')) \\ & \textbf{end} \end{aligned}$

```
EVENT e2 any x where G2(s,c,x,u) then u:|(R(s,c,x,u,u')) end
```

# Merging events

```
\begin{aligned} & \textbf{EVENT e1} \\ & \textbf{any} \\ & x \\ & \textbf{where} \\ & & G1(s,c,x,u) \\ & \textbf{then} \\ & & u: |(R(s,c,x,u,u')) \\ & \textbf{end} \end{aligned}
```

```
EVENT e refines\ e1, e2 any x where H(s,c,x,u) then u:|(R(s,c,x,u,u')) end
```

```
EVENT e2 any x where G2(s,c,x,u) then u:|(R(s,c,x,u,u')) end
```

# Merging events

# $\begin{array}{l} \textbf{EVENT e1}\\ \textbf{any}\\ x\\ \textbf{where}\\ G1(s,c,x,u)\\ \textbf{then}\\ u:|(R(s,c,x,u,u'))\\ \textbf{end} \end{array}$

```
EVENT e refines\ e1, e2 any x where H(s,c,x,u) then u:|(R(s,c,x,u,u')) end
```

```
EVENT e2 any x where G2(s,c,x,u) then u:|(R(s,c,x,u,u')) end
```

#### Checking the Proof Obligation:

$$Ax(s,c), I(s,c,u), H(s,c,x,u) \vdash G1(s,c,x,u) \lor G2(s,c,x,u)$$

# Synthesis Phase

Preparing merging by transforming actions.

```
EVENT e any x where G(s,c,x,u) then u:|(R(s,c,x,u,u')) end
```

```
EVENT f refines e any x where G(s,c,x,u) then u:|(G(s,c,x,u)\Rightarrow R(s,c,x,u,u')) end
```

- Internalizing the action as a before after relation
- $G(s,c,x,u) \wedge (G(s,c,x,u) \Rightarrow R(s,c,x,u,u')) \Leftrightarrow G(s,c,x,u) \wedge R(s,c,x,u,u')$

## Synthesis Phase

Preparing merging by transforming actions.

```
EVENT e any x where G(s,c,x,u) then u:|(R(s,c,x,u,u')) end
```

```
EVENT f refines e any x where G(s,c,x,u) then u:|(G(s,c,x,u)\Rightarrow R(s,c,x,u,u')) end
```

- $G(s,c,x,u) \wedge (G(s,c,x,u) \Rightarrow R(s,c,x,u,u')) \Leftrightarrow G(s,c,x,u) \wedge R(s,c,x,u,u')$
- $A(s,c,u) \wedge I(s,c,u) \wedge BA(f)(s,c,u,u') \Rightarrow I(s,c,u') \wedge BA(e)(s,c,u,u')$

## Synthesis Phase

Preparing merging by transforming actions.

```
EVENT e any x where G(s,c,x,u) then u:|(R(s,c,x,u,u')) end
```

```
EVENT f refines e any x where G(s,c,x,u) then u:|(G(s,c,x,u)\Rightarrow R(s,c,x,u,u')) end
```

- $G(s,c,x,u) \wedge (G(s,c,x,u) \Rightarrow R(s,c,x,u,u')) \Leftrightarrow G(s,c,x,u) \wedge R(s,c,x,u,u')$
- $A(s, c, u) \land I(s, c, u) \land BA(f)(s, c, u, u') \Rightarrow I(s, c, u') \land BA(e)(s, c, u, u')$
- $A(s,c,u) \wedge I(s,c,u) \wedge G(s,c,x,u) \wedge (G(s,c,x,u) \Rightarrow R(s,c,x,u,u')) \Rightarrow I(s,c,u') \wedge G(s,c,x,u) \wedge R(s,c,x,u,u')$

MACHINE M15 SEES C0, C1 VARIABLES

MACHINE M16 SEES C0, C1 VARIABLES

MACHINE M17 SEES C0, C1 VARIABLES

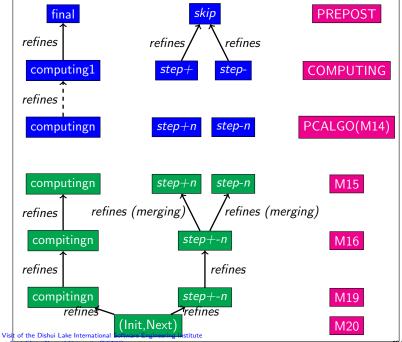
MACHINE M18 SEES C0, C1 VARIABLES

MACHINE M19 SEES C0, C1 VARIABLES

MACHINE M20 SEES C0, C1 VARIABLES

# Generating a TLA specification

```
next1 ==
      /\ (cur'=cur+1 /\ ce'=ce /\ l'=l
      /\ cs'=cs+cur+1 /\ re'=re /\ rs'=rs)
0
delsnext2 ==
      (l="start" /\ cur < n /\ (cur % 2 # 0))
      /\ (cur'=cur+1 /\ ce'=ce+cur+1 /\ l'=l
      /\ cs'=cs+cur+1 /\ re'=re /\ rs'=rs)
next.3 ==
  (l="start" /\ cur=n) /\ (rs'=cs /\ re'=ce
  /\ l'="end" /\ cur'=cur /\ cs'=cs/\ ce'=ce)
Next ==
      (next1 \/ next2 \/ next3)
Init == l="start" \wedge cur=0 \wedge rs=0 \wedge cs=0 \wedge re=0 \wedge ce =0
Visit of the Dishui Lake International Software Engineering Institute
```



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#### Conclusion

- Paradigm for planning refinements.
- Teaching why and how sequential algorithms are working.
- Relating Event-B to TLA
- Application to controller synthesis: events versus operations.

#### Conclusion

- Paradigm for planning refinements.
- Teaching why and how sequential algorithms are working.
- Relating Event-B to TLA
- Application to controller synthesis: events versus operations.

#### Next

- Atlas of correct-by-construction sequential algorithms
- Definition of link between events and codes
- Integration of Cyclone for validating Event-B models

#### Case studies

#### Case studies

- primes
- binary search
- **power functions:**  $x^n$
- gcd
- fibonacci-like functions

