

Correct by Construction Algorithms by Refinement

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Summary

① Introduction of Correct by Construction by Example

Detecting overflows in computations

Computing the velocity of an aircraft on the ground

Tracking bugs in C codes

② Programming by contract

③ Short Summary on Event-B

④ Analysis and then Synthesis

Analysis using Refinement

Synthesis by Merging

⑤ Conclusion

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- 5 Conclusion

Detecting overflows of computations

Listing 1: Function average

```
#include <stdio.h>
#include <limits.h>
int average(int a,int b)
{
    return ((a+b)/2);
}

int main()
{
    int x,y;
    x=INT_MAX;y=INT_MAX;
    printf(" Average - - for -%d - and -%d - is -%d\n",x,y,
        average(x,y));
    return 0;
}
```

Execution produces a result

Average for 2147483647 and 2147483647 is -1

Execution produces a result

Average for 2147483647 and 2147483647 is -1

Using frama-c produces a required annotation

```
int average(int a, int b)
{
    int __retres;
    /*@ assert rte: signed_overflow: -2147483648 <= a + b; */
    /*@ assert rte: signed_overflow: a + b <= 2147483647; */
    __retres = (a + b) / 2;
    return __retres;
}
```

Annotated Example 1

Listing 2: Function average.....

```
#include <stdio.h>
#include <limits.h>
/*@ requires 0 <= a;
    requires a <= INT_MAX ;
    requires 0 <= b;
    requires b <= INT_MAX ;
    requires 0 <= a+b;
    requires a+b <= INT_MAX ;
    ensures \result <= INT_MAX;

*/
int average(int a,int b)
{
    return((a+b)/2);
}

int main()
{
    int x,y;
    x=INT_MAX / 2;y=INT_MAX / 2;
    // printf("Average for %d and %d is %d\n",x,y,
    //      );
    return average(x,y);
}
```


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Nose Gear Velocity



- Estimated ground velocity of the aircraft should be available only if it is within 3 km/hr of the true velocity at some moment within past 3 seconds

Characterization of a System (I)

■ NG velocity system:

▶ **Hardware:**

- *Electro-mechanical sensor*: detects rotations
- *Two 16-bit counters*: Rotation counter, Milliseconds counter
- *Interrupt service routine*: updates rotation counter and stores current time.

▶ **Software:**

- *Real-time operating system*: invokes update function every 500 ms
- *16-bit global variable*: for recording rotation counter update time
- *An update function*: estimates ground velocity of the aircraft.

■ Input data available to the system:

- ▶ *time*: in milliseconds
- ▶ *distance*: in inches
- ▶ *rotation angle*: in degrees

■ Specified system performs velocity estimations in *imperial* unit system

■ **Note**: expressed functional requirement is in *SI* unit system (km/hr).

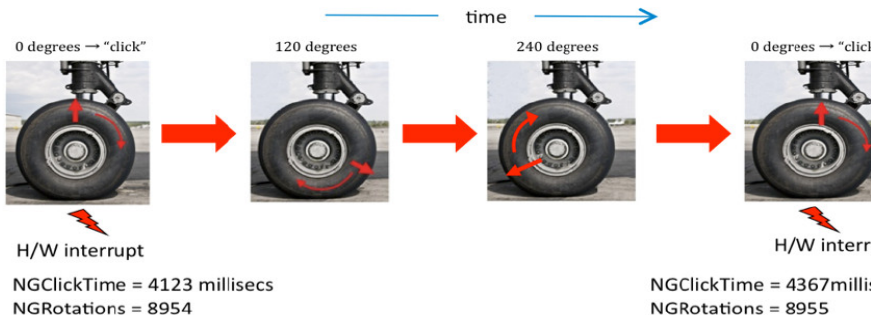
What are the main properties to consider for formalization?

- Two different types of data:
 - ▶ counters with modulo semantics
 - ▶ non-negative values for time, distance, and velocity
- Two dimensions: *distance* and *time*
- Many units: distance (inches, kilometers, miles), time (milliseconds, hours), velocity (kph, mph)
- And interaction among components

How should we model?

- Designer needs to consider units and conversions between them to manipulate the model
- One approach: Model units as *sets*, and conversions as constructed types – *projections*.
- Example:
 - 1 $estimateVelocity \in \text{MILES} \times \text{HOURS} \rightarrow \text{MPH}$
 - 2 $mphTokph \in \text{MPH} \rightarrow \text{KPH}$

Sample Velocity Estimation



WHEEL_DIAMETER = 22 inches
PI = 3.14

12 inches/foot
5280 feet/mile

$$\begin{aligned}\text{estimatedGroundVelocity} &= \text{distance travel/elapsed time} \\ &= ((3.14 * 22)/(12*5280))/((4367-4123)/(1000*3600)) \\ &= 16 \text{ mph}\end{aligned}$$

Safety Property

Safety Property

- Storing the number of `NGClick` in a n-bit variable `VNGClick`
 - Integers are denoted by the set *Int* and is simply defined by the interval $Int \hat{=} INT_MIN..INT_MAX$.
 - Safety requirement:
*The value of `VNGClick` is always in the range of implementation *Int* or equivalently $VNGClick \in Int$*
-

Safety Property

- Storing the number of *NGClick* in a *n*-bit variable *VNGClick*
- Integers are denoted by the set *Int* and is simply defined by the interval $Int \hat{=} INT_MIN..INT_MAX$.
- Safety requirement:
The value of VNGClick is always in the range of implementation Int
or equivalently $VNGClick \in Int$

■ $Length = \pi * diameter * VNGClick$ (**mathematical property**)

■ $Length \leq 6000$ (**domain property**)

■ $\pi * diameter * VNGClick \leq 6000$

■ $VNGClick \leq 6000 / (\pi * diameter)$

- if $n=8$, then $2^7 - 1 = 127$ and $6000 / (\pi * [22, inch]) = 6000 / (\pi * 55, 88) = 6000 / (3, 24 * [55, 88, cm]) = 6000 / (3, 24 * 0.5588) \approx 3419$ and the condition of safety can not be satisfied in any situation.

- if $n=16$, then $2^{15} - 1 = 65535$ and $6000 / (\pi * [22, inch]) \approx 3419$ and the condition of safety can be satisfied in any situation since $3419 \leq 65535$.

Safety Property

- Storing the number of `NGClick` in a n-bit variable `VNGClick`
- Integers are denoted by the set *Int* and is simply defined by the interval $Int \hat{=} INT_MIN..INT_MAX$.
- Safety requirement:
The value of `VNGClick` is always in the range of implementation `Int` or equivalently $VNGClick \in Int$

$$RTE_VNGClick : 0 \leq vNGClick \leq INT_MAX \quad (1)$$

- The current value of `VNGClick` is always bounded by the two values 0 and `INT_MAX`.

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Verifying program correctness (Run Time Errors, ...)

A program P *satisfies* a (pre,post) contract:

- P transforms a variable v from initial values v_0 and produces a final value v_f : $v_0 \xrightarrow{P} v_f$
- v_0 satisfies pre: $\text{pre}(v_0)$ and v_f satisfies post : $\text{post}(v_0, v_f)$
- $\text{pre}(v_0) \wedge v_0 \xrightarrow{P} v_f \Rightarrow \text{post}(v_0, v_f)$
- \mathbb{D} est le domaine RTE de V

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- \mathbb{D} est le domaine RTE de V

```

requires  $\text{pre}(v_0)$ 
ensures  $\text{post}(v_0, v_f)$ 
variables  $X$ 
[
  begin
    0 :  $P_0(v_0, v)$ 
    instruction0
    ...
    i :  $P_i(v_0, v)$ 
    ...
    instructionf-1
    f :  $P_f(v_0, v)$ 
  end

```

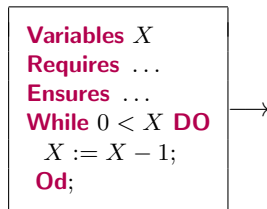
- $\text{pre}(v_0) \wedge v = v_0 \Rightarrow P_0(v_0, v)$
- $\text{pre}(v_0) \wedge P_f(v_0, v) \Rightarrow \text{post}(v_0, v)$
- For any pair of labels ℓ, ℓ' such that $\ell \longrightarrow \ell'$, one verifies that, pour any values $v, v' \in \text{MEMORY}$

$$\left(\begin{array}{l} \text{pre}(v_0) \wedge P_\ell(v_0, v) \\ \wedge \text{cond}_{\ell, \ell'}(v) \wedge v' = f_{\ell, \ell'}(v) \end{array} \right) \Rightarrow P_{\ell'}(v_0, v')$$
- For any pair of labels m, n such taht $m \longrightarrow n$, one verifies that, $\forall v, v' \in \text{MEMORY}$:
$$\text{pre}(v_0) \wedge P_m(v_0, v) \Rightarrow \mathbf{DOM}(m, n)(v)$$

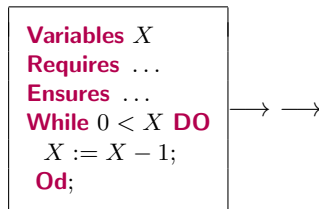
Example of an annotation

```
Variables  $X$   
Requires ...  
Ensures ...  
While  $0 < X$  DO  
   $X := X - 1$ ;  
Od;
```

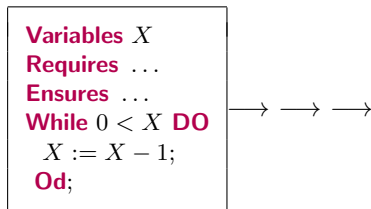
Example of an annotation



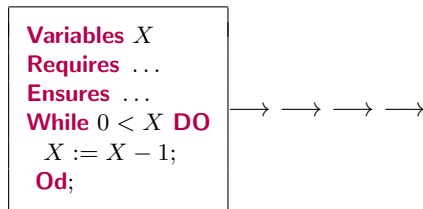
Example of an annotation



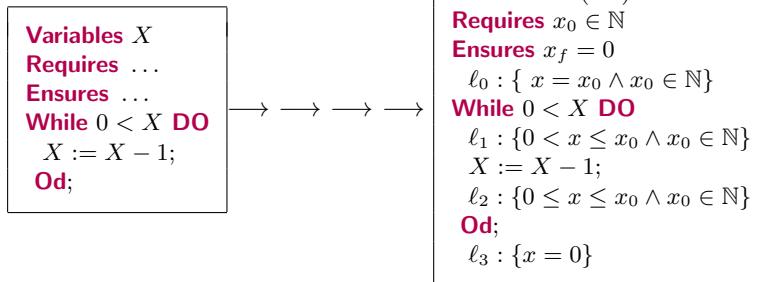
Example of an annotation



Example of an annotation



Example of an annotation



A Simple C Function

Listing 3: Simple contract

```
/*@ requires  \false ;  
   @ ensures  \false ; */  
int f1(int x)  
{ if (f1(x) <= 0)  
    { return(1);  
    }  
  else  
    { return(0);  
    }  
}
```

A Simple C Function

Listing 4: Simple contract

```
#include <stdio.h>
#include <math.h>

/*@ requires \false ;
    @ ensures \false ; */
int f1(int x)
{ if (f1(x) <= 0)
    { return(1);
    }
  else
    { return(0);
    }
}
```

A Simple C Function

Listing 5: Simple contract

```
#include <stdio.h>
#include <math.h>

/*@ requires \false ;
    @ ensures \false ; */
int f1(int x)
{ if (f1(x) <= 0)
    { return(1);
    }
  else
    { return(0);
    }
}
```

- Finding or computing annotations is difficult and even undecidable!

Correct by Construction

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- Given

Contract EX
Variables $X(int)$
Requires $pre(x_0)$
Ensures $post(x_0, x_f)$

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- Design of the algorithm ALG fulfilling the contract

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Contract EX
Variables $X(int)$
Requires $pre(x_0)$
Ensures $post(x_0, x_f)$

- Design of the algorithm ALG fulfilling the contract
- HOARE triple:

$$\{\mathbf{pre}(\mathbf{x}_0) \wedge \mathbf{x} = \mathbf{x}_0\} \text{ALG} \{\mathbf{post}(\mathbf{x}_0, \mathbf{x})\}$$

Correct by Construction

- Finding or computing annotations is difficult and even undecidable!

- Given

Contract EX
Variables $X(int)$
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- HOARE triple:

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Idea?

From Contract EX , using a step by step approach to find an algorithm ALG satisfying it using refinement and Event-B models.
Applying the CLEANROOM model!

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Short Summary on Event-B (context)

- Context: static properties of Event-B models
 - ▶ Sets: user-defined types
 - ▶ Constants: static object in development
 - ▶ Axioms: presumed properties about sets and constants
 - ▶ Theorems: derived properties about sets and constants

SETS

A

CONSTANTS

B, C, f

AXIOMS

$ax1 : B \subseteq A$

$ax2 : C \subseteq A$

$ax3 : g \in B \rightarrow C$

$ax4 : \forall A. A \subseteq \mathbb{N} \wedge 0 \in A \wedge suc[A] \subseteq A \Rightarrow \mathbb{N} \subseteq A$

...

Short Summary on Event-B (discrete)

■ Machine: behavioral properties of Event-B models

- ▶ Variables: states
- ▶ Invariants: properties of variables that always need to hold
- ▶ Theorems: derived properties about variables
- ▶ Events: possible state changes

■ c et s are constantes and visible sets by e

EVENT e

ANY t

WHERE

$G(c, s, t, x)$

THEN

$x : |(P(c, s, t, x, x'))$

END

■ x is a state variable or a list of variables

■ $G(c, s, t, x)$ is the condition for observing e .

■ $P(c, s, t, x, x')$ is the assertion for the relation over x and x' .

■ $BA(e)(c, s, x, x')$ is the *before-after* relationship for e and is defined by $\exists t. G(c, s, t, x) \wedge P(c, s, t, x, x')$.

Short Summary on Event-B (refinement)

- Given an **abstract** and a corresponding **concrete** event

EVENT $ae \hat{=}$
any v **where**
 $G(x, v)$
then
 $x := E(x, v)$
end

EVENT $ce \hat{=}$
any w **where**
 $H(y, w)$
then
 $y := F(y, w)$
end

$$\begin{aligned} & I(x) \wedge J(x, y) \wedge H(y, w) \\ \implies & \exists v \cdot (G(x, v) \wedge J(E(x, v), F(y, w))) \end{aligned}$$

- $BA(ae)(x, x') \hat{=} \exists v. G(x, v) \wedge x' = E(x, v)$
- $BA(ce)(y, y') \hat{=} \exists w. H(y, w) \wedge y' = F(y, w)$

Modelling systems in Event-B

Modelling systems in Event-B

MACHINE

m

SEES

c

VARIABLES

x

INVARIANT

$I(x)$

THEOREMS

$Q(x)$

INITIALISATION

$Init(x)$

EVENTS

$\dots e$

END

Modelling systems in Event-B

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END

c defines the static environment for the proofs related to m : sets, constants, axioms, theorems $\Gamma(m)$.

Modelling systems in Event-B

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$$\Gamma(m) \vdash \forall x \in Values : \text{INIT}(x) \Rightarrow I(x)$$

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c defines the static environment for the proofs related to m : sets, constants, axioms, theorems $\Gamma(m)$.

$\Gamma(m) \vdash \forall x \in Values : \text{INIT}(x) \Rightarrow I(x)$

$\forall e :$

$\Gamma(m) \vdash \forall x, x', u \in Values : I(x) \wedge R(u, x, x') \Rightarrow I(x')$

Modelling systems in Event-B

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$\Gamma(m) \vdash \forall x \in Values : I(x) \Rightarrow Q(x)$

e

ANY

u

WHERE

$G(x, u)$

THEN

$x : |(R(u, x, x'))|$

END

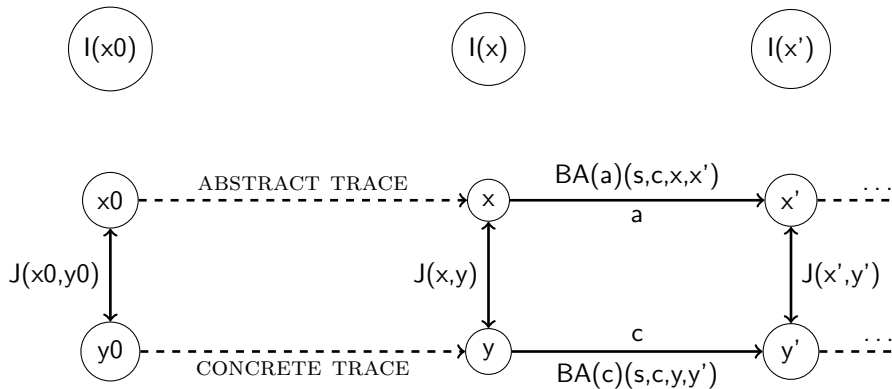
or e is **observed** $x \xrightarrow{e} x'$

Event B Structure and Proofs

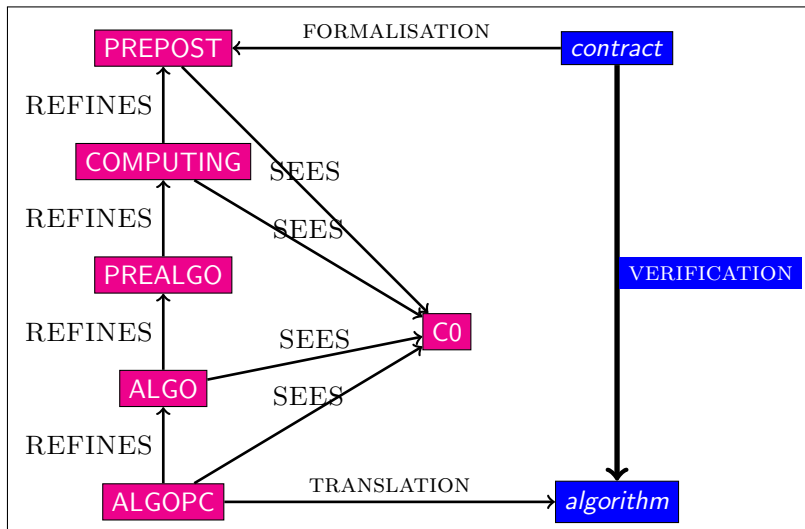
CONTEXT <i>ctxt_id_2</i>	MACHINE <i>machine_id_2</i>
EXTENDS <i>ctxt_id_1</i>	REFINES <i>machine_id_1</i>
SETS <i>s</i>	SEES <i>ctxt_id_2</i>
CONSTANTS <i>c</i>	VARIABLES <i>v</i>
AXIOMS $A(s, c)$	INVARIANTS $I(s, c, v)$
THEOREMS $T_c(s, c)$	THEOREMS $T_m(s, c, v)$
END	VARIANT $V(s, c, v)$
	EVENTS
	EVENT <i>e</i>
	any <i>x</i>
	where $G(s, c, v, x)$
	then
	$v : BA(s, c, v, x, v')$
	end
	END

Invariant preservation	$A(s, c) \wedge I(s, c, v)$ $\wedge G(s, c, v, x)$ $\wedge BA(s, c, v, x, v')$ $\Rightarrow I(s, c, v')$
Event feasibility	$A(s, c) \wedge I(s, c, v)$ $\wedge G(s, c, v, x)$ $\Rightarrow \exists v'. BA(s, c, v, x, v')$
Variant modelling progress	$A(s, c) \wedge I(s, c, v)$ $\wedge G(s, c, v, x)$ $\wedge BA(s, c, v, x, v')$ $\Rightarrow V(s, c, v') < V(s, c, v)$
Theorems	$A(s, c) \Rightarrow T_c(s, c)$ $A(s, c) \wedge I(s, c, v)$ $\Rightarrow T_m(s, c, v)$

Refinement between two machines



The Iterative Pattern



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First n numbers and first odd/even numbers

- First the **pre/post specification** ...
- Possibility to use a programming language with contracts too

Computing two sums

First n numbers and first odd/even numbers

- First the **pre/post specification** ...
- Possibility to use a programming language with contracts too

requires $input_0 \geq 0 \wedge rs_0, re_0 \in \mathbb{Z}$

ensures $\begin{cases} rs_f = s(input_0) \\ re_f = es(input_0) \\ input_f = input_0 \end{cases}$

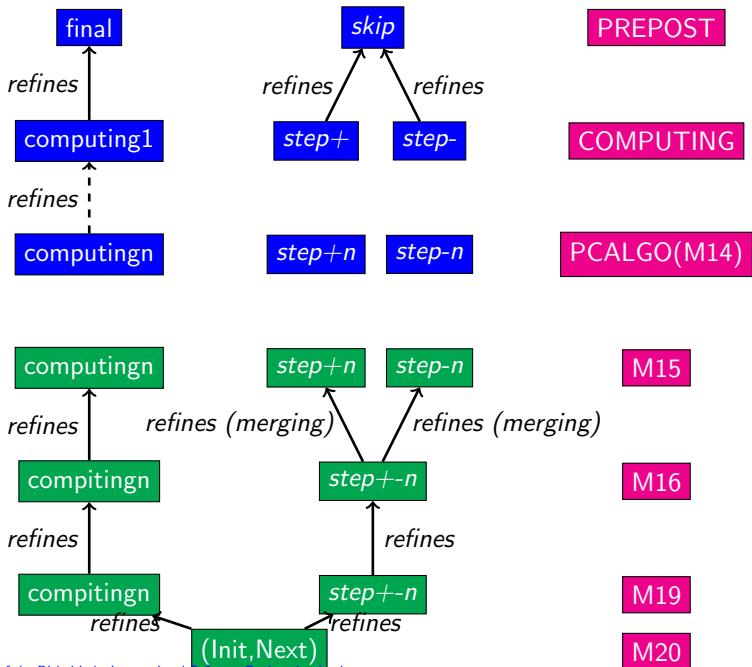
variables $input, re, rs$

- Find two sequences s and es computing the sum of first n natural numbers and first even numbers smaller than n

- Prove that:

$$\blacktriangleright \forall n. n \in \mathbb{N} \Rightarrow s(n) = \sum_{i=0}^{i=n} i.$$

$$\blacktriangleright \forall n. n \in \mathbb{N} \Rightarrow es(n) = \sum_{i=0}^{i=n/2} 2 * i.$$



First n numbers and first odd/even numbers

$$axm1 : n \in \mathbb{N}$$

$$axm2 : s \in \mathbb{N} \rightarrow \mathbb{N} \wedge os \in \mathbb{N} \rightarrow \mathbb{N} \wedge es \in \mathbb{N} \rightarrow \mathbb{N}$$

$$axm3 : es(0) = 0 \wedge os(0) = 0 \wedge s(0) = 0$$

$$axm4 : \forall i, l. i \in \mathbb{N} \wedge l \in \mathbb{N} \wedge i = 2 * l \Rightarrow s(i + 1) = s(i) + i + 1 \wedge es(i + 1) =$$

$$axm5 : \forall i, l. i \in \mathbb{N} \wedge l \in \mathbb{N} \wedge i = 2 * l + 1 \Rightarrow s(i + 1) = s(i) + i + 1 \wedge es(i + 1) =$$

$$axm6 : suc \in \mathbb{N} \rightarrow \mathbb{N} \wedge (\forall i. i \in \mathbb{N} \Rightarrow suc(i) = i + 1)$$

$$axm7 : \forall A. A \subseteq \mathbb{N} \wedge 0 \in A \wedge suc[A] \subseteq A \Rightarrow \mathbb{N} \subseteq A$$

$$th1 : \forall i. i \in \mathbb{N} \Rightarrow s(i + 1) = s(i) + i + 1$$

$$th2 : \forall u, v. u \in \mathbb{N} \wedge v \in \mathbb{N} \wedge 2 * u = v \Rightarrow u = v / 2$$

$$th3 : \forall k. k \in \mathbb{N} \Rightarrow 2 * s(k) = k * k + k$$

$$th4 : \forall k. k \in \mathbb{N} \Rightarrow s(k) = (k * k + k) / 2$$

$$th5 : \forall k. k \in \mathbb{N} \Rightarrow es(2 * k) = 2 * s(k)$$

$$th6 : \forall k. k \in \mathbb{N} \Rightarrow es(2 * k + 1) = 2 * s(k)$$

$$th7 : \forall k. k \in \mathbb{N} \wedge k \neq 0 \Rightarrow os(2 * k) = k * k$$

$$th8 : \forall k. k \in \mathbb{N} \Rightarrow os(2 * k + 1) = (k + 1) * (k + 1)$$

Stating the pre/post specification in Event-B

INVARIANTS

$inv1 : input \in \mathbb{Z}$

$inv6 : input = n$

$inv2 : rs \in \mathbb{Z} \wedge re \in \mathbb{Z}$

$inv3 : ok \in \text{BOOL}$

$inv4 : ok = \text{TRUE} \Rightarrow rs = s(input) \wedge re = es(input)$

END

Stating the pre/post specification in Event-B

then

$act1 : ok := FALSE$

$act2 : rs \in \mathbb{Z}$

$act3 : re \in \mathbb{Z}$

$act4 : input := n$

EVENT computing

when

$grd1 : ok = FALSE$

then

$act1 : rs := s(input)$

$act2 : ok := TRUE$

$act3 : re := es(input)$

END

Refining for computing (1)

INVARIANTS

$inv1 : cur \in 0 .. n$

$inv2 : ee \in 0 .. n \leftrightarrow \mathbb{N}$

$inv3 : ss \in 0 .. n \leftrightarrow \mathbb{N}$

$inv5 : dom(ss) = 0 .. cur \wedge dom(ee) = dom(ss) \wedge dom(ss) \subseteq \mathbb{N}$

$inv6 : \forall i. i \in 0 .. cur \Rightarrow ee(i) = es(i) \wedge ss(i) = s(i)$

Variant

then

$act1 : ok := FALSE$

$act2 : rs \in \mathbb{Z}$

$act3 : re \in \mathbb{Z}$

$act4 : input := n$

$act5 : ee := \{0 \mapsto 0\}$

$act6 : ss := \{0 \mapsto 0\}$

$act7 : cur := 0$

END

Refining for computing (2)

EVENT computing11

when

$grd1 : ok = FALSE$

$grd2 : cur = n$

then

$act1 : rs := ss(input)$

$act2 : ok := TRUE$

$act3 : re := ee(input)$

END

Refining for computing (3)

EVENT *step11*+

Any

k,

when

grd1 : *ok* = *FALSE*

grd2 : $k \in \mathbb{N} \wedge cur = 2 * k + 1$

grd3 : *cur* < *n*

grd4 : *cur* < *n*

then

act1 : *ss*(*cur* + 1) := *ss*(*cur*) + *cur* + 1

act2 : *ee*(*cur* + 1) := *ee*(*cur*) + *cur* + 1

act3 : *cur* := *cur* + 1

END

Refining for computing (4)

EVENT *step11* =

Any

k,

when

grd1 : *ok* = *FALSE*

grd2 : $k \in \mathbb{N} \wedge cur = 2 * k$

grd3 : *cur* < *n*

then

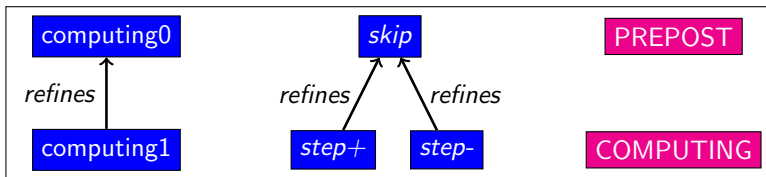
act1 : $ss(cur + 1) := ss(cur) + cur + 1$

act2 : $ee(cur + 1) := ee(cur)$

act3 : *cur* := *cur* + 1

END

Diagram of events



Completing the analysis

MACHINE $M1$ **SEES** $C0$

VARIABLES

$input, rs, re, ok,$

INVARIANTS

$inv1 : input \in \mathbb{Z}$

$inv6 : input = n$

$inv2 : rs \in \mathbb{Z} \wedge re \in \mathbb{Z}$

$inv3 : ok \in \text{BOOL}$

$inv4 : ok = \text{TRUE} \Rightarrow rs = s(input) \wedge re = es(input)$

Completing the analysis

MACHINE *M11* **SEES** *C0*

VARIABLES

input, rs, re, ok, ee, ss, cur,

INVARIANTS

inv1 : $cur \in 0 .. n$

inv2 : $ee \in 0 .. n \leftrightarrow \mathbb{N}$

inv3 : $ss \in 0 .. n \leftrightarrow \mathbb{N}$

inv5 : $dom(ss) = 0 .. cur \wedge dom(ee) = dom(ss) \wedge dom(ss) \subseteq \mathbb{N}$

inv6 : $\forall i. i \in 0 .. cur \Rightarrow ee(i) = es(i) \wedge ss(i) = s(i)$

Completing the analysis

MACHINE *M12* **SEES** *C0*

VARIABLES

input, rs, re, ok, ee, ss, cur, cs, ce,

INVARIANTS

inv1 : cs = ss(cur)

inv2 : ce = ee(cur)

Completing the analysis

MACHINE *M13* **SEES** *C0*

VARIABLES

input, rs, re, ok, ee, ss, cur, cs, ce,

INVARIANTS

inv1 : cs = ss(cur)

inv2 : ce = ee(cur)

inv4 : ce = es(cur)

inv3 : cs = s(cur)

Completing the analysis

MACHINE $M14$ **SEES** $C0, C1$

VARIABLES

$input, rs, re, cur, cs, ce, l,$

INVARIANTS

$inv1 : cs = s(cur)$

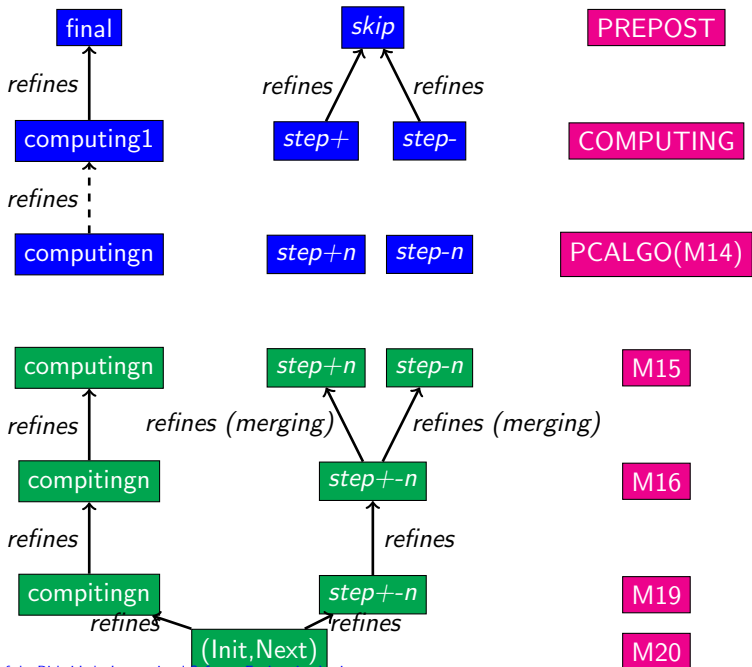
$inv5 : l = start \Leftrightarrow ok = FALSE$

$inv6 : l = end \Leftrightarrow ok = TRUE$

$inv2 : cs = s(cur)$

$inv3 : l \in L$

$inv4 : l = end \Rightarrow re = es(n) \wedge rs = s(n)$



Generation of an algorithm from M14

Translation from Evenrts

```
struct sums  codesum(int n)
{int  k,ce,cs; struct sums r;
  r.s=0;r.se=0;k=0;ce=0;cs=0;
  while (k<n)
  {
    if ( k % 2 != 0)
      { ce = ce + k + 1;cs = cs +k+1;          k = k +1;}
    else
      { ce = ce ;cs = cs +k+1;          k = k +1;}
  }
  r.s=cs;r.se=ce;
  return(r);
}
```

Generation of an algorithm from M14

Improving and checking with Frama-c

```
#include "structure.h"
#include "trans-even.h"
struct sums codesum(int n)
{int k, ce, cs; struct sums r;
  r.s=0; r.se=0; k=0; ce=0; cs=0;
  /*@ loop invariant k >= 0 && k <= n && mathsum(k) == cs;
    @ loop invariant ( (k % 2 == 0) ==> (mathse(k) == ce));
    @ loop invariant ( (k % 2 != 0) ==> (mathse(k) == ce));
    loop assigns k, ce, cs;
    loop variant n-k;
  */
  while (k<n)
  {
    if ( k % 2 != 0)
      { ce = ce + k + 1; cs = cs +k+1;          k = k +1;}
    else
      { ce = ce ;cs = cs +k+1;          k = k +1;}
  }
  r.s=cs; r.se=ce;
```

Generation of an algorithm from M14

Improving and checking with Frama-c

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#include "structure.h"
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struct sums codesum(int n)
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    @ loop invariant ( (k % 2 == 0) ==> (mathse(k) == ce));
    @ loop invariant ( (k % 2 != 0) ==> (mathse(k) == ce));
    loop assigns k, ce,cs;
    loop variant n-k;
  */
  while (k<n)
  {
    if ( k % 2 != 0)
      { ce = ce + k + 1;}
    cs = cs +k+1;      k = k +1;
  }
  cp trabs-e*
  r.s=cs;r.se=ce;
  return(r);
```

Generation of an algorithm from M14

Using the Plugin EB2Algo

```
rs :∈ Z ||
re :∈ Z ||
input = n ||
cur = 0 ||
ce = 0 ||
cs = 0

while cur≠n do
  if cur mod 2≠0 then
    cur = cur+1 ||
    cs = cs+cur+1 ||
    ce = ce+cur+1
  else
    cur = cur+1 ||
    cs = cs+cur+1 ||
    ce = ce
```

Current Summary

① Introduction of Correct by Construction by Example

Detecting overflows in computations

Computing the velocity of an aircraft on the ground

Tracking bugs in C codes

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③ Short Summary on Event-B

④ Analysis and then Synthesis

Analysis using Refinement

Synthesis by Merging

⑤ Conclusion

Merging events

EVENT e1

any

x

where

$G1(s, c, x, u)$

then

$u : |(R(s, c, x, u, u'))$

end

EVENT e2

any

x

where

$G2(s, c, x, u)$

then

$u : |(R(s, c, x, u, u'))$

end

Merging events

EVENT e1

any

x

where

$G1(s, c, x, u)$

then

$u : |(R(s, c, x, u, u'))$

end

EVENT e2

any

x

where

$G2(s, c, x, u)$

then

$u : |(R(s, c, x, u, u'))$

end

EVENT e *refines* e1, e2

any

x

where

$H(s, c, x, u)$

then

$u : |(R(s, c, x, u, u'))$

end

Merging events

EVENT e_1

any

x

where

$G1(s, c, x, u)$

then

$u : |(R(s, c, x, u, u'))$

end

EVENT e_2

any

x

where

$G2(s, c, x, u)$

then

$u : |(R(s, c, x, u, u'))$

end

EVENT e *refines* e_1, e_2

any

x

where

$H(s, c, x, u)$

then

$u : |(R(s, c, x, u, u'))$

end

Checking the Proof Obligation:

$$Ax(s, c), I(s, c, u), H(s, c, x, u) \vdash \\ G1(s, c, x, u) \vee G2(s, c, x, u)$$

- Preparing merging by transforming actions.

EVENT e

any

x

where

$G(s, c, x, u)$

then

$u : |(R(s, c, x, u, u'))$

end

EVENT f refines e

any

x

where

$G(s, c, x, u)$

then

$u : |(G(s, c, x, u) \Rightarrow R(s, c, x, u, u'))$

end

- Internalizing the action as a before after relation
- $G(s, c, x, u) \wedge (G(s, c, x, u) \Rightarrow R(s, c, x, u, u')) \Leftrightarrow$
 $G(s, c, x, u) \wedge R(s, c, x, u, u')$

- Preparing merging by transforming actions.

EVENT e

any

x

where

$G(s, c, x, u)$

then

$u : |(R(s, c, x, u, u'))$

end

EVENT f refines e

any

x

where

$G(s, c, x, u)$

then

$u : |(G(s, c, x, u) \Rightarrow R(s, c, x, u, u'))$

end

- $G(s, c, x, u) \wedge (G(s, c, x, u) \Rightarrow R(s, c, x, u, u')) \Leftrightarrow$
 $G(s, c, x, u) \wedge R(s, c, x, u, u')$
- $A(s, c, u) \wedge I(s, c, u) \wedge BA(f)(s, c, u, u') \Rightarrow$
 $I(s, c, u') \wedge BA(e)(s, c, u, u')$

- Preparing merging by transforming actions.

EVENT e

any

x

where

$G(s, c, x, u)$

then

$u : |(R(s, c, x, u, u'))$

end

EVENT f refines e

any

x

where

$G(s, c, x, u)$

then

$u : |(G(s, c, x, u) \Rightarrow R(s, c, x, u, u'))$

end

- $G(s, c, x, u) \wedge (G(s, c, x, u) \Rightarrow R(s, c, x, u, u')) \Leftrightarrow G(s, c, x, u) \wedge R(s, c, x, u, u')$
- $A(s, c, u) \wedge I(s, c, u) \wedge BA(f)(s, c, u, u') \Rightarrow I(s, c, u') \wedge BA(e)(s, c, u, u')$
- $A(s, c, u) \wedge I(s, c, u) \wedge G(s, c, x, u) \wedge (G(s, c, x, u) \Rightarrow R(s, c, x, u, u')) \Rightarrow I(s, c, u') \wedge G(s, c, x, u) \wedge R(s, c, x, u, u')$

Synthesis Phase: review of machines from M15-M20

MACHINE *M15* **SEES** *C0, C1*
VARIABLES
input, rs, re, cur, cs, ce, l,

Synthesis Phase: review of machines from M15-M20

MACHINE *M16* **SEES** *C0, C1*

VARIABLES

input, rs, re, cur, cs, ce, l,

Synthesis Phase: review of machines from M15-M20

MACHINE *M17* **SEES** *C0, C1*

VARIABLES

input, rs, re, cur, cs, ce, l,

Synthesis Phase: review of machines from M15-M20

MACHINE *M18* **SEES** *C0, C1*

VARIABLES

input, rs, re, cur, cs, ce, l,

Synthesis Phase: review of machines from M15-M20

MACHINE *M19* **SEES** *C0, C1*

VARIABLES

input, rs, re, cur, cs, ce, l,

Synthesis Phase: review of machines from M15-M20

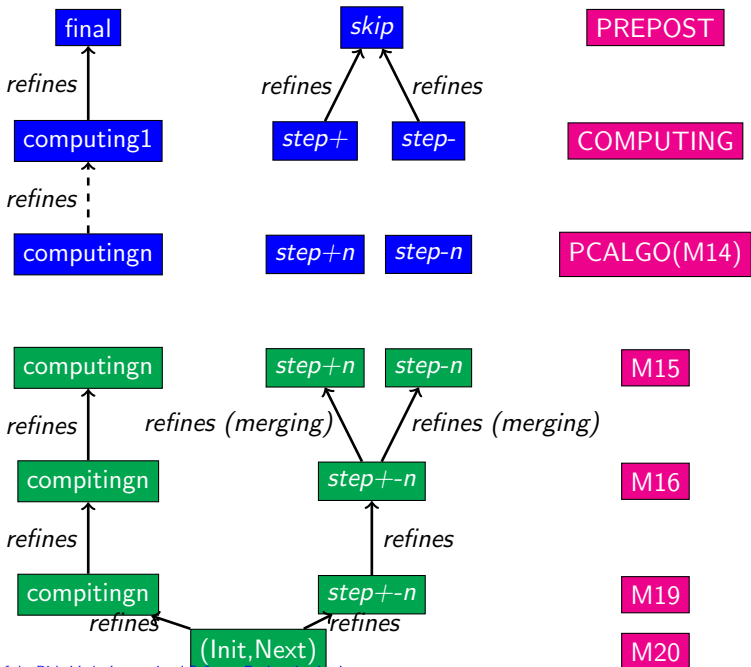
MACHINE *M20* **SEES** *C0, C1*

VARIABLES

input, rs, re, cur, cs, ce, l,

Generating a TLA specification

```
-----  
next1 ==  
    (l="start" /\    cur < n /\ ( cur % 2 = 0))  
    /\    (cur'=cur+1 /\    ce'=ce /\    l'=l  
    /\    cs'=cs+cur+1 /\    re'=re /\    rs'=rs)  
  
o  
delsnext2 ==  
    (l="start" /\    cur < n /\ ( cur % 2 # 0))  
    /\    (cur'=cur+1 /\    ce'=ce+cur+1 /\    l'=l  
    /\    cs'=cs+cur+1 /\    re'=re /\    rs'=rs)  
  
next3 ==  
    (l="start" /\    cur=n) /\    (rs'=cs /\    re'=ce  
    /\    l'="end" /\    cur'=cur /\    cs'=cs /\    ce'=ce)  
  
Next ==  
    (next1 \/ next2 \/ next3)  
  
Init == l="start" /\    cur=0 /\ rs=0 /\ cs=0 /\ re=0 /\ ce =0  
=====
```



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Conclusion

- Paradigm for planning refinements.
- Teaching why and how sequential algorithms are working.
- Relating Event-B to TLA
- Application to controller synthesis: events versus operations.

Conclusion

- Paradigm for planning refinements.
- Teaching why and how sequential algorithms are working.
- Relating Event-B to TLA
- Application to controller synthesis: events versus operations.

Next

- Atlas of *correct-by-construction* sequential algorithms
- Definition of link between events and codes
- Integration of certification techniques for proofs.

Case studies

Case studies

- odd and even summation (gc-oddevensummation)
- power functions: x^n (bb-power3)
- primes
- binary search
- gcd
- fibonacci-like functions

