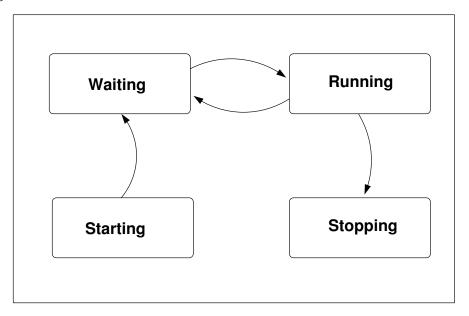
# Tutorial Modelling Software-based Systems

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Tutorial 1 : Specifying a problem using the Eevent-B modelling language
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25 septembre 2025

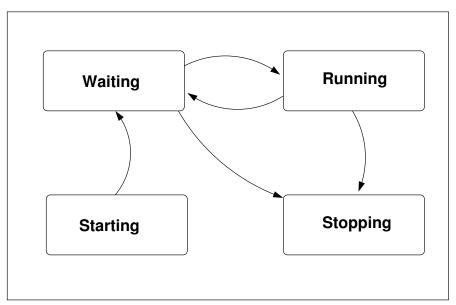
#### Exercice 1 ex1-tut1.zip

Express the following states machine using an Event B machines and check properties on the resulting models.



## Exercice 2 ex2-tut1.zip

Express the following states machine using an Event B machines and check properties on the resulting models.



# **Exercice 3** (ex3-simple-tut.zip)

Soient deux ensembles A et B qui sont des parties de U.

— Ecrire un modèle Event-B qui utilise deux variables v et w deux sous-ensembles de A et B

- Ajouter une fonction partielle de A dans B.
- Définir un événement  $\ominus$  l qui transfert un élément de A dans B s'il n'est pas dans A.
- Définir un événement ⊖2 qui crée un lien entre un élément de A et un élément de B.

#### Exercice 4 ex4-tut1.zip

We consider a finite sequence of integers  $v_1, \ldots, v_n$  where n is the length of the sequence and is supposed to be fixed. Write an Event B specification modelling the computation of the value of the summation of the sequence v. You should define cerafully v, n and the summation of a finite sequence of integers.

#### Exercice 5 ex51-tut1.zip and ex52-tut1.zip

Express the following property in Event B:

- (ex51-tut1.zip) We assume to have p resources which may be shared by n processes. If a process uses a given resource, the resource can not be used by another process. A process can use only at most one resource.
- (ex52-tut1.zip) We assume to have p resources which may be shared by nmcs processes. If a process uses a given resource, the resource can not be used by another process. A process can use possibly more than one ressource.

#### Exercice 6 ex6-tut1.zip

A Petri net is a uple R=(S,T,F,K,M,W)

- S is a finite set of places.
  - T is a finite set of transitions.
  - $-S \cap T = \emptyset$
  - F is the flow relation :  $F \subseteq S \times T \cup T \times S$
  - K is expressing the capacity of each place :
    - $K \in S o Nat \cup \{\omega\}$
  - *M* is reprenting the initial marking of each place :
    - $M \in S \rightarrow Nat \cup \{\omega\}$  and satisfies the following condition  $\forall s \in S : M(s) < K(s)$ .
  - W is the weight of each edge:
    - $W \in F \rightarrow Nat \cup \{\omega\}$

THe state of a Petri net R is defined by a set of markings:

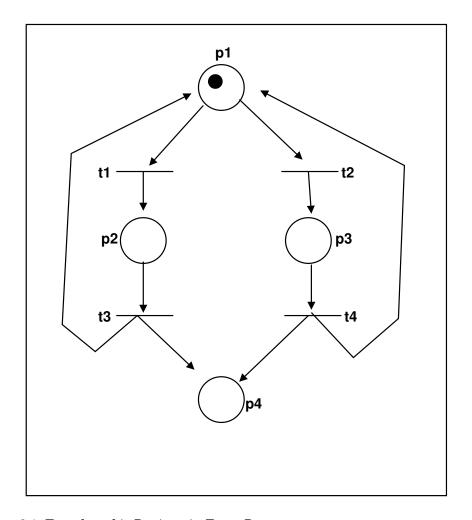
- a marking M for R is a function from S to Nat  $\cup \{\omega\}$ :
  - $M \in S \rightarrow Nat \cup \{\omega\}$  and it satisfies the condition  $\forall s \in S : M(s) \leq K(s)$ .
  - a transition t of T is ready to fire for a marking M of R, if
    - 1.  $\forall s \in \{ s' \in S \mid (s',t) \in F \} : M(s) > W(s,t).$
    - 2.  $\forall s \in \{s' \in S \mid (t,s') \in F\}$ :  $M(s) \leq K(s) W(s,t)$ .
  - $-t \in T : Pre(t) = \{s' \in S : (s', t) \in F\} \text{ and } Post(t) = \{s' \in S : (t, s') \in F\}$

The simulation of a Petri net is defined by a relation linking three elements : a marking M, a marking M' and a transition t as follows :

— the new marking M' is defined as follows from M:

```
\mathit{M'(s)} = \left\{ \begin{array}{l} M(s) - W(s, T), \text{ si } s \in PRE(T) - POST(T) \\ M(s) + W(T, S), \text{ si } s \in POST(T) - PRE(T) \\ M(s) - W(s, T) + W(T, S), \text{ si } s \in PRE(T) \cap POST(T) \\ M(s), \text{ sinon} \end{array} \right.
```

We consider the following Petri net:



**Question 6.1** Translate this Petri net in Event B.

**Question 6.2** Express safety properties that you can discover from the diagram.

# **Exercice 7** (*ex7-tut1.zip*)

Nous considérons le modèle suivant.

```
MACHINE M1
VARIABLES
INVARIANTS
EVENTS
EVENT INITIALISATION
 BEGIN
 act1: x := -10
 END
 EVENT evt1
  WHEN
 grd1: x \ge -1
 THEN
 act1:x:=x{+}1
 END
 EVENT evt2
 WHEN
 grd1: x \leq -1
 grd2: x \geq -44
 THEN
 act1: x := x-1
 END
END
```

On considère plusieurs cas pour l'invariant.

## **Question 7.1** (*M1*)

 $inv1: x \in \mathbb{Z}$  $inv3: x \le -1$ 

Est-ce que toutes les conditions de vérification sont prouvées par le prouveur de l'application Rodin? Expliquez clairement pourquoi elles sont prouvées ou non.

# **Question 7.2** (M2)

 $\begin{array}{l} inv1: x \in \mathbb{Z} \\ inv3: x \leq -3 \end{array}$ 

Est-ce que toutes les conditions de vérification sont prouvées par le prouveur de l'application Rodin? Expliquez clairement pourquoi elles sont prouvées ou non.

# **Question 7.3** (*M3*)

```
\begin{array}{l} inv1: x \in \mathbb{Z} \\ inv4: -45 \leq x \wedge x \leq -10 \end{array}
```

Est-ce que toutes les conditions de vérification sont prouvées par le prouveur de l'application Rodin? Expliquez clairement pourquoi elles sont prouvées ou non.

## **Question 7.4** (*M4*)

```
\begin{array}{l} inv1: x \in \mathbb{Z} \\ inv3: x \leq -3 \\ inv4: -45 \leq x \wedge x \leq -10 \\ inv2: x \leq -1 \end{array}
```

Est-ce que toutes les conditions de vérification sont prouvées par le prouveur de l'application Rodin ? Expliquez clairement pourquoi elles sont prouvées ou non.

## Exercice 8 ex8-tut1.zip

A semaphore s is a shared variable accessible by two operations : P(s) and V(s). Informally, we can describe the effect of these two operations as follows :

- P(s) is testing if the value of s is greater than 0 and is not equal to 0. If the value of s is 0, the process which is executing P(s) is inserted in a queue.
- V(s) is increasing the value of s by one, if the queue is non empty. If the queue is non empty, the first waiting process of the queue is awaken and becomes a lively process.

Using the Event B modelling features, describe a system using the primitives.

#### Exercice 9 ex9-tut1.zip

We assume that two  $n \times n$  matrices of boolean values are given : A and B. Write an Event B specification modelling the multiplication of the two matrices.

#### **Exercice 10** (ex10-1-tut1.zip and ex10-2-tut1.zip)

A system is used to sum two numbers x0 and y0 by adding one unit to a variable z. It includes an incx2z event which decreases the value of x by one and increases the value of z by one, and an incy2z event which decreases y by one and increases z by one. The overall process stops when the two variables x and y are zero.

Write a model in Event-B for the syste.