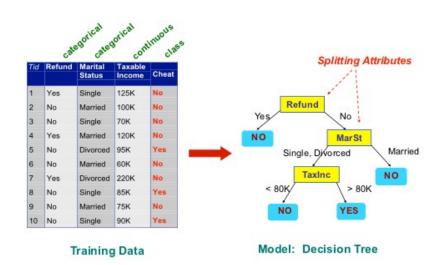
Classification trees

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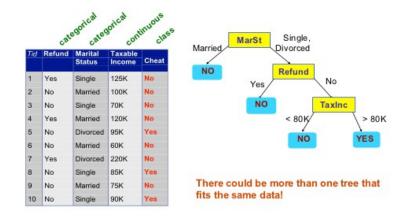
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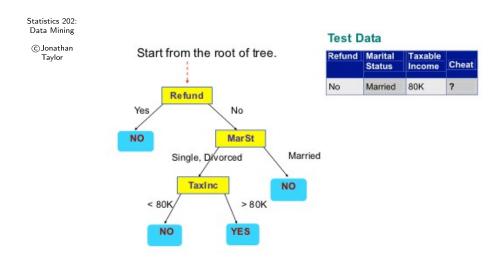


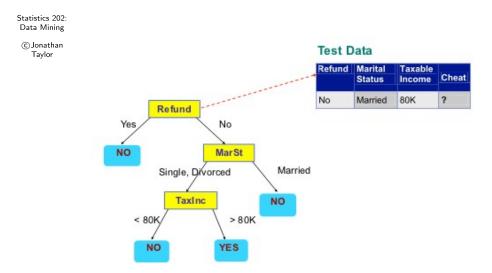
Classification trees

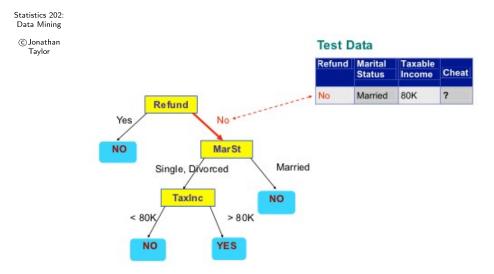
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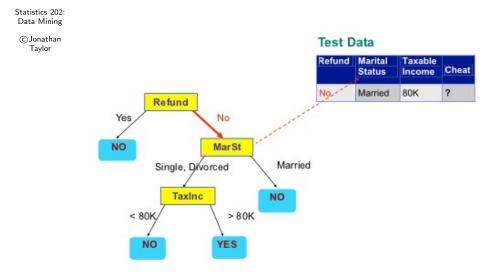
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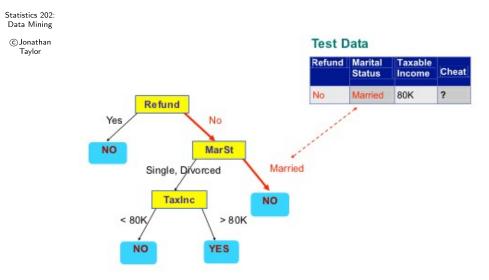


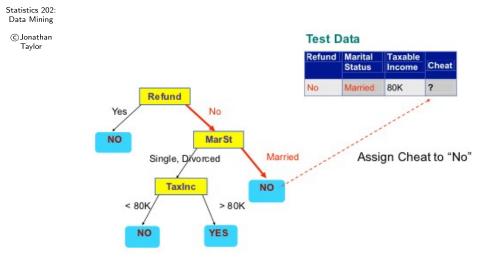








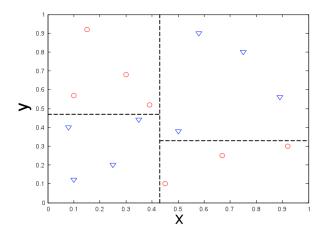




Decision boundary for tree



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Decision boundary for tree

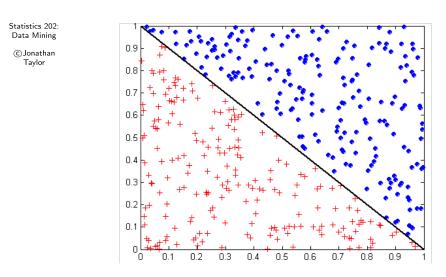


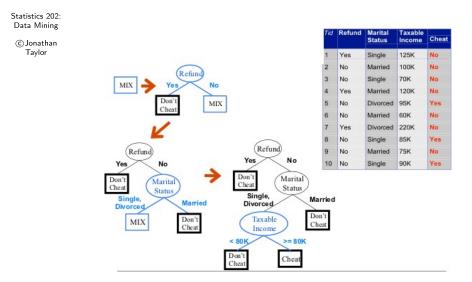
Figure: Trees have trouble capturing structure not parallel to axes

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Hunt's algorithm (generic structure)

- Let D_t be the set of training records that reach a node t
- If D_t contains records that belong the same class y_t , then t is a leaf node labeled as y_t .
- If $D_t = \emptyset$, then t is a leaf node labeled by the default class, y_d .
- If D_t contains records that belong to more than one class, use an attribute test to split the data into smaller subsets. Recursively apply the procedure to each subset.
- This splitting procedure is what can vary for different tree learning algorithms . . .



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Issues

Greedy strategy: Split the records based on an attribute test that optimizes certain criterion.

What is the best split: What criterion do we use? Previous example chose first to split on Refund ...

How to split the records: Binary or multi-way? Previous example split Taxable Income at $\geq 80 K \dots$

When do we stop? Should we continue until each node if possible? Previous example stopped with all nodes being completely homogeneous

Different splits: ordinal / nominal

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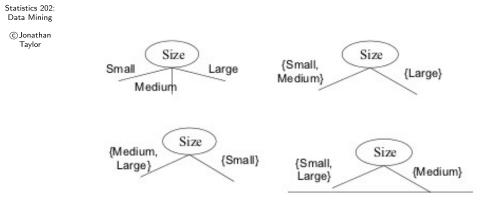


Figure: Binary or multi-way?

Different splits: continuous

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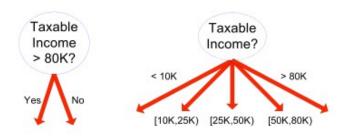


Figure : Binary or multi-way?

Choosing a variable to split on

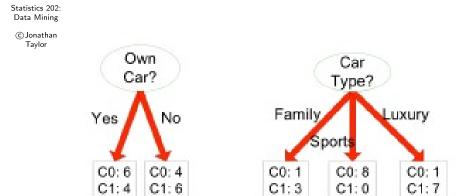


Figure: Which should we start the splitting on?

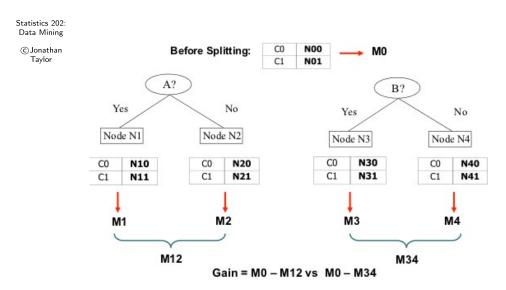
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Choosing the best split

- Need some numerical criterion to choose among possible splits.
- Criterion should favor homogeneous or pure nodes.
- Common cost functions:
 - Gini Index
 - Entropy / Deviance / Information
 - Misclassification Error

Choosing a variable to split on



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GINI Index

- Suppose we have k classes and node t has frequencies $p_t = (p_{1,t}, \dots, p_{k,t})$.
- Criterion

$$extit{GINI(t)} = \sum_{(j,j') \in \{1,...,k\}: j
eq j'} p_{j,t} p_{j',t} = 1 - \sum_{j=1}^l p_{j,t}^2.$$

- ullet Maximized when $p_{j,t}=1/k$ with value 1-1/k
- Minimized when all records belong to a single class.
- Minimizing GINI will favour pure nodes . . .

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Gain in GINI Index for a potential split

- Suppose t is to be split into j new child nodes $(t_l)_{1 \le l \le j}$.
- Each child node has a count n_l and a vector of frequencies $(p_{1,t_l},\ldots,p_{k,t_l})$. Hence they have their own GINI index, $GINI(t_l)$.
- The gain in GINI Index for this split is

$$\mathsf{Gain}(\mathit{GINI},t o (t_l)_{1 \leq l \leq j}) = \mathit{GINI}(t) - rac{\sum_{l=1}^{j} n_l \mathit{GINI}(t_l)}{\sum_{l=1}^{j} n_l}.$$

• Greedy algorithm chooses the biggest gain in GINI index among a list of possible splits.

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Entropy / Deviance / Information

- Suppose we have k classes and node t has frequencies $p_t = (p_{1,t}, \dots, p_{k,t})$.
- Criterion

$$H(t) = -\sum_{j=1}^k p_{j,t} \log p_{j,t}$$

- Maximized when $p_{i,t} = 1/k$ with value $\log k$
- Minimized when one class has no records in it.
- Minimizing entropy will favour *pure* nodes . . .

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Gain in entropy for a potential split

- Suppose t is to be split into j new child nodes $(t_l)_{1 < l < j}$.
- Each child node has a count n_l and a vector of frequencies $(p_{1,t_l}, \ldots, p_{k,t_l})$. Hence they have their own entropy $H(t_l)$.
- The gain in entropy for this split is

$$\mathsf{Gain}(H, t \to (t_l)_{1 \le l \le j}) = H(t) - \frac{\sum_{l=1}^{j} n_l H(t_l)}{\sum_{l=1}^{j} n_l}.$$

• Greedy algorithm chooses the biggest gain in *H* among a list of possible splits.

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Stopping training

- As trees get deeper, or if splits are multi-way the number of data points per leaf node drops very quickly.
- Trees that are too deep tend to overfit the data.
- A common strategy is to "prune" the tree by removing some internal nodes.



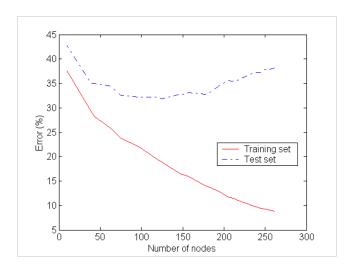


Figure : Underfitting corresponds to the left-hand side, overfit to the right $$_{\rm 41/1}$$

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Cost-complexity pruning (tree library)

© Jonathan Taylor • Given a criterion Q like H or GINI, we define the cost-complexity of a tree with terminal nodes $(t_i)_{1 \le j \le m}$

$$C_{\alpha}(T) = \sum_{j=1}^{m} n_{j}Q(t_{j}) + \alpha m$$

- Given a large tree T_L we might compute $C_{\alpha}(T)$ for any subtree T of T_L .
- The optimal tree is defined as

$$\hat{T}_{\alpha} = \underset{T \leq T_L}{\operatorname{argmin}} C_{\alpha}(T).$$

• Can be found by "weakest-link" pruning. See *Elements of Statistical Learning* for more . . .