

i) a. * saat $t=t_1$ sampai $t=t_3$, $a_x(t) = -\frac{3}{5}t + 9$ sehingga

$$a_x(t_3) = -3$$

$$-\frac{3}{5}t_3 + 9 = -3$$

$$-\frac{3}{5}t_3 = -12$$

$$t_3 = 20 \text{ sekon}$$

* Karena di t_4 , mobil berhenti maka

$$\int_0^{t_4} a_x(t) dt = 0$$

$$\frac{(10+15)}{2} \cdot 3 - \frac{(t_4 - 15 + t_4 - 20)}{2} \cdot 3 = 0$$

$$\frac{75}{2} - \frac{(2t_4 - 35)}{2} \cdot 3 = 0$$

$$75 - 6t_4 + 105 = 0$$

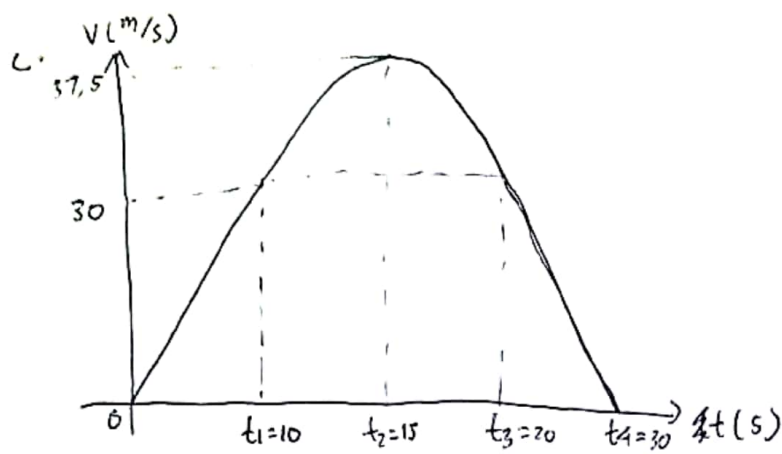
$$6t_4 = 180$$

$$t_4 = 30 \text{ sekon}$$

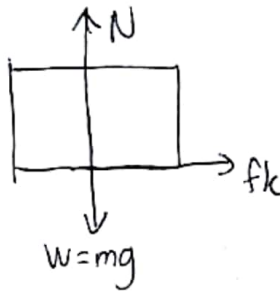
b. * Untuk $t_1 - t_2$: $V(t) = 3t \Rightarrow V(t_1) = V(10) = 30$

+ Untuk $t_1 - t_2$: $V(t) = -\frac{3}{10}t^2 + 9t + C \Rightarrow V(10) = -\frac{3}{10} \cdot 10^2 + 90 + C = 30$
 $\Rightarrow C = -30$

$$\begin{aligned} \text{* Jarak: } \int_0^{t_2} v(t) dt &= \int_0^{t_1} v(t) dt + \int_{t_1}^{t_2} v(t) dt \\ &= \int_0^{10} 3t dt + \int_{10}^{15} \left(-\frac{3}{10}t^2 + 9t - 30\right) dt \\ &= \left.\frac{3}{2}t^2\right|_0^{10} + \left[-\frac{1}{10}t^3 + \frac{9}{2}t^2 - 30t\right]_{10}^{15} \\ &= 150 + \left(-\frac{1}{10} \cdot 15^3 + \frac{9}{2} \cdot 15^2 - 30 \cdot 15 + \frac{1}{10} \cdot 10^3 - \frac{9}{2} \cdot 10^2 + 30 \cdot 10\right) \\ &= 150 + 175 \\ &= 325 \text{ m} \end{aligned}$$



2) a.



b. $\Sigma F_x = m \cdot a_1$ (a_1 percepatan^{balok} relatif terhadap tanah)
 $f_k = m \cdot a_1$
 $\mu_k \cdot N = m \cdot a_1$
 $\mu_k mg = m \cdot a_1$
 $a_1 = \mu_k \cdot g = (0,5)(10) = 1,5 \text{ m/s}^2$

c. Misal a_{12} percepatan relatif balok terhadap mobil.

$$a_{12} = a_1 - a_2 = 1,5 - 2 = -0,5 \text{ m/s}^2$$

$$\Rightarrow s = v_0 \cdot t + \frac{1}{2} a_{12} t^2$$

$$-4 = 0 - \frac{1}{2} (0,5) t^2$$

$$t^2 = 16$$

$$t = 4 \text{ sekon}$$

d. ~~komponen~~ komponen kecepatan horizontal saat menyentuh tanah sama dengan kecepatan horizontal saat meninggalkan mobil.

$$v_x = v_0 + a_1 t = 0 + (1,5)(4) = 6 \text{ m/s}$$

3) a. Misal benda berhenti di titik D (Di antara B dan C).

$$\Delta E_k + \Delta E_p = W_{\text{gesek}}$$

$$(0 - \frac{1}{2} m v_0^2) + (mg s_{BD} \sin \theta) = -\mu_k mg \cos \theta \cdot s_{BD}$$

$$\mu_k mg \cos \theta s_{BD} + mg s_{BD} \sin \theta = \frac{1}{2} m v_0^2$$

$$s_{BD} = \frac{v_0^2}{2g (\mu_k \cos \theta + \sin \theta)} = \frac{5^2}{2(10)(0,5 \cdot \frac{4}{5} + \frac{3}{5})} = \frac{1,25}{1,25} = 1 \text{ m}$$

b. Energi yang hilang : $|W_{\text{gesek}}| = \mu_k mg \cos \theta S_{BD} = (0,5)(5)(10) \frac{4}{5} (\frac{1,25}{1,25}) \approx 25 \text{ J}$

c. * ~~gaya gesek~~ ^{statik max} : $\mu_s mg \cos \theta = \frac{28}{1,25} \text{ N}$

* gaya ~~gesek~~ : $mg \sin \theta = \frac{30}{1,25} \text{ N}$

karena gaya lebih besar maka benda akan turun kembali

d. Dari a),

$$V_0^2 = 2g S_{BC} (\sin \theta + \mu_k \cos \theta) = \frac{28}{1,25} \cdot 40$$

$$V_0 = \sqrt{40} \text{ m/s} \approx 6,32 \text{ m/s}$$

4) a. Karena lenting sempurna maka,

$$V_A - V_B = V_B' - V_A'$$

$$V_A - 0 = V_B' - V_A'$$

$$V_A = V_B' - V_A' \Rightarrow V_A' = V_B' - V_A = V_B' - V_0$$

\Rightarrow Hukum kekekalan momentum,

$$m_A V_A + m_B V_B = m_A V_A' + m_B V_B'$$

$$2m_B V_0 + m_B(0) = 2m_B(V_B' - V_0) + m_B V_B'$$

$$2V_0 = 2V_B' - 2V_0 + V_B'$$

$$4V_0 = 3V_B'$$

$$V_B' = \frac{4}{3} V_0$$

$$\Rightarrow m_B V_B' + m_C V_C = m_B V_B'' + m_C V_C'$$

$$m_B(\frac{4}{3} V_0) + 2m_B(0) = m_B(V_C' - V_B') + 2m_B V_C'$$

$$\frac{4}{3} V_0 = V_C' - V_B' + 2V_C'$$

$$\frac{4}{3} V_0 = 3V_C' - \frac{4}{3} V_0$$

$$\frac{8}{3} V_0 = 3V_C'$$

$$V_C' = \frac{8}{9} V_0$$

b. Karena tidak ada gaya eksternal maka kecepatan pusat massa konstan.

$$V = \frac{m_A V_A + m_B V_B + m_C V_C}{m_A + m_B + m_C} = \frac{m_A V_0}{m_A + \frac{1}{2} m_A + m_A} = \frac{m_A V_0}{\frac{5}{2} m_A} = \frac{2}{5} V_0$$

$$\begin{aligned}
 \text{C. * Waktu dari B ke C: } t_1 &= \frac{L}{V_B'} = \frac{3L}{4V_0} \Rightarrow \text{jarak A} = V_A' t_1 \\
 &= (V_B' - V_A) t_1 \\
 &= \left(\frac{4}{3}V_0 - V_0\right) \frac{3L}{4V_0} \\
 &= \frac{1}{4}L \text{ meter}
 \end{aligned}$$

* Ketika B menembule A untuk kedua kalinya,

$$\begin{aligned}
 \cancel{V_A'} t + V_B' t &= \frac{3}{4}L \\
 \frac{1}{3}V_0 t + (V_C' - V_B') t &= \frac{3}{4}L \\
 \frac{1}{3}V_0 t + \frac{4}{9}V_0 t &= \frac{3}{4}L \\
 \frac{7}{9}V_0 t &= \frac{3}{4}L \\
 t &= \frac{27}{28} \frac{L}{V_0} \text{ sekon}
 \end{aligned}$$

$$\text{* Selang waktu: } t_1 + t = \frac{3}{4} \frac{L}{V_0} + \frac{27}{28} \frac{L}{V_0} = \frac{48}{28} \frac{L}{V_0} = \frac{12}{7} \frac{L}{V_0} \text{ sekon}$$

$$\begin{aligned}
 5) a. \quad \cancel{20 \text{ detik} = 10 \text{ putaran}} \quad * \theta &= \omega_0 \cdot t + \frac{1}{2} \alpha_1 t^2 & * \omega_t &= \omega_0 + \alpha_1 t \\
 \cancel{20 \text{ detik} = 10 \text{ putaran}} \quad 20\pi &= 0 + \frac{1}{2} \alpha_1 (20)^2 & \omega_{20} &= 0 + \frac{\pi}{10} \cdot 20 \\
 40\pi &= 200 \alpha_1 & &= 2\pi \text{ rad/s} \\
 \alpha_1 &= \frac{\pi}{10} \text{ rad/s}^2
 \end{aligned}$$

$$\begin{aligned}
 b. \quad \cancel{\omega_0^2 = \omega_{20}^2 + 2\alpha_2 \theta} \quad * \theta &= \omega_0 \cdot t + \frac{1}{2} \alpha_2 t^2 \\
 * \omega_t &= \omega_0 + \alpha_2 t & &= \omega_{20} t + \frac{1}{2} \alpha_2 t^2 \\
 0 &= \omega_{20} + \alpha_2 (50) & &= 2\pi (50) + \frac{1}{2} \cdot \frac{\pi}{25} \cdot (50)^2 \\
 0 &= 2\pi + \alpha_2 (50) & &= 100\pi - 50\pi \\
 \alpha_2 &= -\frac{\pi}{25} \text{ rad/s}^2 & &= 50\pi \rightarrow 25 \text{ putaran}
 \end{aligned}$$

$$\text{C. * } a_t = \alpha R = \alpha_2 \cdot R = -\frac{\pi}{25} \cdot 2 = -\frac{2\pi}{25} \text{ m/s}^2$$

$$\begin{aligned}
 * a_{sp} &= \omega^2 R = \omega_{25}^2 \cdot R = \left(2\pi \cdot 5 - \frac{1}{2} \cdot \frac{\pi}{25} \cdot 5^2\right)^2 \cdot 2 \\
 &= \left(\frac{19}{2}\pi\right)^2 \cdot 2 \\
 &= \frac{361}{2} \pi^2 \text{ m/s}^2
 \end{aligned}$$