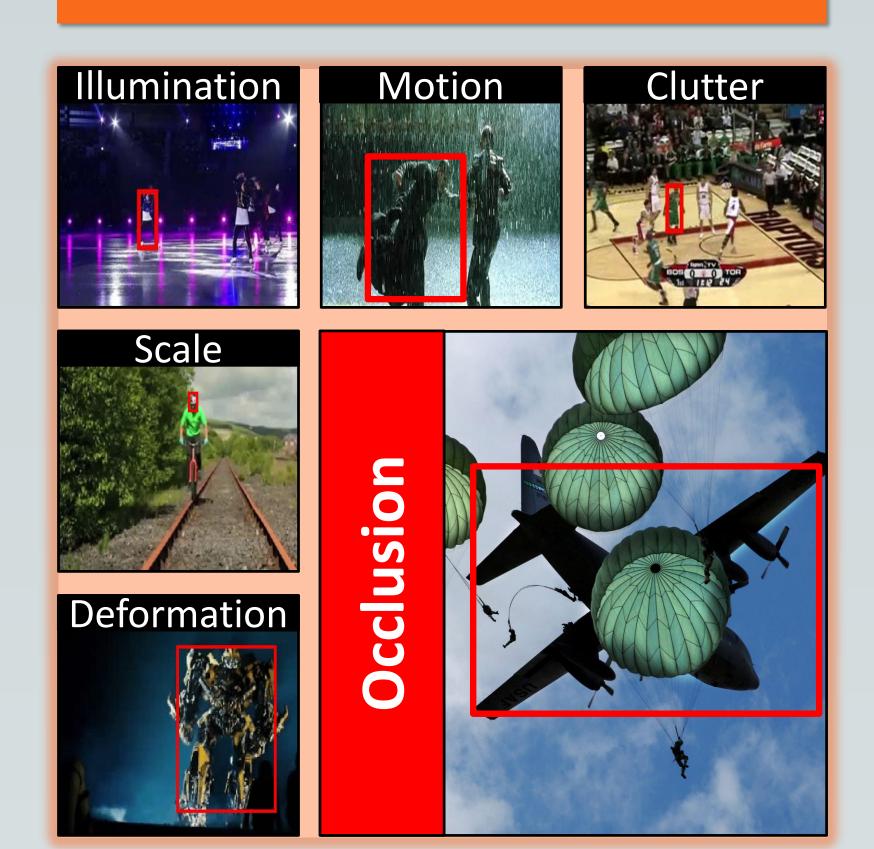


# Occlusion-Aware Visual Object Tracking to Handle Complex and Persistent Occlusions

Kourosh MESHGI, Shin-ichi MAEDA, Shigeyuki OBA, Shin ISHII Department of Systems Science, Graduate School of Informatics, Kyoto University

# TRACKING CHALLENGES



## TRACKING APPLICATIONS

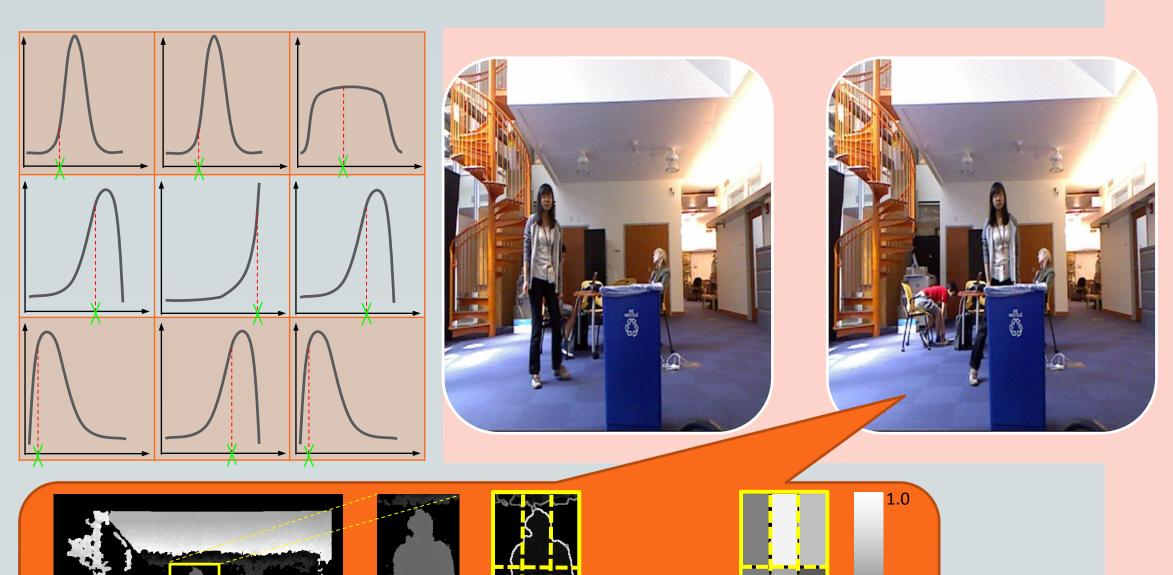


# **OCCLUSION TYPES**



### HANDLING PARTIAL OCCLUSIONS

**Learning an Observation Mask from data** Undermining the impact of occluded parts of the template







#### HANDLING FULL OCCLUSIONS

Switching Sampling Method and Motion Model of Candidates between:

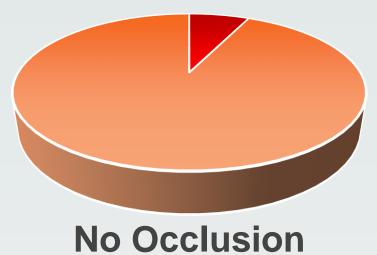
- **Template Matching Particles that keep track of target**
- Occlusion Detecting Particles that expand search area for occluded target



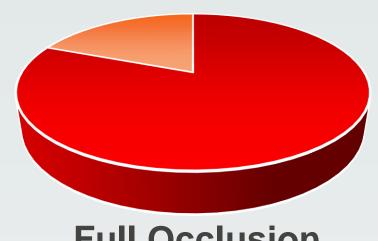










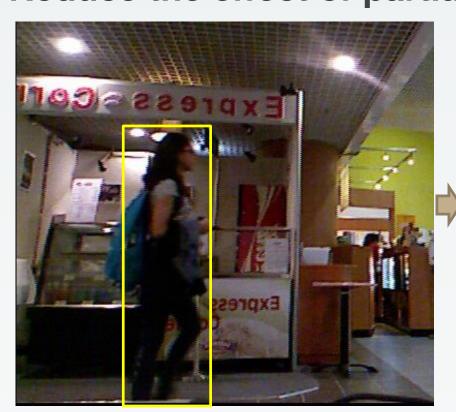


**Occlusion Recovery** 

**Full Occlusion** 

## EMPLOYING MULTIPLE FEATURES AND SMART UPDATE

**Fusing multiple Features from Color and Depth domains** Updating the template only when no occlusion is detected Reduce the effect of partially occluded observations using observation mask

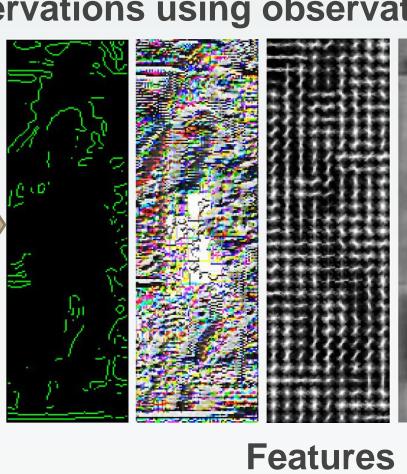


**Frame** 

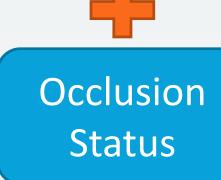
Target Type



target Size

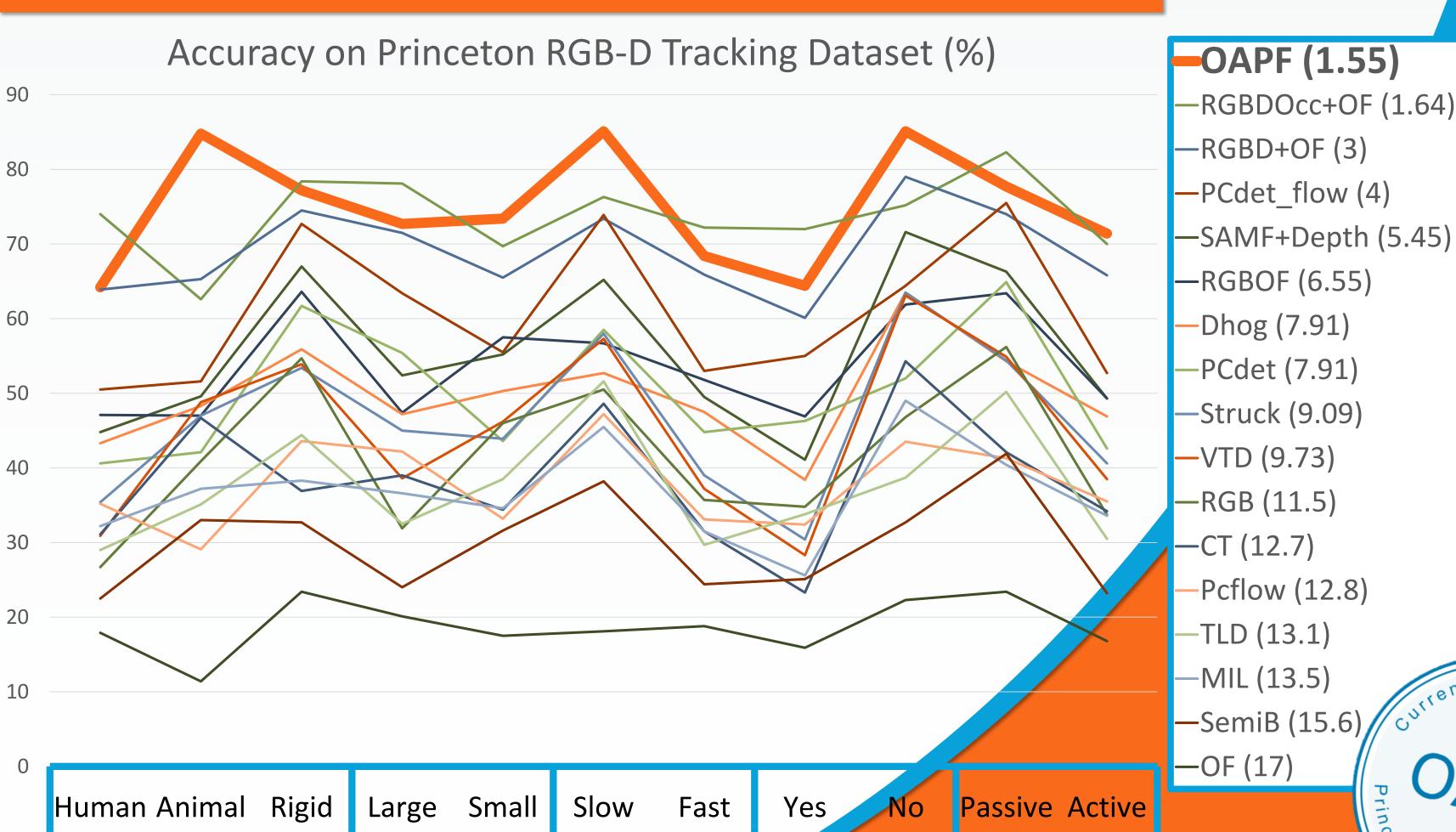


Observation Confidence



Good Model Update

**RESULTS** 



Movement

Occlusion

-RGBDOcc+OF (1.64) -SAMF+Depth (5.45)

Tracking Date

Motion Type