

EE362 - HW #4 Solution

Q.1) a) $N_{sync} = \frac{120f}{p} = \frac{120 \times 50}{6} = 1000 \text{ rpm}$

b) $I_{rated} = \frac{S}{\sqrt{3} V_{LL}} = \frac{40 \times 10^3}{400 \times \sqrt{3}} = 57.74 \text{ A}$

$$\vec{E}_f = \vec{V}_t + j X_s \vec{I}_s \quad \text{--- (1)}$$

Take \vec{V}_t as reference phasor.

Open circuit terminal voltage : $|\vec{E}_f| = 231 \text{ V/phase}$

φ : phase angle between \vec{V}_t & \vec{I}_s

δ : " " " \vec{V}_t & \vec{E}_f

From equation (1)

$$|\vec{E}_f| \cos \delta = |\vec{V}_t| + X_s |\vec{I}_s| \sin \varphi \quad \text{--- (2)}$$

$$|\vec{E}_f| \sin \delta = X_s |\vec{I}_s| \cos \varphi \quad \text{--- (3)}$$

b-i) $\vec{I}_s = 57.74 \angle 0^\circ$ (unity pf)

Using (3): $\sin \delta = \frac{X_s |\vec{I}_s|}{|\vec{E}_f|} = \frac{1 \times 57.74}{231} = 0.25 \Rightarrow \delta = 14.48^\circ$

Using (2): $|\vec{V}_t| = |\vec{E}_f| \cos \delta - X_s |\vec{I}_s| \sin \varphi = 231 \times 0.968 = 222.7 \text{ V/phase}$

b-ii) $\vec{I}_s = 57.74 \angle -37^\circ$ (0.8 lagging pf)

Using (3): $\sin \delta = \frac{X_s |\vec{I}_s| \cos \varphi}{|\vec{E}_f|} = \frac{1 \times 57.74 \times 0.8}{231} = 0.2 \Rightarrow \delta = 11.53^\circ$

Using (2): $|\vec{V}_t| = |\vec{E}_f| \cos \delta - X_s |\vec{I}_s| \sin \varphi = 231 \times 0.98 - 1 \times 57.74 \times 0.6 = 191.7 \text{ V/phase}$

b-iii) $\vec{I}_s = 57.74 \angle 37^\circ$ (0.8 leading pf)

Using (3): $\sin \delta = \frac{1 \times 57.74 \times 0.8}{231} = 0.2 \Rightarrow \delta = 11.53^\circ$

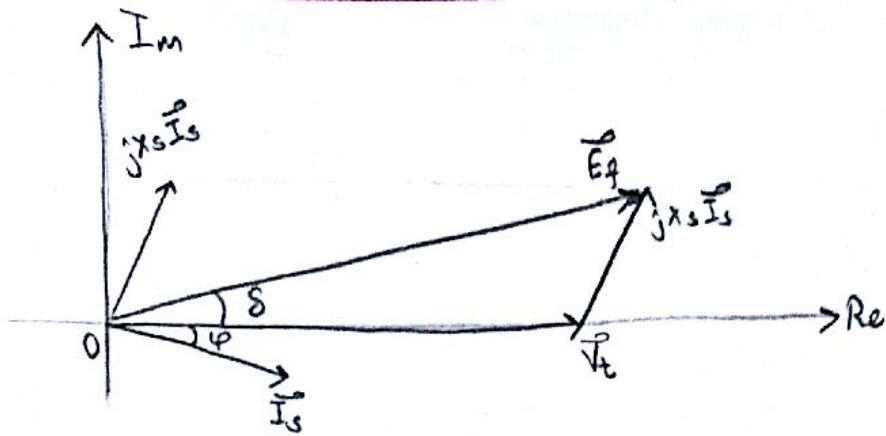
Using (2): $|\vec{V}_t| = |\vec{E}_f| \cos \delta - X_s |\vec{I}_s| \sin \varphi = 231 \times 0.98 + 1 \times 57.74 \times 0.6 = 261 \text{ V/phase}$

c) Total mechanical input power: $P_{in} = P_{fsw} + V_t I_s$ (unity pf)

$$\Rightarrow P_{in} = 1 + 38.6 = 39.6 \text{ kW}$$

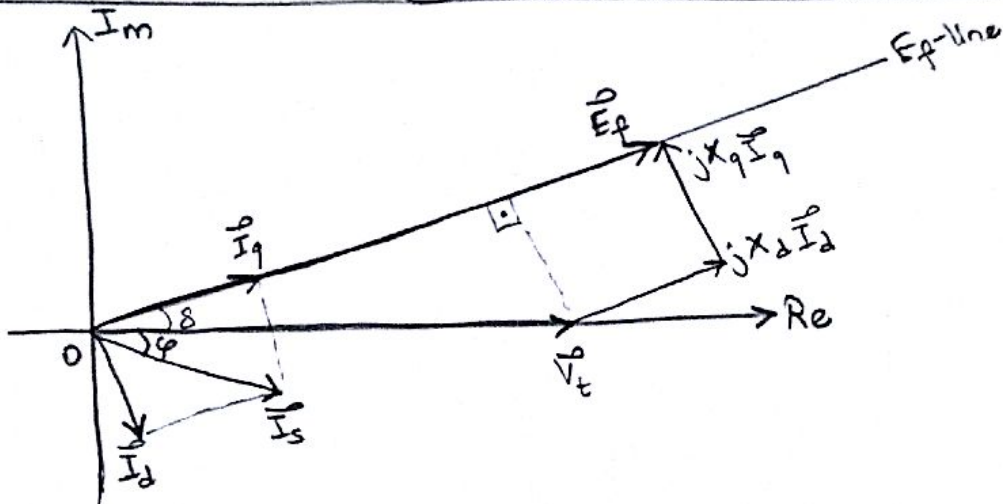
$$\Rightarrow T_{in} = P_{in} / \omega = \frac{39.6 \times 10^3}{1000 \times \frac{2\pi}{60}} = 378.15 \text{ Nm}$$

d)



e) Already found: $\delta = 11.53^\circ$

Q2) a)



b) $\sin \delta = \frac{X_q |\vec{I}_q|}{|\vec{V}_t|}$, $\delta = 21.34^\circ$, $|\vec{V}_t| = 3464 \text{ V/phase} \rightarrow \text{infinite bus}$

$|\vec{I}_q| = |\vec{I}_s| \cos(\varphi + \delta)$ where $\varphi = 37^\circ$ (0.8 pf) and $|\vec{I}_s| = \frac{S}{V \times \sqrt{3}}$

$|\vec{I}_s| = \frac{2.6 \times 10^6}{\sqrt{3} \times 6 \times 10^3} = 250 \text{ A}$

$\Rightarrow |\vec{I}_q| = 131.3 \text{ A} \Rightarrow X_q = \frac{3464 \times 0.36}{131.3} = 9.5 \text{ } \Omega/\text{phase.}$

c) $|\vec{E}_f| = |\vec{V}_t| \cos \delta + X_d |\vec{I}_d|$ where $|\vec{I}_d| = |\vec{I}_s| \sin(\varphi + \delta) = 212.8 \text{ A}$

$\Rightarrow |\vec{E}_f| = 3464 \times 0.93 + 15 \times 212.8 = 6418 \text{ V/phase}$

d) All losses are neglected: $P_m = P_e$

$\Rightarrow P_m = S \cos \varphi = 2.6 \times 10^6 \times 0.8 = 2.08 \text{ MW}$

$N_{\text{sync}} = \frac{120f}{p} = \frac{120 \times 50}{8} = 750 \text{ rpm} \Rightarrow \omega_m = 78.54 \text{ rad/sec}$

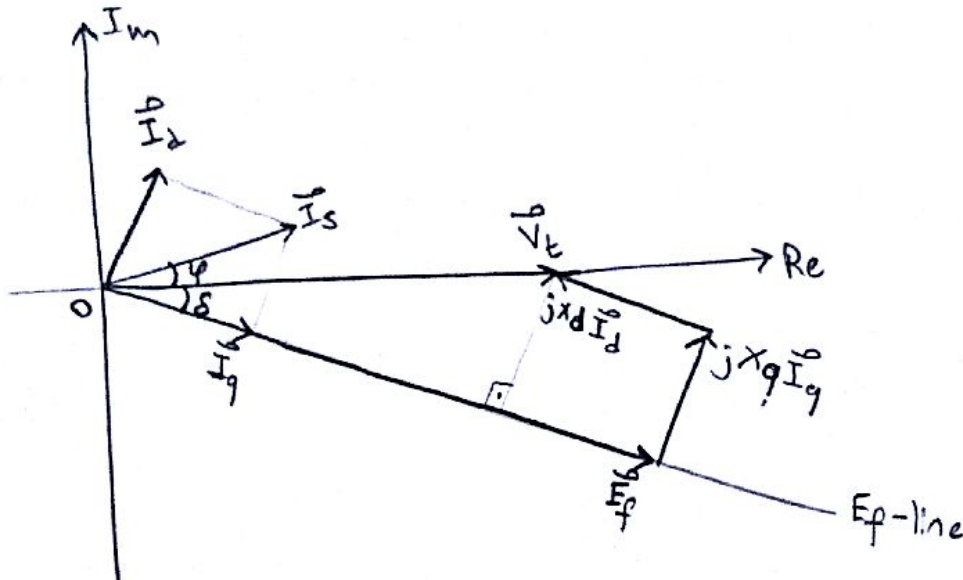
$\Rightarrow T_{em} = \frac{P_m}{\omega_m} = \frac{2.08 \times 10^6}{78.54} = 26.48 \text{ kNm}$

e) No losses : $P_m = P_e = 2 \text{ MW}$

$$\text{pf} = \frac{P}{\sqrt{P^2 + Q^2}} = 0.8 //$$

Active power consumption : $P > 0$
 Reactive power generation : $Q < 0$ } leading pf (acts as a capacitive load)

f)



g) $\sin \delta = \frac{X_q |\vec{I}_q|}{|\vec{V}_t|}$ where $|\vec{V}_t| = 3464 \text{ V/phase} \rightarrow \text{rated voltage}$

$|\vec{I}_q| = |\vec{I}_s| \cos(\varphi + \delta)$ where $\varphi = 37^\circ (0.8 \text{ pf})$ and $|\vec{I}_s| = \frac{5}{\sqrt{3}}$

$|\vec{I}_s| = \frac{2.5 \times 10^6}{6 \times 10^3 \times \sqrt{3}} = 240.6 \text{ A}$

$\Rightarrow \sin \delta = \frac{9.5 \times 240.6 \times \cos(37 + \delta)}{3464} = 0.66 \cos(37 + \delta)$

$[\cos(a+b) = \cos a \cos b - \sin a \sin b]$

$\Rightarrow \sin \delta = 0.66 [0.8 \cos \delta - 0.6 \sin \delta] \Rightarrow 1.396 \sin \delta = 0.528 \cos \delta$

$\Rightarrow \tan \delta = 0.378 \Rightarrow \delta = 20.7 //$