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1 Introduction and Functional Overview

This document describes the concept, core functionality, optional features, interfaces and configuration issues of the AUTOSAR UDP Network Management (UdpNm). UdpNm is intended to be an optional feature. **It is intended to work together with a TCP/IP Stack, independent of the physical layer of the communication system used.** The AUTOSAR UDP Network Management is a hardware independent protocol that can be used on TCP/IP based systems (for limitations refer to chapter 4.1). **Its main purpose is to coordinate the transition between normal operation and bus-sleep mode of the network.**

In addition to the core functionality optional features are provided e.g. to implement a service to detect all present nodes or to detect if all other nodes are ready to sleep. The UDP Network Management (UdpNm) function provides an adaptation between Network Management Interface (Nm) and a TCP/IP Stack (TCP/IP). For a general understanding of the AUTOSAR Network Management functionality please refer to [9].

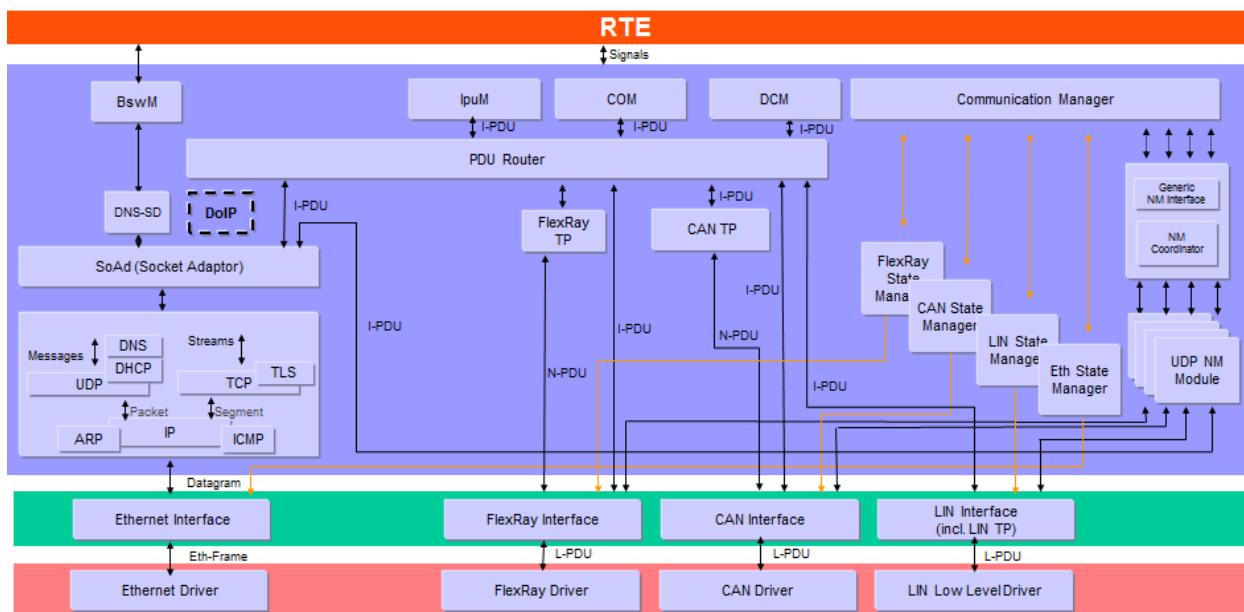


Figure 1: Extended AUTOSAR Communication Stack.

2 Acronyms and abbreviations

Acronym or Abbreviation:	Description:
API	Application Programming Interface
BSW	Basic Software
CWU	Car Wakeup
EthIf	Ethernet Interface
DET	Default Error Tracer
IP	Internet Protocol
NM	Network Management
PDU	Protocol Data Unit
SDU	Service Data Unit
TCP	Transmission Control Protocol
TCP/IP	A family of communication protocols used in computer networks
UDP	User Datagram Protocol
PNI	Partial Network Information
UdpNm	UDP Network Management

Term:	Description:
PDU transmission ability is disabled	This means that the NM message transmission has been disabled by the optional service UdpNm_DisableCommunication.
Repeat Message Request Bit Indication	UdpNm_SoAdIfRxIndication finds the Repeat Message Bit set in the Control Bit Vector of a received NM message.
NM PDU	Refers to the payload transmitted in a packet. It contains the NM User Data as well as the Control Bit Vector and the Source Node Identifier.
NM Packet	Refers to an Ethernet Frame containing an IP as well as a UDP header in addition to the data (PDU) transmitted by the NM in the payload section.
NM Message	Most abstract term referring to any single information item transferred within the methodology of the NM algorithm.
Bus-Off state	Refers to a situation where no cable is connected to the Ethernet HW.

3 Related documentation

3.1 Input documents

- [1] Layered Software Architecture
AUTOSAR_EXP_LayeredSoftwareArchitecture.pdf
- [2] General Requirements on Basic Software Modules
AUTOSAR_SRS_BSWGeneral.pdf
- [3] Requirements on Network Management
AUTOSAR_SRS_NetworkManagement.pdf
- [4] Specification of Ethernet Interface
AUTOSAR_SWS_EthernetInterface.pdf
- [5] Specification of FlexRay Network Management
AUTOSAR_SWS_FlexRayNetworkManagement.pdf
- [6] Specification of Communication Stack Types
AUTOSAR_SWS_CommunicationStackTypes.pdf
- [7] Specification of ECU Configuration
AUTOSAR_TPS_ECUConfiguration.pdf
- [8] Specification of BSW Scheduler
AUTOSAR_SWS_BSW_Scheduler.pdf
- [9] Specification of Generic Network Management Interface
AUTOSAR_SWS_NetworkManagementInterface.pdf
- [10] Specification of Communication Manager
AUTOSAR_SWS_ComManager.pdf
- [11] Specification of ECU State Manager
AUTOSAR_SWS_ECUSTateManager.pdf
- [12] Specification of Operating System
AUTOSAR_SWS_OS.pdf
- [13] Specification of Default Error Tracer
AUTOSAR_SWS_DefaultErrorTracer.pdf
- [14] Specification of Standard Types
AUTOSAR_SWS_StandardTypes.pdf
- [15] Specification of Platform Types
AUTOSAR_SWS_PlatformTypes.pdf

- [16] Specification of Compiler Abstraction
AUTOSAR_SWS_CompilerAbstraction.pdf
- [17] Basic Software Module Description Template
AUTOSAR_TPS_BSWModuleDescriptionTemplate.pdf
- [18] Specification of Socket Adaptor
AUTOSAR_SWS_SocketAdaptor.pdf
- [19] Requirements on Ethernet
AUTOSAR_SRS_Ethernet.pdf
- [20] List of Basic Software Modules
AUTOSAR_TR_BSWModuleList
- [21] General Specification of Basic Software Modules
AUTOSAR_SWS_BSWGeneral.pdf

3.2 Related standards and norms

- [22] IEEE
<http://www.opengroup.org/onlinepubs/000095399/>
- [23] ISO 14229 Road Vehicles – Unified Diagnostic Services (UDS)

3.3 Related specification

AUTOSAR provides a General Specification on Basic Software modules [21] (SWS BSW General), which is also valid for UDP Network Management.

Thus, the specification SWS BSW General shall be considered as additional and required specification for UDP Network Management.

4 Constraints and assumptions

4.1 Limitations

1. One instance of UdpNm is associated with only one NM-Cluster in one network. One NM-Cluster can have only one instance of UdpNm in one node.
2. One instance of UdpNm is associated with only one network within the same ECU.
3. UdpNm is only applicable for TCP/IP based systems.

Figure 2 presents an AUTOSAR NM stack within an example ECU belonging to two UDP NM-clusters.

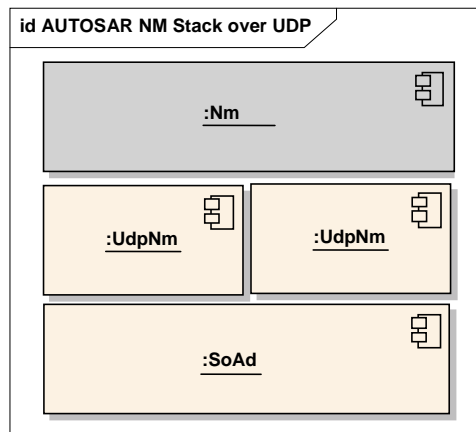


Figure 2: AUTOSAR NM stack within an example ECU belonging to two UDP NM-clusters

[SWS_UdpNm_00131] The AUTOSAR UdpNm algorithm shall support up to 250 nodes per NM-Cluster by default.

Note: The AUTOSAR UdpNm algorithm can support an arbitrary number of nodes per NM-cluster (even more than default 250 nodes per cluster, if necessary) – it is only a matter of configuration, since the upper limit is not fixed and depends on the trade off between response time, fault-tolerance and resulted bus load configured for the AUTOSAR UdpNm coordination algorithm. This might depend on the physical layer used.] ()

4.2 Applicability to car domains

N/A

5 Dependencies on other modules

UDP Network Management (UdpNm) uses services of the TCP/IP Stack and provides services to the Generic Network Management Interface (Nm).

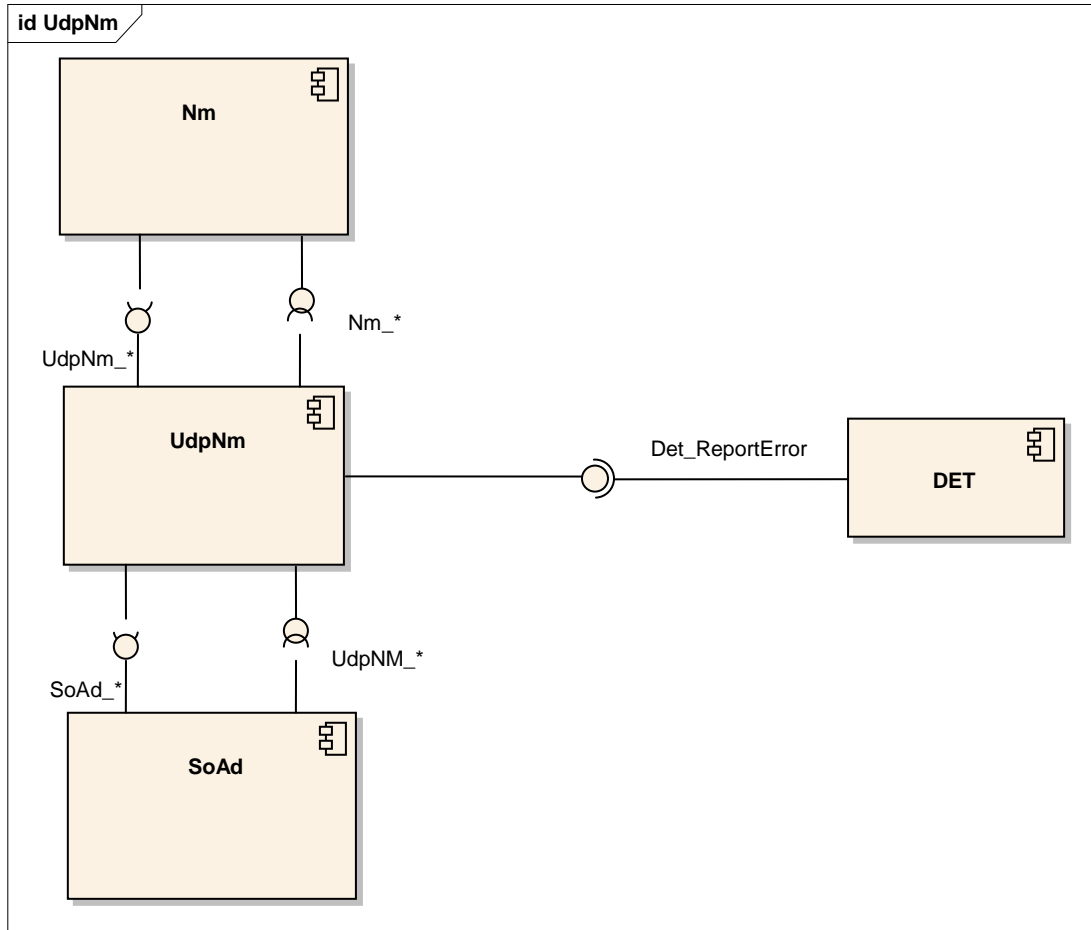


Figure 3: Dependencies on other modules.

5.1 File Structure

5.1.1 Code File Structure

[SWS_UdpNm_00081] The code file structure shall not be fully defined within this specification. However, the code file structure shall include the following files:

UdpNm_Lcfg.c (for link time configurable parameters)

UdpNm_PBcfg.c (for post build time configurable parameters)

These files shall contain all link time post build time configurable parameters.
] (SRS_BSW_00419, SRS_BSW_00346, SRS_BSW_00158, SRS_BSW_00308)

5.1.2 Header File Structure

[SWS_UdpNm_00044] The UdpNm module shall provide the following H-files:

UdpNm.h (for declaration of provided interface functions)

UdpNm_Cbk.h (for declaration of provided call-back functions)

UdpNm_Cfg.h (for pre-compile time configurable parameters)

] (SRS_BSW_00345, SRS_BSW_00381, SRS_BSW_00412,
SRS_BSW_00346, SRS_BSW_00158, SRS_BSW_00302)

[SWS_UdpNm_00082] [The UdpNm module shall include the following H-files:

ComStack_Types.h

Note: The following header files are indirectly included by
ComStack_Types.h:

- o Std_Types.h (for AUTOSAR standard types)
- o Platform_Types.h (for platform specific types)
- o Compiler.h (for compiler specific language extensions)

UdpNm.h (for declaration of provided interface functions)

Nm_Cbk.h (for UdpNm specific call-backs to the Generic Network
Management Interface)

Det.h (for interface of DET – optional included only if DET is configured)

NmStack_Types.h (for common network management types)

SchM_UdpNm.h (for services of the Basic Software Scheduler)

UdpNm_MemMap.h (for Memory Mapping)] (SRS_BSW_00348,
SRS_BSW_00353, SRS_BSW_00361, SRS_BSW_00301)

[SWS_UdpNm_00083] [The UdpNM module shall include the following header
files containing configuration data:

SoAd_Cfg.h (for the PDU IDs and socket connections)

Nm_Cfg.h (for the derived configuration items from Nm)
] (SRS_BSW_00383, SRS_BSW_00301)

[SWS_UdpNm_00311] [The UdpNm module shall include PduR_UdpNm.h if
UdpNmComUserDataSupport is enabled.] ()

6 Requirements traceability

Requirement	Description	Satisfied by
SRS_BSW_00005	Modules of the μ C Abstraction Layer (MCAL) may not have hard coded horizontal interfaces	SWS_UdpNm_NA_00999
SRS_BSW_00006	The source code of software modules above the μ C Abstraction Layer (MCAL) shall not be processor and compiler dependent.	SWS_UdpNm_NA_00999
SRS_BSW_00010	The memory consumption of all Basic SW Modules shall be documented for a defined configuration for all supported platforms.	SWS_UdpNm_NA_00999
SRS_BSW_00158	All modules of the AUTOSAR Basic Software shall strictly separate configuration from implementation	SWS_UdpNm_00044, SWS_UdpNm_00081
SRS_BSW_00160	Configuration files of AUTOSAR Basic SW module shall be readable for human beings	SWS_UdpNm_NA_00999
SRS_BSW_00161	The AUTOSAR Basic Software shall provide a microcontroller abstraction layer which provides a standardized interface to higher software layers	SWS_UdpNm_NA_00999
SRS_BSW_00162	The AUTOSAR Basic Software shall provide a hardware abstraction layer	SWS_UdpNm_NA_00999
SRS_BSW_00164	The Implementation of interrupt service routines shall be done by the Operating System, complex drivers or modules	SWS_UdpNm_NA_00999
SRS_BSW_00168	SW components shall be tested by a function defined in a common API in the Basis-SW	SWS_UdpNm_NA_00999
SRS_BSW_00170	The AUTOSAR SW Components shall provide information about their dependency from faults, signal qualities, driver demands	SWS_UdpNm_NA_00999
SRS_BSW_00172	The scheduling strategy that is built inside the Basic Software Modules shall be compatible with the strategy used in the system	SWS_UdpNm_NA_00999
SRS_BSW_00301	All AUTOSAR Basic Software Modules shall only import the necessary information	SWS_UdpNm_00082, SWS_UdpNm_00083
SRS_BSW_00302	All AUTOSAR Basic Software Modules shall only export information needed by other modules	SWS_UdpNm_00044
SRS_BSW_00305	Data types naming convention	SWS_UdpNm_NA_00999
SRS_BSW_00306	AUTOSAR Basic Software Modules shall be compiler and platform independent	SWS_UdpNm_NA_00999
SRS_BSW_00307	Global variables naming convention	SWS_UdpNm_NA_00999
SRS_BSW_00308	AUTOSAR Basic Software Modules shall not define global data in their header files, but in the C file	SWS_UdpNm_00081
SRS_BSW_00309	All AUTOSAR Basic Software Modules shall indicate all global data with read-only purposes by explicitly assigning the const keyword	SWS_UdpNm_NA_00999
SRS_BSW_00312	Shared code shall be reentrant	SWS_UdpNm_NA_00999
SRS_BSW_00314	All internal driver modules shall separate the	SWS_UdpNm_NA_00999

	interrupt frame definition from the service routine	
SRS_BSW_00321	The version numbers of AUTOSAR Basic Software Modules shall be enumerated according specific rules	SWS_UdpNm_NA_00999
SRS_BSW_00325	The runtime of interrupt service routines and functions that are running in interrupt context shall be kept short	SWS_UdpNm_NA_00999
SRS_BSW_00328	All AUTOSAR Basic Software Modules shall avoid the duplication of code	SWS_UdpNm_NA_00999
SRS_BSW_00330	It shall be allowed to use macros instead of functions where source code is used and runtime is critical	SWS_UdpNm_NA_00999
SRS_BSW_00331	All Basic Software Modules shall strictly separate error and status information	SWS_UdpNm_NA_00999
SRS_BSW_00333	For each callback function it shall be specified if it is called from interrupt context or not	SWS_UdpNm_NA_00999
SRS_BSW_00334	All Basic Software Modules shall provide an XML file that contains the meta data	SWS_UdpNm_NA_00999
SRS_BSW_00335	Status values naming convention	SWS_UdpNm_NA_00999
SRS_BSW_00336	Basic SW module shall be able to shutdown	SWS_UdpNm_NA_00999
SRS_BSW_00341	Module documentation shall contains all needed informations	SWS_UdpNm_NA_00999
SRS_BSW_00345	BSW Modules shall support pre-compile configuration	SWS_UdpNm_00044
SRS_BSW_00346	All AUTOSAR Basic Software Modules shall provide at least a basic set of module files	SWS_UdpNm_00044, SWS_UdpNm_00081
SRS_BSW_00347	A Naming separation of different instances of BSW drivers shall be in place	SWS_UdpNm_NA_00999
SRS_BSW_00348	All AUTOSAR standard types and constants shall be placed and organized in a standard type header file	SWS_UdpNm_00082
SRS_BSW_00353	All integer type definitions of target and compiler specific scope shall be placed and organized in a single type header	SWS_UdpNm_00082
SRS_BSW_00361	All mappings of not standardized keywords of compiler specific scope shall be placed and organized in a compiler specific type and keyword header	SWS_UdpNm_00082
SRS_BSW_00375	Basic Software Modules shall report wake-up reasons	SWS_UdpNm_NA_00999
SRS_BSW_00377	A Basic Software Module can return a module specific types	SWS_UdpNm_NA_00999
SRS_BSW_00381	The pre-compile time parameters shall be placed into a separate configuration header file	SWS_UdpNm_00044
SRS_BSW_00383	The Basic Software Module specifications shall specify which other configuration files from other modules they use at least in the description	SWS_UdpNm_00083
SRS_BSW_00410	Compiler switches shall have defined values	SWS_UdpNm_NA_00999

SRS_BSW_00412	References to c-configuration parameters shall be placed into a separate h-file	SWS_UdpNm_00044
SRS_BSW_00413	An index-based accessing of the instances of BSW modules shall be done	SWS_UdpNm_NA_00999
SRS_BSW_00415	Interfaces which are provided exclusively for one module shall be separated into a dedicated header file	SWS_UdpNm_NA_00999
SRS_BSW_00416	The sequence of modules to be initialized shall be configurable	SWS_UdpNm_NA_00999
SRS_BSW_00417	Software which is not part of the SW-C shall report error events only after the DEM is fully operational.	SWS_UdpNm_NA_00999
SRS_BSW_00419	If a pre-compile time configuration parameter is implemented as "const" it should be placed into a separate c-file	SWS_UdpNm_00081
SRS_BSW_00423	BSW modules with AUTOSAR interfaces shall be describable with the means of the SW-C Template	SWS_UdpNm_NA_00999
SRS_BSW_00424	BSW module main processing functions shall not be allowed to enter a wait state	SWS_UdpNm_NA_00999
SRS_BSW_00425	The BSW module description template shall provide means to model the defined trigger conditions of schedulable objects	SWS_UdpNm_NA_00999
SRS_BSW_00426	BSW Modules shall ensure data consistency of data which is shared between BSW modules	SWS_UdpNm_NA_00999
SRS_BSW_00427	ISR functions shall be defined and documented in the BSW module description template	SWS_UdpNm_NA_00999
SRS_BSW_00429	BSW modules shall be only allowed to use OS objects and/or related OS services	SWS_UdpNm_NA_00999
SRS_BSW_00432	Modules should have separate main processing functions for read/receive and write/transmit data path	SWS_UdpNm_NA_00999
SRS_Nm_00046	It shall be possible to trigger the startup of all Nodes at any Point in Time.	SWS_UdpNm_NA_00999
SRS_Nm_00050	The NM shall provide the current state of NM	SWS_UdpNm_NA_00999
SRS_Nm_00052	The NM interface shall signal to the application that all other ECUs are ready to sleep.	SWS_UdpNm_NA_00999
SRS_Nm_00054	There shall be a deterministic time from the point where all nodes agree to go to bus sleep to the point where bus is switched off.	SWS_UdpNm_NA_00999
SRS_Nm_00142	NM shall guarantee an upper limit for the bus load generated by NM itself.	SWS_UdpNm_NA_00999
SRS_Nm_00144	NM shall support communication clusters of up to 64 ECUs	SWS_UdpNm_NA_00999
SRS_Nm_00147	The NM algorithm shall be processor independent.	SWS_UdpNm_NA_00999
SRS_Nm_00151	The Network Management algorithm shall allow any node to integrate into an already running NM cluster	SWS_UdpNm_NA_00999

SRS_Nm_00153	The Network Management shall optionally provide a possibility to detect present nodes	SWS_UdpNm_NA_00999
SRS_Nm_00154	The Network Management API shall be independent from the communication bus	SWS_UdpNm_NA_00999
SRS_Nm_02509	The NM interface shall signal to the application that at least one other ECUs is not ready to sleep anymore.	SWS_UdpNm_NA_00999
SRS_Nm_02512	The NM shall give the possibility to enable or disable the network management related communication configured for an active NM node	SWS_UdpNm_00215, SWS_UdpNm_00216

7 Functional specification

7.1 Coordination algorithm

The AUTOSAR UdpNm is based on decentralized direct network management strategy, which means that every network node performs activities self-sufficient depending only on the UDP packets received and/or transmitted within the communication system.

The AUTOSAR UdpNm coordination algorithm is based on periodic NM packets, which are received by all nodes in the cluster via broadcast transmission. Reception of NM packets indicates that sending nodes want to keep the NM-cluster awake. If any node is ready to go to the Bus-Sleep Mode, it stops sending NM packets, but as long as NM packets from other nodes are received, it postpones transition to the Bus-Sleep Mode. Finally, if a dedicated timer elapses because no NM packets are received anymore, every node initiates transition to the Bus-Sleep Mode. If any node in the NM-cluster requires bus-communication, it can keep the NM-cluster awake by transmitting NM packets. For more details concerning the wakeup procedure itself, please refer to [10].

The main concept of the AUTOSAR UdpNm coordination algorithm can be defined by the following two key-requirements:

[SWS_UdpNm_00087] [Every network node shall transmit periodic NM PDUs as long as it requires bus-communication; otherwise it shall not transmit NM PDUs.] ()

[SWS_UdpNm_00088] [If bus communication is released and there are no NM PDUs on the bus for a configurable amount of time, determined by `UdpNmTimeoutTime` + `UdpNmWaitBusSleepTime` (both configuration parameters), transition into the Bus-Sleep Mode shall be performed.] ()

The overall state machine of the AUTOSAR UdpNm coordination algorithm can be defined as follows:

[SWS_UdpNm_00089] [The AUTOSAR UdpNm state machine shall contain states, transitions and triggers required for the AUTOSAR UdpNm coordination algorithm as seen from the point of view of one single node in the NM cluster.] ()

Note: A UML state chart of the AUTOSAR UdpNm state machine from the point of view of one single node in the NM cluster can be found in the API specifications chapter 8

7.2 Operational Modes

This chapter describes the operational modes of the AUTOSAR UdpNm coordination algorithm.

[SWS_UdpNm_00092] [The AUTOSAR UdpNm shall contain three operational modes visible at the modules interface:

Network Mode

Prepare Bus-Sleep Mode

Bus-Sleep Mode] ()

[SWS_UdpNm_00093] [Changes of the AUTOSAR UdpNm operational modes shall be signalled to the upper layer by means of call-back functions.] ()

7.2.1 Network Mode

[SWS_UdpNm_00094] [The Network Mode shall consist of three internal states:

Repeat Message State

Normal Operation State

Ready Sleep State] ()

[SWS_UdpNm_00095] [When the Network Mode is entered from Bus-Sleep Mode or Prepare Bus-Sleep Mode, by default, the Repeat Message State shall be entered.] ()

[SWS_UdpNm_00096] [When the Network Mode is entered, the NM-Timeout Timer shall be started.] ()

[SWS_UdpNm_00097] [When the Network Mode is entered, the UdpNm shall notify the upper layer by calling `Nm_NetworkMode`.] ()

[SWS_UdpNm_00098] [Upon successful reception of an NM PDU (call of `UdpNm_SoAdIfRxIndication`) in Network Mode, the NM-Timeout Timer shall be restarted.] ()

[SWS_UdpNm_00099] [Upon transmission of an NM PDU (call of `UdpNm_SoAdIfTxConfirmation` with `E_OK`) in the Network Mode, the NM-Timeout Timer shall be restarted.] ()

Note: As no transmission confirmation is available from the SoAd or the TCP/IP stack it is assumed that each Network Management PDU transmission request results in a successful Network Management PDU transmission.

[SWS_UdpNm_00206] [The NM-Timeout Timer shall be reset every time it is started or restarted.] ()

7.2.1.1 Repeat Message State

For nodes that are not in passive mode (refer to chapter 7.7.3) the Repeat Message State ensures, that any transition from Bus-Sleep or Prepare Bus-Sleep to the Network Mode becomes visible for the other nodes on the network. Additionally it

ensures that any node stays active for a minimum amount of time (`UdpNmRepeatMessageTime`). Optionally it can be used for detection of present nodes.

[SWS_UdpNm_00100] [When the Repeat Message State is entered from Bus-Sleep Mode, Prepare-Bus-Sleep Mode, Normal Operation State or Ready Sleep State transmission of NM packets shall be (re-) started unless passive mode is enabled.] ()

[SWS_UdpNm_00101] [When the NM-Timeout Timer expires in the Repeat Message State, the NM-Timeout Timer shall be restarted.] ()

[SWS_UdpNm_00102] [The NM shall stay in the Repeat Message State for a configurable amount of time determined by the `UdpNmRepeatMessageTime` (configuration parameter); after that time the Repeat Message State shall be left.] ()

[SWS_UdpNm_00103] [When Repeat Message State is left, the Normal Operation State shall be entered, if the network has been requested (see [SWS_UdpNm_00104](#)).] ()

[SWS_UdpNm_00106] [When Repeat Message State is left, the Ready Sleep State shall be entered, if the network has been released (see `SWS_UdpNm_00105`).] ()

[SWS_UdpNm_00107] [When Repeat Message State is left and the option `UdpNmNodeDetectionEnabled` is enabled, the Repeat Message Bit shall be cleared.] ()

[SWS_UdpNm_00137] [If the service `UdpNm_RepeatMessageRequest` is called in Repeat Message State, Prepare Bus-Sleep Mode or Bus-Sleep Mode, the UdpNm module shall not execute the service and return `E_NOT_OK`.] ()

7.2.1.2 Normal Operation State

The Normal Operation State ensures that any node can keep the NM-cluster awake as long as the network functionality is required.

[SWS_UdpNm_00116] [When the Normal Operation State is entered from Ready Sleep State, transmission of NM PDUs shall be started unless passive mode is enabled or the NM message transmission ability has been disabled.] ()

[SWS_UdpNm_00117] [When the NM-Timeout Timer expires in the Normal Operation State, the NM-Timeout Timer shall be restarted.] ()

[SWS_UdpNm_00118] [When the network is released and the current state is Normal Operation State, the Normal Operation State shall be left and the Ready Sleep state shall be entered (refer to [SWS_UdpNm_00105](#)).] ()

[SWS_UdpNm_00119] [At Repeat Message Request Bit Indication in the Normal Operation State, the Normal Operation State shall be left and the Repeat Message State shall be entered.] ()

[SWS_UdpNm_00120] [At Repeat Message Request (UdpNm_RepeatMessageRequest) in the Normal Operation State, the Normal Operation State shall be left and the Repeat Message State shall be entered.] ()

[SWS_UdpNm_00121] [At Repeat Message Request (UdpNm_RepeatMessageRequest) in Normal Operation State the Repeat Message Bit shall be set.] ()

7.2.1.3 Ready Sleep State

The Ready Sleep State ensures that any node in the NM-cluster waits with transition to the Prepare Bus-Sleep Mode as long as any other node keeps the NM-cluster awake.

[SWS_UdpNm_00108] [When the Ready Sleep State is entered from Repeat Message State or Normal Operation State, transmission of NM PDUs shall be stopped.] ()

Note: If passive mode is enabled no NM PDUs are transmitted, no action is required.

[SWS_UdpNm_00109] [When the NM-Timeout Timer expires in the Ready Sleep State, the Ready Sleep State shall be left and the Prepare Bus-Sleep Mode shall be entered.] ()

[SWS_UdpNm_00110] [When the network is requested and the current state is the Ready Sleep State, the Ready Sleep State shall be left and the Normal Operation State shall be entered (refer to [SWS_UdpNm_00104](#)).] ()

[SWS_UdpNm_00111] [At Repeat Message Request Bit Indication in the Ready Sleep State, the Ready Sleep State shall be left and the Repeat Message State shall be entered.] ()

[SWS_UdpNm_00112] [At Repeat Message Request (UdpNm_RepeatMessageRequest) in the Ready Sleep State, the Ready Sleep State shall be left and the Repeat Message State shall be entered.] ()

[SWS_UdpNm_00113] [At Repeat Message Request (UdpNm_RepeatMessageRequest) in Ready Sleep State the Repeat Message Bit shall be set.] ()

7.2.2 Prepare Bus-Sleep Mode

The purpose of the Prepare Bus Sleep state is to ensure that all nodes have time to stop their network activity before the Bus Sleep state is entered. Bus activity is calmed down (i.e. queued messages are transmitted in order to empty all Tx-buffers) and finally there is no activity on the bus in the Prepare Bus-Sleep Mode.

[SWS_UdpNm_00114] [When Prepare Bus-Sleep Mode is entered, the UdpNm shall notify the upper layer by calling `Nm_PrepareBusSleepMode.`] ()

[SWS_UdpNm_00115] [The NM shall stay in the Prepare Bus-Sleep Mode for a configurable amount of time determined by the `UdpNmWaitBusSleepTime` (configuration parameter); after that time the Prepare Bus-Sleep Mode shall be left and the Bus-Sleep Mode shall be entered.] ()

[SWS_UdpNm_00124] [Upon successful reception of an NM PDU in the Prepare Bus-Sleep Mode, the Prepare Bus-Sleep Mode shall be left and the Network Mode shall be entered; by default the Repeat Message State is entered (refer to SWS_UdpNm_00095).] ()

[SWS_UdpNm_00123] [When the network is requested in the Prepare Bus-Sleep Mode, the Prepare Bus-Sleep Mode shall be left and the Network Mode shall be entered; by default the Repeat Message State is entered (refer to SWS_UdpNm_00095)] ()

[SWS_UdpNm_00122] [When the network has been requested (see [SWS_UdpNm_00104](#)) in the Prepare Bus-Sleep Mode and the UdpNm module has entered Network Mode and if `UdpNmImmediateRestartEnabled` (configuration parameter) is `TRUE`, the UdpNm module shall transmit a Network Management PDU.] ()

Rationale: Other nodes in the cluster are still in Prepare Bus-Sleep Mode; in the exceptional situation described above transition into the Bus-Sleep Mode shall be avoided and bus-communication shall be restored as fast as possible.

Caused by the transmission offset for Network Management PDUs in UdpNm, the transmission of the first Network Management PDU in Repeat Message State can be delayed significantly. In order to avoid a delayed re-start of the network the transmission of a Network Management PDU can be requested immediately.

Note: If `UdpNmImmediateRestartEnabled` is `TRUE` and a wake-up line is used, a burst of Network Management PDUs occurs if all network nodes get a network request in Prepare Bus-Sleep Mode.

7.2.3 Bus-Sleep Mode

The purpose of the Bus-Sleep state is to reduce power consumption in the node, when no messages are to be exchanged.

The communication controller is switched to sleep mode, respective wakeup mechanisms are activated and finally power consumption is reduced to the adequate level in the Bus-Sleep Mode.

If a configurable amount of time determined by the `UdpNmTimeoutTime` + `UdpNmWaitBusSleepTime` (both configuration parameters) is identically configured for all nodes in the network management cluster, all nodes in the network management cluster that are coordinated with use of the AUTOSAR NM algorithm perform the transition into the Bus-Sleep Mode at approximately the same time.

Note: The parameters `UdpNmTimeoutTime` and `UdpNmWaitBusSleepTime` should have the same values within all network nodes of the NM-cluster.

Depending on the specific implementation, transition into the Bus-Sleep Mode takes place approximately at the same time. The time jitter experienced for this transition depends on the following factors:

- internal clock precision (oscillator's drift),
- NM-task cycle time (if tasks are not synchronized with a global time),
- NM PDUs waiting time in the Tx-queue (if transmission confirmation is made immediately after transmit request).

For a best case estimation only oscillator drift should be taken into account for a configurable amount of time determined by the value `UdpNmTimeoutTime` + `UdpNmWaitBusSleepTime` (both configuration parameters).

[SWS_UdpNm_00126] [When Bus-Sleep Mode is entered, the UdpNm shall notify the upper layer by calling `Nm_BusSleepMode`; this shall not be the case if Bus-Sleep Mode is entered by default at initialization.] ()

[SWS_UdpNm_00127] [When the UdpNm module receives successfully Network Management PDU in the Bus-Sleep Mode (call of `UdpNm_SoAdIfRxIndication`), the UdpNm module shall notify the upper layer by calling the callback function `Nm_NetworkStartIndication`.] ()

Rationale: To avoid race conditions and state inconsistencies between Network and Mode Management, UdpNm will not automatically perform the transition from Bus-Sleep Mode to Network Mode. UdpNm will only inform the upper layers which have to make the wake-up decision. NM packet reception in Bus-Sleep Mode must be handled depending on the current state of the ECU shutdown or startup process.

[SWS_UdpNm_00128] [If `UdpNm_PassiveStartUp` is called in the Bus-Sleep Mode or Prepare Bus Sleep Mode, the UdpNm module shall enter the Network Mode; by default the Repeat Message State is entered (refer to [SWS_UdpNm_00095](#) and [SWS_UdpNm_00104](#)).] ()

Note: In the Prepare Bus-Sleep Mode and Bus-Sleep Mode is assumed that the network is released, unless bus communication is explicitly requested.

[SWS_UdpNm_00129]: [When the network is requested in Bus-Sleep Mode, the UdpNm module shall enter the Network Mode; by default the UdpNm module shall enter the Repeat Message State (refer to [SWS_UdpNm_00095](#) and [SWS_UdpNm_00104](#)).] ()

7.3 Network states

Network states (i.e. 'requested' and 'released') are two additional states of the AUTOSAR UdpNm state machine that exist in parallel to the state machine. Network states denote, whether the software components need to communicate on the bus (the network state is then 'requested'); or whether the software components don't have to communicate on the bus (the bus network state is then 'released'); note that if the network is released an ECU may still communicate because some other ECU still request the network.

[SWS_UdpNm_00104] [The function call `UdpNm_NetworkRequest` shall request the network. I.e. the UdpNm module shall change network state to 'requested'.] ()

[SWS_UdpNm_00105] [The function call `UdpNm_NetworkRelease` shall release the network. I.e. the UdpNm module shall change network state to 'released'.] ()

7.4 Initialization

[SWS_UdpNm_00141] [After successful initialization the Network Management state shall be set to BusSleep Mode.] ()

Note: The UdpNm module should be initialized after SoAd is initialized and before any other network management service is called.

[SWS_UdpNm_00143] [When initialized, by default, the UdpNm module shall set the network state to 'released'.] ()

[SWS_UdpNm_00144] [When initialized, by default, the UdpNm module shall enter the Bus-Sleep Mode.] ()

[SWS_UdpNm_00145] [If AUTOSAR UdpNm is not initialized it shall not prohibit bus traffic.] ()

[SWS_UdpNm_00060] [The function `UdpNm_Init` shall select the active configuration set by means of a configuration pointer parameter being passed (see 8.3.1).] ()

[SWS_UdpNm_00061] [After initialization the UdpNm Message Cycle Timer shall be stopped.] ()

Note: No timer (UdpNm Message Cycle Timer) is needed if `UdpNmPassiveModeEnabled` is `TRUE`, because no NM messages are transmitted by such nodes.

[SWS_UdpNm_00033] [After initialization the transmission of NM messages shall be stopped.

] ()

[SWS_UdpNm_00039] [If UdpNm is not initialized a call of any UdpNm function except `UdpNm_Init` shall be rejected and `E_NOT_OK` shall be returned. If Default Error detection is enabled it shall report `UDPNM_E_NO_INIT` to the Default Error Tracer.] ()

[SWS_UdpNm_00025] [After initialization each byte of the user data bytes shall be set to `0xFF`.] ()

[SWS_UdpNm_00085] [After initialization the Control Bit Vector shall be set to `0x00`.] ()

[SWS_UdpNm_00148] [All instances of UDP NM on different ECUs in one NM cluster shall use the same UDP receive port.] ()

7.5 Execution

7.5.1 Processor architecture

[SWS_UdpNm_00146] [The AUTOSAR UdpNm coordination algorithm shall be processor independent, meaning it shall not rely on any processor specific hardware support and thus shall be realizable on any processor architecture that is within the scope of AUTOSAR.] ()

7.5.2 Timing parameters

[SWS_UdpNm_00246] [The configuration parameter `UdpNmTimeoutTime` shall determine the AUTOSAR UdpNm timing parameter NM-Timeout Time.] ()

[SWS_UdpNm_00247] [The configuration parameter `UdpNmRepeatMessageTime` shall determine the AUTOSAR UdpNm timing parameter Repeat Message Time.] ()

[SWS_UdpNm_00248] [The configuration parameter `UdpNmWaitBusSleepTime` shall determine the AUTOSAR UdpNm timing parameter Wait Bus-Sleep Time.] ()

[SWS_UdpNm_00249] [The optional configuration parameter `UdpNmRemoteSleepIndTime` shall determine the AUTOSAR UdpNm timing parameter Remote Sleep Indication Time.] ()

7.6 Communication Scheduling

7.6.1 NM Message Transmission

Note: The transmission mechanisms described in this chapter are only relevant if the NM message transmission ability is enabled.

[SWS_UdpNm_00072] [The transmission of NM messages shall be configurable by means of `UdpNmPassiveModeEnabled` (see chapter 10.2).] ()

Note: Passive nodes do not transmit NM messages, i.e. they can not actively influence the shut down decision, but they do receive NM message in order to be able to shut down synchronously.

Note: The transmission mechanisms described in this chapter are only relevant if `UdpNmPassiveModeEnabled` is `FALSE`.

[SWS_UdpNm_00237] [The `UdpNm` module shall provide the periodic transmission mode. In this transmission mode the `UdpNm` module shall send Network Management PDUs periodically.] ()

Note: The periodic transmission mode is used in the "Repeat Message State" and "Normal Operation State".

[SWS_UdpNm_00005] [If the Repeat Message State is not entered via `UdpNm_NetworkRequest` OR `UdpNmImmediateNmTransmissions` is zero the transmission of NM PDU shall be delayed by `UdpNmMsgCycleOffset` after entering the repeat message state.] ()

Note: This mechanism prevents bursts of NM messages.

[SWS_UdpNm_00334] [When entering the Repeat Message State from Bus Sleep Mode or Prepare Bus Sleep Mode because of `UdpNm_NetworkRequest()` (active wakeup) and if `UdpNmImmediateNmTransmissions` is greater zero, the NM PDUs shall be transmitted using `UdpNmImmediateNmCycleTime` as cycle time. The transmission of the first NM PDU shall be triggered as soon as possible. After the transmission the Message Cycle Timer shall be reloaded with `UdpNmImmediateNmCycleTime`. The `UdpNmMsgCycleOffset` shall not be applied in this case.] ()

[SWS_UdpNm_00006] [If Normal Operation State is entered from Ready Sleep State the transmission of NM PDUs shall be started immediately.] ()

[SWS_UdpNm_00454] [If `UdpNmPnHandleMultipleNetworkRequests` is set to `TRUE` `UdpNm_NetworkRequest` shall trigger a state transition from Network Mode to Repeat Message state. If PDU transmission ability is enabled the NM PDUs shall be transmitted using `UdpNmImmediateNmCycleTime` as cycle time. The

transmission of the first NM PDU shall be triggered as soon as possible. After the transmission the Message Cycle Timer shall be reloaded with `UdpNmImmediateNmCycleTime`. The `UdpNmMsgCycleOffset` shall not be applied in this case.] ()

Note: `UdpNmImmediateNmTransmissions` has to be greater zero in this case due to [ECUC UdpNm 00075](#).

[SWS_UdpNm_00330] [If NM PDUs shall be transmitted with `UdpNmImmediateNmCycleTime` (See [SWS UdpNm 00334](#) and [SWS UdpNm 00454](#)), `UdpNm` shall ensure that `UdpNmImmediateNmTransmissions` (including first immediate transmission) with this timing are requested successfully. If a transmission request to SoAd fails (`E_NOT_OK` is returned), `UdpNm` shall retry the transmission request in the next main function. Afterwards `UdpNm` shall continue transmitting NM PDUs using the `UdpNmMsgCycleTime`.] ()

Note: While transmitting NM PDUs using the `UdpNmImmediateNmCycleTime` no other Nm PDUs shall be transmitted (i.e. the `UdpNmMsgCycleTime` transmission cycle is stopped).

[SWS_UdpNm_00032] [If transmission of NM PDUs has been started and the `UdpNm` Message Cycle Timer expires an NM PDU shall be transmitted through the SoAd by calling `SoAd_IfTransmit`.] ()

[SWS_UdpNm_00040] [If the `UdpNm` Message Cycle Timer expires it shall be restarted with `UdpNmMsgCycleTime`.] ()

[SWS_UdpNm_00051] [If transmission of NM PDUs has been stopped the `UdpNm` Message Cycle Timer shall be canceled.] ()

[SWS_UdpNm_00007] [If parameter `UdpNmRetryFirstMessageRequest` (see [ECUC_UdpNm_00085](#)) is TRUE and if the first transmit request after transition from Bus Sleep to Repeat Message State is not accepted by SoAd, the message request shall be repeated in the next main function until one transmit request is accepted by SoAd.]()

Note: This feature can be used in case of partial network wakeup filter to avoid a blocking of all messages in case of passive start-up and first message request is not accepted by SoAd due to EthSM could not enable transmission path fast enough (e.g. in case of asynchronous transceiver handling).

7.6.2 Reception

If an NM message has been successfully received, the SoAd will call `UdpNm_SoAdIfRxIndication`.

[SWS_UdpNm_00035] [Upon a call of `UdpNm_SoAdIfRxIndication`, the `UdpNm` module shall copy the data of the Network Management PDU referenced in the function parameter to an internal buffer.] ()

[SWS_UdpNm_00037] [When an NM PDU has been received, the `Nm` function `Nm_PduRxIndication` shall be called, if `UdpNmPduRXIndicationEnabled` (configuration parameter) is `TRUE`.] ()

7.7 Additional features

7.7.1 Detection of Remote Sleep Indication (optional)

The “Remote Sleep Indication” denotes a situation, where a node in Normal Operation State finds all other nodes in the cluster are ready to sleep. The node still in Normal Operation State will still keep the bus awake.

[SWS_UdpNm_00149] [Detection of remote sleep indication shall be statically configurable with use of the `UdpNmRemoteSleepIndEnabled` switch (configuration parameter).] ()

[SWS_UdpNm_00150] [If no NM PDUs are received in the Normal Operation State for a configurable amount of time determined by the `UdpNmRemoteSleepIndTime` (configuration parameter), the NM shall notify the Generic Network Management Interface that all other nodes in the cluster are ready to sleep (the so-called ‘Remote Sleep Indication’) by calling `Nm_RemoteSleepIndication`.] ()

[SWS_UdpNm_00151] [If Remote Sleep Indication has been previously detected and if an NM PDU is received in the Normal Operation State or Ready Sleep State again, the NM shall notify the Generic Network Management Interface that some nodes in the cluster are not ready to sleep anymore (the so-called ‘Remote Sleep Cancellation’) by calling `Nm_RemoteSleepCancellation`.] ()

[SWS_UdpNm_00152] [If Remote Sleep Indication has been previously detected and if Repeat Message State is entered from Normal Operation State, the NM shall notify the Generic Network Management Interface that some nodes in the cluster are not ready to sleep anymore (the so-called ‘Remote Sleep Cancellation’) by calling `Nm_RemoteSleepCancellation`.] ()

[SWS_UdpNm_00154] [The NM shall reject a check of Remote Sleep Indication in Bus-Sleep Mode, Prepare Bus-Sleep Mode and Repeat Message State; the service shall not be executed and `E_NOT_OK` shall be returned.] ()

7.7.2 User Data (optional)

[SWS_UdpNm_00158] [Support of NM user data shall be statically configurable using the `UdpNmUserDataEnabled` switch (configuration parameter).] ()

[SWS_UdpNm_00159] [When `UdpNm_SetUserData` is called, the NM user data for NM packets transmitted next on the bus shall be set; operation of setting the NM user data shall guarantee data consistency.] ()

[SWS_UdpNm_00160] [When `UdpNm_GetUserData` is called, the NM user data contained in the payload of the most recently received NM PDU shall be provided; operation of providing the NM user data shall guarantee data consistency.] ()

Note: If NM user data is configured it will be sent for sure in the Repeat Message State. In Ready Sleep State the user data will not be sent.

[SWS_UdpNm_00312] [If `UdpNmComUserDataSupport` is enabled the API `UdpNm_SetUserData` shall not be available.] ()

[SWS_UdpNm_00317] [If `UdpNmComUserDataSupport` is enabled and NM-PDU is not configured for triggered transmission in `SoAd` (`SoAdBswModules/SoAdIfTriggerTransmit = FALSE`), the `UdpNm` shall collect the NM User Data from the referenced NM I-PDU by calling `PduR_UdpNmGetTxData` and combine the user data with the further NM bytes each time before it requests the transmission of the corresponding NM message.] ()

Note: In case of triggered transmission no data is needed at the transmission request, just the length is needed. The data will be collected within `UdpNm_TriggerTransmit` (see chapter 8.4.3 `UdpNm_TriggerTransmit`).

7.7.3 Passive Mode (optional)

In Passive Mode the node is only receiving NM messages but not transmitting any NM messages.

[SWS_UdpNm_00161] [Passive Mode shall be statically configurable with use of the `UdpNmPassiveModeEnabled` switch (configuration parameter).] ()

[SWS_UdpNm_00162] [Passive Mode shall be statically configured consistent for all instances within one ECU.] ()

[SWS_UdpNm_00163] [If Passive Mode is used (configuration parameter `UdpNmPassiveModeEnabled`) the following options must not be used:

Bus	Synchronization
(configuration parameter <code>UdpNmBusSynchronizationEnabled</code>)	
Remote	Sleep
(configuration parameter <code>UdpNmRemoteSleepIndEnabled</code>)	Indication
Node	Detection
(configuration parameter <code>UdpNmNodeDetectionEnabled</code>)]	()

7.7.4 NM PDU Rx Indication (optional)

[SWS_UdpNm_00164] [At successful reception of a NM PDU the UdpNm shall notify the upper layer by calling `Nm_PduRxIndication`.] ()

Rationale: If any higher software layer needs to retrieve the NM PDU data of every NM PDU it is required to have an Rx Indication. Polling of the NM PDU data could result in loss of received NM PDU data in case of an NM PDU burst.

Note: `UdpNm_SoAdIfRxIndication` is called by SoAd upon NM PDU reception.

[SWS_UdpNm_00165] [The optional service `Nm_PduRxIndication` shall be statically configurable. It shall be available if `UdpNmPduRXIndicationEnabled` is `TRUE`.] ()

7.7.5 State change notification (optional)

[SWS_UdpNm_00166] [All changes of the AUTOSAR UdpNm states shall be notified to the upper layer by calling `Nm_StateChangeNotification` if the callback `Nm_StateChangeNotification` is enabled (configuration parameter `UdpNmStateChangeIndEnabled` is `TRUE`).] ()

7.7.6 Communication Control (optional)

[SWS_UdpNm_00168] [Communication Control shall be statically configurable with use of the `UdpNmComControlEnabled` switch (configuration parameter).] ()

[SWS_UdpNm_00169] [During initialization of the UdpNm module, the UdpNm module shall enable the Network Management PDU transmission (start the UdpNm Message Cycle Timer with `UdpNmMsgCycleOffset`).] ()

[SWS_UdpNm_00170] [The optional service `UdpNm_DisableCommunication` shall disable the NM PDU transmission ability.] ()

Note: The NM coordination algorithm cannot work correctly if NM PDU transmission ability is disabled. Therefore it has to be ensured that the ECU is not shutdown as long as the NM PDU transmission ability is disabled.

If `UdpNm_NetworkRelease` is called and NM PDU transmission ability has been disabled, ECU will shut down. This ensures that ECU can shut down also in case of race conditions (e.g. diagnostic session left shortly before enabling communication) or a wrong usage of communication control.

[SWS_UdpNm_00172] [The optional service `UdpNm_DisableCommunication` shall return `E_NOT_OK`, if the current mode is not Network Mode.] ()

[SWS_UdpNm_00173] [When the Network Management PDU transmission ability is disabled, the UdpNm module shall stop the UdpNm Message Cycle Timer in order to stop the transmission of Network Management PDUs.] ()

[SWS_UdpNm_00174] [When the NM PDU transmission ability is disabled, the NM-Timeout Timer shall be stopped.] ()

[SWS_UdpNm_00175] [When the NM PDU transmission ability is disabled, the detection of Remote Sleep Indication Timer shall be suspended.] ()

[SWS_UdpNm_00178] [When the Network Management PDU transmission ability is enabled, the UdpNm module shall start the UdpNm Message Cycle Timer with `UdpNmMsgCycleOffset` in order to start transmission of Network Management PDUs.] ()

[SWS_UdpNm_00179] [When the NM PDU transmission ability is enabled, the NM-Timeout Timer shall be restarted.] ()

[SWS_UdpNm_00180] [When the NM PDU transmission ability is enabled, the detection of Remote Sleep Indication Timer shall be resumed.] ()

[SWS_UdpNm_00181] [The optional service `UdpNm_RequestBusSynchronization` shall return `E_NOT_OK` if the NM PDU transmission ability is disabled.] ()

7.7.7 NM Coordinator synchronization support (optional)

When having more than one coordinator connected to the same bus a special bit in the CBV, the `NmCoordinatorSleepReady` bit is used to indicate that the main coordinator requests to start shutdown sequence. The main functionality of the algorithm is described in the Nm module.

[SWS_UdpNm_00320] [If the UdpNm called `NM_CoordReadyToSleepIndication` and is still in Network Mode it shall notify the Nm by calling `Nm_CoordReadyToSleepCancellation` on the first reception of a NM message with the `NmCoordinatorSleepReady` bit (see CBV) set it to 0] ()

[SWS_UdpNm_00364] [If UdpNm has entered Network mode or called `Nm_CoordReadyToSleepCancellation` before it shall notify the NM by calling `Nm_CoordReadyToSleepIndication` on the first reception of NM message with the `NmCoordinatorSleepReady` bit (see CBV) set to 1] ()

[SWS_UdpNm_00321] [If `UdpNmCoordinatorSyncSupport` is set to `TRUE` and the API `UdpNm_SetSleepReadyBit` is called UdpNm shall set the "NM Coordinator

Sleep Ready Bit" bit to passed value and trigger a single Network Management PDU.] ()

[SWS_UdpNm_00322] [The API `UdpNm_SetSleepReadyBit()` and the feature "Coordinated Bus Shutdown" shall only be available if `UdpNmCoordinatorSyncSupport` is set to TRUE.] ()

7.8 Partial Networking

7.8.1 Rx Handling of NM PDUs

[SWS_UdpNm_00328] If the `UdpNmPnEnabled` is FALSE, the `UdpNm` shall perform the normal Rx Indication handling and the partial networking extensions shall be disabled.] ()

[SWS_UdpNm_00329] If `UdpNmPnEnabled` is TRUE, the PNI bit in the received NM-PDU is 0 and `UdpNmAllNmMessagesKeepAwake` is TRUE, the `UdpNm` module shall perform the normal Rx Indication handling omitting the extensions for partial networking.] ()

[SWS_UdpNm_00462] If `UdpNmPnEnabled` is TRUE, the PNI bit in the received NM-PDU is 0 and `UdpNmAllNmMessagesKeepAwake` is FALSE, the `UdpNm` module shall ignore the received NM-PDU.] ()

[SWS_UdpNm_00331] [If `UdpNmPnEnabled` is TRUE and the PNI bit in the received NM-PDU is 1, `UdpNm` module shall process the Partial Networking Information of the NM-PDU as described in chapter 7.8.3 to 7.8.5.] ()

7.8.2 Tx Handling of NM PDUs

[SWS_UdpNm_00332] If `UdpNmPnEnabled` is TRUE the `UdpNm` module shall set the value of the transmitted PNI bit in the CBV to 1.] ()

Note: The usage of the CBV is mandatory in case Partial Networking is used.

[SWS_UdpNm_00333] [If `UdpNmPnEnabled` is FALSE the `UdpNm` module shall set the value of the transmitted PNI bit in the CBV always to 0.] ()

7.8.3 NM PDU Filter Algorithm

[SWS_UdpNm_00335] [The range (in bytes) that contains the PN request information (PN Info Range) in the received NM-PDU is defined by `UdpNmPnInfoOffset` (in bytes) starting from byte 0 and `UdpNmPnInfoLength` (in bytes). This range is called PN Info Range.] ()

Example:

- `UdpNmPnInfoOffset` = 3
- `UdpNmPnInfoLength` = 2

Only Byte 3 and Byte 4 of the NM message contains PN request information

[SWS_UdpNm_00336] [Every bit of the PN Info Range represents one Partial Network. If the bit is set to 1 the Partial Network is requested. If the bit is set to 0 there is no request for this PN.] ()

[SWS_UdpNm_00337] [By means of the configuration parameter `UdpNmPnFilterMaskByte` the UdpNm is able to detect which PN is relevant for the ECU and which not.

Each bit of `UdpNmPnFilterMaskByte` has the following meaning:

- 0 The PN request is irrelevant for the ECU. The communication stack of the ECU is not kept awake if this bit is set in a received NM-PDU.
- 1 The PN request is relevant for the ECU. The communication stack of the ECU is kept awake if this bit is set in a received NM-PDU.] ()

[SWS_UdpNm_00338] [Each PN filter mask byte shall be mapped (bitwise AND) to the corresponding byte in the PN info range of the NM message.] ()

[SWS_UdpNm_00339] [If at least one bit within the PN Info Range of the received NM-PDU matches with a bit in the NM filter mask the PN request information is relevant for the ECU] ()

[SWS_UdpNm_00460] [If no relevant PN is requested in the received NM-PDU and `UdpNmAllNmMessagesKeepAwake` is `FALSE` the PDU shall be dropped from further processing.] ()

[SWS_UdpNm_00461] [If no relevant PN is requested in the received NM-PDU and `UdpNmAllNmMessagesKeepAwake` is `TRUE` the PDU shall not be dropped from further Rx Indication handling.] ()

7.8.4 Aggregation of Internal and External Requested Partial Networks

Note: This feature is used by every ECU that has to switch I-PDU-Groups because of the activity of partial networks. (e.g. to prevent false timeouts) I-PDU-Groups shall be switched on if the corresponding PN is requested internally or externally. I-PDU-Groups shall not be switched off until all internal and external requests for the corresponding PN are released.

The logic for switching the IPDU-Groups is implemented by ComM. The UdpNm only provides the information if a PN is requested or not. The COM module is used to transfer the data to the upper layers.

To switch the I-PDU-Groups synchronously on all direct connected ECUs, UdpNm shall provide the information of a request change to the upper layer at (almost) the same time on every ECU. This is why the reset timer is restarted on every received and every sent NM message (see below).

The aggregated state of the internal/external requested PNs is called External

Internal Requests Aggregated (EIRA).

[SWS_UdpNm_00344] [If `UdpNmPnEiraCalcEnabled` is `TRUE`, the `UdpNm` shall provide the possibility to store external and internal requested PNs combined over all relevant channels (all `UdpNm` Channels where `UdpNmPnEnabled` is `TRUE`). At initialization the values of all PNs shall be set to 0 (not requested)] ()

[SWS_UdpNm_00347] [If

- `UdpNmPnEiraCalcEnabled` is `TRUE`
- a NM-PDU is received
- PNs are requested within this message (bits are set to 1)
- And the requested PNs are set to 1 within the [configured PN filter mask] then `UdpNm` shall store the request information (value 1) for these PNs] ()

[SWS_UdpNm_00348] [If

- `UdpNmPnEiraCalcEnabled` is `TRUE`
- NM-PDU is being requested to send by `UdpNm`
- PNs are requested within this message (bits are set to 1)
- And the requested PNs are set to 1 within the [configured PN filter mask] then `UdpNm` shall store the request information (value 1) for these PNs.] ()

[SWS_UdpNm_00345] [If `UdpNmPnEiraCalcEnabled` is `TRUE`, the `UdpNm` module shall provide a possibility to monitor each PN, if this PN is still externally or internally requested on at least one of the relevant channels.] ()

Note: This means, only one timer is required to handle one PN on multiple connected physical channels. For example: only 8 EIRA reset timers are required to handle the requests of a Gateway with 6 physical channels and 8 partial networks. This is possible because the switch of PN PDU-Groups is done global for the ECU and not dependent of the physical channel.

[SWS_UdpNm_00349] [If `UdpNmPnEiraCalcEnabled` is `TRUE` and a PN is requested by message reception or sending (see [SWS UdpNm_00347](#) and [SWS UdpNm_00348](#)) the monitoring for this PN shall be restarted with respect to `UdpNmPnResetTime`.] ()

Note: `UdpNmPnResetTime` shall be configured to a value greater than `UdpNmMsgCycleTime`. If `UdpNmPnResetTime` is configured to a value smaller than `UdpNmMsgCycleTime` and only one ECU requests the PN, the request state toggles in the EIRA because request state is reset before the requesting ECU is able to send the next NM message.

Note: `UdpNmPnResetTime` shall be configured to a value smaller than `UdpNmTimeoutTime` to avoid that the timer could elapse after NM already changed to Prepare Bus Sleep.

[SWS_UdpNm_00351] [If `UdpNmPnEiraCalcEnabled` is `TRUE` and a PN is not requested again within `UdpNmPnResetTime` the corresponding stored value for this PN shall be set to 0 (not requested)] ()

[SWS_UdpNm_00352] [If `UdpNmPnEiraCalcEnabled` is `TRUE` and the stored value for a PN is set to requested or back to not requested (see [SWS UdpNm_00347](#), [SWS UdpNm_00348](#) and [SWS UdpNm_00351](#)) `UdpNm` shall inform upper layers by calling `PduR_UdpNmRxIndication()` for the configured EIRA PDU (i.e changed EIRA information shall be passed to COM).] ()

[SWS_UdpNm_00372][If `UdpNmPnEiraCalcEnabled` is `TRUE` and `UdpNmPnEraCalcEnabled` is `TRUE`, the PN status information has to be stored separately for both, the EIRA and ERA information (compare [SWS UdpNm_00344](#) and [SWS UdpNm_00355](#))
] ()

7.8.5 Aggregation of External Requested Partial Networks

Note: This feature is used by the Gateways to collect only the external PN requests. The external PN requests are mirrored back to the requesting bus and provided to other (required) physical channels of a central gateway.

In case of a sub gateway the requests bit must not be mirrored back to the requesting physical channel in order to avoid static waking between central- and sub gateways. This logic shall be implemented by the ComM.

The `UdpNm` module provides the information if the PN is externally requested or not. The COM module is used for data transmission to the upper layer. The aggregated state of the external requested PNs is called “External Requests Aggregated” (ERA).

[SWS_UdpNm_00355] [If `UdpNmPnEraCalcEnabled` is `TRUE`, the `UdpNm` shall provide the possibility to store external requested PNs on each relevant channel. At initialization the values of all PNs shall be set to 0 (not requested)] ()

[SWS_UdpNm_00357] [If

- `UdpNmPnEraCalcEnabled` is `TRUE`
- a NM-PDU is received
- PNs are requested within this message (bits are set to 1)
- and the requested PNs are set to 1 within the [configured PN filter mask] then `UdpNm` shall store the request information (value 1) for these PNs] ()

[SWS_UdpNm_00358] [If `UdpNmPnEraCalcEnabled` is `TRUE`, the `UdpNm` module shall provide a possibility to monitor each relevant channel and for each PN if this PN is still externally requested.] ()

Note: This means, a separate timer is required to handle one PN on multiple physical channels.

For example: 48 ERA reset timers are required to handle the requests of a gateway with 6 physical channels and 8 partial networks. It is not possible to combine the reset timer like EIRA timers, because the external request mustn't be mirrored back to the requesting bus by a sub gateway. Thus it is required to detect the physical channel that is the source of the request bit.

[SWS_UdpNm_00359] [If `UdpNmPnEraCalcEnabled` is `TRUE` and a PN is requested by message reception (see [SWS UdpNM 00357](#)) the monitoring for this PN shall be restarted with respect to the `UdpNmPnResetTime`.] ()

Note: `UdpNmPnResetTime` shall be configured to a value greater than `UdpNmMsgCycleTime`. If `UdpNmPnResetTime` is configured to a value smaller than `UdpNmMsgCycleTime` and only one ECU requests the PN, the request state toggles in the ERA because request state is reset before the requesting ECU is able to send the next NM-PDU.

Note: `UdpNmPnResetTime` shall be configured to a value smaller than `UdpNmTimeoutTime` to avoid that the timer could elapse after NM already changed to Prepare Bus Sleep.

[SWS_UdpNm_00360] [If `UdpNmPnEraCalcEnabled` is `TRUE` and PN is not requested again within `UdpNmPnResetTime` then the corresponding stored value for this PN shall be set to not requested (value 0)] ()

[SWS_UdpNm_00361] [If `UdpNmPnEraCalcEnabled` is `TRUE` and the stored value for a PN changes to requested or back to not requested (see [SWS UdpNm 00357](#) and [SWS UdpNm 00360](#)), the `UdpNm` module shall inform the upper layers by calling `PduR_UdpNmRxIndication()` for the configured ERA PDU (i.e. changed ERA information shall be passed to the COM module).] ()

[SWS_UdpNm_00371][If `UdpNmPnEraCalcEnabled` is `TRUE` and `UdpNmPnEraCalcEnabled` is `TRUE`, the PN status information has to be stored separately for both EIRA and ERA information (compare [SWS UdpNm 00355](#)] ()

7.8.6 Spontaneous Transmission of NM-PDUs via `UdpNm_NetworkRequest`

[SWS_UdpNm_00362][If `UdpNm_NetworkRequest` is called, `UdpNmPnHandleMultipleNetworkRequests` is set to `TRUE` and `UdpNm` is in Ready Sleep State, Normal Operation State or Repeat Message State, `UdpNm` shall change to or restart the Repeat Message State] () .

Note: If `UdpNmPnHandleMultipleNetworkRequests` is set to `TRUE` the `UdpNm` feature 'Immediate Transmission' is mandatory.

Note: The PN Control Module (e.G. ComM) is responsible to call `UdpNm_NetworkRequest` if the PN request bits changes.

7.9 Payload (PDU) Structure

The figure below shows an example for n bytes PDU length:

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Byte 0	Source Node Identifier (default)							
Byte 1	Control Bit Vector (default)							
Byte 2	User data 0							
Byte 3	User data 1							
Byte 4	User data 2							
Byte 5	User data 3							
...	...							
Byte n	User data $n-2$							

Figure 4: NM packet payload (NM PDU) default format.

Note:

The length of the Network Management PDU is defined by the `PduLength` parameter in the "global" ECUC module ([`EcuC003_Conf`], see Ecu Configuration specification). The difference between number of enabled system bytes and length is the amount of user data bytes.

[SWS_UdpNm_00074] [The location of the source node identifier shall be configurable by means of `UDPNM_PDU_NID_POSITION` to Byte 0, Byte 1, or off (default: Byte 0).] ()

[SWS_UdpNm_00075] [The location of the control Bit vector shall be configurable by means of `UDPNM_PDU_CBV_POSITION` to Byte 0, Byte 1, or off (default: Byte 1).] ()

[SWS_UdpNm_00076] [The length of an NM packet shall not exceed the MTU(Maximum Transmission Unit)of the underlying physical transport layer.] ()

The figure below describes the format of the Control Bit Vector:

	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CBV	Res	PNL Bit	Res	Active Wakeup Bit	NM Coordinator Sleep Ready	Res R3.2 NM Coordinator ID (High Bit)	Res R3.2 NM Coordinator ID (Low Bit)	Repeat Message Request

Figure 5: Control Bit Vector.

[SWS_UdpNm_00045] [The Control Bit Vector shall consist of:

Bit 0: Repeat Message Request

0: Repeat Message State not requested

1: Repeat Message State requested

Bit 3 :NM Coordinator Sleep Bit

0: Start of synchronized shutdown is not requested by main coordinator

1: Start of synchronized shutdown is requested by main coordinator

Bit 4 Active Wakeup Bit

0: Node has not woken up the network (passive wakeup)

1: Node has woken up the network (active Wakeup)

- Bit 6 Partial Network Information Bit (PNI)

0: NM message contains no Partial Network request information

1: NM message contains Partial Network request information

Bit 1,2,5,7 are reserved for future extensions

0 : Disabled / Reserved for future usage] ()

Note: The Control Bit Vector is initialized with 0x00 during initialization (also refer to [SWS_UdpNm_00085](#)).

[SWS_UdpNm_00013] [The source node identifier shall be set with the configuration parameter `UDPNM_NODE_ID` unless `UDPNM_PDU_NID_POSITION` is set to off.] ()

[SWS_UdpNm_00135] [Support of Repeat Message Request Bit and Repeat Message State Request shall be statically configurable with use of the `UdpNmNodeDetectionEnabled` switch (configuration parameter).] ()

[SWS_UdpNm_00138] [The optional service call `UdpNm_GetPduData` shall provide whole payload (Source Node ID, Control Bit Vector and User Data) of the most recently received UDP NM packet.] ()

[SWS_UdpNm_00139] [The optional service `UdpNm_GetPduData` shall be statically configurable. It shall be available if `UdpNmNodeIdEnabled` or `UdpNmNodeDetectionEnabled` or `UdpNmUserDataEnabled` is TRUE.] ()

[SWS_UdpNm_00366] [If the `UdpNm` performs a state change from `BusSleep` state or `PrepareBusSleep` state to `NetworkMode` due to a call to `UdpNm_NetworkRequest()` (i.e. due to an active wakeup) and `UdpNmActiveWakeupBitEnabled` is TRUE, the `UdpNm` shall set the `ActiveWakeupBit` in the CBV.] ()

[SWS_UdpNm_00367] If the UdpNm module leaves the NetworkMode and UdpNmActiveWakeupBitEnabled is TRUE, the UdpNm module shall clear the ActiveWakeupBit in the CBV.] ()

7.10 Functional requirements on UdpNm API

[SWS_UdpNm_00014] If the node detection functionality is enabled, the function Nm_RepeatMessageIndication shall be called upon every reception of the RepeatMessageRequest bit if UDPNM_REPEAT_MSG_IND_ENABLED is enabled.] ()

[SWS_UdpNm_00086] If UdpNmUserDataEnabled is enabled and UDPNM_USER_DATA_LENGTH is set to 0x00 an error during configuration or compilation time shall be raised.] ()

7.11 Car Wakeup

[SWS_UdpNm_00373] The position of the Car Wakeup bit in the NM-PDU is defined by the configuration parameters UdpNmCarWakeUpBytePosition and UdpNmCarWakeUpBitPosition.] ()

[SWS_UdpNm_00374] If the Car Wakeup bit within any received NM-PDU is 1, UdpNmCarWakeUpRxEnabled is TRUE, and UdpNmCarWakeUpFilterEnabled is FALSE UdpNm shall call Nm_CarWakeUpIndication and perform the standard Rx indication handling.] ()

[SWS_UdpNm_00375] If UdpNm_GetPduData is called in the context of Nm_CarWakeUpIndication, UdpNm shall return the PDU data of the PDU that causes the call of Nm_CarWakeUpIndication.] ()

Note: This is required to enable ECU to identify detail about the sender of the Car Wakeup request

[SWS_UdpNm_00376] If UdpNmCarWakeUpFilterEnabled is TRUE, the Car Wakeup bit within any received NM-PDU is 1, UdpNmCarWakeUpRxEnabled is TRUE and the Node ID in the received NM-PDU is equal to UdpNmCarWakeUpFilterNodeId the UdpNm module shall call Nm_CarWakeUpIndication and perform the standard Rx Indication handling] ()

Note: The Car Wakeup filter is necessary to realize sub gateways that only consider the Car Wakeup of the central Gateway to avoid wrong wakeups

7.12 Error Classification

This section describes how the UdpNm module has to manage the error classes that may occur during the life cycle of this basic software.

The general requirements document of AUTOSAR [2] specifies that all basic software modules must distinguish (according to the product life cycle) two error types:

Development errors: these errors should be detected and fixed during the development phase. In most cases, these errors are software errors. The detection errors that should only occur during development can be switched off for production code (by static configuration, namely preprocessor switches).

Production errors: these errors are hardware errors and software exceptions that cannot be avoided and are expected to occur in the production (i.e. series) code. This kind of error is commonly known as a run-time error.

[SWS_UdpNm_00223] [On errors and exceptions, the UdpNm module shall not modify its current module state.] ()

7.12.1 Development Errors

[SWS_UdpNm_00018] [The following errors shall be detectable by the UdpNm depending on its build version (development/production mode).]

Type or error	Relevance	Related error code	Error Value
API service used without module initialization	Development	UDPNM_E_NO_INIT	0x01
API service called with wrong channel handle	Development	UDPNM_E_INVALID_CHANNEL	0x02
API service called with wrong PDU ID.	Development	UDPNM_E_INVALID_PDUID	0x03
UdpNm initialization has failed, e.g. selected configuration set doesn't exist	Development	UDPNM_E_INIT_FAILED	0x04
Null pointer has been passed as an argument	Development	UDPNM_E_PARAM_POINTER	0x12

] ()

7.12.2 Run Time Errors

The UdpNm module, currently does not specify any Run Time Error.

7.12.3 Transient Faults

The UdpNm module, currently does not specify any Transient Faults

7.12.4 Production Errors

The UdpNm module, currently does not specify any Production Errors

7.12.5 Extended Production Errors

The UdpNm module, currently does not specify any Extended Production Errors

7.12.6 Error detection

For details refer to the chapter 7.3 “Error Detection” in *SWS_BSWGeneral*.

7.12.7 Error notification

[SWS_UdpNm_00189] [Development errors shall not be returned by API functions; in case of a development error, the respective API function will return `E_NOT_OK`, if applicable.] ()

[SWS_UdpNm_00190] [Production errors shall not be returned by API functions; in case of a production error, the respective API function will return `E_NOT_OK`, if applicable.] ()

[SWS_UdpNm_00191] [If not initialized, the NM shall reject every API service apart from `UdpNm_Init`; the called function shall not be executed, but instead of that it shall report `UDPNM_E_NO_INIT` to the Default Error Tracer (if development error detection is enabled) and it shall return `E_NOT_OK` to the calling function] ()

[SWS_UdpNm_00192] [When NM API service with an invalid network handle is called, the called function shall not be executed, but instead of that it shall report `UDPNM_E_INVALID_CHANNEL` to the Default Error Tracer (if development error detection is enabled) otherwise it shall return `E_NOT_OK` to the calling function] ()

Note: The network handle is invalid if it is different from allowed configured values.

[SWS_UdpNm_00314] [If `UdpNmComUserDataSupport` is enabled and the `UdpNm User Data` length does not match with the length of the referenced I-PDU an error shall be reported at generation time.] ()

Note: NULL Pointer checking is specified within BSW General [\[22\]](#)

7.13 Scheduling of the main function

For details refer to the chapter 8.5 “Scheduled functions” in *SWS_BSWGeneral*.

7.14 Application notes

7.14.1 Wakeup notification

Wakeup notification is defined in detail in the ECU State Manager specification [\[11\]](#).

7.14.2 Coordination of coupled networks

[SWS_UdpNm_00185] [Support of bus synchronization on demand shall be statically configurable with use of the `UdpNmBusSynchronizationEnabled` switch (configuration parameter).] ()

Note: Since the shutdown of `UdpNm` can be done at any time, the call of the API `Nm_SynchronizationPoint` is not supported.

7.14.3 Debugging Concept

For details refer to the chapter 7.1.17 “Debugging support” in *SWS_BSWGeneral*.

7.15 Version check

For details refer to the chapter 5.1.8 “Version Check” in *SWS_BSWGeneral*.

7.16 Parameter check

[SWS_UdpNm_00196] [If detection of development errors is enabled by `UDPNM_DEV_ERROR_DETECT` (configuration parameter), validity checks for all input parameters shall be performed for each UDP NM API service call.] ()

[SWS_UdpNm_00197] [Parameter type checking shall be performed at compile time; if types do not match, the compilation process shall be stopped and respective compilation warnings or errors shall be returned as far as supported by the compiler.] ()

[SWS_UdpNm_00198] [Parameter value check (for parameters of the constant value) shall be performed at configuration time; if the value is invalid, the configuration process shall be stopped and the respective configuration error shall be reported.] ()

[SWS_UdpNm_00199] [Parameter value check (for parameters of the variable value) shall be performed at execution time; if the value is invalid, execution of a service shall be denied and the respective development error shall be reported.] ()

8 API specification

[SWS_UdpNm_00244] [The UdpNm module shall reject the execution of a service called with an invalid parameter and shall inform the DET.] ()

AUTOSAR UdpNm API consists of services, which are UDP specific and can be called whenever they are required; each service apart from `UdpNm_Init` refers to one NM channel only.

8.1 Imported Types

The following types of `Std_Types.h` are imported:

```
boolean
uint8
uint16
uint32
```

Module	Imported Type
ComStack_Types	NetworkHandleType
	PduIdType
	PduInfoType
Nm	Nm_ModeType
	Nm_StateType
Std_Types	Std_ReturnType
	Std_VersionInfoType

8.2 Type Definitions

8.2.1 UdpNm_ConfigType

This type shall contain the parameters of the container `UdpNm_GlobalConfig` and its sub containers.

[SWS_UdpNm_00308] [

Name:	UdpNm_ConfigType		
Type:	Structure		
Element:	void	implementation specific	This type shall contain the parameters of the container <code>UdpNm_GlobalConfig</code> and its sub containers.
Description:	--		

] ()

8.2.2 UdpNm_PduPositionType

[SWS_UdpNm_00304] [

Name:	UdpNm_PduPositionType		
Type:	Enumeration		
Range:	UDPNM_PDU_BYTE_0	0x00	Byte 0 is used
	UDPNM_PDU_BYTE_1	0x01	Byte 1 is used
	UDPNM_PDU_OFF	0xFF	Node Identification is not used
Description:	Used to define the position of the control bit vector within the NM PACKET.		

] ()

8.3 Function definitions

8.3.1 UdpNm_Init

[SWS_UdpNm_00208] [

Service name:	UdpNm_Init	
Syntax:	<pre>void UdpNm_Init(const UdpNm_ConfigType* UdpNmConfigPtr)</pre>	
Service ID[hex]:	0x01	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant	
Parameters (in):	UdpNmConfigPtr	Pointer to a selected configuration structure
Parameters (inout):	None	
Parameters (out):	None	
Return value:	None	
Description:	<p>Initialize the complete UdpNm module, i.e. all channels which are activated at configuration time are initialized. A UDP socket shall be set up with the TCP/IP stack.</p> <p>Caveats: This function has to be called after initialization of the TCP/IP stack.</p> <p>Configuration: Mandatory</p>	

] ()

[SWS_UdpNm_00210] [If an error has to be indicated to the DET the value 0x00 shall be used as the instance id.] ()

Rationale: the value 0 x 00 is not error value but instance ID

8.3.2 UdpNm_PassiveStartUp

[SWS_UdpNm_00211] [

Service name:	UdpNm_PassiveStartUp	
Syntax:	Std_ReturnType UdpNm_PassiveStartUp(NetworkHandleType nmChannelHandle)	
Service ID[hex]:	0x0e	
Sync/Async:	Asynchronous	
Reentrancy:	Reentrant (but not for the same NM-Channel)	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Passive startup of network management has failed
Description:	Passive startup of the AUTOSAR UdpNm. It triggers the transition from Bus-Sleep Mode or Prepare Bus Sleep Mode to the Network Mode in Repeat Message State. Caveats: UdpNm is initialized correctly. Configuration: Mandatory	

] ()

[SWS_UdpNm_00147] [If UdpNm_PassiveStartUp is called in the Network Mode, the UdpNm module shall not execute this service and shall return E_NOT_OK.] ()

8.3.3 UdpNm_NetworkRequest

[SWS_UdpNm_00213] [

Service name:	UdpNm_NetworkRequest	
Syntax:	Std_ReturnType UdpNm_NetworkRequest(NetworkHandleType nmChannelHandle)	
Service ID[hex]:	0x02	
Sync/Async:	Asynchronous	
Reentrancy:	Reentrant (but not for the same NM-Channel)	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Requesting of network has failed
Description:	Request the network, since ECU needs to communicate on the bus. Network state shall be changed to 'requested' Caveats: UdpNm is initialized correctly. Configuration: Optional (Only available if UdpNmPassiveModeEnabled == false)	

] ()

8.3.4 UdpNm_NetworkRelease

[SWS_UdpNm_00214] [

Service name:	UdpNm_NetworkRelease	
Syntax:	Std_ReturnType UdpNm_NetworkRelease(NetworkHandleType nmChannelHandle)	
Service ID[hex]:	0x03	
Sync/Async:	Asynchronous	
Reentrancy:	Reentrant (but not for the same NM-Channel)	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Releasing of network has failed
Description:	Release the network, since ECU doesn't have to communicate on the bus. Network state shall be changed to 'released'. Caveats: UdpNm is initialized correctly. Configuration: Optional (Only available if UdpNmPassiveModeEnabled == false)	

] ()

8.3.5 UdpNm_DisableCommunication

[SWS_UdpNm_00215] [

Service name:	UdpNm_DisableCommunication	
Syntax:	Std_ReturnType UdpNm_DisableCommunication(NetworkHandleType nmChannelHandle)	
Service ID[hex]:	0x0c	
Sync/Async:	Asynchronous	
Reentrancy:	Reentrant (but not for the same NM-Channel)	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Disabling of NM PDU transmission ability has failed
Description:	Disable the NM PDU transmission ability due to a ISO14229 Communication Control (0x28) service Caveats: UdpNm is initialized correctly. Configuration: Optional (Only available if UdpNmComControlEnabled == true)	

] (SRS_Nm_02512)

[SWS_UdpNm_00307] [If the module operates in passive mode (UdpNmPassiveModeEnabled) the service UdpNm_DisableCommunication shall have no effects and shall directly return E_NOT_OK.] ()

8.3.6 UdpNm_EnableCommunication

[SWS_UdpNm_00216] [

Service name:	UdpNm_EnableCommunication	
Syntax:	Std_ReturnType UdpNm_EnableCommunication(NetworkHandleType nmChannelHandle)	
Service ID[hex]:	0x0d	
Sync/Async:	Asynchronous	
Reentrancy:	Reentrant (but not for the same NM-Channel)	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Enabling of NM PDU transmission ability has failed
Description:	<p>Enable the NM PDU transmission ability due to a ISO14229 Communication Control (0x28) service</p> <p>Caveats: UdpNm is initialized correctly.</p> <p>Configuration: Optional (Only available if UdpNmComControlEnabled == true).</p>	

] (SRS_Nm_02512)

[SWS_UdpNm_00176] [The optional service UdpNm_EnableCommunication shall enable the NM PDU transmission ability if the NM PDU transmission ability is disabled.] ()

[SWS_UdpNm_00177] [The optional service UdpNm_EnableCommunication shall return E_NOT_OK if the NM PDU transmission ability is already enabled when the service is called.] ()

[SWS_UdpNm_00305] [The service UdpNm_EnableCommunication shall return E_NOT_OK, if the current mode is not Network Mode.] ()

[SWS_UdpNm_00306] [If the module operates in passive mode (UdpNmPassiveModeEnabled is TRUE) the service UdpNm_EnableCommunication shall have no effects and shall directly return E_NOT_OK.] ()

8.3.7 UdpNm_SetUserData

[SWS_UdpNm_00217] [

Service name:	UdpNm_SetUserData	
Syntax:	<pre>Std_ReturnType UdpNm_SetUserData(NetworkHandleType nmChannelHandle, const uint8* nmUserDataPtr)</pre>	
Service ID[hex]:	0x04	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
	nmUserDataPtr	Pointer where the user data for the next transmitted NM message shall be copied from.
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: No error
		E_NOT_OK: Setting of user data has failed
Description:	<p>Set user data for all NM messages transmitted on the bus after this function has returned without error.</p> <p>Caveats: UdpNm is initialized correctly.</p> <p>Configuration: Optional (Only available if UdpNmUserDataEnabled==true and UdpNmPassiveModeEnabled==false).</p>	

] ()

8.3.8 UdpNm_GetUserData

[SWS_UdpNm_00218] [

Service name:	UdpNm_GetUserData	
Syntax:	<pre>Std_ReturnType UdpNm_GetUserData(NetworkHandleType nmChannelHandle, uint8* nmUserDataPtr)</pre>	
Service ID[hex]:	0x05	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	nmUserDataPtr	Pointer where user data out of the most recently received NM message shall be copied to.
Return value:	Std_ReturnType	E_OK: No error
		E_NOT_OK: Getting of user data has failed
Description:	<p>Get user data from the most recently received NM message.</p> <p>Caveats: UdpNm is initialized correctly.</p> <p>Configuration: Optional (Only available if UdpNmUserDataEnabled == true).</p>	

] ()

8.3.9 UdpNm_GetNodeIdentifier

[SWS_UdpNm_00219] [

Service name:	UdpNm_GetNodeIdentifier	
Syntax:	<pre>Std_ReturnType UdpNm_GetNodeIdentifier(NetworkHandleType nmChannelHandle, uint8* nmNodeIdPtr)</pre>	
Service ID[hex]:	0x06	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	nmNodeIdPtr	Pointer where the source node identifier from the most recently received NM PDU shall be copied to.
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Getting of the source node identifier from the most recently received NM PDU has failed
Description:	Get node identifier from the most recently received NM PDU. Caveats: UdpNm is initialized correctly. Configuration: Optional (Only available if UdpNmNodeIdEnabled == true).	

] ()

[SWS_UdpNm_00132] [The optional service call UdpNm_GetNodeIdentifier shall provide the source node identifier contained in the most recently received NM packet.] ()

8.3.10 UdpNm_GetLocalNodeIdentifier

[SWS_UdpNm_00220] [

Service name:	UdpNm_GetLocalNodeIdentifier	
Syntax:	<pre>Std_ReturnType UdpNm_GetLocalNodeIdentifier(NetworkHandleType nmChannelHandle, uint8* nmNodeIdPtr)</pre>	
Service ID[hex]:	0x07	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	nmNodeIdPtr	Pointer where node identifier of the local node shall be copied to.
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Getting of the node identifier of the local node has failed
Description:	Get node identifier configured for the local node. Caveats: UdpNm is initialized correctly. Configuration: Optional (Only available if UdpNmNodeIdEnabled == true).	

] ()

[SWS_UdpNm_00133] [The optional service call UdpNm_GetLocalNodeIdentifier shall provide the node identifier configured for the local host node.] ()

8.3.11 UdpNm_RepeatMessageRequest

[SWS_UdpNm_00221] [

Service name:	UdpNm_RepeatMessageRequest	
Syntax:	<pre>Std_ReturnType UdpNm_RepeatMessageRequest(NetworkHandleType nmChannelHandle)</pre>	
Service ID[hex]:	0x08	
Sync/Async:	Asynchronous	
Reentrancy:	Reentrant (but not for the same NM-Channel)	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Setting of Repeat Message Request Bit has failed
Description:	Set Repeat Message Request Bit for all NM messages transmitted on the bus after this function has returned without error. Caveats: UdpNm is initialized correctly. Configuration: Configuration of UdpNm_RepeatMessageRequest: Optional (Only available if UdpNmNodeDetectionEnabled == true).	

] ()

8.3.12 UdpNm_GetPduData

[SWS_UdpNm_00309] [

Service name:	UdpNm_GetPduData	
Syntax:	<pre>Std_ReturnType UdpNm_GetPduData(NetworkHandleType nmChannelHandle, uint8* nmPduDataPtr)</pre>	
Service ID[hex]:	0x0a	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	nmPduDataPtr	Pointer where NM PDU shall be copied to.
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Getting of NM PDU data has failed
Description:	Get the whole PDU data out of the most recently received NM message. Caveats: UdpNm is initialized correctly. Configuration: Optional (Only available if UdpNmNodeIdEnabled==true or UdpNmNodeDetectionEnabled==true or UdpNmUserDataEnabled==true).	

] ()

8.3.13 UdpNm_GetState

[SWS_UdpNm_00310] [

Service name:	UdpNm_GetState	
Syntax:	<pre>Std_ReturnType UdpNm_GetState(NetworkHandleType nmChannelHandle, Nm_StateType* nmStatePtr, Nm_ModeType* nmModePtr)</pre>	
Service ID[hex]:	0x0b	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	nmStatePtr	Pointer where state of the network management shall be copied to.
	nmModePtr	Pointer where the mode of the network management shall be copied to.

Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Getting of NM state has failed
Description:	Returns the state and the mode of the network management. Caveats: UdpNm is initialized correctly. Configuration: Mandatory	

] ()

8.3.14 UdpNm_GetVersionInfo

[SWS_UdpNm_00224] [

Service name:	UdpNm_GetVersionInfo	
Syntax:	void UdpNm_GetVersionInfo(Std_VersionInfoType* versioninfo)	
Service ID[hex]:	0x09	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant	
Parameters (in):	None	
Parameters (inout):	None	
Parameters (out):	versioninfo	Pointer to where to store the version information of this module.
Return value:	None	
Description:	This service returns the version information of this module.	

] ()

[SWS_UdpNm_00318] [If DET is enabled for the UdpNm module, the function UdpNm_GetVersionInfo shall raise UDPNM_E_PARAM_POINTER, if the argument versioninfo is a NULL pointer and return without any action.] ()

8.3.15 UdpNm_RequestBusSynchronization

[SWS_UdpNm_00226] [

Service name:	UdpNm_RequestBusSynchronization	
Syntax:	Std_ReturnType UdpNm_RequestBusSynchronization(NetworkHandleType nmChannelHandle)	
Service ID[hex]:	0x14	
Sync/Async:	Asynchronous	
Reentrancy:	Non Reentrant	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Requesting of bus synchronization has failed
Description:	Request bus synchronization. Caveats: UdpNm is initialized correctly. Configuration: Optional (only available if UdpNmBusSynchronizationEnabled==true and UdpNmPassiveModeEnabled==false).	

] ()

[SWS_UdpNm_00130] [The service call UdpNm_RequestBusSynchronization shall trigger transmission of a single Network Management PDU if UdpNmPassiveModeEnabled (configuration parameter) is FALSE.] ()

Rationale: This service is typically used for supporting the NM gateway extensions.

[SWS_UdpNm_00187] [If UdpNm_RequestBusSynchronization is called in Bus-Sleep Mode and Prepare Bus-Sleep Mode the UdpNm module shall not execute the service and shall return E_NOT_OK.] ()

8.3.16 UdpNm_CheckRemoteSleepIndication

[SWS_UdpNm_00227] [

Service name:	UdpNm_CheckRemoteSleepIndication	
Syntax:	<pre>Std_ReturnType UdpNm_CheckRemoteSleepIndication(NetworkHandleType nmChannelHandle, boolean* NmRemoteSleepIndPtr)</pre>	
Service ID[hex]:	0x11	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant (but not for the same NM-Channel)	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
Parameters (inout):	None	
Parameters (out):	NmRemoteSleepIndPtr	Pointer where check result of remote sleep indication shall be copied to.
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Checking of remote sleep indication bits has failed
Description:	Check if remote sleep indication takes place or not. Caveats: UdpNm is initialized correctly. Configuration: Optional (only available if UdpNmRemoteSleepIndEnabled == true)	

] ()
[SWS_UdpNm_00153] [The service call UdpNm_CheckRemoteSleepIndication shall provide the information about current status of Remote Sleep Indication (i.e. already detected or not).] ()

8.3.17 UdpNm_SetCoordBits

[SWS_UdpNm_00222] [

Service name:	UdpNm_SetCoordBits	
Syntax:	<pre>Std_ReturnType UdpNm_SetCoordBits(NetworkHandleType nmChannelHandle, uint8 nmCoordBits)</pre>	
Service ID[hex]:	0x12	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant (but not for the same NM-Channel)	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
	nmCoordBits	2 bit value to set the NM coordinator ID in the control bit vector of each NM message (coding as depicted in Figure "Control Bit Vector".)
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: No error E_NOT_OK: Setting the coordinator ID bits has failed
Description:	Sets the NM coordinator ID in the control bit vector of each NM message.	

] ()

8.3.18 UdpNm_SetSleepReadyBit

[SWS_UdpNm_00324] [

Service name:	UdpNm_SetSleepReadyBit	
Syntax:	<pre>Std_ReturnType UdpNm_SetSleepReadyBit(NetworkHandleType nmChannelHandle, boolean nmSleepReadyBit)</pre>	
Service ID[hex]:	0x16	
Sync/Async:	Synchronous	
Reentrancy:	Non Reentrant	
Parameters (in):	nmChannelHandle	Identification of the NM-channel
	nmSleepReadyBit	Value written to ReadySleep Bit in CBV
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: No error
		E_NOT_OK: Writing of remote sleep indication bit has failed
Description:	Set the NM Coordinator Sleep Ready bit in the Control Bit Vector	

] ()

8.3.19 UdpNm_Transmit

[SWS_UdpNm_00313] [

Service name:	UdpNm_Transmit	
Syntax:	<pre>Std_ReturnType UdpNm_Transmit(PduIdType TxPduId, const PduInfoType* PduInfoPtr)</pre>	
Service ID[hex]:	0x49	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant for different PduIds. Non reentrant for the same PduId.	
Parameters (in):	TxPduId	Identifier of the PDU to be transmitted
	PduInfoPtr	Length of and pointer to the PDU data and pointer to MetaData.
Parameters (inout):	None	
Parameters (out):	None	
Return value:	Std_ReturnType	E_OK: Transmit request has been accepted.
		E_NOT_OK: Transmit request has not been accepted.
Description:	Requests transmission of a PDU.	

] ()

[SWS_UdpNm_00315] [If UdpNmComUserDataSupport is enabled the UdpNm implementation shall provide an API UdpNm_Transmit. This API shall never be called by PduR as the UdpNm will always query the data by means of PduR_UdpNmTriggerTransmit. UdpNm_Transmit is an empty function returning E_OK at any time. This requirement is relevant to avoid linker errors as PduR expects this API to be provided.] ()

8.4 Call-back notifications

8.4.1 UdpNm_SoAdIfTxConfirmation

[SWS_UdpNm_00228] [

Service name:	UdpNm_SoAdIfTxConfirmation	
Syntax:	<pre>void UdpNm_SoAdIfTxConfirmation(PduIdType TxPduId, Std_ReturnType result)</pre>	
Service ID[hex]:	0x40	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant for different PduIds. Non reentrant for the same PduId.	
Parameters (in):	TxPduId	ID of the PDU that has been transmitted.
	result	E_OK: The PDU was transmitted. E_NOT_OK: Transmission of the PDU failed.
Parameters (inout):	None	
Parameters (out):	None	
Return value:	None	
Description:	The lower layer communication interface module confirms the transmission of a PDU, or the failure to transmit a PDU.	

] ()

Note: The callback function `UdpNm_SoAdIfTxConfirmation` is called by the SoAd and is implemented by the UdpNm module.

Note: The callback function `UdpNm_SoAdIfTxConfirmation` is either called on interrupt level (interrupt mode) or on task level (Polling Mode) with respect to the context.

The value passed to UdpNm via the API parameter `TxPduId` shall refer to the NM channel handle, i.e. a mapping from PduId to NM channel handle is not necessary.

[SWS_UdpNm_00229] [The callback function `UdpNm_SoAdIfTxConfirmation` shall inform the DET (if enabled), if the function call has failed because of the following reasons:

Invalid channel handle (`UDPNM_E_INVALID_CHANNEL`)

UdpNm was not initialized (`UDPNM_E_NO_INIT`)] ()

[SWS_UdpNm_00230] [If an error has to be indicated to the DET, the callback function `UdpNm_SoAdIfTxConfirmation` shall use the value of UdpNm channel handle as the instance id.] ()

[SWS_UdpNm_00316] [If `UdpNmComUserDataSupport` is enabled the UdpNm shall call `PduR_UdpNmTxConfirmation` within the message transmission confirmation function `UdpNm_SoAdIfTxConfirmation` called by the SoAd and with result passed by SoAd] ()

8.4.2 UdpNm_SoAdIfRxIndication

[SWS_UdpNm_00231] [

Service name:	UdpNm_SoAdIfRxIndication	
Syntax:	<pre>void UdpNm_SoAdIfRxIndication(PduIdType RxPduId, const PduInfoType* PduInfoPtr)</pre>	
Service ID[hex]:	0x42	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant for different PduIds. Non reentrant for the same PduId.	
Parameters (in):	RxPduId	ID of the received PDU.
	PduInfoPtr	Contains the length (SduLength) of the received PDU, a pointer to a buffer (SduDataPtr) containing the PDU, and the MetaData related to this PDU.
Parameters (inout):	None	
Parameters (out):	None	
Return value:	None	
Description:	Indication of a received PDU from a lower layer communication interface module.	

] ()

The callback function `UdpNm_SoAdIfRxIndication` called by the SoAd and implemented by the UdpNm module. It is called in case of a receive indication event of the SoAd.

The value passed to UdpNm via the API parameter `udpNmRxPduId` shall refer to the UdpNm channel handle, i.e. a mapping from PduId to UdpNm channel handle is not necessary.

[SWS_UdpNm_00232] [The callback function `UdpNm_SoAdIfRxIndication` shall inform the DET (if enabled), if function call has failed because of the following reasons:

Invalid channel handle (`UDPNM_E_INVALID_CHANNEL`)

UdpNm was not initialized (`UDPNM_E_NO_INIT`)

`udpSduPtr` equals `NULL_PTR` (`UDPNM_E_PARAM_POINTER`)

Invalid PDU ID (`UDPNM_E_INVALID_PDUID`)] ()

[SWS_UdpNm_00233] [If an error has to be indicated to the DET, the callback function `UdpNm_SoAdIfRxIndication` shall use the value of UdpNm channel handle as the instance id.] ()

8.4.3 UdpNm_TriggerTransmit

[SWS_UdpNm_91001] [

Service name:	UdpNm_TriggerTransmit	
Syntax:	<pre>Std_ReturnType UdpNm_TriggerTransmit(PduIdType TxPduId, PduInfoType* PduInfoPtr)</pre>	
Service ID[hex]:	0x41	
Sync/Async:	Synchronous	
Reentrancy:	Reentrant for different PduIds. Non reentrant for the same PduId.	
Parameters (in):	TxPduId	ID of the SDU that is requested to be transmitted.
Parameters (inout):	PduInfoPtr	Contains a pointer to a buffer (SduDataPtr) to where the SDU data shall be copied, and the available buffer size in SduLength. On return, the service will indicate the length of the copied SDU data in SduLength.
Parameters (out):	None	
Return value:	Std_ReturnType	<p>E_OK: SDU has been copied and SduLength indicates the number of copied bytes.</p> <p>E_NOT_OK: No SDU data has been copied. PduInfoPtr must not be used since it may contain a NULL pointer or point to invalid data.</p>
Description:	<p>Within this API, the upper layer module (called module) shall check whether the available data fits into the buffer size reported by PduInfoPtr->SduLength. If it fits, it shall copy its data into the buffer provided by PduInfoPtr->SduDataPtr and update the length of the actual copied data in PduInfoPtr->SduLength. If not, it returns E_NOT_OK without changing PduInfoPtr.</p>	

] ()

[SWS_UdpNm_00377] [If UdpNmComUserDataSupport is enabled the UdpNm shall collect the NM User Data from the referenced NM I-PDU by calling PduR_UdpNmGetTxData and combine the user data with the further NM bytes within the call of UdpNm_TriggerTransmit.] ()

[SWS_UdpNm_00378] [The function UdpNm_TriggerTransmit shall copy the NM PDU data of the according NM PDU requested by TxPduId.] ()

Note: The function UdpNm_TriggerTransmit might be called by the SoAd in an interrupt context.

8.5 Scheduled Functions

8.5.1 UdpNm_MainFunction_<Instance Id>

[SWS_UdpNm_00234] [

Service name:	UdpNm_MainFunction<Instance_Id>
Syntax:	<pre>void UdpNm_MainFunction<Instance_Id>(void)</pre>
Service ID[hex]:	0x13
Description:	<p>Main function of the UdpNm which processes the algorithm describes in that document. E.g.:</p> <p>UdpNm_MainFunction_0() represents the UdpNm instance for the UDP channel 0 UdpNm_MainFunction_1() represents the UdpNm instance for the UDP channel 1 ...</p> <p>Inform the DET (if enabled) if function call has failed because of the following reasons: UdpNm was not initialized (UDPNM_E_NO_INIT)</p> <p>If an error has to be indicated to the DET the <Instance Id> shall be used as the instance id.</p> <p>Caveats: UdpNm is initialized correctly, i.e. the function shall be robust if one or more channels are not initialized</p> <p>Configuration: Mandatory</p>

] ()

8.6 Expected Interfaces

In this chapter all interfaces required from other modules are listed.

8.6.1 Mandatory Interfaces

This chapter defines all interfaces which are required to fulfill the core functionality of the module.

API function	Description
Nm_BusSleepMode	Notification that the network management has entered Bus-Sleep Mode.
Nm_NetworkMode	Notification that the network management has entered Network Mode.
Nm_NetworkStartIndication	Notification that a NM-message has been received in the Bus-Sleep Mode, what indicates that some nodes in the network have already entered the Network Mode.
Nm_PrepareBusSleepMode	Notification that the network management has entered Prepare Bus-Sleep Mode.
SoAd_IfTransmit	Requests transmission of a PDU.

8.6.2 Optional Interfaces

This chapter defines all interfaces which are required to fulfill an optional functionality of the module.

API function	Description
Det_ReportError	Service to report development errors.
Nm_CarWakeUpIndication	This function is called by a <Bus>Nm to indicate reception of a CWU request.
Nm_CoordReadyToSleepCancellation	Cancels an indication, when the NM Coordinator Sleep Ready bit in the Control Bit Vector is set back to 0.
Nm_CoordReadyToSleepIndication	Sets an indication, when the NM Coordinator Sleep Ready bit in the Control Bit Vector is set
Nm_PduRxIndication	Notification that a NM message has been received.
Nm_RemoteSleepCancellation	Notification that the network management has detected that not all other nodes on the network are longer ready to enter Bus-Sleep Mode.
Nm_RemoteSleepIndication	Notification that the network management has detected that all other nodes on the network are ready to enter Bus-Sleep Mode.
Nm_RepeatMessageIndication	Service to indicate that an NM message with set Repeat Message Request Bit has been received.
Nm_StateChangeNotification	Notification that the state of the lower layer <BusNm> has changed.
Nm_TxTimeoutException	Service to indicate that an attempt to send an NM message failed.
PduR_UdpNmRxIndication	Indication of a received PDU from a lower layer communication interface module.
PduR_UdpNmTriggerTransmit	Within this API, the upper layer module (called module) shall check whether the available data fits into the buffer size reported by PduInfoPtr->SduLength. If it fits, it shall copy its data into the buffer provided by PduInfoPtr->SduDataPtr and update the length of the actual copied data in PduInfoPtr->SduLength. If not, it returns E_NOT_OK without changing PduInfoPtr.
PduR_UdpNmTxConfirmation	The lower layer communication interface module confirms the transmission of a PDU, or the failure to transmit a PDU.

8.6.3 Configurable interfaces

Not applicable

8.7 Service Interfaces

Not applicable

8.8 UML State chart diagram

The following figure shows an UML state diagram with respect to the API specification. Mode change related transitions are denoted in green, error handling related transitions in red and optional node detection related transitions in blue.

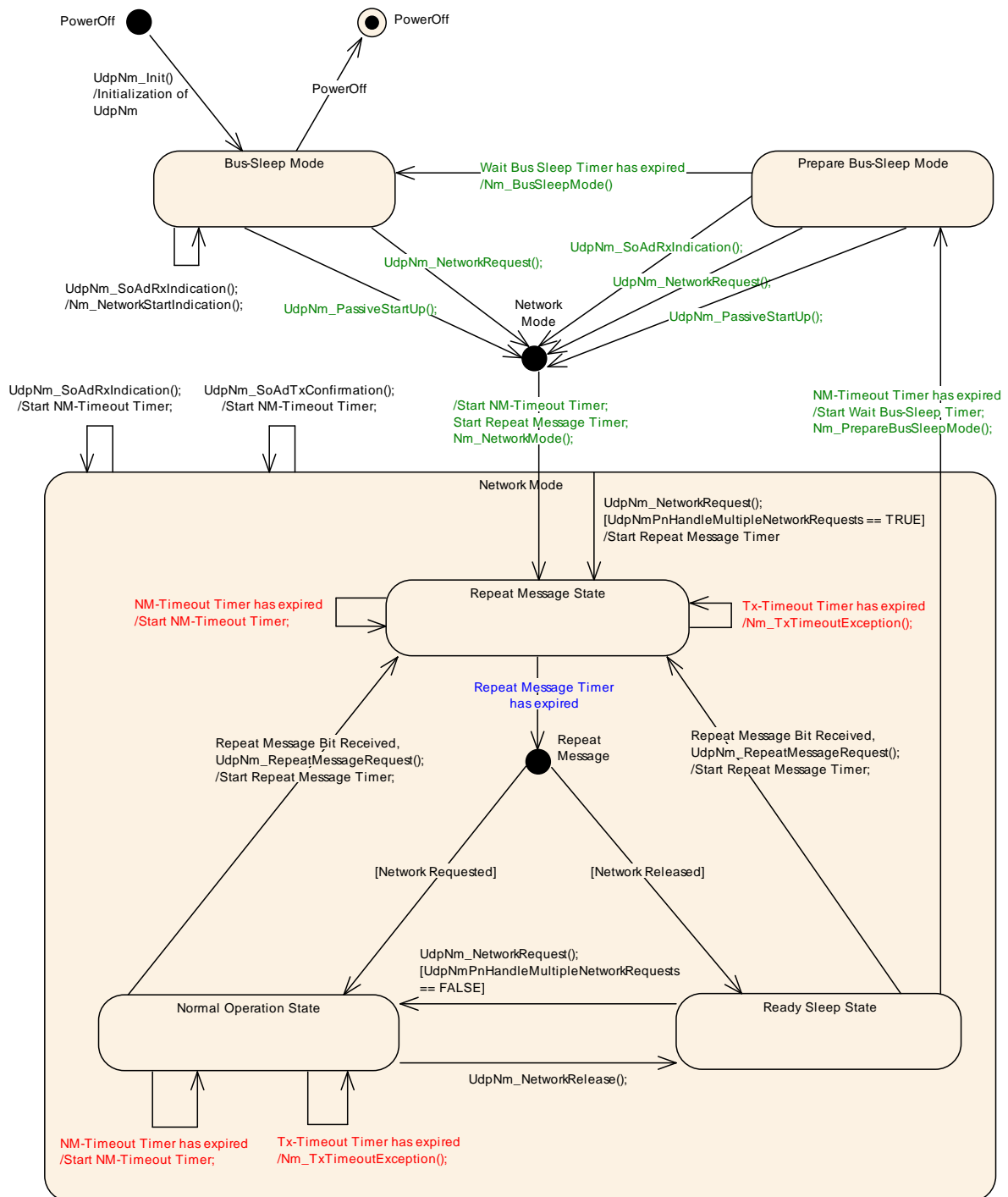


Figure 6: State chart diagram.

9 Sequence diagrams and Transition Tables

9.1 UdpNmTransmission

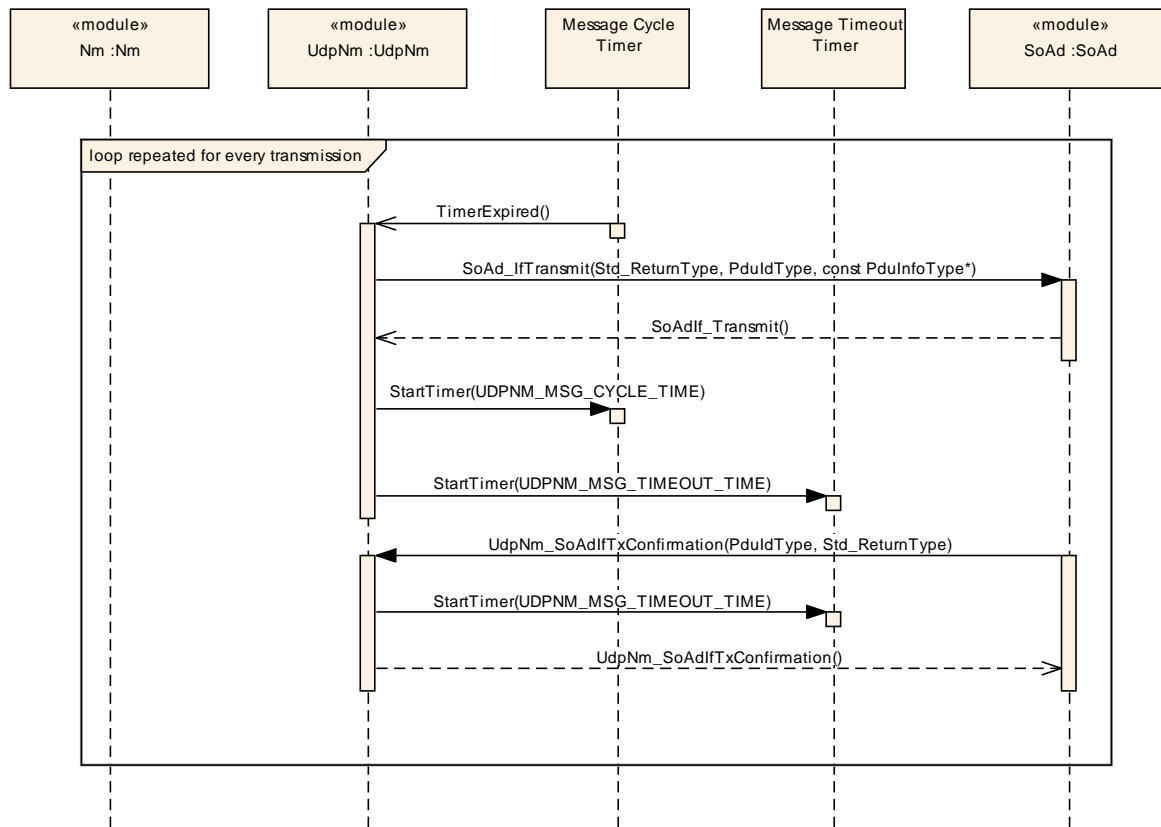


Figure 7: Sequence diagram – PDU transmission.

9.2 UdpNm Reception

Call direction	Action/Decision	Description
SoAd->UdpNm	UdpNm SoAdIfRxIndication()	

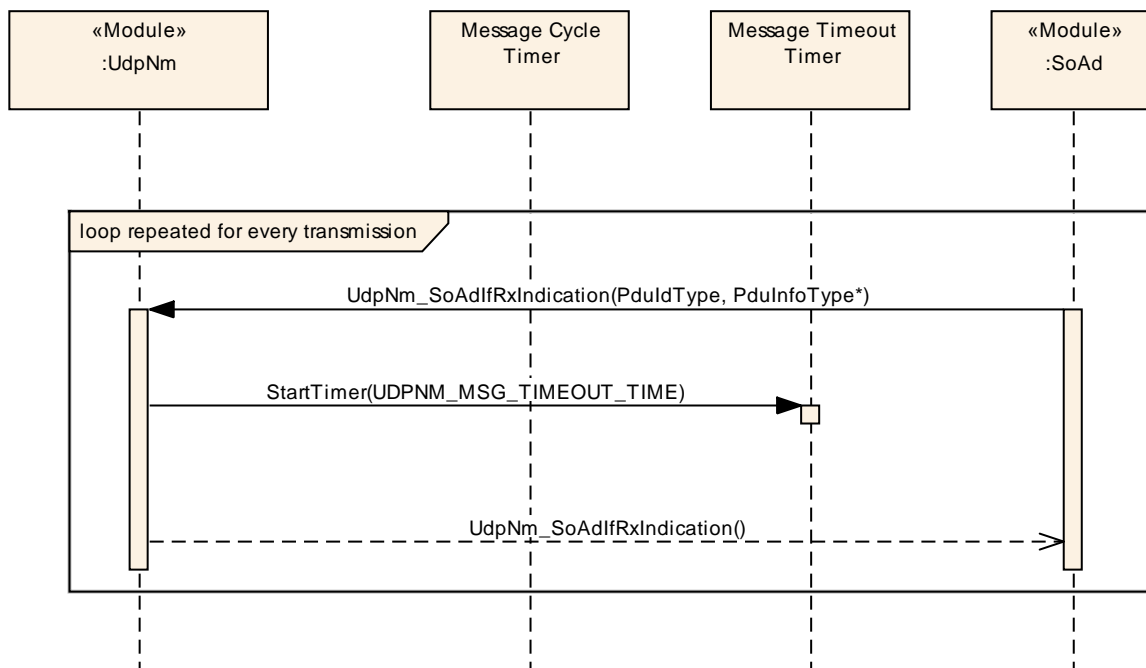


Figure 8: Sequence diagram – PDU reception.

10 Configuration specification

In general, this chapter defines configuration parameters and their clustering into containers. In order to support the specification chapter 10.1 describes fundamentals. It also specifies a template (table) to be use for the parameter specification. Chapter 10.1 is intended to remain in the specification document to ensure comprehensiveness.

Chapter 10.2 specifies the structure (containers) and the parameters of module UdpNm.

Chapter 10.3 specifies published information of module UdpNm.

10.1 How to read this chapter

For details refer to the chapter 10.1 “Introduction to configuration specification” in *SWS_BSWGeneral*.

10.2 Containers and configuration parameters

The configuration parameters as defined in this chapter are used to create a data model for an AUTOSAR tool chain. The realization in the code is implementation specific.

The configuration parameters as defined in this chapter are used to create a data model for an AUTOSAR tool chain. The realization in the code is implementation specific.

The configuration parameters are divided into parameters used to enable features, parameters affecting all instances of the UdpNm and parameters affecting the respective instances of the UdpNm.

[SWS_UdpNm_00026] [All configuration items shall be located outside the kernel of the module.] ()

[SWS_UdpNm_00201] [The Global Scope specifies configuration parameter that shall be defined in the module's configuration header file `UdpNm_Cfg.h`.] ()

[SWS_UdpNm_00202] [The container `UdpNm_ChannelConfig` specifies configuration parameter that shall be located in a data structure of type `UdpNm_ConfigType`.] ()

[SWS_UdpNm_00203] [Runtime configurable parameters listed in container `UdpNm_ChannelConfig` shall be configurable for each NM-cluster separately.] ()

10.2.1 UdpNm

SWS Item	ECUC_UdpNm_00088 :
Module Name	UdpNm
Module Description	--
Post-Build Variant Support	true
Supported Config Variants	VARIANT-LINK-TIME, VARIANT-PRE-COMPILE

Included Containers		
Container Name	Multiplicity	Scope / Dependency
UdpNmGlobalConfig	1	This container contains all global configuration parameters of UDP NM configured from the CanTrcv Module perspective.

10.2.2 UdpNmGlobalConfig

SWS Item	ECUC_UdpNm_00001 :
Container Name	UdpNmGlobalConfig
Description	This container contains all global configuration parameters of UDP NM configured from the CanTrcv Module perspective.
Configuration Parameters	

SWS Item	ECUC_UdpNm_00006 :		
Name	UdpNmBusSynchronizationEnabled		
Description	Pre-processor switch for enabling bus synchronization support. This feature is required for gateway nodes only. It must not be defined if UdpNmPassiveModeEnabled==true. This parameter shall be derived from NmBusSynchronizationEnabled.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00013 :		
Name	UdpNmComControlEnabled		
Description	Pre-processor switch for enabling the Communication Control support.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	

Scope / Dependency	scope: local dependency: calculationFormula = If (UdpNmPassiveModeEnabled == False) then Equal(NmComControlEnabled) else Equal(False)
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SWS Item	ECUC_UdpNm_00055 :		
Name	UdpNmComUserDataSupport		
Description	Enable/disable the user data support.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00040 :		
Name	UdpNmCoordinatorEnabled		
Description	<p>Enable/disable the NM Coordination algorithm to being able to initiate the synchronization algorithm. TRUE: Option is enabled</p> <p>FALSE: The parameter shall be FALSE by default and shall only be allowed to be TRUE if the parameter UdpNmRemoteSleepIndEnabled is TRUE.</p>		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00041 :		
Name	UdpNmCoordinatorId		
Description	<p>Set the NM coordination ID for this gateway. 0x00: passive coordinator only 0x01 - 0x03: coordinator priority</p> <p>Only valid, if UdpNmCoordinatorEnabled is TRUE.</p>		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 3		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	

Scope / Dependency	scope: local
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SWS Item	ECUC_UdpNm_00059 :		
Name	UdpNmCoordinatorSyncSupport		
Description	Enables/disables the coordinator synchronization support.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local dependency: UdpNmCoordinatorSyncSupport has to be set to FALSE if UdpNmPassiveModeEnabled is set to TRUE.		

SWS Item	ECUC_UdpNm_00002 :		
Name	UdpNmDevErrorDetect		
Description	Switches the development error detection and notification on or off. <ul style="list-style-type: none"> true: detection and notification is enabled. false: detection and notification is disabled. 		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00009 :		
Name	UdpNmImmediateRestartEnabled		
Description	Pre-processor switch for enabling the immediate transmission of a NM PACKET upon bus-communication request in Prepare-Bus-Sleep mode. Must not be defined if UdpNmPassiveModeEnabled== true.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	

Scope / Dependency	scope: local
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SWS Item	ECUC_UdpNm_00007 :		
Name	UdpNmNodeDetectionEnabled		
Description	Pre-processor switch for enabling the node detection support. This parameter shall be derived from NmNodeDetectionEnabled. This parameter shall only be enabled if UdpNmNodeIdEnabled == true. If(UdpNmPduCbnPosition != UDPNM_PDU_OFF) then Equal(NmNodeDetectionEnabled) else Equal(False).		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local dependency: Not available if UdpNmPassiveModeEnabled		

SWS Item	ECUC_UdpNm_00008 :		
Name	UdpNmNodeIdEnabled		
Description	Pre-processor switch for enabling the source node identifier. This parameter shall be derived from NmNodeIdEnabled.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00014 :		
Name	UdpNmNumberOfChannels		
Description	Number of NM channels allowed within one ECU.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	1 .. 255		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00010 :		
Name	UdpNmPassiveModeEnabled		
Description	Pre-processor switch for enabling support of the Passive Mode.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	

Scope / Dependency	scope: local
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SWS Item	ECUC_UdpNm_00011 :		
Name	UdpNmPduRxIndicationEnabled		
Description	Pre-processor switch for enabling the PDU Rx Indication. This parameter shall be derived from NmPduRxIndicationEnabled.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00066 :		
Name	UdpNmPnEiraCalcEnabled		
Description	Specifies if UdpNm calculates the PN request information for internal and external requests. (EIRA) true: PN request are calculated false: PN request are not calculated		
Multiplicity	0..1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true for at least one UdpNm Channel		

SWS Item	ECUC_UdpNm_00065 :		
Name	UdpNmPnResetTime		
Description	Specifies the runtime of the reset timer in seconds. This reset time is valid for the reset of PN requests in the EIRA and in the ERA. The value shall be the same for every channel. Thus it is a global config parameter.		
Multiplicity	0..1		
Type	EcucFloatParamDef		
Range	[0.001 .. 65.535]		
Default value	--		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true for at least one UdpNm Channel.
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SWS Item	ECUC_UdpNm_00005 :		
Name	UdpNmRemoteSleepIndEnabled		
Description	Pre-processor switch for enabling remote sleep indication support. This feature is required for gateway nodes only. It must not be defined if UdpNmPassiveModeEnabled==true. This parameter shall be derived from NmRemoteSleepIndEnabled.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00015 :		
Name	UdpNmRepeatMsgIndEnabled		
Description	Enable/disable the notification that a RepeatMessageRequest bit has been received.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local dependency: calculationFormula = If (UdpNmPassiveModeEnabled == False) then Equal(NmRepeatMsgIndEnabled) else Equal(False)		

SWS Item	ECUC_UdpNm_00012 :		
Name	UdpNmStateChangeIndEnabled		
Description	Pre-processor switch for enabling the UDP NM state change notification. This parameter shall be derived from NmStateChangeIndEnabled.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	

Scope / Dependency	scope: local
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SWS Item	ECUC_UdpNm_00004 :		
Name	UdpNmUserDataEnabled		
Description	Pre-processor switch for enabling user data support. This parameter shall be derived from NmUserDataEnabled.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00003 :		
Name	UdpNmVersionInfoApi		
Description	Pre-processor switch for enabling version info API support.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00062 :		
Name	UdpNmPnEiraRxNSduRef		
Description	Reference to a Pdu in the COM-Stack. Only one SduRef is required for UdpNm because the EIRA is the aggregation over all Ethernet Channels.		
Multiplicity	0..1		
Type	Reference to [Pdu]		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true for at least one UdpNm Channel
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Included Containers		
Container Name	Multiplicity	Scope / Dependency
UdpNmChannelConfig	1..*	This container contains the channel-specific configuration parameters of the UdpNm.
UdpNmPnInfo	0..1	PN information configuration

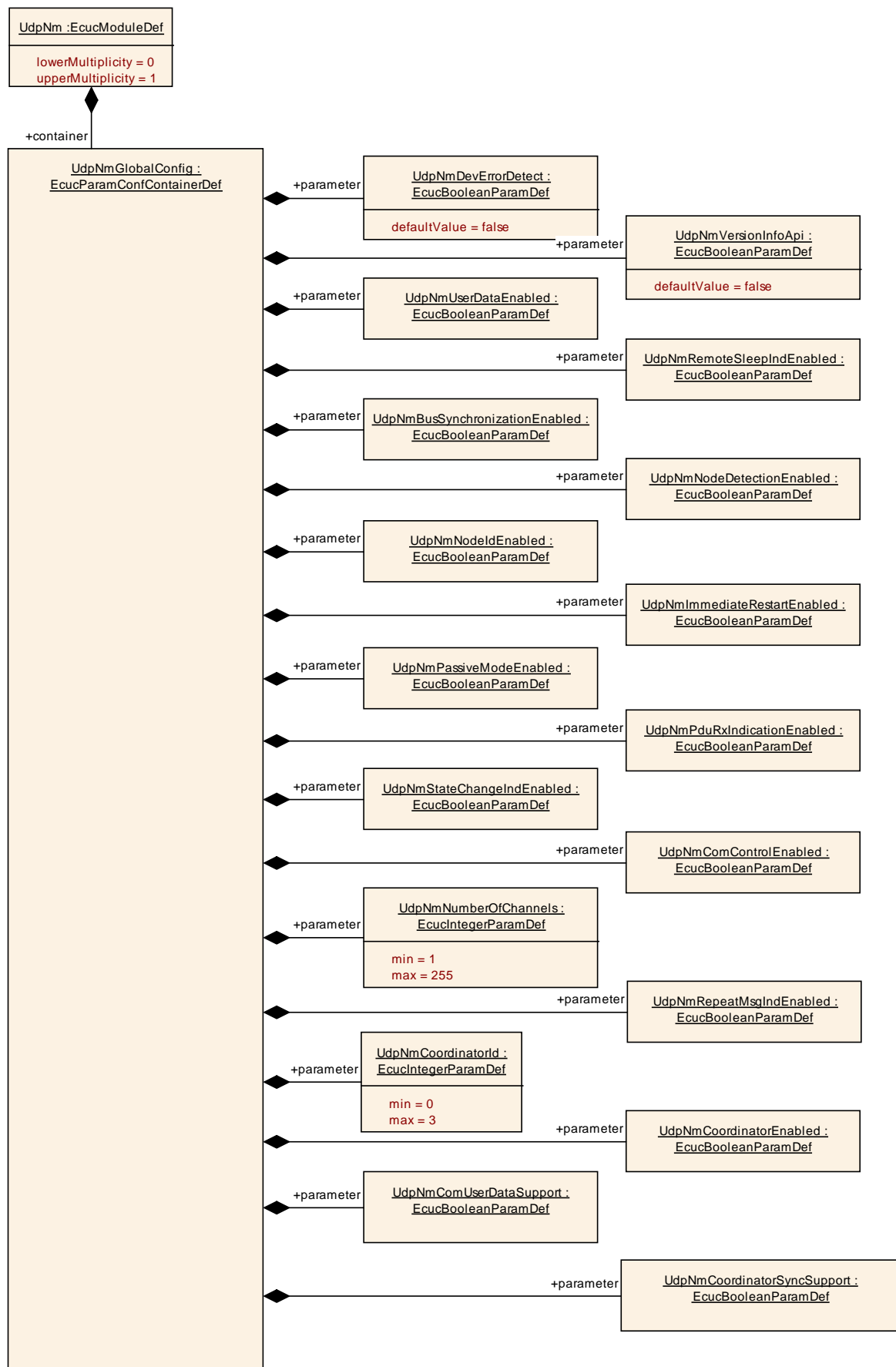


Figure 9: Diagram: UdpNmGlobalConfig

10.2.3 UdpNmChannelConfig

SWS Item	ECUC_UdpNm_00017 :
Container Name	UdpNmChannelConfig
Description	This container contains the channel-specific configuration parameters of the UdpNm.
Configuration Parameters	

SWS Item	ECUC_UdpNm_00074 :		
Name	UdpNmActiveWakeupBitEnabled		
Description	Enables/Disables the handling of the Active Wakeup Bit in the UdpNm module.		
Multiplicity	0..1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local dependency: This parameter is only valid if UdpNmPassiveModeEnabled is False.		

SWS Item	ECUC_UdpNm_00089 :		
Name	UdpNmAllNmMessagesKeepAwake		
Description	Specifies if UdpNm drops irrelevant NM PDUs. false: Only NM PDUs with a PNI bit = true and containing a PN request for this ECU triggers the standard RX indication handling true: Every NM PDU triggers the standard RX indication handling		
Multiplicity	0..1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true
---------------------------	--

SWS Item	ECUC_UdpNm_00087 :		
Name	UdpNmCarWakeUpBitPosition		
Description	Specifies the Bit position of the CWU within the NM PDU.		
Multiplicity	0..1		
Type	EcucIntegerParamDef		
Range	0 .. 7		
Default value	--		
Post-Build Multiplicity	Variant	false	
Post-Build Variant Value		false	
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local dependency: only available if UdpNmCarWakeUpRxEnabled == TRUE		

SWS Item	ECUC_UdpNm_00086 :		
Name	UdpNmCarWakeUpBytePosition		
Description	Specifies the Byte position of the CWU within the NM PDU.		
Multiplicity	0..1		
Type	EcucIntegerParamDef		
Range	0 .. 7		
Default value	--		
Post-Build Multiplicity	Variant	false	
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	scope: local dependency: only available if UdpNmCarWakeUpRxEnabled == TRUE UdpNmCarWakeUpBytePosition ≥ number of enabled system bytes (CBV, NID)
---------------------------	---

SWS Item	ECUC_UdpNm_00077 :		
Name	UdpNmCarWakeUpFilterEnabled		
Description	If CWU filtering is supported, only the CWU bit within the NM PDU with source node identifier UdpNmCarWakeUpFilterNodeId is considered as CWU request. FALSE - CWU filtering is not supported TRUE - CWU filtering is supported.		
Multiplicity	0..1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local dependency: only available if UdpNmCarWakeUpRxEnabled == TRUE		

SWS Item	ECUC_UdpNm_00078 :		
Name	UdpNmCarWakeUpFilterNodeId		
Description	Source node identifier for CWU filtering. If CWU filtering is supported, only the CWU bit within the NM PDU with source node identifier UdpNmCarWakeUpFilterNodeId is considered as CWU request.		
Multiplicity	0..1		
Type	EcucIntegerParamDef		
Range	0 .. 255		
Default value	--		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	scope: local dependency: only available if UdpNmCarWakeUpFilterEnabled == TRUE
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SWS Item	ECUC_UdpNm_00076 :		
Name	UdpNmCarWakeUpRxEnabled		
Description	Enables or disables support of CarWakeUp bit evaluation in received NM PDUs. FALSE - CarWakeUp not supported. TRUE - CarWakeUp supported.		
Multiplicity	1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: ECU		

SWS Item	ECUC_UdpNm_00079 :		
Name	UdpNmImmediateNmCycleTime		
Description	Defines the immediate NM PDU cycle time in seconds which is used for UdpNmImmediateNmTransmissions NM PDU transmissions.		
Multiplicity	0..1		
Type	EcucFloatParamDef		
Range	[0.001 .. 65.535]		
Default value	--		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local dependency: This parameter is only valid if UdpNmImmediateNmTransmissions is greater one.		

SWS Item	ECUC_UdpNm_00075 :		
Name	UdpNmImmediateNmTransmissions		
Description	Defines the number of immediate NM PDUs which shall be transmitted. If the value is zero no immediate NM PDUs are transmitted. The cycle time of immediate NM PDUs is defined by UdpNmImmediateNmCycleTime.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 255		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	scope: local dependency: If UdpNmImmediateRestartEnabled = true then UdpNmImmediateNmTransmissions = 0 If UdpNmPnHandleMultipleNetworkRequests == True then UdpNmImmediateNmTransmissions > 0
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SWS Item	ECUC_UdpNm_00032 :		
Name	UdpNmMainFunctionPeriod		
Description	Call cycle of UdpNm_MainFunction_x for the respective instance in [s].		
Multiplicity	1		
Type	EcucFloatParamDef		
Range]0 .. INF[
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00029 :		
Name	UdpNmMsgCycleOffset		
Description	Time offset in the periodic transmission node. It determines the start delay of the transmission. < UdpNmMsgCycleTime This parameter is only valid if UdpNmPassiveModeEnabled is disabled.		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	[0 .. 65.535]		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00028 :		
Name	UdpNmMsgCycleTime		
Description	Period of a NM-message. It determines the periodic rate and is the basis for transmit scheduling. $NmTimeoutTime = n * UdpNmMsgCycleTime$ This parameter is only valid if UdpNmPassiveModeEnabled is disabled.		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	[0.001 .. 65.535]		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	scope: local
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SWS Item	ECUC_UdpNm_00030 :		
Name	UdpNmMsgTimeoutTime		
Description	<p>Transmission Timeout of NM-message. If there is no transmission confirmation by the UDP Interface within this timeout, the UDPNM module shall give an error notification.</p> <p>This parameter is only valid if UdpNmPassiveModeEnabled is disabled.</p> <p>UdpNmMsgTimeoutTime should be a multiple of UdpNmMsgCycleTime.</p>		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	[0.001 .. 65.535]		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00031 :		
Name	UdpNmNodeId		
Description	<p>Node identifier of local node.</p> <p>This parameter is only valid if UdpNmPassiveModeEnabled is set to OFF and UdpNmNodeDetectionEnabled is set to ON.</p>		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 255		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00026 :		
Name	UdpNmPduCbvPosition		
Description	<p>Defines the position of the control bit vector within the NM PACKET.</p> <p>The value of the parameter represents the location of the control bit vector in the NM PACKET (UDPNM_PDU_BYTE_0 means byte 0, UDPNM_PDU_BYTE_1 means byte 1, UDPNM_PDU_OFF means the control bit vector is not part of the NM PACKET)</p> <p>See also UdpNmPduNidPosition</p> <p>if (UdpNmPduCbvPosition != UDPNM_PDU_OFF && UdpNmPduNidPosition != UDPNM_PDU_OFF) then UdpNmPduCbvPosition != UdpNmPduNidPosition</p> <p>if (UdpNmPduCbvPosition != UDPNM_PDU_OFF && UdpNmPduNidPosition == UDPNM_PDU_OFF) then UdpNmPduCbvPosition = UDPNM_PDU_BYTE0</p>		
Multiplicity	1		
Type	EcucEnumerationParamDef		
Range	UDPNM_PDU_BYTE_0	--	
	UDPNM_PDU_BYTE_1	--	
	UDPNM_PDU_OFF	--	

Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope Dependency	scope: local		

SWS Item	ECUC_UdpNm_00025 :		
Name	UdpNmPduNidPosition		
Description	<p>Defines the position of the source node identifier within the NM PACKET. ImplementationType: UdpNm_PduPositionType</p> <p>The value of the parameter represents the location of the source node identifier in the NM PACKET (UDPNM_PDU_BYTE_0 means byte 0, UDPNM_PDU_BYTE_1 means byte 1, UDPNM_PDU_OFF means source node identifier is not part of the NM PACKET)</p> <p>See also UdpNmPduCbvPosition if (UDPNM_PDU_NID_POSITION != UDPNM_PDU_OFF && UDPNM_PDU_CBV_POSITION != UDPNM_PDU_OFF) then UDPNM_PDU_NID_POSITION != UDPNM_PDU_CBV_POSITION</p> <p>if (UDPNM_PDU_NID_POSITION != UDPNM_PDU_OFF && UDPNM_PDU_CBV_POSITION == UDPNM_PDU_OFF) then UDPNM_PDU_IND_POSITION = UDPNM_PDU_BYTE0</p>		
Multiplicity	1		
Type	EcucEnumerationParamDef		
Range	UDPNM_PDU_BYTE_0	Byte 0 is used.	
	UDPNM_PDU_BYTE_1	Byte 1 is used.	
	UDPNM_PDU_OFF	Node Identification is not used.	
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope Dependency	/scope: local		

SWS Item	ECUC_UdpNm_00061 :		
Name	UdpNmPnEnabled		
Description	<p>Enables or disables support of partial networking. false: Partial networking Range not supported true: Partial networking supported</p>		
Multiplicity	0..1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true
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SWS Item	ECUC_UdpNm_00060 :		
Name	UdpNmPnEraCalcEnabled		
Description	Specifies if UdpNm calculates the PN request information for external requests. (ERA) false: PN request are not calculated true: PN request are calculated.		
Multiplicity	0..1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Multiplicity	Variant	false	
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true		

SWS Item	ECUC_UdpNm_00063 :		
Name	UdpNmPnHandleMultipleNetworkRequests		
Description	false: UdpNm_NetworkRequest is ignored in NO. true: UdpNm_NetworkRequest triggers a change from NO to RM.		
Multiplicity	0..1		
Type	EcucBooleanParamDef		
Default value	false		
Post-Build Multiplicity	Variant	false	
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true
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SWS Item	ECUC_UdpNm_00023 :		
Name	UdpNmRemoteSleepIndTime		
Description	<p>Timeout for Remote Sleep Indication. It defines the time in [s] how long it shall take to recognize that all other nodes are ready to sleep.</p> <p>Typically it should be equal to: $n * \text{UdpNmMsgCycleTime}$, where n denotes the number of NM packets that are normally sent before Remote Sleep Indication is detected. The value of n decremented by one determines the amount of lost NM packets that can be tolerated by the Remote Sleep Indication procedure.</p>		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	[0.001 .. 65.535]		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00022 :		
Name	UdpNmRepeatMessageTime		
Description	<p>Timeout for Repeat Message State. It defines the time in seconds how long the NM shall stay in the Repeat Message State.</p>		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	[0 .. 65.535]		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	<p>scope: local</p> <p>dependency: $\text{UdpNmRepeatMessageTime} = n * \text{UdpNmMsgCycleTime}$; $\text{UdpNmRepeatMessageTime} > \text{UdpNmImmediateNmTransmissions} * \text{UdpNmImmediateNmCycleTime}$</p> <p>Typically it should be equal to: $n * \text{UdpNmMsgCycleTime}$, where n denotes the number of NM PDUs that are normally sent in the Repeat Message State.</p> <p>The value of n decremented by one determines the amount of lost NM PDUs that can be tolerated by the node detection procedure. The value 0 denotes that no Repeat Message State is configured. It means that Repeat Message State is transient what implicates that it is left immediately after entrance and in result no start-up stability is guaranteed and no node detection procedure is possible.</p>
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SWS Item	ECUC UdpNm_00085 :		
Name	UdpNmRetryFirstMessageRequest		
Description	Specifies if first message request in UdpNm is repeated until accepted by SoAd.		
Multiplicity	0..1		
Type	EcucBooleanParamDef		
Default value	--		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	<p>scope: local</p> <p>dependency: $\text{UdpNmRetryFirstMessageRequest} = \text{false}$ if $\text{UdpNmPassiveModeEnabled} == \text{true}$</p>		

SWS Item	ECUC UdpNm_00020 :		
Name	UdpNmTimeoutTime		
Description	<p>Network Timeout for NM packets.</p> <p>It denotes the time in [s] how long the NM shall stay in the Network Mode before transition into Prepare Bus-Sleep Mode shall take place.</p> <p>It shall be equal for all nodes in the cluster.</p> <p>It shall be greater than UdpNmMsgCycleTime.</p> <p>Typically, it should be equal to: $x * \text{UdpNmMsgCycleTime}$, where n denotes the number of NM PACKET cycle times in the Ready Sleep State before transition into the Bus-Sleep Mode is initiated.</p> <p>The value of n decremented by one determines the amount of lost NM packets that can be tolerated by the coordination algorithm.</p>		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	[0.002 .. 65.535]		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	scope: local
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SWS Item	ECUC_UdpNm_00021 :		
Name	UdpNmWaitBusSleepTime		
Description	<p>Timeout for bus calm down phase. It denotes the time in [s] how long the NM shall stay in the Prepare Bus-Sleep Mode before transition into Bus-Sleep Mode shall take place.</p> <p>It shall be equal for all nodes in the cluster. It shall be long enough to empty all Tx-buffer empty.</p>		
Multiplicity	1		
Type	EcucFloatParamDef		
Range	[0.001 .. 65.535]		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00018 :		
Name	UdpNmComMNetworkHandleRef		
Description	<p>This reference points to the unique channel defined by the ComMChannel and provides access to the unique channel index value in ComMChannelId.</p>		
Multiplicity	1		
Type	Symbolic name reference to [ComMChannel]		
Post-Build Variant Value	true		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: ECU		

SWS Item	ECUC_UdpNm_00073 :		
Name	UdpNmPnEraRxNSduRef		
Description	Reference to a Pdu in the COM-Stack. The SduRef is required for every UdpNm Channel, because ERA is reported per channel.		
Multiplicity	0..1		
Type	Reference to [Pdu]		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	

Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true
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Included Containers		
Container Name	Multiplicity	Scope / Dependency
UdpNmRxPdu	1..*	This container describes the UdpNm RX PDU's.
UdpNmTxPdu	0..1	This container describes the UdpNm TX PDU's.
UdpNmUserDataTxPdu	0..1	Preprocessor switch for enabling the Tx path of Com User Data. Use case: Setting of NMUserData via SWC.

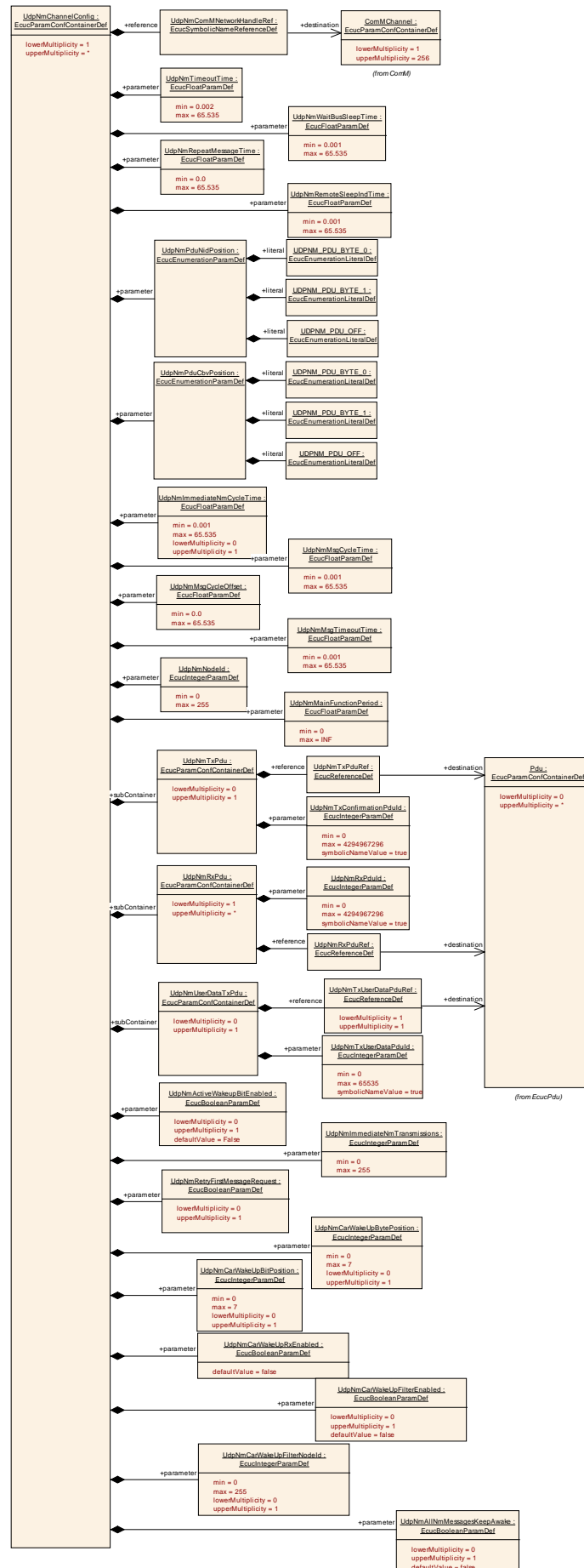


Figure 10: UdpNmChannelConfig

10.2.4 UdpNmRxPdu

SWS Item	ECUC_UdpNm_00038 :
Container Name	UdpNmRxPdu
Description	This container describes the UdpNm RX PDU's.
Configuration Parameters	

SWS Item	ECUC_UdpNm_00043 :		
Name	UdpNmRxPduId		
Description	ID of the RxPdu that will be used by a RxIndication of the lower layer.		
Multiplicity	1		
Type	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
Range	0 .. 4294967296		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00039 :		
Name	UdpNmRxPduRef		
Description	The reference to a PDU in the global PDU structure described in the AUTOSAR ECU Configuration Specification. This reference will be used by the UdpNm module to derive the PDU Id.		
Multiplicity	1		
Type	Reference to [Pdu]		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local		

No Included Containers

10.2.5 UdpNmTxPdu

SWS Item	ECUC_UdpNm_00036 :
Container Name	UdpNmTxPdu
Description	This container describes the UdpNm TX PDU's.
Configuration Parameters	

SWS Item	ECUC_UdpNm_00042 :		
Name	UdpNmTxConfirmationPduId		
Description	Id of the TxPdu that will be used by a TxConfirmation from the lower layer.		
Multiplicity	1		
Type	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
Range	0 .. 4294967296		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00037 :		
Name	UdpNmTxPduRef		
Description	The reference to a PDU in the global PDU structure described in the AUTOSAR ECU Configuration Specification. This reference will be used by the UdpNm module to derive the PDU Id.		
Multiplicity	1		
Type	Reference to [Pdu]		
Post-Build Variant Value	true		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local		

No Included Containers

10.2.6 UdpNmUserDataTxPdu

SWS Item	ECUC_UdpNm_00056 :
Container Name	UdpNmUserDataTxPdu
Description	Preprocessor switch for enabling the Tx path of Com User Data. Use case: Setting of NMUserData via SWC.
Configuration Parameters	

SWS Item	ECUC_UdpNm_00058 :		
Name	UdpNmTxUserDataPduId		
Description	This parameter defines the Handle ID of the NM User Data I-PDU.		
Multiplicity	1		
Type	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
Range	0 .. 65535		
Default value	--		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	--	
	Post-build time	--	
Scope / Dependency	scope: local		

SWS Item	ECUC_UdpNm_00057 :		
Name	UdpNmTxUserDataPduRef		
Description	Reference to the NM User Data I-PDU in the global PDU collection.		
Multiplicity	1		
Type	Reference to [Pdu]		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local		

No Included Containers

10.2.7 UdpNmPnInfo

SWS Item	ECUC_UdpNm_00067 :
Container Name	UdpNmPnInfo
Description	PN information configuration
Configuration Parameters	

SWS Item	ECUC_UdpNm_00069 :		
Name	UdpNmPnInfoLength		
Description	Specifies the length of the PN request information in the NM message.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	1 .. 7		
Default value	1		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true for at least one UdpNm Channel.		

SWS Item	ECUC_UdpNm_00068 :		
Name	UdpNmPnInfoOffset		
Description	Specifies the offset of the PN request information in the NM message.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	1 .. 7		
Default value	1		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true for at least one UdpNm Channel.		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
UdpNmPnFilterMaskByte	0..7	PN information configuration

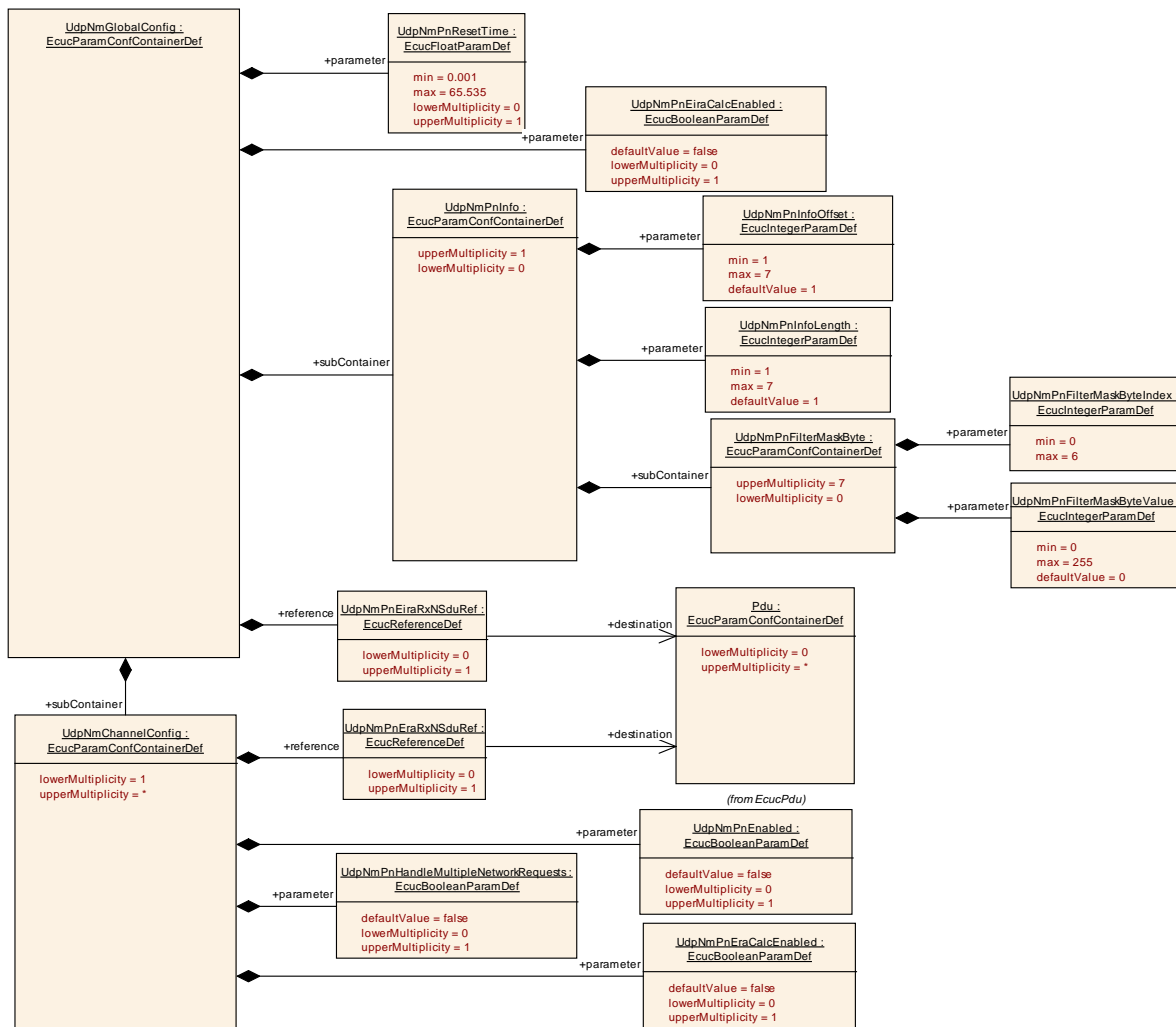


Figure 12: Diagram: UdpNmPNConfig

10.2.8 UdpNmPnFilterMaskByte

SWS Item	ECUC_UdpNm_00070 :
Container Name	UdpNmPnFilterMaskByte
Description	PN information configuration
Configuration Parameters	

SWS Item	ECUC_UdpNm_00071 :		
Name	UdpNmPnFilterMaskByteIndex		
Description	Index of the filter mask byte. Specifies the position within the filter mask byte array.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 6		
Default value	--		
Post-Build Variant Value	true		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true for at least one UdpNm Channel. UdpNmPnFilterMaskByteIndex < UdpNmPnInfoLength		

SWS Item	ECUC_UdpNm_00072 :		
Name	UdpNmPnFilterMaskByteValue		
Description	Parameter to configure the filter mask byte.		
Multiplicity	1		
Type	EcucIntegerParamDef		
Range	0 .. 255		
Default value	0		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	--	
Scope / Dependency	scope: local dependency: only available if UdpNmPnEnabled == true for at least one UdpNm Channel; UdpNmPnFilterMaskByteIndex < UdpNmPnInfoLength		

No Included Containers

10.3 Published parameters

For details refer to the chapter 10.3 “Published Information” in *SWS_BSWGeneral*.

11 Not applicable requirements

[SWS_UdpNm_NA_00999] [This specification item references requirements that are not applicable to this specification.] (SRS_BSW_00170, SRS_BSW_00375, SRS_BSW_00416, SRS_BSW_00168, SRS_BSW_00423, SRS_BSW_00424, SRS_BSW_00425, SRS_BSW_00426, SRS_BSW_00427, SRS_BSW_00429, SRS_BSW_00432, SRS_BSW_00336, SRS_BSW_00417, SRS_BSW_00161, SRS_BSW_00162, SRS_BSW_00005, SRS_BSW_00415, SRS_BSW_00164, SRS_BSW_00325, SRS_BSW_00160, SRS_BSW_00413, SRS_BSW_00347, SRS_BSW_00305, SRS_BSW_00307, SRS_BSW_00335, SRS_BSW_00410, SRS_BSW_00314, SRS_BSW_00328, SRS_BSW_00312, SRS_BSW_00006, SRS_BSW_00377, SRS_BSW_00306, SRS_BSW_00309, SRS_BSW_00330, SRS_BSW_00331, SRS_BSW_00172, SRS_BSW_00010, SRS_BSW_00333, SRS_BSW_00321, SRS_BSW_00341, SRS_BSW_00334, SRS_Nm_00151, SRS_Nm_00046, SRS_Nm_00050, SRS_Nm_00052, SRS_Nm_02509, SRS_Nm_00153, SRS_Nm_00054, SRS_Nm_00142, SRS_Nm_00144, SRS_Nm_00147, SRS_Nm_00154)