

## Announcements & Such

- *Black Roots*.
- Administrative Stuff
  - HW #4 resubs are still being graded. Stay tuned...
  - **HW #6 is due Thurs. Final HW assignment! LMPL Proofs.**
  - **Next week, I will be holding lectures. I will use them for both review, and for some interesting “logic beyond 12A” topics.**
- Today: Chapter 6 — Natural Deductions in LMPL
  - Introduction and Elimination rules for the quantifiers.
  - Sequents and Theorems (SI/TI) for the quantifiers.
  - **Lots of proofs in LMPL!**
- **Next:** Two-Place predicates (*i.e.*, *binary relations*) — “L2PL”.

## The Rule of $\exists$ -Elimination: Some Background

- It is useful to think of an existential claim ‘ $(\exists v)\phi v$ ’ as a *disjunction* which asserts that the predicate expression  $\phi$  is satisfied by *at least one* object in the domain (*i.e.*, that the disjunction ‘ $\phi a \vee (\phi b \vee (\phi c \vee \dots))$ ’ is true).
- In this way, we would expect the elimination rule for  $\exists$  to be similar to the elimination rule for  $\vee$ . That is, we’d expect the  $\exists E$  rule to be similar to the  $\vee E$  rule. Indeed, this is the case. It’s best to start with a simple example.
- Consider the following *legitimate* elimination of an existential claim:

Problem is:  $(\exists x)(Fx \& Gx) \vdash (\exists x)Fx$

1	(1) $(\exists x)(Fx \& Gx)$	Premise
2	(2) $Fa \& Ga$	Assumption
2	(3) $Fa$	2 &E
2	(4) $(\exists x)Fx$	3 $\exists I$
1	(5) $(\exists x)Fx$	1,2,4 $\exists E$

## The Rule of $\exists$ -Elimination: II

- To derive a sentence  $\mathcal{P}$  using the  $\exists E$  rule (with some existential sentence ‘ $(\exists v)\phi v$ ’), we must first *assume* an *instance*  $\phi\tau$  of ‘ $(\exists v)\phi v$ ’.
- If we can deduce  $\mathcal{P}$  from this assumed instance  $\phi\tau$  — *using generalizable reasoning* — then we may infer  $\mathcal{P}$  *outright*.
- It is because our reasoning from the *instance*  $\phi\tau$  of ‘ $(\exists v)\phi v$ ’ to  $\mathcal{P}$  *does not depend on our choice of constant*  $\tau$  (*i.e.*, that our reasoning from  $\phi\tau$  to  $\mathcal{P}$  is *generalizable*) that makes this inference valid.
- When our reasoning is generalizable in this sense, it’s as if we are showing that  $\mathcal{P}$  can be deduced from *any* instance  $\phi\tau$  of ‘ $(\exists v)\phi v$ ’.
- As such, this is just like showing that  $\mathcal{P}$  can be deduced from *any disjunct* of the disjunction ‘ $\phi a \vee (\phi b \vee (\phi c \vee \dots))$ ’. And, this is just like  $\vee E$  reasoning (except that  $\exists E$  only requires *one* assumption).

## The Rule of $\exists$ -Elimination: III

- Here’s an *illegitimate* “ $\exists$ -Elimination” step:

1	(1) $(\exists x)Fx$	Premise
2	(2) $Ga$	Premise
3	(3) $Fa$	Assumption
2,3	(4) $Fa \& Ga$	2,3 &I
2,3	(5) $(\exists x)(Fx \& Gx)$	4 $\exists I$
1,2	(6) $(\exists x)(Fx \& Gx)$	1,3,5 $\exists E$ <b>NO!!</b>

- This is *not* a valid inference:  $(\exists x)Fx, Ga \not\models (\exists x)(Fx \& Gx)$ !
- So, what went wrong here? The problem is that the inference to ‘ $(\exists x)(Fx \& Gx)$ ’ at line (5) does *not* use *generalizable* reasoning.
- We can *not* legitimately infer ‘ $(\exists x)(Fx \& Gx)$ ’ at line (5) from an *arbitrary instance* ‘ $F\tau$ ’ of ‘ $(\exists x)Fx$ ’. We *must* assume ‘**Fa**’ in *particular* at line (3) in order to deduce ‘ $(\exists x)(Fx \& Gx)$ ’ at line (5).

# The Rule of $\exists$ -Elimination: Official Definition

**$\exists$ -Elimination:** If ' $(\exists v)\phi v$ ' occurs at i depending on  $a_1, \dots, a_n$ , an instance  $\phi\tau$  of ' $(\exists v)\phi v$ ' is *assumed* at j, and  $\mathcal{P}$  is inferred at k depending on  $b_1, \dots, b_u$ , then at line m we may infer  $\mathcal{P}$ , with label 'i, j, k  $\exists E$ ' and dependencies  $\{a_1, \dots, a_n\} \cup \{b_1, \dots, b_u\}/j$ :

$a_1, \dots, a_n$	(i)	$(\exists v)\phi v$	
	$\vdots$		
	j	(j) $\phi\tau$	Assumption
	$\vdots$		
$b_1, \dots, b_u$	(k)	$\mathcal{P}$	
	$\vdots$		
$\{a_1, \dots, a_n\} \cup \{b_1, \dots, b_u\}/j$	(m)	$\mathcal{P}$	i, j, k $\exists E$

Provided that **all four** of the following conditions are met:

- $\tau$  (in  $\phi\tau$ ) replaces **every** occurrence of  $v$  in  $\phi v$ . [avoids fallacies]
- $\tau$  **does not occur in** ' $(\exists v)\phi v$ '. [generalizability]
- $\tau$  **does not occur in**  $\mathcal{P}$ . [generalizability]
- $\tau$  **does not occur in any** of  $b_1, \dots, b_u$ , except (possibly)  $\phi\tau$  itself. [generalizability]

# The Rule of $\exists$ -Elimination: Nine Examples

- Here are 9 examples of proofs involving all four quantifier rules.

- $(\exists x)\sim Fx \vdash \sim(\forall x)Fx$  [p. 200, example 5]
- $(\exists x)(Fx \rightarrow A) \vdash (\forall x)Fx \rightarrow A$  [p. 201, example 6]
- $(\forall x)(\forall y)(Gy \rightarrow Fx) \vdash (\forall x)[(\exists y)Gy \rightarrow Fx]$  [p. 203, I. # 19  $\Rightarrow$ ]
- $(\exists x)[Fx \rightarrow (\forall y)Gy] \vdash (\exists x)(\forall y)(Fx \rightarrow Gy)$  [p. 203, I. # 20  $\Leftarrow$ ]
- $A \vee (\exists x)Fx \vdash (\exists x)(A \vee Fx)$  [p. 203, II. # 2  $\Leftarrow$ ]
- $(\exists x)(Fx \& \sim Fx) \vdash (\forall x)(Gx \& \sim Gx)$  [p. 203, I. # 12  $\Rightarrow$ ]
- $(\forall x)[Fx \rightarrow (\forall y)\sim Fy] \vdash \sim(\exists x)Fx$  [p. 203, I. # 5]
- $(\forall x)(\exists y)(Fx \& Gy) \vdash (\exists y)(\forall x)(Fx \& Gy)$  [p. 201, example 7]
- $(\exists y)(\forall x)(Fx \& Gy) \vdash (\forall x)(\exists y)(Fx \& Gy)$  [other direction]

# Proof of (1)

Problem is:  $(\exists x)\sim Fx \vdash \sim(\forall x)Fx$

1	(1) $(\exists x)\sim Fx$	Premise
2	(2) $(\forall x)Fx$	Assumption
3	(3) $\sim Fa$	Assumption
2	(4) $Fa$	2 $\forall E$
2,3	(5) $\Delta$	3,4 $\sim E$
1,2	(6) $\Delta$	1,3,5 $\exists E$
1	(7) $\sim(\forall x)Fx$	2,6 $\sim I$

# Proof of (2)

Problem is:  $(\exists x)(Fx \rightarrow A) \vdash (\forall x)Fx \rightarrow A$

1	(1) $(\exists x)(Fx \rightarrow A)$	Premise
2	(2) $(\forall x)Fx$	Assumption
3	(3) $Fa \rightarrow A$	Assumption
2	(4) $Fa$	2 $\forall E$
2,3	(5) $A$	3,4 $\rightarrow E$
1,2	(6) $A$	1,3,5 $\exists E$
1	(7) $(\forall x)Fx \rightarrow A$	2,6 $\rightarrow I$

**Proof of (3)**

Problem is:  $(\forall x)(\forall y)(Gy \rightarrow Fx) \vdash (\forall x)((\exists y)Gy \rightarrow Fx)$

1	(1) $(\forall x)(\forall y)(Gy \rightarrow Fx)$	Premise
2	(2) $(\exists y)Gy$	Assumption
3	(3) $Gb$	Assumption
1	(4) $(\forall y)(Gy \rightarrow Fa)$	1 $\forall E$
1	(5) $Gb \rightarrow Fa$	4 $\forall E$
1,3	(6) $Fa$	5,3 $\rightarrow E$
1,2	(7) $Fa$	2,3,6 $\exists E$
1	(8) $(\exists y)Gy \rightarrow Fa$	2,7 $\rightarrow I$
1	(9) $(\forall x)((\exists y)Gy \rightarrow Fx)$	8 $\forall I$

**Proof of (4)**

Problem is:  $(\exists x)(Fx \rightarrow (\forall y)Gy) \vdash (\exists x)(\forall y)(Fx \rightarrow Gy)$

1	(1) $(\exists x)(Fx \rightarrow (\forall y)Gy)$	Premise
2	(2) $Fa \rightarrow (\forall y)Gy$	Assumption
3	(3) $Fa$	Assumption
2,3	(4) $(\forall y)Gy$	2,3 $\rightarrow E$
2,3	(5) $Gb$	4 $\forall E$
2	(6) $Fa \rightarrow Gb$	3,5 $\rightarrow I$
2	(7) $(\forall y)(Fa \rightarrow Gy)$	6 $\forall I$
2	(8) $(\exists x)(\forall y)(Fx \rightarrow Gy)$	7 $\exists I$
1	(9) $(\exists x)(\forall y)(Fx \rightarrow Gy)$	1,2,8 $\exists E$

**Proof of (5)**

Problem is:  $A \vee (\exists x)Fx \vdash (\exists x)(A \vee Fx)$

1	(1) $A \vee (\exists x)Fx$	Premise
2	(2) $A$	Assumption
2	(3) $A \vee Fa$	2 $\vee I$
2	(4) $(\exists x)(A \vee Fx)$	3 $\exists I$
5	(5) $(\exists x)Fx$	Assumption
6	(6) $Fa$	Assumption
6	(7) $A \vee Fa$	6 $\vee I$
6	(8) $(\exists x)(A \vee Fx)$	7 $\exists I$
5	(9) $(\exists x)(A \vee Fx)$	5,6,8 $\exists E$
1	(10) $(\exists x)(A \vee Fx)$	1,2,4,5,9 $\vee E$

**Proof of (6)**

Problem is:  $(\exists x)(Fx \& \sim Fx) \vdash (\forall x)(Gx \& \sim Gx)$

1	(1) $(\exists x)(Fx \& \sim Fx)$	Premise
2	(2) $Fa \& \sim Fa$	Assumption
3	(3) $\sim Gb$	Assumption
2	(4) $\sim Fa$	2 $\&E$
2	(5) $Fa$	2 $\&E$
2	(6) $\Delta$	4,5 $\sim E$
2	(7) $\sim \sim Gb$	3,6 $\sim I$
2	(8) $Gb$	7 $DN$
9	(9) $Gb$	Assumption
2	(10) $\sim Gb$	9,6 $\sim I$
2	(11) $Gb \& \sim Gb$	8,10 $\&I$
2	(12) $(\forall x)(Gx \& \sim Gx)$	11 $\forall I$
1	(13) $(\forall x)(Gx \& \sim Gx)$	1,2,12 $\exists E$

**Proof of (7)**

Problem is:  $(\forall x)(Fx \rightarrow (\forall y)\sim Fy) \vdash \sim(\exists x)Fx$

1	(1) $(\forall x)(Fx \rightarrow (\forall y)\sim Fy)$	Premise
2	(2) $(\exists x)Fx$	Assumption
3	(3) $Fa$	Assumption
1	(4) $Fa \rightarrow (\forall y)\sim Fy$	1 $\forall E$
1,3	(5) $(\forall y)\sim Fy$	4,3 $\rightarrow E$
1,3	(6) $\sim Fa$	5 $\forall E$
1,3	(7) $\Delta$	6,3 $\sim E$
1,2	(8) $\Delta$	2,3,7 $\exists E$
1	(9) $\sim(\exists x)Fx$	2,8 $\sim I$

**Proof of (8)**

Problem is:  $(\forall x)(\exists y)(Fx \& Gy) \vdash (\exists y)(\forall x)(Fx \& Gy)$

1	(1) $(\forall x)(\exists y)(Fx \& Gy)$	Premise
1	(2) $(\exists y)(Fa \& Gy)$	1 $\forall E$
3	(3) $Fa \& Gb$	Assumption
1	(4) $(\exists y)(Fc \& Gy)$	1 $\forall E$
5	(5) $Fc \& Gd$	Assumption
5	(6) $Fc$	5 $\&E$
1	(7) $Fc$	4,5,6 $\exists E$
3	(8) $Gb$	3 $\&E$
1,3	(9) $Fc \& Gb$	7,8 $\&I$
1,3	(10) $(\forall x)(Fx \& Gb)$	9 $\forall I$
1,3	(11) $(\exists y)(\forall x)(Fx \& Gy)$	10 $\exists I$
1	(12) $(\exists y)(\forall x)(Fx \& Gy)$	2,3,11 $\exists E$

**Proof of (9)**

Problem is:  $(\exists y)(\forall x)(Fx \& Gy) \vdash (\forall x)(\exists y)(Fx \& Gy)$

1	(1) $(\exists y)(\forall x)(Fx \& Gy)$	Premise
2	(2) $(\forall x)(Fx \& Gb)$	Assumption
2	(3) $Fa \& Gb$	2 $\forall E$
2	(4) $(\exists y)(Fa \& Gy)$	3 $\exists I$
1	(5) $(\exists y)(Fa \& Gy)$	1,2,4 $\exists E$
1	(6) $(\forall x)(\exists y)(Fx \& Gy)$	5 $\forall I$

**Two LMPL Extensions of Sequent Introduction**

- Here are two additions to our list of SI sequents:

(QS) One can infer ' $(\forall x)\sim\phi x$ ' from (the *logically equivalent* sentence) ' $\sim(\exists x)\phi x$ ', and *vice versa*; and, that one can infer ' $(\exists x)\sim\phi x$ ' from (the *logically equivalent*) ' $\sim(\forall x)\phi x$ ', and *vice versa*.

$$(\forall x)\sim\phi x \dashv\vdash \sim(\exists x)\phi x; \text{ and, } (\exists x)\sim\phi x \dashv\vdash \sim(\forall x)\phi x \quad (\text{QS})$$

(AV) One can infer a *closed* LMPL sentence  $\psi$  from (the *logically equivalent* sentence)  $\psi'$ , and *vice versa*, where  $\psi$  and  $\psi'$  are *alphabetic variants*. Two formulas are *alphabetic variants* if and only if they differ *only* in a (conventional) choice of individual *variable* letters (*not* kosher for constants!). E.g., ' $(\forall x)Fx$ ' and ' $(\forall y)Fy$ ' are (closed) *alphabetic variants*, because they differ *only* in which individual variable (' $x$ ' or ' $y$ ') is used, but they have the same *logical* (i.e., *syntactical*) structure.

$$\psi \dashv\vdash \psi' \quad (\text{AV})$$

### Our (New) Official List of Sequents and Theorems (see pp. 123, 204, and 206)

$A \vee B, \sim A \vdash B$ ; or; $A \vee B, \sim B \vdash A$	(DS)	$A \rightarrow B \dashv\vdash \sim A \vee B$	(Imp)
$A \rightarrow B, \sim B \vdash \sim A$	(MT)	$\sim(A \rightarrow B) \dashv\vdash A \& \sim B$	(Neg-Imp)
$A \vdash B \rightarrow A$	(PMI)	$A \& (B \vee C) \dashv\vdash (A \& B) \vee (A \& C)$	(Dist)
$\sim A \vdash A \rightarrow B$	(PMI)	$A \vee (B \& C) \dashv\vdash (A \vee B) \& (A \vee C)$	(Dist)
$A \vdash \sim\sim A$	(DN <sup>+</sup> )	$\wedge \vdash A$	(EFQ, or $\wedge E$ )
$\sim(A \& B) \dashv\vdash \sim A \vee \sim B$	(DEM)	$A * B \vdash B * A$	(Com)
$\sim(A \vee B) \dashv\vdash \sim A \& \sim B$	(DEM)	$\sim\sim A * \sim\sim B \dashv\vdash A * B$	(SDN)
$\sim(\sim A \vee \sim B) \dashv\vdash A \& B$	(DEM)	$A * B \dashv\vdash \sim\sim A * B \dashv\vdash A * \sim\sim B$	(SDN)
$\sim(\sim A \& \sim B) \dashv\vdash A \vee B$	(DEM)	$\vdash A \vee \sim A$	(LEM)
$(\forall x)\sim\phi x \dashv\vdash \sim(\exists x)\phi x$	(QS)	$(\exists x)\sim\phi x \dashv\vdash \sim(\forall x)\phi x$	(QS)
		$\psi \dashv\vdash \psi'$	(AV)

In (Com), ‘\*’ can be any binary connective *except* ‘ $\rightarrow$ ’. In (SDN), ‘\*’ can be *any* binary connective. In (AV),  $\psi$  must be *closed*, and  $\psi'$  must be an *alphabetic variant* of  $\psi$ .

### The Value of (QS) — Its Four Simplest Instances

$(\forall x)\sim Fx \vdash \sim(\exists x)Fx$				$\sim(\exists x)Fx \vdash (\forall x)\sim Fx$			
1	(1)	$(\forall x)\sim Fx$	Premise	1	(1)	$\sim(\exists x)Fx$	Premise
2	(2)	$(\exists x)Fx$	Ass	2	(2)	Fa	Ass
3	(3)	Fa	Ass	2	(3)	$(\exists x)Fx$	2 $\exists I$
1	(4)	$\sim Fa$	1 $\forall E$	1,2	(4)	$\Delta$	1,3 $\sim E$
1,3	(5)	$\Delta$	4,3 $\sim E$	1	(5)	$\sim Fa$	2,4 $\sim I$
1,2	(6)	$\Delta$	2,3,5 $\exists E$	1	(6)	$(\forall x)\sim Fx$	5 $\forall I$
1	(7)	$\sim(\exists x)Fx$	2,6 $\sim I$				

$(\exists x)\sim Fx \vdash \sim(\forall x)Fx$				$\sim(\forall x)Fx \vdash (\exists x)\sim Fx$			
1	(1)	$(\exists x)\sim Fx$	Premise	1	(1)	$\sim(\forall x)Fx$	Premise
2	(2)	$(\forall x)Fx$	Ass	2	(2)	$\sim(\exists x)\sim Fx$	Ass
3	(3)	$\sim Fa$	Ass	3	(3)	$\sim Fa$	Ass
2	(4)	Fa	2 $\forall E$	3	(4)	$(\exists x)\sim Fx$	3 $\exists I$
2,3	(5)	$\Delta$	3,4 $\sim E$	2,3	(5)	$\Delta$	2,4 $\sim E$
2	(6)	$\Delta$	2,3,5 $\exists E$	2	(6)	$\sim\sim Fa$	3,5 $\sim I$
1,2	(6)	$\Delta$	1,3,5 $\exists E$	2	(7)	Fa	6 DN
1	(7)	$\sim(\forall x)Fx$	2,6 $\sim I$	2	(8)	$(\forall x)Fx$	7 $\forall I$
				1,2	(9)	$\Delta$	1,8 $\sim E$
				1	(10)	$\sim\sim(\exists x)\sim Fx$	2,9 $\sim I$
				1	(11)	$(\exists x)\sim Fx$	10 DN

### Three Examples Involving the LMPL SI Extension (QS)

- Here are three examples of proofs involving SI (QS):

- $\sim(\forall x)\sim Fx \vdash (\exists x)Fx$  [p. 207, #7  $\Leftarrow$ ]
- $\sim(\exists x)(Fx \& Gx) \vee (\exists x)\sim Gx, (\forall y)Gy \vdash (\forall z)(Fz \rightarrow \sim Gz)$  [p. 205, ex. 1]
- $(\forall x)Fx \rightarrow A \vdash (\exists x)(Fx \rightarrow A)$  [p. 205, ex. 2]

### Proof of (1)

- (1)  $\sim(\forall x)\sim Fx$  Premise
- (2)  $\sim(\exists x)Fx$  Assumption
- (3)  $(\forall x)\sim Fx$  2 SI (QS)
- (4)  $\wedge$  1, 3  $\sim E$
- (5)  $\sim\sim(\exists x)Fx$  2, 4  $\sim I$
- (6)  $(\exists x)Fx$  5 DN

### Proof of (2)

1	(1)	$\sim(\exists x)(Fx \& Gx) \vee (\exists x)\sim Gx$	Premise
2	(2)	$(\forall y)Gy$	Premise
3	(3)	$\sim(\exists x)(Fx \& Gx)$	Assumption
3	(4)	$(\forall x)\sim(Fx \& Gx)$	3 SI (QS)
3	(5)	$\sim(Fa \& Ga)$	4 $\forall E$
3	(6)	$\sim Fa \vee \sim Ga$	5 SI (DeM)
3	(7)	$Fa \rightarrow \sim Ga$	6 SI (Imp)
3	(8)	$(\forall z)(Fz \rightarrow \sim Gz)$	7 $\forall I$
9	(9)	$(\exists x)\sim Gx$	Assumption
10	(10)	$\sim Ga$	Assumption
2	(11)	$Ga$	2 $\forall E$
2,10	(12)	$\wedge$	10, 11 $\sim E$
2,10	(13)	$(\forall z)(Fz \rightarrow \sim Gz)$	12 SI (EFQ)
2,9	(14)	$(\forall z)(Fz \rightarrow \sim Gz)$	9, 10, 13 $\exists E$
1,2	(15)	$(\forall z)(Fz \rightarrow \sim Gz)$	1, 3, 8, 9, 14 $\forall E$

### Proof of (3)

Problem is:  $(\forall x)Fx \rightarrow A \vdash (\exists x)(Fx \rightarrow A)$

1	(1)	$(\forall x)Fx \rightarrow A$	Premise
1	(2)	$\sim(\forall x)Fx \vee A$	1 SI (Imp)
3	(3)	$\sim(\forall x)Fx$	Assumption
3	(4)	$(\exists x)\sim Fx$	3 SI (QS)
5	(5)	$\sim Fa$	Assumption
5	(6)	$Fa \rightarrow A$	5 SI (PMI)
5	(7)	$(\exists x)(Fx \rightarrow A)$	6 $\exists I$
3	(8)	$(\exists x)(Fx \rightarrow A)$	4,5,7 $\exists E$
9	(9)	$A$	Assumption
9	(10)	$Fa \rightarrow A$	9 SI (PMI)
9	(11)	$(\exists x)(Fx \rightarrow A)$	10 $\exists I$
1	(12)	$(\exists x)(Fx \rightarrow A)$	2,3,8,9,11 $\vee E$

### The Value of (AV)

- Here are the two simplest instances of (AV):

$(\forall x)Fx \vdash (\forall y)Fy$				$(\exists x)Fx \vdash (\exists y)Fy$			
1	(1)	$(\forall x)Fx$	Premise	1	(1)	$(\exists x)Fx$	Premise
1	(2)	Fa	1 $\forall E$	2	(2)	Fa	Ass
1	(3)	$(\forall y)Fy$	2 $\forall I$	2	(3)	$(\exists y)Fy$	2 $\exists I$
				1	(4)	$(\exists y)Fy$	1,2,3 $\exists E$

- Here's an (AV)-aided proof of the following sequent

$(\forall x)Fx, (\forall y)Fy \rightarrow (\forall y)Gy \vdash (\forall z)Gz$

1	(1)	$(\forall x)Fx$	Premise
2	(2)	$(\forall y)Fy \rightarrow (\forall y)Gy$	Premise
1	(3)	$(\forall y)Fy$	1 SI (AV)
1,2	(4)	$(\forall y)Gy$	2,3 $\rightarrow E$
1,2	(5)	$(\forall z)Gz$	4 SI (AV)