

26.1 Consider an operator A in the Shrödinger picture which has no explicit time dependence and which does not evolve in time. The vector $|\psi\rangle$ evolves in time according to (26.4). Consider the expectation value $\langle A \rangle = \langle \psi | A | \psi \rangle$.

(a) Show that

$$\frac{d}{dt}\langle A \rangle = \frac{i}{\hbar}\langle [H, A] \rangle.$$

Proof. Let A be an operator which has no explicit time dependence and which does not evolve in time, and let $|\psi\rangle$ evolve in time according to (26.4). Using the product rule, we have that

$$\begin{aligned} \frac{d}{dt}\langle A \rangle &= \frac{d}{dt}(\langle \psi | A | \psi \rangle) = \langle \psi(0) | \frac{d}{dt} \left(U^\dagger(t) A U(t) \right) | \psi(0) \rangle \\ &= \langle \psi(0) | \left(\frac{\partial U^\dagger}{\partial t} A U + U^\dagger A \frac{\partial U}{\partial t} + \frac{\partial A}{\partial t} \right) | \psi(0) \rangle \\ &= \langle \psi(0) | \left(\frac{i}{\hbar} H U^\dagger A U - \frac{i}{\hbar} U^\dagger A H U \right) | \psi(0) \rangle \\ &= \frac{i}{\hbar} \langle \psi | (H A - A H) | \psi \rangle \\ &= \frac{i}{\hbar} \langle \psi | [H, A] | \psi \rangle = \frac{i}{\hbar} \langle [H, A] \rangle, \end{aligned}$$

as desired. □

(b) Use

$$H = \frac{p_x^2}{2m} + V(x) \quad \text{with } p_x = -i\hbar \frac{\partial}{\partial x}$$

and the result of (a) to show that

$$(i) \quad \frac{d\langle p_x \rangle}{dt} = - \left\langle \frac{\partial V}{\partial x} \right\rangle \quad \text{and} \quad (ii) \quad \frac{d\langle x \rangle}{dt} = \frac{\langle p_x \rangle}{m}.$$

Proof. Directly, we have

$$\begin{aligned} \frac{d\langle p_x \rangle}{dt} &= \frac{i}{\hbar} \left\langle \left[\frac{p_x^2}{2m} + V(x), p_x \right] \right\rangle \\ &= \frac{i}{\hbar} \left\langle \left(\left(\frac{p_x^3}{2m} + V(x)p_x \right) - \left(\frac{p_x^3}{2m} + p_x V(x) + V(x)p_x \right) \right) \right\rangle \\ &= \left\langle \left(-\frac{i}{\hbar} p_x V(x) \right) \right\rangle = - \left\langle \frac{\partial V}{\partial x} \right\rangle \end{aligned}$$

and

$$\begin{aligned}
 \frac{d\langle x \rangle}{dt} &= \frac{i}{\hbar} \left\langle \left[\frac{p_x^2}{2m} + V(x), x \right] \right\rangle \\
 &= \frac{i}{\hbar} \left\langle \left(\left(\frac{1}{2m} (p_x(xp_x - i\hbar)) + V(x)x \right) - \left(x \frac{p_x^2}{2m} + V(x)x \right) \right) \right\rangle \\
 &= \frac{i}{\hbar} \left\langle \left(\left(\frac{1}{2m} (-2i\hbar p_x + xp_x^2) + V(x)x \right) - \left(x \frac{p_x^2}{2m} + V(x)x \right) \right) \right\rangle \\
 &= \frac{\langle p_x \rangle}{m},
 \end{aligned}$$

as desired. □