1. Prove the following product rules

$$\vec{\nabla}(\psi\phi) = \phi\vec{\nabla}\psi + \psi\vec{\nabla}\phi \tag{1}$$

$$\vec{\nabla} \cdot (\psi \vec{A}) = \psi \vec{\nabla} \cdot \vec{A} + \vec{\nabla} \psi \cdot \vec{A} \tag{2}$$

$$\vec{\nabla} \times (\psi \vec{A}) = \psi \vec{\nabla} \times \vec{A} + \vec{\nabla} \psi \times \vec{A} \tag{3}$$

$$(1) \ (\vec{\nabla}(\psi\phi))_i = \partial_i(\psi\phi) = (\partial_i\psi)\phi + \psi(\partial_i\phi) \implies \vec{\nabla}(\psi\phi) = \phi\vec{\nabla}\psi + \psi\vec{\nabla}\phi$$

$$(2) \ \vec{\nabla} \cdot (\psi \vec{A}) = \partial_i (\psi \vec{A})_i = \partial_i (\psi A_i) = (\partial_i A_i) \psi + (\partial_i \psi) A_i \implies \vec{\nabla} \cdot (\psi \vec{A}) = \psi \vec{\nabla} \cdot \vec{A} + \vec{\nabla} \psi \cdot \vec{A}$$

(3) 
$$(\vec{\nabla} \times (\psi \vec{A}))_i = \epsilon_{ijk} \partial_j (\psi \vec{A})_k = \epsilon_{ijk} \partial_j (\psi A_k) = \epsilon_{ijk} [(\partial_j A_k) \psi + (\partial_j \psi) A_k] = \epsilon_{ijk} (\partial_j A_k) \psi + \epsilon_{ijk} (\partial_j \psi) A_k$$
  
 $\implies \vec{\nabla} \times (\psi \vec{A}) = \psi \vec{\nabla} \times \vec{A} + \vec{\nabla} \psi \times \vec{A}$ 

- 2. Quantum mechanical orbital angular momentum (?) is given by  $\vec{L}=\vec{r}\times-i\vec{\nabla}.$ 
  - (a) Show that  $\vec{L}$  has components  $L_x = -i(y\partial_z z\partial_y), L_y = -i(z\partial_x x\partial_z), L_z = -i(x\partial_y y\partial_x).$ Keep in mind that the subscript i is different from the complex number i. We have that  $\vec{r} = (x, y, z)$ . Thus  $L_i = (\vec{r} \times -i\vec{\nabla})_i = -i\epsilon_{ijk}r_j\partial_k = -i(r_j\partial_k - r_k\partial_j)$ . Thus by selecting i, j, k cyclically in x, y, z we can obtain the components as stated above.
  - (b) Show that these components satisfy the "commutation relation"  $[L_x, L_y] \equiv L_x L_y L_y L_x = i L_z$ . Directly, we have that

$$\begin{split} [L_x, L_y] &\equiv L_x L_y - L_y L_x = -i(y\partial_z - z\partial_y) \cdot -i(z\partial_x - x\partial_z) - -i(z\partial_x - x\partial_z) \cdot -i(y\partial_z - z\partial_y) \\ &= -(y\partial_z z\partial_x - z\partial_y z\partial_x - y\partial_z x\partial_z + z\partial_y x\partial_z) + (z\partial_x y\partial_z - x\partial_z y\partial_z - z\partial_x z\partial_y + x\partial_z z\partial_y) \\ &= -(y\partial_x + yz\partial_z \partial_x - z^2\partial_y \partial_x - yx\partial_z \partial_z + zx\partial_y \partial_z) + (zy\partial_x \partial_z - xy\partial_z \partial_z - z^2\partial_x \partial_y + x\partial_y + xz\partial_z \partial_y) \\ &= -y\partial_x + x\partial_y = i(-i(x\partial_y - y\partial_x)) = iL_z, \end{split}$$

where mixed second partial derivative operators are equivalent when they act on twice continuously differentiable functions.