Standards of Competence for Category "B" Hydrographic Surveyors

Edition 1.0.1 – June 2017





Published by the International Hydrographic Organization 4b quai Antoine 1er Principauté de Monaco Tel: (377) 93.10.81.00 Fax: (377) 93.10.81.40 info@iho.int www.iho.int

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Contents

Fore	word	iv
Intro	duction	V
Defin	nitions	vi
Subje	ects, topics, and elements	vi
	ning outcomes and list of content	
Prog	ramme preparation and submission	vii
	of acronyms and initialisms used in this document	
1.	Basic subjects	1
1.1.	B1: Mathematics, Statistics, Theory of Errors	1
1.2.	B2: Information and Communication Technology	3
1.3.	B3: Physics	3
1.4.	B4: Earth Sciences	4
1.5.	B5: Nautical science	5
1.6.	B6: Meteorology	6
2.	Essential subjects	7
2.1.	E1: Underwater Acoustics	7
2.2.	E2: Remote Sensing	9
2.3.	E3: Water Levels and Flow	10
2.4.	E4: Positioning	13
2.5.	E5: Hydrographic Practice	15
2.6.	E6: Hydrographic Data Management	18
2.7.	E7: Environment	23
3.	CFFP: Comprehensive Final Field Project	25

Foreword

Comments arising from the experience gained in the application of the standards are welcome. They should be addressed to the Chair of the International Board on Standards of Competence for Hydrographic Surveyors and Nautical Cartographers at the above address. This document is published periodically. Please check with IHO for the latest edition, including current amendments.

Introduction

All components of the hydrographic surveying and nautical cartography professions face challenges as how best to ensure the continuance of high standards and how best to ensure the continuation of best practices based on minimum standards of competence world-wide. In order to achieve these objectives, three international organizations (FIG, IHO and ICA) have developed Standards of competence that institutions or professional bodies may adopt for their educational/training programmes and competency schemes.

Standards indicate the minimum competences considered necessary for hydrographic surveyors.

Standards recognize two levels of programme. Category A programmes introduces content and learning outcomes primarily from the underlying principles level. Category B programmes introduce them primarily from a practical level.

The intention is that a Category A qualified individual with appropriate experience, would be a senior professional in their chosen field (government, industry, academia). Category B qualified individuals with appropriate experience would be technical professionals preparing and delivering products and services to meet specifications and outcomes.

Definitions

Subjects, topics, and elements

The S5-B standard contains the following list of **Basic subjects** and **Essential subjects**:

B1: Mathematics, Statistics, Theory of Errors

B2: Information and Communication Technology

B3: Physics

B4: Earth Sciences

B5: Nautical science

B6: Meteorology

E1: Underwater Acoustics

E2: Remote Sensing

E3: Water Levels and Flow

E4: Positioning

E5: Hydrographic Practice

E6: Hydrographic Data Management

E7: Environment

CFFP: COMPREHENSIVE FINAL FIELD PROJECT

Topics and Elements:

- Each **Essential** or **Basic** subject is comprised of a list of topics which are denoted by Ex.y or Bx.y;
- Each topic contains elements which are denoted by Ex.y<c>.

For example, the *subject* E5 "Hydrographic practice" contains the *topic* E5.1 "Hydrographic survey projects" which has the *element* E5.1a "Hydrographic surveys purposes".

Learning outcomes and list of content

It is important to understand that each *element* is associated with:

- an intended *learning outcome*, that a student should be able to achieve on completion of the programme. All *learning outcomes* should be evaluated, either by or through a combination of, assessment, examination, laboratory work or final project work.
- a list of *content*. This list is associated with one or more *learning outcomes* and describes the theoretical knowledge or practical/technical context which the course syllabi should address in order to meet a particular *learning outcome*.

For the sake of clarity, a level of knowledge associated with each learning outcome has been defined. It is indicated in italics in the left column, by a letter (*B: Basic, I: Intermediate;* see "Guidelines for the Implementation of the Standards of Competence for Hydrographic Surveyors"). This letter designation (*B: Basic, I: Intermediate*) complements the learning outcome description associated with each element.

Programme preparation and submission

The preparation of a programme submission to the IBSC should be done in accordance with the document entitled GUIDELINES FOR THE IMPLEMENTATION OF THE STANDARDS OF COMPETENCE FOR HYDROGRAPHIC SURVEYORS. This document is available from the IHO website: $\underline{\text{www.iho.int}} \rightarrow \text{Standards} \& \text{Publications}.$

The cross reference table is a mandatory requirement for a programme submission and **MUST** be completed. A template is specified and is available from the IHO website: www.iho.int

List of acronyms and initialisms used in this document

1D One-dimensional2D Two-dimensional

ADCP Acoustic Doppler Current Profiler
AIS Automatic Identification System
ASV Autonomous Surface Vehicle
AUV Autonomous Underwater Vehicle

B Basic (level of knowledge)CAD Computer Aided Design

CFFP Comprehensive Final Field Project

DGNSS Differential Global Navigation Satellite System
EPIRB Emergency Position Indicating Radio Beacon

FIG International Federation of Surveyors
GIS Geographical Information System

GMDSS Global Maritime Distress and Safety System

GNSS Global Navigation Satellite System
 GRS80 Geodetic Reference System (1980)
 I Intermediate (level of knowledge)

IBSC International Board on Standards of Competence for Hydrographic Surveyors and Nautical

Cartographers

ICA International Cartographic Association
IHO International Hydrographic Organization

IMU Inertial Motion Unit

INS Inertial Navigation System

LAN Local Area Network

LiDAR Light Detection And Ranging
MBES Multi Beam Echo Sounder

MSL Mean Sea Level
NAVTEX Navigational Telex

P Practicals (fieldwork and/or laboratories)

RAM Random Access Memory

ROV Remotely Operated Underwater Vehicle

S-44 IHO Publication S-44 — *Standards for Hydrographic Surveys*

S-100 IHO Publication S-100 Universal Hydrographic Data Model

S-102 IHO Publication S-102 Bathymetric Surface Product Specification

SARSAT Search And Rescue Satellite Aided Tracking

SBES Single Beam Echo Sounder
SDB Satellite Derived Bathymetry
SDI Spatial Data Infrastructure

SG Self-guided exercises (or student's personal independent work)

SSDM Standard Seabed Data Model

T Theoretical (theory through lectures)

TIN Triangulated Irregular Network

UNCLOS United Nations Convention on the Law of the Sea

USBL Ultra Short Baseline

UTM Universal Transverse MercatorWGS84 World Geodetic System (1984)XML Extended Markup Language

1

1. Basic subjects

1.1. B1: Mathematics, Statistics, Theory of Errors

Topic/Element	Content	Learning outcomes
B1.1 Linear Algebra (B)	1) Vector and affine spaces, vector and inner products norms.	Describe and apply 2D transformations involved in surveying and mapping. (E4.1c) Solve linear equations using matrix methods.
	2) Linear equation determin	ants.
	3) Analytica geometry line and plane equation	r,
	4) Linear operators matrix represen composition inverse,	tation,
	transpos 5) Translati rotations coordina transforn	ons,
B1.2 Differential calculus (B)	1) Real and vector valued functions	Compute the gradient of a vector valued function. Define a function as a series. Calculate explicit integrals of classical functions.
	2) Gradient of real-valued functions and their discrete approxim	
	3) Series and integrals	
B1.3 Trigonometry (B)	Basic trigonom Sphere, great circle, rhumb lines, sphere angles, spherica triangles and	

Topic/Element	Content	Learning outcomes
	spherical excess.	
B1.4 Statistics (I)	Random variables, mean, variance, standard deviation	Explain what is meant by a random variable, estimate the mean, variance and standard deviation for a random variable and also the covariance between random variables.
	2) Covariand and correlation	
	3) Estimation of mean, variance, covariance	
	4) Normal distribution	ו
B1.5 Theory of errors (B)	Linear observatio equations	Apply the variance propagation law to a linear observation equation, in and derive a measurement uncertainty as a function of observables' covariances.
	2) Covariano propagatio law	
B1.6 Least squares (B)	Least squares procedure	Interpret results from a least square estimation applied to survey measurements.
	2) Covariand of estimated parameter	
	3) Use of unit variance factor estimate	
	4) Interpretat of ellipses of confidence	
B1.7 Interpolation (B)		Differentiate between 1-D and spatial interpolation methods. Create I and compare interpolated surfaces from one set of sparse survey on measurements using appropriate software under different configurations.

1.2. B2: Information and Communication Technology

Topic/Element	Content	Learning outcomes
B2.1 Computer systems (I)	 Central Processing Unit RAM, data storage Communication board, serial links, communication ports buffers, Ethernet links, data transmission rates Communication protocols Clocks, clocks drift, time tagging and synchronization of data Operating systems Device drivers 	Describe the different components of a real-time data acquisition system, including various modes of communication and timetagging. Describe the role of a device driver and its relation to data exchange.
B2.2 Office work software suites (I)	Word processors Spreadsheets Graphics and image processing software Database management systems and query languages	Use classical office work software suites. Construct a database, populate it and query its content.
B2.3 Programming (I)	 Basic operations of a computer program or script Algorithms (loops, conditional instructions) Scientific computation environments Application to data exchange, file conversion 	Write a program for data format conversion and/or basic algorithm computation.
B2.4 Web and network communications (B)	Networks (LANs) Internet Networks integrity Communication protocols	Describe the different network communication protocols used in remote data exchange applications.
B2.5 Databases (B)	 File types (binary, text, XML) Relational databases Geospatial databases 	Describe different types of geospatial data and their representation.

1.3. B3: Physics

Topic/Element	Content	Learning outcomes
B3.1 Mechanics (B)	(anguand linear veloci accelo Effect 3) Newto law, forces accelo	ties, erations) is on's erations,
B3.2 Gravity (B)	1) Gravii field of	ty Describe the gravity field of the earth in terms of acceleration and potential

Topic/Element	Content	Learning outcomes
	the earth	
	2) Equipo surface	otential es
B3.3 Waves (B)		onDatgeretinatiate between types of waves and their generation and propagation. Explain how medium parameters affect wave behavior.
	2) Pressu waves	
	3) Ocean waves	
	4) Wave Propag	gation
	5) Electro	omagnetic um
	6) Radiat emissi and absorp	on
	7) Reflect refract diffract	ion,

1.4. B4: Earth Sciences

Topic/Element	Content	Learning outcomes
B4.1 Geography and geology (B)		Describe the internal structure, the physical characters and dynamics cspf the Earth referring to ocean basin structure, and the major processes uabefisecting coastal morphology
	2) Differe types of rocks	nt
	3) Erosio and deposi	
	4) Rivers and estuari	
B4.2 Substrates (B)	1) Sedim- types	enDistinguish common seafloor characteristics. Describe the ocean bottom as a multilayered structure composed of sediment deposits
	2) Sedimo	
	3) Siltatio	n e
	4) Subme aquation vegeta	
	5) Corals	

1.5. B5: Nautical science

Topic/Element	Content	Learning outcomes
B5.1 Conventional aids to navigation (B)	 Types of buoys and beacons Radar beacons AIS systems 	Describe the principal fixed and floating aids to navigation and the use of automatic identification systems.
B5.2 GMDSS (B)	 Sea areas EPIRBs and SARSAT Digital selective calling NAVTEX Inmarsat-C 	Describe the components and purpose of GMDSS.
B5.3 Nautical charts (B)	 Content, datum, projection, scale and types of nautical charts Chart symbols Chart graticules Uncertainty indicators (e.g. source diagram, reliability diagram, zone of confidence, notes) Navigational hazards Plotting instruments 	Layout a route on a nautical chart, plot positions, identifies navigational hazards and revise navigational plan as required. Describe the content of a nautical chart and explain datum, projection, scale Describe the uncertainty indicators associated with nautical charts.
B5.4 Navigation publications (B)	 Sailing directions, Light and radio lists, Tides and current tables Notice to mariners 	Use content of nautical publications in a survey planning context.
B5.5 Compasses (B)	 Earth magnetic field Magnetic compasses Gyros Compass error and corrections 	Describe the capabilities, limitations and errors of magnetic and gyro compasses. Determine and apply corrections for magnetic and gyro compass error.
B5.6 Emergency procedures (B)	 Fire extinguishers Life preservers and cold water survival suits, life rafts Distress signals and EPIRB Procedures for man-overboard, fire, and abandoning ship 	Explain the importance of the emergency equipment and procedures.
B5.7 Safe working practice (B)	 Water-tight doors and hatches Suspended loads Enclosed spaces Working aloft, with equipment over the side Work permitting Securing equipment for sea Cables and antenna installation Earthing of electrical equipment High voltage electrical safety Personal protective equipment 	Describe procedures for maintaining a safe working environment. Draw a diagram to indicate safe cable routes for survey instruments. Describe methods for securing equipment for heavy weather.
B5.8 Rope and wires (B)	 Types of wire and rope Characteristics (stretch, floating, strength) of ropes. Basic knots 	Select and tie basic knots. Select appropriate wire or rope.

Topic/Element	Content	Learning outcomes	
B5.9 Towed and over the side instruments (B)	 Rosette systems and instruments ROVs, AUVs, towed systems, catenary and layback A-frames, cable blocks, electro-mechanical wire, slip rings and optical cabling Moonpools Launch and recovery Station keeping and maneuvering 	Deploy and recover oceanographic and hydrographic equipment	
B5.10 Anchoring (B)	 Shipboard ground tackle including anchor, chain, windlass, stoppers Small boat anchoring Multiple anchors 	Describe ship and small boats anchoring and ground tackle. Explain how the final position of the vessel can be adjusted through the use of anchors.	
B5.11 Instrument moorings (B)	Launch and recovery Anchors and acoustic releases Scope, wire, flotation, tension Weights	Prepare, deploy and recover seabed instruments.	

1.6. B6: Meteorology

Topic/Element	Content	Learning outcomes
B6.1 Weather observations (B)	and the variabilit of the	e Operate instruments and sensors used to register temperature, pressure, direction and intensity of wind. Record these parameters according to internationally accepted standards. y Identify characteristics of weather by simple observation of the sea and the sky.
B6.2 Wind (B)	2) Tempera humidity dew-point, frost-point	tExplain the relation between atmospheric pressure, temperature and
	3) Atmosph pressure winds	
	4) Clouds and precipita	tions
	5) Rain, snow	
	6) Visibility advection fog and radiation fog	n
	7) Pressure systems	
	8) Geostro winds, anabatic and	

Topic/Element	Content	Learning outcomes
	katabati winds	
	9) Instrume and sensors used to register tempera pressure direction and intensity of wind	tures,
B6.3 Weather forecasting (B)	Synoptic charts Weather forecast	Interpret a synoptic chart. Produce an operational short range forecast based on meteorological information, weather bulletins and facsimile charts

2. Essential subjects

2.1. E1: Underwater Acoustics

Topic/Element	Content	Learning outcomes			
E1.1 Acoustic Th	E1.1 Acoustic Theory				
E1.1a Generation of acoustic waves (B) E1.1b Propagation of	Plane and spherical waves in terms of wavelength, amplitude and frequency. Speed of sound in relation to water properties and profile in the water column. Acoustic units, intensities and sound levels Active Sonar Equation including sound source, causes of propagation loss in relation to water properties together with characteristics of the sea floor and targets, noise level and directivity Refraction and the path of sound rays through the water column. Transducer principles and beam characteristics System parameters including bandwidth, pulse length,	Explain how transducer parameters impact upon beam characteristics. Using appropriate units, describe acoustic wave			
acoustic waves		behavior with reference to physical properties of the water column. Create a sound speed profiles from water column measurements and describe its effect on the acoustic ray path.			
E1.1c Reflection, scattering and system performance (B)	pulse repetition rate, gain, detection threshold, range resolution and spatial resolution.	Detail sources of noise and the impact of noise on operation of acoustic systems.			
E1.1d Reception of acoustic waves (B)		Explain how a system is optimized in terms of environmental factors for measurement and target detection.			
E1.2 Single Beam Systems & Side Scan Sonar					
E1.2a Single beam echo sounders (I)	 Split beam and dual beam echo sounders Components of a single beam echo sounder. Operation of single beam echo sounders. 	Set up, deploy and operate a single beam echo sounder.			

Topic/Element	Content	Learning outcomes
	 5) Full-echo-envelope returns 6) Sub-bottom profiling systems. 7) Validation & Calibration. 8) Principles, components, geometry and deployment of side scan sonar systems. 	Select appropriate range, scale, frequency and pulse repetition rate for specific applications in relation to spatial resolution, bottom penetration and depth of water.
E1.2b Single beam echo sounder data recording. (I)	10) Side scan images and sources of distortion.11) Combining sources of uncertainty.	Interpret echo sounder returns through differentiation between return signals.
E1.2c Range uncertainty (I)		Detail and quantify components contributing to uncertainty in derived ranges.
E1.2d Side scan sonar (I)		Set up, deploy and operate side scan sonar. Interpret side scan sonar records considering target characteristics, system configuration, potential sources of noise and distortion.
E1.3 Swath Syste	ems	
E1.3a Beam characteristics (B)	 Transducer elements and arrays. Beam forming and beam steering Principles and geometry of multi-beam and interferometric (phase measurement) sonar systems Amplitude and phase bottom detection Variations in beam spacing and footprint size Backscatter and seabed classification Hull and pole mounting of transducers considering platform motion. Integration of components including time stamping, attitude compensation, sensor offsets and networking. Surface and water column sound speed monitoring Gain, power, pulse length Quality control procedures 	Define characteristics of beams in relation to transducer settings. Compare phase and interferometric systems with multi-beam systems
E1.3b Backscatter and water column returns (B)		Describe characteristics of returns in the context of seabed type, angle of incidence and scatter from within the water column
E1.3c Bottom spatial coverage (I)		Determine sounding density and object detection capability as functions of system parameters
E1.3d Installation and configuration (B)		Describe suitable mounting structure and location for transducers given operational constraints
E1.3e Range and angle uncertainty (I)		Differentiate between error sources in phase and amplitude detection modes. Identify sources of range and angle uncertainty depending on acoustic parameter configuration

Topic/Element	Content	Learning outcomes
E1.3f Operation (I)		Set up, deploy and operate a swath sonar system. Identify problems or artefacts in on-line data due to inappropriate configuration or changing environmental parameters. Tune acoustic parameters for optimum performance. Apply quality control procedures to data acquisition and on-line processing

2.2. E2: Remote Sensing

Topic/Element	Content	Learning outcomes
E2.1 LiDAR		J
E2.1a Airborne LiDAR systems (B) E2.1b Airborne LiDAR data products (B)	 Wavelength, water penetration and ground detection Scanning frequency and pattern in relation to power, coverage and spatial density. Influence of sea surface roughness, water column turbidity on the beam pattern and penetration. Sea bed optical characteristics and bottom detection. Secchi disc and Secchi depth Optical characteristics of coastal terrain. Influence of geometry and waveform on feature detection. Integration of components including time stamping, attitude compensation, sensor offsets and networking. Combined bathymetric and topographic LiDAR systems 	Explain the principles, capabilities and limitations of topographic and bathymetric LiDAR. Describe the physical environment and operational situations in which bathymetric LiDAR surveys are complementary to echo sounder surveys Extract high and low water lines from bathymetric and topographic LiDAR data sets. Use topographic and bathymetric LiDAR data to complement other spatial data. Use terrestrial LiDAR data to complement other coastal spatial data.
E2.2 Remote Sei	nsing	,
E2.2a Remotely sensed bathymetry (B)	Multispectral imagery and water penetration in relation to wavelength Satellite Derived Bathymetry (SDB) Spatial resolution and accuracy available.	Demonstrate awareness of techniques and data sources in remotely sensed bathymetric data and the spatial parameters associated with such data.
E2.2b Shoreline delineation (B)	Multispectral imagery, reflectance in relation to wavelength and terrain characteristics.	Describe geometrical properties of images

Topic/Element	Content	Learning outcomes
	Geometrical properties of satellite images and aerial photographs	and use them to create a shoreline map from images and aerial photographs.

2.3. E3: Water Levels and Flow

Topic/Element	Content	Learning outcomes
E3.1 Principles of Water Leve	els	
E3.1a Tidal fundamentals (B)	Tide generati forces, the equilibrities and real tides. Major harmoniconstitue and different	the common the common that the
	types of tide. 3) Amphidr points are co-tidal	romi¢
	charts. 4) Geomor influence on tidal characte	
E3.1b Tidal information (B)	Tide and current tables Tide prediction tools	predicted water levels and tidal currents.
E3.1c Non-tidal water level variations (B)	1) Changes water lev caused I atmosph pressure wind, seiches ocean tempera and precipita	levels in the conduct of a hydrographic survey Describe sources of water level variations occurring in inland waters e, , ture ittion.
	2) Water le variation in estuarie: wetland and river	s, s,
	3) Water le variation occurring in inland	g

Topic/Element	Co	ntent	Learning outcomes
		lakes, rivers, reservoirs and canals	
E3.2 Water Level Measureme	ent		
E3.2a Water level gauges (I)	1)	Operating principles of various	Explain the principles of operation of different types of water level gauges. Install, level and calibrate a water level gauge.
E3.2b Tidal measurement (I)		types of water level gauges including	Configure water level gauges for logging data, data communication, data download and for network operation with appropriate quality control measures.
E3.2c Water level datums (B)		pressure (vented and unvented), GNSS	Define various tidally based reference levels on the basis of tide time series and explain how these values are computed. Describe how vertical reference levels in rivers and lakes are defined, and determined in practice.
E3.2d Uncertainty in water level (B)		buoys, float, radar, acoustic sensors and tide poles/ boards/ staffs.	Relate uncertainty in water levels to uncertainties in measurement, duration and distance from water level gauge.
	2)	Installing water level gauges, establishmen and levelling of associated survey	nt
	3)	marks Networks of water level gauges	
	4)	Reference levels such as MSL, chart datum, and mean high water.	
	5)	River and lake datums	
	6)	Uncertainties associated with measurement devices	
	7)	Uncertainties associated with duration of observations	
	8)	Uncertainties associated with spatial	

Topic/Element	Content	Learning outcomes
	separation of water level measuremer	nts.
E3.3 Water Level Reduction		
E3.3a Water level reduction of soundings (I) E3.3b Reduction of soundings using GNSS observations (I)	1) Vessel draft, squat 2) Leverarms and Position Reference Point offsets 3) Vertical datums for sounding reduction 4) Predicted tides versus measured tide reduction 5) Co-tidal charts 6) Reduction of survey data to a datum using GNSS observations 7) Poduction	Use tidal information, and vessel parameters to reduce soundings to a specified datum. Configure and calibrate GNSS to reduce soundings to a specified survey datum.
E3.4 Currents	7) Reduction of survey data using water level observations	
E3.4a Tidal streams and currents (B) E3.4b Current measurement and portrayal (B)	The relationship between currents and tides Rectilinear and rotary tidal streams Methods for measuring tidal streams and currents, including current meters, acoustic current	Explain the forces behind currents and change in currents with tides. Describe techniques for current measurement and identify appropriate methods for acquiring and displaying current data.

Topic/Element	Content	Learning outcomes
	profilers (ADCP) and drogues.	
	4) Current surveys	
	5) Surface current radar observatio	n
	6) Portraying current data	

2.4. E4: Positioning

Topic/Element	Content	Learning outcomes				
E4.1 Geodesy	E4.1 Geodesy					
E4.1a Introduction to Geodesy (B)	 Shape of the Earth as a sphere, ellipsoid of revolution and the geoid; Definitions of astronomical terms and time. 	Describe the shape of the Earth in terms of potential and ellipsoidal models				
E4.1b Coordinate systems, frames and datums (B)	 3) Geodetic computations on the ellipsoid. 4) Local geodetic reference frames 5) Vertical datums 6) Terrestrial reference systems and reference frames. 	Describe modern geodetic reference systems and associated reference frames.				
E4.1c Geodetic transformations and associated computations (B)	7) Modern geodetic datums WGS84, GRS80.8) Datums and datum transformation techniques	Describe horizontal and vertical datum transformation concepts				
E4.1d Ellipsoidal computations (B)		Describe geometry of lines on the ellipsoid and perform forward and inverse computations on the ellipsoidal surface using available software.				
E4.2 Principles of	Cartography					
E4.2 Map projections (B)	 Geometrical properties of map projections Cylindrical, conical projections including the UTM system and stereographic Analytical projection formulae and planimetric coordinates Distortions in distance and direction associated with different map projections 	Describe the properties and distortions in different types of projections used in maps and charts. Explain the selection of projection type and apply appropriate projection formulae.				
E4.3 Positioning	⊔ Measurements, Methods and Techniques	<u> </u>				
E4.3a Positioning fundamentals (I)	Principles of distance measurement and angle measurement Principles of 2D adjustment Sextant Total station Theodolite Electromagnetic positioning devices	Undertake control surveys, establish, mark and describe control stations, describe horizontal positioning procedures, apply appropriate methods and use corresponding				

Topic/Element	Content	Learning outcomes
	 7) Intersection, Resection, Polar and Traverse 8) Astronomic methods for determination of orientation. 9) Expansion of traditional geodetic networks 10) Principle of GNSS positioning 	instruments for positioning. Correct gyros using astronomic methods.
E4.3b Satellite positioning (I)	 GNSS services characteristics (single baseline, network, Precise Point Positioning) Performance of code vs. carrier; differential vs. autonomous modes; multiple vs. single frequency; fixed vs. float ambiguity resolution Atmosphere (troposphere, ionosphere) effects on GNSS signals Control stations Logistical aspects of providing control 	Explain the GNSS concept and principles. Define pseudo ranging and carrier phase based modes of satellite positioning Differentiate between base station and permanent networks, real-time and post-processing.
E4.3c Positioning systems (I)		Field test and use distance and angle measurement instruments. Apply field validation procedures Operate GNSS and DGNSS equipment, assess accuracy and precision, post-process GNSS data using appropriate software.
E4.3d Historical surveys (B)		Relate historical surveys to legacy positioning systems.
E4.3e Survey control (I)		Establish, mark, and describe control stations, particularly hydrographic stations.
E4.4 Vertical Posi	tioning	1
E4.4a Height systems (B)	Height systems (dynamic, orthometric and normal) Leveling instruments Total stations	Differentiate between gravity-related and ellipsoidal heights
E4.4b Elevation measurements and computation (I)	4) Effects of curvature and refraction 5) GNSS observations	Describe methods for determining elevation differences. Determine height using GNSS equipment. Compute elevations and leveling networks from observed leveling data. Use observation techniques for correction of curvature and refraction.
E4.5 Acoustic Pos	sitioning	
E4.5a Acoustic positioning concepts (B)	 Long baseline Short baseline Ultra-short baseline Transponders Depth sensors Integration with INS and velocity sensors 	Describe the deployment, calibration, signal structure and performance of acoustic positioning devices. Describe the use of acoustic positioning

Topic/Element	Content	Learning outcomes	
	Use of acoustics for positioning towed vehicles, ROVs and AUVs	systems in offshore survey operations.	
E4.5b Acoustic positioning systems (B)		Describe the principles of integrated subsea positioning systems and their application to remote survey platforms	
E4.6 Inertial Nav	igation	,	
E4.6a Inertial Measurement Units (B)	Gyros and accelerometers IMU Procedures for INS static and dynamic alignment Use of IMU in heave estimation Aided Inertial navigation: ADCP/INS	Describe principles and use of IMU's including north finding and heave estimation. Compare IMU heading measurements with magnetic and gyro compasses.	
E4.6b Inertial Navigation Systems (B)	b) GNSS/INS c) USBL/Depth/INS	Distinguish IMUs and INS, and describe dynamic alignment of INS. Explain the concepts of aided inertial navigation system.	
E4.7 Uncertainty	in Positioning		
E4.7 Sources of uncertainty (I)	1) Static surveys: a) GNSS observations b) Total stations c) Leveling instruments d) Acoustic positioning 2) Mobile surveys: a) GNSS equipment b) IMU/INS c) Acoustic positioning 3) Total propagated uncertainty	Describe and explain the sources and magnitude of uncertainties associated with each positioning method and positioning system. Monitor, review and assess the performance of each positioning system to be used including repeatability, precision and accuracies of relative and absolute positions using appropriate statistical tools.	

2.5. E5: Hydrographic Practice

Topic/Element	Content	Learning outcomes		
E5.1 Hydrographic Survey Projects				
E5.1a Hydrographic	 IHO S-44 and other survey quality standards. Hydrographic instructions and tenders 	Compare, interpret and apply hydrographic instructions and		

Topic/Element	Content	Learning outcomes		
survey purposes (I) E5.1b Hydrographic survey execution requirements (I) E5.1c Hydrographic survey project organization (B)	3) Types of surveys, such as: a) Nautical charting survey b) Boundary delimitation survey c) Ports, Harbor and waterways surveys d) Engineering works and dredging surveys e) Coastal engineering surveys f) Inland surveys g) Erosion and land-sea interface monitoring h) Environmental impact assessment i) Deep sea and ROVs /AUVs surveys j) Seismic and geomagnetic surveys k) Pipeline route, pipeline installation and cable laying surveys	tenders associated with survey specifications. Identify the different phases and terminology associated with types of survey operations. Distinguish the roles and responsibilities of individuals within a survey team.		
E5.2 Hydrograph	ic Survey Operations			
E5.2a Operational survey data transfer (I)	 Remote water level measurement, Shore based stations in support of positioning systems Use of remote survey platforms and real time communication of data acquired. Data telemetry links including radio, satellite, telephonic and underwater communications. Compatibility between equipment and communications devices. 	Describe data telemetry in support of on board survey data including applications and methods. Implement a data telemetry link between a survey infrastructure component and a survey system for real-time use.		
E5.2b Survey systems (I)	Installation and calibration requirements for: a) Echo sounders b) Swath systems c) Side scan sonar	Explain the importance of the correct installation, calibration and determination of the attitude and position of each sensor.		
E5.2c Calibration and corrections (I)	 d) Surface and sub-surface positioning system e) IMU/INS 2) Sound velocity probes and profilers 3) Data acquisition and integration systems 4) Bar check 5) Boresight calibration for alignment bias 6) Layback calculations 	Setup, integrate and test survey system including sensors, acquisition system time-stamping strategy with appropriate physical offset determination. Explain the purposes and apply speed of sound measurements in acoustic systems.		
E5.2d Line planning (I)	Planning for data acquisition including line spacing and sample locations in alignment with tasks to be performed on surveys and equipment to be used.	Plan survey vessel survey lines as well as towed, remote vehicle and autonomous vehicle lines in space and time.		
E5.2e Line keeping (B)	 Planning of survey operation considering currents, tides and survey speed. Track guidance and route following information systems. 	Explain the methods of maintaining a survey vessel or survey system on a planned survey line or route. Describe the effects on the survey quality due to the vessel motion (speed over the ground, angular velocity).		

E5.2f Survey operations (B)	Survey parameters including: Survey parameters including:	Describe the roles and the
E5.2g Quality control (I)	 a) scale, b) positional accuracy and precision, c) survey speed, d) line orientation, e) environmental and oceanographic parameters f) survey lines, interlines and cross lines, g) sounding density and spatial resolution h) overlap i) data coverage. 2) Quality control of: a) Horizontal position b) Vertical position (heave, squat, water level) c) Coverage and overlap d) Swath system data e) Sound speed 	relationships of the following survey parameters: scale, positional accuracy, survey speed, line orientation, survey lines, interlines, cross lines, fix interval, data coverage. Explain methods for quality control of survey data and the quality assurance of survey operations.
E5.3 Hydrographi	c Survey Documentation	
E5.3a Documentation (/)	 Production of reports associated with the survey to include items such as: Coverage including special investigation areas Features such as rocks, wrecks, obstructions, wellheads and pipelines (least depth, extent and position) Track charts Geodetic control on features such as shoreline and navigation aids Metadata to include data types of data obtained together with associated quality measures such as positional, thematic and temporal uncertainty as well as lineage. Maintaining survey notes on event by event findings during data acquisition. Quality control procedures implemented and calibration reports produced Compliance with survey specifications and standards. 	Create and compare different documents associated with survey procedures in alignment with requirements using files, charts and reporting tools. Describe the sources and means by which metadata files are created and populated.
E5.4 Legal Aspec	ts	
E5.4a Liability of the hydrographic surveyor (B)	 Nautical charts. Notice to mariners. Survey reports. Fundamentals of professional liability relating to surveying 	Detail the role and responsibilities of the hydrographic surveyor as required under professional ethics, industry standards and national/international legislation/conventions. Explain the potential liability of the hydrographic surveyor
E5.4b Delimitations (B)	Historical development of 1982 UNCLOS Baselines – normal (including closing lines); straight and archipelagic Base points	Describe the types of baselines under UNCLOS and how the territorial sea limit is projected from them, including the use of

Topic/Element	Content	Learning outcomes
	3) Baselines	
	4) Internal waters.	
	5) Territorial seas.	
	6) Contiguous zones.	
	7) Exclusive Economic Zone	
	8) Extended continental shelf.	
	9) High seas	

2.6. E6: Hydrographic Data Management

Topic/Element	Content	Learning outcomes	
E6.1 Real-Time Data	E6.1 Real-Time Data Acquisition and Control		
E6.1a Hydrographic Data acquisition (I)	Integration and logging of data	Configure the data collection and recording software for sensors and select sampling rates, gating and filtering settings. Describe the process of on-line data validation and selection.	
E6.1b Real-time data monitoring (I)	of data from various sensors in accordance with survey specification to include equipment such as: a) Echo sound (SBES MBES) b) LiDAF c) Sound velocir profile surface velocir probe d) Sidescan sonar e) Surface positice system f) IMU / INS g) Subse positice system (USBI h) ROV / ASV	ce ching the chi	
	2) Data acquisition		

Topic/Element	Content	Learning outcomes
	system and software 3) Time- tagging 4) Data visualization	on
E6.1c Data transfer and storage (I)	1) Content of files in different formats used to record data in survey planning, data acquisition and products. 2) Organizati of survey databases 3) Data storage and backup systems	on
E6.2 Data Processir	ng and Analysis	
E6.2a Spatial data cleaning (I)	Data cleaning techniques (manual and automated) Identificati of outliers Identificati of real features	n) on
E6.2b Spatial data quality control (I)		
	3) Comparing crossing or adjacent data between	

Topic/Element	Content	Learning outcomes
	survey lines 4) Comparir overlappi data between survey platforms 5) Identificat of systemati errors	ion
E6.2c Spatial data representation (I)]
E6.3 Data Organizat	ion and Preser	ntation
E6.3a Databases (B)	1) Raster and vector data models and commonly used file types 2) Spatial Data Infrastructincluding GIS 3) Database to hold different types of feature and geograph informatic	ical
E6.3b Marine GIS basics (I)	Features and feature types of point, line and polygon with marine examples Marine and coastal data bases	Explain the concept and use of Geographical Information Systems (GIS) within the marine environment. Create a GIS project using marine spatial data. Merge and mash up data sets of different origin by applying datum and projection transformations.

Topic/Element	Content	Learning outcomes
	 3) Coordinate reference system 4) Vertical datums 5) Survey metadata 6) Base maps and images 	
E6.3c Visualization and presentation (I)	Symbology Use of color schemes Shading and illumination Resolution Vertical scale / exaggeration	interest within a hydrographic data set.
E6.3d Deliverables (I)	1) Products provided directly from source data such as sounding data files and metadata. 2) Feature databases such as wrecks, rocks and obstruction	
	3) Data required for sailing directions, light lists, port guides and notices to mariners. 4) Data required for offshore hazards and	

Topic/Element	Content	Learning outcomes
	anomalies	
	survey 5) Digital	
	and	
	paper	
	products derived	
	from	
	source	
	data for	
	various survey	
	types	
	and	
	usage such as	
	GIS and	
	CAD	
	files and/	
	or geo- referenced	
	images.	
	6) Reports	
	on	
	quality control,	
	procedures	5,
	results	
	and conclusion	e e
	detailing	
	processes	
	adopted within	
	survey	
	operations	
	and data	
	processing 7) Product	•
	7) Product standards	
	including:	
	a) IHO S-	
	S- 100	
	and	
	produc	pt .
	standa such	irds
	as S-	
	102.	
	b) Standa	
	Seabe	d
	Data Model	
	(SSDN	/ 1).

2.7. E7: Environment

Topic/Element	Content	Learning outcomes
E7.1 Oceanography		
E7.1a Physical properties of sea water (I)	Units used in measuring and	Use oceanographic sensors to measure physical properties of sea water and compute speed of sound using observed physical properties of sea water.
E7.1b Oceanographic measurements (I)	describing physical properties of sea water, normal ranges and relationship including: salinity, conductivity temperature pressure, density.	os ,
	2) Oceanogra sampling and methods for measuring common oceanograp parameters and profiles	phic
	3) oceanographics sensors (e.g. for temperature conductivity and depth) and need for calibration	e,
E7.1c Waves (B)	Wave parameters and elements involved in the wave growth process including fetch and bathymetry Breaking waves,	
	long-shore drift and rip current processes.	

Topic/Element	Content	Learning outcomes
E7.2 Marine Geology a	nd Geophysics	
E7.2a Seabed characteristics (B)	Seabed samplers such as grabs, corers and dredges and basic sediment types. Types of seabed Processes involved in seabed dynamics	Explain the objectives of seabed sampling detailing sampling equipment and how samples are stored and analyzed.
E7.2b Magnetic surveys (B)	Magnetic fields and anomalies Objectives of magnetic surveys to detect pipelines, cables and ordnance. Magnetomer	Describe Earth's magnetic field and explain the use of magnetometers and the objectives of magnetic surveys.
E7.2c Seismic surveys (B)	Continuous reflection/ refraction seismic profiling. Typical sound sources, receivers and recorders. High resolution seismic systems Sub-bottom profilers	Explain the objectives of seismic surveys and the equipment used to conduct such surveys.
E7.3 Environmental im	pact	
E7.3a Impact of surveys (B)	Permanent and temporary threshold shifts (hearing) for marine mammals. Use of physical techniques such as bar	Describe appropriate procedures and limitations for use of surveying equipment in compliance with environmental laws and marine protected area regulations.

Topic/Element	Content	Learning outcomes
	sweeps ir environme sensitive areas.	
	3) Respect for cultura traditions relation to use of the environme	in D C
	4) Marine protected areas	

3. CFFP: Comprehensive Final Field Project

Programmes must include a supervised and evaluated Comprehensive Final Field Project with a minimum aggregate period of **at least four weeks**; see "GUIDELINES FOR THE IMPLEMENTATION OF THE STANDARDS OF COMPETENCE FOR HYDROGRAPHIC SURVEYORS AND NAUTICAL CARTOGRAPHERS".

The Comprehensive Final Field Project for Category "B" level shall comprise a comprehensive field survey incorporating different aspects of hydrography in a complex environment with varying sea-floor and oceanographic conditions.

Students should undertake:

- Survey specification and planning;
- Hydrographic and oceanographic measurements using a comprehensive suite of instruments;
- Data processing, quality control and quality assurance;
- Preparation of different type of product deliverables and reports.

NOTE: the Comprehensive Final Field Project does not include the practical exercises that form a part of the course modules syllabi and are designed to complement the theory.