

TheGI4 HA4

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14. Juli 2014

Aufgabe 1

Aufgabe 1 a)

Wir bestimmen zunächst $\llbracket X \rrbracket$:

Sei $F_X = \langle a \rangle X \wedge [c] \text{ff}$

$$\begin{aligned}
 \mathcal{O}_{F_X}(\text{Proc}) &= \langle a \cdot \rangle \text{Proc} \cap [\cdot c] \text{ff} \\
 &= \{p_1, p_2, p_5\} \cap \{p_2, p_3, p_5, p_6\} \\
 &= \{p_2, p_5\} \\
 (\mathcal{O}_{F_X})^2(\text{Proc}) &= \langle a \cdot \rangle \{p_2, p_5\} \cap [\cdot c] \text{ff} \\
 &= \{p_2\} \cap \{p_2, p_3, p_5, p_6\} \\
 &= \{p_2\} \\
 (\mathcal{O}_{F_X})^3(\text{Proc}) &= \langle a \cdot \rangle \{p_2\} \cap [\cdot c] \text{ff} \\
 &= \{p_2\} \cap \{p_2, p_3, p_5, p_6\} \\
 &= \{p_2\} \Rightarrow \text{Fixpunkt!}
 \end{aligned}$$

Nun können wir $\text{Safe}(\langle b \rangle X)$ berechnen.

Wir wissen: $\text{Safe}(F) : Y \stackrel{\text{max}}{=} F \wedge ([\text{Act}] \text{ff} \vee \langle \text{Act} \rangle Y)$

Sei nun $F_{\text{Safe}(G)} = G \wedge ([\text{Act}] \text{ff} \vee \langle \text{Act} \rangle Y)$

$$\begin{aligned}
 \mathcal{O}_{F_{\text{Safe}(\langle b \rangle X)}}(\text{Proc}) &\stackrel{\text{Def. } \mathcal{O}_{F_{\text{Safe}(G)}}, X}{=} \langle b \cdot \rangle \{p_2\} \cap ([\cdot a] \text{ff} \cup [\cdot b] \text{ff} \cup [\cdot c] \text{ff} \cup \langle a \cdot \rangle \text{Proc} \cup \langle b \cdot \rangle \text{Proc} \cup \langle c \cdot \rangle \text{Proc}) \\
 &\stackrel{\text{Def. } \langle \cdot \cdot \rangle, [\cdot \cdot]}{=} \{p_1\} \cap (\{p_3, p_4, p_6\} \cup \{p_2, p_5, p_6\} \cup \{p_2, p_3, p_5, p_6\} \\
 &\quad \cup \{p_1, p_2, p_5\} \cup \{p_1, p_3, p_4\} \cup \{p_1, p_4\}) \\
 &\stackrel{\text{Def. } \cap, \cup}{=} \{p_1\} \\
 (\mathcal{O}_{F_{\text{Safe}(\langle b \rangle X)}})^2(\text{Proc}) &\stackrel{\text{Def. } \mathcal{O}_{F_{\text{Safe}(G)}}, X}{=} \langle b \cdot \rangle \{p_2\} \cap ([\cdot a] \text{ff} \cup [\cdot b] \text{ff} \cup [\cdot c] \text{ff} \cup \langle a \cdot \rangle \{p_1\} \cup \langle b \cdot \rangle \{p_1\} \cup \langle c \cdot \rangle \{p_1\}) \\
 &\stackrel{\text{Def. } \langle \cdot \cdot \rangle, [\cdot \cdot]}{=} \{p_1\} \cap (\{p_3, p_4, p_6\} \cup \{p_2, p_5, p_6\} \cup \{p_2, p_3, p_5, p_6\} \cup \emptyset \cup \emptyset \cup \emptyset) \\
 &\stackrel{\text{Def. } \cap, \cup}{=} \emptyset \\
 (\mathcal{O}_{F_{\text{Safe}(\langle b \rangle X)}})^3(\text{Proc}) &\stackrel{\text{Def. } \mathcal{O}_{F_{\text{Safe}(G)}}, X}{=} \langle b \cdot \rangle \{p_2\} \cap ([\cdot a] \text{ff} \cup [\cdot b] \text{ff} \cup [\cdot c] \text{ff} \cup \langle a \cdot \rangle \emptyset \cup \langle b \cdot \rangle \emptyset \cup \langle c \cdot \rangle \emptyset) \\
 &\stackrel{\text{Def. } \langle \cdot \cdot \rangle, [\cdot \cdot]}{=} \{p_1\} \cap (\{p_3, p_4, p_6\} \cup \{p_2, p_5, p_6\} \cup \{p_2, p_3, p_5, p_6\} \cup \emptyset \cup \emptyset \cup \emptyset) \\
 &\stackrel{\text{Def. } \cap, \cup}{=} \emptyset \Rightarrow \text{Fixpunkt!}
 \end{aligned}$$

$$\Rightarrow \text{Safe}(\langle b \rangle X) = \emptyset$$

Aufgabe 1 b)

Wir bestimmen zunächst $\llbracket X \rrbracket$:

Sei $F_X = \langle a \rangle X \vee \langle b \rangle X$

$$\begin{aligned}
 \mathcal{O}_{F_X}(\text{Proc}) &\stackrel{\text{Def. } \mathcal{O}_{F_X}}{=} \langle \cdot a \cdot \rangle \text{Proc} \cup \langle \cdot b \cdot \rangle \text{Proc} \\
 &\stackrel{\text{Def. } \langle \cdot \cdot \rangle, [\cdot \cdot]}{=} \{p_1, p_2, p_5\} \cup \{p_1, p_3, p_4\} \\
 &\stackrel{\text{Def. } \cup}{=} \{p_1, p_2, p_3, p_4, p_5\} \\
 (\mathcal{O}_{F_X})^2(\text{Proc}) &\stackrel{\text{Def. } \mathcal{O}_{F_X}}{=} \langle \cdot a \cdot \rangle \{p_1, p_2, p_3, p_4, p_5\} \cup \langle \cdot b \cdot \rangle \{p_1, p_2, p_3, p_4, p_5\} \\
 &\stackrel{\text{Def. } \langle \cdot \cdot \rangle, [\cdot \cdot]}{=} \{p_1, p_2, p_5\} \cup \{p_1, p_3\} \\
 &\stackrel{\text{Def. } \cup}{=} \{p_1, p_2, p_3, p_5\} \\
 (\mathcal{O}_{F_X})^3(\text{Proc}) &\stackrel{\text{Def. } \mathcal{O}_{F_X}}{=} \langle \cdot a \cdot \rangle \{p_1, p_2, p_3, p_5\} \cup \langle \cdot b \cdot \rangle \{p_1, p_2, p_3, p_5\} \\
 &\stackrel{\text{Def. } \langle \cdot \cdot \rangle, [\cdot \cdot]}{=} \{p_1, p_2, p_5\} \cup \{p_1\} \\
 &\stackrel{\text{Def. } \cup}{=} \{p_1, p_2, p_5\} \\
 (\mathcal{O}_{F_X})^4(\text{Proc}) &\stackrel{\text{Def. } \mathcal{O}_{F_X}}{=} \langle \cdot a \cdot \rangle \{p_1, p_2, p_5\} \cup \langle \cdot b \cdot \rangle \{p_1, p_2, p_5\} \\
 &\stackrel{\text{Def. } \langle \cdot \cdot \rangle, [\cdot \cdot]}{=} \{p_2\} \cup \{p_1\} \\
 &\stackrel{\text{Def. } \cup}{=} \{p_1, p_2\} \\
 (\mathcal{O}_{F_X})^5(\text{Proc}) &\stackrel{\text{Def. } \mathcal{O}_{F_X}}{=} \langle \cdot a \cdot \rangle \{p_1, p_2\} \cup \langle \cdot b \cdot \rangle \{p_1, p_2\} \\
 &\stackrel{\text{Def. } \langle \cdot \cdot \rangle, [\cdot \cdot]}{=} \{p_2\} \cup \{p_1\} \\
 &\stackrel{\text{Def. } \cup}{=} \{p_1, p_2\} \Rightarrow \text{Fixpunkt!}
 \end{aligned}$$

Nun können wir $\llbracket Y \rrbracket$ bestimmen:

Sei $F_Y = [b] X \vee [b] Y$

$$\begin{aligned}
 \mathcal{O}_{F_Y}(\emptyset) &\stackrel{\text{Def. } \mathcal{O}_{F_Y}, X}{=} [b \cdot] \{p_1, p_2\} \cup [b \cdot] \emptyset \\
 &\stackrel{\text{Def. } \langle \cdot \cdot \rangle, [\cdot \cdot]}{=} \{p_1, p_2, p_5, p_6\} \cup \{p_2, p_5, p_6\} \\
 &\stackrel{\text{Def. } \cup}{=} \{p_1, p_2, p_5, p_6\} \\
 (\mathcal{O}_{F_Y})^2(\emptyset) &\stackrel{\text{Def. } \mathcal{O}_{F_Y}, X}{=} [b \cdot] \{p_1, p_2\} \cup [b \cdot] \{p_1, p_2, p_5, p_6\}
 \end{aligned}$$

$$\begin{array}{ll}
\text{Def. } \underline{\underline{\langle \cdot \cdot \rangle, [\cdot \cdot]}} & \{p_1, p_2, p_5, p_6\} \cup \{p_1, p_2, p_4, p_5, p_6\} \\
\text{Def. } \underline{\underline{\cup}} & \{p_1, p_2, p_4, p_5, p_6\} \\
(\mathcal{O}_{F_Y})^3(\emptyset) & \text{Def. } \underline{\underline{\mathcal{O}_{F_Y}, X}} \quad [\cdot b \cdot] \{p_1, p_2\} \cup [\cdot b \cdot] \{p_1, p_2, p_4, p_5, p_6\} \\
& \text{Def. } \underline{\underline{\langle \cdot \cdot \rangle, [\cdot \cdot]}} \quad \{p_1, p_2, p_5, p_6\} \cup \{p_1, p_2, p_3, p_4, p_5, p_6\} \\
& \text{Def. } \underline{\underline{\cup}} \quad \{p_1, p_2, p_3, p_4, p_5, p_6\} \\
& = \quad \text{Proc}
\end{array}$$

\Rightarrow F gilt in allen Zuständen des LTS!

Aufgabe 2

Aufgabe 3

3 a)

$$X_{I1} \stackrel{\max}{=} \langle a \rangle X_R \wedge \langle b \rangle X_G \wedge \langle a \rangle X_W \wedge [a] (X_R \vee X_W) \wedge [b] X_G \wedge [c] \text{ff}$$

$$X_R \stackrel{\max}{=} \langle b \rangle X_W \wedge \langle c \rangle X_T \wedge \langle c \rangle X_{I1} \wedge [c] (X_T \vee X_{I1}) \wedge [b] X_W \wedge [a] \text{ff}$$

$$X_W \stackrel{\max}{=} [a] \text{ff} \wedge [b] \text{ff} \wedge [c] \text{ff}$$

$$X_S \stackrel{\max}{=} \langle c \rangle X_{I1} \wedge [c] X_{I1} \wedge [a] \text{ff} \wedge [b] \text{ff}$$

$$X_D \stackrel{\max}{=} \langle c \rangle X_{I1} \wedge [c] X_{I1} \wedge [a] \text{ff} \wedge [b] \text{ff}$$

$$X_{I2} \stackrel{\max}{=} \langle a \rangle X_T \wedge \langle b \rangle X_S \wedge [a] X_T \wedge [b] X_S \wedge [c] \text{ff}$$

$$X_N \stackrel{\max}{=} \langle a \rangle X_U \wedge \langle a \rangle X_G \wedge \langle b \rangle X_D \wedge [a] (X_U \vee X_G) \wedge [b] X_D \wedge [c] \text{ff}$$

$$X_T \stackrel{\max}{=} \langle b \rangle X_U \wedge [b] X_U \wedge [a] \text{ff} \wedge [c] \text{ff}$$

$$X_G \stackrel{\max}{=} \langle b \rangle X_U \wedge [b] X_U \wedge [a] \text{ff} \wedge [c] \text{ff}$$

$$X_U \stackrel{\max}{=} \langle b \rangle X_U \wedge [b] X_U \wedge [a] \text{ff} \wedge [c] \text{ff}$$

3 b)

$$\{ W \}$$

$$\{ I1 \}$$

$$\{ R \}$$

$$\{ D, S \}$$

$$\{ I2, N \}$$

$$\{ G, U, T \}$$

3 c)

Wir sind gut

Aufgabe 4

Aufgabe 4 a)

$$F = Inv(\langle oeffnen \rangle \#)$$

also $F = X$ mit:

$$X \stackrel{\text{max}}{=} \langle oeffnen \rangle \# \wedge [Act] X$$

Aufgabe 4 b)

$$F = Even(\langle beenden \rangle \#)$$

also $F = X$ mit:

$$X \stackrel{\text{min}}{=} \langle beenden \rangle \# \vee (\langle Act \rangle \# \wedge [Act] X)$$

Aufgabe 4 c)

$$F = Pos(\langle fahren \rangle \#) U^S [oeffnen] \#$$

also $F = X$ mit:

$$X \stackrel{\text{min}}{=} [oeffnen] \# \vee (Y \wedge \langle Act \rangle \# \wedge [Act] X)$$

$$Y \stackrel{\text{min}}{=} \langle fahren \rangle \# \vee \langle Act \rangle Y$$