Yanjie Zhang



Summary

Research Interest

GIScience, GeoAI, Crowdsourced Map, Autonomous Driving, Smart City

Highlight

Cross-disciplinary academic background: Transportation Engineering & Geographic Informatics

Relevant Courses

Advanced Mathematics, Intelligent Transportation System, Travel Behavior Analysis, Transportation Planning and Design, Data Mining, Spatial Programming, Geospatial Statistics and Visualization

Education

2025 - Current	PhD Researcher at National University of Singapore
2021 - 2024	Master's Degree at Tongji University
2017 - 2021	Bachelor's Degree at Nanjing Agriculture University

Projects

HD maps dynamic and long-term updating methods and interaction mechanism

The National Key R&D Program of China leading by **Prof. Wei Huang** (Nov 2021 - May 2024) Based on the **High Definition (HD) map** model proposed in this project, my research focuses on studying the primary components of **dynamic information** within HD maps and their exchange formats. I aim to propose an information interaction approach that is applicable to the interaction between connected vehicles and HD maps.

Solving vehicle routing problems based on deep reinforcement learning

Undergraduate Thesis Research Plan advised by **Assoc. Prof. Yang Liu** (Sep 2020 - May 2021) Utilizing an existing trained **deep learning** model, we aim to address the **route planning problem** by determining optimal delivery paths for vehicles with capacity constraints. Our goal is to find an approximate optimal solution that minimizes the total route distance.

Publications

Ying, S., Wang, R., Huang, W., **Zhang, Y.**, Gu, J., & Jiang, Y. (2025). Framework of updating and interaction for high-definition maps with vehicle-road-cloud context. *International Journal of Digital Earth.* 18(2).

Zhang, Y., Huang, W., Liu, X, Zhang, F, Wu, H., Ying, S., Liu, C. (2024). An Approach for High Definition (HD) Maps Information Interaction for Autonomous Driving. *Geometrics and Information Science of Wuhan University*. 49(4): 662-671.

Liu, C., Huang, W., **Zhang, Y.**, et al. (2024). Dynamic Data Interaction Patterns and Contents of High Definition Maps for Autonomous Driving. *Chinese Society for Geodesy Photogrammetry and Cartography*.

Conference Proceedings

Zhang, Y., Huang, W. (2023). An Approach of High Definition Map Information Interaction. *Int. Arch. Photogramm. Remote Sens. Spatial Inf. Sci.*, XLVIII-1/W2-2023, 861–866.

Conference Presentations

An Approach of High Definition Map Information Interaction. The ISPRS Geospatial Week 2023, Sep 2-7, 2023, Cairo, Egypt

Services

Teaching Assistant GE2215 Introduction to GIS, Fall 2025, National University of Singapore.

Teaching Assistant Advanced Research and Practice Course, Fall 2024, Tongji University.

Teaching Assistant Introduction to Major (Engineering), Fall 2023, Tongji University.

Skills

Programming Python, SQL, Matlab

Frameworks ArcGIS Pro, QGIS, Git, RoadRunner

English IELTS 7, GRE 320

Hobbies

Jogging, Ping Pong, Snorkeling & Reading

Last updated: September 9, 2025