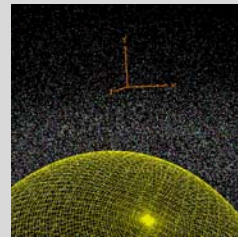


# OpenCL / OpenGL Vertex Buffer Interoperability: A Particle System Case Study

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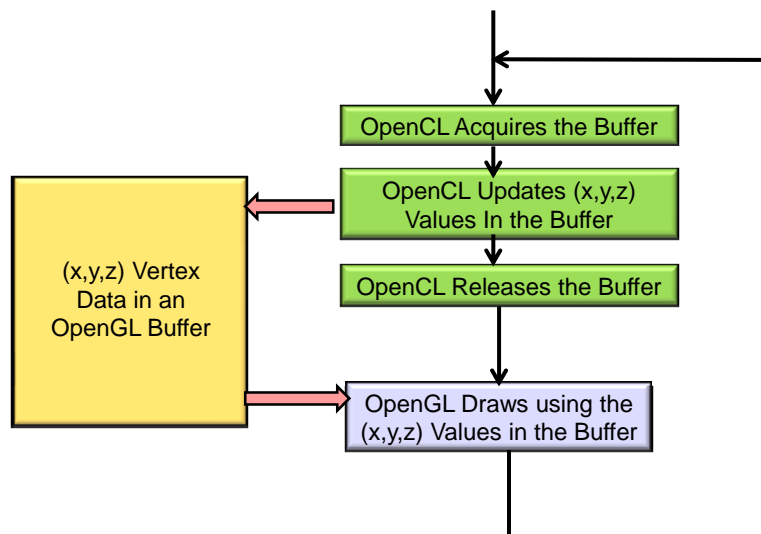


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opengl.opengl.vbo.pptx

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## OpenCL / OpenGL Vertex Interoperability: The Basic Idea



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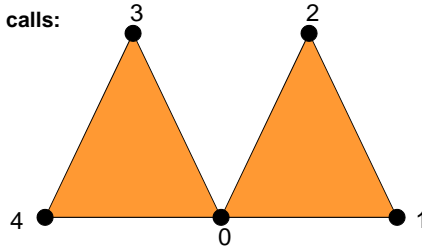
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## In the Beginning of OpenGL ...

You listed the vertices with separate function calls:

```
glBegin( GL_TRIANGLES );
    glVertex3f( x0, y0, z0 );
    glVertex3f( x1, y1, z1 );
    glVertex3f( x2, y2, z2 );

    glVertex3f( x0, y0, z0 );
    glVertex3f( x3, y3, z3 );
    glVertex3f( x4, y4, z4 );
glEnd( );
```



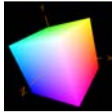
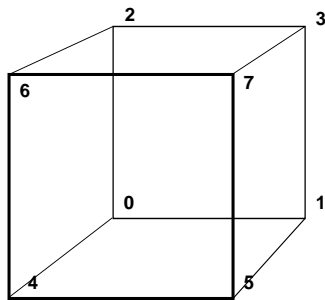
Then someone noticed how inefficient that was.



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## Here's What OpenGL Has Been Moving To: Vertex Arrays



```
GLfloat CubeVertices[ ][3] =
{
    { -1., -1., -1. },
    { 1., -1., -1. },
    { -1., 1., -1. },
    { 1., 1., -1. },
    { -1., -1., 1. },
    { 1., -1., 1. },
    { -1., 1., 1. },
    { 1., 1., 1. }
};
```

```
GLfloat CubeColors[ ][3] =
{
    { 0., 0., 0. },
    { 1., 0., 0. },
    { 0., 1., 0. },
    { 1., 1., 0. },
    { 0., 0., 1. },
    { 1., 0., 1. },
    { 0., 1., 1. },
    { 1., 1., 1. }
};
```

```
GLuint CubeIndices[ ][4] =
{
    { 0, 2, 3, 1 },
    { 4, 5, 7, 6 },
    { 1, 3, 7, 5 },
    { 0, 4, 6, 2 },
    { 2, 6, 7, 3 },
    { 0, 1, 5, 4 }
};
```

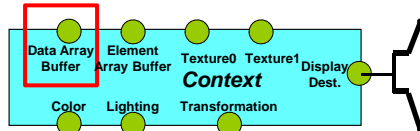


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## A Little Background -- the OpenGL *Rendering Context*

The OpenGL Rendering Context contains all the characteristic information necessary to produce an image from geometry. This includes transformations, colors, lighting, textures, where to send the display, etc.



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## More Background -- What is an OpenGL "Object"?

An OpenGL Object is pretty much the same as a C++, C#, or Java object: it encapsulates a group of data items and allows you to treat them as a unified whole. For example, a Vertex Buffer Object *could* be defined in C++ by:

```
class VertexBufferObject
{
    enum dataType;
    void *memStart;
    int memSize;
};
```

Then, you could create any number of Vertex Buffer Object instances, each with its own characteristics encapsulated within it. When you want to make that combination current, you just need to bring in ("**bind**") that entire object into the Context. When you bind an object, all of its information comes with it.



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## More Background – How do you Create an OpenGL “Object”?

In C++, objects are pointed to by their address.

In OpenGL, objects are pointed to by an unsigned integer handle. You can assign a value for this handle yourself (not recommended), or have OpenGL generate one for you that is guaranteed to be unique. For example:

```
GLuint buf;  
glGenBuffers( 1, &buf );
```

This doesn't actually allocate memory for the buffer object yet, it just acquires a unique handle. To allocate memory, you need to bind this handle to the Context.



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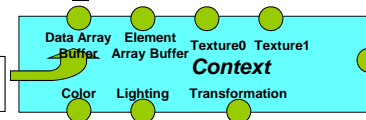
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## More Background -- “Binding” to the Context

The OpenGL term “binding” refers to “attaching” or “docking” (a metaphor which I find to be more visually pleasing) an OpenGL object to the Context. You can then assign characteristics, and they will “flow” through the Context into the object.

```
glBindBuffer( buf, GL_ARRAY_BUFFER );  
glBufferData( GL_ARRAY_BUFFER, numBytes, data, usage );
```

Vertex Buffer Object

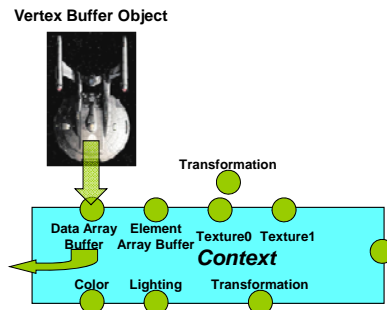


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## More Background -- “Binding” to the Context

When you want to *use* that Vertex Buffer Object, just bind it again. All of the characteristics will then be active, just as if you had specified them again.



```
glBindBuffer( buf, GL_ARRAY_BUFFER );
```



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## Vertex Buffers: Putting Data in the Buffer Object

```
glBufferData( type, numBytes, data, usage );
```

*type* is the type of buffer object this is:

GL\_ARRAY\_BUFFER to store floating point vertices, normals, colors, and texture coordinates

GL\_ELEMENT\_ARRAY\_BUFFER to store integer vertex indices to connect for drawing

*numBytes* is the number of bytes to store in all. Not the number of numbers, but the number of *bytes*!

*data* is the memory address of (i.e., pointer to) the data to be transferred to the graphics card. This can be NULL, and the data can be transferred later.



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## Vertex Buffers: Putting Data in the Buffer Object

```
glBufferData( type, numbytes, data, usage );
```

*usage* is a hint as to how the data will be used: GL\_XXX\_YYY

where XXX can be:

STREAM	this buffer will be written lots
STATIC	this buffer will be written seldom and read seldom
DYNAMIC	this buffer will be written often and used often

and YYY can be:

DRAW	this buffer will be used for drawing
READ	this buffer will be copied into
COPY	not a real need for now, but someday...



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## Vertex Buffers: Step #1 - Fill the Arrays

```
GLfloat Vertices[ ][3] =  
{  
    { 1., 2., 3. },  
    { 4., 5., 6. },  
    ...  
};  
  
int numVertices = sizeof(Vertices) / ( 3*sizeof(GLfloat) );
```



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## Vertex Buffers: Step #2 – Create the Buffers and Fill Them

```
glGenBuffers( 1, &buf );  
  
glBindBuffer( buf, GL_ARRAY_BUFFER );  
glBufferData( GL_ARRAY_BUFFER, 3*sizeof(GLfloat)*numVertices, Vertices, GL_STATIC_DRAW );
```



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## Vertex Buffers: Step #3 – Activate the Array Types That You Will Use

**glEnableClientState( type )**

where *type* can be any of:

```
GL_VERTEX_ARRAY  
GL_COLOR_ARRAY  
GL_NORMAL_ARRAY  
GL_SECONDARY_COLOR_ARRAY  
GL_TEXTURE_COORD_ARRAY
```

- Call this as many times as you need to enable all the arrays that you will need.
- There are other types, too.
- To deactivate a type, call:

**glDisableClientState( type )**



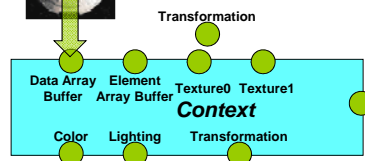
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## Vertex Buffers: Step #4 – To Draw, First Bind the Buffers

```
glBindBuffer( buf, GL_ARRAY_BUFFER );
```

Vertex Buffer Object



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## Vertex Buffers: Step #5 – Specify the Data

```
glVertexPointer( size, type, stride, rel_address);
glColorPointer( size, type, stride, rel_address);
glNormalPointer( type, stride, rel_address);
glSecondaryColorPointer( size, type, stride, rel_address);
glTexCoordPointer( size, type, stride, rel_address);
```

*size* is the spatial dimension, and can be: 2, 3, or 4

*type* can be:

```
GL_SHORT
GL_INT
GL_FLOAT
GL_DOUBLE
```

*stride* is the byte offset between consecutive entries in the array (0 means tightly packed)

*rel\_address*, the 4<sup>th</sup> argument, is the relative byte address from the start of the buffer where the first element of this part of the data lives. Most of the time you use *(void \*)0*

Vertex Data

Color Data

vs.

Vertex Data

Color Data

Vertex Data

Color Data

Vertex Data

Color Data



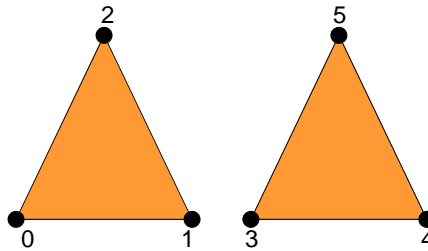
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## Vertex Buffers: Step #6 – Specify the Connections

```
GLfloat Vertices[ ][3] =  
{  
    { x0, y0, z0 },  
    { x1, y1, z1 },  
    { x2, y2, z2 },  
    { x3, y3, z3 },  
    { x4, y4, z4 },  
    { x5, y5, z5 }  
};
```



```
int numVertices = sizeof(Vertices) / ( 3*sizeof(GLfloat) );
```

```
glDrawArrays( GL_TRIANGLES, 0, numVertices );
```



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## Vertex Buffers: Writing Data Directly into a Vertex Buffer

Map the buffer from GPU memory into the memory space of the application:

```
glBindBuffer( buf, GL_ARRAY_BUFFER );  
glBufferData( GL_ARRAY_BUFFER, 3*sizeof(float)*numVertices, NULL, GL_STATIC_DRAW );  
  
float * vertexArray = glMapBuffer( GL_ARRAY_BUFFER, usage );
```

*usage* is an indication how the data will be used:

GL_READ_ONLY	the vertex data will be read from, but not written to
GL_WRITE_ONLY	the vertex data will be written to, but not read from
GL_READ_WRITE	the vertex data will be read from <i>and</i> written to

You can now use *vertexArray[ ]* like any other floating-point array.

When you are done, be sure to call:

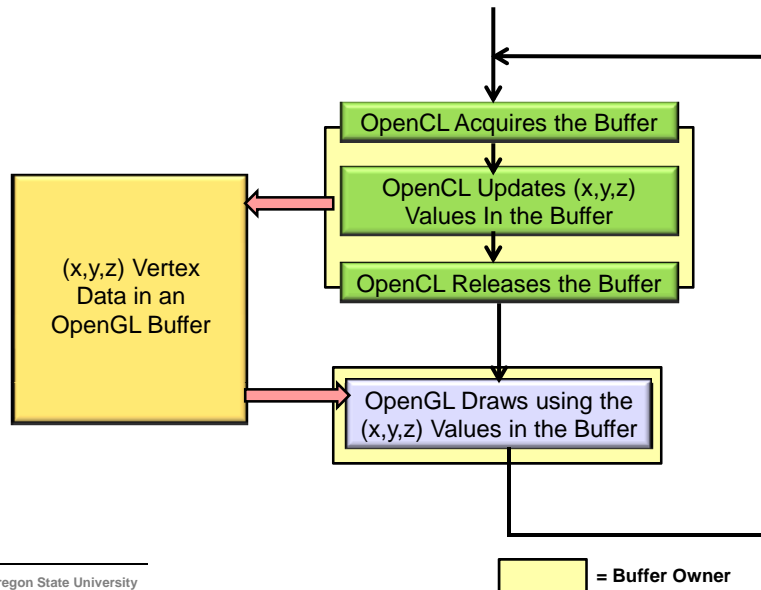
```
glUnmapBuffer( GL_ARRAY_BUFFER );
```



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**Either OpenGL or OpenCL Can Use the Vertex Buffer at a Time, but not Both:  
All of this Happens on the GPU**



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## 1. Program Header

```

#include <stdio.h>
#define _USE_MATH_DEFINES
#include <math.h>
#include <string.h>
#include <stdlib.h>
#include <ctype.h>
#include <omp.h>

#ifdef WIN32
#include <windows.h>
#endif

#ifdef WIN32
#include "glew.h"
#endif

#include <GL/gl.h>
#include <GL/glu.h>
#include "glut.h"
#include "glui.h"

#include "CL/cl.h"
#include "CL/cl_gl.h"

```



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## Structures We Will Use to Fill the Vertex Buffers

```
// structs we will need later:
```

```
struct xyzw
{
    float x, y, z, w;
};
```

```
struct rgba
{
    float r, g, b, a;
};
```



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## OpenCL Global Variables

```
size_t GlobalWorkSize[3] = { NUM_PARTICLES, 1, 1 };
size_t LocalWorkSize[3] = { LOCAL_SIZE, 1, 1 };
```

```
gluint          hPobj; // host opengl object
gluint          hCobj; // host opengl object
struct xyzw *    hVel; // host c array
cl_mem          dPobj; // device memory buffer
cl_mem          dCobj; // device memory buffer
cl_mem          dVel;  // device memory buffer
```

```
cl_command_queue CmdQueue;
cl_device_id     Device;
cl_kernel        Kernel;
cl_platform_id   Platform;
cl_program       Program;
```



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## A Deceptively-Simple Main Program

```
int
main( int argc, char *argv[ ] )
{
    glutInit( &argc, argv );
    InitGraphics( );
    InitLists( );
    InitCL( );
    Reset( );
    InitGlui( );
    glutMainLoop( );
    return 0;
}
```



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## GLEW – the GL Extension Wrangler

```
#ifdef WIN32
    GLenum err = glewInit( );
    if( err != GLEW_OK )
    {
        fprintf( stderr, "glewInit Error\n" );
    }
#endif
```

This *must* wait to be called until after a graphics window is open !



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## Setting up OpenCL: Querying the Existence of an OpenCL Extension

```
void
InitCL( )
{
    ...

    status = clGetDeviceIDs( Platform, CL_DEVICE_TYPE_GPU, 1, &Device, NULL );
    PrintCLError( status, "clGetDeviceIDs: " );

    // since this is an opengl interoperability program,
    // check if the opengl sharing extension is supported
    // (no point going on if it isn't):
    // (we need the Device in order to ask, so we can't do it any sooner than right here)

    if( !isCLExtensionSupported( "cl_khr_gl_sharing" ) )
    {
        fprintf( stderr, "cl_khr_gl_sharing is supported.\n" );
    }
    else
    {
        fprintf( stderr, "cl_khr_gl_sharing is not supported -- sorry.\n" );
        return;
    }
}
```



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## Querying the Existence of an OpenCL Extension

```
bool
isCLExtensionSupported( const char *extension )
{
    // see if the extension is bogus:

    if( extension == NULL || extension[0] == '\0' )
        return false;

    char * where = (char *) strchr( extension, ' ' );
    if( where != NULL )
        return false;

    // get the full list of extensions:

    size_t extensionSize;
    clGetDeviceInfo( Device, CL_DEVICE_EXTENSIONS, 0, NULL, &extensionSize );
    char *extensions = new char [ extensionSize ];
    clGetDeviceInfo( Device, CL_DEVICE_EXTENSIONS, extensionSize, extensions, NULL );

    for( char * start = extensions ; ; )
    {
        where = (char *) strstr( (const char *) start, extension );
        if( where == 0 )
        {
            delete [] extensions;
            return false;
        }

        char * terminator = where + strlen(extension); // points to what should be the separator

        if( *terminator == ' ' || *terminator == '\0' || *terminator == '\r' || *terminator == '\n' )
        {
            delete [] extensions;
            return true;
        }
        start = terminator;
    }
}
```



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## Setting up OpenCL: The Interoperability Context

```
void
InitCL()
{
    ...

    // get the platform id:
    status = clGetPlatformIDs( 1, &Platform, NULL );
    PrintCLError( status, "clGetPlatformIDs: " );

    // get the device id:
    status = clGetDeviceIDs( Platform, CL_DEVICE_TYPE_GPU, 1, &Device, NULL );
    PrintCLError( status, "clGetDeviceIDs: " );

    // 3. create a special opencl context based on the opengl context:
    cl_context_properties props[ ] =
    {
        CL_GL_CONTEXT_KHR,          (cl_context_properties) wglGetCurrentContext( ),
        CL_WGL_HDC_KHR,            (cl_context_properties) wglGetCurrentDC( ),
        CL_CONTEXT_PLATFORM,       (cl_context_properties) Platform,
        0
    };

    cl_context Context = clCreateContext( props, 1, &Device, NULL, NULL, &status );
    PrintCLError( status, "clCreateContext: " );
}
```



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## Setting up OpenCL: The Interoperability Context is Different for each OS (oh good...)

```
For Windows:
cl_context_properties props[ ] =
{
    CL_GL_CONTEXT_KHR,          (cl_context_properties) wglGetCurrentContext( ),
    CL_WGL_HDC_KHR,            (cl_context_properties) wglGetCurrentDC( ),
    CL_CONTEXT_PLATFORM,       (cl_context_properties) Platform,
    0
};
cl_context Context = clCreateContext( props, 1, &Device, NULL, NULL, &status );

For Linux:
cl_context_properties props[ ] =
{
    CL_GL_CONTEXT_KHR,          (cl_context_properties) glXGetCurrentContext( ),
    CL_GLX_DISPLAY_KHR,        (cl_context_properties) glXGetCurrentDisplay( ),
    CL_CONTEXT_PLATFORM,       (cl_context_properties) Platform,
    0
};
cl_context Context = clCreateContext( props, 1, &Device, NULL, NULL, &status );

For Apple:
cl_context_properties props[ ] =
{
    CL_CONTEXT_PROPERTY_USE_CGL_SHAREGROUP_APPLE,
    (cl_context_properties) kCGLShareGroup,
    0
};
cl_context Context = clCreateContext( props, 0, 0, NULL, NULL, &status );
```



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## Setting up OpenCL

```
void
InitCL( )
{
    ...

    // create the velocity array and the opengl vertex array buffer and color array buffer:

    delete [ ] hVel;
    hVel = new struct xyzw [ NUM_PARTICLES ];

    glGenBuffers( 1, &hPobj );
    glBindBuffer( GL_ARRAY_BUFFER, hPobj );
    glBufferData( GL_ARRAY_BUFFER, 4 * NUM_PARTICLES * sizeof(float), NULL, GL_STATIC_DRAW );

    glGenBuffers( 1, &hCobj );
    glBindBuffer( GL_ARRAY_BUFFER, hCobj );
    glBufferData( GL_ARRAY_BUFFER, 4 * NUM_PARTICLES * sizeof(float), NULL, GL_STATIC_DRAW );

    glBindBuffer( GL_ARRAY_BUFFER, 0 );    // unbind the buffer

    // fill those arrays and buffers:

    ResetParticles( );
}
```

“hPobj” stands for “host Points object”



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## Setting the Initial Particle Parameters

```
void
ResetParticles( )
{
    glBindBuffer( GL_ARRAY_BUFFER, hPobj );
    struct xyzw *points = (struct xyzw *) glMapBuffer( GL_ARRAY_BUFFER, GL_WRITE_ONLY );
    for( int i = 0; i < NUM_PARTICLES; i++ )
    {
        points[ i ].x = Ranf( XMIN, XMAX );
        points[ i ].y = Ranf( YMIN, YMAX );
        points[ i ].z = Ranf( ZMIN, ZMAX );
        points[ i ].w = 1.;
    }
    glUnmapBuffer( GL_ARRAY_BUFFER );

    glBindBuffer( GL_ARRAY_BUFFER, hCobj );
    struct rgba *colors = (struct rgba *) glMapBuffer( GL_ARRAY_BUFFER, GL_WRITE_ONLY );
    for( int i = 0; i < NUM_PARTICLES; i++ )
    {
        colors[ i ].r = Ranf( 0., 1. );
        colors[ i ].g = Ranf( 0., 1. );
        colors[ i ].b = Ranf( 0., 1. );
        colors[ i ].a = 1.;
    }
    glUnmapBuffer( GL_ARRAY_BUFFER );

    ...
}
```



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## Setting the Initial Particle Parameters

```
void
ResetParticles( )
{
    ...

    delete [ ] hVel;
    hVel = new struct xyzw [ NUM_PARTICLES ];
    for( int i = 0; i < NUM_PARTICLES; i++ )
    {
        hVel[ i ].x = Ranf( VMIN, VMAX );
        hVel[ i ].y = Ranf( 0. , VMAX );
        hVel[ i ].z = Ranf( VMIN, VMAX );
        hVel[ i ].w = 0.;
    }
}
```



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## Setting-up the Device-Side Buffers

```
void
InitCL( )
{
    ...

    // 5. create the opencl version of the velocity array:
    dVel = clCreateBuffer( Context, CL_MEM_READ_WRITE, 4*sizeof(float)*NUM_PARTICLES, NULL, &status );
    PrintCLError( status, "clCreateBuffer: " );

    // 6. write the data from the host buffers to the device buffers:
    status = clEnqueueWriteBuffer( CmdQueue, dVel, CL_FALSE, 0, 4*sizeof(float)*NUM_PARTICLES, hVel, 0, NULL, NULL );
    PrintCLError( status, "clEnqueueWriteBuffer: " );

    // 5. create the opencl version of the opengl buffers:
    dPobj = clCreateFromGLBuffer( Context, 0, hPobj, &status );
    PrintCLError( status, "clCreateFromGLBuffer (1)" );

    dCobj = clCreateFromGLBuffer( Context, 0, hCobj, &status );
    PrintCLError( status, "clCreateFromGLBuffer (2)" );
}
```



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## Setup the Kernel Arguments...

```
void
InitCL( )
{
    ...

    // 10. setup the arguments to the Kernel object:

    status = clSetKernelArg( Kernel, 0, sizeof(cl_mem), &dPobj );
    PrintCLError( status, "clSetKernelArg (1): " );

    status = clSetKernelArg( Kernel, 1, sizeof(cl_mem), &dVel );
    PrintCLError( status, "clSetKernelArg (2): " );

    status = clSetKernelArg( Kernel, 2, sizeof(cl_mem), &dCobj );
    PrintCLError( status, "clSetKernelArg (3): " );
}
```

## ... to Match the Kernel's Parameter List

```
kernel
void
Particle( global point * dPobj, global vector * dVel, global color * dCobj )
{
    ...
}
```



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## The "Idle Function" Tells OpenGL to Do Its Computing

```
void
Animate( )
{
    // acquire the vertex buffers from opengl:

    glutSetWindow( MainWindow );
    glFinish( );

    cl_int status = clEnqueueAcquireGLObjects( CmdQueue, 1, &dPobj, 0, NULL, NULL );
    PrintCLError( status, "clEnqueueAcquireGLObjects (1): " );
    status = clEnqueueAcquireGLObjects( CmdQueue, 1, &dCobj, 0, NULL, NULL );
    PrintCLError( status, "clEnqueueAcquireGLObjects (2): " );

    double time0 = omp_get_wtime( );

    // 11. enqueue the Kernel object for execution:

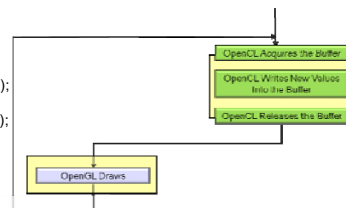
    cl_event wait;
    status = clEnqueueNDRangeKernel( CmdQueue, Kernel, 1, NULL, GlobalWorkSize, LocalWorkSize, 0, NULL, &wait );
    PrintCLError( status, "clEnqueueNDRangeKernel: " );

    status = clWaitForEvents( 1, &wait );
    PrintCLError( status, "clWaitForEvents: " );

    double time1 = omp_get_wtime( );
    ElapsedTime = time1 - time0;

    clFinish( CmdQueue );
    clEnqueueReleaseGLObjects( CmdQueue, 1, &dCobj, 0, NULL, NULL );
    PrintCLError( status, "clEnqueueReleaseGLObjects (1): " );
    clEnqueueReleaseGLObjects( CmdQueue, 1, &dPobj, 0, NULL, NULL );
    PrintCLError( status, "clEnqueueReleaseGLObject (2): " );

    glutSetWindow( MainWindow );
    glutPostRedisplay( );
}
```



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## Redrawing the Scene: The Particles

```
void
Display( )
{
    ...

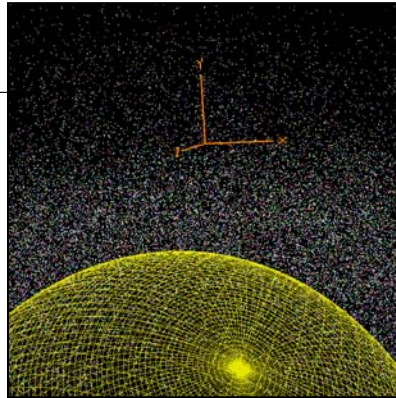
    glBindBuffer( GL_ARRAY_BUFFER, hPobj );
    glVertexPointer( 4, GL_FLOAT, 0, (void *)0 );
    glEnableClientState( GL_VERTEX_ARRAY );

    glBindBuffer( GL_ARRAY_BUFFER, hCobj );
    glColorPointer( 4, GL_FLOAT, 0, (void *)0 );
    glEnableClientState( GL_COLOR_ARRAY );

    glPointSize( 2. );
    glDrawArrays( GL_POINTS, 0, NUM_PARTICLES );
    glPointSize( 1. );

    glDisableClientState( GL_VERTEX_ARRAY );
    glDisableClientState( GL_COLOR_ARRAY );
    glBindBuffer( GL_ARRAY_BUFFER, 0 );

    glutSwapBuffers( );
    glFlush( );
}
```



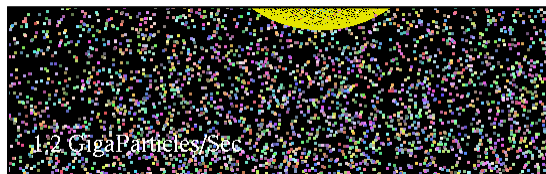
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## Redraw the Scene: The Performance

```
void
Display( )
{
    ...

    if( ShowPerformance )
    {
        char str[128];
        sprintf( str, "%6.1f GigaParticles/Sec", (float)NUM_PARTICLES/ElapsedTime/1000000000. );
        glDisable( GL_DEPTH_TEST );
        glMatrixMode( GL_PROJECTION );
        glLoadIdentity( );
        gluOrtho2D( 0., 100., 0., 100. );
        glMatrixMode( GL_MODELVIEW );
        glLoadIdentity( );
        glColor3f( 1., 1., 1. );
        DoRasterString( 5., 5., 0., str );
    }
}
```



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### 13. Clean-up

```
void
Quit( )
{
    Glui->close( );
    glutSetWindow( MainWindow );
    glFinish( );
    glutDestroyWindow( MainWindow );

    // 13. clean everything up:

    clReleaseKernel(      Kernel );
    clReleaseProgram(     Program );
    clReleaseCommandQueue( CmdQueue );
    clReleaseMemObject(   dPobj );
    clReleaseMemObject(   dCobj );

    exit( 0 );
}
```



### particles.cl

```
kernel
void
Particle( global point * dPobj, global vector * dVel, global color * dCobj )
{
    int gid = get_global_id( 0 );          // particle #

    point p = dPobj[gid];
    vector v = dVel[gid];

    point pp = p + v*DT + .5*DT*DT*G;      // p'
    vector vp = v + G*DT;                  // v'
    pp.w = 1.;
    vp.w = 0.;

    if( !IsInsideSphere( pp, Sphere1 ) )
    {
        vp = BounceSphere( p, v, Sphere1 );
        pp = p + vp*DT + .5*DT*DT*G;
    }

    dPobj[gid] = pp;
    dVel[gid] = vp;
}
```



## particles.cl

```
typedef float4 point;
typedef float4 vector;
typedef float4 color;
typedef float4 sphere;

constant float4 G      = (float4) ( 0., -9.8, 0., 0. );
constant float  DT      = 0.1;
constant sphere Sphere1 = (sphere)( -100., -800., 0., 600. );
```

```
bool
IsInsideSphere( point p, sphere s )
{
    float r = fast_length( p.xyz - s.xyz );
    return ( r < s.w );
}
```



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## particles.cl

```
vector
Bounce( vector in, vector n )
{
    n.w = 0.;
    n = normalize( n );
    vector out = in - 2. * n * dot( in.xyz, n.xyz );
    out.w = 0.;
    return out;
}
```

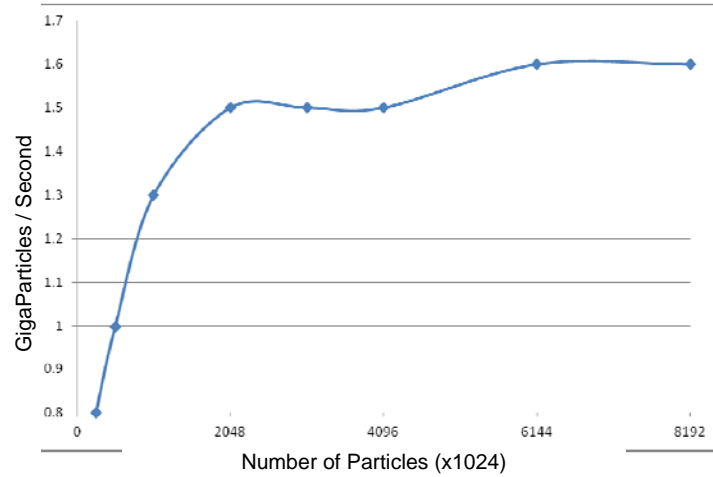
```
vector
BounceSphere( point p, vector v, sphere s )
{
    vector n;
    n.xyz = fast_normalize( p.xyz - s.xyz );
    n.w = 0.;
    return Bounce( in, n );
}
```



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### Joe Parallel's Performance



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