view_frames Result

Recorded at time: 1649626294.489

base_link

Broadcaster: /robot_state_publisher
Average rate: 10.221 Hz
Most recent transform: 1649626294.446 (0.043 sec old)
Buffer length: 4.892 sec

link_1

Broadcaster: /robot_state_publisher
Average rate: 10.221 Hz
Most recent transform: 1649626294.446 (0.043 sec old)
Buffer length: 4.892 sec

link_2

Broadcaster: /robot_state_publisher
Average rate: 10.221 Hz
Most recent transform: 1649626294.446 (0.043 sec old)
Buffer length: 4.892 sec

link_3

Broadcaster: /robot_state_publisher
Average rate: 10.221 Hz
Most recent transform: 1649626294.446 (0.043 sec old)
Buffer length: 4.892 sec

link_4

Broadcaster: /robot_state_publisher
Average rate: 10.221 Hz
Most recent transform: 1649626294.446 (0.043 sec old)
Buffer length: 4.892 sec

link_5

Broadcaster: /robot_state_publisher
Average rate: 10.221 Hz
Most recent transform: 1649626294.446 (0.043 sec old)
Buffer length: 4.892 sec

link_6

Broadcaster: /robot_state_publisher
Average rate: 10.221 Hz
Most recent transform: 1649626294.446 (0.043 sec old)
Buffer length: 4.892 sec

end_effector