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Relevant Literature
Sophocles J. Orfanidis: "Electromagnetic Waves and Antennas";
www.ece.rutgers.edu/~orfanidis/eva

Linear two-port (and multi-port) networks are characterized by a number of equivalent circuit parameters, such as their transfer matrix, impedance matrix, admittance matrix, and scattering matrix. Fig. 12.1.1 shows a typical two-port network.

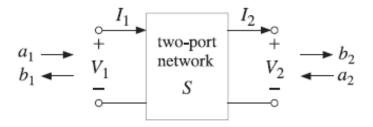


Fig. 12.1.1 Two-port network.

The transfer matrix, also known as the ABCD matrix, relates the voltage and current at port 1 to those at port 2, whereas the impedance matrix relates the two voltages V1, V2 to the two currents I1, I2:

$$\begin{bmatrix} V_1 \\ I_1 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} V_2 \\ I_2 \end{bmatrix}$$
 (transfer matrix) 
$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} \begin{bmatrix} I_1 \\ -I_2 \end{bmatrix}$$
 (impedance matrix) (12.1.1)

Thus, the transfer and impedance matrices are the  $2\times2$  matrices:

$$T = \begin{bmatrix} A & B \\ C & D \end{bmatrix}, \qquad Z = \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix}$$
 (12.1.2)

The admittance matrix is simply the inverse of the impedance matrix,  $Y = Z^{-1}$ .

The scattering matrix relates the outgoing waves  $b_1$ ,  $b_2$  to the incoming waves  $a_1$ ,  $a_2$  that are incident on the two-port:

$$\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}, \quad S = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} \quad \text{(scattering matrix)} \quad (12.1.3)$$

The matrix elements  $S_{11}$ ,  $S_{12}$ ,  $S_{21}$ ,  $S_{22}$  are referred to as the *scattering parameters* or the S-parameters. The parameters  $S_{11}$ ,  $S_{22}$  have the meaning of reflection coefficients, and  $S_{21}$ ,  $S_{12}$ , the meaning of transmission coefficients.

The traveling wave variables a1, b1 at port 1 and a2, b2 at port 2 are defined in terms of  $V_1$ ,  $I_1$  and  $V_2$ ,  $I_2$  and a real-valued positive reference impedance  $Z_0$  as follows:

$$a_1 = \frac{V_1 + Z_0 I_1}{2\sqrt{Z_0}}$$
$$b_1 = \frac{V_1 - Z_0 I_1}{2\sqrt{Z_0}}$$

$$\begin{vmatrix} a_1 = \frac{V_1 + Z_0 I_1}{2\sqrt{Z_0}} \\ b_1 = \frac{V_1 - Z_0 I_1}{2\sqrt{Z_0}} \end{vmatrix} \qquad a_2 = \frac{V_2 - Z_0 I_2}{2\sqrt{Z_0}}$$
 (traveling waves) 
$$b_2 = \frac{V_2 + Z_0 I_2}{2\sqrt{Z_0}}$$

The definitions at port 2 appear different from those at port 1, but they are really the same if expressed in terms of the incoming current  $-I_2$ :

$$a_2 = \frac{V_2 - Z_0 I_2}{2\sqrt{Z_0}} = \frac{V_2 + Z_0 (-I_2)}{2\sqrt{Z_0}}$$

$$b_2 = \frac{V_2 + Z_0 I_2}{2\sqrt{Z_0}} = \frac{V_2 - Z_0 (-I_2)}{2\sqrt{Z_0}}$$

The term traveling waves is justified below. Eqs. (12.1.4) may be inverted to express the voltages and currents in terms of the wave variables:

$$V_{1} = \sqrt{Z_{0}}(a_{1} + b_{1})$$

$$V_{2} = \sqrt{Z_{0}}(a_{2} + b_{2})$$

$$I_{1} = \frac{1}{\sqrt{Z_{0}}}(a_{1} - b_{1})$$

$$I_{2} = \frac{1}{\sqrt{Z_{0}}}(b_{2} - a_{2})$$
(12.1.5)

In practice, the reference impedance is chosen to be Z0 = 50 ohm. At lower frequencies the transfer and impedance matrices are commonly used, but at microwave frequencies they become difficult to measure and therefore, the scattering matrix description is preferred. The S-parameters can be measured by embedding the two-port network (the device under test, or, DUT) in a transmission line whose ends are connected to a network analyzer. Fig. 12.1.2 shows the experimental setup.

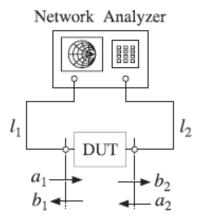


Fig. 12.1.2 Device under test connected to network analyzer.

Fig. 12.1.3 shows more details of the connection. The generator and load impedances are configured by the network analyzer. The connections can be reversed, with the generator connected to port 2 and the load to port 1.

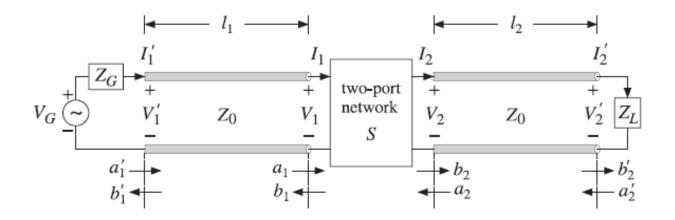


Fig. 12.1.3 Two-port network under test.

The two line segments of lengths  $l_1$ ,  $l_2$  are assumed to have characteristic impedance equal to the reference impedance  $Z_0$ . Then, the wave variables  $a_1$ ,  $b_1$  and  $a_2$ ,  $b_2$  are recognized as normalized versions of forward and backward traveling waves.

We have:

$$a_{1} = \frac{V_{1} + Z_{0}I_{1}}{2\sqrt{Z_{0}}} = \frac{1}{\sqrt{Z_{0}}}V_{1+} \qquad a_{2} = \frac{V_{2} - Z_{0}I_{2}}{2\sqrt{Z_{0}}} = \frac{1}{\sqrt{Z_{0}}}V_{2-}$$

$$b_{1} = \frac{V_{1} - Z_{0}I_{1}}{2\sqrt{Z_{0}}} = \frac{1}{\sqrt{Z_{0}}}V_{1-} \qquad b_{2} = \frac{V_{2} + Z_{0}I_{2}}{2\sqrt{Z_{0}}} = \frac{1}{\sqrt{Z_{0}}}V_{2+}$$

$$(12.1.6)$$

Thus,  $a_1$  is essentially the incident wave at port 1 and  $b_1$  the corresponding reflected wave. Similarly,  $a_2$  is incident from the right onto port 2 and  $b_2$  is the reflected wave from port 2.

The network analyzer measures the waves  $a_1$ ',  $b_1$ ' and  $a_2$ ',  $b_2$ ' at the generator and load ends of the line segments, as shown in Fig. 12.1.3. From these, the waves at the inputs of the two-port can be determined.

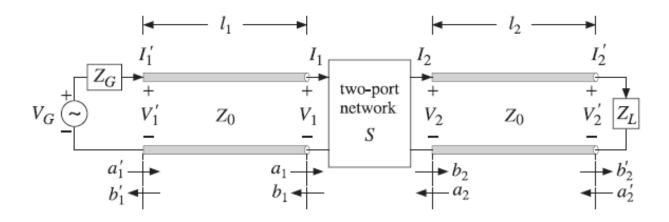


Fig. 12.1.3 Two-port network under test.

$$\begin{bmatrix} V_{1+} \\ V_{1-} \end{bmatrix} = \begin{bmatrix} e^{j\beta l} & 0 \\ 0 & e^{-j\beta l} \end{bmatrix} \begin{bmatrix} V_{2+} \\ V_{2-} \end{bmatrix}$$
 (propagation matrix) (9.7.7)

Assuming lossless segments and using the propagation matrices 9.7.7 shown above, we have:

$$\begin{bmatrix} a_1 \\ b_1 \end{bmatrix} = \begin{bmatrix} e^{-j\delta_1} & 0 \\ 0 & e^{j\delta_1} \end{bmatrix} \begin{bmatrix} a'_1 \\ b'_1 \end{bmatrix}, \quad \begin{bmatrix} a_2 \\ b_2 \end{bmatrix} = \begin{bmatrix} e^{-j\delta_2} & 0 \\ 0 & e^{j\delta_2} \end{bmatrix} \begin{bmatrix} a'_2 \\ b'_2 \end{bmatrix}$$
(12.1.7)

where  $\delta_1 = \beta l_l$  and  $\delta_2 = \beta l_2$  are the phase lengths of the segments. Eqs. (12.1.7) can be rearranged into the forms:

$$\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = D \begin{bmatrix} b'_1 \\ b'_2 \end{bmatrix}, \quad \begin{bmatrix} a'_1 \\ a'_2 \end{bmatrix} = D \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}, \quad D = \begin{bmatrix} e^{j\delta_1} & 0 \\ 0 & e^{j\delta_2} \end{bmatrix}$$

The network analyzer measures the corresponding S-parameters of the primed variables, that is,

$$\begin{bmatrix} b'_1 \\ b'_2 \end{bmatrix} = \begin{bmatrix} S'_{11} & S'_{12} \\ S'_{21} & S'_{22} \end{bmatrix} \begin{bmatrix} a'_1 \\ a'_2 \end{bmatrix}, \quad S' = \begin{bmatrix} S'_{11} & S'_{12} \\ S'_{21} & S'_{22} \end{bmatrix} \quad \text{(measured S-matrix)} \quad (12.1.8)$$

The S-matrix of the two-port can be obtained then from:

$$\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = D \begin{bmatrix} b'_1 \\ b'_2 \end{bmatrix} = DS' \begin{bmatrix} a'_1 \\ a'_2 \end{bmatrix} = DS'D \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} \implies S = DS'D$$

or, more explicitly,

$$\begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} = \begin{bmatrix} e^{j\delta_1} & 0 \\ 0 & e^{j\delta_2} \end{bmatrix} \begin{bmatrix} S'_{11} & S'_{12} \\ S'_{21} & S'_{22} \end{bmatrix} \begin{bmatrix} e^{j\delta_1} & 0 \\ 0 & e^{j\delta_2} \end{bmatrix}$$

$$= \begin{bmatrix} S'_{11}e^{2j\delta_1} & S'_{12}e^{j(\delta_1+\delta_2)} \\ S'_{21}e^{j(\delta_1+\delta_2)} & S'_{22}e^{2j\delta_2} \end{bmatrix}$$
(12.1.9)

Thus, changing the points along the transmission lines at which the S-parameters are measured introduces only phase changes in the parameters.

Without loss of generality, we may replace the extended circuit of Fig. 12.1.3 with the one shown in Fig. 12.1.4 with the understanding that either we are using the extended two-port parameters S, or, equivalently, the generator and segment  $l_1$  have been replaced

by their Thevenin equivalents, and the load impedance has been replaced by its propagated version to distance ½.

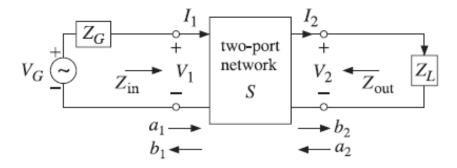


Fig. 12.1.4 Two-port network connected to generator and load.

The actual measurements of the *S*-parameters are made by connecting to a matched load,  $Z_L = Z_0$ . Then, there will be no reflected waves from the load,  $a_2 = 0$ , and the *S*-matrix equations will give:

$$b_1 = S_{11}a_1 + S_{12}a_2 = S_{11}a_1 \Rightarrow S_{11} = \frac{b_1}{a_1}\Big|_{Z_L = Z_0} = \text{reflection coefficient}$$
  
 $b_2 = S_{21}a_1 + S_{22}a_2 = S_{21}a_1 \Rightarrow S_{21} = \frac{b_2}{a_1}\Big|_{Z_L = Z_0} = \text{transmission coefficient}$ 

Reversing the roles of the generator and load, one can measure in the same way the parameters  $S_{12}$  and  $S_{22}$ .

#### Power Flow

Power flow into and out of the two-port is expressed very simply in terms of the traveling wave amplitudes. Using the inverse relationships (12.1.5), we find:

$$\frac{1}{2}\operatorname{Re}[V_1^*I_1] = \frac{1}{2}|a_1|^2 - \frac{1}{2}|b_1|^2 
-\frac{1}{2}\operatorname{Re}[V_2^*I_2] = \frac{1}{2}|a_2|^2 - \frac{1}{2}|b_2|^2$$
(12.2.1)

The left-hand sides represent the power flow *into* ports 1 and 2. The right-hand sides represent the difference between the power incident on a port and the power reflected from it. The quantity  $\text{Re}[V_2^*I_2]/2$  represents the power transferred to the load.

Another way of phrasing these is to say that part of the incident power on a port gets reflected and part enters the port:

$$\frac{1}{2}|a_1|^2 = \frac{1}{2}|b_1|^2 + \frac{1}{2}\operatorname{Re}[V_1^*I_1]$$

$$\frac{1}{2}|a_2|^2 = \frac{1}{2}|b_2|^2 + \frac{1}{2}\operatorname{Re}[V_2^*(-I_2)]$$
(12.2.2)

### Power Flow

One of the reasons for normalizing the traveling wave amplitudes by  $\sqrt{Z_0}$  in the definitions (12.1.4) was precisely this simple way of expressing the incident and reflected powers from a port.

If the two-port is lossy, the power lost in it will be the difference between the power entering port 1 and the power leaving port 2, that is,

$$P_{\text{loss}} = \frac{1}{2} \operatorname{Re}[V_1^* I_1] - \frac{1}{2} \operatorname{Re}[V_2^* I_2] = \frac{1}{2} |a_1|^2 + \frac{1}{2} |a_2|^2 - \frac{1}{2} |b_1|^2 - \frac{1}{2} |b_2|^2$$

Noting that  $\mathbf{a}^{\dagger}\mathbf{a} = |a_1|^2 + |a_2|^2$  and  $\mathbf{b}^{\dagger}\mathbf{b} = |b_1|^2 + |b_2|^2$ , and writing  $\mathbf{b}^{\dagger}\mathbf{b} = \mathbf{a}^{\dagger}S^{\dagger}S\mathbf{a}$ , we may express this relationship in terms of the scattering matrix:

$$P_{\text{loss}} = \frac{1}{2} \mathbf{a}^{\dagger} \mathbf{a} - \frac{1}{2} \mathbf{b}^{\dagger} \mathbf{b} = \frac{1}{2} \mathbf{a}^{\dagger} \mathbf{a} - \frac{1}{2} \mathbf{a}^{\dagger} S^{\dagger} S \mathbf{a} = \frac{1}{2} \mathbf{a}^{\dagger} (I - S^{\dagger} S) \mathbf{a}$$
(12.2.3)

For a lossy two-port, the power loss is positive, which implies that the matrix  $I - S^{\dagger}S$  must be positive definite. If the two-port is lossless,  $P_{loss} = 0$ , the S-matrix will be *unitary*, that is,  $S^{\dagger}S = I$ .

It is straightforward to derive the relationships that allow one to pass from one parameter set to another. For example, starting with the transfer matrix, we have:

$$V_{1} = AV_{2} + BI_{2}$$

$$I_{1} = CV_{2} + DI_{2}$$

$$V_{2} = \frac{1}{C}I_{1} - \frac{D}{C}I_{2}$$

$$V_{3} = \frac{A}{C}I_{1} - \frac{AD - BC}{C}I_{2}$$

$$V_{4} = A(\frac{1}{C}I_{1} - \frac{D}{C}I_{2}) + BI_{2} = \frac{A}{C}I_{1} - \frac{AD - BC}{C}I_{2}$$

The coefficients of  $I_1$ ,  $I_2$  are the impedance matrix elements. The steps are reversible, and we summarize the final relationships below:

$$Z = \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} = \frac{1}{C} \begin{bmatrix} A & AD - BC \\ 1 & D \end{bmatrix}$$

$$T = \begin{bmatrix} A & B \\ C & D \end{bmatrix} = \frac{1}{Z_{21}} \begin{bmatrix} Z_{11} & Z_{11}Z_{22} - Z_{12}Z_{21} \\ 1 & Z_{22} \end{bmatrix}$$
(12.3.1)

We note the determinants det(T) = AD - BC and  $det(Z) = Z_{11}Z_{22} - Z_{12}Z_{21}$ . The relationship between the scattering and impedance matrices is also straightforward to derive. We define the  $2\times1$  vectors:

$$V = \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}, \quad I = \begin{bmatrix} I_1 \\ -I_2 \end{bmatrix}, \quad \mathbf{a} = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$
 (12.3.2)

Then, the definitions (12.1.4) can be written compactly as:

The bold I is a matrix. The cursive I is unit matrix.

$$\mathbf{a} = \frac{1}{2\sqrt{Z_0}} (V + Z_0 \mathbf{I}) = \frac{1}{2\sqrt{Z_0}} (Z + Z_0 \mathbf{I}) \mathbf{I}$$

$$\mathbf{b} = \frac{1}{2\sqrt{Z_0}} (V - Z_0 \mathbf{I}) = \frac{1}{2\sqrt{Z_0}} (Z - Z_0 \mathbf{I}) \mathbf{I}$$
(12.3.3)

where we used the impedance matrix relationship V = ZI and defined the 2×2 unit matrix I.

It follows then,

$$\frac{1}{2\sqrt{Z_0}}I = (Z + Z_0I)^{-1}\mathbf{a} \quad \Rightarrow \quad \mathbf{b} = \frac{1}{2\sqrt{Z_0}}(Z - Z_0I)I = (Z - Z_0I)(Z + Z_0I)^{-1}\mathbf{a}$$

Thus, the scattering matrix S will be related to the impedance matrix Z by

$$S = (Z - Z_0 I) (Z + Z_0 I)^{-1} \Leftrightarrow Z = (I - S)^{-1} (I + S) Z_0$$
(12.3.4)

Explicitly, we have:

$$S = \begin{bmatrix} Z_{11} - Z_0 & Z_{12} \\ Z_{21} & Z_{22} - Z_0 \end{bmatrix} \begin{bmatrix} Z_{11} + Z_0 & Z_{12} \\ Z_{21} & Z_{22} + Z_0 \end{bmatrix}^{-1}$$
$$= \begin{bmatrix} Z_{11} - Z_0 & Z_{12} \\ Z_{21} & Z_{22} - Z_0 \end{bmatrix} \frac{1}{D_Z} \begin{bmatrix} Z_{22} + Z_0 & -Z_{12} \\ -Z_{21} & Z_{11} + Z_0 \end{bmatrix}$$

where  $D_Z = \det(Z + Z_0 I) = (Z_{11} + Z_0)(Z_{22} + Z_0) - Z_{12}Z_{21}$ . Multiplying the matrix factors, we obtain:

$$S = \frac{1}{D_z} \begin{bmatrix} (Z_{11} - Z_0) (Z_{22} + Z_0) - Z_{12} Z_{21} & 2Z_{12} Z_0 \\ 2Z_{21} Z_0 & (Z_{11} + Z_0) (Z_{22} - Z_0) - Z_{12} Z_{21} \end{bmatrix}$$
(12.3.5)

Similarly, the inverse relationship gives:

$$Z = \frac{Z_0}{D_s} \begin{bmatrix} (1+S_{11})(1-S_{22}) + S_{12}S_{21} & 2S_{12} \\ 2S_{21} & (1-S_{11})(1+S_{22}) + S_{12}S_{21} \end{bmatrix}$$
(12.3.6)

where  $D_s = \det(I - S) = (1 - S_{11})(1 - S_{22}) - S_{12}S_{21}$ . Expressing the impedance parameters in terms of the transfer matrix parameters, we also find:

$$S = \frac{1}{Da} \begin{bmatrix} A + \frac{B}{Z_0} - CZ_0 - D & 2(AD - BC) \\ 2 & -A + \frac{B}{Z_0} - CZ_0 + D \end{bmatrix}$$
(12.3.7)

where  $D_a = A + \frac{B}{Z_0} + CZ_0 + D$ .

This is the connection between S and the transfer matrix.

When the two-port is connected to a generator and load as in Fig. 12.1.4, the impedance and scattering matrix equations take the simpler forms:

$$V_1 = Z_{\text{in}} I_1$$

$$V_2 = Z_L I_2$$

$$\Leftrightarrow b_1 = \Gamma_{\text{in}} a_1$$

$$a_2 = \Gamma_L b_2$$
(12.4.1)

where  $Z_{in}$  is the input impedance at port 1, and  $\Gamma_{in}$ ,  $\Gamma_L$  are the reflection coefficients at port 1 and at the load:

$$\Gamma_{\rm in} = \frac{Z_{\rm in} - Z_0}{Z_{\rm in} + Z_0}, \quad \Gamma_L = \frac{Z_L - Z_0}{Z_L + Z_0}$$
 (12.4.2)

The input impedance and input reflection coefficient can be expressed in terms of the Z- and S-parameters, as follows:

$$Z_{\text{in}} = Z_{11} - \frac{Z_{12}Z_{21}}{Z_{22} + Z_L} \Leftrightarrow \Gamma_{\text{in}} = S_{11} + \frac{S_{12}S_{21}\Gamma_L}{1 - S_{22}\Gamma_L}$$
 (12.4.3)

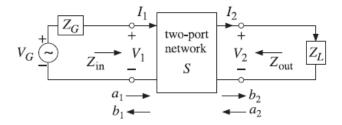


Fig. 12.1.4 Two-port network connected to generator and load.

The equivalence of these two expressions can be shown by using the parameter conversion formulas of Eqs. (12.3.5) and (12.3.6), or they can be shown indirectly, as follows. Starting with  $V_2 = Z_L I_2$  and using the second impedance matrix equation, we can solve for  $I_2$  in terms of  $I_1$ :

$$V_2 = Z_{21}I_1 - Z_{22}I_2 = Z_LI_2 \Rightarrow I_2 = \frac{Z_{21}}{Z_{22} + Z_L}I_1$$
 (12.4.4)

Then, the first impedance matrix equation implies:

$$V_1 = Z_{11}I_1 - Z_{12}I_2 = \left(Z_{11} - \frac{Z_{12}Z_{21}}{Z_{22} + Z_L}\right)I_1 = Z_{\text{in}}I_1$$

Starting again with  $V_2 = Z_L I_2$  we find for the traveling waves at port 2:

$$a_2 = \frac{V_2 - Z_0 I_2}{2\sqrt{Z_0}} = \frac{Z_L - Z_0}{2\sqrt{Z_0}} I_2$$

$$b_2 = \frac{V_2 + Z_0 I_2}{2\sqrt{Z_0}} = \frac{Z_L + Z_0}{2\sqrt{Z_0}} I_2$$

$$\Rightarrow a_2 = \frac{Z_L - Z_0}{Z_L + Z_0} b_2 = \Gamma_L b_2$$

Using  $V_1 = Z_{in}I_1$ , a similar argument implies for the waves at port 1:

$$a_{1} = \frac{V_{1} + Z_{0}I_{1}}{2\sqrt{Z_{0}}} = \frac{Z_{\text{in}} + Z_{0}}{2\sqrt{Z_{0}}}I_{1}$$

$$b_{1} = \frac{V_{1} - Z_{0}I_{1}}{2\sqrt{Z_{0}}} = \frac{Z_{\text{in}} - Z_{0}}{2\sqrt{Z_{0}}}I_{1}$$

$$\Rightarrow b_{1} = \frac{Z_{\text{in}} - Z_{0}}{Z_{\text{in}} + Z_{0}}a_{1} = \Gamma_{\text{in}}a_{1}$$

It follows then from the scattering matrix equations that:

$$b_2 = S_{21}a_1 + S_{22}a_2 = S_{22}a_1 + S_{22}\Gamma_L b_2 \quad \Rightarrow \quad b_2 = \frac{S_{21}}{1 - S_{22}\Gamma_L} a_1$$
 (12.4.5)

which implies for  $b_1$ :

$$b_1 = S_{11}a_1 + S_{12}a_2 = S_{11}a_1 + S_{12}\Gamma_L b_2 = \left(S_{11} + \frac{S_{12}S_{21}\Gamma_L}{1 - S_{22}\Gamma_L}\right)a_1 = \Gamma_{\text{in}}a_1$$

Reversing the roles of generator and load, we obtain the impedance and reflection coefficients from the output side of the two-port:

$$Z_{\text{out}} = Z_{22} - \frac{Z_{12}Z_{21}}{Z_{11} + Z_G} \iff \Gamma_{\text{out}} = S_{22} + \frac{S_{12}S_{21}\Gamma_G}{1 - S_{11}\Gamma_G}$$
 (12.4.6)

where

$$\Gamma_{\text{out}} = \frac{Z_{\text{out}} - Z_0}{Z_{\text{out}} + Z_0}, \quad \Gamma_G = \frac{Z_G - Z_0}{Z_G + Z_0}$$
 (12.4.7)

The input and output impedances allow one to replace the original two-port circuit of Fig. 12.1.4 by simpler equivalent circuits. For example, the two-port and the load can be replaced by the input impedance  $Z_{in}$  connected at port 1, as shown in Fig. 12.4.1.

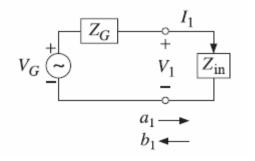


Fig. 12.4.1 Input equivalent circuit

Similarly, the generator and the two-port can be replaced by a Thévenin equivalent circuit connected at port 2. By determining the open-circuit voltage and short-circuit current at port 2, we find the corresponding Thévenin parameters in terms of the impedance parameters:

$$V_{\text{th}} = \frac{Z_{21}V_G}{Z_{11} + Z_G}, \quad Z_{\text{th}} = Z_{\text{out}} = Z_{22} - \frac{Z_{12}Z_{21}}{Z_{11} + Z_G}$$
 (12.4.8)

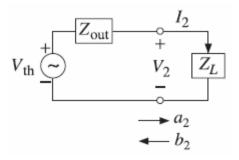


Fig. 12.4.1 output equivalent circuit