

University of Liège

Homework 3

Applied digital signal processing

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Noise filtering

We have a noisy signal

$$x_{\rm ns}[n] = x[n] + v[n]$$

where

$$x[n] = \cos(20\pi t) + 0.5\cos(40\pi t + 1.4) + 0.8\cos(120\pi t + 0.7)$$

and v[n] is an arbitrary noise.

Signals $x_{\rm ns}[n]$ and x[n] are sampled at 1000 Hz.

The goal is to design a filter to remove the noise from $x_{ns}[n]$ without distortion.

Question a

We plot signals x[n] and $x_{ns}[n]$ in the same axis (figure 1).

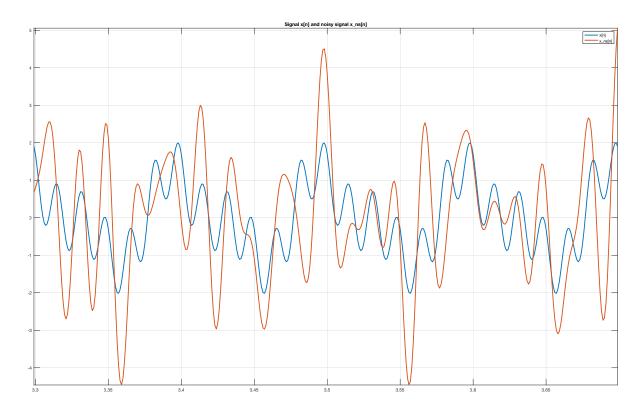


Figure 1 – Signals x[n] and $x_{ns}[n]$ in the same axis.

Question b

We plot the single-sided amplitude spectrum of the noisy signal $x_{\rm ns}[n]$ (figure 2).

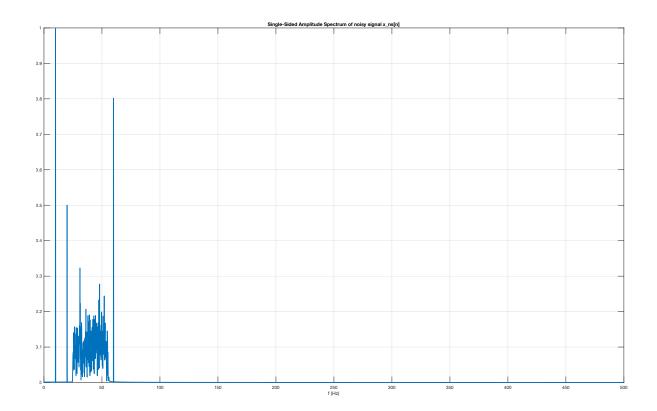


Figure 2 – Single-sided amplitude spectrum of the noisy signal $x_{ns}[n]$.

Question c

Thanks to the figure 2 and a piece of code, we determined that the approximate frequency range of the noise v[n] is [24, 56] [Hz].

Question d

As we want to preserve the shape of the signal, we have to design an FIR filter.

Thanks to Matlab, we can create such a filter easily. Properties of the created filter are presented at figure 3.

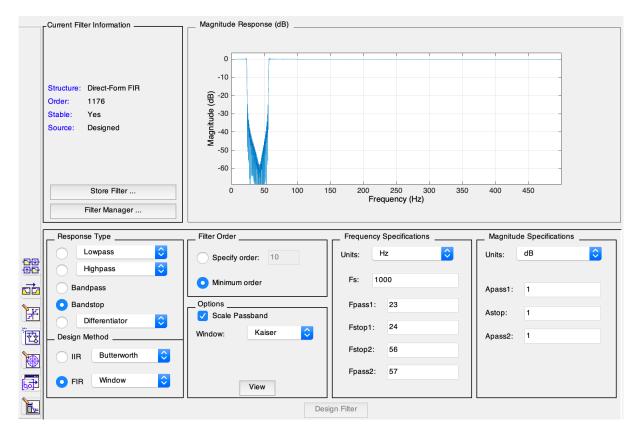


Figure 3 – Design of the FIR filter.

So, we choose a FIR filter in the options. We set F_s to $1000\,\mathrm{Hz}$, and F_{stop1} and F_{stop2} respectively to 24 and 56 Hz. We also set A_{stop} to 1 dB.

Question e

After applying the filter on the noisy signal, we plot the single-sided amplitude spectrum of the filtered signal $x_{\text{filt}}[n]$ (figure 4).

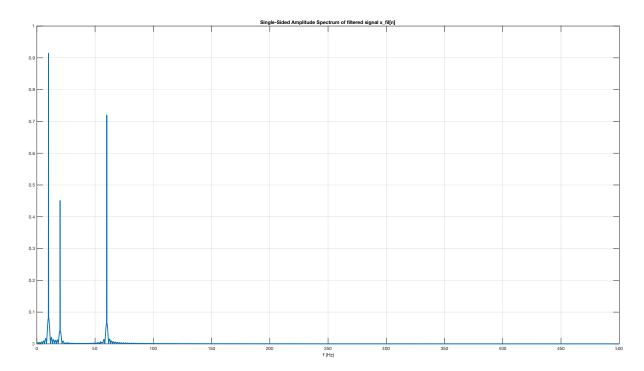


Figure 4 – Single-sided amplitude spectrum of the filtered signal $x_{\rm filt}[n]$.

We clearly see that the noise in the frequency range [24, 56] [Hz] has been attenuated.

Question f

Finally, we plot signals x[n] and $x_{\rm fil}[n]$ in the same axis to check the result of our FIR filter (figure 5).

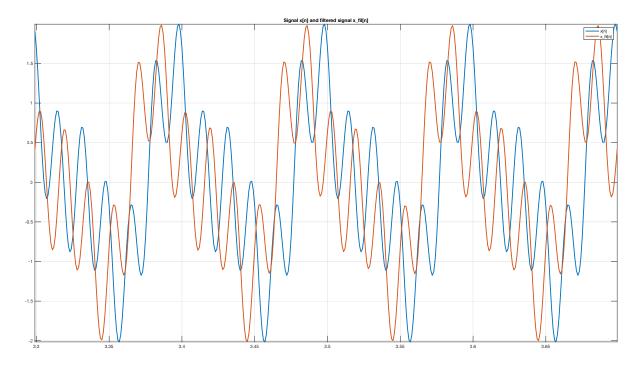


Figure 5 – Signals x[n] and $x_{\rm fil}[n]$ in the same axis.

We can observe that the signal $x_{\rm fil}[n]$ is exactly the same than the original signal x[n] (no distortion occurred because FIR filter has linear phase response).

Matlab code

```
1 %% Applied digital signal processing — Homework 3
 3 % Question 1 — Noise filtering
 5 % University of Liege
 6 % Academic year 2018-2019
 8 % Authors:
   % - Quentin Graillet
10 % — Maxime Meurisse
11 % - Adrien Schoffeniels
12
13 %% Load
14
15 load('hw3_noisy_signal.mat');
16
17 %% Data
18
19 Fs = 1000; % sampling period
20 Ts = 1 / Fs; % sampling interval
21 N = length(x); % length of the signal
22 Tmax = (N - 1) * Ts; % maximum time
23 t = 0:Ts:Tmax; % time vector
24
25 %% Subquestion a)
26
27 plot_range = ((N / 2 - 200):(N / 2 + 200));
28
29 figure
30 plot(t(plot_range), x(plot_range), 'LineWidth', 2);
31 hold on
32 plot(t(plot_range), x_ns(plot_range), 'LineWidth', 2);
33 axis tight
34 title('Signal x[n] and noisy signal x\_ns[n]');
35 legend('x[n]', 'x\_ns[n]');
36 grid on
37
38 %% Subquestion b)
39
40 X = fft(x_ns);
41 X2 = abs(X / N);
42 X1 = X2(1:N/2 + 1);
43 X1(2:end - 1) = 2 * X1(2:end - 1);
44
45 F = Fs * (0:(N / 2)) / N;
46
47 figure
48 plot(F, X1, 'LineWidth', 2);
49 title('Single-Sided Amplitude Spectrum of noisy signal x\_ns[n]');
50 xlabel('f (Hz)');
51 grid on
52
53 %% Subquestion c)
```

```
54
55 fr = find((X1 >= 0.1) & (X1 <= 0.4));
57 fprintf('Approximate frequency range of the noise v[n] : [%f - %f]
      Hz \setminus n', F(fr(1)), F(fr(end));
58
59 %% Subquestion e)
60
61 load('fir.mat');
62 fvtool(fir);
63
64 x_clean_FIR = filter(fir, x_ns);
65
66 X = fft(x_clean_FIR);
67 X2 = abs(X / N);
68 X1 = X2(1:N/2 + 1);
69 X1(2:end - 1) = 2 * X1(2:end - 1);
70 F = Fs * (0:(N / 2)) / N;
71
72 figure
73 plot(F, X1, 'LineWidth', 2);
74 title('Single-Sided Amplitude Spectrum of filtered signal x\_fil[n]');
75 xlabel('f (Hz)');
76 grid on
77
78 %% Subquestion f)
79
80 figure
81 plot(t(plot_range), x(plot_range), 'LineWidth', 2);
82 hold on
83 plot(t(plot_range), x_clean_FIR(plot_range), 'LineWidth', 2);
84 axis tight
85 title('Signal x[n] and filtered signal x \in [n]');
86 legend('x[n]', 'x\_fil[n]');
87 grid on
88
89 %% Cleaning workspace
90
91 clearvars
```