

Adaptive Algorithms for Automatic Link Selection in Multiple Access with Link Failures

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Outline

1 Introduction

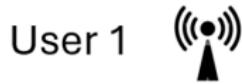
2 Our Contribution

3 Algorithm

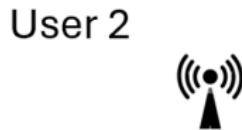
4 Results

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System Model



Channel 1



Channel 2

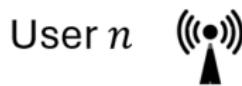
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Channel m

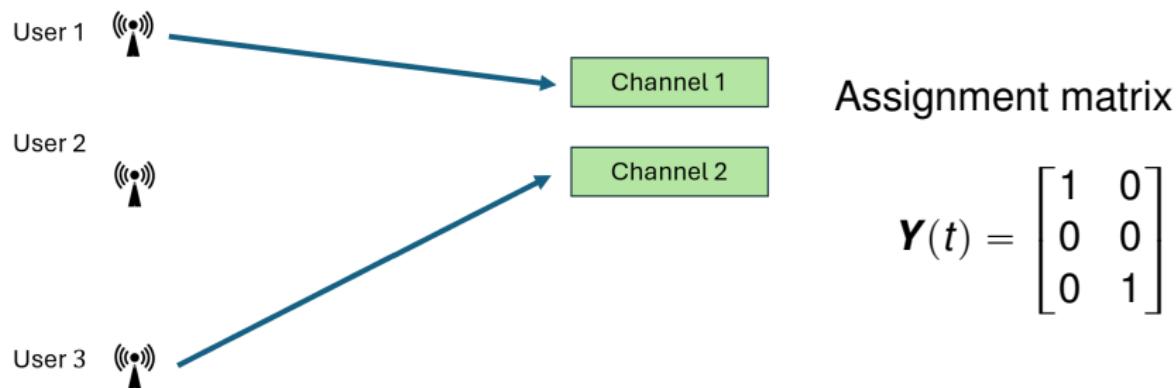


Centralized
Controller

Link Selection

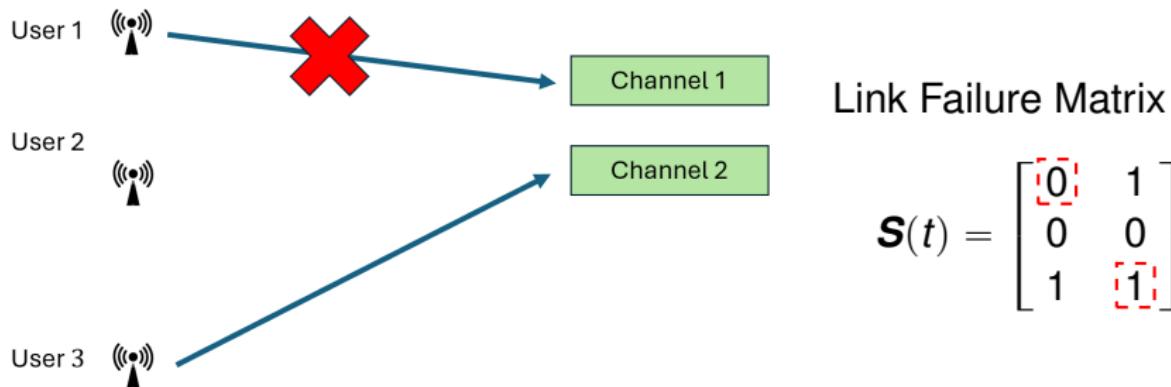
In each slot, the controller assigns the users to channels

- Each user is assigned to at most one channel
- Each channel is assigned to at most one user.



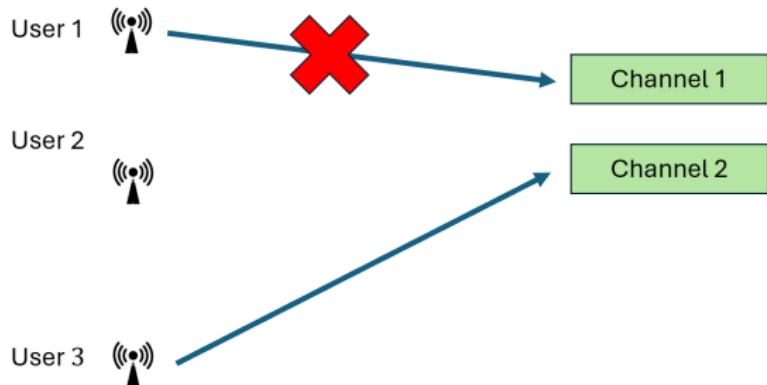
Link Failures

- 1 After assignment, link (i, j) fails with probability $1 - q_{i,j}$
- 2 $q_{i,j}$ have to be estimated using bandit feedback



Throughput Vector

- 1 Throughput vector $\mathbf{X}(t) \in \{0, 1\}^n$.



$$\mathbf{X}(t) = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

Maximizing System Throughput

Time horizon - T

$$\text{maximize} \sum_{i=1}^n \frac{1}{T} \sum_{t=1}^T X_i(t)$$

Pros: Widely analyzed

Cons: Unfair for some users

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	Channel 1	Channel 2
User 1	0.7	0.7
User 2	0.3	0.2
User 3	0.6	0.4

Figure: Example $q_{i,j}$ values

Network Utility Maximization

$$\text{Maximize } \phi \left(\underbrace{\left[\frac{1}{T} \sum_{t=1}^T X_1(t), \frac{1}{T} \sum_{t=1}^T X_2(t), \dots, \frac{1}{T} \sum_{t=1}^T X_n(t) \right]}_{\text{Time-average throughput vector}} \right)$$

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Assumptions

- ① Concave
- ② Entrywise nondecreasing
- ③ Bounded subgradients $|\phi_i'(\mathbf{x})| \leq B$.

Utility Functions

Examples

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- ③ $\phi(\mathbf{x}) = \sum_{i=1}^n \log(1 + \beta x_i).$

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- ③ $\phi(\mathbf{x}) = \sum_{i=1}^n \log(1 + \beta x_i).$
- ④ $\phi(\mathbf{x}) = w_1 \min\{x_1, x_2, \dots, x_n\} + w_2 \sum_{i=1}^n \log(1 + \beta x_i).$

Known $q_{i,j}$ Values

- 1 Sample $\mathbf{Y}(t) \sim \mathbf{P}^*$ in each time slot, where \mathbf{P}^* is doubly stochastic.

Known $q_{i,j}$ Values

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- ② How to find \mathbf{P}^*

Maximize: $\phi \left(\sum_{j=1}^m P_{1,j} q_{1,j}, \sum_{j=1}^m P_{2,j} q_{2,j}, \dots, \sum_{j=1}^m P_{n,j} q_{n,j} \right)$

s.t. \mathbf{P} is doubly stochastic

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s.t. \mathbf{P} is doubly stochastic

- ③ Optimal value ϕ^{opt}

Our Goal

- Can we get close to ϕ^{opt} when $q_{i,j}$ are **unknown**.

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Finite Time Bounds

$$\phi^{\text{opt}} - \phi \left(\frac{1}{T} \sum_{t=1}^T \mathbb{E}\{\mathbf{X}(t)\} \right) \leq g(T),$$

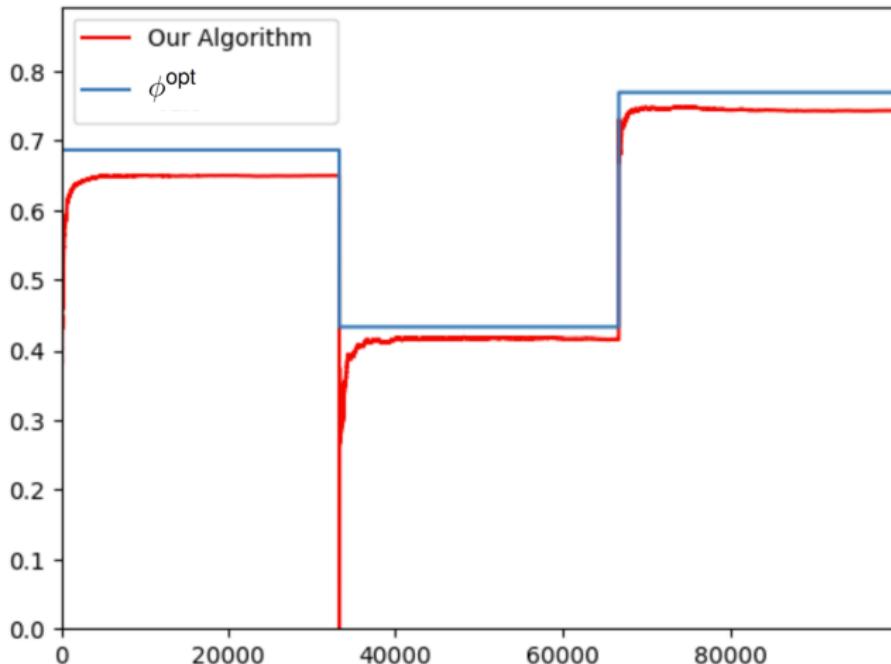
such that $g(x) \rightarrow 0$ as $x \rightarrow \infty$.

Prior Work on Single-Channel Case

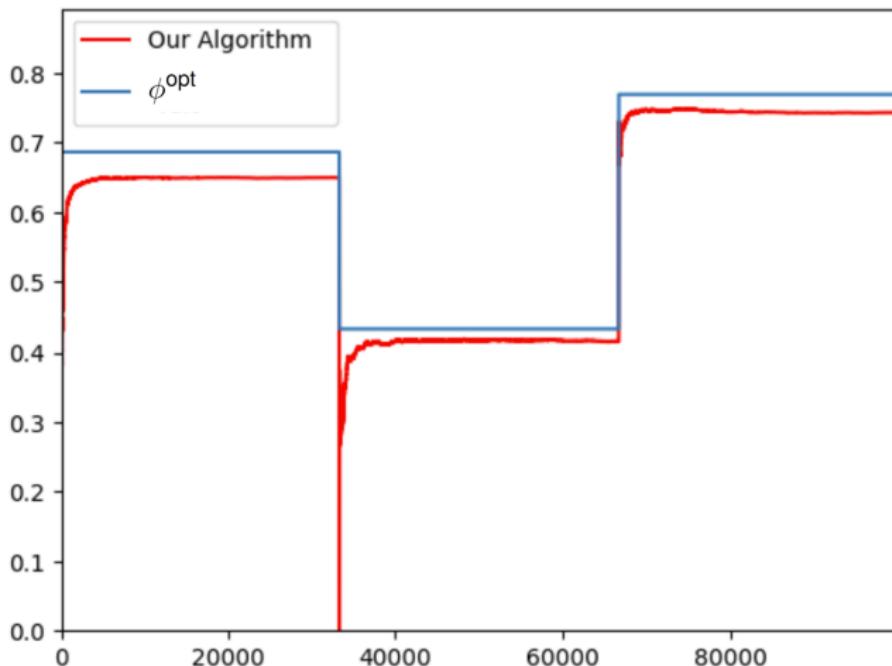
- Can be solved using¹.
- **Issues:** Above UCB based algorithms are not **adaptive**.

¹Shipra Agrawal and Nikhil R. Devanur. “Bandits with concave rewards and convex knapsacks”. In: *Proceedings of the Fifteenth ACM Conference on Economics and Computation*. Palo Alto, California, USA, June 2014, pp. 989–1006.

Adaptiveness



Adaptiveness



- **Idea:** Combining Lyapunov Optimization with Importance Sampling Based Estimation (EXP3 style)

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In time slot t

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- **Estimate** $S(t)$ ($q_{i,j}$ values) using feedback

$$\hat{S}_{i,j}(t) = S_{i,j}(t) Y_{i,j}(t) / P_{i,j}(t)$$

Algorithm

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- **Sample** an action $\mathbf{Y}(t) \sim \mathbf{P}(t)$ ($\mathbf{P}(t)$ is doubly stochastic)
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$$\hat{S}_{i,j}(t) = S_{i,j}(t) Y_{i,j}(t) / P_{i,j}(t)$$
- **Update** $\mathbf{P}(t+1)$

Virtual Queues and Auxiliary Variables

Auxiliary variables $\gamma(t) \in [0, 1]^n$, Virtual queue $\mathbf{Q}(t) \in [0, \infty)^n$

- ① $\gamma(t + 1) = \arg \min_{\gamma \in [0, 1]^n} \left[-V\phi(\gamma) + \sum_{i=1}^n Q_i(t)\gamma_i \right]$
- ② $\mathbf{Q}(t + 1) = \max\{\mathbf{Q}(t) + \gamma(t + 1) - \mathbf{X}(t), \mathbf{0}\}$

Update for $\mathbf{P}(t)$

$$\mathbf{P}(t+1) = \arg \min_{\substack{\mathbf{P} \text{ is doubly stochastic} \\ \text{with each entry } \geq \varepsilon}} \left[- \sum_{i=1}^n \sum_{j=1}^m Q_i(t) \hat{S}_{i,j}(t) P_{i,j} + \frac{1}{\eta} D(\mathbf{P} \| \tilde{\mathbf{P}}(t)) \right]$$

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- ① No closed form solution!!
- ② **Possible approach :** Sinkhorn's iterations.

Even/Odd Iterations

$$① \quad \tilde{\mathbf{P}}(t+1) = \arg \min_{\mathbf{P} \in \mathcal{Q}} \left[- \sum_{i=1}^n \sum_{j=1}^m Q_i(t) \hat{S}_{i,j}(t) P_{i,j} + \frac{1}{\eta} D(\mathbf{P} \| \tilde{\mathbf{P}}(t)) \right],$$

- \mathcal{Q} = column stochastic matrices with each entry $\geq \varepsilon$, when t is **even**
- \mathcal{Q} = row stochastic matrices with each entry $\geq \varepsilon$, when t is **odd**

² Jason Altschuler, Jonathan Niles-Weed, and Philippe Rigollet. “Near-linear time approximation algorithms for optimal transport via Sinkhorn iteration”. In: *Advances in Neural Information Processing Systems*. Dec. 2017.

Even/Odd Iterations

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$$② \quad \mathbf{P}(t+1) = \text{ROUND}(\tilde{\mathbf{P}}(t+1))$$

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Even/Odd Iterations

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③ Used for transport polytopes in²

²Altschuler, Niles-Weed, and Rigollet, “Near-linear time approximation algorithms for optimal transport via Sinkhorn iteration”.

Why Do We Need to Sample Alternatively

- 1 **Idea :** In the long run, $\tilde{\mathbf{P}}(t)$ will get closer and closer to a doubly stochastic matrix (close to $\mathbf{P}(t)$).

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Performance Bound

Theorem

For any $T, T_0 \in \mathbb{N}$,

$$\phi^{opt} - \phi \left(\frac{1}{T} \sum_{t=T_0}^{T+T_0-1} \mathbb{E}\{\mathbf{X}(t)\} \right) = O \left(\frac{nm \max^2\{n, m\} \log(T)}{T^{1/3}} \right)$$

Proof: <https://arxiv.org/abs/2501.14971>

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Adaptiveness: This holds independent of the behavior outside of $[T_0 : T + T_0 - 1]$.

Bound for the Single Channel Case

Recall for our multi-channel algorithm

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2 If we enforce each user to transmit more than θ fraction of the time,

$$\phi^{\text{opt}} - \phi \left(\frac{1}{T} \sum_{t=T_0}^{T+T_0-1} \mathbb{E}\{\mathbf{X}(t)\} \right) = O \left(\frac{n}{T^{1/2}} \right)$$

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Conclusions

- ① We developed an **adaptive** algorithm for the problem of automatic link selection in multi-channel multiple access with link failures.
- ② We provided theoretical guarantees for the convergence.
- ③ The algorithm simplifies in the single channel case with faster convergence.

Future Work

- ① Time-correlated scenarios, where channel successes are modulated by an unknown Markov process.

Thank You