

# Adaptive Algorithms for Automatic Link Selection in Multiple Access with Link Failures

**Mevan Wijewardena<sup>1</sup>**   Michael J. Neely<sup>1</sup>

<sup>1</sup>Department of Electrical and Computer Engineering  
University of Southern California.

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- 2 Our Contribution
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# Outline


- 1 Introduction
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# System Model

User 1 

User 2 

•  
•  
•

User  $n$  

Channel 1

Channel 2

•  
•  
•

Channel  $m$

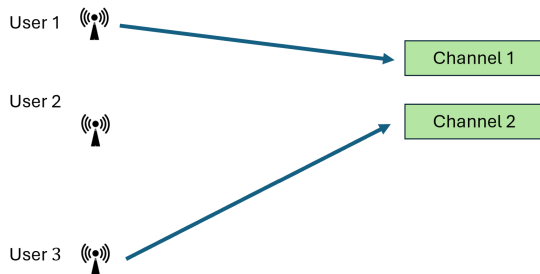


Centralized  
Controller

# Link Selection

In each slot, the controller assigns the users to channels

- Each user is assigned to at most one channel
- Each channel is assigned to at most one user.

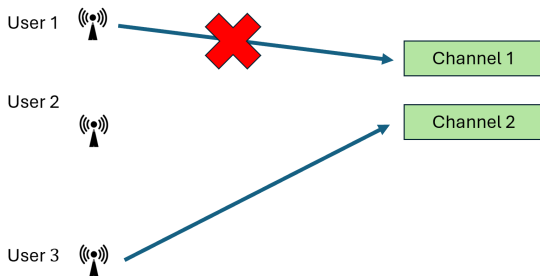


Assignment matrix

$$\mathbf{Y}(t) = \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix}$$

# Link Failures

- 1 After assignment, link  $(i, j)$  fails with probability  $1 - q_{i,j}$
- 2  $q_{i,j}$  have to be estimated using bandit feedback

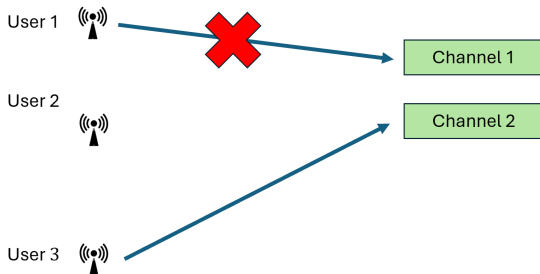


Link Failure Matrix

$$\mathbf{S}(t) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \\ 1 & 1 \end{bmatrix}$$

# Throughput Vector

① Throughput vector  $\mathbf{X}(t) \in \{0, 1\}^n$ .



$$\mathbf{X}(t) = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

# Maximizing System Throughput

Time horizon -  $T$

$$\text{maximize } \sum_{i=1}^n \frac{1}{T} \sum_{t=1}^T x_i(t)$$

**Pros:** Widely analyzed

**Cons:** Unfair for some users



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	Channel 1	Channel 2
User 1	0.7	0.7
User 2	0.3	0.2
User 3	0.6	0.4

Figure: Example  $q_{i,j}$  values

# Network Utility Maximization

$$\text{Maximize } \phi \left( \underbrace{\frac{1}{T} \sum_{t=1}^T X_1(t), \frac{1}{T} \sum_{t=1}^T X_2(t), \dots, \frac{1}{T} \sum_{t=1}^T X_n(t)}_{\text{Time-average throughput vector}} \right)$$

# Network Utility Maximization

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## Assumptions

- 1 Concave
- 2 Entrywise nondecreasing
- 3 Bounded subgradients  $|\phi'_i(\mathbf{x})| \leq B$ .

## Examples

# Utility Functions

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- ❶  $\phi(\mathbf{x}) = \sum_{i=1}^n x_i$
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- ❸  $\phi(\mathbf{x}) = \sum_{i=1}^n \log(1 + \beta x_i).$

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- 2  $\phi(\mathbf{x}) = \min\{x_1, x_2, \dots, x_n\}.$
- 3  $\phi(\mathbf{x}) = \sum_{i=1}^n \log(1 + \beta x_i).$
- 4  $\phi(\mathbf{x}) = w_1 \min\{x_1, x_2, \dots, x_n\} + w_2 \sum_{i=1}^n \log(1 + \beta x_i).$



# Known $q_{i,j}$ Values

- 1 Sample  $\mathbf{Y}(t) \sim \mathbf{P}^*$  in each time slot, where  $\mathbf{P}^*$  is doubly stochastic.

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- 2 How to find  $\mathbf{P}^*$

$$\begin{aligned} \text{Maximize: } & \phi \left( \boxed{\sum_{j=1}^m P_{1,j} q_{1,j}}, \sum_{j=1}^m P_{2,j} q_{2,j}, \dots, \sum_{j=1}^m P_{n,j} q_{n,j} \right) \\ \text{s.t. } & \mathbf{P} \text{ is doubly stochastic} \end{aligned}$$

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- 3 Optimal value  $\phi^{\text{opt}}$

# Our Goal

- Can we get close to  $\phi^{\text{opt}}$  when  $q_{i,j}$  are **unknown**.

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# Finite Time Bounds

$$\phi^{\text{opt}} - \phi \left( \frac{1}{T} \sum_{t=1}^T \mathbb{E}\{\mathbf{x}(t)\} \right) \leq g(T),$$

such that  $g(x) \rightarrow 0$  as  $x \rightarrow \infty$ .

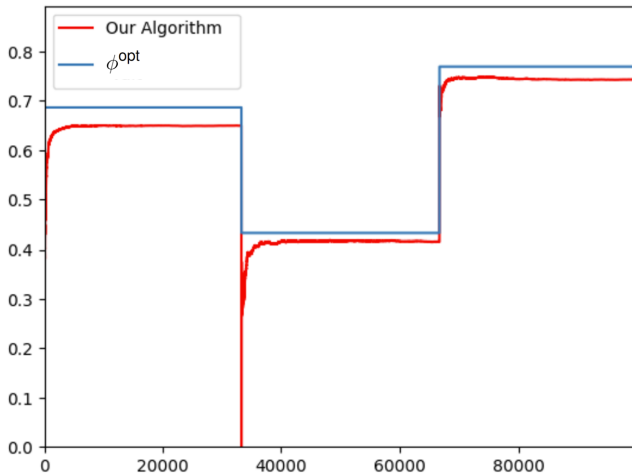
# Prior Work on Single-Channel Case

- Can be solved using<sup>1</sup>.
- **Issues:** Above UCB based algorithms are not **adaptive**.

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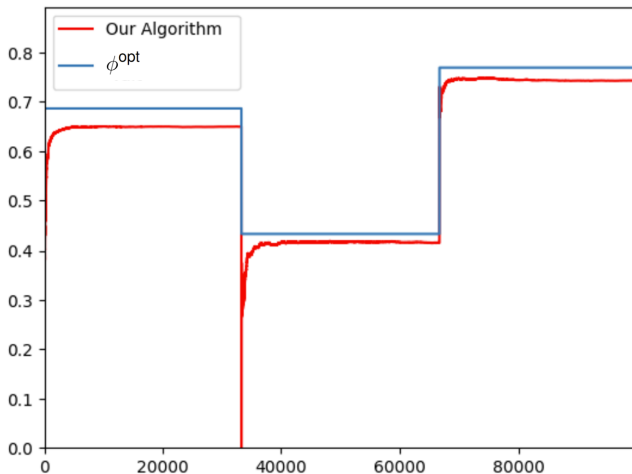
<sup>1</sup>Shipra Agrawal and Nikhil R. Devanur. “Bandits with concave rewards and convex knapsacks”. In: *Proceedings of the Fifteenth ACM Conference on Economics and Computation*. Palo Alto, California, USA, June 2014, pp. 989–1006.

# Adaptiveness





# Adaptiveness



- **Idea:** Combining Lyapunov Optimization with Importance Sampling Based Estimation (EXP3 style)

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- **Sample** an action  $\mathbf{Y}(t) \sim \mathbf{P}(t)$  ( $\mathbf{P}(t)$  is doubly stochastic)
- **Estimate**  $S(t)$  ( $q_{i,j}$  values) using feedback
$$\hat{S}_{i,j}(t) = S_{i,j}(t) Y_{i,j}(t) / P_{i,j}(t)$$

# Algorithm

In time slot  $t$

- **Sample** an action  $\mathbf{Y}(t) \sim \mathbf{P}(t)$  ( $\mathbf{P}(t)$  is doubly stochastic)
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$$\hat{S}_{i,j}(t) = S_{i,j}(t) Y_{i,j}(t) / P_{i,j}(t)$$
- **Update**  $\mathbf{P}(t+1)$

# Virtual Queues and Auxiliary Variables

Auxiliary variables  $\gamma(t) \in [0, 1]^n$ , Virtual queue  $\mathbf{Q}(t) \in [0, \infty)^n$

- 1  $\gamma(t+1) = \arg \min_{\gamma \in [0, 1]^n} \left[ -V\phi(\gamma) + \sum_{i=1}^n Q_i(t)\gamma_i \right]$
- 2  $\mathbf{Q}(t+1) = \max\{\mathbf{Q}(t) + \gamma(t+1) - \mathbf{X}(t), \mathbf{0}\}$

# Update for $\mathbf{P}(t)$

$$\mathbf{P}(t+1) = \arg \min_{\substack{\mathbf{P} \text{ is doubly stochastic} \\ \text{with each entry} \geq \varepsilon}} \left[ - \sum_{i=1}^n \sum_{j=1}^m Q_i(t) \hat{S}_{i,j}(t) P_{i,j} + \frac{1}{\eta} D(\mathbf{P} \| \tilde{\mathbf{P}}(t)) \right]$$



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- 1 No closed form solution!!
- 2 **Possible approach** : Sinkhorn's iterations.

# Even/Odd Iterations

$$\textcircled{1} \quad \tilde{\mathbf{P}}(t+1) = \arg \min_{\mathbf{P} \in \mathcal{Q}} \left[ - \sum_{i=1}^n \sum_{j=1}^m Q_i(t) \hat{S}_{i,j}(t) P_{i,j} + \frac{1}{\eta} D(\mathbf{P} \| \tilde{\mathbf{P}}(t)) \right],$$

- $\mathcal{Q}$  = column stochastic matrices with each entry  $\geq \varepsilon$ , when  $t$  is **even**
- $\mathcal{Q}$  = row stochastic matrices with each entry  $\geq \varepsilon$ , when  $t$  is **odd**

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<sup>2</sup>Jason Altschuler, Jonathan Niles-Weed, and Philippe Rigollet. “Near-linear time approximation algorithms for optimal transport via Sinkhorn iteration”. In: *Advances in Neural Information Processing Systems*. Dec. 2017.

# Even/Odd Iterations

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$$\textcircled{2} \quad \mathbf{P}(t+1) = \text{ROUND}(\tilde{\mathbf{P}}(t+1))$$

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# Even/Odd Iterations

1  $\tilde{\mathbf{P}}(t+1) = \arg \min_{\mathbf{P} \in \mathcal{Q}} \left[ - \sum_{i=1}^n \sum_{j=1}^m Q_i(t) \hat{S}_{i,j}(t) P_{i,j} + \frac{1}{\eta} D(\mathbf{P} \| \tilde{\mathbf{P}}(t)) \right],$

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2  $\mathbf{P}(t+1) = \text{ROUND}(\tilde{\mathbf{P}}(t+1))$

3 Used for transport polytopes in<sup>2</sup>

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# Why Do We Need to Sample Alternatively

- 1 **Idea :** In the long run,  $\tilde{\mathbf{P}}(t)$  will get closer and closer to a doubly stochastic matrix (close to  $\mathbf{P}(t)$ ).

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## Theorem

For any  $T, T_0 \in \mathbb{N}$ ,

$$\phi^{opt} - \phi \left( \frac{1}{T} \sum_{t=T_0}^{T+T_0-1} \mathbb{E}\{\mathbf{X}(t)\} \right) = O \left( \frac{nm \max^2\{n, m\} \log(T)}{T^{1/3}} \right)$$

**Proof:** <https://arxiv.org/abs/2501.14971>



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**Adaptiveness:** This holds independent of the behavior outside of  $[T_0 : T + T_0 - 1]$ .

# Bound for the Single Channel Case

Recall for our multi-channel algorithm

$$\phi^{\text{opt}} - \phi \left( \frac{1}{T} \sum_{t=T_0}^{T+T_0-1} \mathbb{E}\{\mathbf{X}(t)\} \right) = O \left( \frac{nm \max^2\{n, m\} \log(T)}{T^{1/3}} \right)$$

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For any  $T, T_0$

1

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2 If we enforce each user to transmit more that  $\theta$  fraction of the time,

$$\phi^{\text{opt}} - \phi \left( \frac{1}{T} \sum_{t=T_0}^{T+T_0-1} \mathbb{E}\{\mathbf{X}(t)\} \right) = O \left( \frac{n}{T^{1/2}} \right)$$

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# Conclusions

- 1 We developed an **adaptive** algorithm for the problem of automatic link selection in multi-channel multiple access with link failures.
- 2 We provided theoretical guarantees for the convergence.
- 3 The algorithm simplifies in the single channel case with faster convergence.

## Future Work

- 1 Time-correlated scenarios, where channel successes are modulated by an unknown Markov process.

# Thank You