

I. Change of Basis.

$$\textcircled{1} \quad \underline{x} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

$$\underline{x} = \alpha_1 \underline{v}_1 + \alpha_2 \underline{v}_2$$

$$\Rightarrow \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \begin{bmatrix} \alpha_1 + \alpha_2 \\ \alpha_1 - \alpha_2 \end{bmatrix}$$

$$\Rightarrow \alpha_1 = \alpha_2 = 1 \Rightarrow \underline{x} = \underline{v}_1 + \underline{v}_2$$

$$\textcircled{2} \quad y = Kx.$$

$$x : \begin{bmatrix} F_1 \\ F_2 \\ \text{Force} \end{bmatrix} \quad y : \begin{bmatrix} h \\ n_B \end{bmatrix}$$

Assuming the initial basis to be natural basis,

$$\hat{x} = W^{-1}x \quad \text{and} \quad \hat{y} = W^{-1}y.$$

$$\text{where } W = [\underline{w}_1 \quad \underline{w}_2 \quad \underline{w}_3] \quad \text{and} \quad V = [\underline{v}_1 \quad \underline{v}_2 \quad \underline{v}_3]$$

$$\Rightarrow \cancel{W}y = (\cancel{W}^{-1}K).$$

$$\Rightarrow y = Kx \Rightarrow W^{-1}y = W^{-1}K(W^{-1}x) \quad (\because WW^{-1} = I)$$

$$\Rightarrow \hat{y} = (\hat{W}^{-1}K\hat{W})(\hat{x})$$

$$W = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \quad V = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

$$\Rightarrow V^{-1} = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & -1 \end{bmatrix}, W^{-1} = \begin{bmatrix} 0.5 & 0.5 \\ 0.5 & -0.5 \end{bmatrix}$$

$$K_{\text{new}} = W^{-1} K V$$

$$= \begin{bmatrix} 0.5 & 0.5 \\ 0.5 & -0.5 \end{bmatrix} \begin{bmatrix} 4 & 2 & 4 \\ 0.5 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & -1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.5 & 0.5 \\ 0.5 & -0.5 \end{bmatrix} \begin{bmatrix} 4 & 6 & -2 \\ 0.5 & 1.5 & 1 \end{bmatrix}$$

$$\Rightarrow \text{the new gain} = \begin{bmatrix} 2.25 & 3.75 & -0.5 \\ 1.75 & 2.25 & -1.5 \end{bmatrix}$$

Problem 2: Linear Dependence

- ③ If p vectors are linearly independent, then their dimension $n \geq p$.

\therefore The correct options: $n = 3, 4, 5$
(c), (d), (e).

- ④ If possible to let $\underline{u}, \underline{v}, \underline{w}$ be linearly dependent.

\Rightarrow there exists ^{non-zero} $\alpha_1, \alpha_2, \alpha_3$ such that

$$\alpha_1 \underline{u} + \alpha_2 \underline{v} + \alpha_3 \underline{w} = 0 \text{ and at least}$$

one of $\alpha_1, \alpha_2, \alpha_3$ is

$$\Rightarrow \alpha_1 (\underline{u}_1 + \underline{u}_2) + \alpha_2 (\underline{u}_1 + \underline{u}_3) + \alpha_3 (\underline{u}_2 + \underline{u}_3) = 0 \quad \text{non-zero}$$

$$\Rightarrow (\alpha_1 + \alpha_2) \underline{u}_1 + (\alpha_1 + \alpha_3) \underline{u}_2 + (\alpha_2 + \alpha_3) \underline{u}_3 = 0$$

$$\Rightarrow (\alpha_1 + \alpha_2) \underline{x}_1 + (\alpha_1 + \alpha_3) \underline{x}_2 + (\alpha_2 + \alpha_3) \underline{x}_3 = 0.$$

ℙ We know that $\underline{x}_1, \underline{x}_2, \underline{x}_3$ are independent

$$\Rightarrow \sum \beta_i \underline{x}_i = 0 \text{ iff } \beta_i = 0 \forall i$$

$$\therefore \alpha_1 + \alpha_2 = 0, \alpha_1 + \alpha_3 = 0, \text{ \& } \alpha_2 + \alpha_3 = 0.$$

$$\left. \begin{array}{l} \alpha_1 + \alpha_3 = 0 \Rightarrow \alpha_1 = -\alpha_3 \\ \alpha_1 + \alpha_2 = 0 \Rightarrow \alpha_1 = -\alpha_2 \\ \alpha_2 + \alpha_3 = 0 \Rightarrow \alpha_2 = -\alpha_3 \end{array} \right\} \Rightarrow \begin{array}{l} \alpha_1 = \alpha_2 \\ \alpha_1 = -\alpha_2 \end{array}$$

$$\Rightarrow \alpha_1 = \alpha_2 = \alpha_3 = 0$$

But we assumed that at least one of

$(\alpha_1, \alpha_2, \alpha_3)$ are non-zero.

\therefore there is a contradiction

$\Rightarrow \underline{u}, \underline{v}$ and \underline{w} are linearly independent

Problem 3: Null and Image Spaces

$$L = \begin{bmatrix} 2 & 0 & 4 \\ 0.5 & 1 & 0 \end{bmatrix} \quad (\because \text{roll-no} = "C418B020")$$

⑤ Null Space: $Lx = 0 \Rightarrow \begin{bmatrix} 2 & 0 & 4 \\ 0.5 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$

$$\Rightarrow \begin{bmatrix} 2x_1 + 4x_3 \\ \frac{x_1}{2} + x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow x_3 = \frac{-2x_1}{-2} \text{ and } x_2 = \frac{-x_1}{2}$$

$$\underline{x} = \begin{bmatrix} x_1 \\ -\frac{x_1}{2} \\ -\frac{x_1}{2} \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ -1/2 \\ -1/2 \end{bmatrix}$$

\therefore all points lying on the line along the vector $(1, -0.5, -0.5)$ belong to the NULL SPACE

Normalized value: $[-0.8165 \quad 0.4082 \quad 0.4082]$

Image Space: vector space formed by columns of L

$$\Rightarrow x_1 \begin{pmatrix} 2 \\ 0.5 \end{pmatrix} + x_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} + x_3 \begin{pmatrix} 4 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} 2x_1 + 4x_3 \\ x_1 + 0.5x_2 \end{pmatrix}$$

We observe that the 2 values can be manipulated independently by modifying x_2 & x_3

\Rightarrow Image space is whole of \mathbb{R}^2 space.

(Spanned by $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$)

Problem 4: Eigenvalue decomposition and Matrix Exponent.

Roll no. : CH18B020.

$$B = \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$$

$$\textcircled{6} \quad |A - \lambda I| = 0 \Rightarrow \begin{vmatrix} 1-\lambda & 0 \\ 2 & -\lambda \end{vmatrix} = 0$$

$$\Rightarrow \lambda^2 - \lambda = 0 \text{ - characteristic equation}$$

$$\lambda = 0, 1$$

$$\textcircled{7} \quad LHS = B^2 - B$$

$$= \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = RHS$$

The Cayley Hamilton theorem is verified.

$$\textcircled{8} \quad Bx = \lambda x$$

$$\text{i) } \lambda = 0 \Rightarrow \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{matrix} x_1 = 0 \\ x_2 = 1 \end{matrix}$$

$$\text{ii) } \lambda = 1 \Rightarrow \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \Rightarrow x_1 = x_2$$

⇒ the eigen vectors are $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} 1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix}$

$$V = \begin{bmatrix} 0 & \frac{1}{\sqrt{5}} \\ 1 & \frac{2}{\sqrt{5}} \end{bmatrix} \Rightarrow V^{-1} = \begin{bmatrix} -2 & 1 \\ \sqrt{5} & 0 \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ \sqrt{5} & 0 \end{bmatrix}$$

$$B = V \Lambda V^{-1} = \begin{bmatrix} 0 & \frac{1}{\sqrt{5}} \\ 1 & \frac{2}{\sqrt{5}} \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -2 & 1 \\ \sqrt{5} & 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1/\sqrt{5} \\ 1 & 2/\sqrt{5} \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -2 & 1 \\ \sqrt{5} & 0 \end{bmatrix}$$

eigen vector $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ corresponds to $\lambda = 0$

and eigen vector $\begin{bmatrix} 1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix}$ corresponds to $\lambda = 1$

(9)

$$B = V \Lambda V^{-1}$$

$$\Rightarrow e^B = V e^\Lambda V^{-1}$$

$$e^\Lambda = \begin{bmatrix} e^0 & 0 \\ 0 & e^1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & e \end{bmatrix}$$

$$\therefore e^B = \begin{bmatrix} 0 & 1/\sqrt{5} \\ 1 & 2/\sqrt{5} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & e \end{bmatrix} \begin{bmatrix} -2 & 1 \\ \sqrt{5} & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1/\sqrt{5} \\ 1 & 2/\sqrt{5} \end{bmatrix} \begin{bmatrix} -2 & 1 \\ \sqrt{5}e & 0 \end{bmatrix}$$

$$\Rightarrow e^B = \begin{bmatrix} e & 0 \\ -2+2e & 1 \end{bmatrix} = \begin{bmatrix} 2.7183 & 0 \\ 3.4366 & 1 \end{bmatrix}$$

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Problem 5: Jordan decomposition.

$$C = \begin{bmatrix} 1 & 1 \\ -1 & 3 \end{bmatrix} \quad |C - \lambda I| = 0$$

$$\Rightarrow (1-\lambda)(3-\lambda) + 1 = 0$$

$$\Rightarrow 3 + \lambda^2 - 4\lambda + 1 = 0$$

$$\Rightarrow \lambda = 2, 2 \quad (\text{repeated roots})$$

$$C \underline{x} = \lambda \underline{x} \quad (\text{eigen vector})$$

$$\Rightarrow \begin{bmatrix} 1 & 1 \\ -1 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2x_1 \\ 2x_2 \end{bmatrix}$$

$$\Rightarrow \begin{cases} x_1 + x_2 = 2x_1 \\ -x_1 + 3x_2 = 2x_2 \end{cases} \Rightarrow x_1 = x_2$$

∴ The eigen vector is $\underline{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

Generalised eigen vector: $(A - \lambda I) \underline{v}_2 = \underline{v}_1$

$$\Rightarrow \left(\begin{bmatrix} 1 & 1 \\ -1 & 3 \end{bmatrix} - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \right) \underline{v} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -x_1 + x_2 \\ x_2 - x_1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \Rightarrow x_2 - x_1 = 1$$

⇒ The family of vectors satisfying the generalised eigen vector eqn: $\begin{bmatrix} \beta \\ \beta + 1 \end{bmatrix}$

where β is an arbitrary vector, real number.

For simplicity, let $\beta = 0$, $\underline{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$$\therefore \underline{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \text{ and } \underline{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$1b) \quad X = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \Rightarrow X^{-1} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$$

$$\Rightarrow C = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$$

This is the "Jordan Canonical Form".

If $C = X \Lambda X^{-1}$, it means,

$$e^C = X e^{\Lambda} X^{-1}$$

$$\Rightarrow e^C = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} e^{\begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix}} \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$$

$$\text{also } \exp \left(\begin{bmatrix} \lambda & 1 \\ 0 & \lambda \end{bmatrix} \right) = \begin{bmatrix} e^{\lambda} & e^{\lambda} \\ 0 & e^{\lambda} \end{bmatrix}$$

$$\begin{aligned} \Rightarrow e^C &= \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} e^{\lambda} & e^{\lambda} \\ 0 & e^{\lambda} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} e^2 & e^2 \\ 0 & e^2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \end{aligned}$$

$$\Rightarrow \text{exp}(C) = \begin{bmatrix} e^2 & e^2 \\ e^2 & 2e^2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & e^2 \\ -e^2 & 2e^2 \end{bmatrix}$$

$$\Rightarrow \text{exp}(C) = \begin{bmatrix} 0 & 7.3891 \\ -7.3891 & 14.7781 \end{bmatrix}$$