

(4)

For convenience, I would like to label Kevin as player A, Karen as player B, Kannan as player C.

To model the problem as an MDP, where 'A' is the decision maker we need to know the decisions (in fact, optimal) of 'B' & 'C'.

### 2-Game scenarios.

consider

Consider the game has reduced to A & B and it is A's turn to fire. Let us analyse this from the point of view of B:

- B can't miss intentionally - has to shoot at A.
- Rule permits A to shoot into the air. But that will ~~to~~ increase chance of B winning - because B will take more turns to fire & hence the probability of reaching the target (which will be a geometric distribution) increases

So, to obtain a lower bound of probability of B winning we can as well assume B & A always shoot & doesn't miss intentionally

$$P_{\text{B wins in } k \text{ turns}} = P(\text{A misses } k \text{ times despite shooting}) \times P(\text{B misses } k-1 \text{ times consecutively before firing is his turn})$$

$$= (1-\alpha)^k (1-\beta)^{k-1} \beta.$$

$$\therefore P(B \text{ wins in } A \text{ vs } B) = \sum_{k=1}^{\infty} (1-\alpha)^k (1-\beta)^{k-1} \beta.$$

$$= \frac{(1-\alpha) \cancel{(1-\alpha)} \times \beta}{1 - (1-\alpha)(1-\beta)}$$

Proceeding similarly

$$P(B \text{ wins in } B \text{ vs } C) = \frac{(1-\alpha\beta)}{1 - (1-\beta)(1-\beta)} \times \beta$$

$$\text{But } (1-\beta) < (1-\alpha) \quad \because \alpha > \beta$$

$$\Rightarrow \frac{(1-\alpha)(1-\beta)}{1 - (1-\beta)(1-\beta)} < \frac{(1-\alpha\beta)}{1 - (1-\beta)(1-\beta)}$$

So we conclude

$$P(B \text{ wins } A \text{ vs } B) > P(B \text{ wins } B \text{ vs } C)$$

Similarly for arguing in a similar fashion,

$$P(C \text{ wins } C \text{ vs } A) > P(C \text{ wins } C \text{ vs } B)$$

From this analysis, we understand that B and C would seek to eliminate each other first because they prefer duelling to maximising winning chance.

So, when all of ABC are alive,

\* B shoots C in his turn

\* C shoots B in his turn

~~States~~

Now that we have decided the possible actions of B & C we can build an MDP.

- Note that a single transition in the MDP incorporates all changes in the position of the game between 2 turns of A (eg. if B & C are alive, one transition implies A, B, and C have all taken their turns)

State Space :  $\{ \overset{(1)}{A \text{ lost}}, \overset{(2)}{A \text{ and B are alive}}, \overset{(3)}{A \text{ and B \& C are alive}}, \overset{(4)}{A, B \text{ and C are alive}}, \overset{(5)}{A \text{ alive (A has won!)}} \}$

Action space :  $\{ \}$

state ① : no action - A already out of the game (terminal)

state ② : shoot at B, miss intentionally.

state ③ : shoot at ~~B~~<sup>C</sup>, miss intentionally

state ④ : shoot at B, shoot at C, miss intentionally

state ⑤ : A has won! - no actions (terminal)

Cost/Rewards :

∴ We want to minimise probability of winning,

~~we will normalise~~  $g(i, a, j) = 0 \forall i, a, j$

Note that the A lost & A won are terminal states

$$J_N(x_N) = \begin{cases} 0 & \text{if } x \neq x_5 \\ 1 & \text{if } x = x_5 \end{cases}$$

$$\begin{aligned} \text{So objective} & \max_a E \left( \alpha + J_N^+(x_N) - \sum_{k=1}^N g_k(x_k, u_k, x_{k-1}) \right) \\ & = \max_a E \left( J_N^+(x_N) \right) \end{aligned}$$

$$= \max_a E \left( g_N(x_N) \right)$$

which is eqvt to minimising probability of win.

→  $\therefore$  probability = expectation of indicator variable for the event

Transition probabilities

Let  $a_1$ : A shoots B  $a_2$ : A shoots C  $a_3$ : A shoots air.

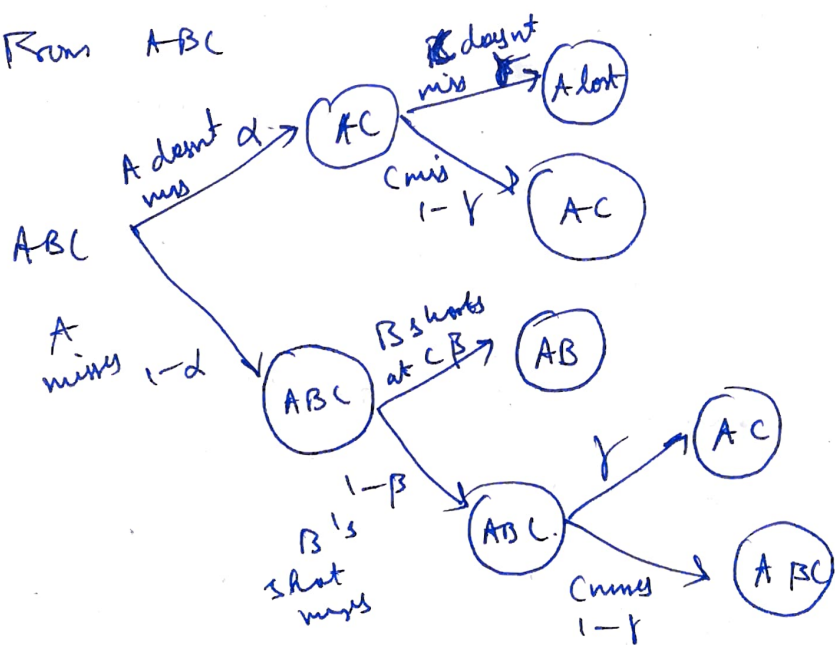
a) Action  $a_1$ :

From AB: A wins if A shoots properly:  $\alpha$

A ~~loses~~ if A misses & B shoots properly:  $(1-\alpha)\beta$

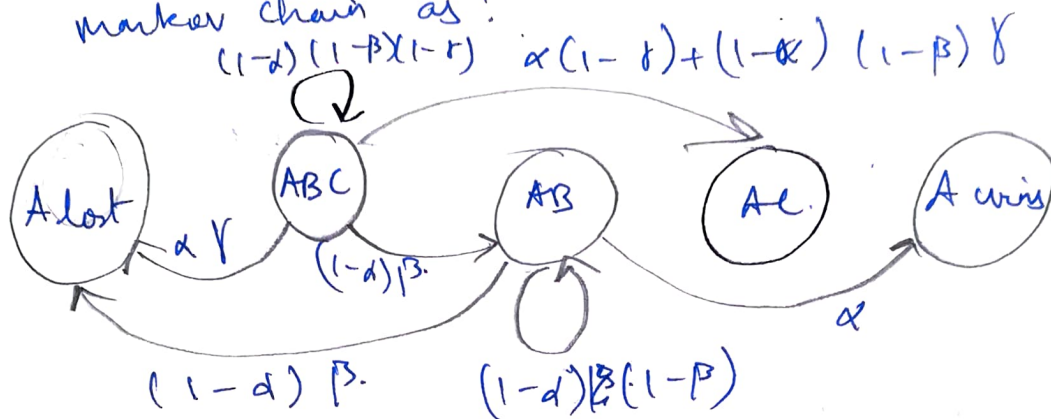
Back to same state if A & B both miss:  $(1-\alpha)(1-\beta)$

From ABC





Using these transition probabilities we get the  
 Markov chain as:



No transitions from AC because A can't shoot B in that state -

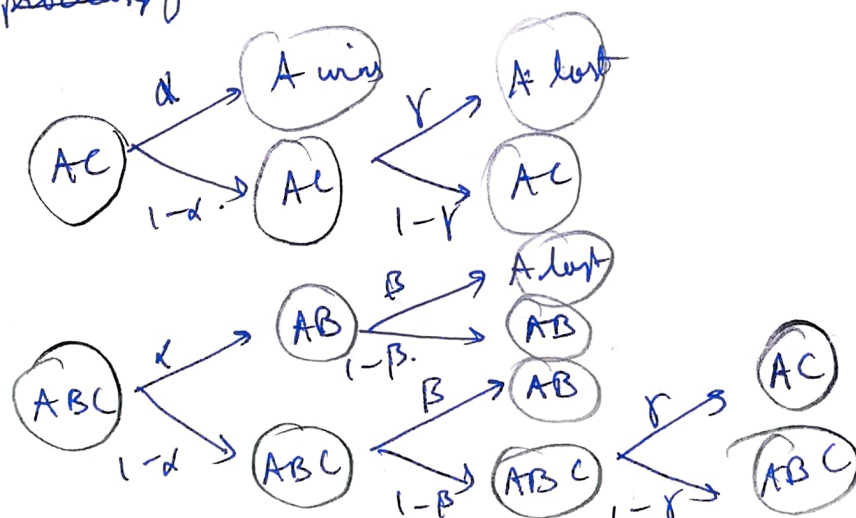
$$P_{21} = \alpha\gamma \quad P_{22} = (1-\alpha)(1-\beta)(1-\gamma) \quad P_{24} = \alpha(1-\gamma) + (1-\alpha)(1-\beta)\gamma$$

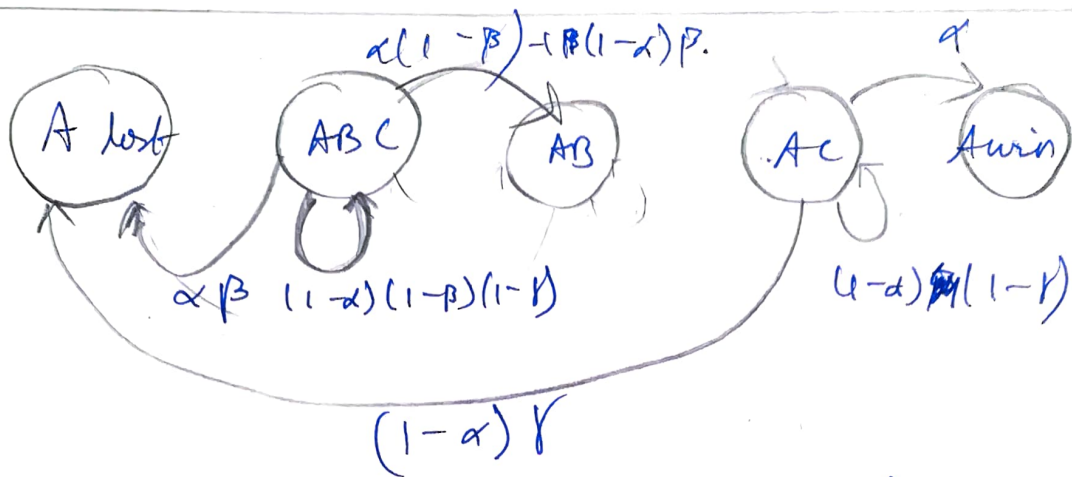
$$P_{23} = (1-\alpha)\beta$$

$$P_{31} = (1-\alpha)\beta \quad P_{33} = (1-\alpha)(1-\beta)$$

$$P_{35} = \alpha ; \text{ other } P_{ij} = 0$$

ii) Action  $a_2$ : A shoots C  
 Proceeding similarly



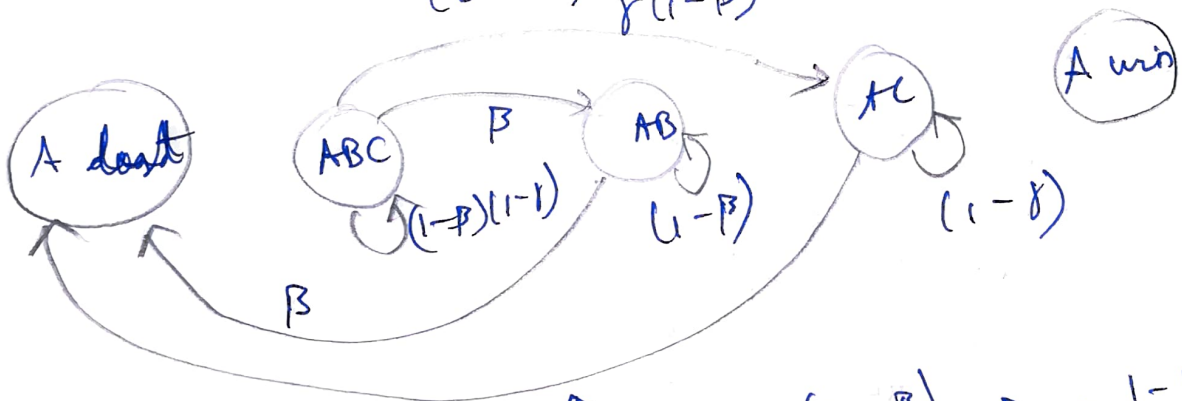
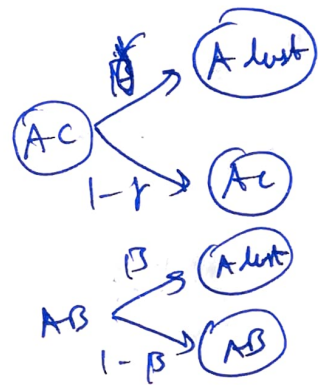
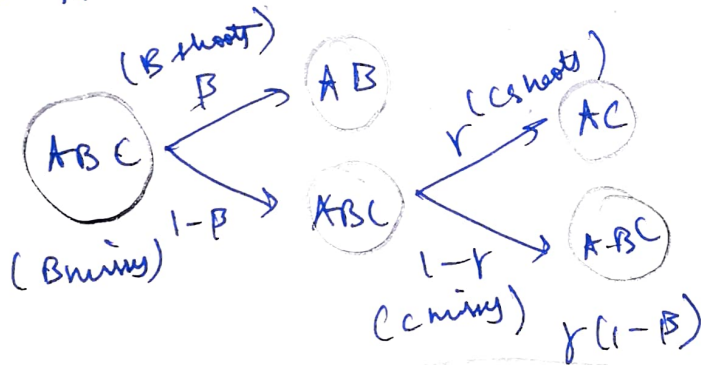


$$P_{21} = \alpha\beta \quad P_{22} = (1-\alpha)(1-\beta)(1-\gamma)$$

$$P_{23} = \alpha(1-\beta) + (1-\alpha)\beta\gamma; P_{31} = (1-\alpha)\gamma$$

$$P_{44} = (1-\alpha)\gamma(1-1); P_{45} = \alpha; \text{other } P_{ij} = 0$$

iii) Action  $a_3$ : A shoots air.



$$P_{22} = (1-\beta)(1-\gamma) \quad P_{23} = \beta \quad P_{24} = (1-\beta)\gamma \quad P_{33} = (1-\beta) \quad P_{31} = \beta \quad P_{44} = 1-\gamma \quad P_{41} = \gamma \quad \text{other } P_{ij} = 0$$

b) Bellman optimality equations

$$T J^+ = J^+ ; \quad J^+(A_{win}) = 1$$

$$\Rightarrow J^+(i) = \max_{a \in A(i)} E(g(i, a, j) + J^+(j))$$

(  $\because$  maximizing rewards )

$$= \max_{a \in A(i)} E(J^+(j))$$

$J(AB) = \max_a$   
 At  $AB$  state  $AB$ , we have 2 actions allowed  
 - shoot  $B$  or shoot at

$$\Rightarrow J(AB) = \max \left\{ \begin{array}{l} (1-\beta)J(AB), \\ (1-\alpha)(1-\beta)J(AB) + \alpha J(A_{win}) \end{array} \right\}$$

A shoots at      A shoots B

$$= \max \left\{ \begin{array}{l} (1-\beta)J(AB), \\ (1-\alpha)(1-\beta)J(AB) + \alpha \end{array} \right\}$$

①

Similarly

$$J(AC) = \max \left\{ \begin{array}{l} (1-\gamma)J(AC), \\ (1-\alpha)(1-\gamma)J(AC) + \alpha \end{array} \right\}$$

A shoots at      A shoots C

(2 actions: shoot ~~B~~ or shoot C)

②

At state ABC, all 3 actions are allowed, so we take max over the 3 actions

$$J(ABC) = \max \left\{ \begin{aligned} &[(1-\alpha)(1-\beta)(1-\gamma)J(ABC) \\ &+ (\alpha(1-\gamma) + (1-\alpha)(1-\beta)\gamma)J(AC) \\ &+ (1-\alpha)\beta J(AB) \end{aligned} \right. \\ \left. \begin{aligned} &[(1-\alpha)(1-\beta)(1-\gamma)J(ABC) + (\alpha(1-\beta) + (1-\alpha)\beta)J(AB) \\ &+ (1-\alpha)\gamma(1-\beta)\gamma J(AC) \end{aligned} \right. \\ \left. \begin{aligned} &[(1-\beta)(1-\gamma)J(ABC) + \beta J(AB) + \gamma(1-\beta)J(AC)] \end{aligned} \right\} \quad (3)$$

c) Given  $\alpha = 0.3$ ,  $\beta = 0.5$ ,  $\gamma = 0.6$ . Substituting,

eqn ①:  $J_{AB} = \max(0.5J_{AB}, 0.5 \times 0.7, 0.3J_{AB} + 0.3)$

part i) giving  $J_{AB} = 0$  - not correct - then not probability

part ii) giving  $J_{AB} = \frac{0.3}{0.65} = \boxed{0.4615}$  - shoot B preferred  
 & ii)  $> 0$  when  $J_{AB} = 0$   
 (i.e.  $0.5(0.4615) < 0.35(0.4615)$ )

eqn ②:  $J_{AC} = \max(0.4J_{AC}, 0.28J_{AC} + 0.3, 0.3)$

using a similar argument,

$J_{AC} = \frac{0.3}{0.72} = \boxed{0.4167}$  - shoot C preferred



eqn ③

(i) term:

$$J_{ABE}^* = (0.7)(0.5)(0.4) J_{ABC} \\ + [(0.3)(0.4) + (0.7)(0.5)(0.6)] J_{AC} \\ + (0.7)(0.5) J_{AB}$$

$$\Rightarrow J_{ABC}^* = \frac{0.299}{0.86} = 0.3477$$

(ii) term:

$$J_{ABC}^* = 0.14 J_{ABC} + [(0.3)(0.5) + (0.7)(0.5)] J_{AB} \\ + (0.5)(0.7)(0.6) J_{AC}$$

$$\Rightarrow J_{ABC}^* = \frac{0.3183}{0.86} \approx 0.37$$

(iii) term:

$$J_{ABC}^* = 0.2 J_{AB} + 0.5 J_{AB} + 0.3 J_{AC}$$

$$\Rightarrow J_{ABC}^* = \frac{0.35}{0.8} = \boxed{0.445}$$

Using  $J_{ABC}^* = 0.445$ ,

(iii) term > (i) & (ii)

$\Rightarrow$  eqn is solved.

— short cut is preferred.

State	$J^*(x)$	$U^*(x)$ (optimal action)
A lost	0	— (A can do anything)
AB	0.4615	Shoot B
AC	0.467	Shoot C
ABC	0.445	Shoot in air