

# Computational Fabrication:

## From Design Automation to New Manufacturing

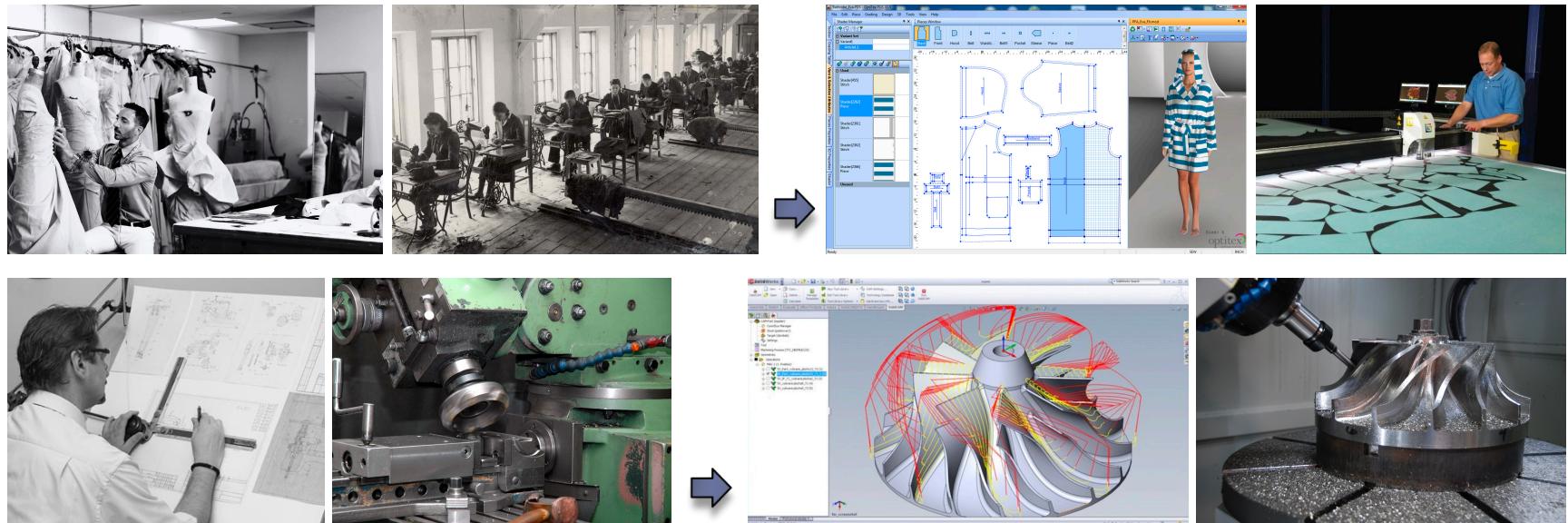
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December 3, 2018

# Computational Design & Manufacturing

- ▶ History can be traced back to 1970s
  - ▶ How to advance **conventional** production?
  - ▶ Make it **better, faster** and **more economical**
  - ▶ Revolution of conventional industrial by **Digitization**
  - ▶ How about **future**?



# Computational Design and Fabrication

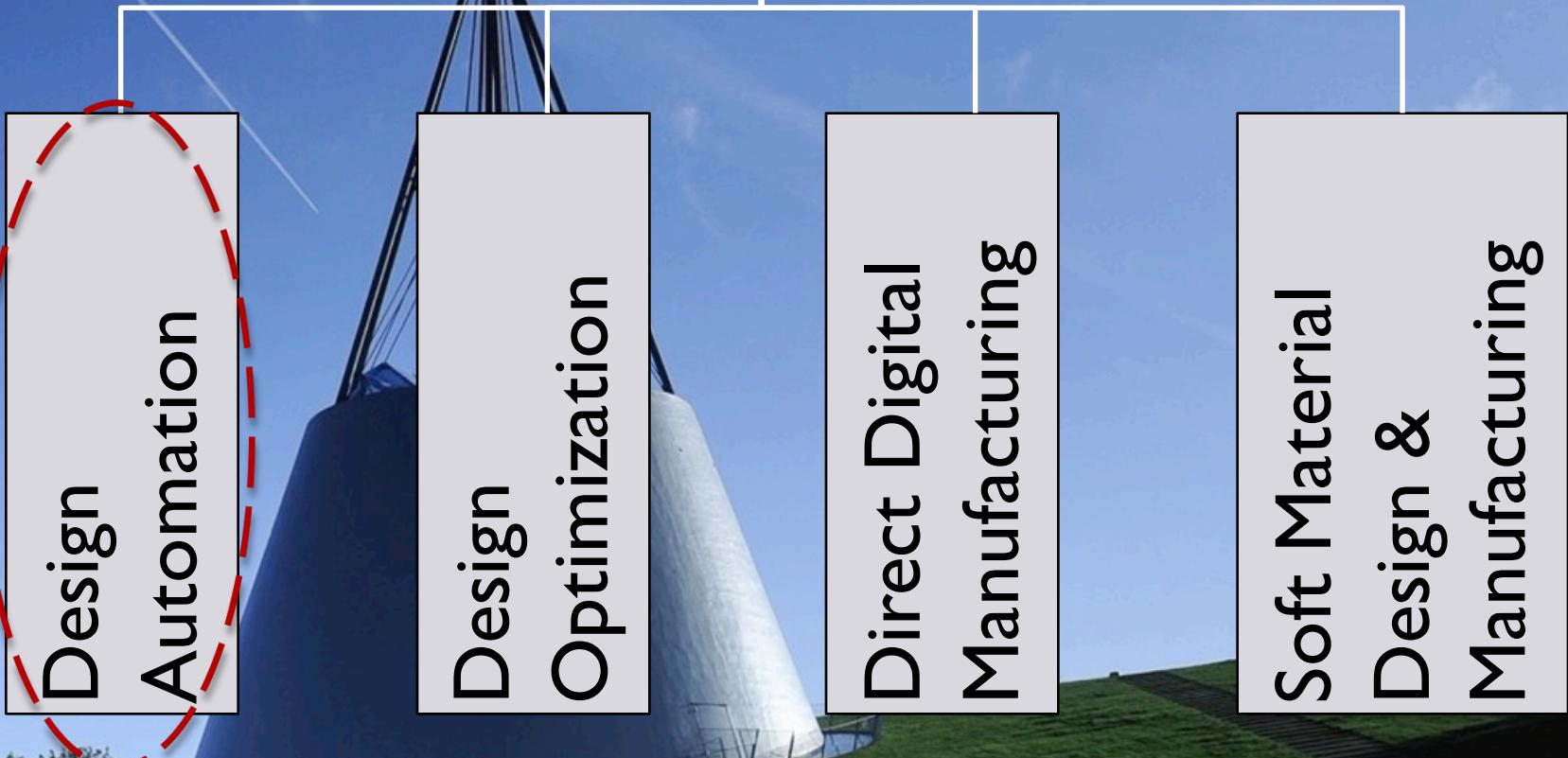
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CAD ≠ Computer-Aided Drafting

CAD ≠ Computer-Aided Documentation

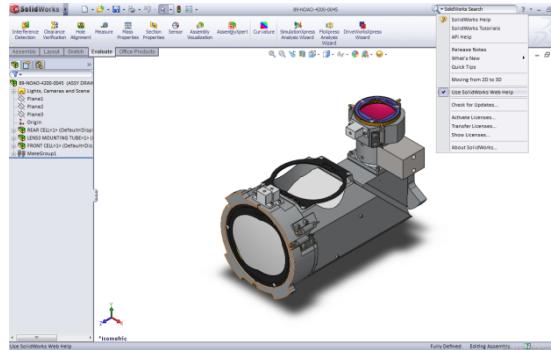
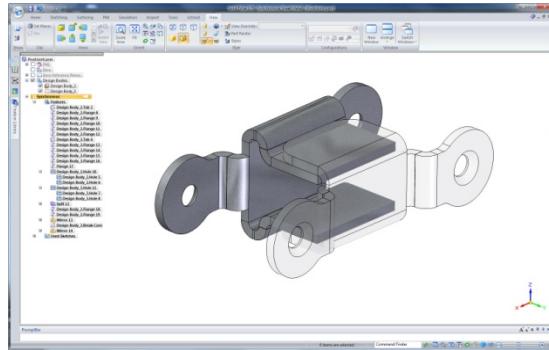
- ▶ **Demand:** tools completely integrated into the process of design practice
  - ▶ Automatic design process (Design Automation)
  - ▶ Design better products (Design Optimization)
  - ▶ Called Generative Design in Industry (e.g., Autodesk)
- ▶ **Our vision** in Advanced Design and Manufacturing
  - ▶ Making the design process more automatic, intelligent and systematic
  - ▶ Solving manufacturing problems at the design phase
- ▶ **Our focus:** inventing advanced computational tools to face the grand challenges of design and manufacturing

# Computational Design and Fabrication



Geometric and Physical Modeling

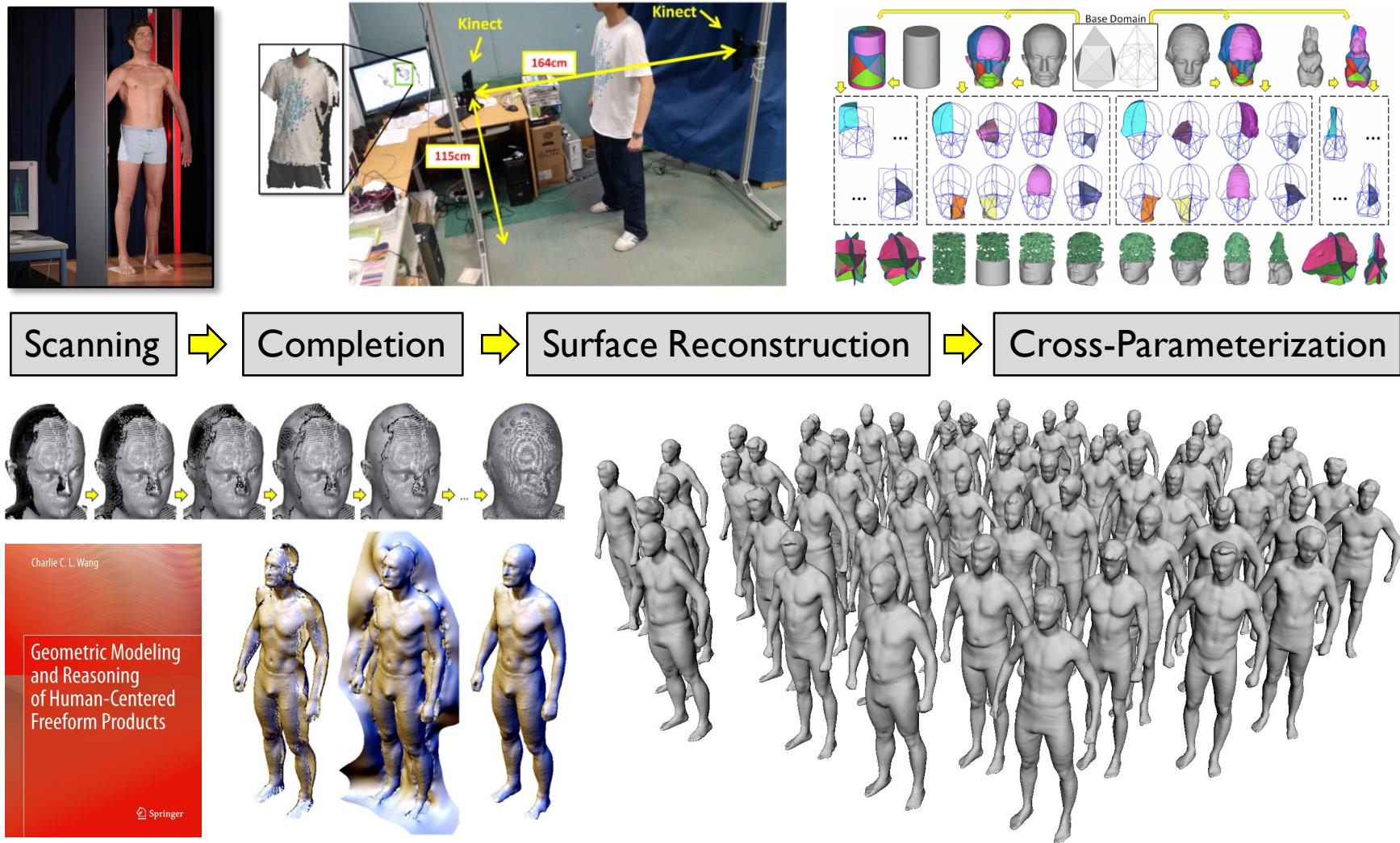
# Design Automation: Ultra Personalized Products Driven by Body Shape



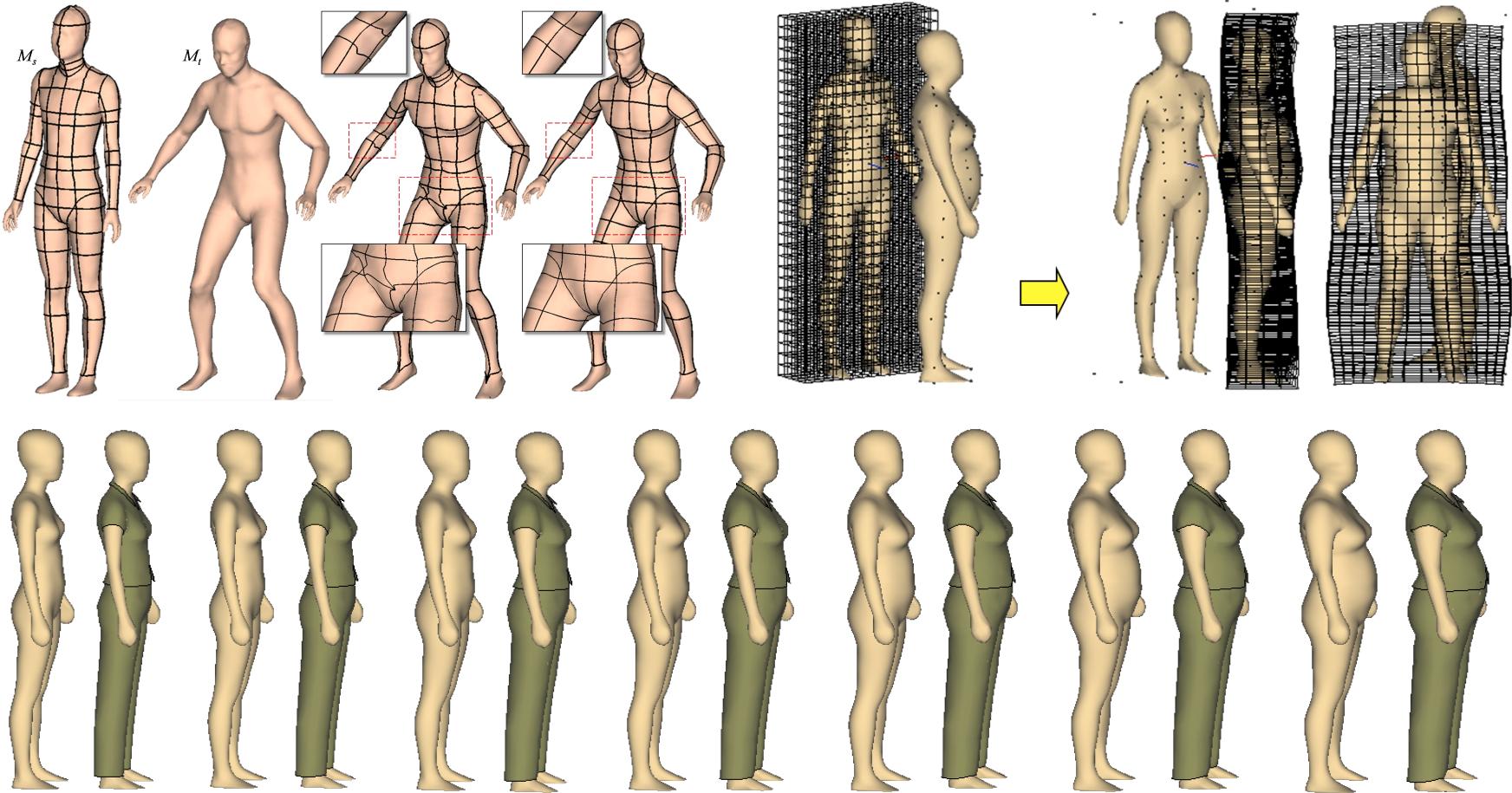
- ▶ Design automation in commercial CAD/CAM systems (parametric design)
  - ▶ Developed for products with **regular shape**
  - ▶ Usually driven by **dimensional parameters**
- ▶ Technology has been developed for overcoming these challenges – shape drive design automation
  - ▶ **Consistent** modeling of digital human bodies
  - ▶ Encoding/decoding the spatial relationship between **human body** and **product**
  - ▶ Geometric optimization for **fabrication**

Exoskeleton as a future product:  
**freeform geometry** and **conformal** to the shape of human body

# Design Automation: Consistent Modeling of Digital Human Bodies



# Design Automation: Design Transfer for Wearable Products



Charlie C.L. Wang, K.-C. Hui, and K.M. Tong, "Volume parameterization for design automation of customized free-form products", *IEEE Transactions on Automation Science and Engineering*, 2007.

# Design Automation for Personalized Wearable Products

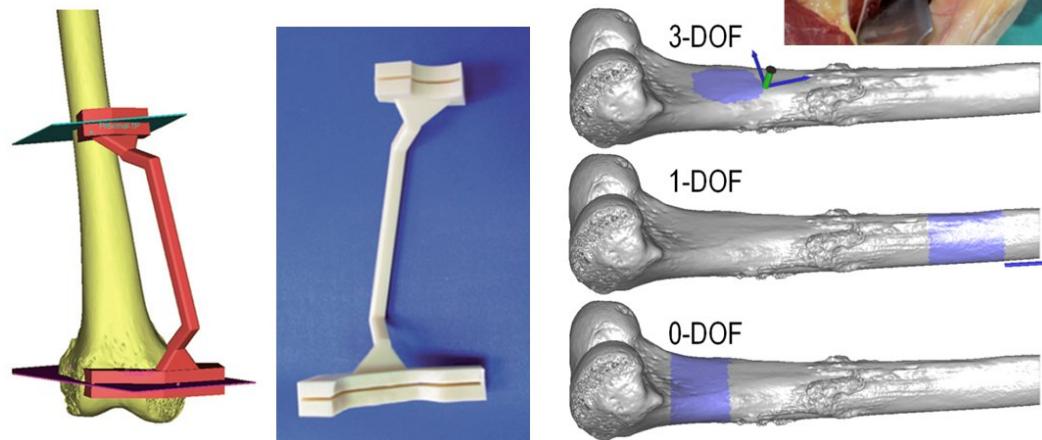
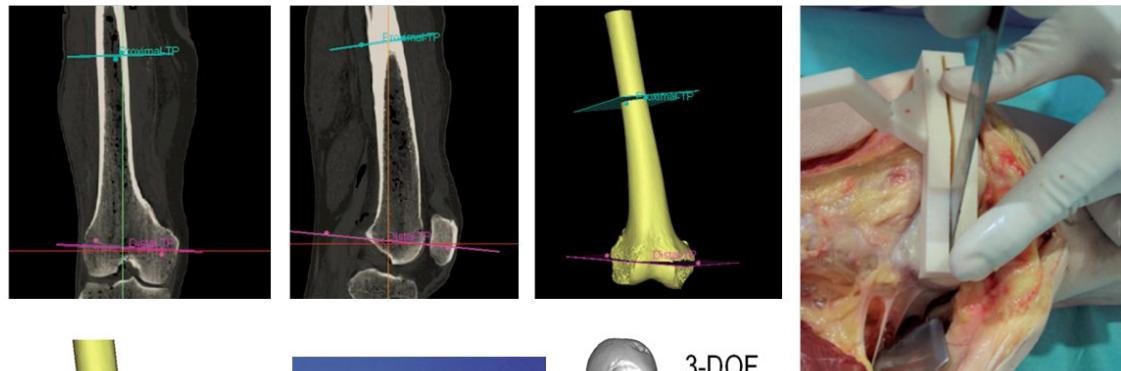
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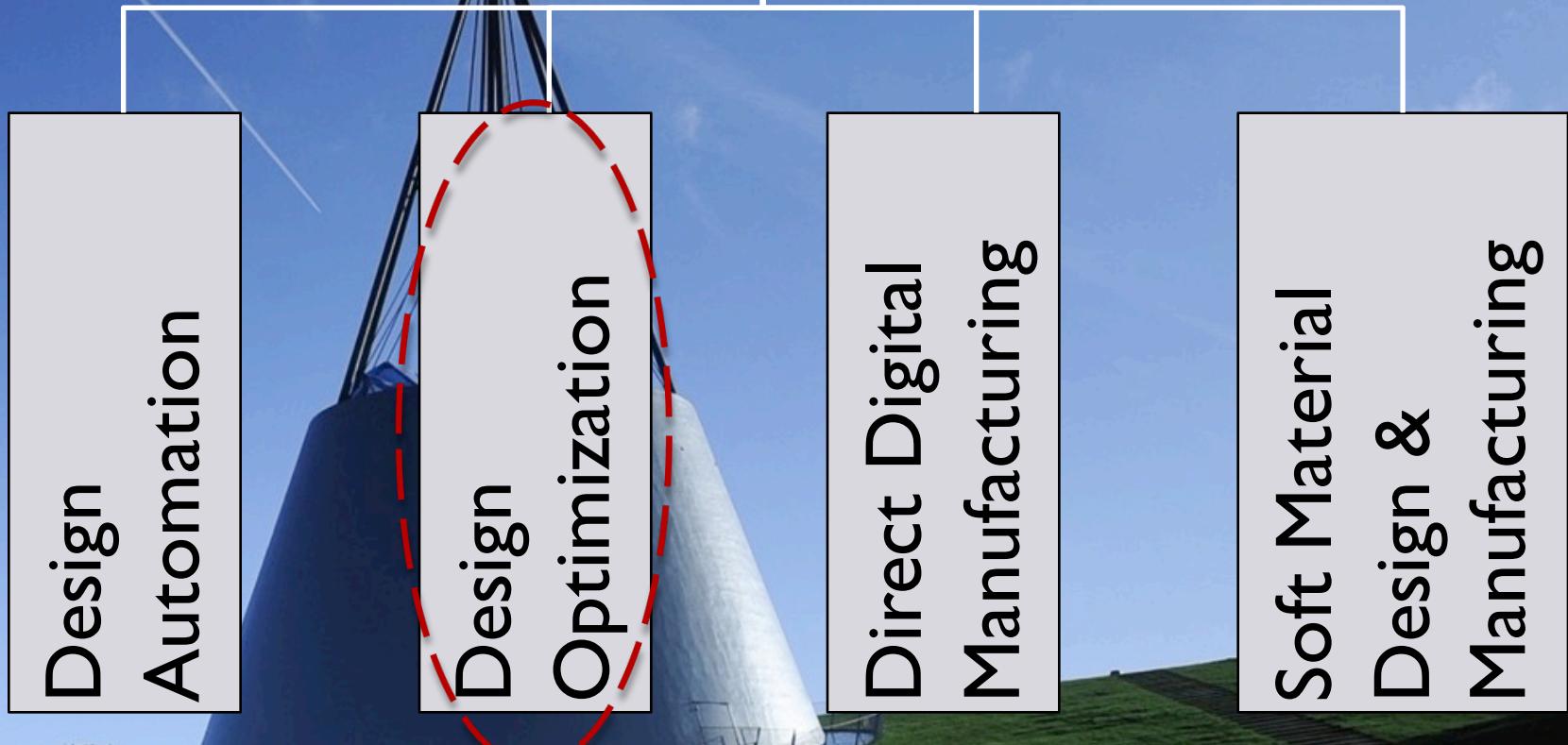
- 
- ▶ 8 **C.C.L. Wang, Y. Zhang, and H. Sheung**, "From designing products to fabricating them from planar materials", IEEE Computer Graphics and Applications, 2010.

# Design Automation: Searching for ‘Best’-Fit is General for All Wearable Instruments

- ▶ Computing **unique footprint** to align the image / patient coordinate systems – **Patient Specific Instruments (PSI)**
- ▶ Preoperatively planned resection path can be precisely realized

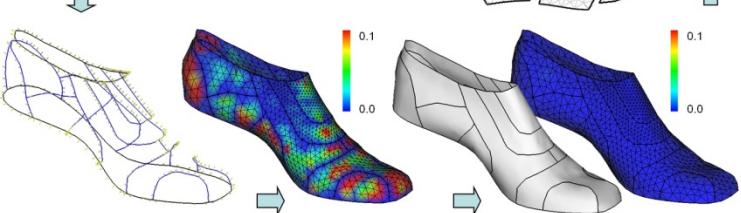
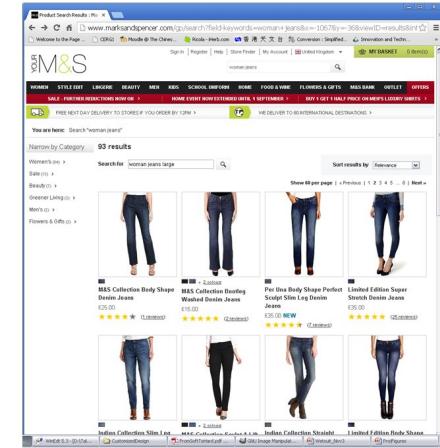
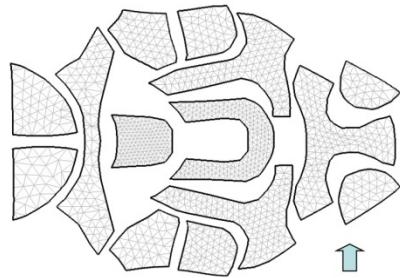
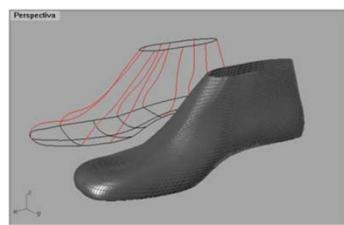


# Computational Design and Fabrication

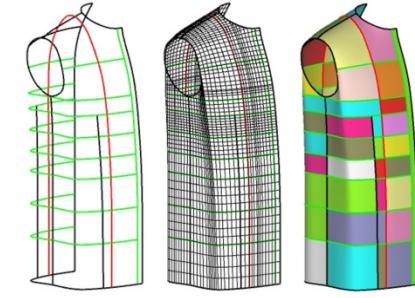
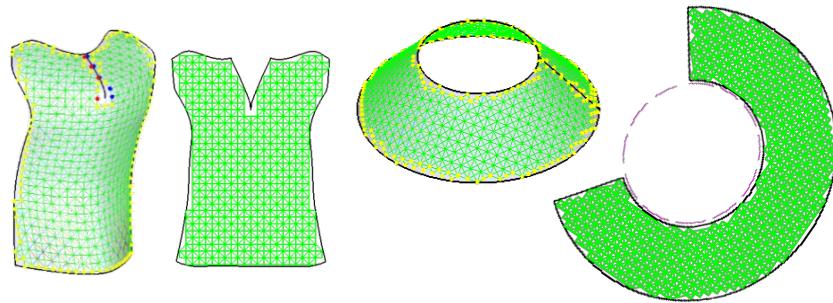


Geometric and Physical Modeling

# Design Optimization for Manufacturing (i): Flattening Solution for Planar Materials



WireWarping++



- Charlie C.L. Wang, "Methods for Flattening a 3D Surface into a 2D Piece", U.S. Patent 8,411,090, April 2, 2013.
- Yunbo Zhang, and Charlie C.L. Wang, "WireWarping++: Robust and flexible surface flattening with length control", *IEEE Transactions on Automation Science and Engineering*, vol.8, no.1, pp.205-215, 2011.
- Charlie C.L. Wang, "Towards flattenable mesh surfaces", *Computer-Aided Design*, vol.40, no.1, pp.109-122, 2008.

# Design Optimization for Manufacturing (ii): Flattening Solution for Glass Production



Figure 77: Mould of variation 2



Figure 78: Result of variation 2



Figure 83: Mould of variation 5



Figure 84: Result of variation 5



Figure 79: Mould of variation 3



Figure 80: Result of variation 3



Figure 85: Mould of variation 6



Figure 86: Result of variation 6



Figure 81: Mould of variation 4



Figure 82: Result of variation 4



Figure 87: 'Mould' of variation 7



Figure 88: Result of variation 7

# Design Optimization for Manufacturing (ii): Flattening Solution for Glass Production

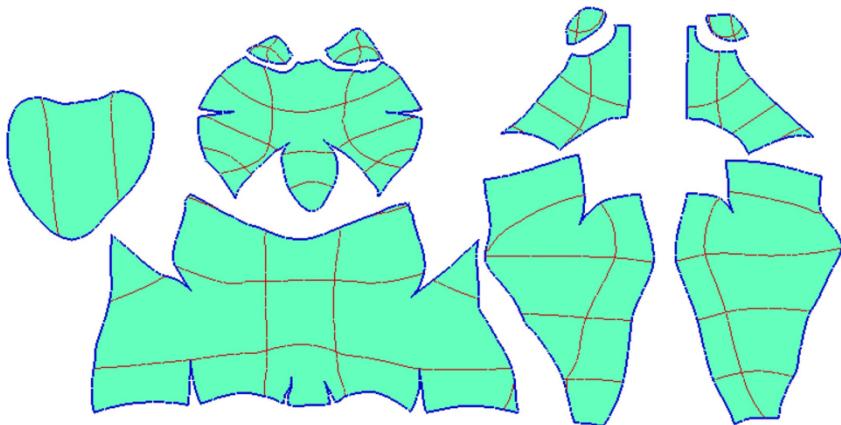
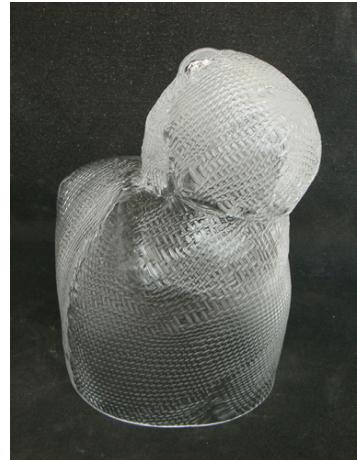
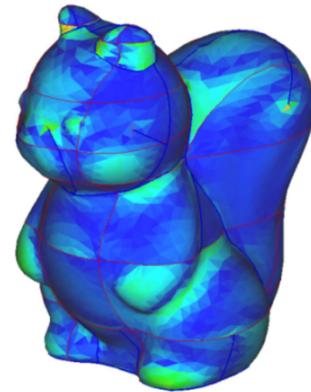
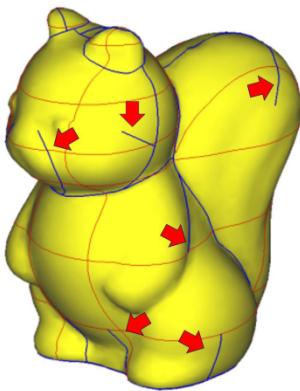
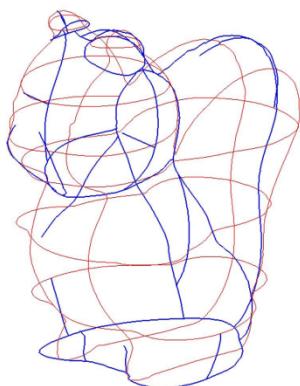


# Design Optimization for Manufacturing (ii): Flattening Solution for Glass Production



# Design Optimization for Manufacturing (ii): Flattening Solution for Glass Production

## ► Molding by carbon fibers



# Design Optimization for Manufacturing (ii): Flattening Solution for Glass Production



# 3D Printing is NOT Completely Flexible

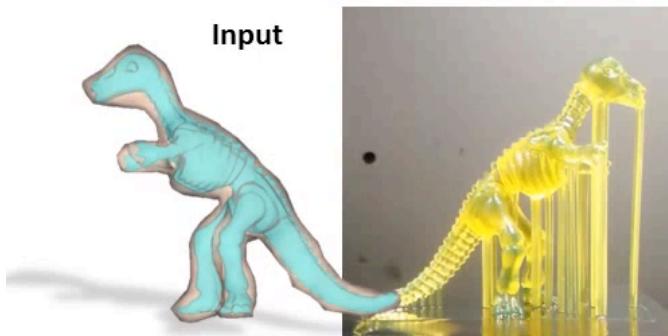
- ▶ Definition by ASTM for **Additive Manufacturing (AM)**
  - ▶ Process of joining materials to make objects from 3D model data, usually **layer upon layer**
- ▶ Good choice for personalized products
- ▶ **Overhangs – collapse during fabrication**
- ▶ Supporting structures – **hard to remove**



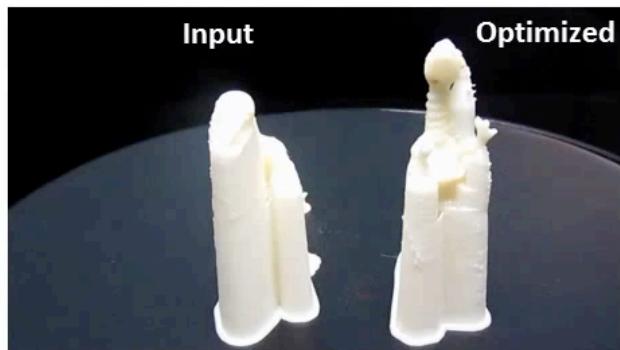
# Design Optimization for Manufacturing (iii): Deformation to Reduce Overhang

Reduce the usage of **support** by **deformation**

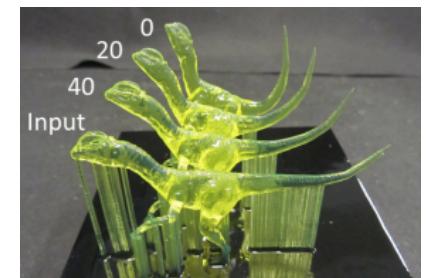
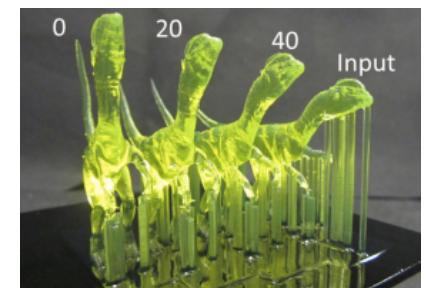
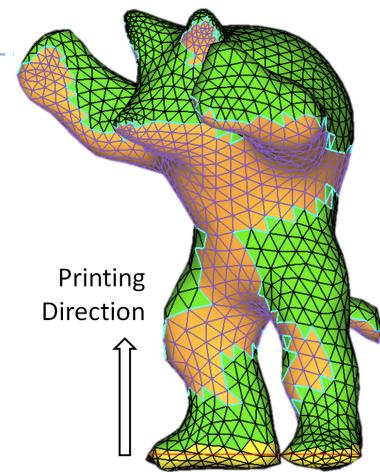
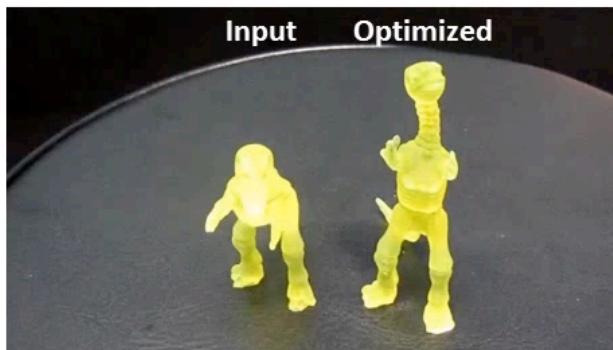
Dino



Fabricated by FDM

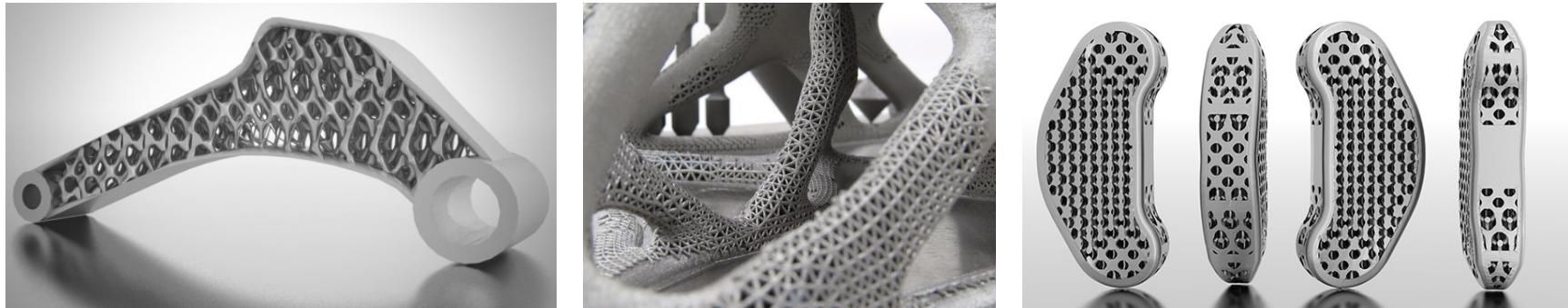


Fabricated by MIP-SLA



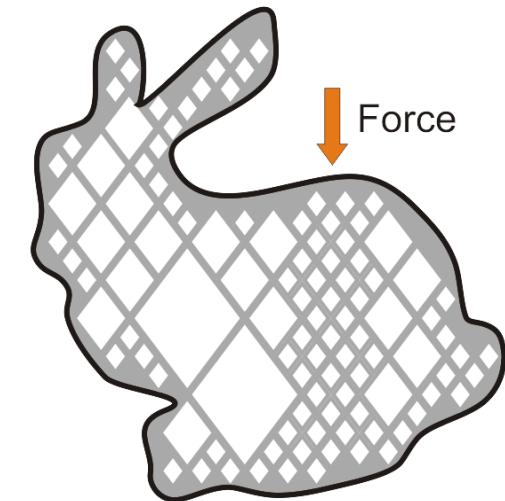
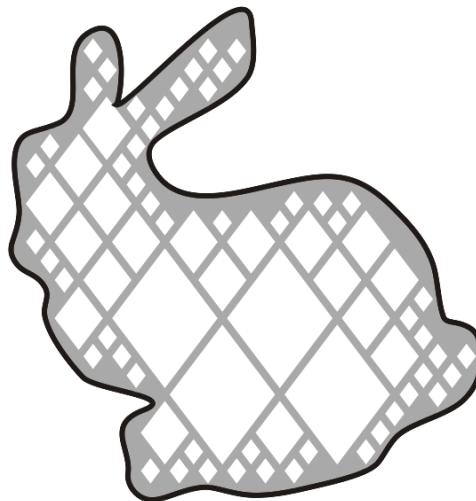
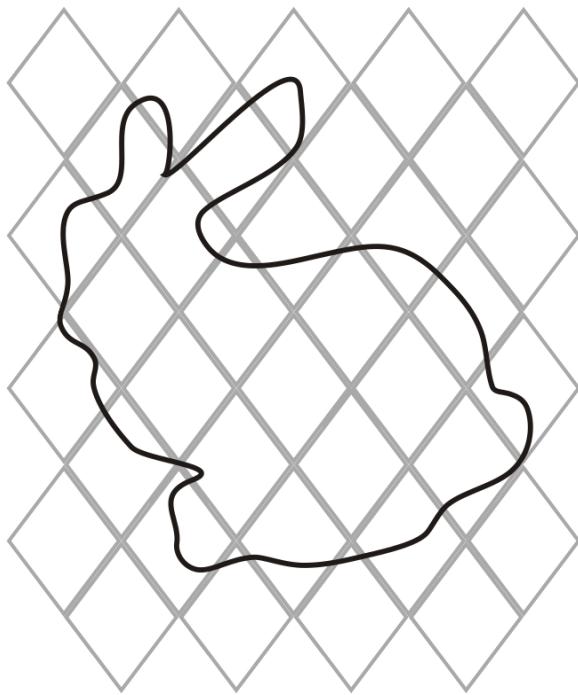
# Fabrication-Aware Design Optimization: Infill Optimization for Mechanical Strength

- ▶ A lot of recent work in topology optimization



- ▶ **Problem: Manufacturability?** Especially for infill
- ▶ **Our solution:** by restricting topology optimization to generate structures in a manufacturability-ensured space
  - ▶ Use of grid **refinement** and **grid-to-cell** operators to efficiently perform the optimization
  - ▶ **Manufacturable** structure ensured by **rhombic** structures
  - ▶ Optimization of **mechanical stiffness** effectively and efficiently

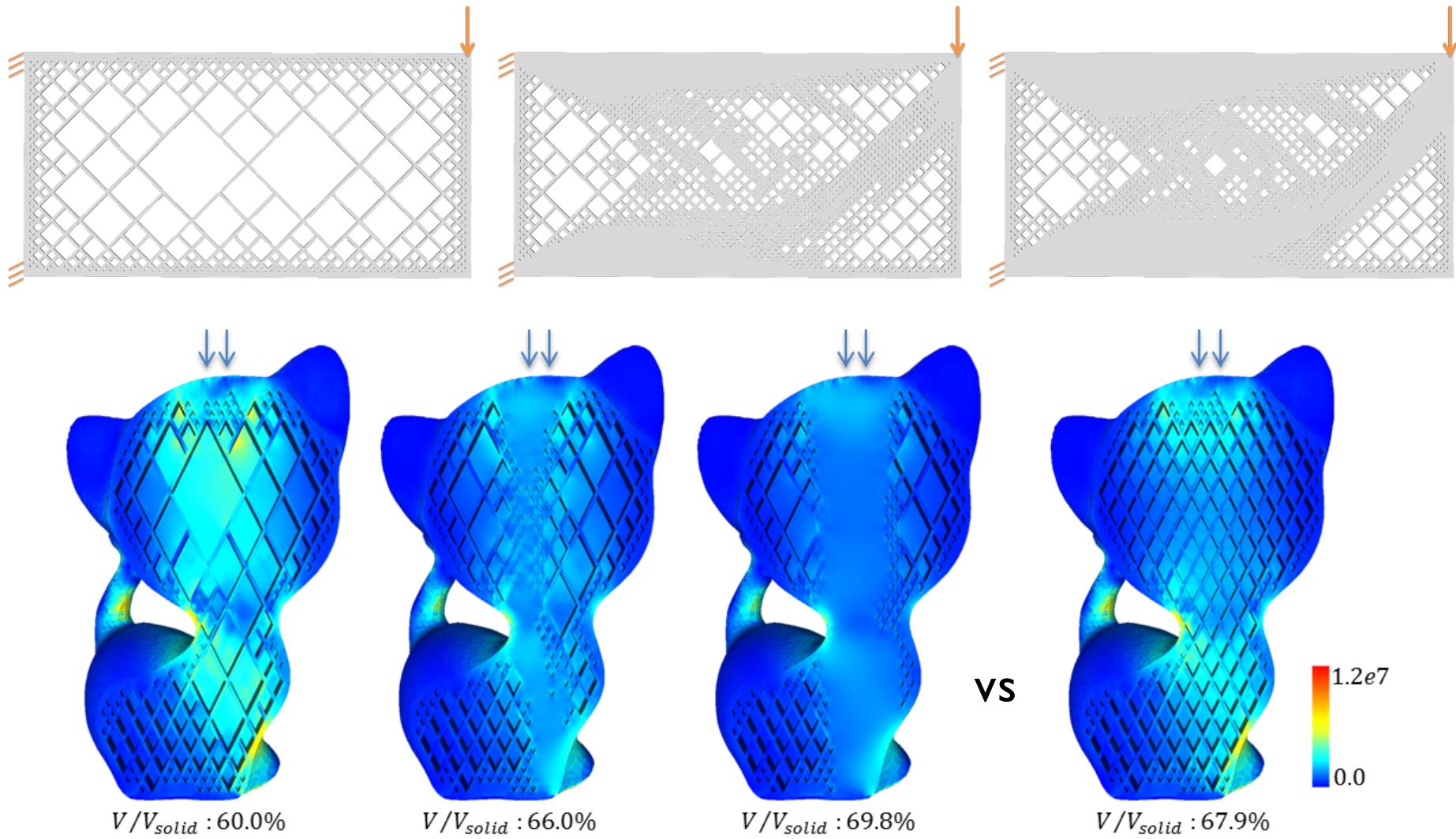
# Fabrication-Aware Design Optimization: Infill Optimization for Mechanical Strength



- ▶ An iterative process by sensitivity analysis:
  1. Finite Element Analysis of elasticity
  2. Evaluate the sensitivity
  3. Update the rhombic structure by subdividing selected cells

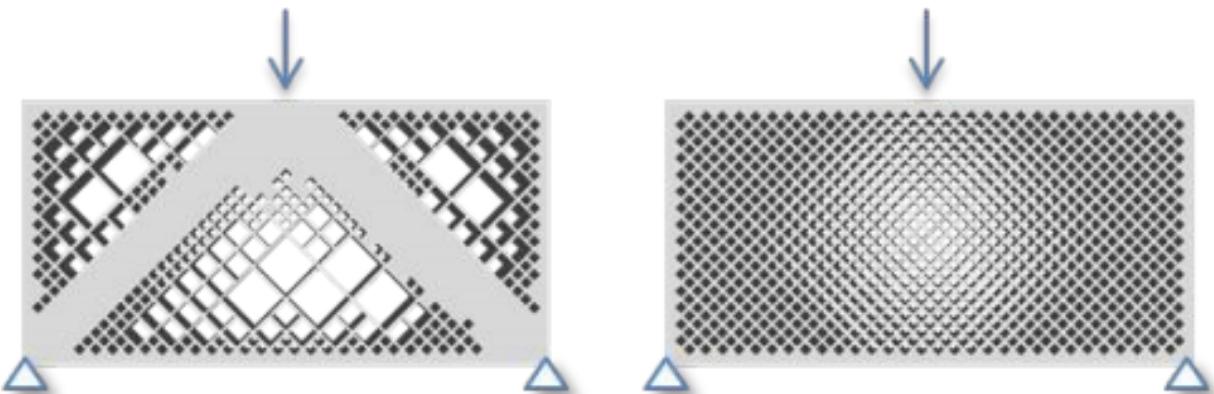
$$G_c = \frac{-\partial E / \partial \beta_c}{\partial V / \partial \beta_c}$$

# Fabrication-Aware Design Optimization: Infill Optimization for Mechanical Strength

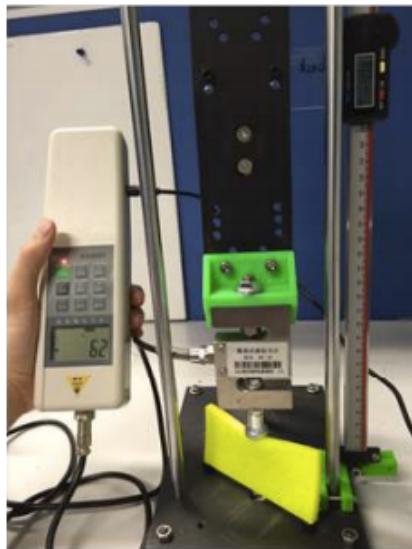


# Fabrication-Aware Design Optimization: Infill Optimization for Mechanical Strength

- ▶ Physical Tests  
(for comparison)



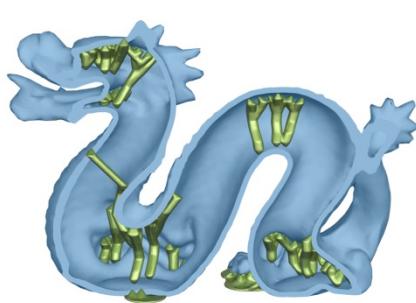
Applying the same loading (2.11 vs 4.08mm)



Under the same displacement (3mm)

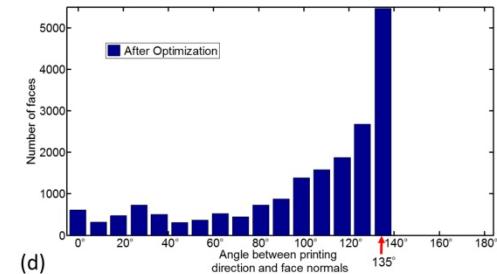
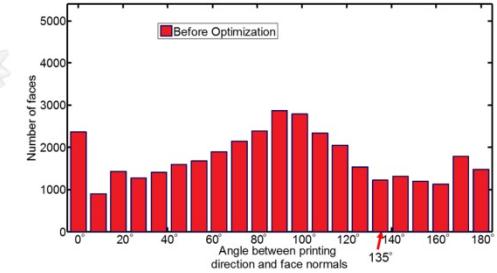
# Fabrication-Aware Design Optimization (ii): Support-Free Hollowing

- ▶ To further enhance the sparsity of infill structures
  - ▶ Support-free hollowing **operator** based on **layered** formulation
  - ▶ A **repetitive hollowing strategy** to enlarge the solution space
  - ▶ Intrinsic solution for physics optimization

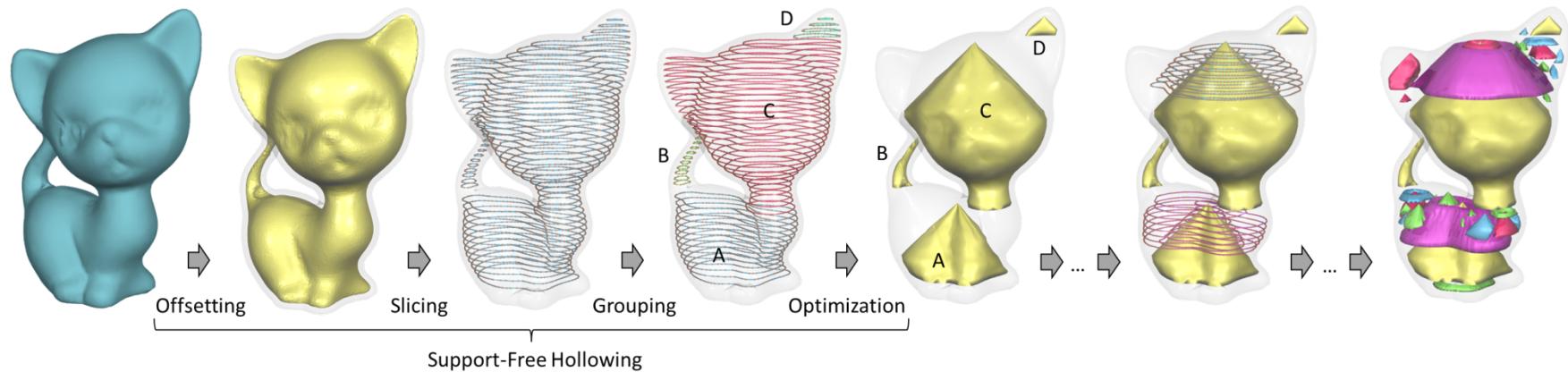


Reduce 38.0% Weight

Reduce 69.9% Weight

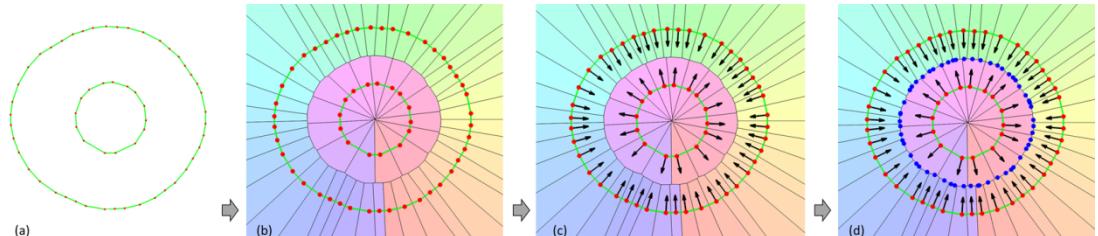


# Fabrication-Aware Design Optimization (ii): Support-Free Hollowing

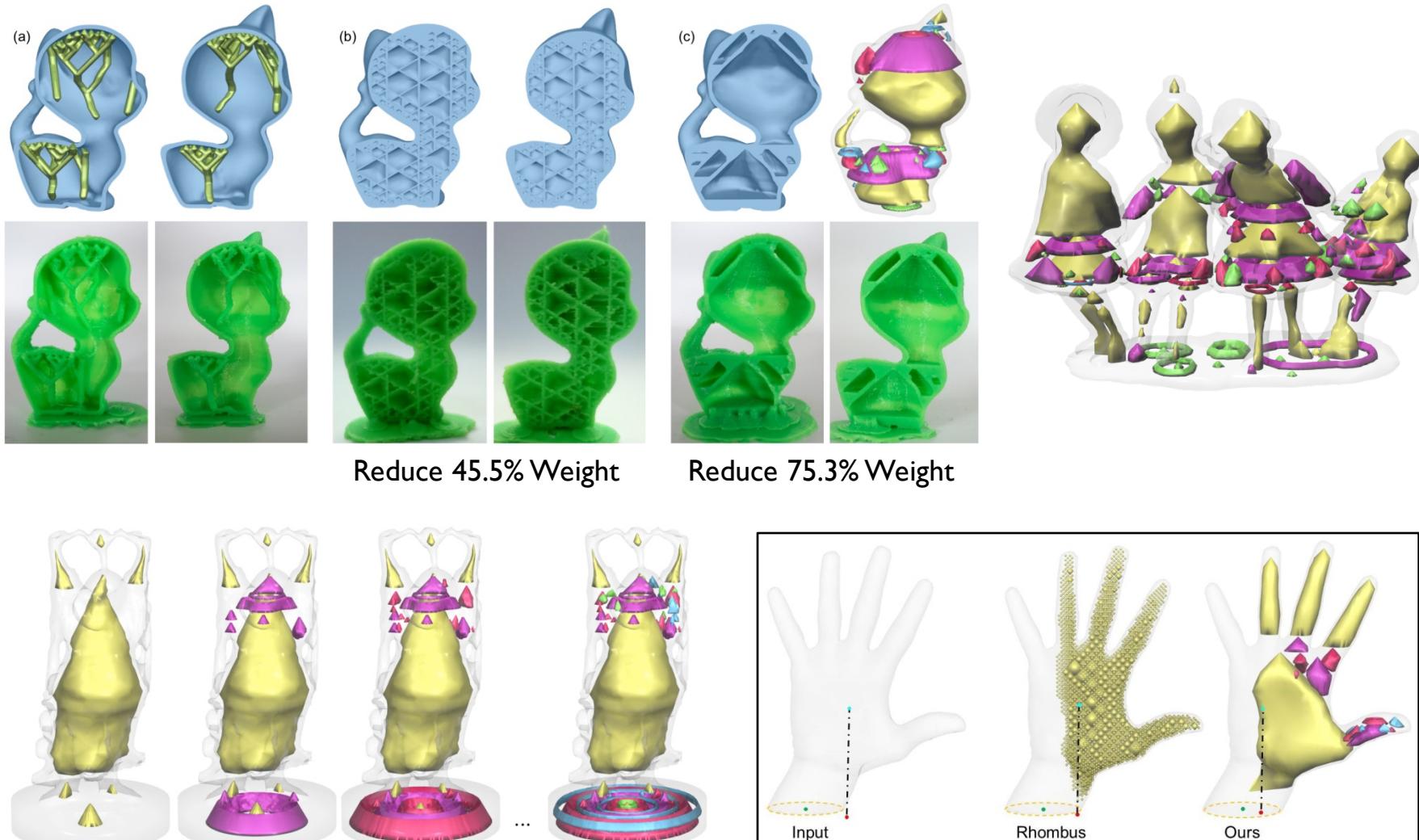


## ▶ Pipeline of iterative computation:

- ▶ Generate uniform offset surface as initial shape
- ▶ Slicing offset and **cluster** cross-sections into groups according to **topology** variation
- ▶ Planar Voronoi-Diagram governed collision-free optimization
- ▶ Repeat above steps



# Fabrication-Aware Design Optimization (ii): Support-Free Hollowing



# Optimization for Comfort: Thermal-Comfort Design of Personalized Casts

## Thermal-Comfort Design of Personalized Casts

Xiaoting Zhang<sup>1</sup>, Guoxin Fang<sup>2</sup>, Chengkai Dai<sup>2</sup>,  
Jouke Verlinden<sup>2</sup>, Jun Wu<sup>2</sup>, Emily Whiting<sup>1</sup>, Charlie C.L. Wang<sup>2</sup>

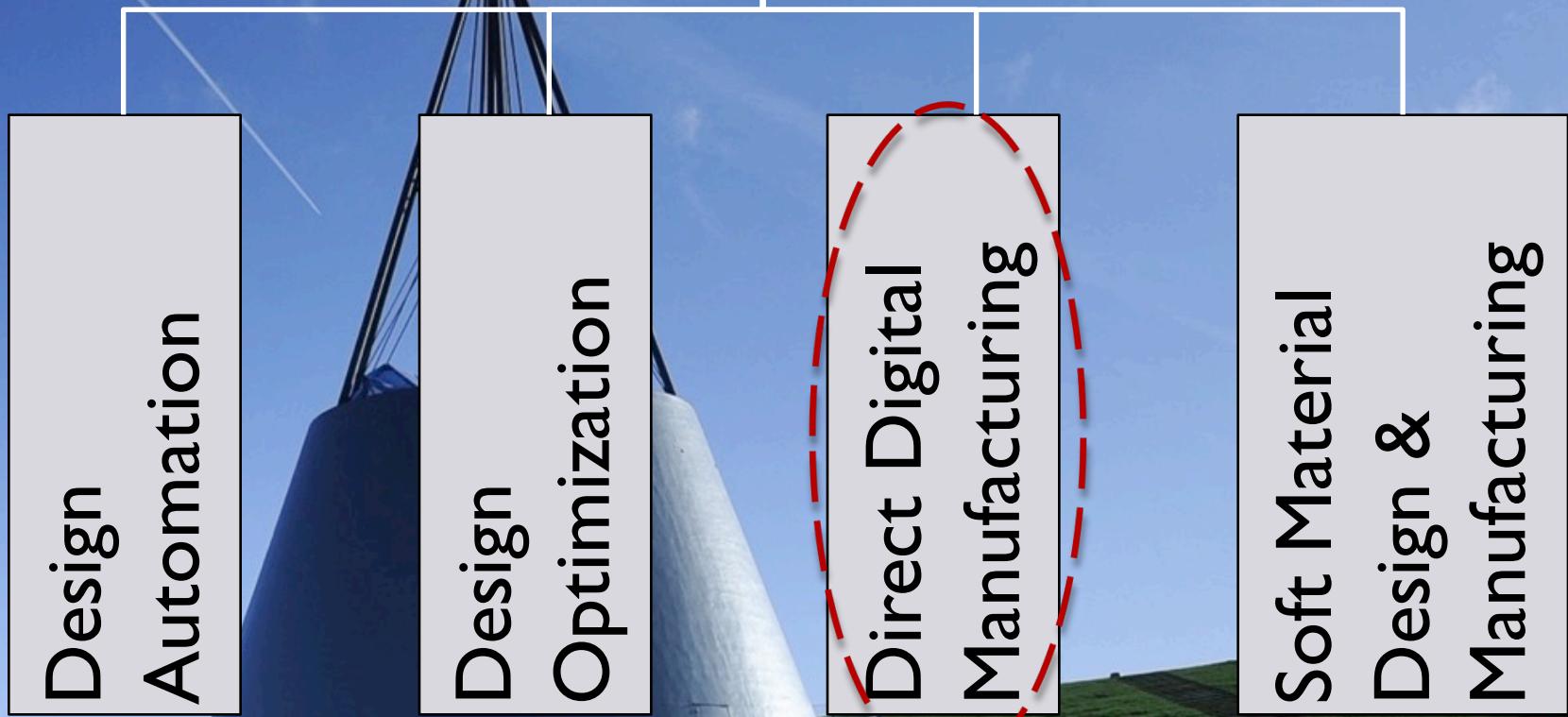
<sup>1</sup>Boston University

<sup>2</sup>TU Delft

ACM User Interface Software and Technology Symposium (UIST) 2017

- 26 X. Zhang, G. Fang, C. Dai, J. Verlinden, J. Wu, E. Whiting, and **C.C.L. Wang**, "Thermal-comfort design of personalized casts", *ACM Symposium on User Interface Software and Technology (UIST)*, 2017, accepted.

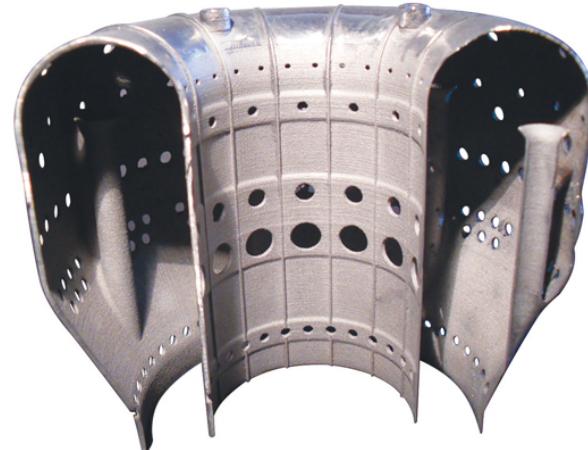
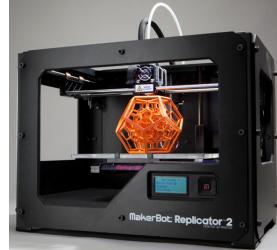
# Computational Design and Fabrication



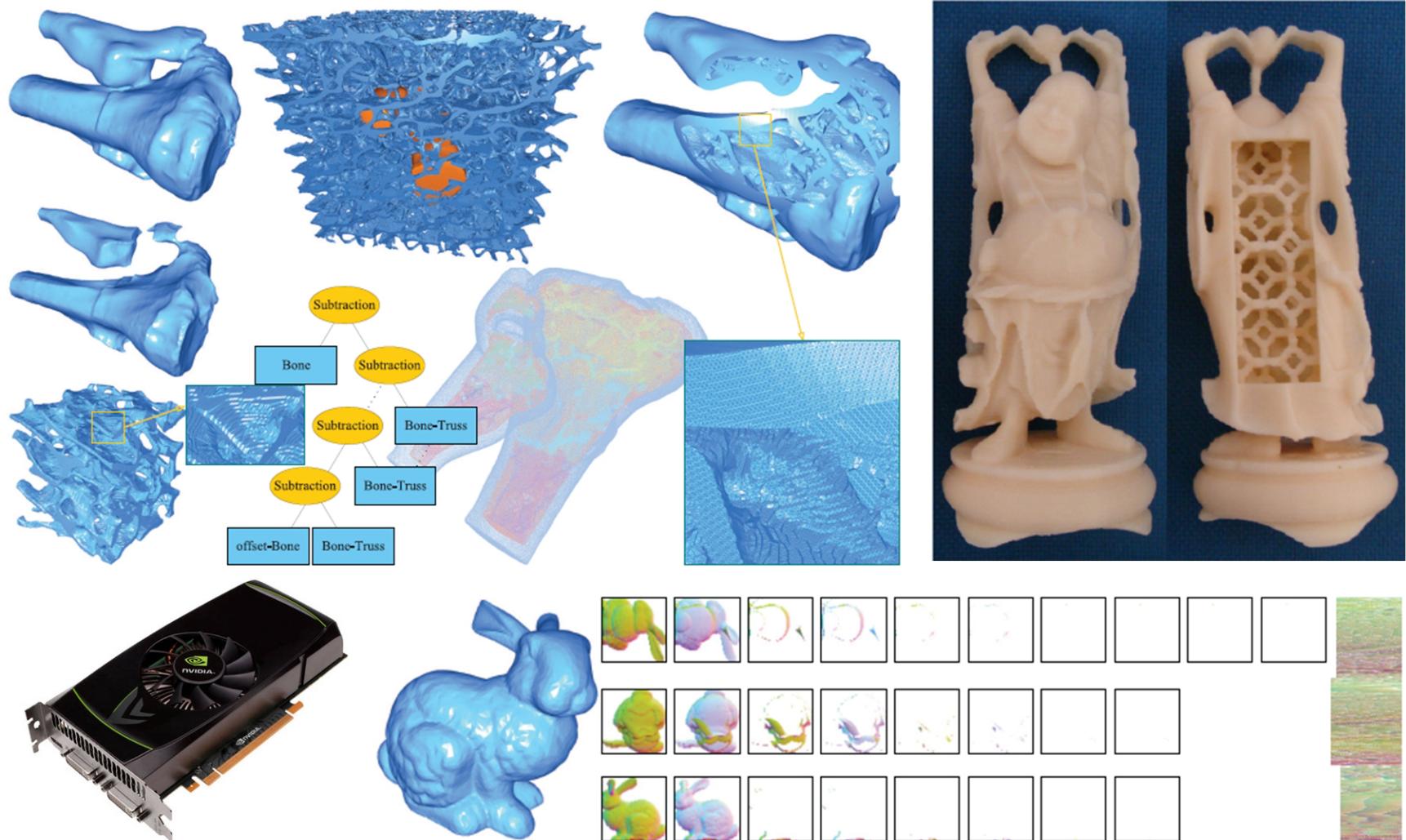
Geometric and Physical Modeling

# Direct Digital Manufacturing: Benefit and Challenge

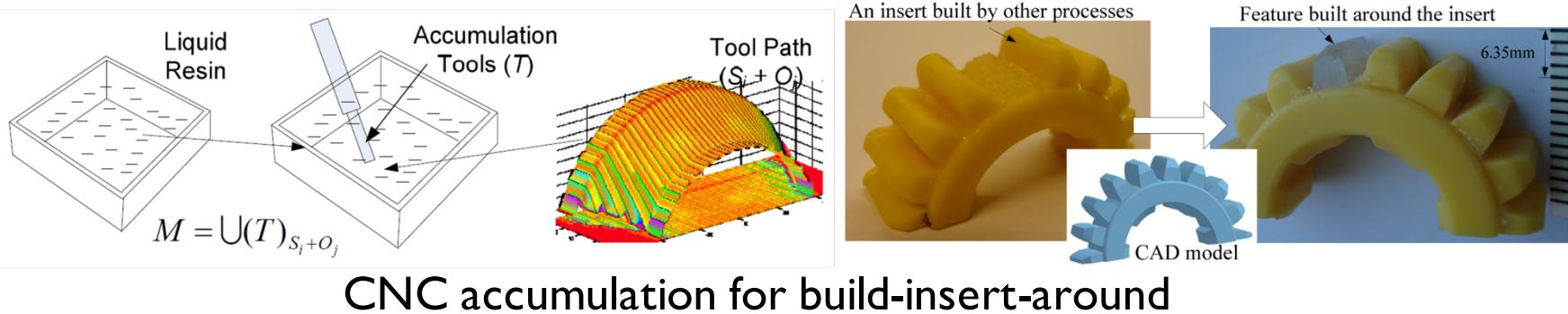
- ▶ Advantages: **flexibility** of fabricating complex shape and structure
- ▶ **Software for Computational Fabrication** becomes a **bottleneck** for new manufacturing methods
  - ▶ A **new modeling kernel** for complex shape and topology
  - ▶ **Control & optimization** for new manufacturing processes



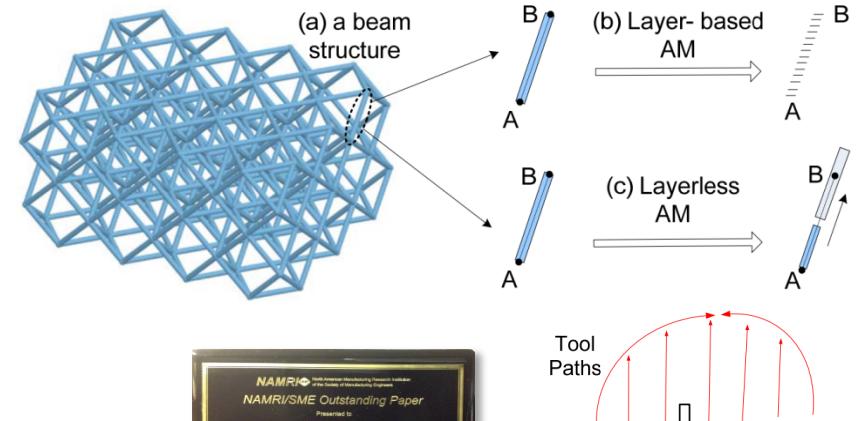
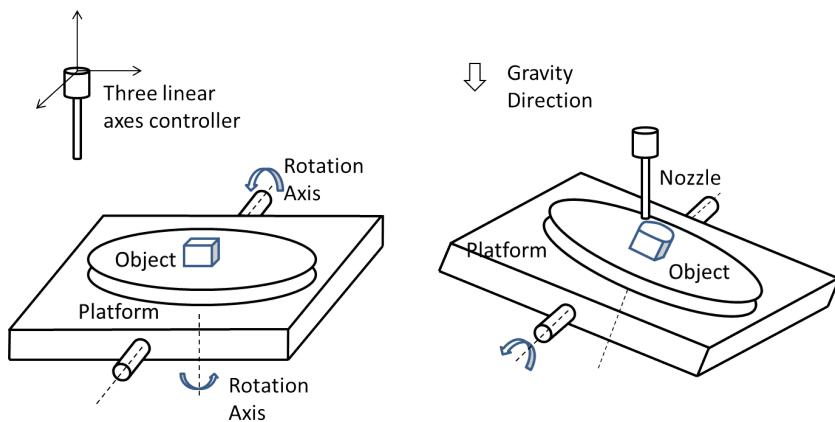
# Geometric Kernel for 3D Printing: Highly Parallel Solid Modeling on GPUs



# 2.5D vs. 3D Printing: Simple or More DOF?

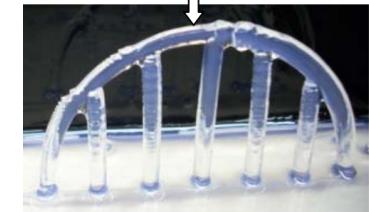


CNC accumulation for build-insert-around



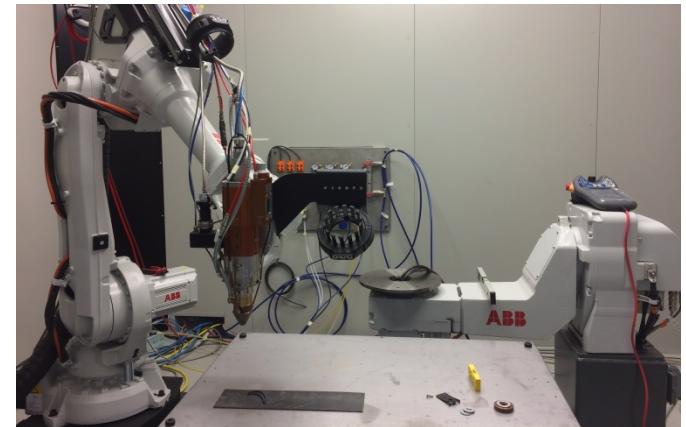
## Develop a new non-layered AM

- Fused Deposition Modeling (FDM)
- Multi-axis motion introducing more flexibility

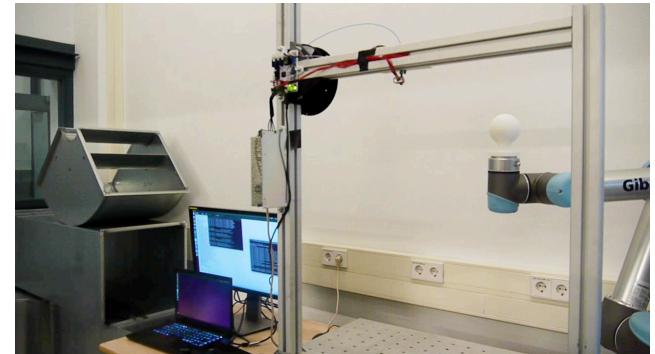
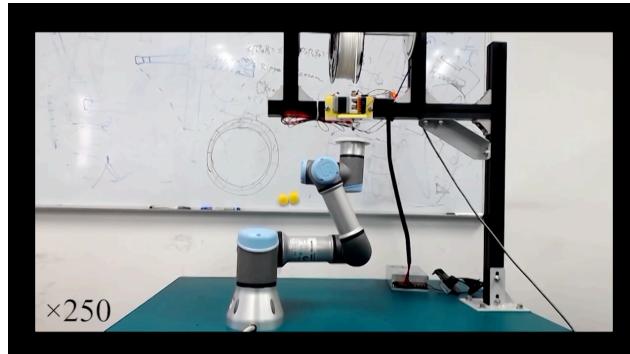


# Robot-Assisted Multi-Axis AM

- ▶ Using robot arms as device for motion control in AM
- ▶ Collaborative operations on two arms – **More DoFs** to fabricate curved regions / layers
- ▶ Challenges:
  - ▶ Model **decomposition**
  - ▶ **Collision-free** tool path generation
  - ▶ Configurations in **joint-angle** space



vs



# Decomposition by 3-half-half Axis AM

## RoboFDM: A Robotic System for Support-Free Fabrication using FDM

Chenming Wu<sup>1\*</sup>, Chengkai Dai<sup>2\*</sup>, Guoxin Fang<sup>2</sup>,  
Yong-Jin Liu<sup>1</sup> and Charlie C.L. Wang<sup>2†</sup>

1. TNList, Department of Computer Science and Technology, Tsinghua University
  2. Department of Design Engineering and TU Delft Robotics Institute, Delft University of Technology
- \* Contributed equally   † Corresponding Author

# Field-Governed 5DOF Volume Printing



GENERATIONS/  
SIGGRAPH 2018  
VANCOUVER  
12-16 AUGUST

## Support-Free Volume Printing by Multi-Axis Motion

Chengkai Dai<sup>1</sup> Charlie C.L. Wang<sup>1\*</sup> Chenming Wu<sup>2</sup> Sylvain Lefebvre<sup>3</sup>  
Guoxin Fang<sup>1</sup> Yong-Jin Liu<sup>2</sup>

<sup>1</sup>Delft University of Technology

<sup>2</sup>Tsinghua University

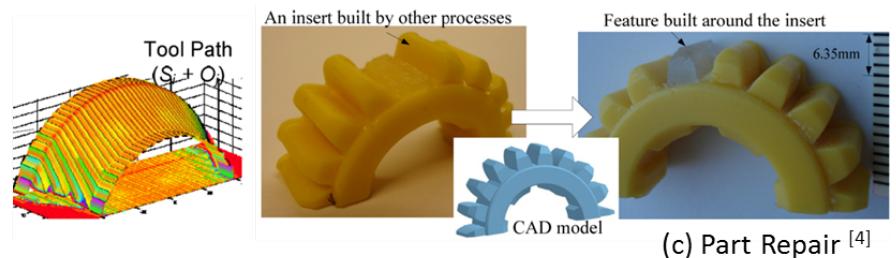
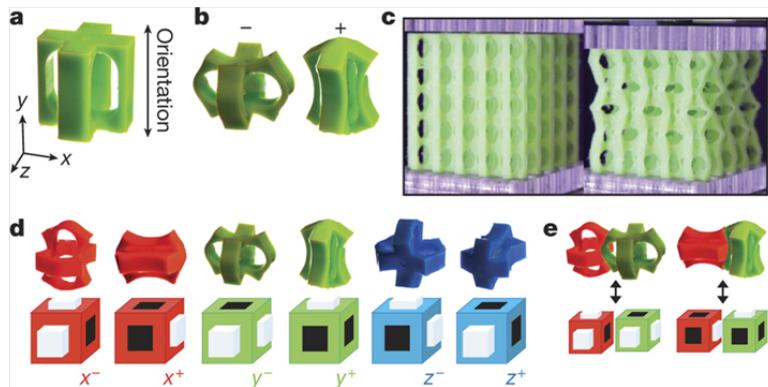
<sup>3</sup>Inria

\*Corresponding Author

- 33 C. Dai, C.C.L. Wang, C. Wu, S. Lefebvre, G. Fang, and Y. Liu, "Support-free volume printing by multi-axis motion", ACM Transactions on Graphics (SIGGRAPH 2018).

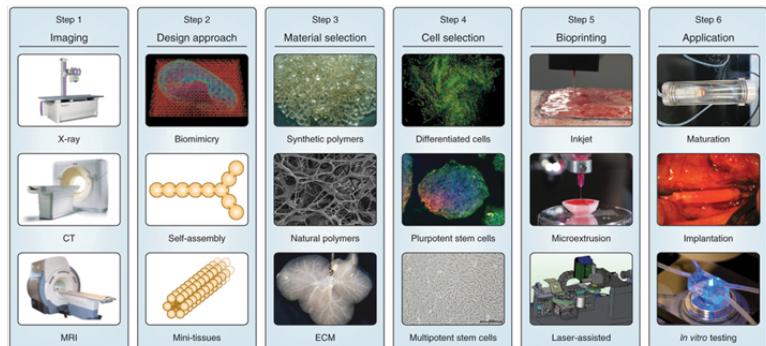
# Impact of Developing “Real” 3D Printing

- ▶ Accumulating materials in **space** but not **planar layers**



Multi-Axis Additive  
Manufacturing  
(Next Generation of  
3D Printing)

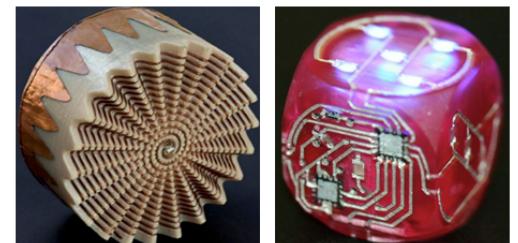
Geometric Computing



(b) Tissue Engineering [3] (Life Science)



(e) Large-Scale Construction [6]



(f) Printing Electronics [8]

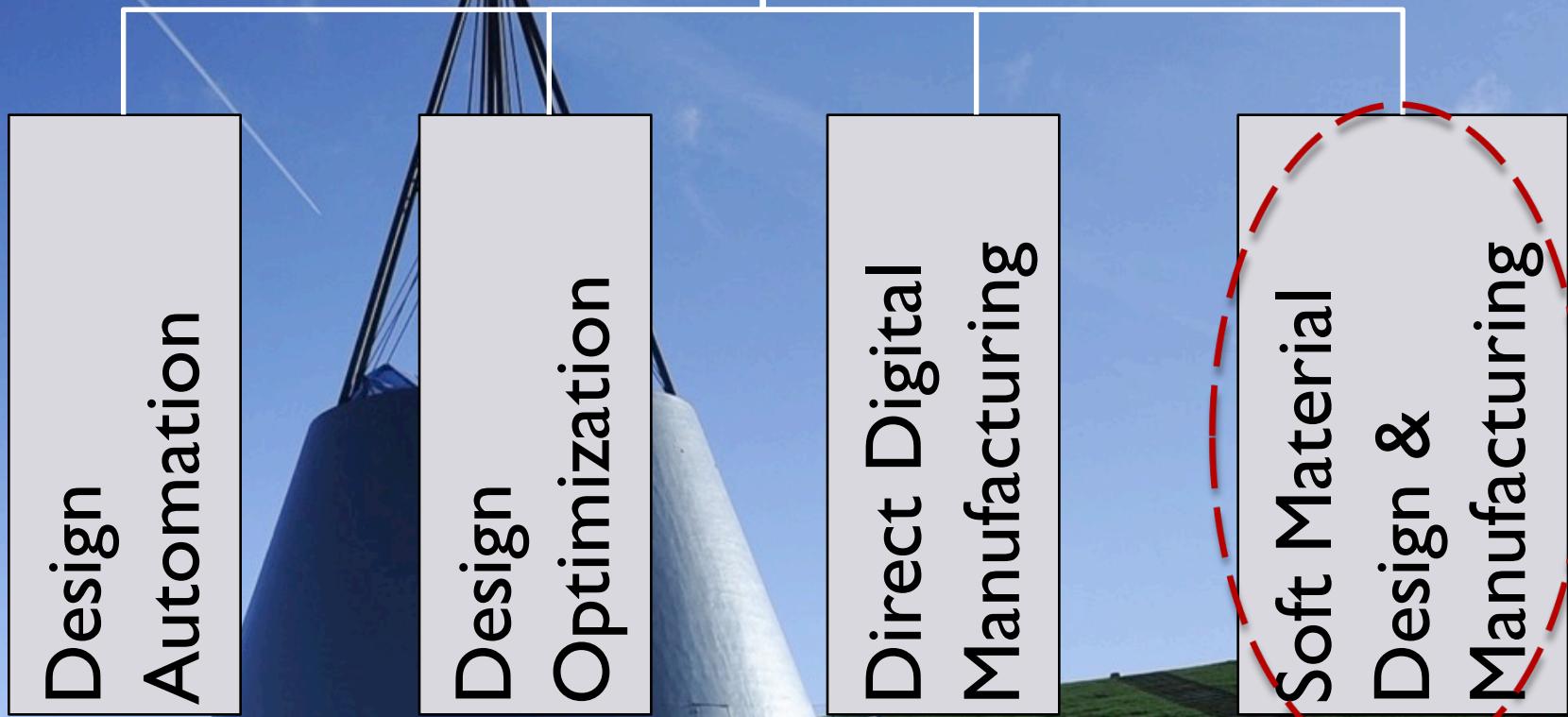
# From 3D to 4D Printing

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- ▶ 3D Printed **Self-Assembly** Structures
- ▶ How to **predict** the shape of fabricated model?
- ▶ Pattern Design / Process Optimization / New Triggers



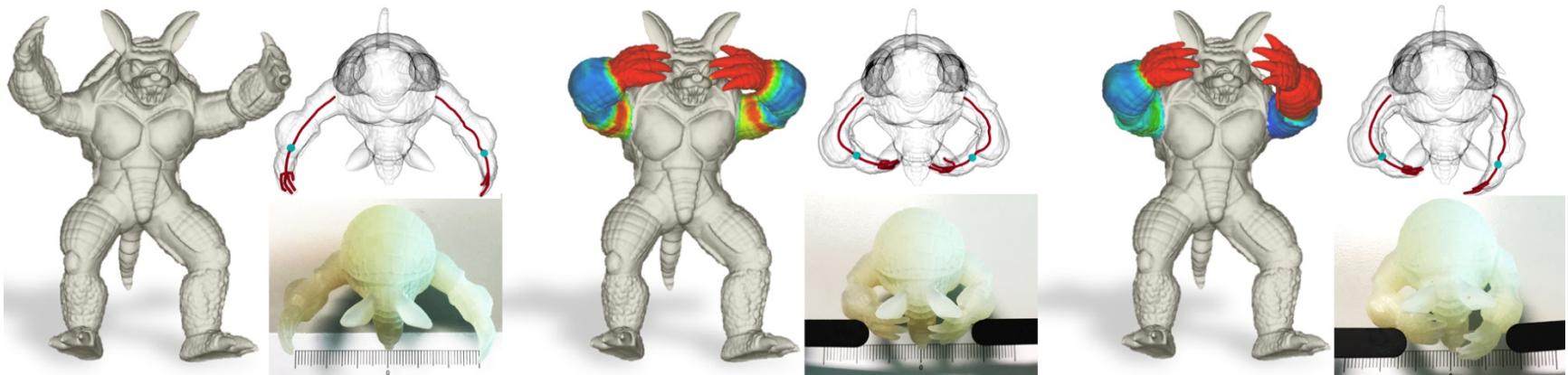
# Computational Design and Fabrication



Geometric and Physical Modeling

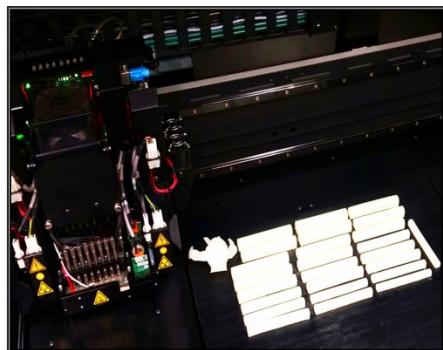
# Deformation Behavior Design by Materials

- ▶ 3D printing with elastomers => Deformation Behavior?
- ▶ Applications: personalized products, toys and soft robotics
- ▶ Different external forces lead to five different loads:
  - ▶ Bending, Compression, Shear, Tension and Torsion
  - ▶ Bending gives the most **visible change** to shapes
- ▶ We provide – an interactive tool to design bending behavior
  - ▶ Non-uniform hollowing on **generalized cylindrical** shapes

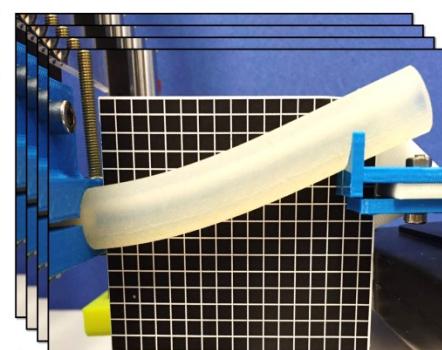


# Data-Driven Approach – Learning Function of Local Bending w.r.t. Shell Thickness

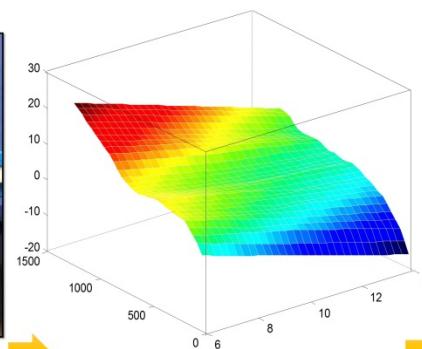
- ▶ Variable for bending behavior design: thickness of hollowing
- ▶ An interface to design the bending behavior – ID skeleton
- ▶ Offload time-consuming steps to the phase of learning
- ▶ Challenge:
  - ▶ To match the desired bending behavior
  - ▶ A function with elasticity, thickness & dimension of cross-section



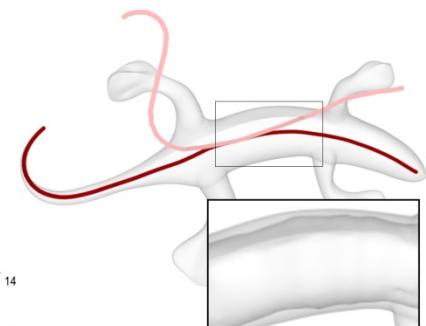
Data Acquisition



Learning

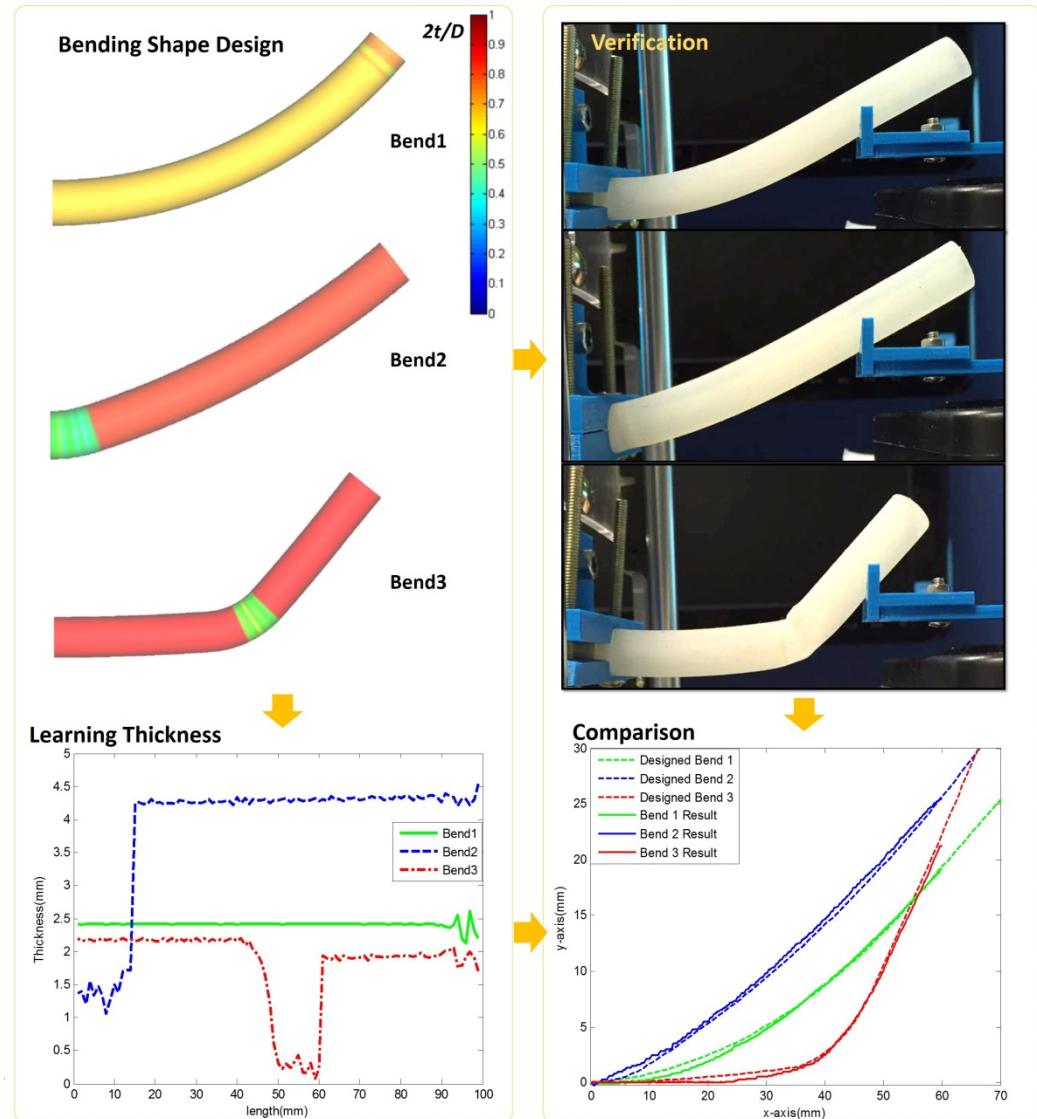


Shape Modeling



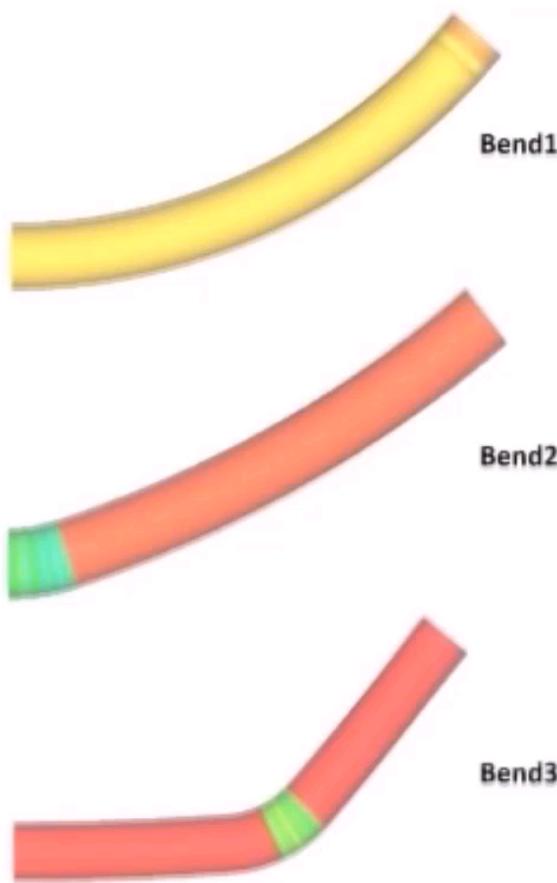
# Result: Verification on Tubes

- ▶ Easy Interface

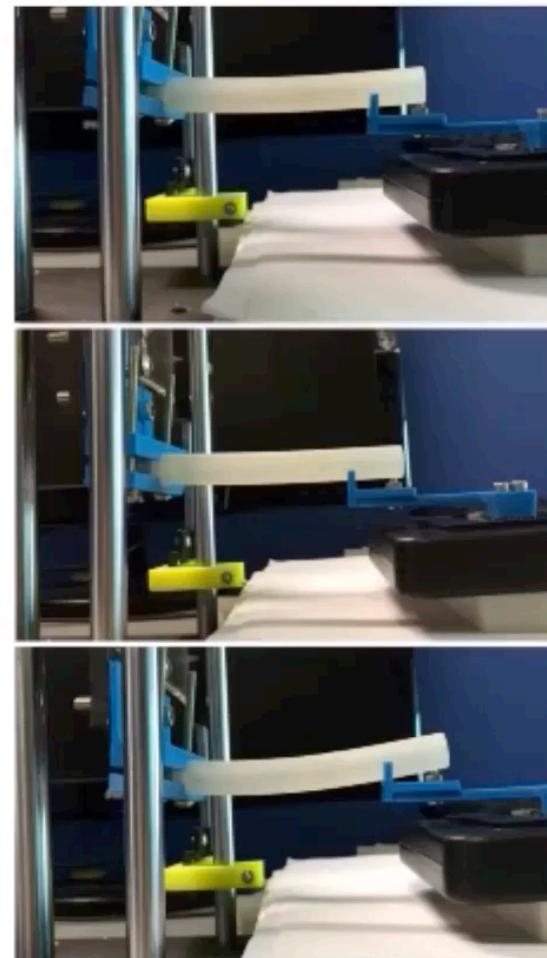


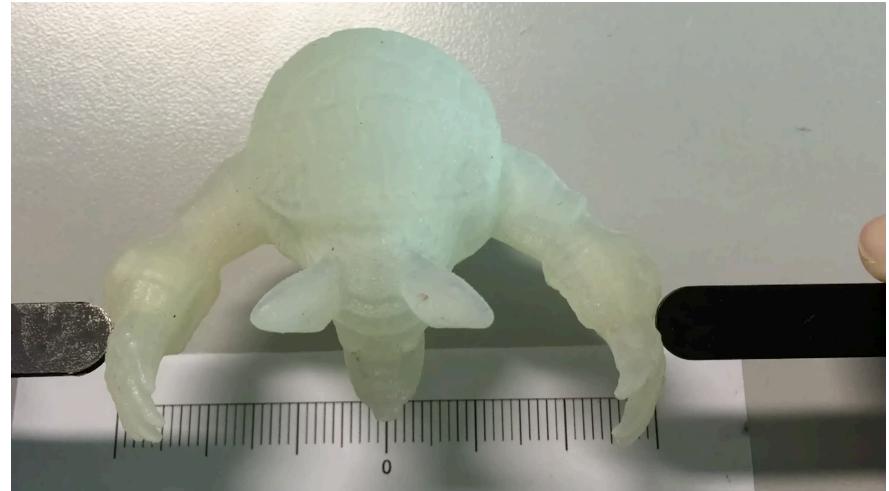
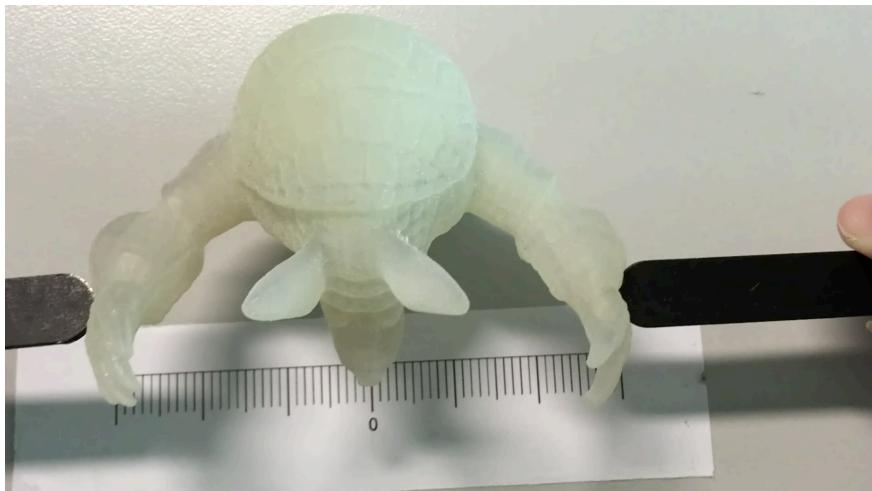
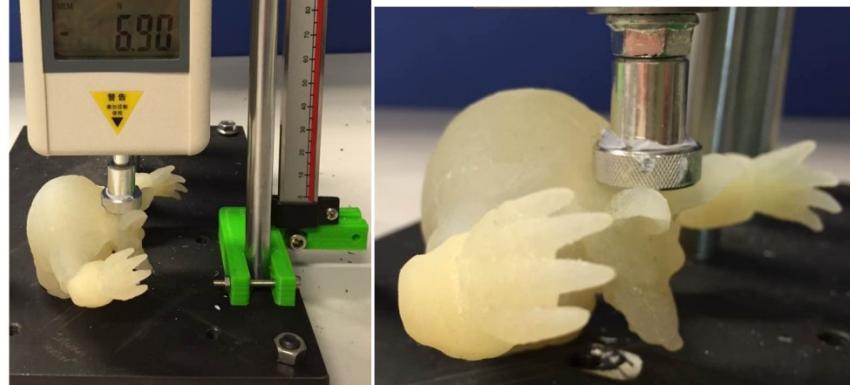
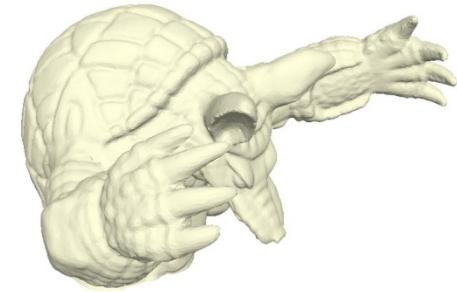
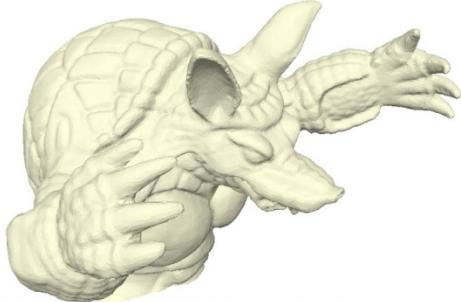
- ▶ Different behaviors
- ▶ Physical tests **match** designed behavior???

- Design

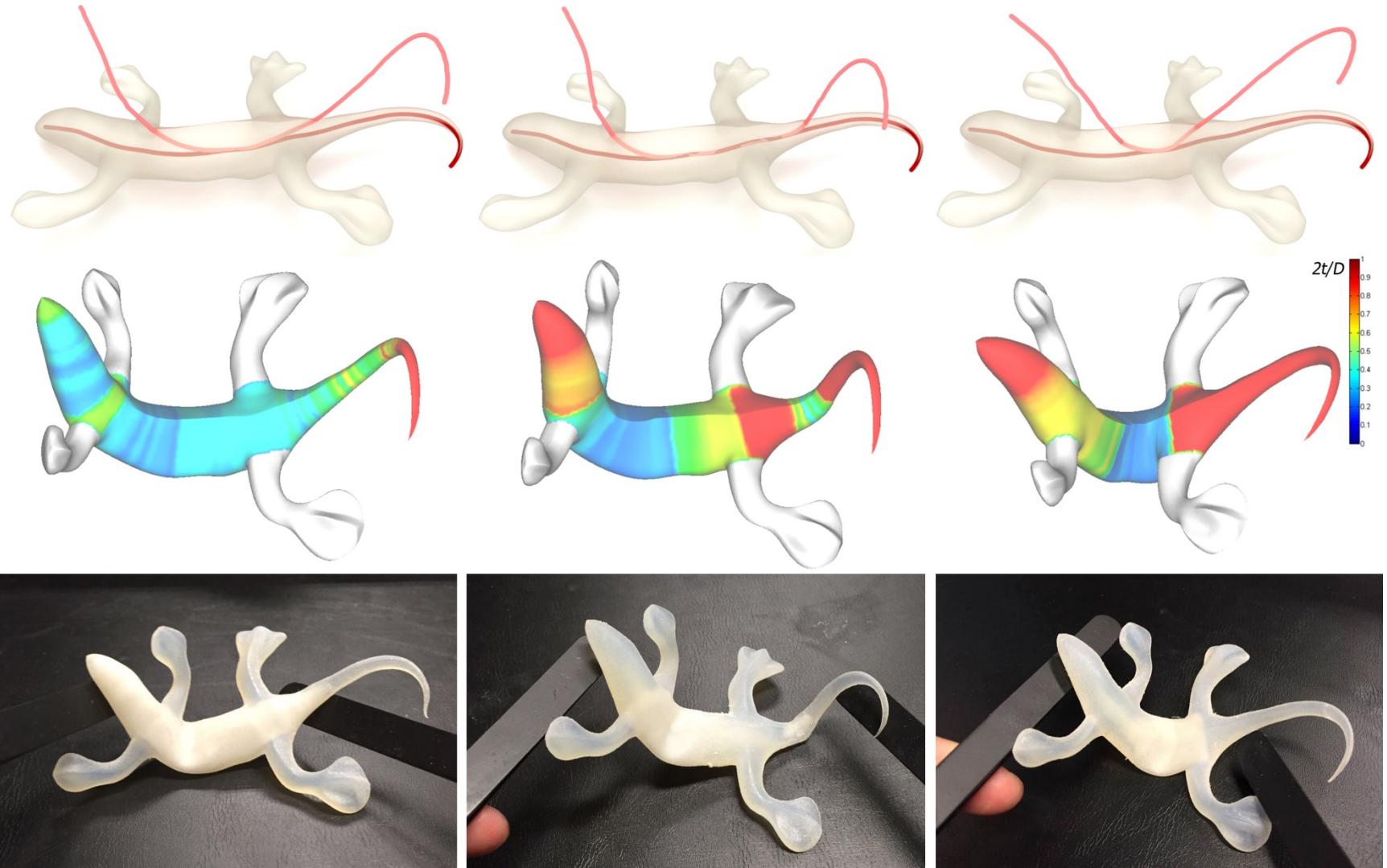


- Test



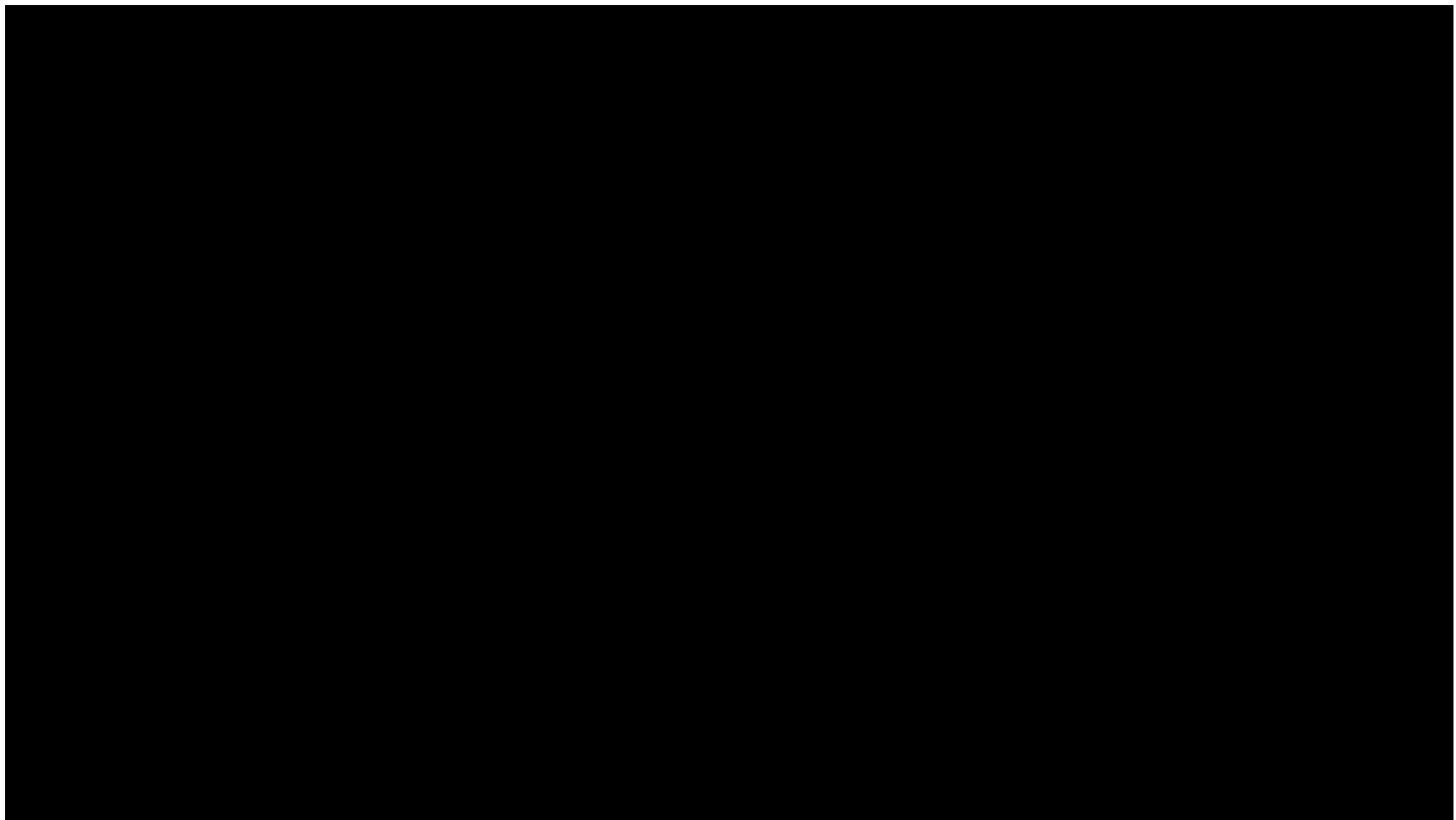


# Result: Models with Complex Shape



# Direct Digital Manufacturing for Soft Robotics

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# Designing Deformation Behaviors for Soft Grippers

- ▶ Soft robotics application for better grippers
- ▶ Deformation behavior can also be influenced by the material distribution (Multi-Material Printing)



Parameterize  
Deformation  
Behavior  
under:

- Bending
- Twisting
- Stretching

# Behavior Design by Multi-Material AM

## Designing Coupled Behavior of 3D-Printed Heterogeneous Materials for Soft Robotics

*Rob B.N. Scharff, Eugeni L. Doubrovski, Jan de Boer, Yu  
Song, Jouke C. Verlinden, Charlie C.L. Wang*

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# Sensing of Bending Deformation

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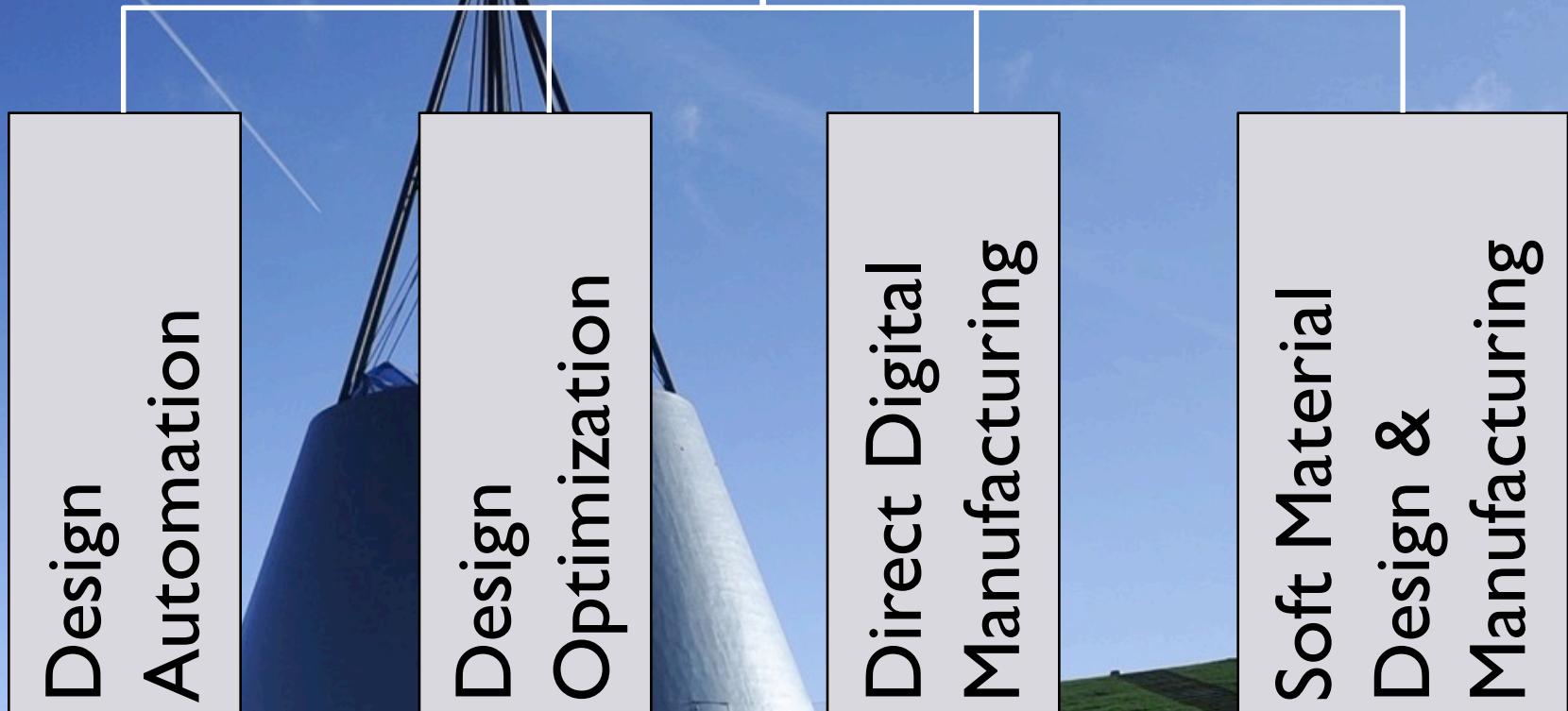
## Color-Based Sensing of Bending Deformation on Soft Robots

Scharff, R.B., Doornbusch, R.M., Klootwijk X.L., Doshi A.A.,  
Dobrovski, E.L., Wu, J., Geraedts, J.M., Wang, C.C.\*

\*Corresponding author: C.C.Wang@tudelft.nl



# Computational Design and Fabrication



Geometric and Physical Modeling