

L12 - Generative Design

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Additive Manufacturing

- ▶ Defined by ASTM as:
 - ▶ Process of joining materials to make objects from 3D model data, usually layer upon layer
- ▶ Six Different Types of AM:
 - ▶ Lasers: Stereolithography Apparatus (**SLA**), Selective Laser Sintering (**SLS**)
 - ▶ Nozzles: Fused Deposition Modeling (**FDM**)
 - ▶ Print-heads: Multi-jet Modeling (**MJM**), Binder-jet Printing (**3DP**)
 - ▶ Cutters: Laminated Object Modeling (**LOM**)
- ▶ Mainly used for **Rapid Prototyping (Past)**
- ▶ More and More used for ‘Mass’-Production (**Present**)



Example of Printed Consumer Products

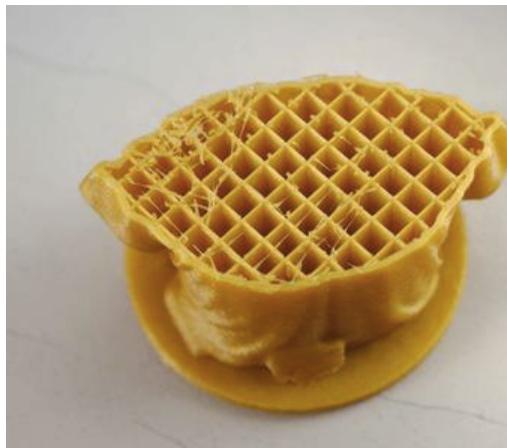


Boeing Air-Ducting Parts

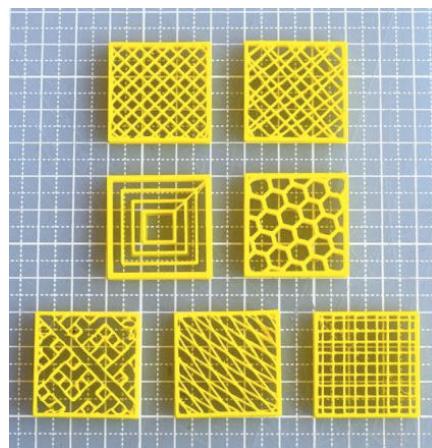
Air-Intake for a Turbine

Lightweight Parts by AM

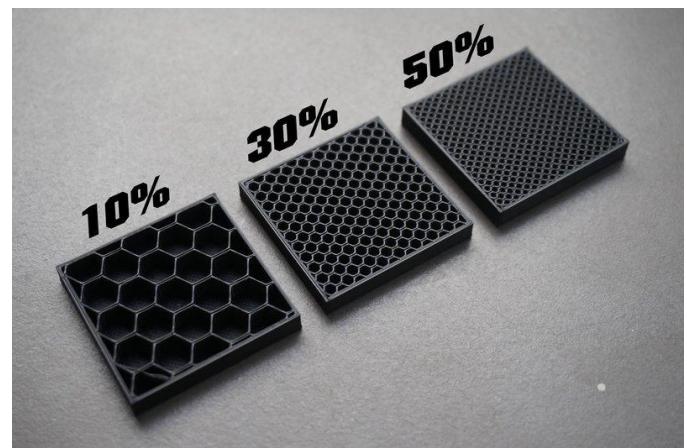
- ▶ Infill structures used to reduce **weight / time-cost**
- ▶ Different infill structures are selected **heuristically**
- ▶ Problems:
 - ▶ Limited types of patterns
 - ▶ Not optimized according to different problems



Regular Uniform Infill



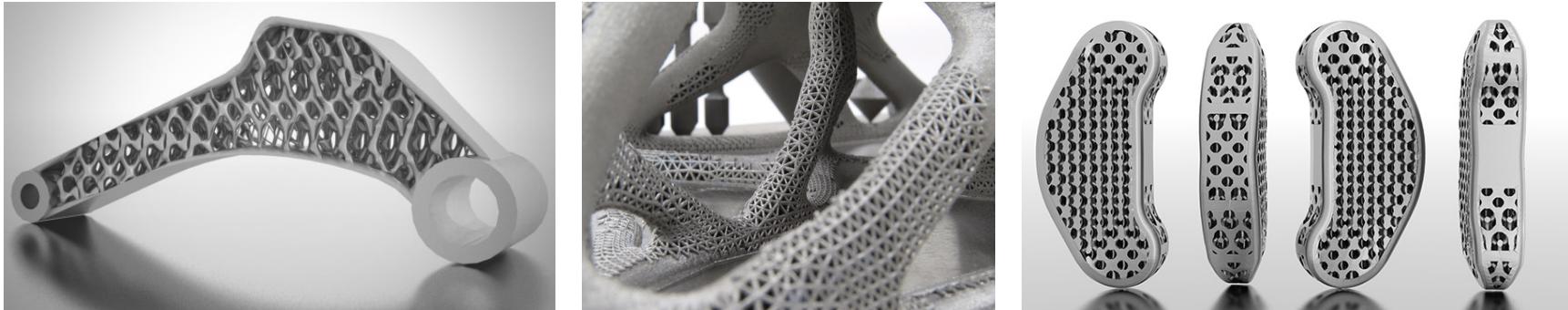
Different Patterns



Different Volumes (by Scaling)

Optimization on Interior Structures

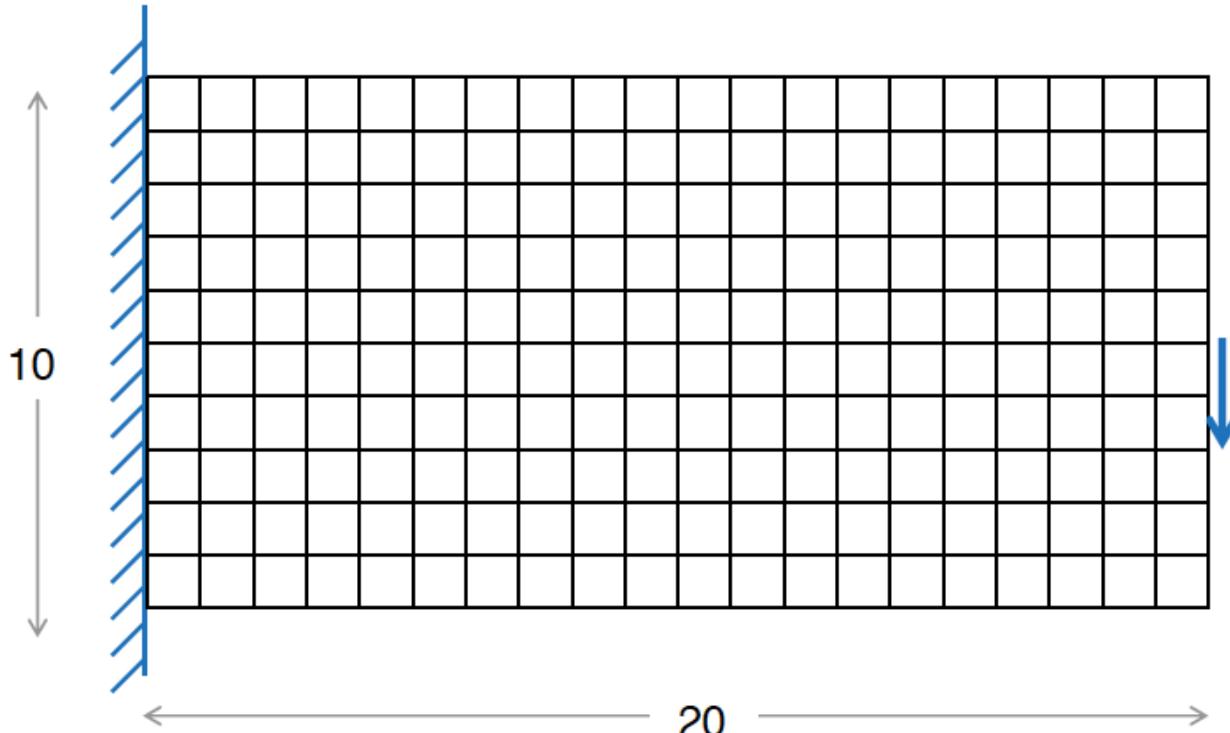
- ▶ A lot of recent work in topology optimization



- ▶ **Problem: Manufacturability?** Especially for infill
- ▶ **Our solution:** by restricting topology optimization to generate structures in a manufacturability-ensured space
 - ▶ Use of grid **refinement** and **grid-to-cell** operators to efficiently perform the optimization
 - ▶ Optimization of **mechanical stiffness** and **static stability** effectively and efficiently

Framework of Topology Optimization

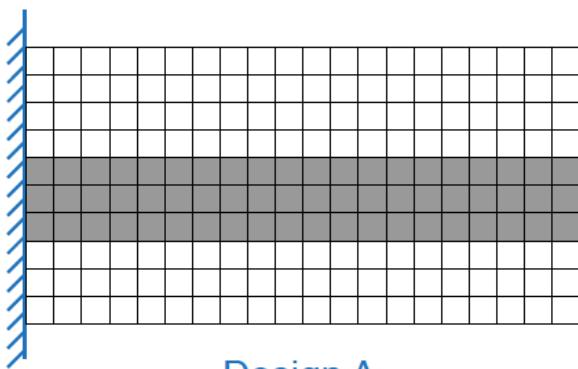
- ▶ Design a stiffest shape by placing 60 LEGO blocks
 - ▶ **60?** as smallest number as possible (i.e., **lightweight** demand)



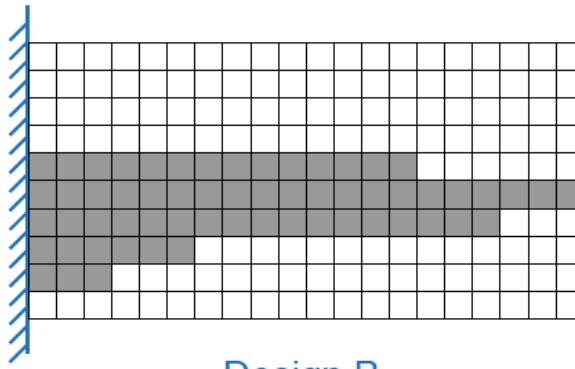
Bone Chair
by Joris Laarman

A Toy Example: Possible Choices

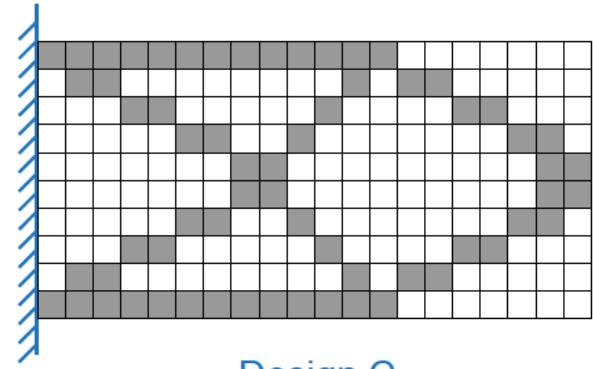
- ▶ Number of possible designs: $C_{200}^{60} = 7.04 \times 10^{51}$
- ▶ Which one has the highest stiffness?



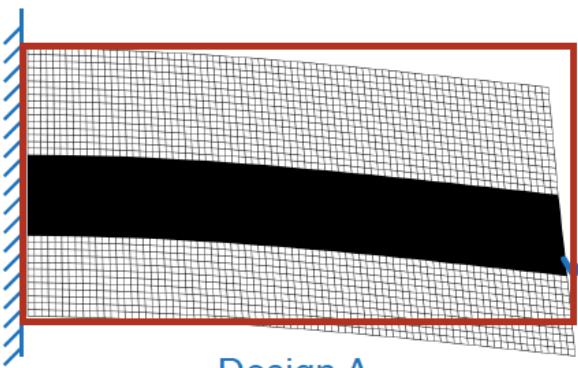
Design A



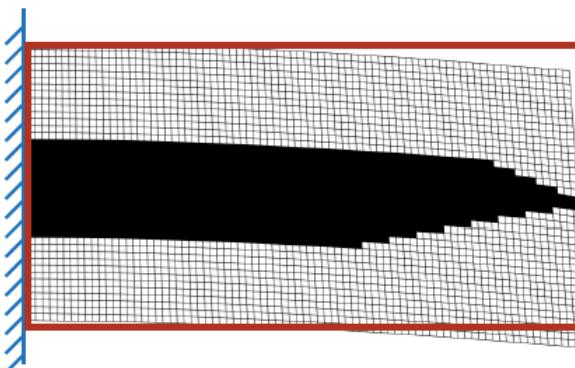
Design B



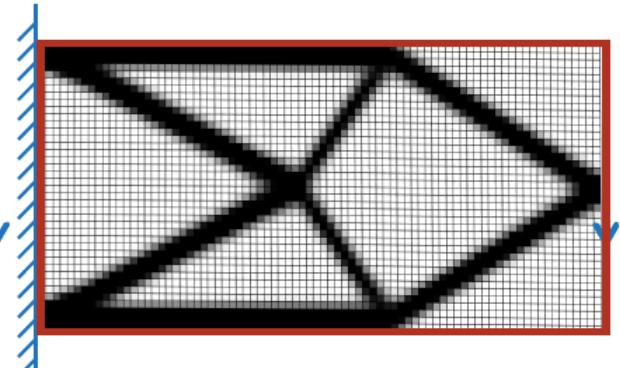
Design C



Design A



Design B



Design C

Framework of Topology Optimization

- Topology optimization for minimizing the strain energy

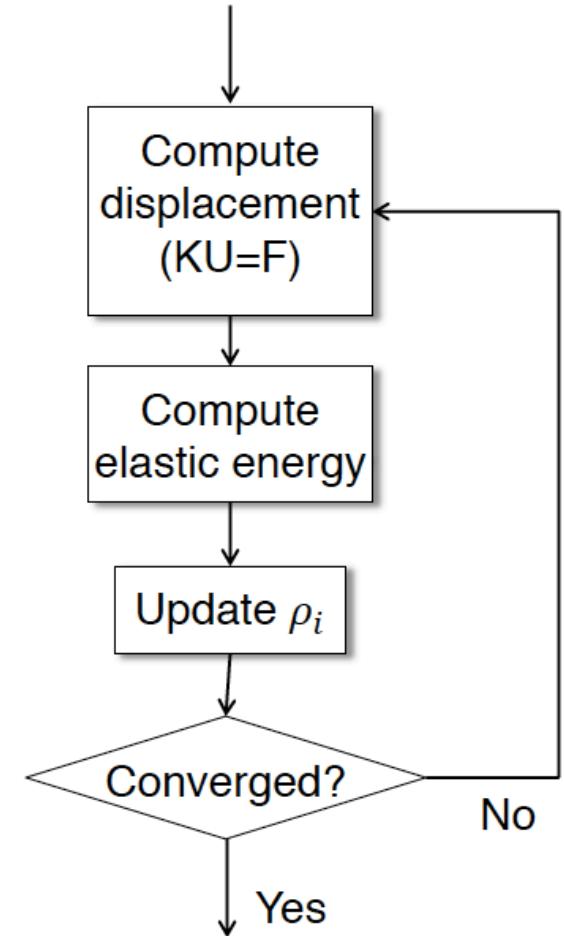
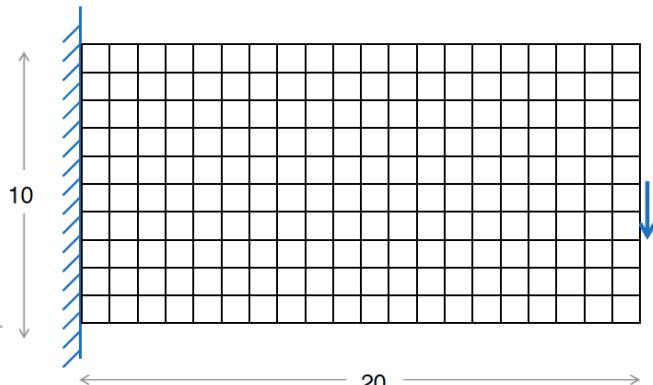
$$\underset{\beta}{\text{minimize}} \quad E = \frac{1}{2} u^T K(\rho) u,$$

subject to $K(\rho)u = f,$

$$V(\rho) = \sum_e \rho_e \leq V^*,$$

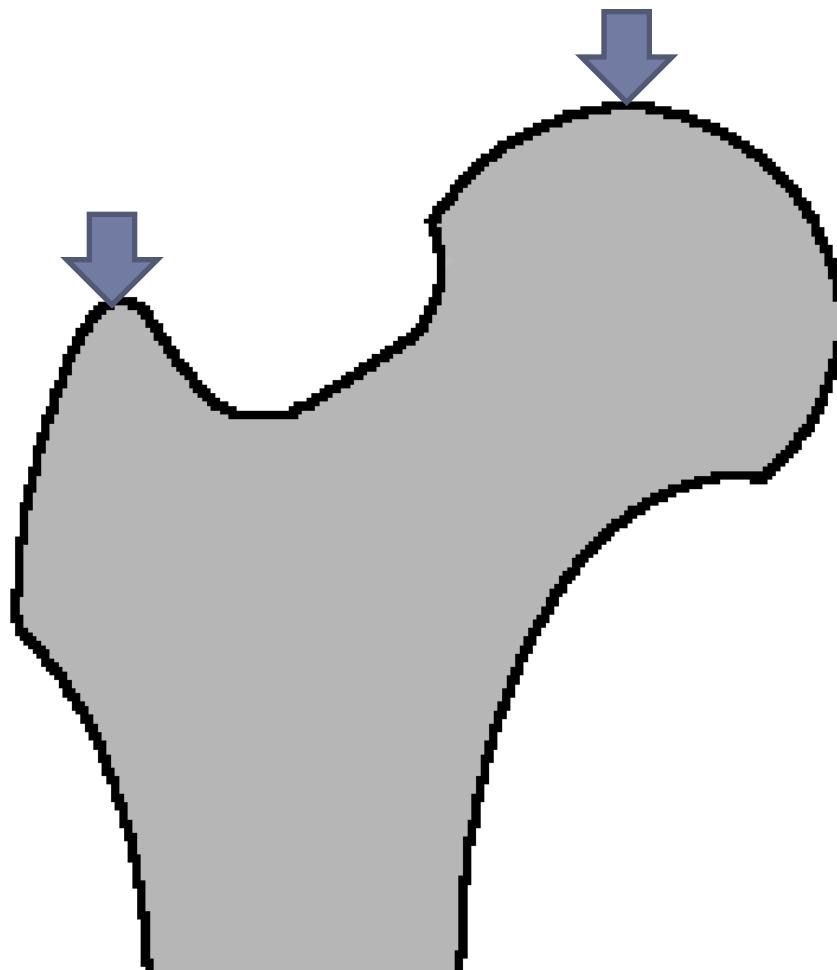
$$\rho_e(\beta) = \begin{cases} 1.0 & e \in \text{solid}, \\ \rho_{\min} & e \in \text{cavity}, \end{cases}$$

$$\beta_c \in \{0, 1\}, \forall C.$$



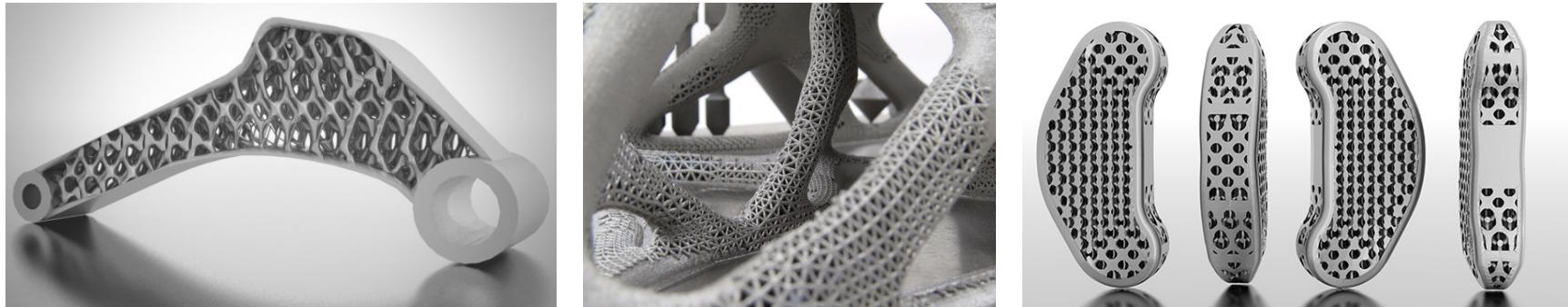
Illustration

Illustration of Topology Optimization



Optimization on Rhombic Structures

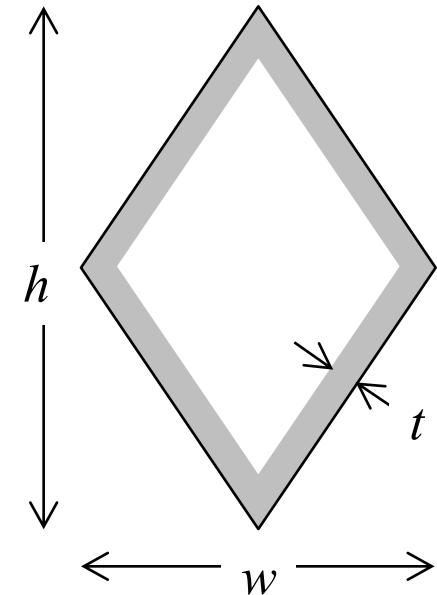
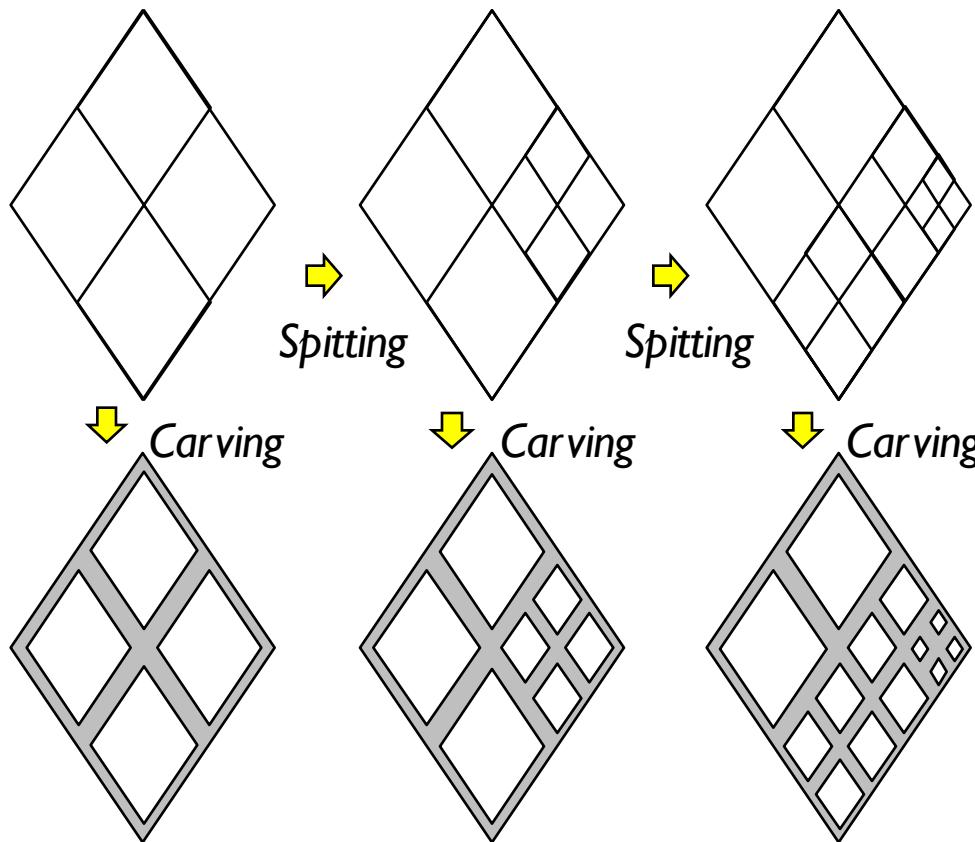
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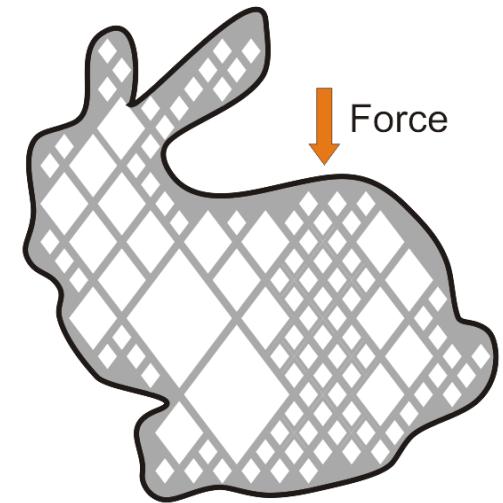
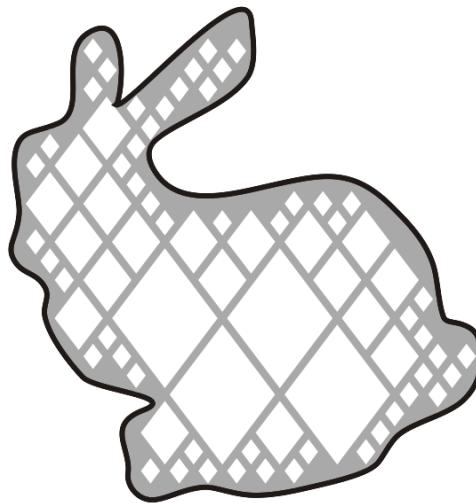
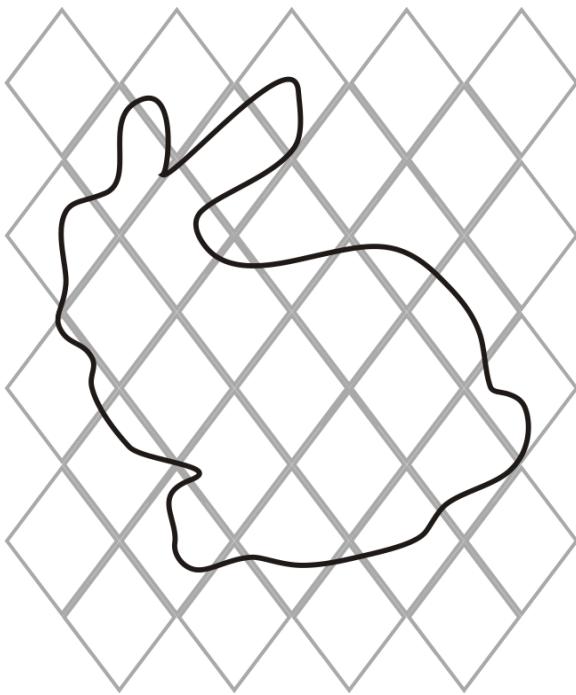
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Adaptive Subdivision and Dual-Rep.

- ▶ Manufacturability can be ensured by the geometric setting: *Slope Angle* and *Wall Thickness*



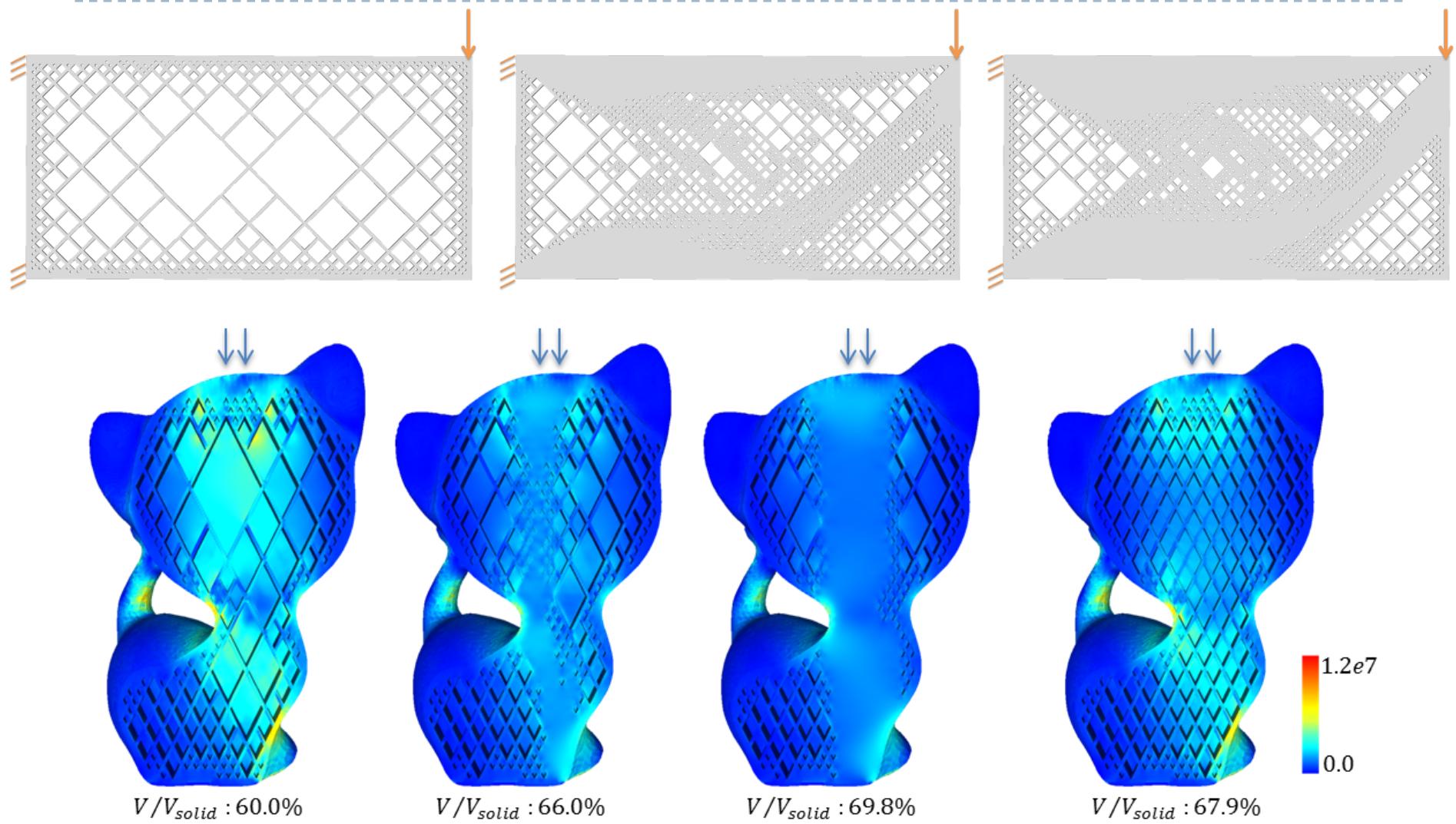
Flow of Optimization by Refinement



- ▶ An iterative process by sensitivity analysis:
 1. Finite Element Analysis of elasticity
 2. Evaluate the sensitivity
 3. Update the rhombic structure by subdividing selected cells

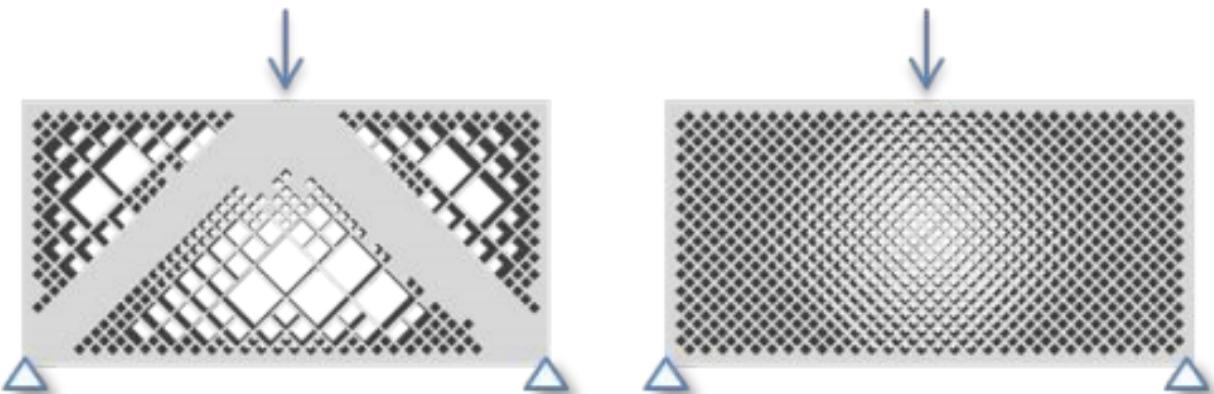
$$G_c = \frac{-\partial E / \partial \beta_c}{\partial V / \partial \beta_c}$$

Self-Supporting Infill Optimization



Optimization of Infill Structures

- ▶ Physical Tests
(for comparison)



Applying the **same loading** (2.11 vs 4.08mm)

Under the **same displacement** (3mm)

Formulation: Static Stability

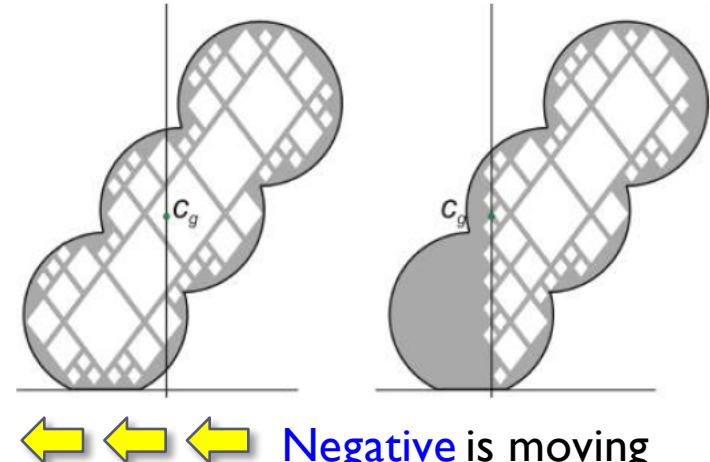
- ▶ Defining an energy to move the **center of gravity**, \mathbf{c}_g , into the **convex hull** of **contacted point** on the ground
- ▶ A **weak form** formulation using center of convex hull, \mathbf{c}_h

$$\underset{\beta}{\text{minimize}} \quad E_s = \|(\mathbf{c}_g - \mathbf{c}_h)^{\perp g}\|_2^2,$$

subject to $\beta_c \in \{0, 1\}, \forall C.$

The gradient

$$\frac{\partial E_s}{\partial \beta_c} = \frac{2m_c}{m_c + m_g} \left[(\mathbf{c}_g - \mathbf{c}_h)^{\perp g} \cdot (\mathbf{c}_c - \mathbf{c}_g)^{\perp g} \right]$$



\mathbf{m}_c : the center of mass **after refining** a considered cell

\mathbf{m}_g : the **current center** of mass

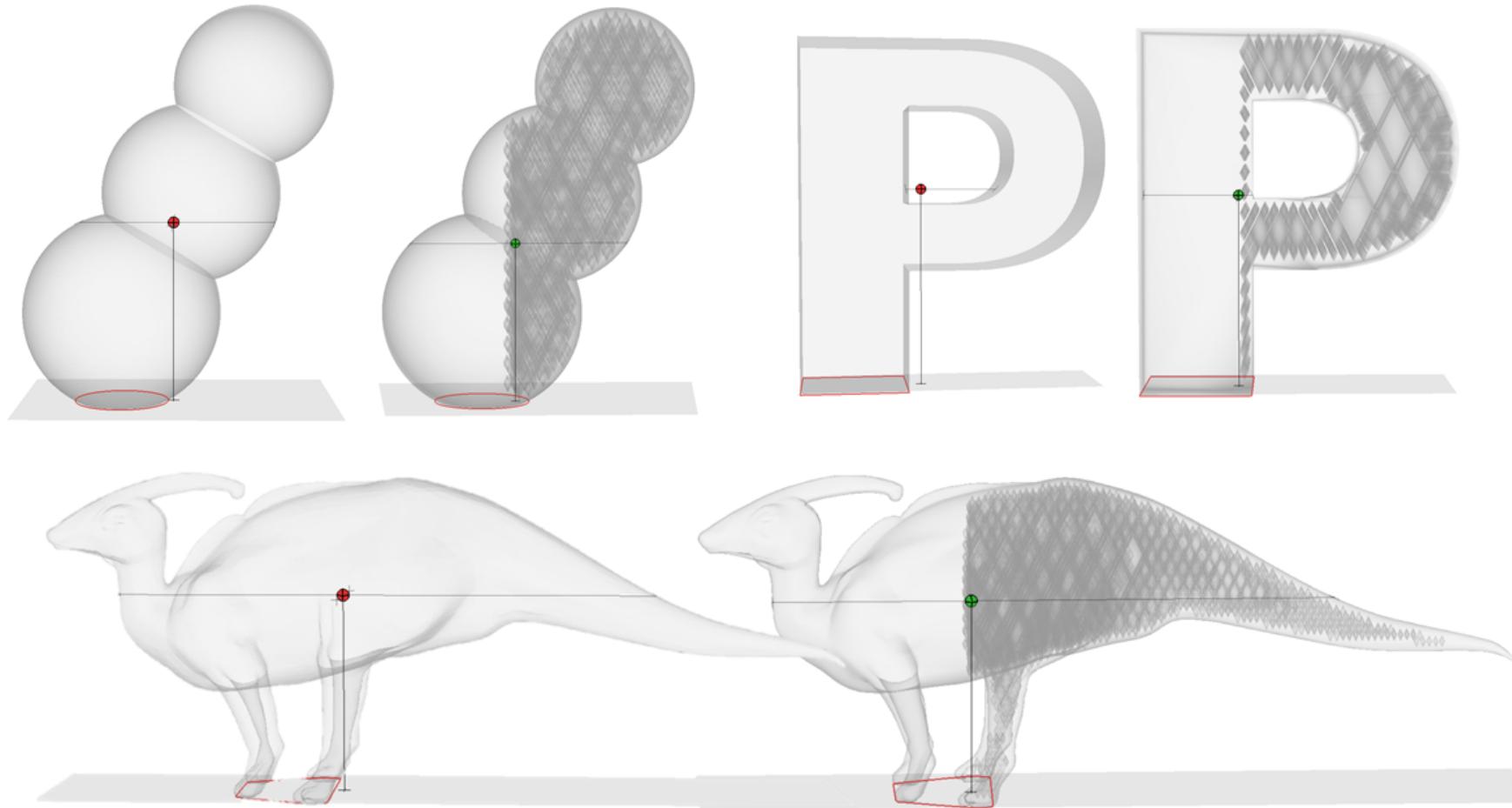
\mathbf{c}_c : the **geometric center** of the cell under consideration

Negative is moving towards the center \mathbf{c}_h

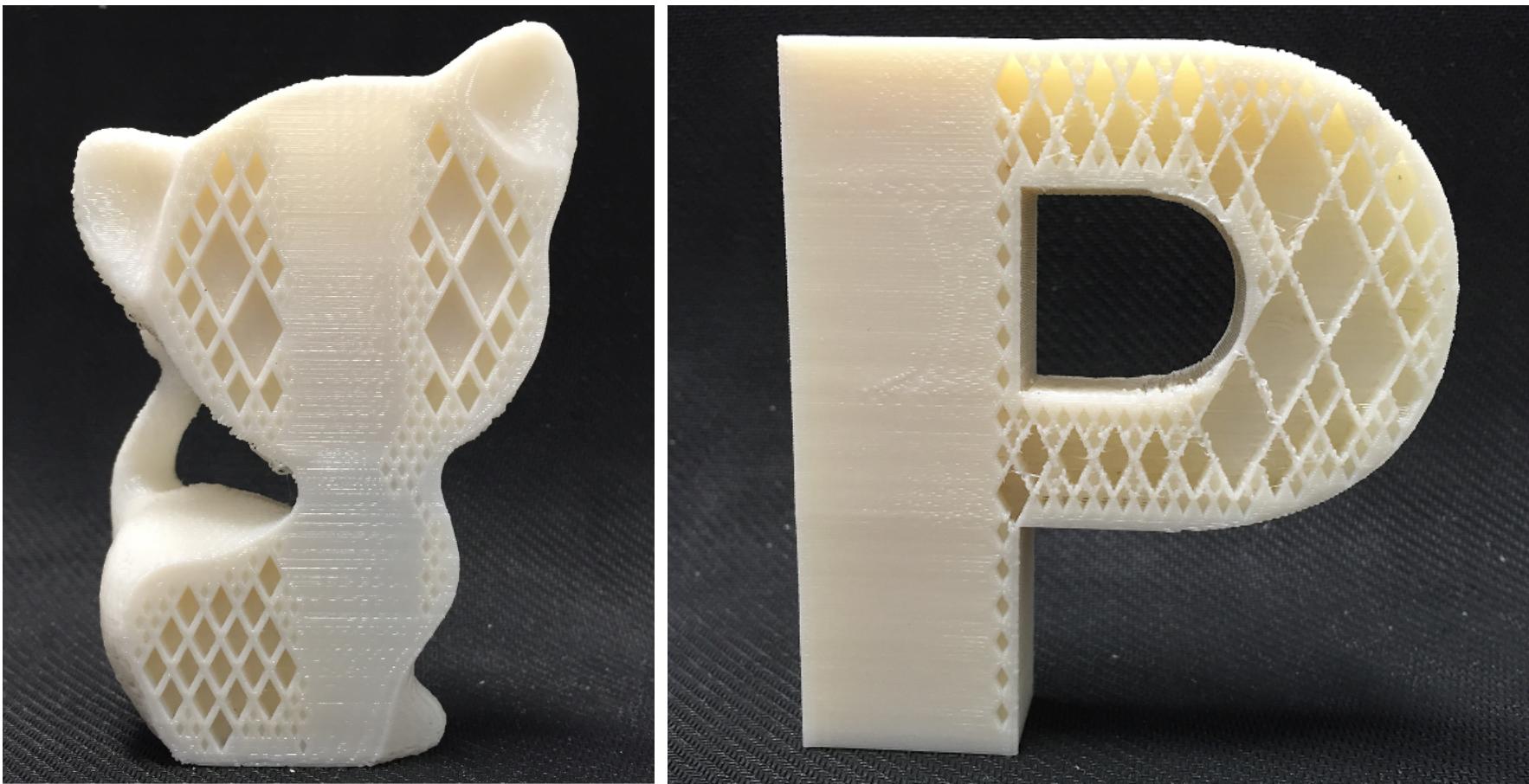
Sort candidate cells in ascending order

Refine one by one

Infill Optimization for Static Stability



Self-Supporting Infill Optimization



Jun Wu, Charlie C.L.Wang, Xiaoting Zhang, and Rudiger Westermann, "Self-supporting infill optimization on rhombic cells", *Computer-Aided Design*, 2016.

Conclusion Remarks

- ▶ An infill optimization approach ensures **manufacturability explicitly**
 - ▶ By restricting optimization to generate **rhombic structures**
 - ▶ **Overhang constraint** and **minimal-wall constraint** are seamlessly satisfied
 - ▶ Validated in both **mechanical stiffness** and **static stability** problems
- ▶ Open questions:
 - ▶ Greedy approach – no guarantee of **global optimality**
 - ▶ What about allowing **boundary** to deform? within **controlled region?**
 - ▶ **More sparse** self-supporting structures?
 - ▶ Current - minimizing compliance, how about **other objectives?**
 - ▶ Maximizing compliance?
 - ▶ Constraints on maximum stress?