

# ECE 275A: Parameter Estimation I

## Random Vectors and Bayes Rule

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0

## Discrete Random Vectors

- $\mathbf{x} \in \mathbb{R}^n$  denotes a *random vector*
- $\mathbf{x}$  can take on a countable number of values in  $\mathcal{X} = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_I\}$
- $p_{\mathbf{x}}(\mathbf{x}_i)$ , or  $p(\mathbf{x}_i)$ , is the *probability* that the random vector  $\mathbf{x}$  takes on value  $\mathbf{x}_i$
- $p(\cdot)$  is called *probability mass function (pmf)*
- Example: If  $x$  is the outcome of a dice roll, we have  $\mathcal{X} = \{1, 2, \dots, 6\}$  and
$$p(x_i) = 1/6, \forall x_i \in \mathcal{X}$$

1

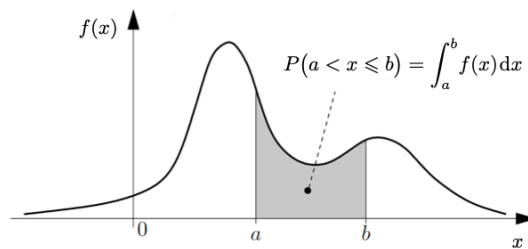
1

## Continuous Random Vectors

- Random vector  $\mathbf{x} \in \mathbb{R}^n$  takes on values in the continuum
- $f_{\mathbf{x}}(\mathbf{x})$ , or  $f(\mathbf{x})$ , is its **probability density function (pdf)**, i.e.,

$$P(\mathbf{x} \in \mathcal{R}) = \int_{\mathcal{R}} f(\mathbf{x}) d\mathbf{x}$$

- Example:



2

2

## Joint and Conditional Distributions

- $p_{\mathbf{x},\mathbf{y}}(\mathbf{x}, \mathbf{y})$  or  $p(\mathbf{x}, \mathbf{y})$  is the joint pmf of random vectors  $\mathbf{x}$  and  $\mathbf{y}$
- If  $\mathbf{x}$  and  $\mathbf{y}$  are **independent** then

$$p(\mathbf{x}, \mathbf{y}) = p(\mathbf{x})p(\mathbf{y})$$

- $p(\mathbf{x}|\mathbf{y})$  is the probability of  $\mathbf{x}$  given (conditioned on)  $\mathbf{y}$

$$p(\mathbf{x}|\mathbf{y}) = p(\mathbf{x}, \mathbf{y})/p(\mathbf{y}) \quad p(\mathbf{x}, \mathbf{y}) = p(\mathbf{x}|\mathbf{y})p(\mathbf{y})$$

- If  $\mathbf{x}$  and  $\mathbf{y}$  are **independent** then

$$p(\mathbf{x}|\mathbf{y}) = p(\mathbf{x}) \quad p(\mathbf{y}|\mathbf{x}) = p(\mathbf{y})$$

- Equivalent expressions exist for the pdfs of continuous random vectors

3

3

## Law of Total Probabilities, Marginals

### Discrete Case

$$\sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{x}) = 1$$

$$p(\mathbf{x}) = \sum_{\mathbf{y} \in \mathcal{Y}} p(\mathbf{x}, \mathbf{y})$$

$$p(\mathbf{x}) = \sum_{\mathbf{y} \in \mathcal{Y}} p(\mathbf{x}|\mathbf{y}) p(\mathbf{y})$$

### Continuous Case

$$\int f(\mathbf{x}) d\mathbf{x} = 1$$

$$f(\mathbf{x}) = \int f(\mathbf{x}, \mathbf{y}) d\mathbf{y}$$

$$f(\mathbf{x}) = \int f(\mathbf{x}|\mathbf{y}) f(\mathbf{y}) d\mathbf{y}$$

4

4

## Bayes Rule

- Recall  $p(\mathbf{x}, \mathbf{y}) = p(\mathbf{x}|\mathbf{y}) p(\mathbf{y}) = p(\mathbf{y}|\mathbf{x}) p(\mathbf{x})$
- It therefore follows that

$$p(\mathbf{x}|\mathbf{y}) = \frac{\text{likelihood (}\mathbf{y}\text{ is fixed)} \quad \text{prior}}{\text{evidence}}$$

The diagram shows the equation  $p(\mathbf{x}|\mathbf{y}) = \frac{p(\mathbf{y}|\mathbf{x}) p(\mathbf{x})}{p(\mathbf{y})}$  inside a yellow box. A red arrow points from the text "likelihood (y is fixed)" to the term  $p(\mathbf{y}|\mathbf{x})$ . A blue arrow points from the text "prior" to the term  $p(\mathbf{x})$ . A green arrow points from the text "evidence" to the term  $p(\mathbf{y})$  in the denominator.

- Equivalent expressions exist for the pdfs of continuous random vectors

5

5

## Normalization

- For  $\mathbf{y}$  observed and thus fixed

$$\begin{aligned} p(\mathbf{x}|\mathbf{y}) &= \frac{p(\mathbf{y}|\mathbf{x}) p(\mathbf{x})}{p(\mathbf{y})} \\ &= C p(\mathbf{y}|\mathbf{x}) p(\mathbf{x}) \\ &\propto p(\mathbf{y}|\mathbf{x}) p(\mathbf{x}) \end{aligned}$$

- The constant  $C$  ensures that  $p(\mathbf{x}|\mathbf{y})$  sums to one and can be calculated as

$$C = \frac{1}{\sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{y}|\mathbf{x}) p(\mathbf{x})}$$

- Equivalent expressions exist for the pdfs of continuous random vectors

6

6

## Conditioning

- Law of total probability

$$\begin{aligned} p(\mathbf{x}|\mathbf{z}) &= \int p(\mathbf{x}, \mathbf{y}|\mathbf{z}) d\mathbf{y} \\ &= \int p(\mathbf{x}|\mathbf{y}, \mathbf{z}) p(\mathbf{y}|\mathbf{z}) d\mathbf{y} \end{aligned}$$

- Bayes rule with background knowledge

$$p(\mathbf{x}|\mathbf{y}, \mathbf{z}) = \frac{p(\mathbf{y}|\mathbf{x}, \mathbf{z}) p(\mathbf{x}|\mathbf{z})}{p(\mathbf{y}|\mathbf{z})}$$

- Equivalent expressions exist for the pdfs of continuous random vectors

7

7

## Conditional Independence

- **Condition on  $z$** , random variables  $x$  and  $y$  are independent if

$$p(x, y|z) = p(y|z)p(x|z)$$

- This is equivalent to

$$p(x|z) = p(x|z, y)$$

and

$$p(y|z) = p(y|z, x)$$

- Equivalent expressions exist for the pdfs of continuous random vectors

8

8

## Expectation

- **Expectation** of a random vector  $x$

$$\mu_x = \mathbb{E}\{x\} = \sum_{x \in \mathcal{X}} x p(x) \quad \text{discrete case}$$

$$\mu_x = \mathbb{E}\{x\} = \int x f(x) dx \quad \text{continuous case}$$

- Expectation of transformed random vector  $g(x)$

$$\mathbb{E}\{g(x)\} = \sum_{x \in \mathcal{X}} g(x) p(x)$$

$$\mathbb{E}\{g(x)\} = \int g(x) f(x) dx$$

9

## Covariance

- **Covariance** of a random vector  $\mathbf{x}$

$$\begin{aligned} & \text{discrete case} \\ \mathbb{E}\{(\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})(\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})^{\text{T}}\} \\ &= \sum_{\mathbf{x} \in \mathcal{X}} (\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})(\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})^{\text{T}} p(\mathbf{x}) \end{aligned}$$

$$\begin{aligned} & \text{continuous case} \\ \mathbb{E}\{(\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})(\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})^{\text{T}}\} \\ &= \int (\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})(\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})^{\text{T}} f(\mathbf{x}) d\mathbf{x} \end{aligned}$$

- **Cross-Covariance** of random vectors  $\mathbf{x}$  and  $\mathbf{y}$

$$\begin{aligned} \mathbb{E}\{(\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})(\mathbf{y} - \boldsymbol{\mu}_{\mathbf{y}})^{\text{T}}\} \\ &= \sum_{\mathbf{x} \in \mathcal{X}} \sum_{\mathbf{y} \in \mathcal{Y}} (\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})(\mathbf{y} - \boldsymbol{\mu}_{\mathbf{y}})^{\text{T}} p(\mathbf{x}, \mathbf{y}) \end{aligned}$$

$$\begin{aligned} \mathbb{E}\{(\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})(\mathbf{y} - \boldsymbol{\mu}_{\mathbf{y}})^{\text{T}}\} \\ &= \int (\mathbf{x} - \boldsymbol{\mu}_{\mathbf{x}})(\mathbf{y} - \boldsymbol{\mu}_{\mathbf{y}})^{\text{T}} f(\mathbf{x}, \mathbf{y}) d\mathbf{x} d\mathbf{y} \end{aligned}$$