

# All Pass Filters and Spectral Factorization

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# WSS and LTI systems

WSS process  $x[n]$  is input to a LTI system with transfer function  $H(z)$  and output is  $y[n]$ .

$y[n]$  is WSS and  $x[n]$  and  $y[n]$  are jointly WSS.

$y[n]$  is WSS with mean  $\mu_y = H(0)\mu_x$  and autocorrelation sequence  $r_{yy}[m] = h[m] * h^*[-m] * r_{xx}[m]$ .

$x[n]$  and  $y[n]$  are jointly WSS and  $r_{xy}[m] = E(x[n+m]y^*[n]) = r_{xx}[m] * h^*[-m]$ .

In the z-domain  $R_{xy}(z) = \mathcal{Z}(r_{xy}[m]) = R_{xx}(z)H^*(\frac{1}{z^*})$  and simplifies to  $R_{xx}(z)H(z^{-1})$  for real systems.

$$R_{yy}(z) = R_{xx}(z)H(z)H^*(\frac{1}{z^*}) \text{ or } R_{yy}(e^{j\omega}) = R_{xx}(e^{j\omega})|H(e^{j\omega})|^2$$

Spectral Factorization: Given  $R_{yy}(z)$  and with white noise input,

$R_{xx}(z) = 1$ , find  $H(z)$  or equivalently factor  $R_{yy}(z)$  such that  $R_{yy}(z) = H(z)H^*(\frac{1}{z^*})$ .

# All Pass Filters

$$H_{ap}(z) = \frac{z^{-1} - a^*}{1 - az^{-1}}, |a| < 1$$

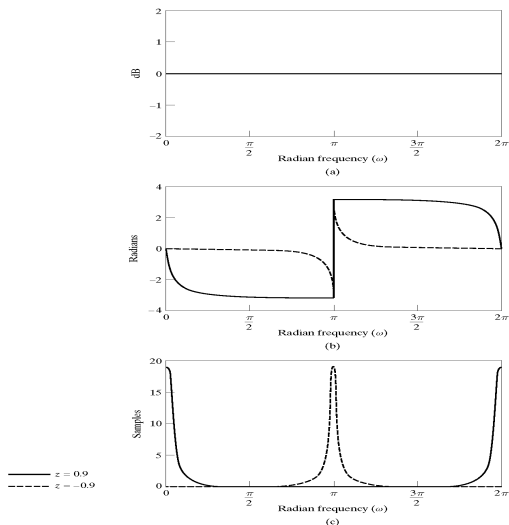
With  $a = re^{j\theta}$ , can show  $|H_{ap}(e^{j\omega})| = 1$ , and

$$\phi(\omega) = \angle H_{ap}(e^{j\omega}) = -\omega - 2 \arctan \left[ \frac{r \sin(\omega - \theta)}{1 - r \cos(\omega - \theta)} \right]$$

$$\text{grd}(H(e^{j\omega})) = -\frac{d\phi(\omega)}{d\omega} = \frac{1 - r^2}{1 + r^2 - 2r \cos(\omega - \theta)} = \frac{1 - r^2}{|1 - r e^{j\theta} e^{-j\omega}|^2} \geq 0$$

A first order all pass filter has a pole at  $a = re^{j\theta}$  and a zero at  $\frac{1}{a^*} = \frac{1}{r} e^{j\theta}$ .

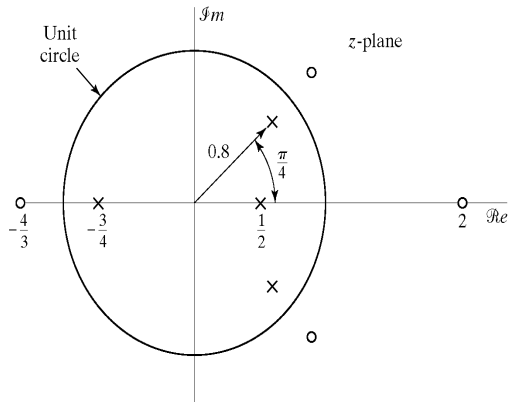
# Magnitude and Phase Plots for First Order All Pass Filter



**Figure 5.22** Frequency response for all-pass filters with real poles at  $z = 0.9$  (solid line) and  $z = -0.9$  (dashed line). (a) Log magnitude. (b) Phase (principal value). (c) Group delay.

# Poles-Zeros for a General All-Pass Filter

$$H_{ap}(z) = \prod_{k=1}^{M_r} \frac{z^{-1} - d_k}{1 - d_k z^{-1}} \prod_{k=1}^{M_c} \frac{(z^{-1} - e_k)(z^{-1} - e_k^*)}{(1 - e_k z^{-1})(1 - e_k^* z^{-1})}, \quad (d_k \text{ real})$$



# Spectral-Factorization

Some Notation

$$\begin{aligned}H(z) &= h[0] + h[1]z^{-1} + \dots + h[N-1]z^{-(N-1)} \\ H^*\left(\frac{1}{z^*}\right) &= h^*[0] + h^*[1]z^1 + \dots + h^*[N-1]z^{(N-1)} = \tilde{H}(z)\end{aligned}$$

Will use  $\tilde{H}(z) = H^*\left(\frac{1}{z^*}\right)$  for notational simplicity.

Note: If  $z_i$  is a root of  $H(z)$ , then  $\frac{1}{z_i^*}$  is a root of  $\tilde{H}(z)$ .

Problem: Given  $R(e^{j\omega}) \geq 0$ ,  $\forall \omega$ , find  $H(z)$  or  $H(e^{j\omega})$  such that  $R(e^{j\omega}) = |H(e^{j\omega})|^2$  or equivalently  $R(z) = H(z)\tilde{H}(z)$ .

# Spectral-Factorization: Rational Systems

We will consider the version where  $R(e^{j\omega}) = \frac{P(e^{j\omega})}{Q(e^{j\omega})}$  where  $P(e^{j\omega}) \geq 0$  and  $Q(e^{j\omega}) > 0$ . We will assume no zeros on unit circle and so  $P(e^{j\omega}) > 0$

Equivalent z-domain problem is  $R(z) = \frac{P(z)}{Q(z)}$ , with Region of Convergence (ROC) an annular ring including the unit circle.

Spectral Factorization in this case is equivalent to

$$R(z) = \frac{P(z)}{Q(z)} = \frac{B(z)\tilde{B}(z)}{A(z)\tilde{A}(z)}$$

We will concentrate on  $P(z)$  and similar considerations apply to  $Q(z)$ .

For the rest of the discussion  $R(z) = P(z)$  and  $H(z) = B(z)$  and we will also restrict  $P(z)$  to have finite order

$$R(z) = \sum_{m=-M}^M r[m]z^{-m} \overset{?}{=} H(z)\tilde{H}(z)$$

Since  $r[m] = r^*[-m]$ , we have  $R(z) = R^*(\frac{1}{z^*})$ .

Consequence: if  $z_i$  is a zero (root) of  $R(z)$ , then  $\frac{1}{z_i^*}$  is also a zero of the system. If we consider real systems ( $r[m] = r^*[-m] = r[-m]$ ), then  $z_i^*$  is also a zero and so is  $\frac{1}{z_i}$ .

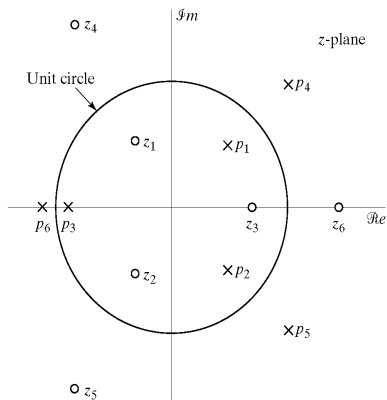
Factorization: If  $z_i$  is assigned to  $H(z)$ , then  $\frac{1}{z_i^*}$  is assigned to  $\tilde{H}(z)$ .

General  $R(z) = \frac{P(z)}{Q(z)}$ : For the denominator  $Q(z)$ , because of causality and stability (poles inside unit circle), there is only one useful factorization. For the numerator options exist.



## Zeros of $H(z)\tilde{H}(z)$ .

$$R(z) = c z^M \prod_{i=1}^M (1 - z_i z^{-1}) (1 - \frac{1}{z_i^*} z^{-1})$$



# Minimum-Phase and Maximum-Phase Systems

$$R(z) = d z^M \prod_{i=1}^M (1 - z_i z^{-1})(z^{-1} - z_i^*), \quad |z_i| < 1$$

This factorization is chosen to align with the all-pass numerator.  
Alternately

$$R(z) = d \prod_{i=1}^M (1 - z_i z^{-1})(1 - z_i^* z) = d \prod_{i=1}^M (z - z_i)(z^{-1} - z_i^*)$$

Also indicates  $d$  is real and positive.

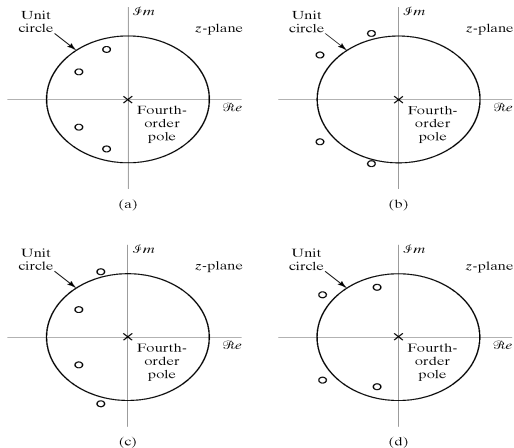
Minimum-Phase:  $H_{min}(z) = \sqrt{d} \prod_{i=1}^M (1 - z_i z^{-1})$ . All zeros inside unit circle. The filter is (causally) invertible.

Maximum-Phase:  $H_{max}(z) = \sqrt{d} \prod_{i=1}^M (z^{-1} - z_i^*)$ . All zeros outside unit circle.

$$H_{max}(z) = H_{min}(z)H_{ap}(z), \quad \text{where} \quad H_{ap}(z) = \prod_{i=1}^M \frac{z^{-1} - z_i^*}{1 - z_i z^{-1}}.$$

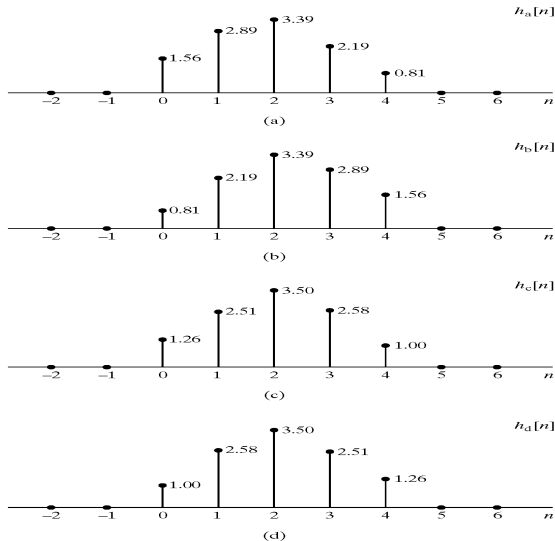
In general, all factors can be written as  $H_{min}(z)H_{ap}(z)$  with an appropriate  $H_{ap}(z)$ . (Depends on how many zeros have to be flipped)

# Options for a system with four zeros



**Figure 5.30** Four systems, all having the same frequency-response magnitude. Zeros are at all combinations of  $0.9e^{\pm j0.6\pi}$  and  $0.8e^{\pm j0.8\pi}$  and their reciprocals.

# Impulse response options for a system with four zeros



**Figure 5.31** Sequences corresponding to the pole-zero plots of Figure 5.30.

# Whitening Filter

Consider  $x[n] \rightarrow H(z) \rightarrow y[n]$  where  $x[n]$  is zero mean white noise, i.e.  $r_{xx}[m] = \delta[m]$  and  $R_{xx}(z) = 1$ . So we know from LTI theory that  $R_{yy}(e^{j\omega}) = |H(e^{j\omega})|^2$  and  $R_{yy}(z) = H(z)\tilde{H}(z)$ .

Now we want to white  $y[n]$  through linear filtering, i.e.

$$y[n] \rightarrow G(z) \rightarrow v[n]$$

Problem (Whitening Operation): Choose  $G(z)$  such that  $v[n]$  is white, i.e.  $r_{vv}[m] = \delta[m]$ , and  $R_{vv}(z) = 1$ .

Answer:  $G(z) = \frac{1}{H_{min}(z)}$ , where  $R_{yy}(z) = H_{min}(z)\tilde{H}_{min}(z)$ .

$$R_{vv}(z) = R_{yy}(z)G(z)\tilde{G}(z) = R_{yy}(z)\frac{1}{H_{min}(z)\tilde{H}_{min}(z)} = R_{yy}(z)\frac{1}{R_{yy}(z)} = 1$$

$H_{min}(z)$  is referred as the innovations filter and ensuing model (white noise filtered by  $H_{min}(z)$ ) the innovations representation.