

SIO 207A: Fundamentals of Digital Signal Processing

Class 17

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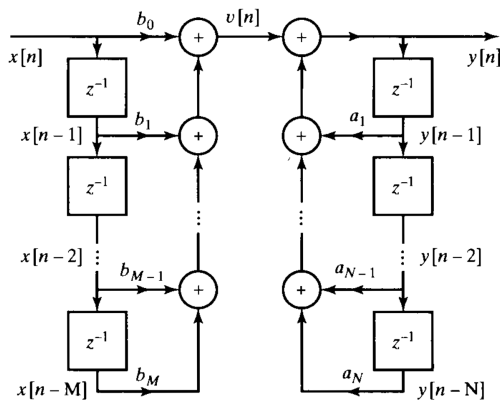
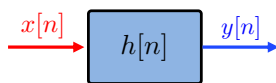


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0

Infinite Impulse Response (IIR) Filter Structures

System Input/Output Description:



Linear Constant Difference Equation:

$$y[n] = \sum_{k=1}^N a_k y[n-k] + \sum_{r=0}^M b_r x[n-r]$$

Z-Transform:

$$Y(z) = \sum_{k=1}^N a_k z^{-k} Y(z) + \sum_{r=0}^M b_r z^{-r} X(z)$$

$$= H(z)X(z)$$

Z-Domain Representation:

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{r=0}^M b_r z^{-r}}{1 - \sum_{k=1}^N a_k z^{-k}}$$

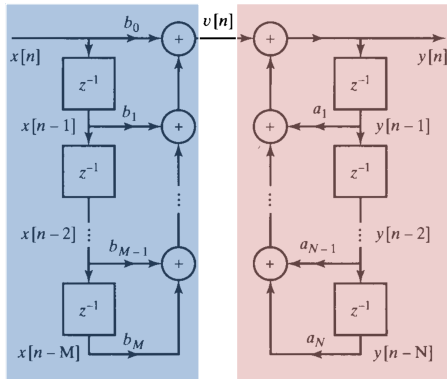
$$= \frac{b_0 z^M + b_1 z^{M-1} + \dots + b_M}{z^N + a_1 z^{N-1} + \dots + a_N}$$

1

1

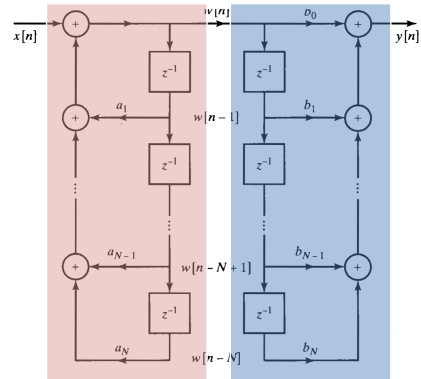
Infinite Impulse Response (IIR) Filter Structures

Direct Form I:



$$v[n] = \sum_{k=0}^M b_k x[n-k] \quad y[n] = \sum_{k=1}^N a_k y[n-k] + v[n]$$

Direct Form II:



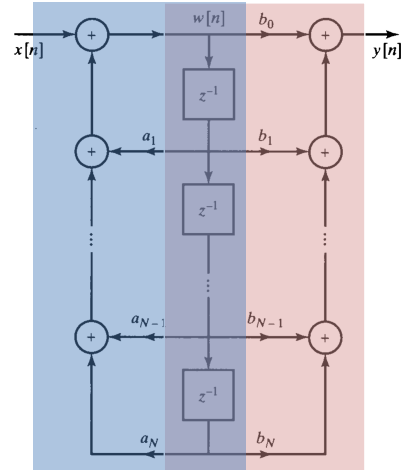
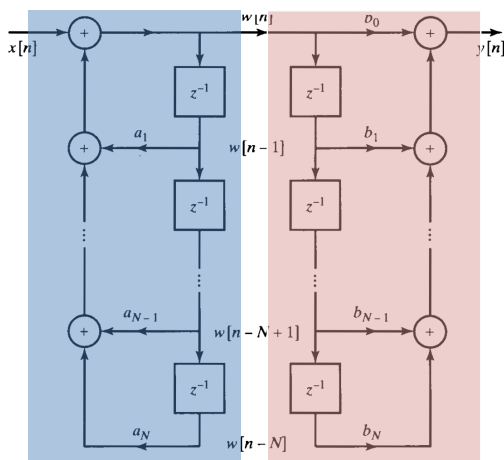
$$w[n] = \sum_{k=1}^N a_k w[n-k] + x[n] \quad y[n] = \sum_{k=0}^M b_k w[n-k]$$

Since we have a linear system we can interchange **subsystem one** with **subsystem two**

2

Infinite Impulse Response (IIR) Filter Structures

In **direct form II**, we can save half of the delays by combining the vertical “delay line” of the two subsystems

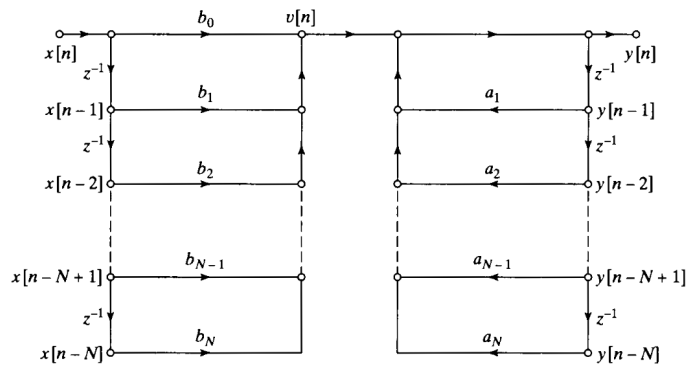


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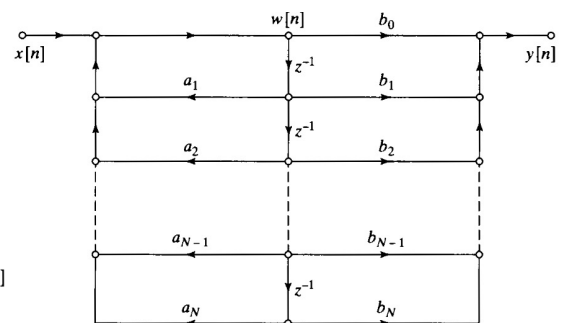
Representation as Flow Diagrams

- If multiple signals enter a node, this represents a summation
- Every branch is a linear operation indicated by a coefficient (no coefficient is equal to a multiplication by 1)

Direct Form I:



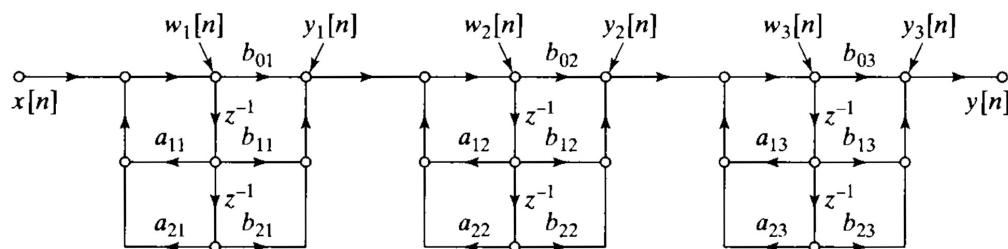
Direct Form II:



4

Cascade of 2nd Order Filters

$$H(z) = \prod_{k=1}^{N_s} \frac{b_{0k} + b_{1k}z^{-1} + b_{2k}z^{-2}}{1 - a_{1k}z^{-1} - a_{2k}z^{-2}}$$



Note that possible pole and zero locations after quantization depend on filter structure

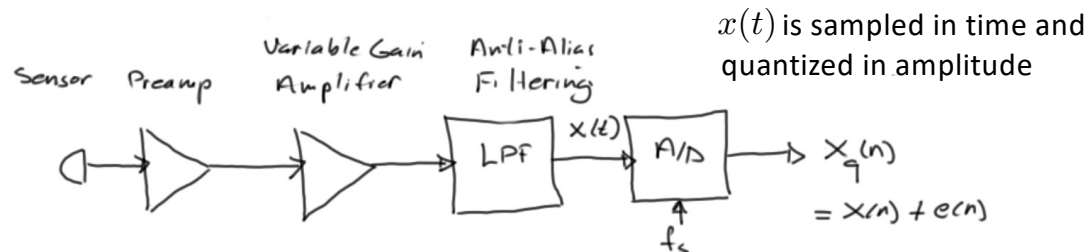
see also Section 6.3, 6.4, and 6.8
in *Oppenheim & Schaffer, 1999*

This implementation is typically used for numerical stability

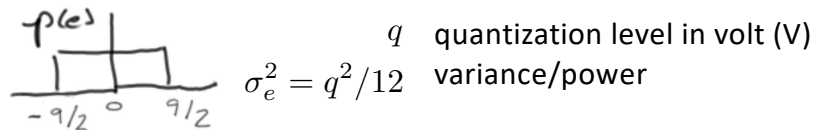
5

Quantization Noise at the A/D Converter Output

- Recall the block diagram of a data acquisition system



- $e[n]$ is error due to A/D amplitude quantization also known as quantization noise
- $e[n]$ can be modeled as a sequence of independent random variables with uniform probability density function



6

Noise Sources

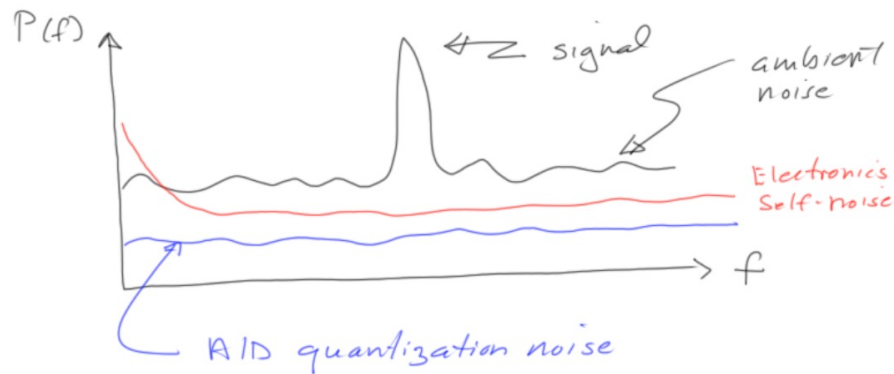
- There are three sources of noise in the output signal of an analog to digital (A/D) converter
 1. Ambient noise in the environment
 2. Electronics-related self-noise (typically dominated by the preamp immediately after the sensors)
 3. A/D converter quantization noise (governed by the aperture of the A/D and number of bits)
- Quantization noise example: an A/D with aperture $[-5V, +5V]$ (10V in total) and 10 bits (1024 levels) has a resolution of $q = 10V/1024 \approx 10mV$

Note: An additional source of error is clipping in case the analog signal $x(t)$ exceeds the A/D aperture

7

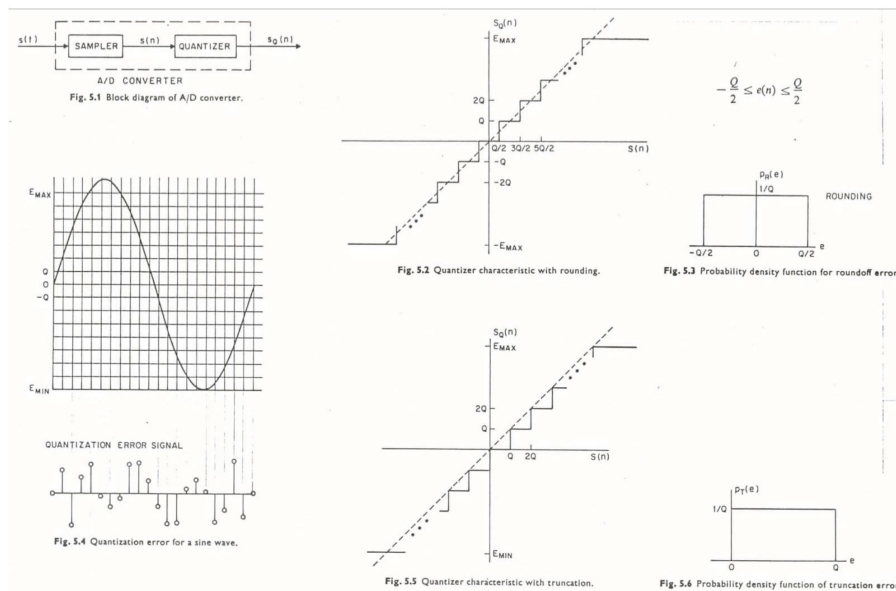
Noise Sources

- It is desired that the ambient noise dominates over electronics self-noise and A/D converter quantization noise



8

Quantization Noise



9

Quantization Noise

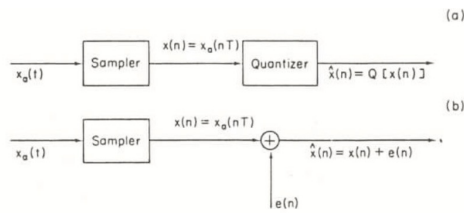


Fig. 9.2 Representation of sampling of an analog signal: (a) nonlinear model; (b) statistical model.

$$-\frac{\Delta}{2} < e(n) \leq \frac{\Delta}{2}$$

1. The sequence of error samples $\{e(n)\}$ is a sample sequence of a stationary random process.
2. The error sequence is uncorrelated with the sequence of exact samples $\{x(n)\}$.
3. The random variables of the error process are uncorrelated; i.e., the error is a white-noise process.
4. The probability distribution of the error process is uniform over the range of quantization error.

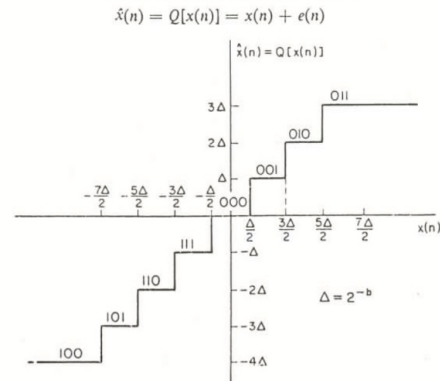
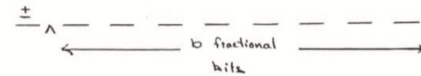


Fig. 9.3 Two's-complement rounding of samples for $b = 2$.



10

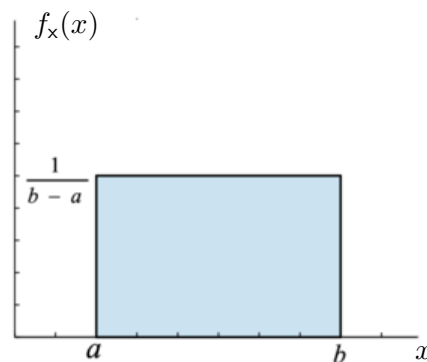
Uniformly Distributed Random Variable

Probability Density Function:

$$f_x(x) = \begin{cases} \frac{1}{b-a} & \text{for } a < x < b \\ 0 & \text{for } a < x \text{ or } x > b \end{cases}$$

Mean: $\mu_x = \frac{b+a}{2}$

Standard Deviation: $\sigma_x = \frac{b-a}{\sqrt{12}}$



11

Quantization Noise – SNR Calculations

$$\frac{\sigma_x^2}{\sigma_e^2} = \frac{\sigma_x^2}{2^{-2b}/12} = (12 \cdot 2^{2b}) \sigma_x^2$$

$$\text{SNR} = 6.02b + 10.79 + 10 \log \sigma_x^2 \text{ dB}$$

for: $-1 \leq x(n) \leq 1$

$$= 6.02b + 10.79 + 10 \log \sigma_x^2 + 20 \log A \text{ dB}$$

for: $-1 \leq Ax(n) \leq 1$; A = attenuation factor

A. $x(n)$ sinusoidal \rightarrow max. amplitude $= 1 - 2^{-b} \approx 1$
 $\therefore \sigma_x^2 \approx 1/2$

$$\text{SNR}_{\text{max, sinusoid}} = 6.02b + 7.79 \text{ dB}$$

B. $x(n)$ = random process with $P(x(n) > 4\sigma_x) \ll 1$
 \therefore let $A = 1/4\sigma_x$

$$\text{SNR}_{\text{random process}} = 6.02b - 1.24 \text{ dB}$$

Note: a 9.03 dB (= 1 1/2 bits) drop from sinusoidal signal case