

Muhammad Fadhil Ginting

Last Updated on : 15th October, 2019

Pasadena, CA 91103 • gintingf@student.ethz.ch • 626-360-6243 • [mfadhilgtg.github.io](https://github.com/mfadhilgtg)

EDUCATION

- 2018-Now **Master of Science in Robotics, System, and Control** - ETH ZÜRICH
GPA: 5.65/6.00 | Tutor: Prof. Margarita Chli
- 2013-2017 **Bachelor of Science in Electrical Engineering** - INSTITUT TEKNOLOGI BANDUNG
GPA: 3.94/4.00 | Advisor: Prof. Bambang Riyanto Trilaksono

EXPERIENCE

- SEP 2019 - NOW NASA JET PROPULSION LABORATORY(JPL), Pasadena, CA, USA
Visiting Robotics Researcher
Developing innovative multi-robot system for underground operation participating in DARPA Subterranean Challenge.
Highlights: *Mixed Reality, Face Recognition, Design Thinking, Magic Leap One, Unity, C++.*
- MAR 2019 - SEP ETH JUNIORS, Zürich, Switzerland
Magic Leap Mixed Reality Developer
Developing mixed reality application using face recognition and virtual interaction for healthcare industry.
Highlights: *Mixed Reality, Face Recognition, Design Thinking, Magic Leap One, Unity, C++.*
- FEB 2019 - AUG ETH ZÜRICH, Zürich, Switzerland
Graduate Research Student, Autonomous System Laboratory(ASL)
Designing learning based method to perform visual localization and mapping using text based landmark, and leveraging text descriptor with existing localization method in place recognition task.
Supervisor: Dr. Cesar Dario Cadena
Research Student, Vision for Robotics Lab(V4RL)
Designing swarm drones formation estimation using relative distance between agents in distributed system.
Supervisor: Prof. Margarita Chli
Highlights: *Deep Learning, SLAM, Tracking, Mapping, Computer Vision, Sensor Fusion, EKF, CUDA, TensorFlow, Python, C++, ROS.*
- MAY 2017 - AUG 2018 BANDUNG INSTITUTE OF TECHNOLOGY, Bandung, Indonesia
Robotics Engineer, Advanced Robotics Research Laboratory
Developed navigation and guidance system for Autonomous Underwater Glider, and conducted sea testing.
Supervisor: Prof. Dr. Ir. Bambang Riyanto Trilaksono
Highlights: *Autonomous Underwater Vehicle(AUV), Sonar, IMU, Altimeter, Sensor Fusion, Path Planning, Hardware-in-the-loop (HIL) simulation, C++, ROS.*
- JUN 2016 -AUG 2016 CERN, Geneva , Switzerland
Summer Intern, CERN Summer Student Programme 2016
Devised a controlled high voltage module for Micro Pattern Gas Detectors(MPGD), wrote the report and presented the result to MPGD Collaboration.
Supervisor: Dr. Leszek Ropelewski
Highlights: *GEMs Detector, PCB Design, LabVIEW, HV Power Supply, Microcontroller, C++.*

PUBLICATIONS

1. **Ginting, M. F.**, et al.“Hardware In the Loop Simulation Development of Guidance System for Autonomous Underwater Glider.”*International Conference on Electrical Engineering and Informatics*, 2017.

SKILLS

- Language** ENGLISH(Proficient C1, IELTS 7.5/9.0) , GERMAN(Independent B1), INDONESIAN(Native)
- Programming** C/C++, Python, MATLAB, Bash(●●●●●), Java, VHDL(●●●●○),C#,MySQL(●●●○)
- Software** Systems(Linux, Windows, ROS, Virtual Box), Tensorflow, Pytorch, CUDA, OpenCV, PCL, Eigen, LabVIEW, MPI, Eagle, Altium Designer, IDEs(Visual Studio, Unity, Android Studio)
- Hardware** NVIDIA Jetson, FPGA, Beaglebone, Raspberry-Pi, TS-7250 SBC, ARM STM32

AWARDS AND ACHIEVEMENT

- PRESENT MINISTRY OF FINANCE OF INDONESIA - Awardee of LPDP Education Scholarship(CHF 59,000)
- 2017 MCKINSEY YOUNG LEADER FOR INDONESIA 2016 - Top 10 graduates(USD 1,000)
- 2016 INSTITUT TEKNOLOGI BANDUNG - Outstanding Student Award
- 2015 ABU ROBOCON(ASIA PACIFIC BROADCASTING UNION ROBOT CONTEST) - 2nd Runner Up

SOCIAL ACTIVITIES

2017 *Project Lead*, Assesment Center Project - McKinsey Young Leader for Indonesia

2016 *Chairman*, University Student Robotics Team

2015 *Senior Staff of Character Development Division*, Electrical Engineering Student Association

Hobbies : Tennis, Travelling, Photography, Reading

Master of Science in ROBOTICS, SYSTEM AND CONTROL Grades

Exam	Grade	Credit Hrs
System Identification	6/6	4
Robot Dynamics	5.75/6	4
Probabilistic Artificial Intelligence	5.75/6	4
Programming for Robotics	6/6	1
Computer Vision	5.25/6	6
Self-Organizing Multi-Agent Systems	5.75/6	3