#### **REPORT**

# Breast Ultrasound Noise Reduction and Simple ML Classification Prepared by: Muhammad Ridzuan

### Task 1: Breast Ultrasound

Task 1.1. Split data for training and testing using the first (sorted in an ascending order by ID) 80% of images per class for training and the remaining 20% for testing. Report a table with the number of images for training and testing for each class.

FOLDER PATH = "/share/data drivel/Dataset BUSI with GT4"

#### Code:

```
FILES = glob.glob(os.path.join(FOLDER PATH, "*", "*.png"))
def flatten(t):
    return [item for sublist in t for item in sublist]
dt = \{\}
patient ids = []
unique_patient ids = []
labels = []
files = []
for i in FILES:
    if "mask" in i:
        # ignore any mask files
       pass
    else:
        patient_id = i.split("(") [1].split(")") [0]
        categ = i.split("/")[-2]
        if categ == "normal":
            label = 0
            unique patient id = "n" + patient id
        elif categ == "benign":
            label = 1
            unique_patient_id = "b" + patient id
        elif categ == "malignant":
            label = 2
            unique patient id = "m" + patient id
        patient id = int(patient_id)
        patient ids.append(patient id)
        unique patient ids.append(unique patient id)
        labels.append(label)
        files.append(i)
# convert lists to dataframe
df = pd.DataFrame([files, patient ids, unique patient ids, labels]).T
df = df.rename(columns={0: "filepath", 1: "patient_id", 2: "unique_patient_id", 3:
"label"})
# sort values in ascending order by label, then by patient id
df = df.sort values(["label", "patient id"])
df.reset index(drop=True, inplace=True)
train pid, test pid = [], []
y train, y test = [], []
for i in set(df["label"]):
    X = df[df["label"] == i]["unique patient id"].values
    y = df[df["label"] == i]["label"].values
    X_train_by_class, X_test_by_class, y_train_by_class, y_test_by_class =
         train_test_split(X, y, test_size=0.2, shuffle=False)
    print("class {}: {} train samples, {} test samples".format(i, len(X_train_by_class),
         len(X test by class)))
    train_pid.append(X_train_by_class)
    test pid.append(X test by class)
```

```
y_train.append(y_train_by_class)
y_test.append(y_test_by_class)

# flatten list
train_pid = flatten(train_pid)
test_pid = flatten(test_pid)
y_train = flatten(y_train)
y_test = flatten(y_train)
y_test = flatten(y_test)

print("\nTotal:\t {} train samples, {} test samples".format(len(train_pid), len(test_pid)))
```

### Result:

```
class 0: 106 train samples, 27 test samples
class 1: 349 train samples, 88 test samples
class 2: 168 train samples, 42 test samples
Total: 623 train samples, 157 test samples
```

Class	Number of Train Samples	Number of Test Samples
0 Normal	106	27
1 Benign	349	88
2 Malignant	168	42
Total	623	157

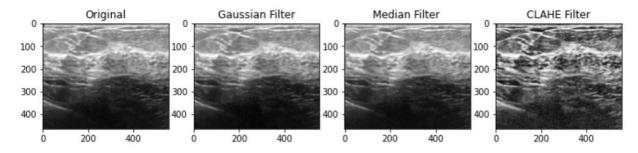
Task 1.2. Use 3 different filtering techniques to reduce noise. This will create 3 versions of each image which will be added to the training set. Include a brief description for the selection of these filters and the main parameters used for each filter.

#### Code:

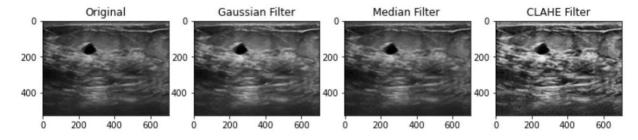
```
X train filepaths = []
for unique pid in train pid:
    filepath = df[df["unique patient id"] == unique pid]["filepath"].values[0]
    filepath out = filepath.split(".png")[0]
    label = df[df["unique patient id"] == unique pid]["label"].values[0]
    \# Using 0 to read image in grayscale mode
    img = cv2.imread(filepath, 0)
    # apply filters
    img gauss = filters.gaussian(img, sigma=1)
    img med = filters.median(img)
    # CLAHE Adaptive Histogram Equalization
    clahe = cv2.createCLAHE(clipLimit=2.0, tileGridSize=(8, 8))
    img clahe = clahe.apply(img)
    cv2.imwrite(filepath_out + "_gauss.png", img_gauss)
cv2.imwrite(filepath_out + "_med.png", img_med)
cv2.imwrite(filepath_out + "_clahe.png", img_clahe)
    X train filepaths.append([filepath, filepath out + " gauss.png", filepath out +
         "_med.png", filepath_out + " clahe.png"])
    # plot sample images
    if "(15)" in filepath out:
        fig, ((ax1, ax2, ax3, ax4)) = plt.subplots(1, 4, figsize=(12,8))
        [print("benign") if label == 1 else print("malignant") if label == 2 else
         print("normal")]
        ax1.set_title("Original")
        ax1.imshow(img, cmap="gray")
        ax2.set title("Gaussian Filter")
        ax2.imshow(img gauss, cmap="gray")
        ax3.set title("Median Filter ")
        ax3.imshow(img_med, cmap="gray")
        ax4.set title("CLAHE Filter")
        ax4.imshow(img clahe, cmap="gray")
        plt.show()
# flatten train filepaths
X train filepaths = [item for sublist in X train filepaths for item in sublist]
# multiply each label by 4 (since there are 4 versions of each image: 1 ori + 3 augs)
y train = [[i]*4 for i in y train]
# flatten y train
y train = [item for sublist in y train for item in sublist]
```

# **Result:**

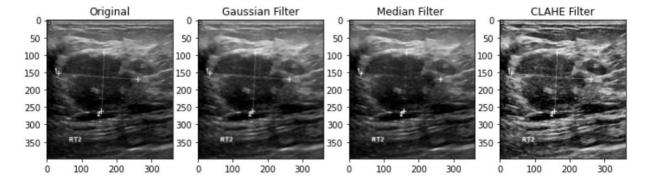
normal



benign



malignant



# **Brief Description:**

I chose the Gaussian, median, and contrast limited adaptive histogram equalization (CLAHE) filters as are commonly used in mammograms [1, 2, 3]. The Gaussian and median filters are effective at reducing speckle and salt and pepper noises. The Gaussian filter takes a sigma input which defines the standard deviation of the Gaussian kernel, while the median filter returns the local median of an image for a given kernel size. The CLAHE filter helps to enhance the contrast of an image via a histogram adjustment strategy. This filter is used with the intention of highlighting important features of the image for the model to distinguish between the normal and abnormal regions.

### Task 2: Classification of breast ultrasound images

Develop a machine learning algorithm trained and tested on Task 1.1 data. Use the data from Task 1.2 for training only.

- Describe the data augmentation strategy used and the choice of network architecture.
- Try **exactly** 5 different values for some hyperparameters.
- Report the accuracy, confusion matrices, figures for training accuracy and loss for the top 2 experiments performed.

#### Code:

```
if torch.cuda.is available():
    device = torch.device("cuda:0")
else:
    device = torch.device("cpu")
def flatten(t):
    return [item for sublist in t for item in sublist]
def train_val(exp_name):
   train loss = []
   train acc = []
   val loss = []
   val acc = []
    best accuracy = 0
    for epoch num in range(0, epochs):
        model.train()
        epoch_total_loss = 0
        correct = 0
        for batch num, (inp, target) in enumerate(train loader):
            optimizer.zero grad()
            output = model(inp.to(device))
            batch loss = criterion(output, target.to(device))
            , batch prediction = torch.max(output, dim=1)
            epoch total loss += batch loss.item()
            batch_loss.backward()
            optimizer.step()
            correct += (batch_prediction == target.to(device)).float().sum()
        accuracy = 100 * correct / len(train_dataset)
        avrg loss = epoch total loss / train dataset. len ()
        train loss.append(avrg loss)
        train acc.append(accuracy.detach().cpu())
        model.eval()
        with torch.no grad():
           labels = []
            predictions = []
            epoch_total_loss = 0
            for (inp, target) in val loader:
                labels+=target
                batch prediction = model(inp.to(device))
                batch loss = criterion(batch prediction, target.to(device))
                epoch total loss += batch_loss.item()
                 , batch prediction = torch.max(batch prediction, dim=1)
                predictions += batch prediction.detach().tolist()
            accuracy_val = metrics.accuracy_score(labels, predictions)*100
            avrg_loss_val = epoch_total_loss / val_dataset._len_()
            val loss.append(avrg loss val)
            val acc.append(accuracy val)
        if accuracy_val > best_accuracy:
            best accuracy = accuracy val
```

```
torch.save(model.state dict(), FOLDER PATH +
"/best acc {}.pt".format(exp name))
        print("Epoch %d - loss=%0.4f - acc=%0.4f - val-loss=%0.4f - val-acc=%0.4f" %
(epoch num, avrg loss, accuracy, avrg loss val, accuracy val))
    return train loss, train acc, val loss, val acc
def test(exp name):
    model.eval()
    labels = []
    predictions = []
    test loss = []
    test acc = []
    for (inp, target) in test loader:
        labels+=target
        batch prediction = model(inp.to(device))
        _, batch_prediction = torch.max(batch prediction, dim=1)
        predictions += batch_prediction.detach().tolist()
    accuracy = metrics.accuracy score(labels, predictions)
    print("Test Accuracy = %0.2f" % (accuracy))
    confusion = metrics.confusion matrix(labels, predictions)
   print(exp name)
   sns.heatmap(confusion, annot=True, cmap='Blues')
    plt.title("Confusion Matrix (sample count)")
    plt.show()
    sns.heatmap(confusion/np.sum(confusion), annot=True,
            fmt='.1%', cmap='Blues')
    plt.title("Confusion Matrix (%)")
    plt.show()
X_train_filepaths = []
X val filepaths = []
for label in ["normal", "benign", "malignant"]:
    files = [i for i in X train filepaths if label in i]
    files = sorted(files)
    # indices of unique patients
    pid = [i*4 for i in range(int(len(files)/4))]
    # (incorrect) labels of unique patients - used as a placeholder..
    y tr = [sorted(y train)[i] for i in pid]
    # get indices of train-val splits
    X_tr_u, X_val_u, _, _ = train_test_split(pid, y_tr, test_size=0.2)
X_tr_u = flatten([[i, i+1, i+2, i+3] for i in X_tr_u])
    X \text{ val } u = \text{flatten}([[i, i+1, i+2, i+3] \text{ for } i \text{ in } X \text{ val } u])
    \# get elements of train-val splits
    X tr2 = [X train filepaths[i] for i in X tr u]
    X val2 = [X train filepaths[i] for i in X val u]
    X train filepaths.append(X tr2)
    X val filepaths.append(X val2)
X train filepaths = flatten(X train filepaths)
X_val_filepaths = flatten(X_val_filepaths)
# create train & test directories, then move (copy) files
train dest = FOLDER PATH + "/train"
val dest = FOLDER PATH + "/val"
test dest = FOLDER PATH + "/test"
if not os.path.exists(train dest):
```

```
os.mkdir(train dest)
    os.mkdir(train_dest + "/normal")
    os.mkdir(train dest + "/benign")
    os.mkdir(train dest + "/malignant")
if not os.path.exists(val dest):
    os.mkdir(val_dest)
    os.mkdir(val_dest + "/normal")
os.mkdir(val_dest + "/benign")
    os.mkdir(val dest + "/malignant")
if not os.path.exists(test dest):
    os.mkdir(test_dest)
    os.mkdir(test_dest + "/normal")
os.mkdir(test_dest + "/benign")
    os.mkdir(test_dest + "/malignant")
for file in X train filepaths2:
    filename = file.split("/")[-1]
    folder labelname = file.split("/")[-2]
    shutil.copy(file, os.path.join(train dest, folder labelname, filename))
for file in X val filepaths:
    filename = file.split("/")[-1]
    folder labelname = file.split("/")[-2]
    shutil.copy(file, os.path.join(val dest, folder labelname, filename))
for file in X test filepaths:
    filename = file.split("/")[-1]
    folder_labelname = file.split("/")[-2]
    shutil.copy(file, os.path.join(test dest, folder labelname, filename))
train dataset = DatasetFolder(root=train dest + "/",
                                loader=cv2.imread,
                                extensions=(".png",),
                                transform=transforms.Compose([
                                    transforms.ToTensor(),
                                    transforms.RandomHorizontalFlip(p=0.5),
                                    transforms.RandomAffine(degrees=0, scale=(1, 1.15)),
                                    transforms.RandomApply(torch.nn.ModuleList([
                                        transforms.RandomRotation((90,90)),
                                        transforms.RandomRotation((180,180)),
                                        transforms.RandomRotation((270,270)),
                                    ]), p=0.5),
                                    transforms.Resize((256,256)),
                               ]
                           ))
val dataset = DatasetFolder(root=val dest + "/",
                               loader=cv2.imread,
                                extensions=(".png",),
                               transform=transforms.Compose([
                                    transforms.ToTensor(),
                                    transforms. Resize ((256, 256)),
                           ))
test dataset = DatasetFolder(root=test dest + "/",
                                loader=cv2.imread,
                                extensions=(".png",),
                                transform=transforms.Compose([
                                    transforms. To Tensor(),
                                    transforms.Resize((256,256)),
                                ]
                           ))
train loader = DataLoader(train dataset,
                           batch size=4,
```

```
shuffle=True,
                          num workers=0)
val loader = DataLoader(val dataset,
           batch size=4,
            shuffle=False,
            num workers=0)
test loader = DataLoader(test dataset,
            batch size=4,
            shuffle=False,
            num workers=0)
# parameters
epochs = 15
lr = 1e-3
weights = [4.0, 1.0, 2.0]
weight decay = 0.2
dropout = 0.5
model = resnet18(num\_classes=3).to(device)
if dropout is not None:
    model.fc = nn.Sequential(nn.Dropout(dropout),
                             nn.Linear(model.fc.in_features, 3)).to(device)
class weights = torch.FloatTensor(weights).to(device)
criterion = CrossEntropyLoss(weight=class weights)
optimizer = optim.Adam(model.parameters(),lr=lr,weight decay=weight decay)
train loss1, train acc1, test loss1, test acc1 = train val("expX")
test("expX")
print("Train (blue) vs. Val (red)")
plt.plot([i for i in range(epochs)], train_loss1, color="b")
plt.plot([i for i in range(epochs)], test loss1, color="r")
plt.xlim(0,20)
plt.title("Loss")
plt.show()
plt.plot([i for i in range(epochs)], train_acc1, color="b")
plt.plot([i for i in range(epochs)], test acc1, color="r")
plt.xlim(0,20)
plt.title("Accuracy")
plt.show()
```

## **Description:**

Based on a work published on abnormality diagnosis in mammograms [4], I chose ResNet18 as my network architecture as the authors have found it to give the best performance compared to other larger ResNet architectures.

I augmented the images primarily using geometric transformations to create combinations that are likely to be representative of a blind test image. Following [4], [5], and [6], I used a random horizontal flip, random upscaling up to 115%, and random rotation between 90, 180, and 270 degrees. I resized the images to 256.

Given the dissimilarity between ImageNet and mammograms, I decided to train the network from scratch instead of using pretrained ImageNet weights. My experiments were as follows:

Experiment 1. ResNet18 baseline, 15 epochs, learning rate of 1e-3. This gives an accuracy of 0.43.

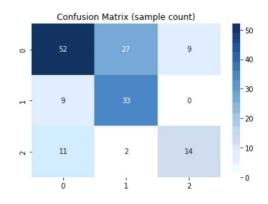
Experiment 2. Given that the classes were imbalanced with the test set having 27, 88, and 42 samples for normal, benign, and malignant images respectively, I added class weights in inverse proportions [4, 1, 2] to penalize the model more for misclassifying samples with the least number of samples. This increased the accuracy to 0.52.

Experiment 3. In Experiments 1 and 2, the model had overfitted to the training set. To reduce this overfitting, I added dropout to the fully connected layer with a probability of 0.5. This increased the accuracy to 0.54.

Experiment 4. Given the sporadic accuracy and losses, I reduced the learning rate to 1e-5. This resulted in a more stable loss, and an improved accuracy to 0.63.

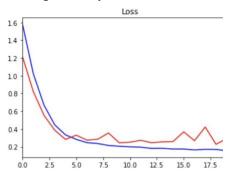
Experiment 5. Finally, I combined the previous experiments by adding class weight [4, 1, 2], dropout of 0.4, and learning rate 1e-5. This gave the best accuracy of 0.67..

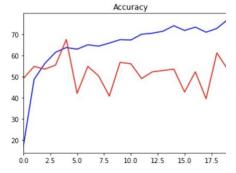
# Results: Experiment 4 (Accuracy 0.63)



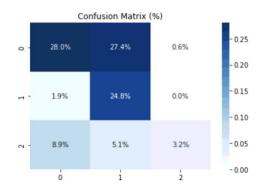


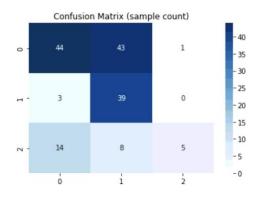
# **Training accuracy and loss**



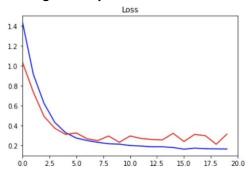


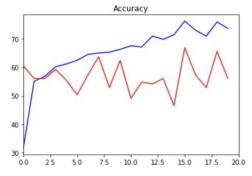
# **Experiment 5 (Accuracy 0.67)**





# **Training accuracy and loss**





## Task 3: Visualization of heat maps

- Use the best classification model to create heatmaps that highlight the regions on images which contributed to the classification results. Discuss briefly the way you achieved this.
- Report results by showing 6 images from testing set with heat maps super-imposed. These 6 images are 2 images (one correct and one incorrect classification) from each class.

#### **Brief discussion:**

I used GradCAM inspired by the code from <a href="https://github.com/jacobgil/pytorch-grad-cam">https://github.com/jacobgil/pytorch-grad-cam</a>. In order to find the correctly and incorrectly classified images, I used GradCAM's inbuilt function to compare the heatmap from the model's prediction versus the heatmap from the class labels. If the heatmaps match, the image is correctly classified; otherwise, the image is incorrectly classified.

#### Code:

```
!pip install grad-cam
import glob, os, cv2
from pytorch grad cam import GradCAM, ScoreCAM, GradCAMPlusPlus, AblationCAM, XGradCAM,
from pytorch grad cam.utils.image import show cam on image
from torchvision.models import resnet50
def my gradcam(model path, input path, true label, correct prediction=True):
    true_label: "malignant", "benign", or "normal"
   model = resnet18(num classes=3)
    model.load state dict(torch.load(model path))
    target layers = [model.layer4[-1]]
    if true label == "malignant":
    target_category = 2
elif true_label == "benign":
       target category = 1
    elif true_label == "normal":
        target category = 0
    if true label in input path:
        img = cv2.imread(input path, 1)
        img = cv2.resize(img, (256, 256))
        filename = input_path.split("/") [-1].split(".png") [0]
        input tensor = transforms.ToTensor()(img).unsqueeze (0)
        input tensor = input tensor.expand(-1, 3, -1, -1)
        cam = GradCAM(model=model, target layers=target layers, use cuda=True)
        grayscale cam predicted label = cam(input tensor=input tensor,
                                             target category=None)
        grayscale_cam_true_label = cam(input_tensor=input_tensor,
                                         target category=target category)
        if correct prediction:
            if np.array equal (grayscale cam predicted label, grayscale cam true label):
                print("{} Prediction".format(correct prediction))
                print(filename)
                grayscale cam = grayscale cam predicted label[0, :]
                visualization = show cam on image(img/255, grayscale cam, use rgb=True)
                plt.imshow(visualization)
                plt.show()
                return
```

else:

```
if not np.array equal(grayscale cam predicted label, grayscale cam true label):
                print("{} Prediction".format(correct prediction))
                print(filename)
                grayscale cam = grayscale cam predicted label[0, :]
                visualization = show cam on image(img/255, grayscale cam, use rgb=True)
                plt.imshow(visualization)
                plt.show()
                return
FOLDER PATH = "/share/data drive1/Dataset BUSI with GT"
current testpaths = glob.glob(os.path.join(FOLDER PATH, "test", "*", "*"))
for testpath in current testpaths:
    my gradcam("/share/data drive1/Dataset BUSI with GT/best acc exp2.pt", testpath,
                  "malignant", True)
    my gradcam("/share/data drive1/Dataset BUSI with GT/best acc exp2.pt", testpath,
                  "malignant", False)
for testpath in current testpaths:
    my gradcam("/share/data drive1/Dataset BUSI with GT/best acc exp2.pt", testpath,
                  "benign", True)
    my_gradcam("/share/data_drive1/Dataset_BUSI_with_GT/best_acc_exp2.pt", testpath,
                  "benign", False)
for testpath in current testpaths:
    my gradcam("/share/data drive1/Dataset BUSI with GT/best acc exp2.pt", testpath,
                  "normal", True)
    my_gradcam("/share/data_drive1/Dataset_BUSI_with_GT/best acc exp2.pt", testpath,
                  "normal", False)
```

# **Results:**

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From the GradCAM outputs, the model seems to be able to focus on specific regions for the correctly predicted images. Conversely, on the incorrectly classified images, the heatmaps seem more spread out, and the model has a harder time focusing on specific regions of the image. This suggests that the model has not yet fully learned the proper features that distinguish the abnormalities on the mammograms

<u>.</u> <u>.</u> <u>.</u> <u>.</u> True Prediction False Prediction normal (112) normal (109) 50 100 100 150 150 200 200

150

200

#### References

- [1] Mari, Kamarasan & Santhakumari, V. (2020). Early Detection of Breast Cancer using Image Processing Techniques: A Study on Mammogram Image Analysis. XII. 2266-2296.
- [2] Kshema, & George, Jayesh & Dhas, Anto. (2017). Preprocessing filters for mammogram images: A review. 1-7. 10.1109/ICEDSS.2017.8073694.
- [3] Pisano, Etta & Cole, Elodia & Hemminger, Bradley & Yaffe, Martin & Aylward, Stephen & Maidment, Andrew & Johnston, R. & Williams, Mark & Niklason, Loren & Conant, Emily & Fajardo, Laurie & Kopans, Daniel & Brown, Marylee & Pizer, Stephen. (2000). Image Processing Algorithms for Digital Mammography: A Pictorial Essay1. Radiographics: a review publication of the Radiological Society of North America, Inc. 20. 1479-91. 10.1148/radiographics.20.5.g00se311479.
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- [5] Abdelhafiz, D., Yang, C., Ammar, R. *et al.* Deep convolutional neural networks for mammography: advances, challenges and applications. *BMC Bioinformatics* **20**, 281 (2019). https://doi.org/10.1186/s12859-019-2823-4
- [6] Costa, Arthur & Oliveira, Helder & Catani, Juliana & Barros, Nestor & Melo, Carlos & Vieira, Marcelo. (2019). Detection of Architectural Distortion with Deep Convolutional Neural Network and Data Augmentation of Limited Dataset. 10.1007/978-981-13-2517-5\_24.