

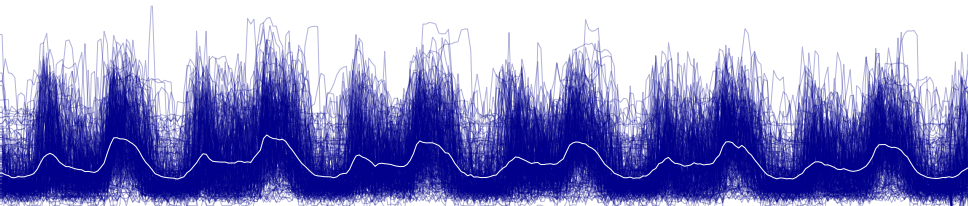
Electricity demand forecasting with Generalised Additive Models

Matteo Fasiolo

matteo.fasiolo@bristol.ac.uk

Material available at:

https://github.com/mfasiolo/GAM_Workshop_DS_Soc



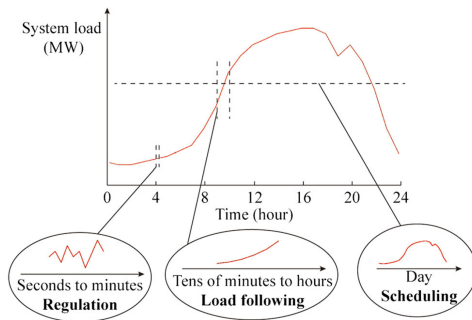
- 1 Why electricity demand forecasting?
- 2 What is a GAM?
- 3 Introducing smooth effects
- 4 GAM modelling with mgcv and mgcViz

Electricity demand forecasting

Electric power system present some unique challenges:

- very limited storage
- supply must meet demand in near-real time

Short-term operations rely on accurate forecasts at several time scales:



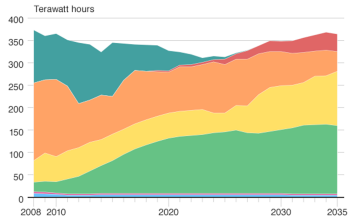
Kroposki (2017)

Electricity demand forecasting

Importance of forecasts increased by developments on **supply side**:

Projected sources of energy generation in the UK

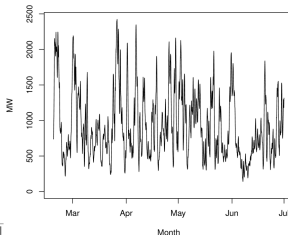
Coal Coal and gas with carbon capture Gas Nuclear
Renewable Storage Oil and other thermal



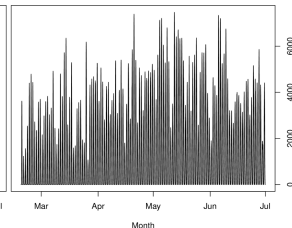
Source: Department of Energy & Climate Change (November 2015)

BBC

UK wind generation 2016



UK solar generation 2016



- increased renewable penetration → **more uncertainty**
- fossil fuel replaced by nuclear plants → **less flexibility**

Supply-side uncertainty & less tolerance to forecasting errors.

Electricity demand forecasting

Demand-side and IT trends:

- emergence of prosumers
 - embedded solar & wind production
- smart meters in every home
 - handle larger and more complex data sets
- electric vehicles
 - higher load & uncertainty

Automated grid management systems to avoid distribution grid overload.

Forecasts at multiple levels of aggregation will be key input.

Electricity demand forecasting

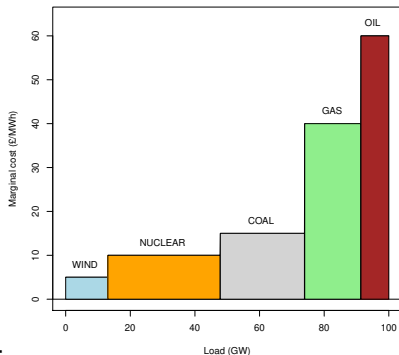
Focus on day-ahead forecast of aggregate UK demand.

Forecast is main input for decision in operations:

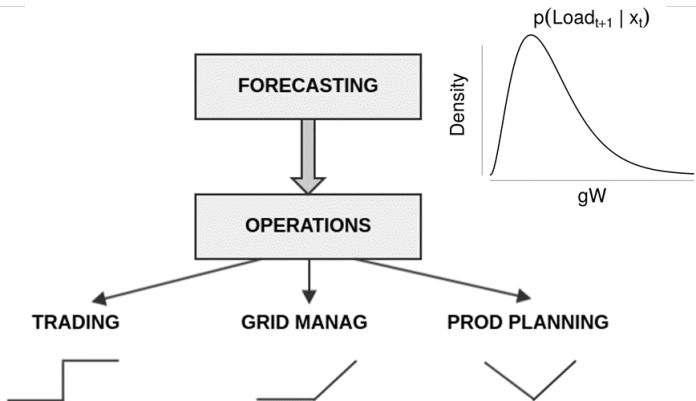
- trading
- grid management
- production planning

Each has specific loss functions:

- regulation
 - sanctions for over/under production
- technological factors
 - availability of storage and generation cost



Electricity demand forecasting



Optimization process:

$$D^* = \underset{D}{\operatorname{argmin}} \mathbb{E}\{L(\text{Load}_{t+1}, D)\}.$$

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What is an additive model

Regression setting:

- y is our response or dependent variable (demand here)
- \mathbf{x} is a vector of covariates or independent variables

In **distributional regression** we want a good model for $\text{Dist}(y|\mathbf{x})$.

Model is $\text{Dist}_m\{y|\theta_1(\mathbf{x}), \theta_2, \dots, \theta_q\}$, where $\theta_1, \dots, \theta_q$ are param.

We assume that $\theta_2, \dots, \theta_q$ do not depend on \mathbf{x} .

Gaussian additive model:

$$y|\mathbf{x} \sim N\{y|\mu(\mathbf{x}), \sigma^2\},$$

where

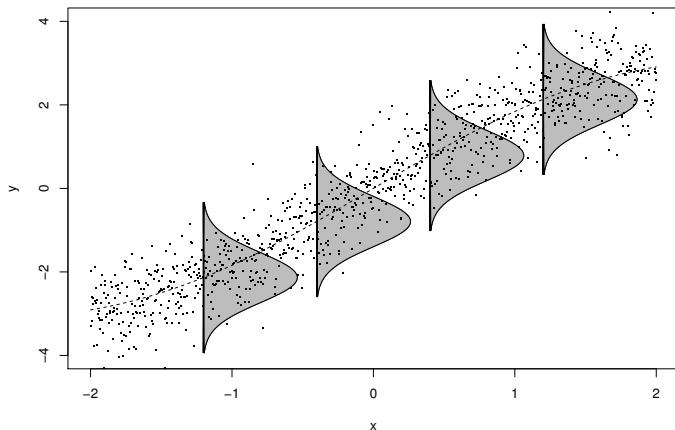
$$\mu(\mathbf{x}) = \sum_{j=1}^m f_j(\mathbf{x}),$$

and

$$\sigma^2 = \text{Var}(y|\mathbf{x}).$$

f_j 's can be linear or non-linear (smooth) effects.

NB: we call $\sum_{j=1}^m f_j(\mathbf{x})$ **linear predictor** because it is linear in β .



Gaussian model with variable mean.

In mgcv: `gam(y~s(x), family=gaussian).`

Generalized additive model (GAM) (Hastie and Tibshirani, 1990):

$$y|\mathbf{x} \sim \text{Distr}\{y|\theta_1 = \mu(\mathbf{x}), \theta_2, \dots, \theta_p\},$$

where

$$g\{\mu(\mathbf{x})\} = \sum_{j=1}^m f_j(\mathbf{x}),$$

and g is a one-to-one function.

Poisson GAM:

- $y|\mathbf{x} \sim \text{Pois}\{y|\mu(\mathbf{x})\}$
- $\mu(\mathbf{x}) = \exp\left\{\sum_{j=1}^m f_j(\mathbf{x})\right\}$
- $g = \log$ assures $\mu(\mathbf{x}) > 0$

Recall GAM model structure:

$$y|\mathbf{x} \sim \text{Distr}\{y|\theta_1 = \mu(\mathbf{x}), \theta_2, \dots, \theta_p\}.$$

Multi-parameter GAM structure (Wood et al., 2016):

$$y|\mathbf{x} \sim \text{Distr}\{y|\theta_1 = \mu_1(\mathbf{x}), \theta_2 = \mu_2(\mathbf{x}), \dots, \theta_p = \mu_p(\mathbf{x})\},$$

where

$$g_1\{\mu_1(\mathbf{x})\} = \sum_{j=1}^m f_j^1(\mathbf{x}), \quad \dots \quad g_p\{\mu_p(\mathbf{x})\} = \sum_{j=1}^m f_j^p(\mathbf{x}).$$

Special case are **Generalized Additive Models for Location Scale and Shape** (GAMLSS) (Rigby and Stasinopoulos, 2005).

See appendix for complete list of distributions in `mgcv`.

Example: **Gaussian location-scale model**

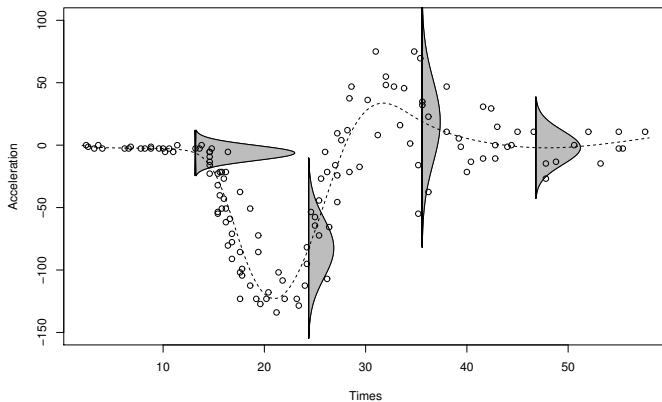
Model is

$$y|\mathbf{x} \sim N\{y|\mu(\mathbf{x}), \sigma^2(\mathbf{x})\}$$

where

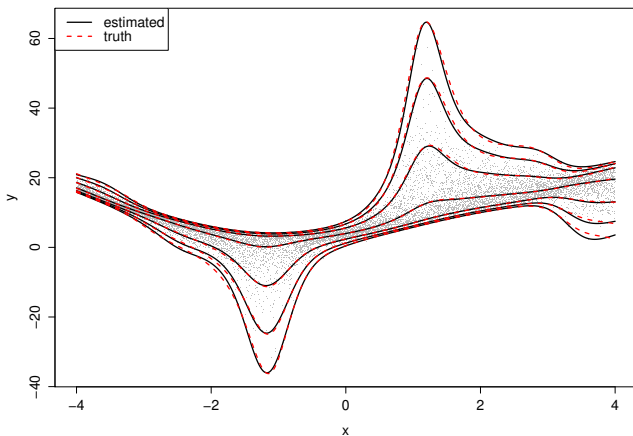
$$\mu(\mathbf{x}) = \sum_{j=1}^m f_j^1(\mathbf{x})$$

$$\log \sigma(\mathbf{x}) = \sum_{j=1}^m f_j^2(\mathbf{x})$$



In mgcv: `gam(list(y ~ s(x), ~ s(x)), family=gaulss).`

Example: **Sinh-arcsinh (shash) distribution** (Jones and Pewsey, 2009)



```
gam(list(y~s(x), ~s(x), ~s(x), ~s(x)), family=shash).
```


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Introducing smooth effects

Consider additive model

$$g\{\mu(\mathbf{x})\} = f_1(\mathbf{x}) + f_2(\mathbf{x}) + f_3(\mathbf{x}),$$

where

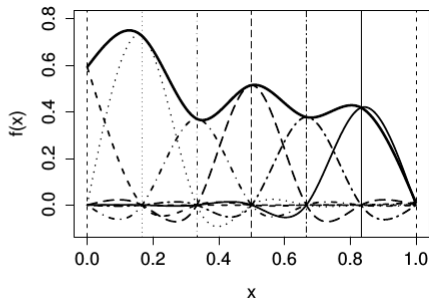
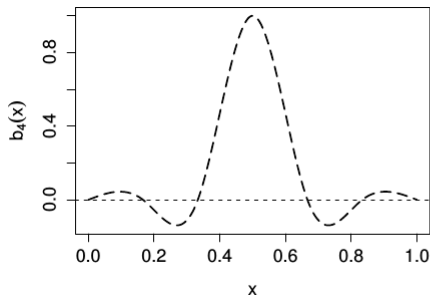
- $f_1(\mathbf{x}) = \beta_0 + \beta_1 x_1 + \beta_2 x_1^2$
- $f_2(\mathbf{x}) = \begin{cases} 0 & \text{if } x_2 = \text{FALSE} \\ \beta_4 & \text{if } x_2 = \text{TRUE} \end{cases}$
- $f_3(\mathbf{x}) = f_3(x_3)$ is a non-linear smooth function.

Smooth effects built using spline bases

$$f_3(x_3) = \sum_{k=1}^r \beta_k b_k(x_3)$$

where β_k are unknown coeff and $b_k(x_3)$ are known spline basis functions.

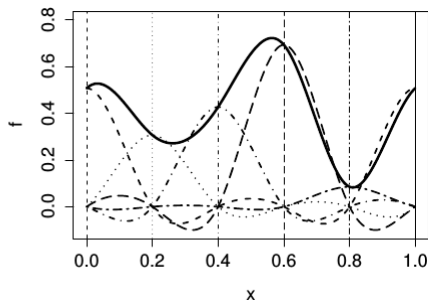
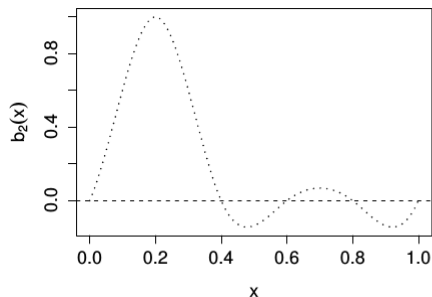
`s(x, bs = "cr", k = 20)`



Cubic regression splines are related to the optimal solution to

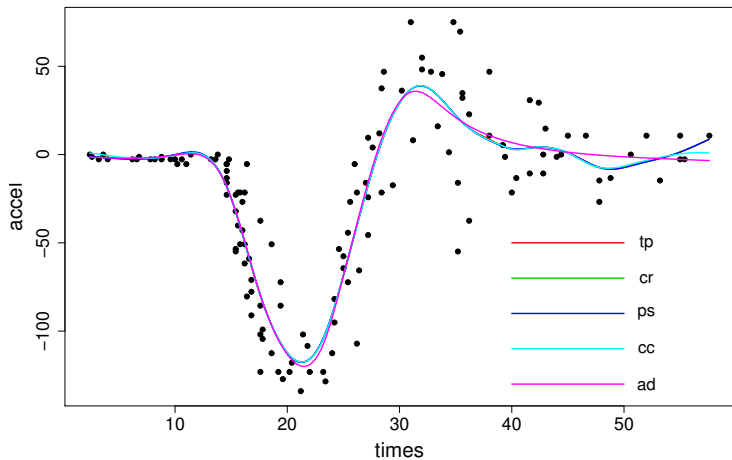
$$\sum_{i=1}^n \{y_i - f(x_i)\}^2 + \gamma \int f''(x)^2 dx.$$

mgcv offers many smooths (see `?smooth.terms`). `s(x, bs = "cc")`:



Cyclic cubic regression splines make so that

- $f(x_{min}) = f(x_{max})$
- $f'(x_{min}) = f'(x_{max})$
- $f''(x_{min}) = f''(x_{max})$

$s(x, \text{bs} = \text{"ad"})$


The wiggleness or smoothness of $f(x)$ depends on x .

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Recall structure of smooth effects:

$$f(\mathbf{x}) = \sum_{j=1}^k \beta_j b_j(\mathbf{x}).$$

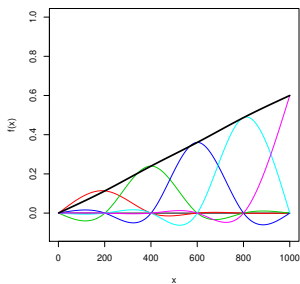
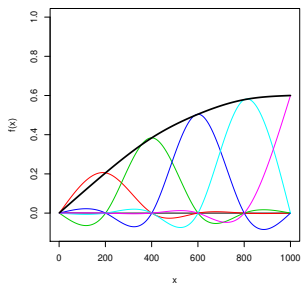
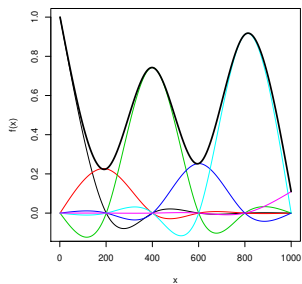
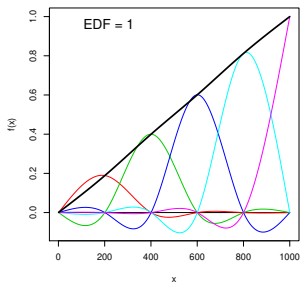
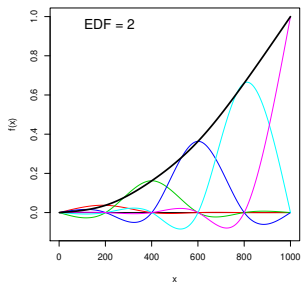
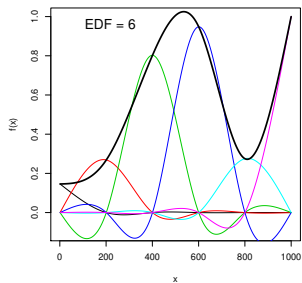
where β shrunk toward smoothness by penalty

$$\hat{\beta} = \underset{\beta}{\operatorname{argmax}} \left\{ \overbrace{\log p(\mathbf{y}|\beta)}^{\text{goodness of fit}} - \underbrace{\operatorname{Pen}(\beta|\gamma)}_{\text{penalize complexity}} \right\}$$

Exact k is unimportant, we choose it large and let penalty work.

Effective number of parameters we are using is $\leq k$.

Approximation is **Effective Degrees of Freedom** (EDF) $\leq k$.



Learning more

Here we covered basic GAM and GAMLSS modelling with `mgcv` and `mgcViz` (Fasiolo et al., 2018).

`mgcv` is a recommended R package, included in R by default.

There are alternatives to `mgcv` for GAM modelling, such as:

- `mboost` (Hothorn et al., 2010)
- `gamlss` (Rigby and Stasinopoulos, 2005)
- `brms` (Bürkner et al., 2017)
- `BayesX` (Brezger et al., 2003)
- `INLA` (Rue et al., 2009)

The `mgcv` ecosystem is still expanding.

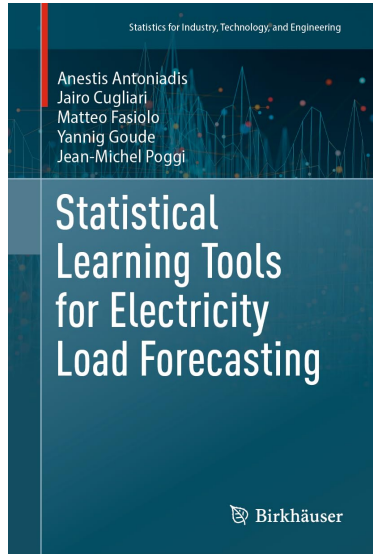
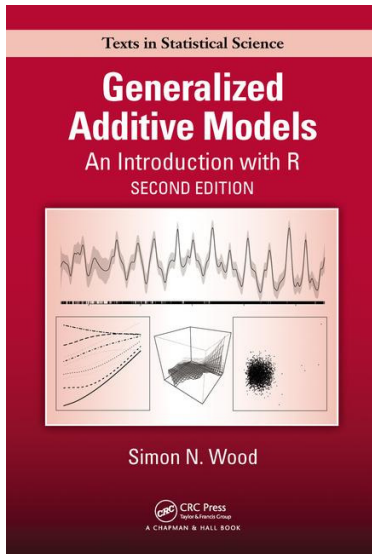
New developments are multivariate forecasting models with SCM package of Gioia et al. (2024):

<https://github.com/VinGioia90/SCM>

Quantile GAMs of Fasiolo et al. (2018) can be used to forecast demand without assuming its distribution.

See the `qgam` package on CRAN.

See also the Big Data GAM methods of Wood et al. (2017) and `mgcv::bam`.



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List of distributions in mgcv

Type `?mgcv::family` on the R console to see a list of distributions from the exponential family.

Wood et al. (2016) allows $\text{Distr} \not\in$ exponential family (**extended GAMs**):

- 1 `scat` \rightarrow scaled Student-t;
- 2 `betar` \rightarrow beta for $y \in (0, 1)$;
- 3 `ziP` \rightarrow zero-inflated Poisson;
- 4 `tw` \rightarrow Tweedie;
- 5 `ocat` \rightarrow order categorical;
- 6 `nb` \rightarrow negative binomial.

Note that these EGAMs have one linear predictor, i.e.

$$y_i | \mathbf{x}_i \sim \text{Distr}\{y_i | \theta_1(\mathbf{x}), \theta_2, \dots, \theta_p\}.$$

hence are not GAMLSSs.

Available GAMLSS families:

- ① `gammals` → 2-par gamma;
- ② `gaulss` → 2-par Gaussian;
- ③ `shash` → 4-par sinh-arsinh;
- ④ `ziplss` → 2-par zero-inflated Poisson;
- ⑤ `gevlss` → 3-par generalised extreme value distribution (GEV);
- ⑥ `gumb1s` → 2-par Gumbel (special case of GEV);
- ⑦ `twlss` → 3-par Tweedie.

z Further models are:

- ① `multinom` → multinomial categorical;
- ② `cox.ph` → Cox Proportional Hazards model;
- ③ `mvn` → multivariate Gaussian model (fixed covariance).