

# Intro to generalized additive models in R (with mgcv)

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Material available at:

[https://github.com/mfasiolo/GAM\\_Workshop\\_Enbis\\_EDF\\_23](https://github.com/mfasiolo/GAM_Workshop_Enbis_EDF_23)

# Workshop content

Today we will cover:

- 1 Intro to standard GAMs
- 2 Multi-parameter GAMs, including GAMLSS
- 3 Quantile GAMs

Focus on **GAM modelling**, not fitting/inferential/computational aspects.

We will mention but not explain Big Data methods for GAMs.

On Github you can find:

- 1 slides
- 2 html files for R demos
- 3 exercises and solutions

We firstly cover:

- 1 What is an additive model?
- 2 Introducing smooth effects
- 3 GAM modelling with mgcv and mgcViz

# What is an additive model

Regression setting:

- $y$  is our response or dependent variable
- $\mathbf{x}$  is a vector of covariates or independent variables

In **distributional regression** we want a good model for  $\text{Dist}(y|\mathbf{x})$ .

Model is  $\text{Dist}_m\{y|\theta_1(\mathbf{x}), \theta_2, \dots, \theta_q\}$ , where  $\theta_1, \dots, \theta_q$  are param.

We assume that  $\theta_2, \dots, \theta_q$  do not depend on  $\mathbf{x}$ .

**Gaussian additive** model:

$$y|\mathbf{x} \sim N\{y|\mu(\mathbf{x}), \sigma^2\},$$

where

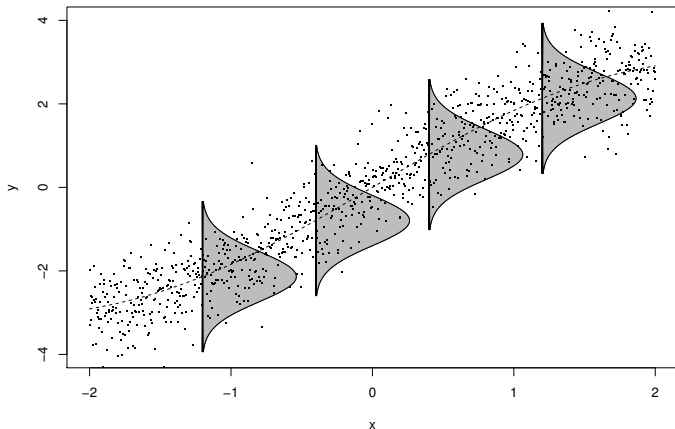
$$\mu(\mathbf{x}) = \sum_{j=1}^m f_j(\mathbf{x}),$$

and

$$\sigma^2 = \text{Var}(y|\mathbf{x}).$$

$f_j$ 's can be fixed, random or smooth effects.

NB: we call  $\sum_{j=1}^m f_j(\mathbf{x})$  **linear predictor** because it is linear in  $\beta$ .



Gaussian model with variable mean.

In mgcv: `gam(y~s(x), family=gaussian)`.

**Generalized** additive model (GAM) (Hastie and Tibshirani, 1990):

$$y|\mathbf{x} \sim \text{Distr}\{y|\theta_1 = \mu(\mathbf{x}), \theta_2, \dots, \theta_p\},$$

where

$$g\{\mu(\mathbf{x})\} = \sum_{j=1}^m f_j(\mathbf{x}),$$

and  $g$  is a one-to-one function.

Poisson GAM:

- $y|\mathbf{x} \sim \text{Pois}\{y|\mu(\mathbf{x})\}$
- $\mu(\mathbf{x}) = \exp\left\{\sum_{j=1}^m f_j(\mathbf{x})\right\}$
- $g = \log$  assures  $\mu(\mathbf{x}) > 0$

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# Introducing smooth effects

Consider additive model

$$g\{\mu(\mathbf{x})\} = f_1(\mathbf{x}) + f_2(\mathbf{x}) + f_3(\mathbf{x}),$$

where

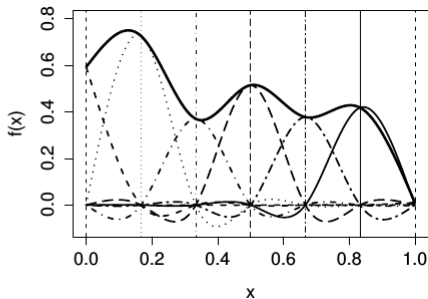
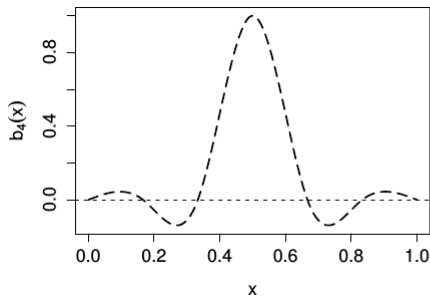
- $f_1(\mathbf{x}) = \beta_0 + \beta_1 x_1 + \beta_2 x_1^2$
- $f_2(\mathbf{x}) = \begin{cases} 0 & \text{if } x_2 = \text{FALSE} \\ \beta_4 & \text{if } x_2 = \text{TRUE} \end{cases}$
- $f_3(\mathbf{x}) = f_3(x_3)$  is a non-linear smooth function.

Smooth effects built using spline bases

$$f_3(x_3) = \sum_{k=1}^r \beta_k b_k(x_3)$$

where  $\beta_k$  are unknown coeff and  $b_k(x_3)$  are known spline basis functions.

`s(x, bs = "cr", k = 20)`



Knot-based cubic regression splines are related to the optimal solution to

$$\sum_{i=1}^n \{y_i - f(x_i)\}^2 + \gamma \int f''(x)^2 dx.$$

mgcv offers a wide variety of smooths (see `?smooth.terms`).

Univariate types:

- $s(x) = s(x, bs = "tp")$  thin-plate-splines
- $s(x, bs = "cr")$  cubic regression spline
- $s(x, bs = "ad")$  adaptive smooth

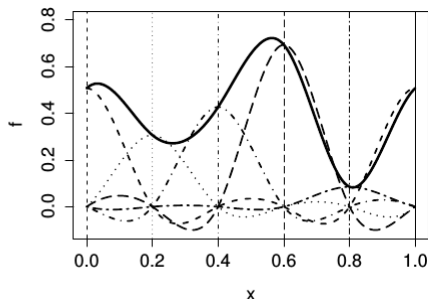
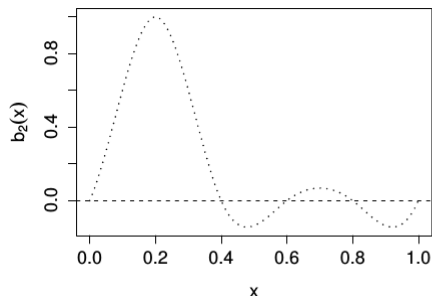
Multivariate type:

- $s(x1, x2) = s(x1, x2, bs = "tp")$  thin-plate-splines (isotropic)
- $te(x1, x2)$  tensor-product-smooth (anisotropic)
- $s(x, y, bs = "sos")$  smooth on sphere

They can depends on factors:

- $s(x, by = Subject)$
- $s(x, Subject, bs = "fs")$

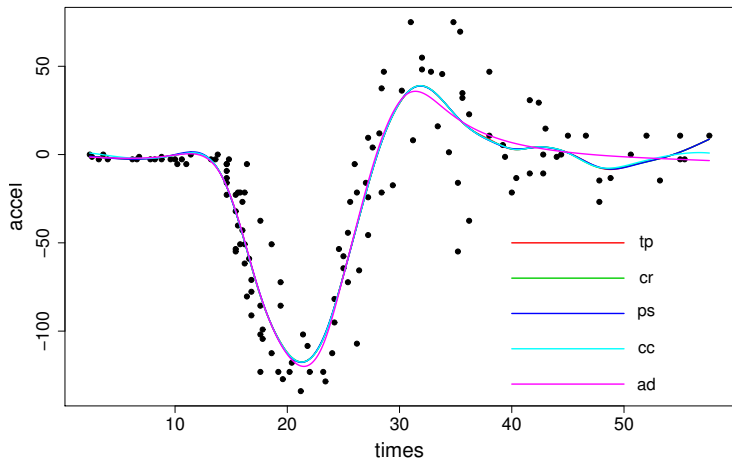
$s(x, \text{bs} = "cc")$



Cyclic cubic regression splines make so that

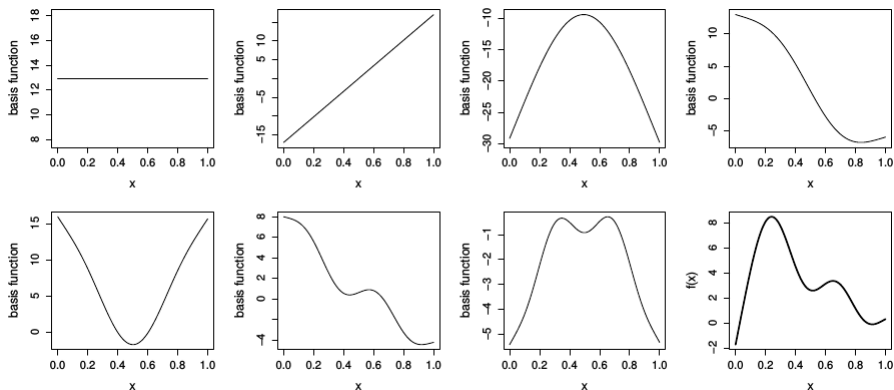
- $f(x_{min}) = f(x_{max})$
- $f'(x_{min}) = f'(x_{max})$
- $f''(x_{min}) = f''(x_{max})$

$s(x, \text{bs} = \text{"ad"})$

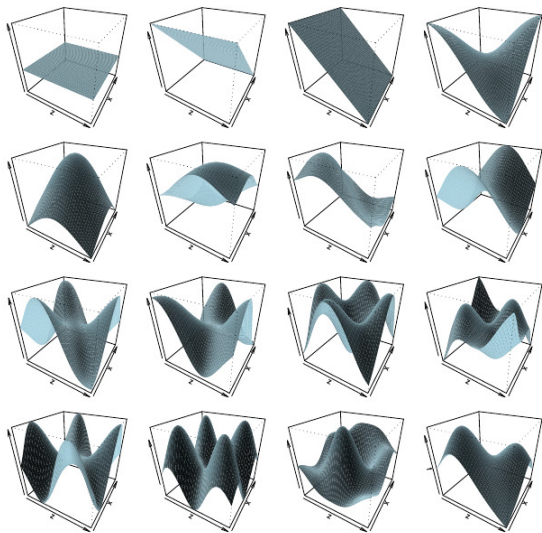


The wiggleness or smoothness of  $f(x)$  depends on  $x$ .

$s(x, \text{bs} = \text{"tp"})$  or  $s(x)$ : Thin plate regression splines (TPRS)



Rank 7 TPRS basis. Image from Wood (2017).



Rank 17 2D TPRS basis. Courtesy of Simon Wood.

$s(x_1, x_2), s(x_1, x_2, x_3), \dots$

Based on thin plate regression splines basis.

Related to optimal solution to:

$$\sum_i \{y_i - f(x_i, z_i)\}^2 + \gamma \int f_{xx}^2 + 2f_{xz}^2 + f_{zz}^2 dx dz$$

A single smoothing parameter  $\gamma$ .

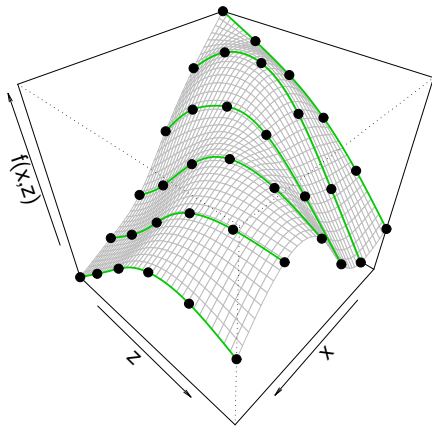
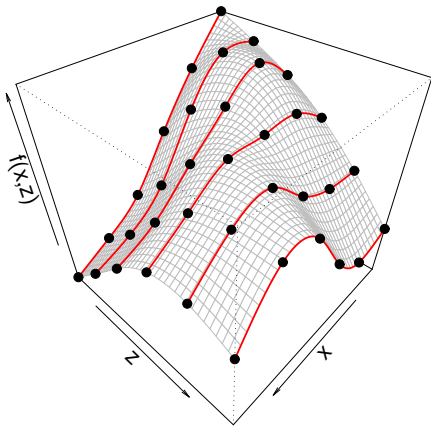
Isotropic: same smoothness along  $x_1, x_2, \dots$



Isotropic effect are ok if  $x_1, x_2$  are in same unit (e.g. Km).

If different units better use tensor product smooths  $\text{te}(x_1, x_2)$ .

- x-penalty: average wiggleness of red curves
- z-penalty: average wiggleness of green curves



Can use (almost) any kind of marginal:

- `te(x1, x2, x3)` product of 3 cubic regression splines bases
- `te(x1, x2, bs = c("cc", "cr"), k = c(10, 6))`
- `te(L0, LA, t, d=c(2,1), bs=c("tp","cc"))`

Basis of `te` contains functions of the form  $f(x_1)$  and  $f(x_2)$ .

To fit  $f(x_1) + f(x_2) + f(x_1, x_2)$  separately use:

```
y ~ ti(x1) + ti(x2) + ti(x1, x2)
```

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mgcv is a recommended R package, included in R by default.

There are alternatives to mgcv, such as:

- mboost (Hothorn et al., 2010)
- gamlss (Rigby and Stasinopoulos, 2005)
- brms (Bürkner et al., 2017)
- BayesX (Brezger et al., 2003)
- INLA (Rue et al., 2009)

The mgcv ecosystem:

- mgcViz visualising GAMs
- qgam quantile GAMs
- SCM multivariate Gaussian GAMs
- gamFactory aggregation of experts with GAMs
- and many others gamm4, refund, scam, vagam, GJRM, itsadug, ...

Recall structure of smooth effects:

$$f(\mathbf{x}) = \sum_{j=1}^k \beta_j b_j(\mathbf{x}).$$

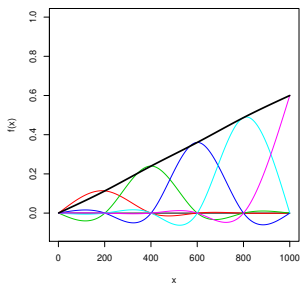
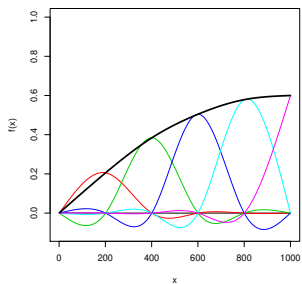
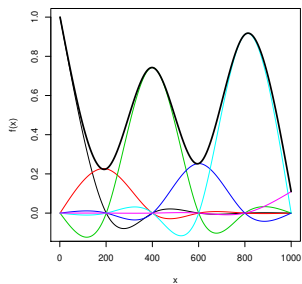
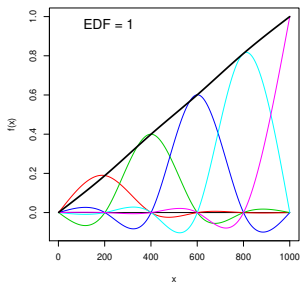
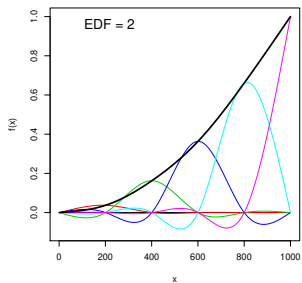
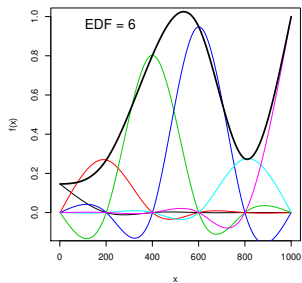
where  $\beta$  shrunk toward smoothness by penalty

$$\hat{\beta} = \underset{\beta}{\operatorname{argmax}} \operatorname{PenLogLik}(\beta|\gamma) = \underset{\beta}{\operatorname{argmax}} \left\{ \overbrace{\log p(\mathbf{y}|\beta)}^{\text{goodness of fit}} - \underbrace{\operatorname{Pen}(\beta|\gamma)}_{\text{penalize complexity}} \right\}$$

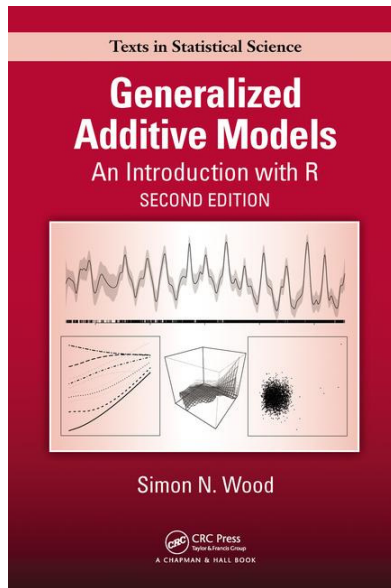
Exact  $k$  is unimportant, we choose it large enough and let penalty work.

Effective number of parameters we are using is  $\leq k$ .

Approximation is **Effective Degrees of Freedom** (EDF)  $\leq k$ .



## Further reading



# References I

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