Introducing mgcViz

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Material available at:

 $https://github.com/mfasiolo/workshop_EDF19$

Workshop plan

First session: basic mgcViz framework and tools

Talk + 30min hands-on session.

Second session: advanced mgcViz tools

Talk + 30min hands-on session.

Basic mgcViz: talk structure

These slides cover:

- 1 mgcViz: why do we need it and how does it work?
 - Limitations of mgcv plotting methods
 - mgcViz solution and smooth effects plots
- Diagnostics and model selection tools
 - QQ-plots with qq.gamViz
 - Layered checks
- Intro to hands-on session

Let's start with mgcv's standard plotting methods:

```
fit <- gam(y ~ s(x1) + s(x2, x3))
plot(fit)
```

this calls plot.gam:

```
plot(x,residuals=FALSE,rug=NULL,se=TRUE,pages=0,
    select=NULL,scale=-1,n=100,n2=40,n3=3,pers=FALSE,
    theta=30,phi=30,jit=FALSE,xlab=NULL,ylab=NULL,
    main=NULL,ylim=NULL,xlim=NULL,too.far=.1,
    all.terms=FALSE,shade=FALSE,shade.col="gray80",
    shift=0,trans=I,seWithMean=FALSE,
    unconditional=FALSE,by.resids=FALSE,scheme=0,...)
```

Quite a lot of arguments!

Let's group the main arguments:

- se,residuals,rug add optional graphical layers?
- \blacksquare 1D effect \rightarrow n or 2D \rightarrow n2,too.far,pers,jit,phi,theta
- vlab,ylab,main,ylim,xlim labs and limits
- select, all.terms which effects to plot?
- page,n3 control layout of multiple plots
- ... extra graphical parameters

Problems:

- order in which layers are rendered is fixed
- cannot change all graphical settings via "..."
- difficult to add new layers

mgvViz's solution is:

break GAM model into individual effects

```
fit <- getViz( gam(y ~ s(x1) + s(x2, x3)) )
e <- sm(fit, 1)
```

plot effect using effect-specific methods

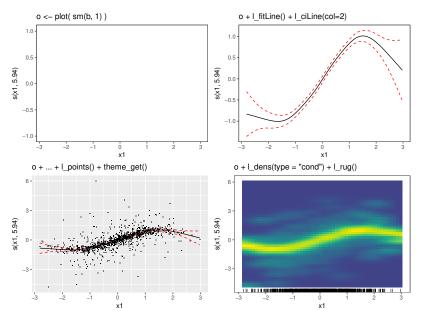
```
pl <- plot(e) # calls plot.mgcv.smooth.1D()</pre>
```

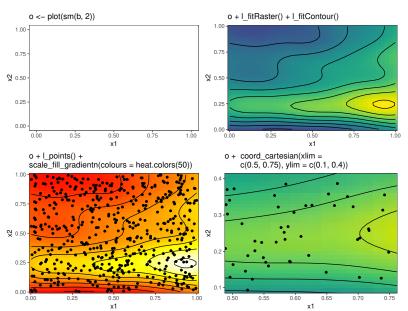
implement layers separately from plots

```
pl <- pl + l_fitLine() + l_ciLine()</pre>
```

• modify using ggplot2 and rendering done at the end

```
pl <- pl + xlim(1, 10) + xlab("myLabel")
pl # calls print.plotSmooth()</pre>
```





Basic workflow:

```
fit <- gam(y ~ s(x1) + s(x2, x3), method = "REML")
fit <- getViz(fit, nsim=50) # convert to "gamViz" object</pre>
```

or in one step:

Then

```
pl <- plot(sm(fit, 1), n = 100)
pl + l_fitLine() + l_ciLine()</pre>
```

To list all available layers:

```
listLayers( plot(sm(fit, 1)) ) # 1D effect
[1] "l_ciLine" "l_ciPoly" "l_dens2D" "l_fitDens" ...
listLayers( plot(sm(fit, 2)) ) # 2D effect
[1] "l_den" "l_fitContour" "l_fitRaster" "l_points" ...
```

To plot all effects do:

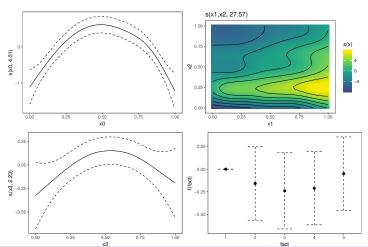
```
plot(fit) # calls plot.gamViz()
```

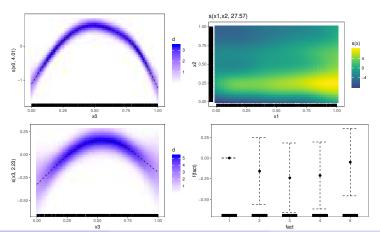
this loops over all effects, and adds default layers.

Layout controlled by print.plotGam:

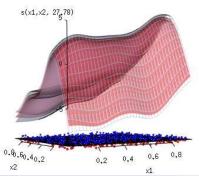
```
pl <- plot(fit)
print(pl, pages = 1)</pre>
```

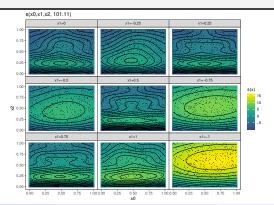
b <- bamV(y $\tilde{}$ fact + s(x0) + s(x1, x2) + s(x3), data=dat) print(plot(b, allTerms = TRUE), pages = 1)

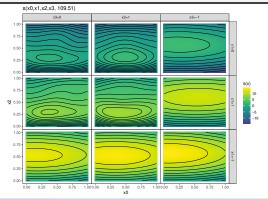


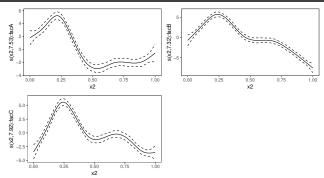


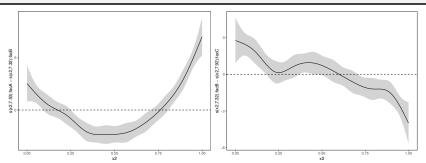
```
library(mgcViz) # see ?plotRGL.mgcv.smooth.2D
dat <- gamSim(1, n=1000, dist="normal", scale=2)
b <- gamV(y~s(x0)+s(x1, x2)+s(x3), data = dat)
plotRGL(sm(b, 2), residuals = TRUE) # <- not layered!</pre>
```











What if I want to plot the effects of the same model, estimated on different data?

We can use plot.mgamViz.

See "plot_mgamViz.html".

Smooth effect plots in mgcViz, summary:

- o<-gam(...) then o<-getViz(o), or faster o<-gamV(...)
- plot(sm(o,1)), plotDiff(), ... output class plotSmooth
- can add mgcViz (start with 1_) or ggplot2 layers
- layers available depends on effect type
- listLayers() shows available mgcViz layers
- plot(o) plots all effects (as plot.gam)

Special smooth effects plots:

- plotRGL interactive 2D (not layered)
- plotSlice above 2D
- plotDiff for 1D, 2D and smooths on sphere

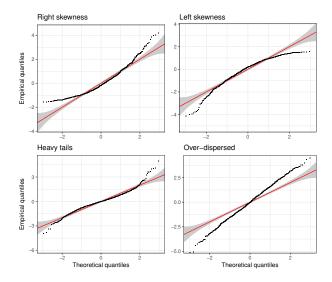
plot.mgamViz for multi-GAM plots.

Basic mgcViz: talk structure

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- 3 Intro to hands-on session

QQ-plots



QQ-plots produced by qq.gamViz.

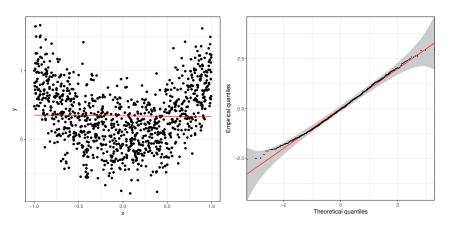
Usage:

```
b <- gamV(y ~ s(x))
qq(b, type = "deviance", CI = "normal") # see ?qq.gamViz</pre>
```

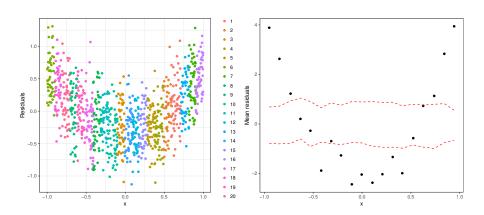
Notice:

- currently not layered
- scales to large data sets (if discrete = TRUE)
- interactivity by shine(qq(fit))

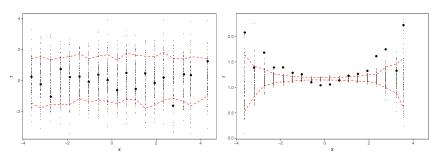
QQ-plots useful for choosing $\operatorname{Dist}_m(y|\mathbf{x})$ (e.g. Poisson vs Neg. Binom.) Less useful for finding omitted variables and non-linearities.



Conditional residuals checks are more helpful here.



check1D useful for 1D checks. Usage:



Especially useful for GAMLSS models.

Example: mgcFam::shash family of Jones and Pewsey (2009):

Should we put x3 in model for skewness? x5 in kurtosis formula?

```
library(e1071)
check1D(fit, "x3") + l_gridCheck1D(gridFun = skewness)
check1D(fit, "x5") + l_gridCheck1D(gridFun = kurtosis)
```

1_densCheck compares empirical and theoret. residuals distribution.

Generates heat-map of:

$$\delta(x,r) = d\operatorname{Fun}\{\hat{p}(r|x) - \phi(r|x)\},\$$

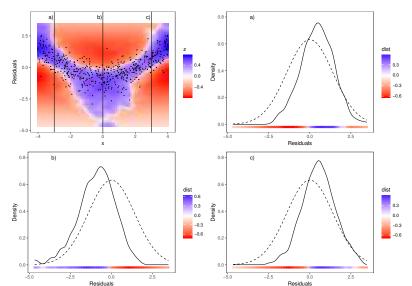
where

- $\hat{p}(r|x)$ k.d.e. of p(r|x);
- $\phi(r|x)$ is theoretical distribution (generally N(0,1));
- dFun is a distance function. By default:
 dFun <- function(emp, th) abs(sqrt(em)-sqrt(th))^(1/3);

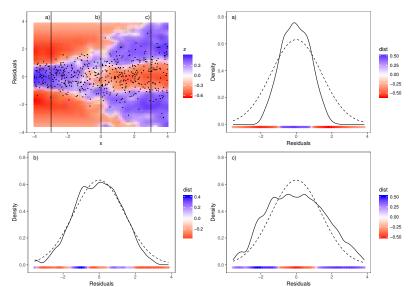
Usage

check1D(fit, "x3") + l_densCheck()

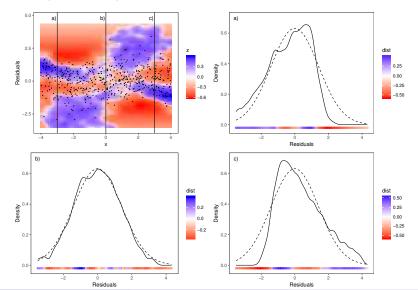
Mean changes with x



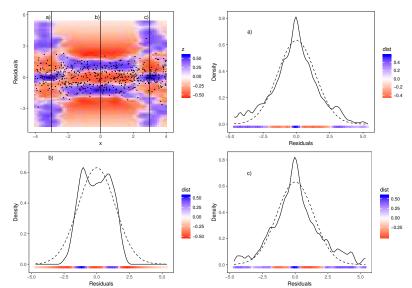
Variance changes with x



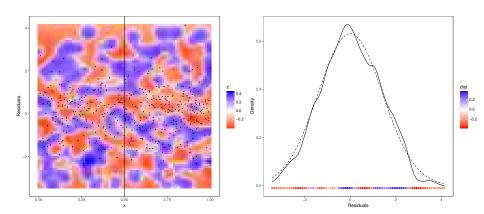
Skewness (asymmetry) changes with x



Kurtosis (tail-weight) changes with \boldsymbol{x}



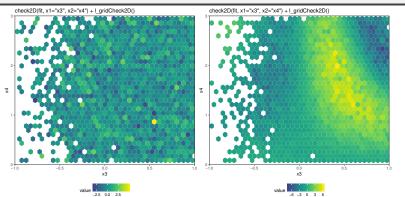
Nothing seems to change with \boldsymbol{x}



In 2D we can use check2D. Usage:

```
b <- gamV(y ~ s(x1) + s(x2))

check2D(fit, "x1", "x2") + l_gridCheck2D()
check2D(fit, "x1", "x2") + l_gridCheck2D(gridFun = sd)</pre>
```



Finally the check(fit) function produces:

```
Method: GCV Optimizer: magic
Smooth param selection converged after 8 iterations.
The RMS GCV score gradient at convergence was 1.09e-05.
The Hessian was positive definite.
Model rank = 37 / 37
##
              k' edf k-index p-value
## s(wM) 9.00 8.60 0.91 <2e-16 ***
## s(wM_s95) 9.00 8.13 1.02 0.76
```

To summarize model checking in mgcViz:

get gamViz object by doing

```
fit <- gam(y ~ s(x)) #Option 1
fit <- getViz(fit, nsim = 100)

fit <- gamV(y~s(x), aViz = list(nsim=100)) #Option 2</pre>
```

- QQ-plots using qq(fit) (no layers)
- Checks along 1D or 2D with check1D or check2D + 1_ ...
- Check convergence and number of basis with check(fit)

Intro to hands on session

Further mgcViz material on:

https://mfasiolo.github.io/mgcViz/

In particular, see article "An introduction to mgcViz: visual tools for GAMs".

Also see our paper "Scalable visualisation methods for modern Generalized Additive Models" for an example on UK load forecasting.

References I

- Fasiolo, M., R. Nedellec, Y. Goude, and S. N. Wood (2018). Scalable visualisation methods for modern generalized additive models. arXiv preprint arXiv:1809.10632.
- Hastie, T. and R. Tibshirani (1990). *Generalized Additive Models*, Volume 43. CRC Press.
- Jones, M. and A. Pewsey (2009). Sinh-arcsinh distributions. Biometrika 96(4), 761-780.
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- Wickham, H., W. Chang, et al. (2008). ggplot2: An implementation of the grammar of graphics. R package version 0.7, URL: http://CRAN. R-project. org/package= ggplot2.
- Wood, S. (2006). Generalized additive models: an introduction with R. CRC press.