

Additive quantile regression 2

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Structure of the talk

Structure:

- ① Fitting additive quantile models
- ② Convergence checking
- ③ Types of smooths
- ④ More quantile regression using `qgam`

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Fitting additive quantile models

Here I describe our approach to estimating quantile GAMs.

This is implemented in `qgam` and in `mgcv`.

I explain the main ideas, for details see Fasiolo et al. (2017).

Recall $\mu_\tau(\mathbf{x}) = \sum_{j=1}^m f_j(\mathbf{x})$ where $f_j(\mathbf{x})$ can be

- parametric e.g. $f_j(\mathbf{x}) = \alpha x_j + \beta x_j^2$
- random effects
- spline-based smooths such as

$$f_j(x_j) = \sum_{i=1}^r \beta_{ji} b_{ji}(x_j)$$

where β_{ji} are coefficients and $b_{ji}(x_j)$ are known spline basis functions.

Fitting additive quantile models

In **linear quantile regression** $\mu_\tau(\mathbf{x}) = \boldsymbol{\beta}^\top \mathbf{x} = \beta_1 x_1 + \dots \beta_p x_p$.

$\hat{\boldsymbol{\beta}}$ is the minimizer of total pinball loss

$$\hat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta}}{\operatorname{argmin}} L_y(\boldsymbol{\beta}) = \sum_{i=1}^n \rho_\tau(y_i - \boldsymbol{\beta}^\top \mathbf{x}_i).$$

When random or smooth effects included, minimized penalized loss

$$\hat{\boldsymbol{\beta}} = \underset{\boldsymbol{\beta}}{\operatorname{argmin}} \left\{ \frac{1}{\sigma} L_y(\boldsymbol{\beta}) + \operatorname{Pen}(\boldsymbol{\beta}|\boldsymbol{\gamma}) \right\},$$

where

- $L_y(\boldsymbol{\beta})$ quantifies goodness of fit
- $\operatorname{Pen}(\boldsymbol{\beta}|\boldsymbol{\gamma})$ penalizes complexity
- $\boldsymbol{\gamma}$ smoothing parameters ($\uparrow \boldsymbol{\gamma} \uparrow$ smoothness)
- $1/\sigma$ is learning rate

Fitting additive quantile models

We use a hierarchical fitting framework:

- 1 Calibrate $1/\sigma$ to have correct coverage of confidence intervals
- 2 For fixed $1/\sigma$:
select γ to have “right” amount of smoothness
- 3 For fixed $1/\sigma$ and γ :
estimate β to determine actual fit

Fitting additive quantile models

We use a hierarchical fitting framework:

- 1 Calibrate $1/\sigma$ to have correct coverage of confidence intervals

$$\hat{\sigma} = \operatorname{argmin}_{\sigma} \operatorname{IKL}(\sigma).$$

- 2 For fixed $1/\sigma$:
select γ to have “right” amount of smoothness

$$\hat{\gamma} = \operatorname{argmin}_{\gamma} \hat{G}(\gamma|\sigma).$$

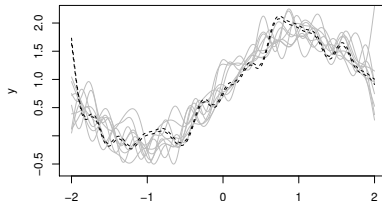
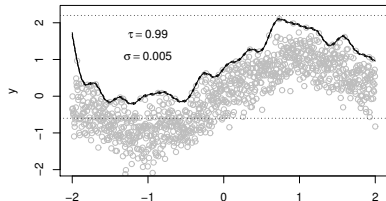
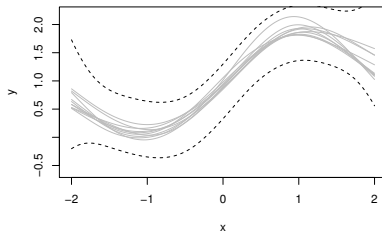
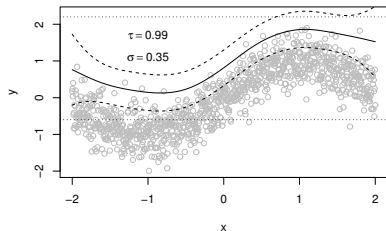
- 3 For fixed $1/\sigma$ and γ :
estimate β to determine actual fit

$$\hat{\beta} = \operatorname{argmin}_{\beta} V(\beta|\gamma, \sigma).$$

Fitting additive quantile models

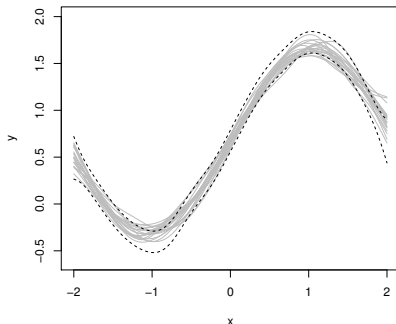
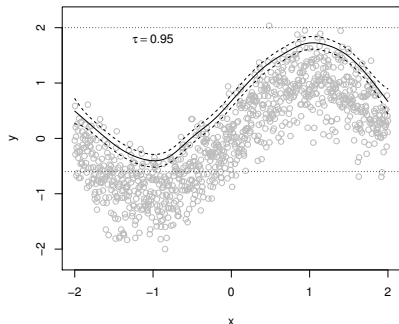
Effect of σ and γ is interrelated:

- credible intervals: $\uparrow \sigma \rightarrow \uparrow$ intervals width
- complexity of fit: $\uparrow \sigma \rightarrow \uparrow \hat{\gamma} \rightarrow \uparrow$ smoothness



Fitting additive quantile models

We choose σ so that confidence intervals for $\mu_\tau(\mathbf{x})$ are well calibrated.

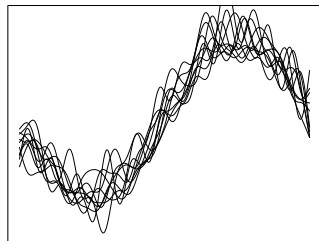
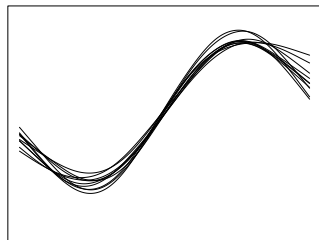
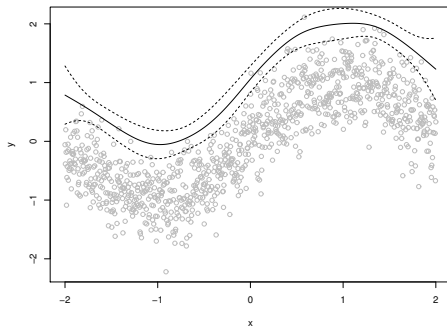


This results also in good smoothness selection for $\gamma|\sigma$.

Fitting additive quantile models

The hierarchical fitting framework:

- 1 Calibrate $1/\sigma$
- 2 Select $\gamma|\sigma$
- 3 Estimate $\beta|\gamma, \sigma$ to determine fit

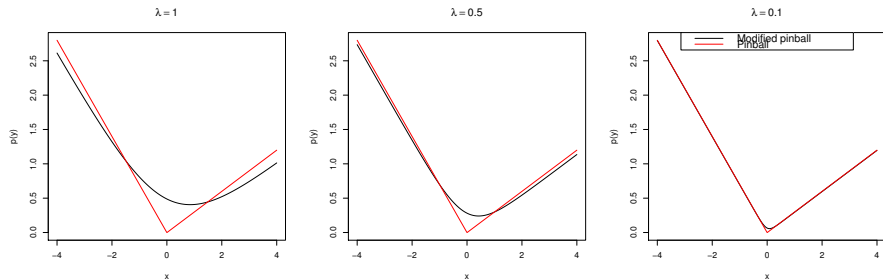


Fitting additive quantile models

We use a modified loss based on the Extended log-F (ELF) density:

$$\tilde{p}(y|\mu, \sigma, \tau, \lambda) \propto -(1 - \tau) \frac{y - \mu}{\sigma} + \lambda \log \left[1 + e^{\frac{y - \mu}{\lambda \sigma}} \right],$$

This is smooth and convex and, as $\lambda \rightarrow 0$, we have recover pinball loss.



NB in `qgam`, λ reparametrized as `err` $\in (0, 1)$ (\downarrow `err` implies $\downarrow \lambda$).

Fitting additive quantile models

Increasing `err` leads to:

- faster and more stable computation
- more bias

Interpretation, if μ^* is minimizer of ELF loss:

$$|F(\mu^*) - \tau| \leq \text{err}$$

`err` is an upper bound on the bias.

By default:

```
qgam(..., err = 0.05, ...)
```

Structure of the talk

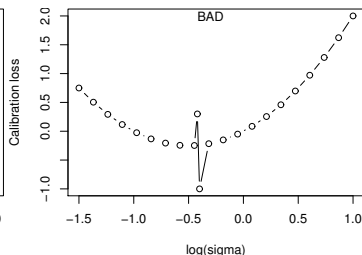
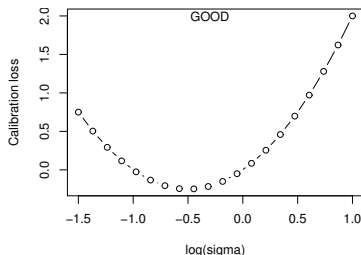
Structure:

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- 2 **Convergence checking**
- 3 Types of smooths
- 4 More quantile regression using `qgam`

Convergence checking

There might be problems at each step:

1 Calibrate $1/\sigma$



2 Select $\gamma|\sigma$

Warning: outer Newton did not converge fully

3 Estimate $\beta|\gamma, \sigma$ to determine fit

Error: In gam.fit5(...): iteration limit reached

Convergence checking

Problems might be due to structural problems:

```
fit <- qgam(y <- x1 + s(x1), qu = 0.5)
```

```
Error in chol.default(iS) :  
  the leading minor of order 11 is not positive definite
```

In general increasing `err` alleviates problem but increases bias.

`mgcViz` and `qgam` provide some diagnostics.

Structure of the talk

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Types of smooths

mgcv offers a wide variety of smooths (see `?smooth.terms`).

Univariate types:

- $s(x) = s(x, bs = "tp")$ thin-plate-splines
- $s(x, bs = "cr")$ cubic regression spline
- $s(x, bs = "ad")$ adaptive smooth

Multivariate type:

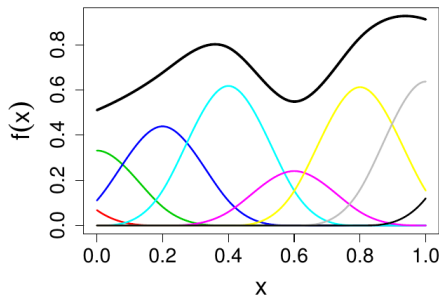
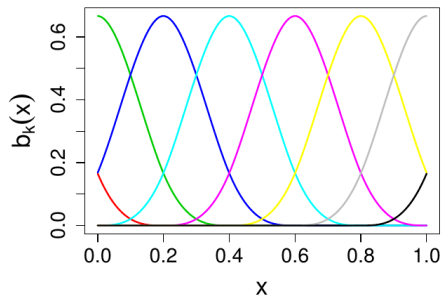
- $s(x_1, x_2) = s(x_1, x_2, bs = "tp")$ thin-plate-splines (isotropic)
- $te(x_1, x_2)$ tensor-product-smooth (anisotropic)
- $s(x, y, bs = "sos")$ smooth on sphere

They can depends on factors:

- $s(x, by = \text{Subject})$
- $s(x, \text{Subject}, bs = "fs")$

Types of smooths

`s(x, bs = "cr", k = 20)`

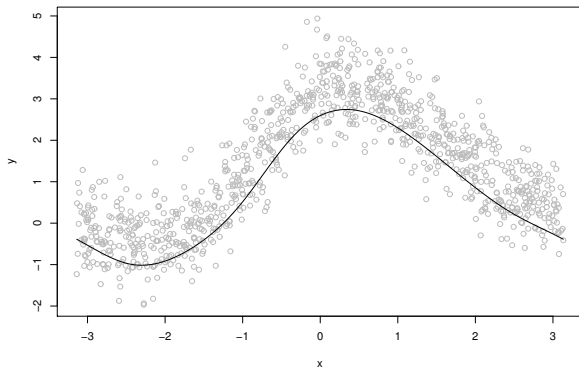


Cubic regression spline are related to the optimal solution to

$$\sum_{i=1}^n \{y_i - f(x_i)\}^2 + \gamma \int f''(x)^2 dx.$$

Types of smooths

`s(x, bs = "cc")`

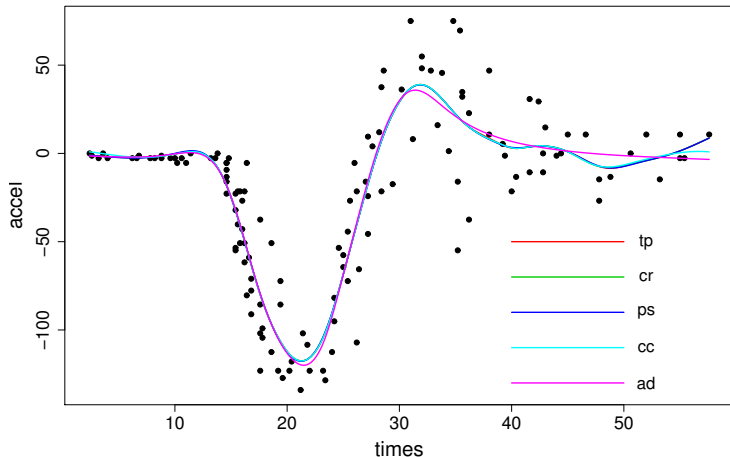


Cyclic cubic regression spline make so that

- $f(x_{min}) = f(x_{max})$
- $f'(x_{min}) = f'(x_{max})$

Types of smooths

`s(x, bs = "ad")`



The wiggleness or smoothness of $f(x)$ depends on x .

Types of smooths

$s(x_1, x_2), s(x_1, x_2, x_3), \dots$

Based on thin plate regression splines basis.

Related to optimal solution to:

$$\sum_i \{y_i - f(x_i, z_i)\}^2 + \gamma \int f_{xx}^2 + 2f_{xz}^2 + f_{zz}^2 dx dz$$

A single smoothing parameter γ .

Isotropic: same smoothness along x_1, x_2, \dots

Types of smooths

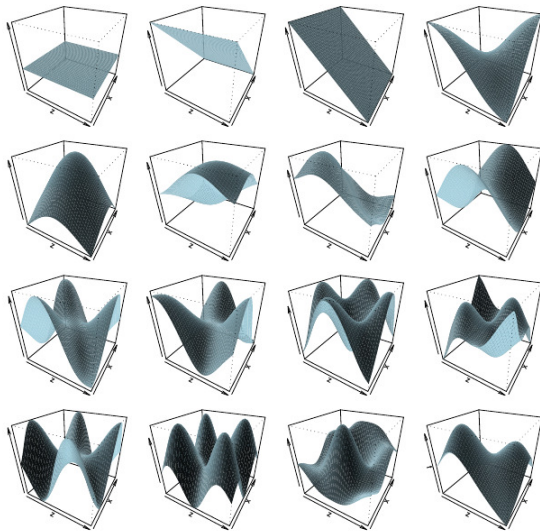


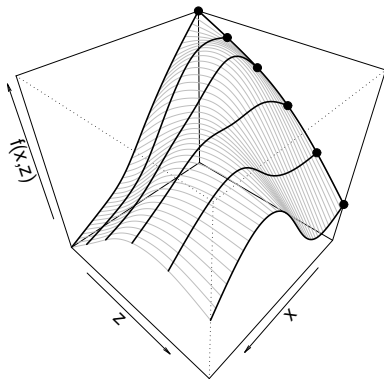
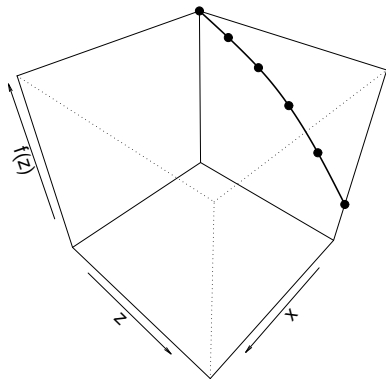
Figure: Rank 17 2D TPRS basis. Courtesy of Simon Wood.

Types of smooths

Isotropic effect of x_1, x_2 are in same unit (e.g. Km).

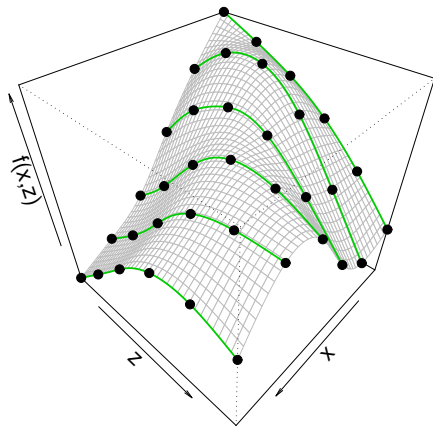
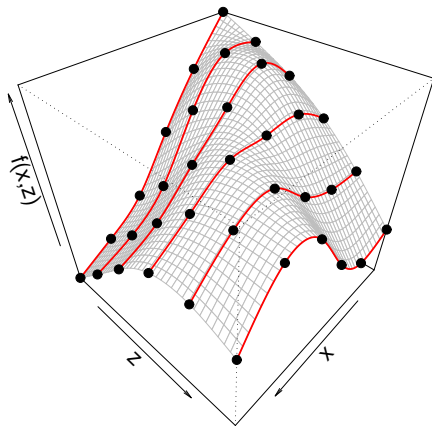
If different units better use tensor product smooths $\text{te}(x_1, x_2)$.

Construction: make a spline $f_z(z)$ a function of x by letting its coefficients vary smoothly with x



Types of smooths

- x-penalty: average wiggleness of red curves
- z-penalty: average wiggleness of green curves



Types of smooths

Can use (almost) any kind of marginal:

- `te(x1, x2, x2)` product of 3 thin-plate-spline bases
- `te(x1, x2, bs = c("cc", "cr"), k = c(10, 6))`
- `te(L0, LA, t, d=c(2,1), k=c(20,10), bs=c("tp","cc"))`

Basis of `te` contains functions of the form $f(x_1) + f(x_2)$.

To fit $f(x_1) + f(x_2) + f(x_1, x_2)$ separately use:

```
y ~ ti(x1) + ti(x2) + ti(x1, x2)
```

Types of smooths

By-factor smooths

Approach (1) is $s(x, \text{by} = \text{subject})$, which means

- $\rho_\tau(x) = f_1(x) + \dots$ if subject = 1
- $\rho_\tau(x) = f_2(x) + \dots$ if subject = 2
- ...

Approach (2) is $s(x, \text{subject}, \text{bs} = \text{"fs"})$, which means

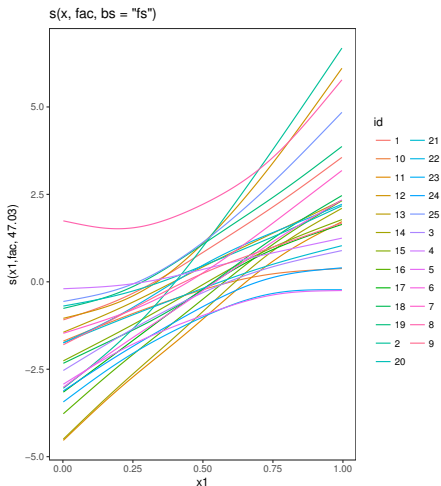
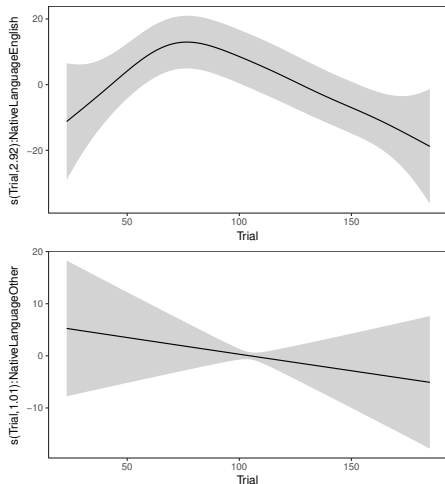
- $\rho_\tau(x) = b_1 + f_1(x) + \dots$ if subject = 1
- $\rho_\tau(x) = b_2 + f_2(x) + \dots$ if subject = 2
- ...

where $b_1, b_2, \dots \sim N(0, \gamma_{\mathbf{b}} \mathbf{I})$ are random effects.

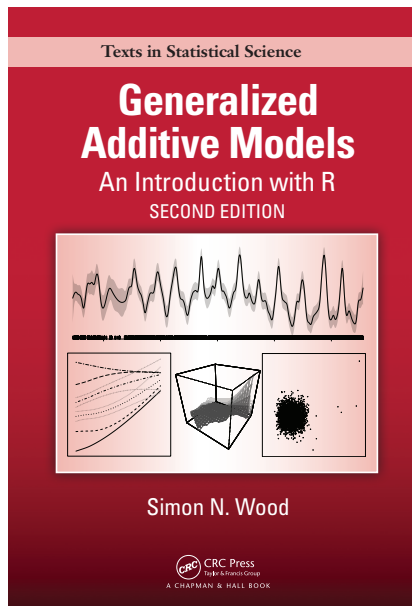
In (1) each f_j has its own smoothing parameter.

In (2) all f_j 's have the same smoothing parameter.

Types of smooths



Further reading



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- ④ **More quantile regression using qgam**

References I

Fasiolo, M., Y. Goude, R. Nedellec, and S. N. Wood (2017). Fast calibrated additive quantile regression. *arXiv preprint arXiv:1707.03307*.