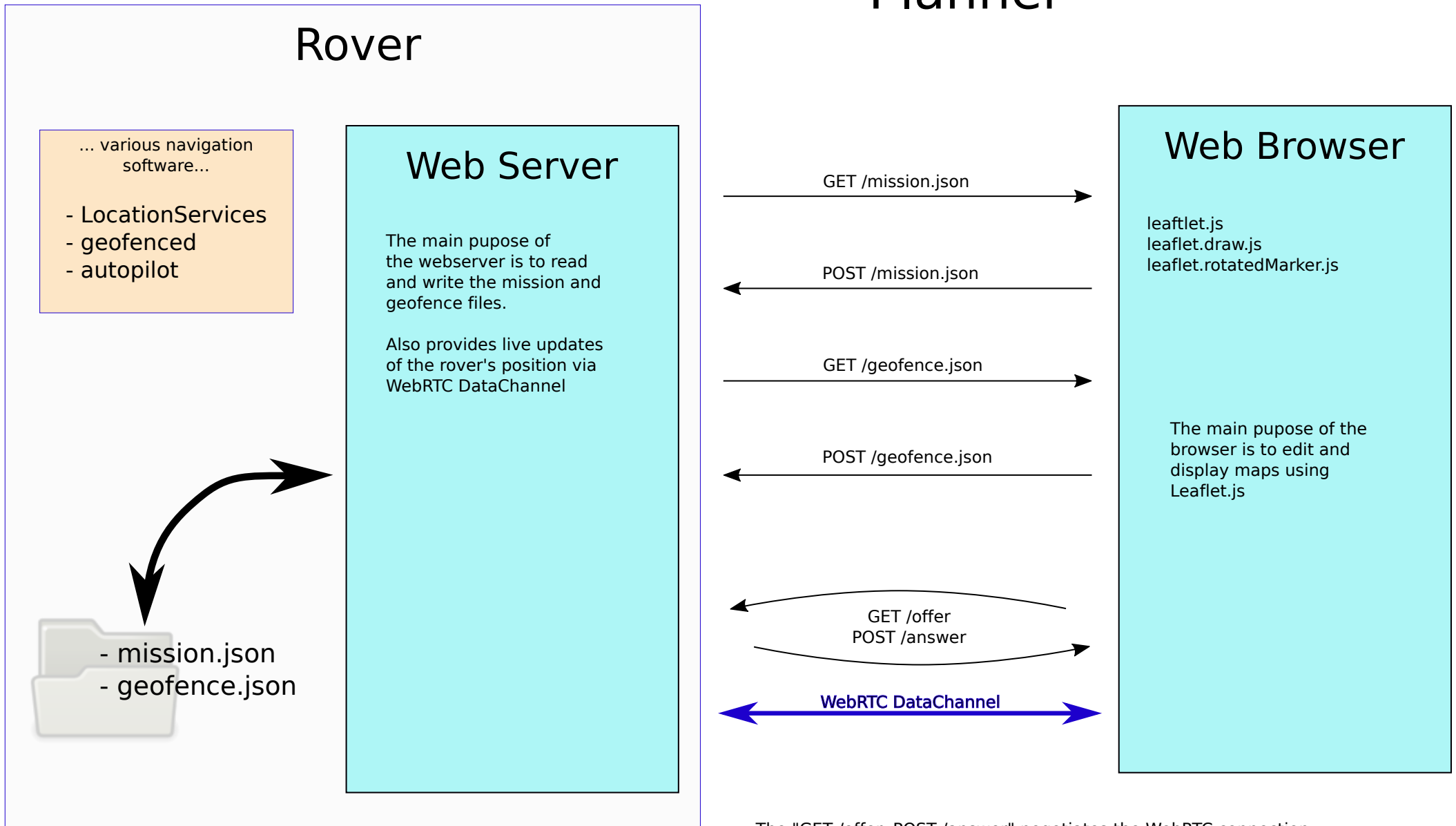


# AT Drive Planner



The "GET /offer, POST /answer" negotiates the WebRTC connection.

The DataChannel provides live updates of the rover's position, and notifications if any files have changed.