AT Drive Planner

Rover

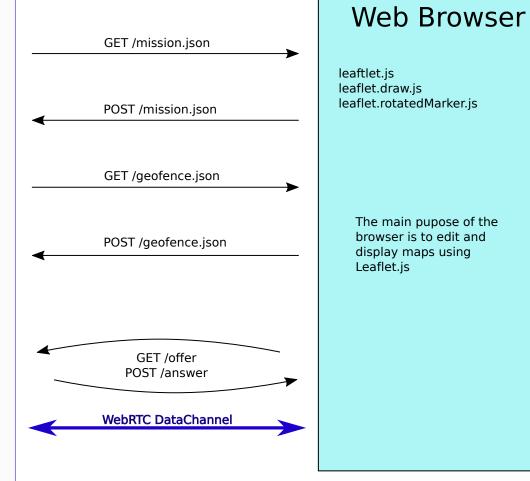
- ... various navigation software...
- LocationServices
- geofenced
- autopilot



Web Server

The main pupose of the webserver is to read and write the mission and geofence files.

Also provides live updates of the rover's position via WebRTC DataChannel



The "GET /offer, POST /answer" negotiates the WebRTC connection.

The DataChannel provides live updates of the rover's position, and notifications if any files have changed.