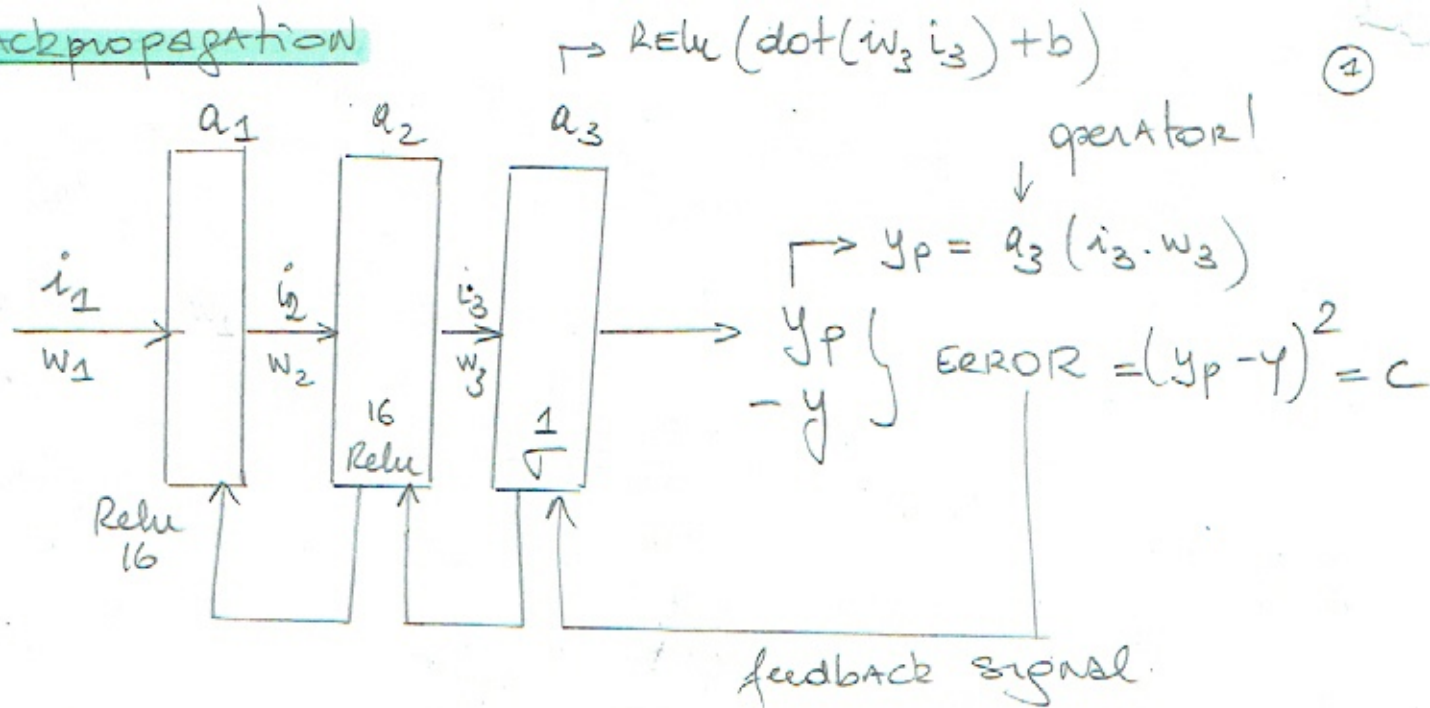


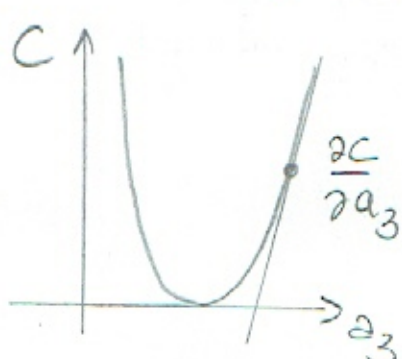
Backpropagation



Goal of NN \rightarrow train on training data

\rightarrow as a_i and i_1 and y are fixed, the only way to reduce error is by changing the weights

ERROR $= C = (y_p - y)^2$ and $y_p = a_3 (i_3 \cdot w_3) = \sigma(i_3 w_3)$



\hookrightarrow function of a_3 $\hookrightarrow [0, 1]$ (1)
and a_3 is function of w_3
 \rightarrow Nested function.

\rightarrow Gradient descent.

(1) $i_3 w_3 = \text{ReLU}(i_2 \cdot w_2)$

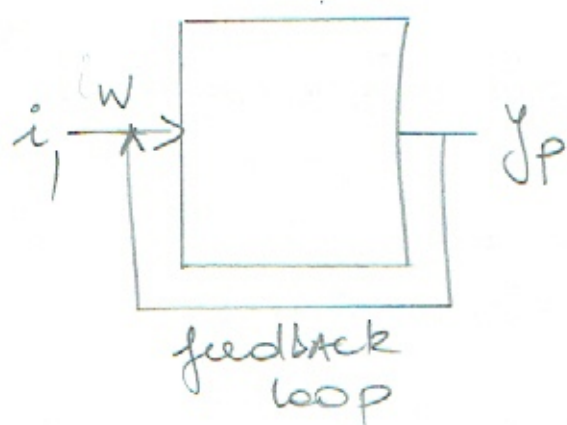
$\hookrightarrow \text{ReLU}(i_1 w_1)$

$\rightarrow y_p = \sigma(i_3 w_3) = \sigma(\text{ReLU}(\text{ReLU}(i_1 w_1)))$

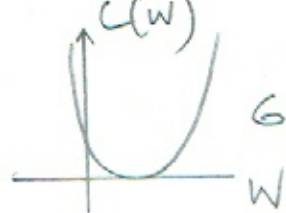
derivative of nested function \rightarrow chain Rule

Given: $f(g(x)) \rightarrow \frac{\partial f}{\partial x} = \frac{\partial f}{\partial g} \frac{\partial g}{\partial x}$

Shallow Learning

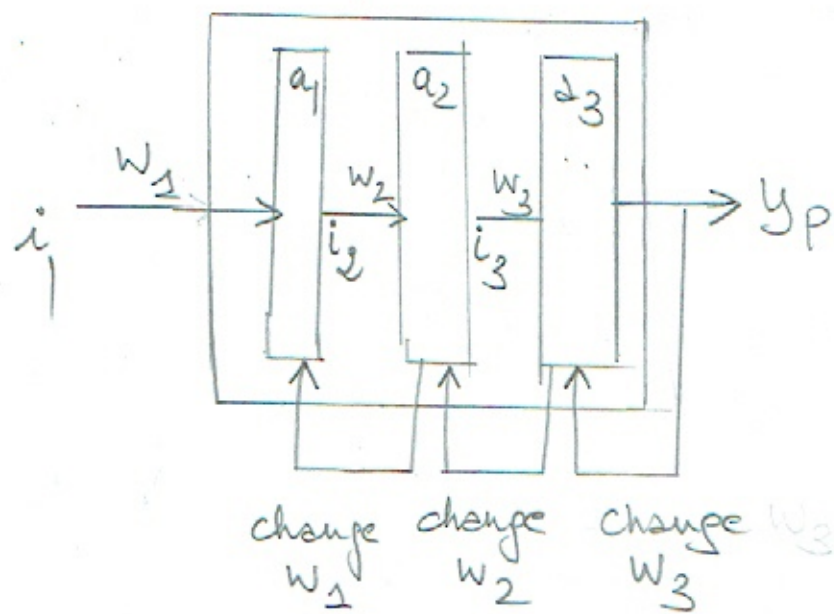


$$C = (y_p - y)^2$$



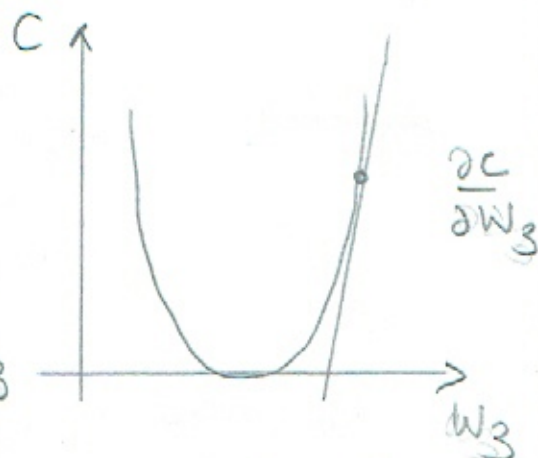
Gradient Descent

Deep Learning



$$C = (y_p - y)^2$$

Gradient Descent



update rule

$$w_3^{t+1} \leftarrow w_3^t - \alpha \frac{\partial C}{\partial w_3}$$

$\hookrightarrow w_3$ not directly Accessible

\Downarrow chain rule

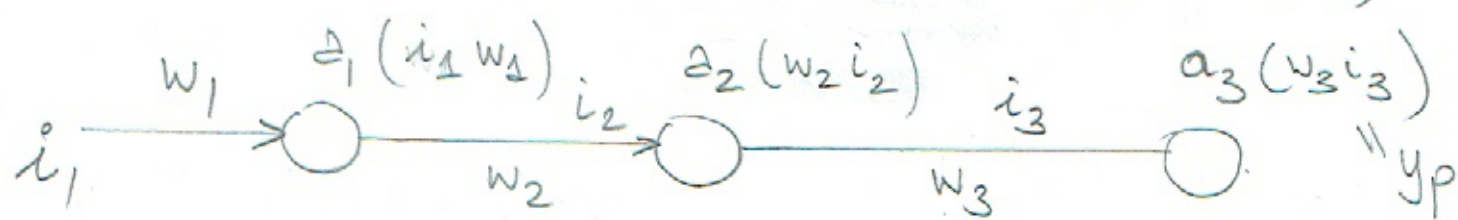
$$\frac{\partial C}{\partial a_3} \frac{\partial a_3}{\partial w_3}$$

what about w_2 and w_1 ?

$$a_1(i_1 w_1) \quad (3)$$

$$y_p = a_3(\underbrace{i_3 w_3}) = a_3(a_2(\underbrace{i_2 w_2}))$$

$$a_2(i_2 w_2) \rightarrow a_2 = a_2(w_2)$$



$$-\alpha \frac{\partial C}{\partial a_3} \frac{\partial a_3}{\partial w_3}$$

$$-\alpha \frac{\partial a_2}{\partial w_2} \frac{\partial a_3}{\partial a_2} \frac{\partial C}{\partial a_3}$$

$$-\alpha \frac{\partial a_1}{\partial w_1} \frac{\partial a_2}{\partial a_1} \frac{\partial a_3}{\partial a_2} \frac{\partial C}{\partial a_3}$$

links change in C to changes in w_1 , $2(a_2 - y)$

$$\Rightarrow w_3^{t+1} := w_3^t - \alpha \left(\frac{\partial a_1}{\partial w_1} \frac{\partial a_2}{\partial a_1} \frac{\partial a_3}{\partial a_2} \frac{\partial C}{\partial a_3} \right)$$

$$C = (a_3 - y)^2$$

$$\frac{\partial C}{\partial a_3} = 2(a_3 - y) \frac{\partial (a_3 - y)}{\partial a_3} = 2(a_3 - y) \cdot 1$$