```
import numpy as np
import matplotlib.pyplot as plt
import os
import shutil
from google.colab import drive
drive.mount('/content/drive')
    Г⇒
We will split cat and dog images and give them their own directories training_set_cats
look for files that start with dog. This process will take a few hours as we need to proc
source = os.listdir('/content/drive/My Drive/Colab Notebooks/train/'
dst 1='/content/drive/My Drive/Colab Notebooks/training dogs/'
dst 2='/content/drive/My Drive/Colab Notebooks/training cats/'
os.chdir('/content/drive/My Drive/Colab Notebooks/train')
for file in source:
            if file.startswith('dog.'):
                        shutil.copy(file, dst 1)
            else:
                        shutil.copy(file, dst 2)
list = os.listdir('/content/drive/My Drive/Colab Notebooks/training of the content of the c
number files = len(list)
print(number files)
    \Box
No we will set aside our training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and store them in training set of 1000 dogs and 1000 cats and 1000 dogs and 1000 cats and 1000 dogs and 100
```

os.chdir('/content/drive/My Drive/Colab Notebooks/training\_dogs')

source\_2 = os.listdir('/content/drive/My Drive/Colab Notebooks/train.source\_3 = os.listdir('/content/drive/My Drive/Colab Notebooks/train.dst\_3='/content/drive/My Drive/Colab Notebooks/training\_2000/training.dst\_4='/content/drive/My Drive/Colab Notebooks/training\_2000/training.

```
for file in source_2:
    shutil.copy(file, dst_3)

os.chdir('/content/drive/My Drive/Colab Notebooks/training_cats')

for file in source_3:
    shutil.copy(file, dst_4)

No we will set aside our validation set of 500 dogs and 500 cats and store them in val_
source_4 = os.listdir('/content/drive/My Drive/Colab Notebooks/train.source_5 = os.listdir('/content/drive/My Drive/Colab Notebooks/train.dst_5='/content/drive/My Drive/Colab Notebooks/val_1000/val_dogs_500.dst_6='/content/drive/My Drive/Colab Notebooks/val_1000/val_cats_500.os.chdir('/content/drive/My Drive/Colab Notebooks/training_dogs')

for file in source 4:
```

```
os.chdir('/content/drive/My Drive/Colab Notebooks/training cats')
```

```
for file in source_5:
    shutil.copy(file, dst_6)
```

shutil.copy(file, dst 5)

```
list = os.listdir('/content/drive/My Drive/Colab Notebooks/training_2
number_files = len(list)
print(number_files)
```

**C**→

No we will set aside our test set of 500 dogs and 500 cats in test\_set\_dogs\_500 and te

```
source 6 = os.listdir('/content/drive/My Drive/Colab Notebooks/train
source 7 = os.listdir('/content/drive/My Drive/Colab Notebooks/train
dst 7='/content/drive/My Drive/Colab Notebooks/test 1000/test dogs 5
dst 8='/content/drive/My Drive/Colab Notebooks/test 1000/test cats 5
os.chdir('/content/drive/My Drive/Colab Notebooks/training dogs/')
for file in source 6:
  shutil.copy(file, dst 7)
os.chdir('/content/drive/My Drive/Colab Notebooks/training cats/')
for file in source 7:
  shutil.copy(file, dst 8)
list = os.listdir('/content/drive/My Drive/Colab Notebooks/training )
number files = len(list)
print(number files)
\Box
```

model.add(layers.Conv2D(32, (3,3), activation='relu', input shape=(1

model.add(layers.Conv2D(64, (3,3), activation='relu'))

model.add(layers.Conv2D(128, (3,3), activation='relu'))

model.add(layers.Conv2D(128, (3,3), activation='relu'))

from keras import models from keras import layers

model=models.Sequential()

model.add(layers.MaxPooling2D(2,2))

model.add(layers.MaxPooling2D(2,2))

model.add(layers.MaxPooling2D(2,2))

```
model.add(layers.MaxPooling2D(2,2))
model.add(layers.Flatten())
#model.add(layers.Dropout(0.5))
model.add(layers.Dense(512, activation='relu'))
model.add(layers.Dense(1, activation='sigmoid'))

from keras import optimizers
model.compile(loss='binary_crossentropy', optimizer=optimizers.RMSpromodel.compile(loss='binary_crossentropy', optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimizer=optimi
```

Generator allows you to loop over the training data in pieces(batches), avoiding large n

```
from keras.preprocessing.image import ImageDataGenerator

train_datagen=ImageDataGenerator(rescale=1./255)
validation_datagen=ImageDataGenerator(rescale=1./255)

train_generator=train_datagen.flow_from_directory('/content/drive/My
validation_generator=validation_datagen.flow_from_directory('/content/drive/My)
```

 $\Box$ 

Generators are objects that act as an iterator (for loop). However the generator yields the train and val generators will yield batches of inputs and targets indefinitely. However declaring the epoch is over. The steps\_per\_epoch argument takes care of this. In our cases of the control of th

```
history = model.fit_generator(train_generator, steps_per_epoch=100, e
```



```
acc=history.history['acc']
val_acc=history.history['val_acc']
loss=history.history['loss']
val_loss=history.history['val_loss']
```

```
plt.plot(epochs, acc, 'bo', label='training acc')
plt.plot(epochs, val_acc, 'b', label='validation acc')
plt.title('training and validation accuracy')
plt.legend()
plt.figure()

plt.plot(epochs, loss, 'bo', label='training loss')
plt.plot(epochs, val_loss, 'b', label='validation loss')
plt.title('training and validation loss')
plt.legend()
plt.show()
```

```
import numpy as np
import matplotlib.pyplot as plt

import os
import shutil

from google.colab import drive
drive.mount('/content/drive')
```

We will split cat and dog images and give them their own directories training\_set\_cats a look for files that start with dog. This process will take a few hours as we need to proce

```
source = os.listdir('/content/drive/My Drive/Colab Notebooks/train/')
dst_1='/content/drive/My Drive/Colab Notebooks/training_dogs/'
dst_2='/content/drive/My Drive/Colab Notebooks/training_cats/'

os.chdir('/content/drive/My Drive/Colab Notebooks/train')

for file in source:
    if file.startswith('dog.'):
        shutil.copy(file, dst_1)
    else:
        shutil.copy(file, dst_2)

list = os.listdir('/content/drive/My Drive/Colab Notebooks/training_conumber_files = len(list)
    print(number files)
```

## С→

No we will set aside our training set of 1000 dogs and 1000 cats and store them in train

```
source_2 = os.listdir('/content/drive/My Drive/Colab Notebooks/traini
source_3 = os.listdir('/content/drive/My Drive/Colab Notebooks/traini
dst_3='/content/drive/My Drive/Colab Notebooks/training_2000/training
dst_4='/content/drive/My Drive/Colab Notebooks/training_2000/training
```

```
os.chdir('/content/drive/My Drive/Colab Notebooks/training dogs')
for file in source 2:
  shutil.copy(file, dst 3)
os.chdir('/content/drive/My Drive/Colab Notebooks/training cats')
for file in source 3:
  shutil.copy(file, dst 4)
No we will set aside our validation set of 500 dogs and 500 cats and store them in val_s
source 4 = os.listdir('/content/drive/My Drive/Colab Notebooks/traini
source 5 = os.listdir('/content/drive/My Drive/Colab Notebooks/traini
dst 5= /content/drive/My Drive/Colab Notebooks/val 1000/val dogs 500/
dst 6='/content/drive/My Drive/Colab Notebooks/val 1000/val cats 500/
os.chdir('/content/drive/My Drive/Colab Notebooks/training dogs')
for file in source 4:
  shutil.copy(file, dst 5)
os.chdir('/content/drive/My Drive/Colab Notebooks/training cats')
for file in source 5:
  shutil.copy(file, dst 6)
list = os.listdir('/content/drive/My Drive/Colab Notebooks/training 2
number files = len(list)
print(number files)
Гэ
No we will set aside our test set of 500 dogs and 500 cats in test_set_dogs_500 and te
```

source\_6 = os.listdir('/content/drive/My Drive/Colab Notebooks/traini
source\_7 = os.listdir('/content/drive/My Drive/Colab Notebooks/traini
dst 7='/content/drive/My Drive/Colab Notebooks/test 1000/test dogs 50

```
dst 8='/content/drive/My Drive/Colab Notebooks/test 1000/test cats 50
os.chdir('/content/drive/My Drive/Colab Notebooks/training dogs/')
for file in source 6:
  shutil.copy(file, dst 7)
os.chdir('/content/drive/My Drive/Colab Notebooks/training cats/')
for file in source 7:
  shutil.copy(file, dst 8)
list = os.listdir('/content/drive/My Drive/Colab Notebooks/training 2
number files = len(list)
print(number files)
Гэ
from keras import models
from keras import layers
model=models.Sequential()
model.add(layers.Conv2D(32, (3,3), activation='relu', input_shape=(15
model.add(layers.MaxPooling2D(2,2))
model.add(layers.Conv2D(64, (3,3), activation='relu'))
```

```
from keras import models
from keras import layers

model=models.Sequential()
model.add(layers.Conv2D(32, (3,3), activation='relu', input_shape=(15)
model.add(layers.MaxPooling2D(2,2))
model.add(layers.Conv2D(64, (3,3), activation='relu'))
model.add(layers.MaxPooling2D(2,2))
model.add(layers.Conv2D(128, (3,3), activation='relu'))
model.add(layers.MaxPooling2D(2,2))
model.add(layers.Conv2D(128, (3,3), activation='relu'))
model.add(layers.MaxPooling2D(2,2))
model.add(layers.MaxPooling2D(2,2))
model.add(layers.Flatten())
#model.add(layers.Dropout(0.5))
model.add(layers.Dense(512, activation='relu'))
model.add(layers.Dense(1, activation='relu'))
```

```
from keras import optimizers

model.compile(loss='binary_crossentropy', optimizer=optimizers.RMSpro
```

Congretor allows you to loop over the training data in pieces (hatches), avoiding large m

deficiation allows you to loop over the training data in pieces (batches), avoiding large in

```
from keras.preprocessing.image import ImageDataGenerator

train_datagen=ImageDataGenerator(rescale=1./255)
validation_datagen=ImageDataGenerator(rescale=1./255)

train_generator=train_datagen.flow_from_directory('/content/drive/My
validation_generator=validation_datagen.flow_from_directory('/content/drive/My)
```

С→

Generators are objects that act as an iterator (for loop). However the generator yields be the train and val generators will yield batches of inputs and targets indefinitely. However declaring the epoch is over. The steps\_per\_epoch argument takes care of this. In our cases

```
history = model.fit generator(train generator, steps per epoch=100, e
```



```
acc=history.history['acc']
val_acc=history.history['val_acc']
loss=history.history['loss']
val_loss=history.history['val_loss']

epochs=range(1, len(acc)+1)
```

```
plt.plot(epochs, acc, 'bo', label='training acc')
plt.plot(epochs, val_acc, 'b', label='validation acc')
plt.title('training and validation accuracy')
plt.legend()
plt.figure()
```

```
plt.plot(epochs, loss, 'bo', label='training loss')
plt.plot(epochs, val_loss, 'b', label='validation loss')
plt.title('training and validation loss')
plt.legend()
plt.show()
```

