

# Mohammad Farid AZAMPOUR

## Post doctoral researcher

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 Herzogstr 125, 80796, München

## PROFESSIONAL EMPLOYMENT

Now Sep. 2024	Post Doctoral Researcher, TECHNISCHE UNIVERSITÄT MÜNCHEN, Munich <ul style="list-style-type: none"><li>&gt; Chair for <a href="#">Computer Aided Medical Procedures</a> with <a href="#">Nassir Navab</a></li></ul>
Sep. 2024 Feb. 2021	Research fellow, TECHNISCHE UNIVERSITÄT MÜNCHEN, Munich <ul style="list-style-type: none"><li>&gt; Chair for <a href="#">Computer Aided Medical Procedures</a> with <a href="#">Nassir Navab</a></li></ul>
Apr. 2021 Oct. 2020	Visiting researcher, IMPERIAL COLLEGE LONDON, London <ul style="list-style-type: none"><li>&gt; The group of <a href="#">Biomedical Image Analysis</a> at the Department of Computing with <a href="#">Bernhard Kainz</a></li></ul>
Feb. 2019 Jun. 2016	Technical director, DARIC PARS SOLUTIONS, Tehran <ul style="list-style-type: none"><li>&gt; Designed tourism wallet aimed for areas with limited access to major payment services, with <a href="#">Mohammad Javad Salehi</a></li></ul>
Jun. 2018 Apr. 2018	Data scientist, TARAABARNET, Tehran <ul style="list-style-type: none"><li>&gt; Examine truck–goods relationships to extract patterns and propose a pricing algorithm using 40 million data points, with <a href="#">Sharyar Noei</a> and <a href="#">Keivan Jafari</a></li></ul>
May 2015 Sep. 2011	Software developer   R & D member, ETICK PARS INTELLIGENT TECHNOLOGIES DEVELOPMENT, Tehran <ul style="list-style-type: none"><li>&gt; Developed embedded navigation applications using Qt and C# for public transport devices, with <a href="#">Mohammad Javad Salehi</a></li></ul>

## EDUCATION

Sep. 2024 Sep. 2015	Bio Electrical Engineering, PHD, Sharif University of Technology, Tehran, Iran thesis: <b>Multimodal medical image registration using deep learning</b> under supervision of <i>Dr. Emad Fatemizadeh</i> GPA: <b>18.60/20</b> - via 16 Credits
Jan. 2014 Sep. 2011	Bio Electrical Engineering, GRADUATE STUDIES, Sharif University of Technology, Tehran, Iran thesis: <b>Image Registration Using Manifold Learning Based Methods</b> under supervision of <i>Dr. Emad Fatemizadeh</i> GPA: <b>17.07/20</b> - via 32 Credits
Sep. 2011 Sep. 2007	Electrical Engineering, B.Sc., Sharif University of Technology, Tehran, Iran GPA: <b>17.7/20</b> - via 140 Credits

### Academic Service and Teaching

- > Member of the Coordination Committee, Chair of CAMP 2024–present
- > Organizer, Practical Course: *Computational Engineering* 2024–present
- > Organizer, Practical Course: *Project Management and Software Development for Medical Applications* 2023–2024
- > Lecturer, *CAMP I & II* 2023–present

### Conference Organization

- > (Co-)Organizer, ASMUS Workshop at MICCAI 2026

### Journal Reviewing

- > *Medical Physics*
- > *IEEE Journal of Biomedical and Health Informatics (JBHI)*
- > *IEEE Transactions on Medical Imaging (TMI)*
- > *IEEE Robotics and Automation Letters (RA-L)*
- > *Medical Image Analysis (MedIA)*

### Conference Reviewing

- > Medical Image Computing and Computer Assisted Interventions (MICCAI)
- > International Conference on Information Processing in Computer-Assisted Interventions (IPCAI)
- > IEEE International Conference on Robotics and Automation (ICRA)
- > IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
- > IEEE/CVF International Conference on Computer Vision (ICCV)
- > European Conference on Computer Vision (ECCV) *Outstanding Reviewer Award, 2024*
- > IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)

## FUNDING

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- > ICL–TUM Global Incentive Fund 2020  
Grant amount: 10,000 €
- > Nantes–TUM Global Incentive Fund 2022  
Grant amount: 5,000 €
- > Bayerische Transformations- und Forschungsstiftung Pending final approval  
Total funding: 1,000,000 €; Share for CAMP chair: 280,000 €
- > Deutsche Forschungsgemeinschaft (DFG) Submitted  
Total funding: 850,000 €; Share for CAMP Chair: 410,000 €

## MENTORSHIP AND TEACHING

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PhD Mentor	Mentor of three PhD students as of Oct. 2023
Co-supervisor of master and bachelor thesis	Successfully co-supervised more than 15 M.Sc. and B.Sc. theses
Lectures, seminars and practical courses	Responsible for the lecture of Image registration at the course CAMP I & II, Co-organizer of the practical courses (Project Management and Software Development for Medical Applications (PMSD) and Computational Surgineering)

## RESERCH INTERESTS

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- > Medical Image Processing
- > Physics-based Deep Learning
- > Generative models
- > Ultrasound imaging

## LANGUAGES

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Farsi (Native)	<input checked="" type="radio"/> <input checked="" type="radio"/> <input checked="" type="radio"/> <input checked="" type="radio"/> <input checked="" type="radio"/>
English	<input checked="" type="radio"/> <input checked="" type="radio"/> <input checked="" type="radio"/> <input checked="" type="radio"/> <input type="radio"/>
German	<input checked="" type="radio"/> <input checked="" type="radio"/> <input checked="" type="radio"/> <input type="radio"/> <input type="radio"/>

## PUBLICATIONS

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### Publication summary

I have (first or last/co)-authored 3/5 journal articles, 7/13 conference papers, and 3/3 peer-reviewed workshop papers, and I am an inventor on a patent applications in process. A detailed list is available below and on [Google Scholar](#).

## Peer-reviewed Journal Articles

- > **MF Azampour**, K Mach, E Fatemizadeh, B Demiray, K Westenfelder, et al. Multitask weakly supervised generative network for mr-us registration. *IEEE Transactions on Medical Imaging*, 43(11), 2024
- > **MF Azampour**, M Tirindelli, J Lameski, M Gafencu, E Tagliabue, et al. Anatomy-aware computed tomography-to-ultrasound spine registration. *Medical Physics*, 51(3), 2024
- > Y Velikova, W Simson, **MF Azampour**, P Paprottka, and N Navab. Cactuss: Common anatomical ct-us space for us examinations. *International Journal of Computer Assisted Radiology and Surgery*, 19(5), 2024
- > MA Gafencu, Y Velikova, M Saleh, T Ungi, N Navab, T Wendler, and **MF Azampour**. Shape completion in the dark: completing vertebrae morphology from 3d ultrasound. *International Journal of Computer Assisted Radiology and Surgery*, 19, 2024
- > MY Ansari, Y Yang, S Balakrishnan, J Abinshed, A Al-Ansari, M Warfa, **MF Azampour**, and et al. A lightweight neural network with multiscale feature enhancement for liver ct segmentation. *Scientific Reports*, 12(1), 2022
- > A Segato, C Di Vece, S Zucchelli, M Di Marzo, T Wendler, **MF Azampour**, et al. Position-based dynamics simulator of brain deformations for path planning and intra-operative control in keyhole neurosurgery. *IEEE Robotics and Automation Letters*, 6(3), 2021
- > D Grzech, **MF Azampour**, H Qiu, B Glocker, B Kainz, and LL Folgoc. Uncertainty quantification in non-rigid image registration via stochastic gradient markov chain monte carlo. *Melba Journal*, 1, 2021
- > A Bitarafan, M Mozafari, **MF Azampour**, MS Baghshah, N Navab, et al. Self-supervised 3d medical image segmentation by flow-guided mask propagation learning. *Medical Image Analysis*, 101, 2025

## Peer-reviewed Conference and Workshop Papers

- > H Hase\*, **MF Azampour\***, M Tirindelli, M Paschali, W Simson, et al. Ultrasound-guided robotic navigation with deep reinforcement learning. In *2020 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2020
- > M Wysocki\*, **MF Azampour\***, C Eilers, B Busam, M Salehi, and N Navab. Ultra-nerf: Neural radiance fields for ultrasound imaging. In *Medical Imaging with Deep Learning (MIDL)*, 2023
- > M Tirindelli, C Eilers, W Simson, M Paschali, **MF Azampour**, and N Navab. Rethinking ultrasound augmentation: A physics-inspired approach. In *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, 2021
- > B Zhang, S Faghihroohi, **MF Azampour**, S Liu, R Ghotbi, H Schunkert, et al. A patient-specific self-supervised model for automatic x-ray/ct registration. In *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, 2023
- > D Grzech, **MF Azampour**, B Glocker, J Schnabel, N Navab, B Kainz, et al. A variational bayesian method for similarity learning in non-rigid image registration. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)*, 2022
- > M Domínguez, Y Velikova, N Navab, and **MF Azampour**. Diffusion as sound propagation: Physics-inspired model for ultrasound image generation. In *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, 2024
- > Y Velikova\*, **MF Azampour\***, W Simson, M Esposito, and N Navab. Implicit neural representations for breathing-compensated volume reconstruction in robotic ultrasound. In *2024 IEEE International Conference on Robotics and Automation (ICRA)*, 2024
- > B Jian, **MF Azampour**, F De Benetti, J Oberreuter, C Bukas, AS Gersing, et al. Weakly-supervised biomechanically-constrained ct/mri registration of the spine. In *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, 2022
- > A Bitarafan, **MF Azampour**, K Bakhtari, M Soleymani Baghshah, et al. Vol2flow: Segment 3d volumes using a sequence of registration flows. In *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, 2022
- > Y Velikova, **MF Azampour**, W Simson, V Gonzalez Duque, and N Navab. Lotus: Learning to optimize task-based us representations. In *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, 2023
- > M Fehrentz, **MF Azampour**, R Dorent, H Rasheed, C Galvin, A Golby, et al. Intraoperative registration by cross-modal inverse neural rendering. In *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, 2024
- > M Mozafari, A Bitarafan, **MF Azampour**, A Farshad, et al. Visa-fss: A volume-informed self supervised approach for few-shot 3d segmentation. In *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, 2023
- > LD Reyes Vargas, MJ Menten, JC Paetzold, N Navab, and **MF Azampour**. Skelite: Compact neural networks for efficient iterative skeletonization. In *International Conference on Information Processing in Medical Imaging (IPMI)*, 2025
- > **MF Azampour**, A Ghaffari, A Hamidinekoo, and E Fatemizadeh. Manifold learning based registration algorithms applied to multimodal images. In *2014 36th Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC)*, 2014
- > F Duelmer, **MF Azampour**, M Wysocki, and N Navab. Ultraray: Introducing full-path ray tracing in physics-based ultrasound simulation. In *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, 2025
- > D Grzech, LL Folgoc, **MF Azampour**, A Vlontzos, B Glocker, N Navab, et al. Unsupervised similarity learning for image registration with energy-based models. In *International Workshop on Biomedical Image Registration*, 2024
- > MA Gafencu, Y Velikova, N Navab, and **MF Azampour**. Us-x complete: A multi-modal approach to anatomical 3d shape recovery. In *International Workshop on Shape in Medical Imaging*, 2025
- > J Janelidze, L Folle, N Navab, and **MF Azampour**. Tubular anatomy-aware 3d semantically conditioned image synthesis. In

MICCAI Workshop on Deep Generative Models, 2025

- M Wysocki, F Ducloux, A Bal, N Navab, and **MF Azampour**. Ultron: Ultrasound occupancy networks. In *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, 2025
- S Joutard, M Stollenga, M Balle Sanchez, **MF Azampour**, and R Prevost. Hypersort: Self-organising robust training with hyper-networks. In *International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI)*, 2025
- F Ducloux, **MF Azampour**, and N Navab. Ultrascatter: Ray-based simulation of ultrasound scattering. In *2025 IEEE International Ultrasonics Symposium (IUS)*, 2025
- VB Yesilkaynak, VG Duque, M Wysocki, **MF Azampour**, N Navab, et al. Ultramba: Neural bundle adjustment for pose refinement in 3d freehand ultrasound. In *Proceedings of the IEEE/CVF International Conference on Computer Vision (ICCV)*, 2025
- MB Sanchez, S Joutard, **MF Azampour**, and R Prevost. Why is patch size important? dealing with context variability in segmentation networks. In *Medical Imaging with Deep Learning – Short Papers*, 2025
- **MF Azampour**, Y Velikova, E Fatemizadeh, SP Dakua, and N Navab. Self-supervised probe pose regression via optimized ultrasound representations for us-ct fusion. In *International Conference on Medical Imaging and Computer-Aided Diagnosis*, 2023
- Z Zhang, B Zhang, **MF Azampour**, S Faghihroohi, A Tomczak, et al. Self-supervised vessel segmentation from x-ray images using digitally reconstructed radiographs. In *BVM Workshop*, 2024
- F Ducloux, W Simson, **MF Azampour**, M Wysocki, A Karlas, and N Navab. Phocus: Physics-based deconvolution for ultrasound resolution enhancement. In *International Workshop on Advances in Simplifying Medical Ultrasound*, 2024

## SUMMARY OF RESEARCH CONTRIBUTIONS

**1. Physics-Aware Generative Ultrasound Modeling (Ray Tracing, Diffusion, NeRF).** I introduced a family of physics-integrated generative models for ultrasound simulation, domain translation, and volumetric reconstruction. *UltraRay* provides fast, full-path acoustic ray tracing for realistic simulation; the *Physics-Inspired Diffusion (B-Maps)* scheduler incorporates depth-dependent noise to mimic ultrasound attenuation, yielding large gains in perceptual quality (e.g., Liver FID 73.4  $\rightarrow$  0.86); and *UltraNeRF* is the first ultrasound-specific neural radiance field with physics-based volumetric rendering for view-dependent synthesis. Together, these works form a foundational stack for simulation, virtual re-scanning, and autonomous ultrasound systems.

References: Ducloux, Azampour et al., MICCAI 2025; Domínguez, Azampour et al., MICCAI 2024; Wysocki, Azampour et al., MIDL 2023.

**2. Scalable Weakly Supervised MR–Ultrasound Registration.** I developed *ProRegGAN*, the first multitask weakly supervised MR–US registration framework that requires no ultrasound annotations. A dual-path pseudo-US generator and a structure-preserving MaskNCE objective enable robust cross-modal alignment. The model achieves state-of-the-art prostate MR–US fusion on a 600-patient dataset and generalizes to external cohorts.

Reference: Azampour et al., IEEE TMI 2024.

**3. Anatomy-Aware CT–Ultrasound Registration for Spinal Navigation.** I introduced the first anatomy-aware CT–US registration framework for spinal imaging, combining a structural ultrasound representation (SUR) with an anatomically weighted similarity metric. The method achieves  $\sim 2.4$  mm TRE on robotic spine ultrasound acquisitions and outperforms both classical and learning-based baselines.

Reference: Azampour et al., Medical Physics 2024.

**4. 3D Shape Completion and Anatomical Reconstruction from Sparse Ultrasound.** I developed methods for ultrasound-first 3D anatomical reconstruction capable of recovering complete vertebral geometry from fragmentary and occluded ultrasound. *Implicit Morphometry Networks* reconstruct smooth, anatomically consistent vertebrae from sparse ultrasound observations, while *US-X Complete* fuses sparse ultrasound with a single X-ray via a coarse-to-fine variational completion pipeline, yielding major improvements in CD, EMD, and F1 scores (all  $p < 10^{-6}$ ). These works enable low-radiation, CT-free 3D spine reconstruction suitable for navigation and robotics.

References: Gafencu, Azampour et al., IJCARS 2024; Gafencu, Velikova, Navab, Azampour et al., SMIMI 2025.

**5. Task-Driven Ultrasound Representations and Autonomous Robotic Guidance.** I advanced ultrasound toward autonomy through cross-modal representation learning and ultrasound-guided control. *CACTUSS* introduced a CT-informed intermediate representation for robust aortic segmentation (88–90% DSC across devices). *LOTUS*, introduced subsequently, is a differentiable ultrasound renderer whose parameters are optimized end-to-end for segmentation, achieving  $>89\%$  DSC without ultrasound labels. Finally, *Ultrasound-Guided RL Navigation* demonstrated one of the first reinforcement-learning-driven robotic navigation systems using ultrasound alone, achieving  $\sim 83\%$  success on unseen trials.

References: Velikova, Simson, Azampour et al., IJCARS 2024; Velikova, Azampour et al., MICCAI 2023; Hase, Azampour et al., IROS 2020.

This document was last updated on December 15, 2025.