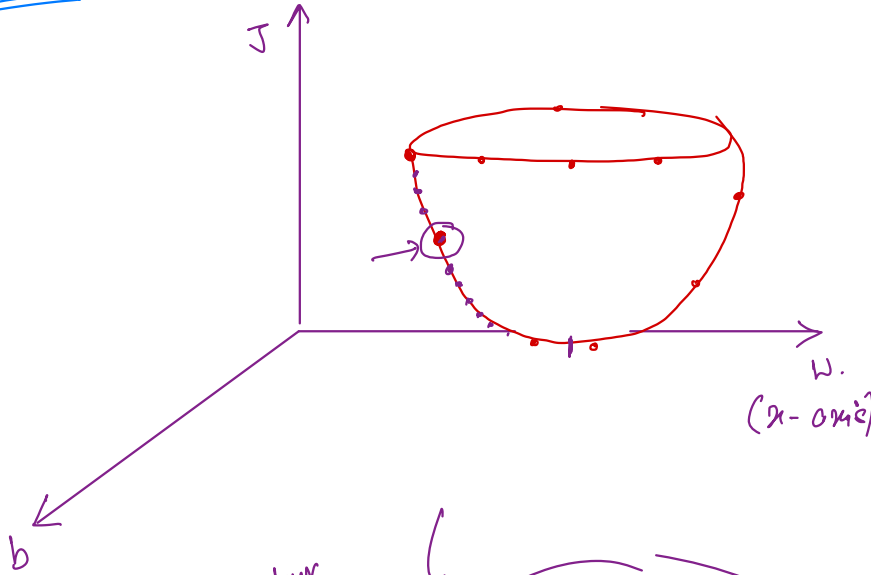
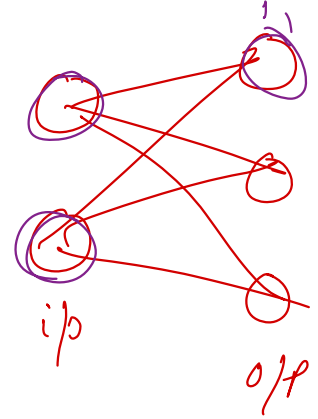


Optimizers



$$J(w, b)$$

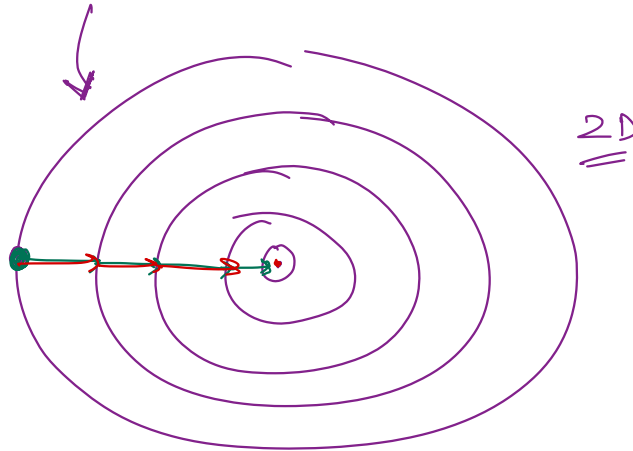
3w



In a contour

Batch gradient descent

faster



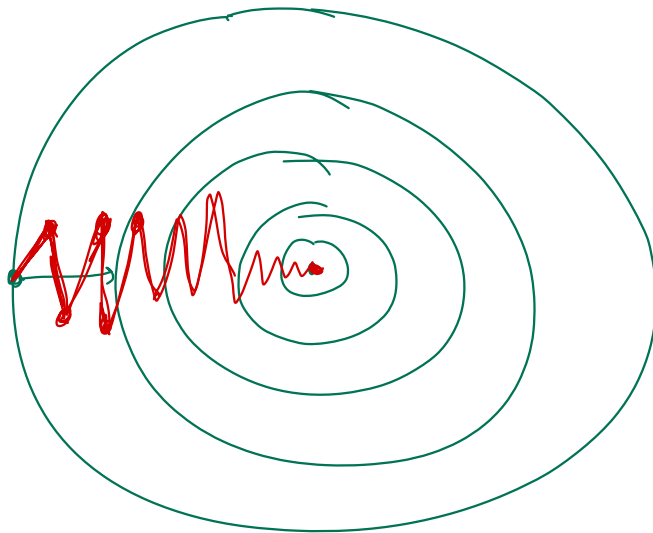
Calculation

5 steps \rightarrow global minima

\Rightarrow

$$5 \times 300 \Rightarrow 1500$$

Mini batch
GD

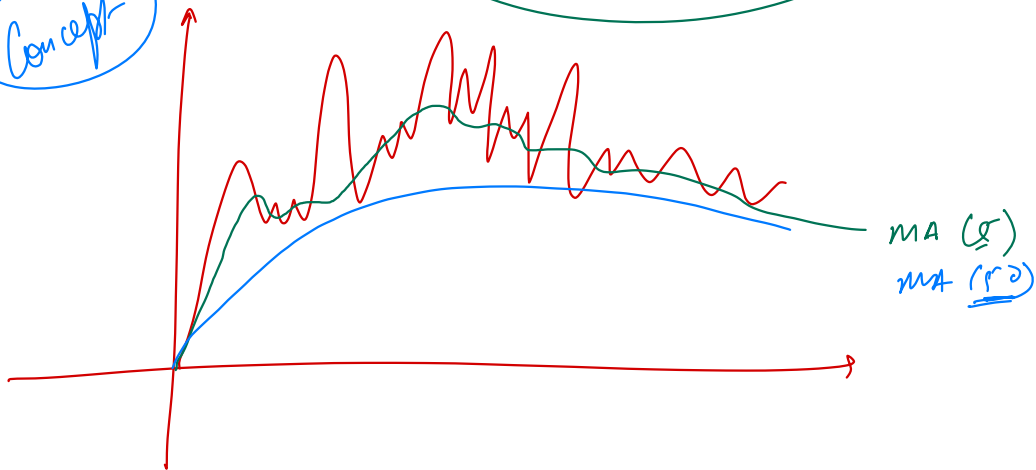


100 data points

10 steps

\Rightarrow 10,00 \Rightarrow

Concept



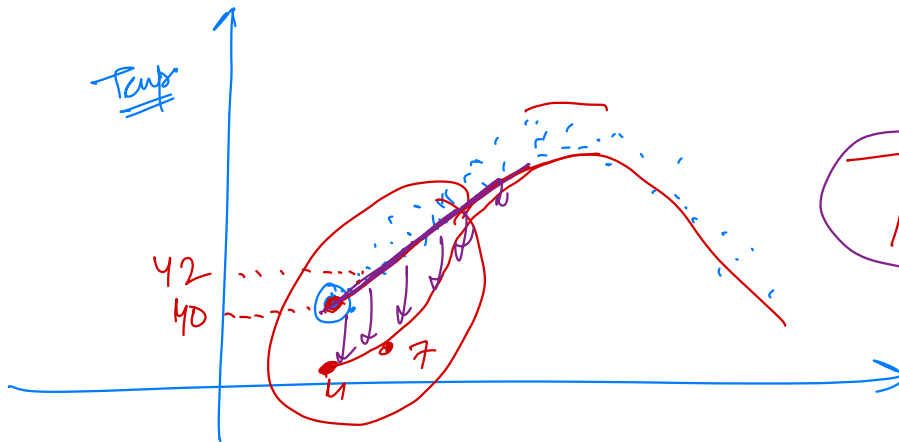
Exponential weighted average

$$t(1) \rightarrow 40$$

$$t(2) \rightarrow 42$$

$$t(3) \rightarrow 50$$

$$t(360) \rightarrow 45$$



$$\frac{V_t}{1 - \beta^t} = \frac{4}{1 - (0.9)^1} \Rightarrow \frac{4}{1 - 0.9}$$

$$\Rightarrow \frac{4}{0.1} \Rightarrow 40$$

gd with momentum

$$V_0 = 0$$

$$\begin{aligned} \underline{V_1} &= (0.9) \underline{V_0} + (0.1) t_1 \\ &\Rightarrow (0.9) \times 0 + (0.1) 40 \Rightarrow \underline{4} \\ \underline{V_2} &= \underline{0.9} (\underline{40}) + (\underline{0.1}) \underline{42} \Rightarrow \underline{7} \end{aligned}$$

$$= 36 + 4.2 \Rightarrow [40.2]!$$

$$V(t) = \beta V_{t-1} + (1-\beta) t$$

Bias corrected

$$V_{dw} = \beta V_{dw} + (1-\beta) dw$$

Calculation of ΣMA .

$$\frac{7}{1-\beta^7}$$

$$dw = \frac{\partial J}{\partial w}$$

$$w^{new} = w^{old} - \alpha dw$$

wavyness

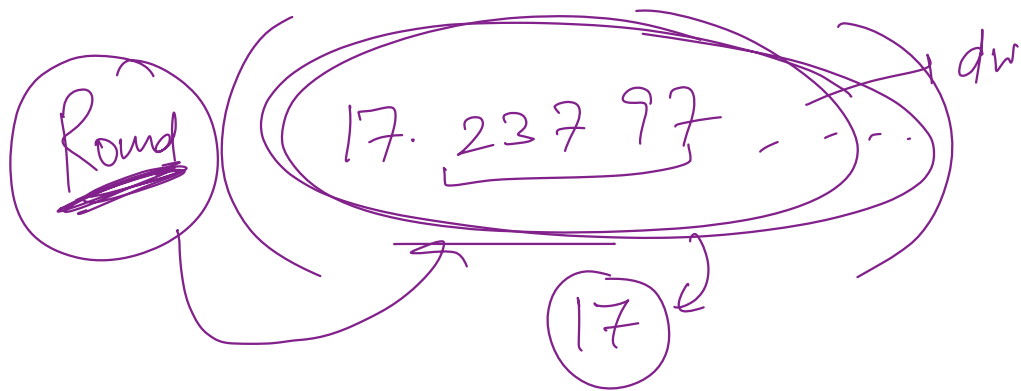
$$w^{new} = w^{old} - \alpha V_{dw}$$

$$db = \frac{\partial J}{\partial b}$$

$$V_{db} = \beta V_{db} + (1-\beta) db$$

friction momentum acceleration

$$b^{new} = b^{old} - \alpha V_{db}$$



V_{dw}



$\beta = 0.9$

$\beta = 0.90$

$\frac{1}{1-\beta}$

$\frac{1}{1-0.9} = 10$

$$\begin{array}{l}
 \textcircled{\beta = 0.5} \\
 \textcircled{1 - \beta = 0.5}
 \end{array}
 \Rightarrow \boxed{\frac{1}{1 - 0.5}} \Rightarrow \textcircled{\underline{2}}$$

$$\rightarrow \boxed{\frac{1}{1 - 0.98}} = \frac{1}{\cancel{0.02}} 0.02 \Rightarrow \frac{100}{0.02} = \underline{\underline{5000}}$$

$$\Rightarrow \frac{100}{0.02} = \underline{\underline{5000}}$$