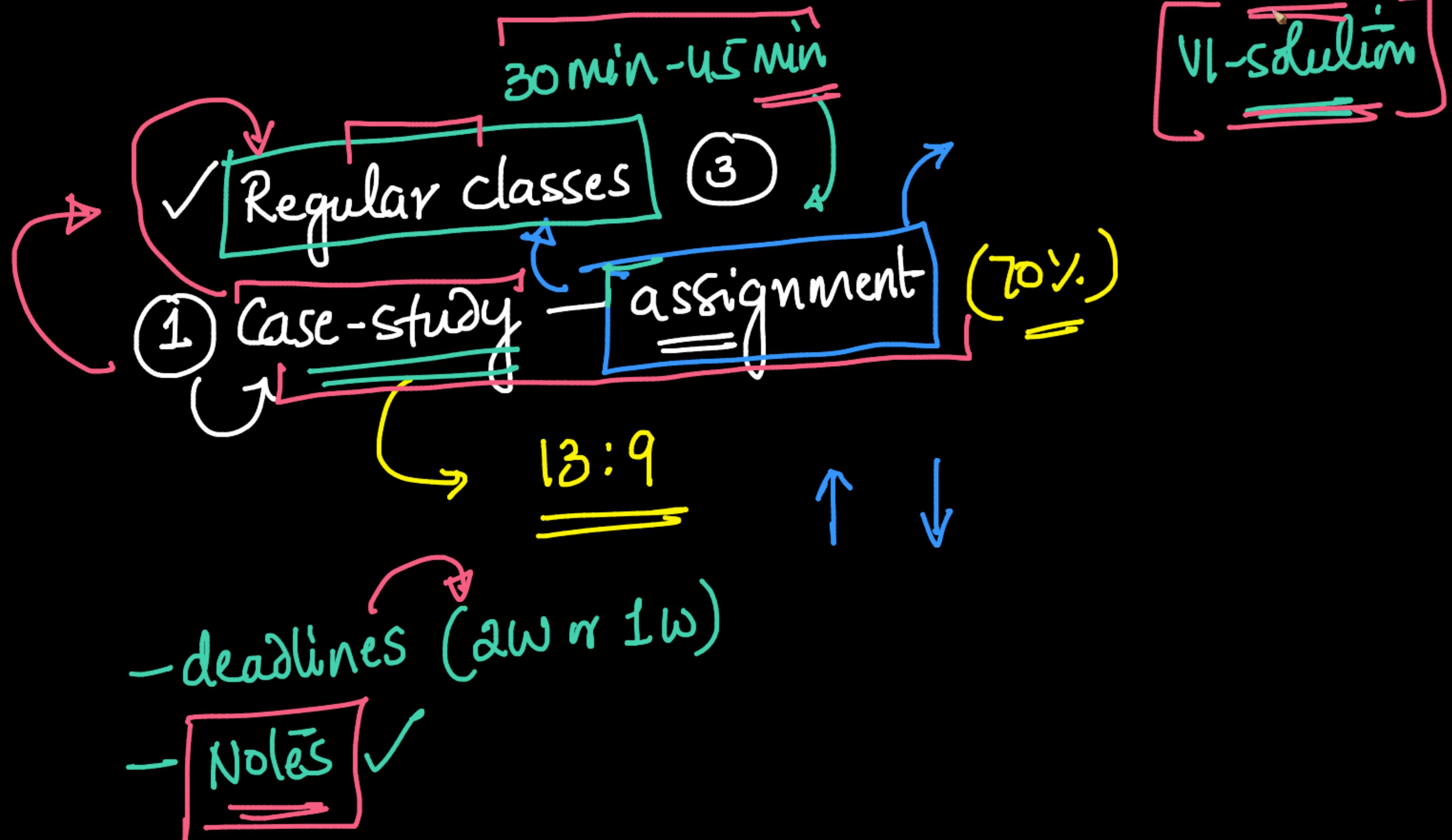
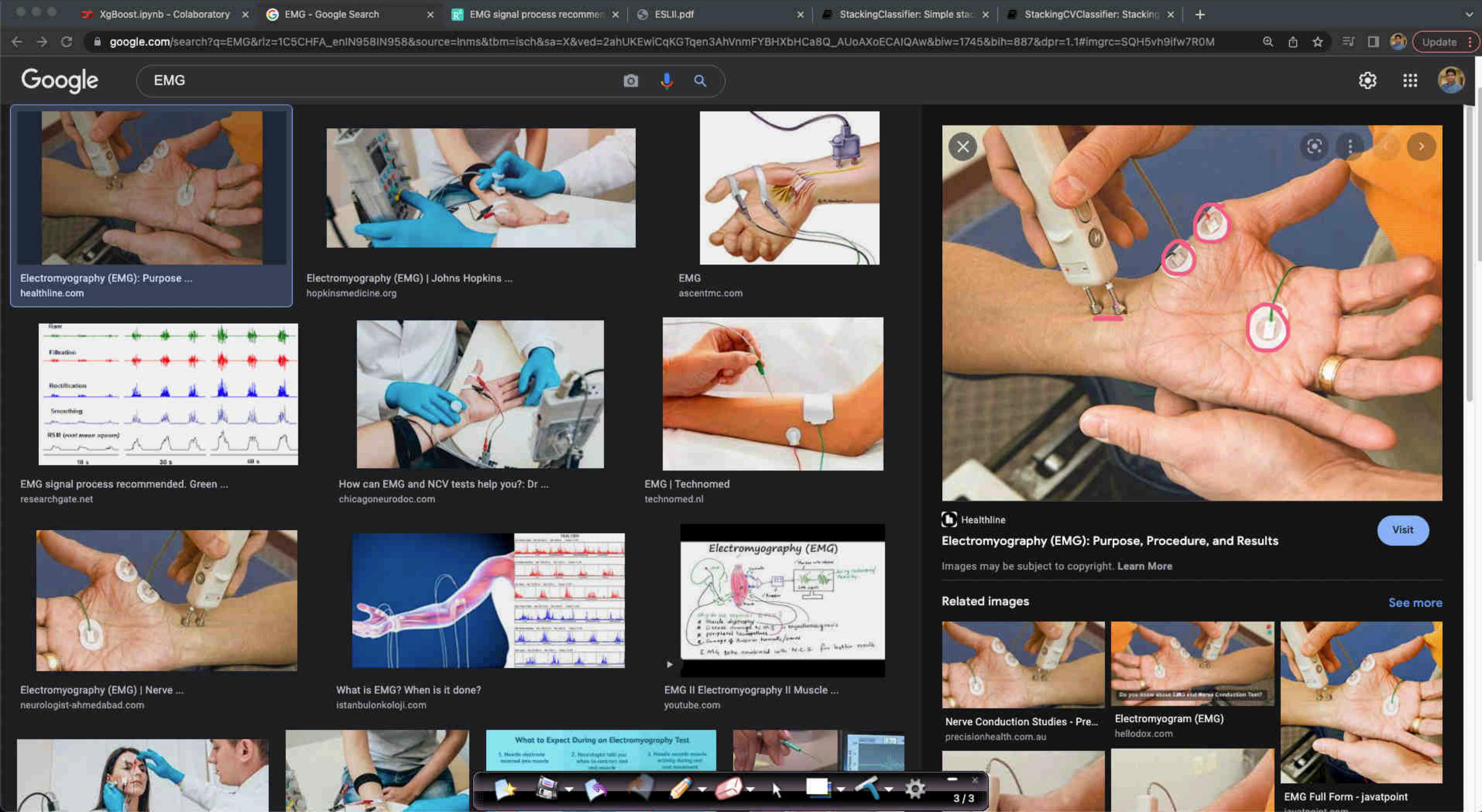


Topics:

- EMG →  DT
- ① Case-study: Bio-signals
 - ② { Code for XgBoost
 - ✓ ③ k-fold CV
 - ✓ ④ GridSearch & RandomSearch
 - ⑤ Feature Importance: GBDT
 - ⑥ Cascading ✓
 - ⑦ Stacking ✓
 - ⑧ Q&A
→
$$\frac{-\partial L}{\partial f(x)} \approx \text{residuals}$$





| Segment | R-Arm | L-Arm | R-Leg | L-Leg |
+-----+-----+-----+-----+-----+-----+
Channel	ch1	ch2	ch3	ch4	ch5	ch6	ch7	ch8
Muscle	R-Bic	R-Tri	L-Bic	L-Tri	R-Thi	R-Ham	L-Thi	L-Ham
Column	0	1	2	3	4	5	6	7
+-----+-----+-----+-----+-----+-----+

Segment: A segment defines a body segment or limb.

- Right arm (R-Arm)
- Left arm (L-Arm)
- Right leg (R-Leg)
- Left leg (L-Leg)

Channel: A channel corresponds to an electrode attached on a muscle.

Muscle: A pair of muscles that corresponds to a segment.

- R-Bic: right bicep (C1)
- R-Tri: right tricep (C2)
- L-Bic: left bicep (C3)
- L-Tri: left tricep (C4)
- R-Thi: right thigh (C5)
- R-Ham: right hamstring (C6)
- L-Thi: left thigh (C7)
- L-Ham: left hamstring (C8)

Relevant Papers:

N/A

Citation Request:



XgBoost.ipynb - Colaboratory x EMG - Google Search x R EMG signal process recommen x ESLII.pdf x StackingClassifier: Simple sta x StackingCVClassifier: Stackin x UCI Machine Learning Reposit x + colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=J9y5YFVFw8t6

+ Code + Text Reconnect  

[] # EMG Data Analysis
Source: <https://archive.ics.uci.edu/ml/datasets/EMG+Physical+Action+Data+Set>

{x}

[] #How was the data collected ?
Person/Subject was asked to perform specific physical actions
Signals produced due to that movement were recorded over time.
8 channels were used to record the signals
Channels here correspond to muscles\ For eg: Right-hand bicep
Frequency : 10 per ms

[] !wget "<https://drive.google.com/uc?export=download&id=1ZgZYFdM1QyccRtHs16AhJUEnLPhgjCc7>" -O EMG_data.rar

--2022-05-18 13:05:36-- <https://drive.google.com/uc?export=download&id=1ZgZYFdM1QyccRtHs16AhJUEnLPhgjCc7>
Resolving drive.google.com (drive.google.com)... 108.177.119.102, 108.177.119.139, 108.177.119.113, ...
Connecting to drive.google.com (drive.google.com)|108.177.119.102|:443... connected.
HTTP request sent, awaiting response... 303 See Other
Location: <https://doc-0o-14-docs.googleusercontent.com/docs/securesc/ha0ro937gcuc717deffksulhg5h7mbpl/bkumsf47lms7nj>
Warning: wildcards not supported in HTTP.
--2022-05-18 13:05:42-- <https://doc-0o-14-docs.googleusercontent.com/docs/securesc/ha0ro937gcuc717deffksulhg5h7mbpl>
Resolving doc-0o-14-docs.googleusercontent.com (doc-0o-14-docs.googleusercontent.com)... 142.250.145.132, 2a00:1450:
Connecting to doc-0o-14-docs.googleusercontent.com (doc-0o-14-docs.googleusercontent.com)|142.250.145.132|:443... co
HTTP request sent, awaiting response... 200 OK

5/5

colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=J9y5YFVFw8t6

+ Code + Text Reconnect  

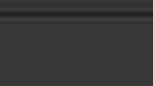
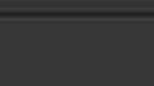
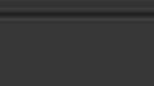
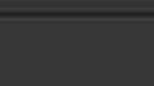
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Source: <https://archive.ics.uci.edu/ml/datasets/EMG+Physical+Action+Data+Set>

{x}          

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--2022-05-18 13:05:36-- <https://drive.google.com/uc?export=download&id=1ZgZYFdM1QyccRtHs16AhJUEnLPhgjCc7>
Resolving drive.google.com (drive.google.com)... 108.177.119.102, 108.177.119.139, 108.177.119.113, ...
Connecting to drive.google.com (drive.google.com)|108.177.119.102|:443... connected.
HTTP request sent, awaiting response... 303 See Other
Location: <https://doc-0o-14-docs.googleusercontent.com/docs/securesc/ha0ro937gcuc717deffksulhg5h7mbpl/bkumsf47lms7nj>
Warning: wildcards not supported in HTTP.
--2022-05-18 13:05:42-- <https://doc-0o-14-docs.googleusercontent.com/docs/securesc/ha0ro937gcuc717deffksulhg5h7mbpl>
Resolving doc-0o-14-docs.googleusercontent.com (doc-0o-14-docs.googleusercontent.com)... 142.250.145.132, 2a00:1450:
Connecting to doc-0o-14-docs.googleusercontent.com (doc-0o-14-docs.googleusercontent.com)|142.250.145.132|:443... co
HTTP request sent, awaiting response... 200 OK

              6/6

+ Code + Text

Reconnect



```
[ ] # EMG Data Analysis  
# Source: https://archive.ics.uci.edu/ml/datasets/EMG+Physical+Action+Data+Set
```



```
#How was the data collected ?  
## Person/Subject was asked to perform specific physical actions  
## Signals produced due to that movement were recorded over time.  
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```

```
[ ] !wget "https://drive.google.com/uc?export=download&id=1ZgZYFdM1QyccRtHs16AhJUEnLPhgjCc7" -O EMG_data.rar  
--2022-05-18 13:05:36-- https://drive.google.com/uc?export=download&id=1ZgZYFdM1QyccRtHs16AhJUEnLPhgjCc7  
Resolving drive.google.com (drive.google.com)... 108.177.119.102, 108.177.119.139, 108.177.119.113, ...  
Connecting to drive.google.com (drive.google.com)|108.177.119.102|:443... connected.  
HTTP request sent, awaiting response... 303 See Other  
Location: https://doc-0o-14-docs.googleusercontent.com/docs/securesc/ha0ro937gcuc717deffksulhg5h7mbpl/bkumsf47lms7nj  
Warning: wildcards not supported in HTTP.  
--2022-05-18 13:05:42-- https://doc-0o-14-docs.googleusercontent.com/docs/securesc/ha0ro937gcuc717deffksulhg5h7mbpl  
Resolving doc-0o-14-docs.googleusercontent.com (doc-0o-14-docs.googleusercontent.com)... 142.250.145.132, 2a00:1450:  
Connecting to doc-0o-14-docs.googleusercontent.com (doc-0o-14-docs.googleusercontent.com)|142.250.145.132|:443... co  
HTTP request sent, awaiting response... 200 OK
```

+ Code + Text

Reconnect   

```
[ ] # EMG Data Analysis  
# Source: https://archive.ics.uci.edu/ml/datasets/EMG+Physical+Action+Data+Set
```

4 people

8 signals → activity

```
#How was the data collected ?  
## Person/Subject was asked to perform specific physical actions  
## Signals produced due to that movement were recorded over time.  
## 8 channels were used to record the signals  
## Channels here correspond to muscles\ For eg: Right-hand bicep  
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```

```
[ ] !wget "https://drive.google.com/uc?export=download&id=1ZgZYFdM1QyccRtHs16AhJUEnLPhgjCc7" -O EMG_data.rar  
  
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Resolving drive.google.com (drive.google.com)... 108.177.119.102, 108.177.119.139, 108.177.119.113, ...  
Connecting to drive.google.com (drive.google.com)|108.177.119.102|:443... connected.  
HTTP request sent, awaiting response... 303 See Other  
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Warning: wildcards not supported in HTTP.  
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Resolving doc-0o-14-docs.googleusercontent.com (doc-0o-14-docs.googleusercontent.com)... 142.250.145.132, 2a00:1450:  
Connecting to doc-0o-14-docs.googleusercontent.com (doc-0o-14-docs.googleusercontent.com)|142.250.145.132|:443... co  
HTTP request sent, awaiting response... 200 OK
```

colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=WW7no69lwQVj

+ Code + Text

EMG_data.rar 100% [=====] 1 / 14M 35.3MB/S in 0.5s ✓ RAM Disk

2022-05-18 15:47:22 (35.3 MB/s) - 'EMG_data.rar' saved [18602479/18602479]

{x}

```
[ ] !unrar x "./EMG_data.rar" "./"  
Extracting ./EMG Physical Action Data Set/sub3/Normal/log/Hugging.log OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/log/Jumping.log OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/log/Running.log OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/log/Seating.log OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/log/Standing.log OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/log/Walking.log OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/log/Waving.log OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Bowing.txt OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Clapping.txt OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Handshaking.txt OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Hugging.txt OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Jumping.txt OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Running.txt OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Seating.txt OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Standing.txt OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Walking.txt OK  
Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Waving.txt OK  
Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/Elbowing.log OK  
Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/FrontKicking.log OK  
Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/Hamerling.log OK
```

colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=WW7no69lwQVj

+ Code + Text ✓ RAM Disk

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/log/Seating.log OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/log/Standing.log OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/log/Walking.log OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/log/Waving.log OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Bowing.txt OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Clapping.txt OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Handshaking.txt OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Hugging.txt OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Jumping.txt OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Running.txt OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Seating.txt OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Standing.txt OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Walking.txt OK

[] Extracting ./EMG Physical Action Data Set/sub3/Normal/txt/Waving.txt OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/Elbowing.log OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/FrontKicking.log OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/Hamerling.log OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/Headering.log OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/Kneeing.log OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/Pulling.log OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/Punching.log OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/Pushing.log OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/SideKicking.log OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/log/Slapping.log OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/txt/Elbowing.txt OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/txt/Frontkicking.txt OK

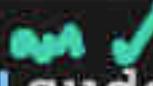
[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/txt/Hamerling.txt OK

[] Extracting ./EMG Physical Action Data Set/sub4/Aggressive/txt/Headering.txt OK

XgBoost.ipynb - Colaboratory x EMG - Google Search x R EMG signal process recommen x ESLII.pdf x StackingClassifier: Simple sta x StackingCVClassifier: Stackin x UCI Machine Learning Reposit x + colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=ZcwB3XVWxPgj Update :

+ Code + Text

Extracting ./EMG Physical Action Data Set/sub4/Normal/txt/Seating.txt OK
[] Extracting ./EMG Physical Action Data Set/sub4/Normal/txt/Standing.txt OK
Extracting ./EMG Physical Action Data Set/sub4/Normal/txt/Walking.txt OK
Extracting ./EMG Physical Action Data Set/sub4/Normal/txt/Waving.txt OK
All OK

 !sudo apt install tree

Reading package lists... Done
Building dependency tree
Reading state information... Done
tree is already the newest version (1.7.0-5).
The following packages were automatically installed and are no longer required:
libnvidia-common-460 nsight-compute-2020.2.0
Use 'sudo apt autoremove' to remove them.
0 upgraded, 0 newly installed, 0 to remove and 67 not upgraded.

[] !tree "./EMG Physical Action Data Set/sub1"

./EMG Physical Action Data Set/sub1
└── Aggressive
 ├── log
 │ ├── Elbowing.log
 │ └── FrontKicking.log

RAM Disk

problem XGBoost

 XgBoost.ipynb - Colaboratory EMG - Google Search

 EMG - Google Search

R EMG signal process recomm. ESLII.pdf

StackingClassifier: Simple sta

StackingCVClassifier: Stacking X | S UCI Machine Learning R

deposit   

Code # Text

✓ RAM Disk

A small icon representing user settings or preferences.

▼

```
[ ] Extracting ./EMG Physical Action Data Set/sub4/Normal/txt/Seating.txt OK
[ ] Extracting ./EMG Physical Action Data Set/sub4/Normal/txt/Standing.txt OK
[ ] Extracting ./EMG Physical Action Data Set/sub4/Normal/txt/Walking.txt OK
[ ] Extracting ./EMG Physical Action Data Set/sub4/Normal/txt/Waving.txt OK
All OK
```

```
!sudo apt install tree
```

```
Reading package lists... Done
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```

```
[ ] !tree "./EMG Physical Action Data Set/sub1
```

```
./EMG Physical Action Data Set/sub1  
|   __ Aggressive  
|       |   log  
|           |   Elbowing.log  
|           |   FrontKicking.log
```

XgBoost.ipynb - Colaboratory x EMG - Google Search x R EMG signal process recommen x ESLII.pdf x StackingClassifier: Simple sta x StackingCVClassifier: Stackin x UCI Machine Learning Reposit x + colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=ZcwB3XVWxPgj Update :+ Code + Text

RAM Disk ✓

Extracting ./EMG Physical Action Data Set/sub4/Normal/txt/Seating.txt OK
[] Extracting ./EMG Physical Action Data Set/sub4/Normal/txt/Standing.txt OK
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./EMG Physical Action Data Set/sub1
└── Aggressive
 ├── log
 │ ├── Elbowing.log
 │ └── FrontKicking.log

13 / 13

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+ Code + Text

RAM Disk

[]

```
./EMG Physical Action Data Set/sub1
  └── Aggressive
      ├── log
      │   ├── Elbowing.log
      │   ├── FrontKicking.log
      │   ├── Hamering.log
      │   ├── Headering.log
      │   ├── Kneeing.log
      │   ├── Pulling.log
      │   ├── Punching.log
      │   ├── Pushing.log
      │   ├── SideKicking.log
      │   └── Slapping.log
      └── txt
          ├── Elbowing.txt
          ├── Frontkicking.txt
          ├── Hamering.txt
          ├── Headering.txt
          ├── Kneeing.txt
          ├── Pulling.txt
          ├── Punching.txt
          ├── Pushing.txt
          ├── Sidekicking.txt
          └── Slapping.txt
  └── Normal
      └── log
```

{x}

14 / 14

colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=ZcwB3XVWxPgj

+ Code + Text

RAM Disk

Kneeling.txt
Pulling.txt
Punching.txt
Pushing.txt
Sidekicking.txt
Slapping.txt

{x}

Normal

log

Bowing.log
Clapping.log
Handshaking.log
Hugging.log
Jumping.log
Running.log
Seating.log
Standing.log
Walking.log
Waving.log

txt

Bowing.txt
Clapping.txt
Handshaking.txt
Hugging.txt
Jumping.txt
Running.txt
Seating.txt
Standing.txt
Walking.txt

XgBoost.ipynb - Colaboratory x EMG - Google Search x R EMG signal process recommen x ESLII.pdf x StackingClassifier: Simple sta x StackingCVClassifier: Stackin x UCI Machine Learning Reposit x + colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=ZcwB3XVWxPgj Update :

+ Code + Text

[]

- Running.txt
- Seating.txt
- Standing.txt
- Walking.txt
- Waving.txt

{x}

6 directories, 40 files

[] !ls -lrt ./EMG\ Physical\ Action\ Data\ Set/sub1/Aggressive/txt/

total 3768

-rw-r--r-- 1 root root 361096 Feb 7 2010 Slapping.txt

-rw-r--r-- 1 root root 388912 Feb 7 2010 Sidekicking.txt

-rw-r--r-- 1 root root 379428 Feb 7 2010 Pushing.txt

-rw-r--r-- 1 root root 379597 Feb 7 2010 Punching.txt

-rw-r--r-- 1 root root 387656 Feb 7 2010 Pulling.txt

-rw-r--r-- 1 root root 398523 Feb 7 2010 Kneeing.txt

-rw-r--r-- 1 root root 350285 Feb 7 2010 Headering.txt

-rw-r--r-- 1 root root 402363 Feb 7 2010 Hamering.txt

-rw-r--r-- 1 root root 390158 Feb 7 2010 Frontkicking.txt

-rw-r--r-- 1 root root 398095 Feb 7 2010 Elbowing.txt

[] !cat ./EMG\ Physical\ Action\ Data\ Set/sub1/Aggressive/txt/Slapping.txt

-999	392	38	-51	1409	-90	628	-348
-979	335	30	-95	1995	-71	653	-297
-858	213	-9	-98	2516	-153	419	-305

RAM Disk

16 / 16

colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=ZcwB3XVWxPgj

+ Code + Text

RAM Disk

{x}

10 times per MS

1ms

8-channels/sensors

```
[ ] !cat ./EMG\ Physical\ Action\ Data\ Set\ sub1\ Aggressive/txt/Slapping.txt
```

	-999	292	38	-51	1409	-90	628	-248
<>	-979	335	30	-95	1995	-71	653	-297
1ms	-858	213	-9	-98	2516	-153	419	-305
	-649	93	-63	-62	2822	-11	384	-297
	-417	-15	-52	-90	2968	-87	102	-294
	-245	-91	-76	-54	2947	-216	-379	-319
	-93	-192	-59	-48	2822	-251	-236	-288
	-42	-215	-66	-12	2374	-137	329	-276
	-58	-136	-37	-5	1771	-140	411	-278
	-39	-161	62	-4	1409	-32	329	-314
	6	-173	37	18	1017	180	702	-333
	38	-167	7	1	519	426	1119	-380
	73	-210	19	23	-147	766	1520	-314
	12	-161	9	10	-1007	365	1591	-195
	-104	43	2	23	-1980	-6	1451	-179
	-84	87	21	2	-2395	101	1402	-154
	41	-53	8	16	-1945	-113	1320	-105

XgBoost.ipynb - Colaboratory | EMG - Google Search | R EMG signal process recomm | ESLII.pdf | StackingClassifier: Simple sta | StackingCVClassifier: Stackin | UCI Machine Learning Repos | +

+ Code	+ Text							
-172	-18	-148	-23	-2484	429	-350	-93	
[1]	-447	38	-127	10	-2344	319	-1142	-43
	-665	122	-39	-3	-1729	-193	-2015	37
	-453	282	158	-19	-1685	-347	-2549	296
	-307	212	299	-17	-1837	-34	-3455	485
	-187	-38	272	-1	-1398	167	-4000	387
	-191	-275	140	4	-864	107	-4000	339
	-482	-318	50	-5	-658	283	-4000	308
	-596	-162	8	-12	-406	115	-4000	202
	-361	-149	-55	4	625	85	-4000	155
	-26	-224	-91	-16	976	-37	-4000	-5
	186	-155	-87	-32	635	27	-4000	-338
	408	72	-97	22	635	27	-4000	-338

10 lines \rightarrow 1 msec

9788 → 978 msec
< 1 sec

```
▶ wc -l ./EMG\ Physical\ Action\ Data\ Set/sub1/Aggressive/txt/Slapping.txt
```

```
[ ] import os  
import matplotlib.pyplot as plt  
import numpy as np  
import pandas as pd  
import sklearn  
  
actions = {}
```

 XgBoost.ipynb - Colaboratory EMG - Google Search

 EMG - Google Search

R EMG signal process recommend ESLII.pdf

StackingClassifier: Simple sta: ×

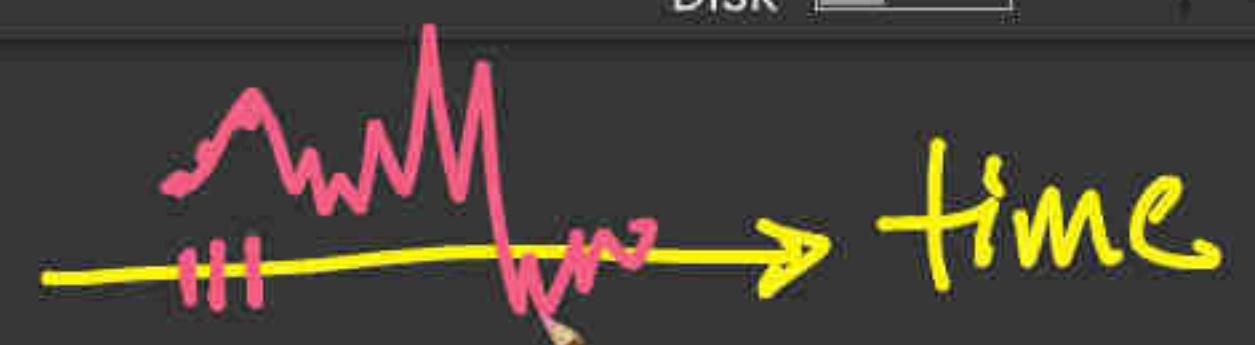
StackingCVClassifier: StackingCVClassifier | UCI Machine Learning Repository

10

1

+ Code + Text

[]	-172	-18	-148	-23	-2484	429	-350	-93
	-447	38	-127	10	-2344	319	-1142	-43
	-665	122	-39	-3	-1729	-193	-2015	37
	-453	282	158	-19	-1685	-347	-2549	296
	-307	212	299	-17	-1837	-34	-3455	485
	-187	-38	272	-1	-1398	167	-4000	387
	-191	-275	140	4	-864	107	-4000	339
	-482	-318	50	-5	-658	283	-4000	308
	-596	-162	8	-12	-406	115	-4000	202
	-361	-149	-55	4	625	85	-4000	155
	-26	-224	-91	-16	976	-37	-4000	-5
	186	-155	-87	-32	635	27	-4000	-338
	408	72	-97	22	635	27	-4000	-338



```
!wc -l ./EMG\ Physical\ Action\ Data\ Set/sub1/Aggressive/txt/Slapping.txt
```

9788 ./EMG Physical Action Data Set/sub1/Aggressive/txt/Slapping.txt

```
[ ] import os  
import matplotlib.pyplot as plt  
import numpy as np  
import pandas as pd  
import sklearn  
  
actions = {}
```

+ Code + Text

RAM
Disk

```
[ ] {x} [ ]
```

	-172	-18	-148	-23	-2484	429	-350	-93
[]	-447	38	-127	10	-2344	319	-1142	-43
{x}	-665	122	-39	-3	-1729	-193	-2015	37
[]	-453	282	158	-19	-1685	-347	-2549	296
{x}	-307	212	299	-17	-1837	-34	-3455	485
[]	-187	-38	272	-1	-1398	167	-4000	387
{x}	-191	-275	140	4	-864	107	-4000	339
[]	-482	-318	50	-5	-658	283	-4000	308
{x}	-596	-162	8	-12	-406	115	-4000	202
[]	-361	-149	-55	4	625	85	-4000	155
{x}	-26	-224	-91	-16	976	-37	-4000	-5
[]	186	-155	-87	-32	635	27	-4000	-338
{x}	408	72	-97	22	635	27	-4000	-338

```
[ ] !wc -l ./EMG\ Physical\ Action\ Data\ Set\sub1/Aggressive/txt/Slapping.txt
```

```
9788 ./EMG Physical Action Data Set/sub1/Aggressive/txt/Slapping.txt
```

```
[ ] <> import os  
import matplotlib.pyplot as plt  
import numpy as np  
import pandas as pd  
import sklearn  
  
actions = {}
```

+ Code + Text

RAM Disk

Disabled

8-sensors → Robot

ML → 20 activities

[]	-172	-18	-148	-23	-2484	429	-350	-93
{x}	-447	38	-127	10	-2344	319	-1142	-43
	-665	122	-39	-3	-1729	-193	-2015	37
	-453	282	158	-19	-1685	-347	-2549	296
	-307	212	299	-17	-1837	-34	-3455	485
	-187	-38	272	-1	-1398	167	-4000	387
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	-596	-162	8	-12	-406	115	-4000	202
	-361	-149	-55	4	625	85	-4000	155
	-26	-224	-91	-16	976	-37	-4000	-5
	186	-155	-87	-32	635	27	-4000	-338
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!wc -l ./EMG\ Physical\ Action\ Data\ Set/sub1/Aggressive/txt/Slapping.txt

9788 ./EMG Physical Action Data Set/sub1/Aggressive/txt/Slapping.txt

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import matplotlib.pyplot as plt  
import numpy as np  
import pandas as pd  
import sklearn  
  
actions = {}
```

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 EMG - Google Search

R EMG signal process recomm x | ESLI.pdf

kingClassifier: Simple sta

StackingCVClassifier: Stacking X | UCI Machine Learning

51 | +

1

+ Code	+ Text							
-172	-18	-148	-23	-2484	429	-350	-93	
[]	-447	38	-127	10	-2344	319	-1142	-43
	-665	122	-39	-3	-1729	-193	-2015	37
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	186	-155	-87	-32	635	27	-4000	-338
	408	72	-97	22	635	27	-4000	-338

raw 8 signals \rightarrow activity

```
!wc -l ./EMG\ Physical\ Action\ Data\ Set/sub1/Aggressive/txt/Slapping.txt
```

9788 ./EMG Physical Action Data Set/sub1/Aggressive/txt/Slapping.txt

```
[ ] import os  
import matplotlib.pyplot as plt  
import numpy as np  
import pandas as pd  
import sklearn  
  
actions = {}
```

+ Code + Text

✓ RAM
Disk



```
[ ] [x] -172 -18 -148 -23 -2484 429 -350 -93
[ ] [-447 38 -127 10 -2344 319 -1142 -43
[ ] -665 122 -39 -3 -1729 -193 -2015 37
[ ] -453 282 158 -19 -1685 -347 -2549 296
[ ] -307 212 299 -17 -1837 -34 -3455 485
[ ] -187 -38 272 -1 -1398 167 -4000 387
[ ] -191 -275 140 4 -864 107 -4000 339
[ ] -482 -318 50 -5 -658 283 -4000 308
[ ] -596 -162 8 -12 -406 115 -4000 202
[ ] -361 -149 -55 4 625 85 -4000 155
[ ] -26 -224 -91 -16 976 -37 -4000 -5
[ ] 186 -155 -87 -32 635 27 -4000 -338
[ ] 408 72 -97 22 635 27 -4000 -338
```

!wc -l ./EMG\ Physical\ Action\ Data\ Set/sub1/Aggressive/txt/Slapping.txt

9788 ./EMG Physical Action Data Set/sub1/Aggressive/txt/Slapping.txt

```
[ ] import os
import matplotlib.pyplot as plt
import numpy as np
import pandas as pd
import sklearn

actions = {}
```

+	-----+	-----+	-----+	-----+	-----+
Segment R-Arm L-Arm R-Leg L-Leg					
+	-----+	-----+	-----+	-----+	-----+
Channel ch1 ch2 ch3 ch4 ch5 ch6 ch7 ch8					
Muscle R-Bic R-Tri L-Bic L-Tri R-Thi R-Ham L-Thi L-Ham					
Column 0 1 2 3 4 5 6 7					
+	-----+	-----+	-----+	-----+	-----+

Segment: A segment defines a body segment or limb.

- Right arm (R-Arm)
- Left arm (L-Arm)
- Right leg (R-Leg)
- Left leg (L-Leg)

Channel: A channel corresponds to an electrode attached on a muscle.

Muscle: A pair of muscles that corresponds to a segment.

- R-Bic: right bicep (C1)
- R-Tri: right tricep (C2)
- L-Bic: left bicep (C3)
- L-Tri: left tricep (C4)
- R-Thi: right thigh (C5)
- R-Ham: right hamstring (C6)
- L-Thi: left thigh (C7)
- L-Ham: left hamstring (C8)

8 signals $\xrightarrow{\text{ML}}$ activity

Relevant Papers:

N/A

colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=VRVsWrzO_NQn

+ Code + Text

RAM Disk

8-channels =

Data:

1 → 1/10ms

1sec → 10K obs

```
[ ] import os
import matplotlib.pyplot as plt
import numpy as np
import pandas as pd
import sklearn

actions = {}

data_dirs = [ "./EMG Physical Action Data Set/sub1/Aggressive/txt",
              "./EMG Physical Action Data Set/sub1/Normal/txt"]

ind = 0
data = pd.DataFrame()

for dirs in data_dirs :

    for files in os.listdir(dirs):

        with open(os.path.join(dirs, files), "r") as f:

            temp = pd.read_csv(f.name,
                               sep = "\t",
                               header = None,
                               names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels
            
```

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colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=VRVsWrzO_NQn

+ Code + Text

RAM Disk

Import

```
[ ] import matplotlib.pyplot as plt
import numpy as np
import pandas as pd
import sklearn
{x}
✓ actions = {}

{
    data_dirs = ["./EMG Physical Action Data Set/sub1/Aggressive/txt",
                 "./EMG Physical Action Data Set/sub1/Normal/txt"]

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                temp = pd.read_csv(f.name,
                                   sep = "\t",
                                   header = None,
                                   names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels
                )

```

Update

+ Code + Text

import os

```
[ ] import matplotlib.pyplot as plt  
import numpy as np  
import pandas as pd  
import sklearn
```

```
actions = {}
```

```
data_dirs = ["./EMG Physical Action Data Set/sub1/Aggressive/txt",  
            "./EMG Physical Action Data Set/sub1/Normal/txt"]
```

✓
ind = 0

```
data = pd.DataFrame()
```

```
for dirs in data_dirs :
```

```
    for files in os.listdir(dirs):
```

```
        with open(os.path.join(dirs, files), "r") as f:
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            temp = pd.read_csv(f.name,  
                               sep = "\t",  
                               header = None,  
                               names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels  
            )
```

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[ ] data_dirs = ["./EMG Physical Action Data Set/sub1/Aggressive/txt",
    "./EMG Physical Action Data Set/sub1/Normal/txt"] .  
  
ind = 0  
data = pd.DataFrame()  
  
for dirs in data_dirs :  
    for files in os.listdir(dirs):  
        with open(os.path.join(dirs, files), "r") as f:  
            temp = pd.read_csv(f.name,  
                               sep = "\t",  
                               header = None,  
                               names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels  
            )  
  
# chunking using Max of every 10 sequential values.  
temp_chunked = pd.DataFrame()  
  
for i in range(0, len(temp), 10):  
    temp_chunked = temp_chunked.append(temp.iloc[i:i+10].max(), ignore_index = True)  
  
labels = [files[:-4] for i in range(len(temp_chunked))] # remove the last 4 characters=".txt" from the filena
```

colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=VRVsWrzO_NQn

+ Code + Text

RAM Disk

TSV

```
[ ] for dirs in data_dirs :  
    for files in os.listdir(dirs):  
        with open(os.path.join(dirs, files), "r") as f:  
            temp = pd.read_csv(f.name,  
                                sep = "\t",  
                                header = None,  
                                names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels  
            )  
  
            # chunking using Max of every 10 sequential values.  
            temp_chunked = pd.DataFrame()  
  
            for i in range(0, len(temp), 10):  
                temp_chunked = temp_chunked.append(temp.iloc[i:i+10].max(), ignore_index = True)  
  
            labels = [files[:-4] for i in range(len(temp_chunked))] # remove the last 4 characters=".txt" from the filenames  
            actions[files[:-4]] = ind  
  
            temp_chunked["Action"] = labels  
  
            data = pd.concat([data, temp_chunked])
```

29 / 29

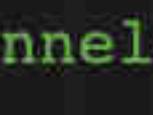
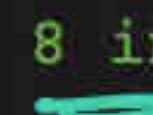
+ Code + Text

✓ RAM Disk



```
[ ] for dirs in data_dirs :  
  
    for files in os.listdir(dirs):  
  
        with open(os.path.join(dirs, files), "r") as f:  
  
            temp = pd.read_csv(f.name,  
                                sep = "\t", ✓  
                                header = None, ✓  
                                names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels  
                                )  
  
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            labels = [files[:-4] for i in range(len(temp_chunked))] # remove the last 4 characters=".txt" from the filena  
            actions[files[:-4]] = ind  
  
            temp_chunked["Action"] = labels  
  
            data = pd.concat([data, temp_chunked])
```

ch1 ch2 --- ch8



Signal-processing

Biomedical-Signal -



SpiKes → Mallet

Max
time
1ms



1μA MS → 1obs
10

1sec → 1000obs

+ Code + Text

✓ RAM Disk



```
[ ] for dirs in data_dirs :  
  
    for files in os.listdir(dirs):  
  
        with open(os.path.join(dirs, files), "r") as f:  
  
            temp = pd.read_csv(f.name,  
                                sep = "\t",  
                                header = None,  
                                names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels  
            )  
  
            # chunking using Max of every 10 sequential values.  
            temp_chunked = pd.DataFrame()  
  
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                temp_chunked = temp_chunked.append(temp.iloc[i:i+10].max(), ignore_index = True)  
  
            labels = [files[:-4] for i in range(len(temp_chunked))] # remove the last 4 characters=".txt" from the filenames  
            actions[files[:-4]] = ind  
  
            temp_chunked["Action"] = labels  
  
            data = pd.concat([data, temp_chunked])
```

max (---) 10-obs
values

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+ Code + Text RAM Disk

```
[ ] names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels
)
# chunking using Max of every 10 sequential values.
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for i in range(0, len(temp), 10):
    temp_chunked = temp_chunked.append(temp.iloc[i:i+10].max(), ignore_index = True)

labels = [files[:-4] for i in range(len(temp_chunked))] # remove the last 4 characters=".txt" from the filena
actions[files[:-4]] = ind

temp_chunked["Action"] = labels

data = pd.concat([data, temp_chunked])

ind+=1

print(actions)
```

{'Frontkicking': 0, 'Slapping': 1, 'Elbowing': 2, 'Pulling': 3, 'Kneeing': 4, 'Hamering': 5, 'Sidekicking': 6, 'Push': 7}

[] data.head()

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+ Code + Text RAM Disk ✓

```
[ ] names = [ "ch" + str(i) for i in range(1, 9) ] # 8 input channels  
)  
  
{x} # chunking using Max of every 10 sequential values.  
temp_chunked = pd.DataFrame()  
  
for i in range(0, len(temp), 10):  
    temp_chunked = temp_chunked.append(temp.iloc[i:i+10].max(), ignore_index = True)  
  
labels = [files[:-4] for i in range(len(temp_chunked))] # remove the last 4 characters=".txt" from the filena  
actions[files[:-4]] = ind  
  
temp_chunked["Action"] = labels  
  
data = pd.concat([data, temp_chunked])  
  
ind+=1  
  
print(actions)
```

<> {'Frontkicking': 0, 'Slapping': 1, 'Elbowing': 2, 'Pulling': 3, 'Kneeing': 4, 'Hamering': 5, 'Sidekicking': 6, 'Push': 7}

[] data.head()

File Edit View Insert Cell Kernel Help

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+ Code + Text RAM Disk

RAM Disk

Update

{x}

temp = pd.read_csv('EMG.csv', sep=',', header=None, names=["ch" + str(i) for i in range(1, 9)]) # 8 input channels

chunking using Max of every 10 sequential values.

temp_chunked = pd.DataFrame()

for i in range(0, len(temp), 10):

 temp_chunked = temp_chunked.append(temp.iloc[i:i+10].max(), ignore_index=True)

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print(actions)

{'Frontkicking': 0, 'Slapping': 1, 'Elbowing': 2, 'Pulling': 3, 'Kneeing': 4, 'Hamerling': 5, 'Sidekicking': 6, 'Push': 7}

+ Code + Text

```
for dirs in data_dirs:
    for files in os.listdir(dirs):
        with open(os.path.join(dirs, files), "r") as f:
            temp = pd.read_csv(f.name,
                                sep = "\t",
                                header = None,
                                names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels
                                )
# chunking using Max of every 10 sequential values.
temp_chunked = pd.DataFrame()
for i in range(0, len(temp), 10):
    temp_chunked = temp_chunked.append(temp.iloc[i:i+10].max(), ignore_index = True)
labels = [files[:-4] for i in range(len(temp_chunked))] # remove the last 4 characters=".txt" from the filenames
actions[files[:-4]] = ind
temp_chunked["Action"] = labels
data = pd.concat([data, temp_chunked])
ind+=1
```

temp_chunked

temp

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+ Code + Text RAM Disk

RAM Disk

Update

Code Editor

Play

Search

{x}

File

temp = pd.read_csv(f.name,
sep = "\t",
header = None,
names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels
)

chunking using Max of every 10 sequential values.
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labels = [files[:-4] for i in range(len(temp_chunked))] # remove the last 4 characters=".txt" from the filenames
actions[files[:-4]] = ind

temp_chunked["Action"] = labels

data = pd.concat([data, temp_chunked])

ind+=1

print(actions)

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+ Code + Text RAM Disk ✓

header = None,
names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels
)

chunking using Max of every 10 sequential values.
temp_chunked = pd.DataFrame()

for i in range(0, len(temp), 10):
 temp_chunked = temp_chunked.append(temp.iloc[i:i+10].max(), ignore_index = True)

 labels = [files[:-4] for i in range(len(temp_chunked))] # remove the last 4 characters=".txt" from the filenames
 actions[files[:-4]] = ind

 temp_chunked["Action"] = labels

 data = pd.concat([data, temp_chunked])

 ind+=1

print(actions)

{'Frontkicking': 0, 'Slapping': 1, 'Elbowing': 2, 'Pulling': 3, 'Kneeing': 4, 'Hamerling': 5, 'Sidekicking': 6, 'Push': 7}

[] data.head()

40 / 40

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+ Code + Text RAM Disk

Q {x} D

import os
import matplotlib.pyplot as plt
import numpy as np
import pandas as pd
import sklearn

actions = {}

data_dirs = ['./EMG Physical Action Data Set/sub1/Aggressive/txt',
 './EMG Physical Action Data Set/sub1/Normal/txt']

ind = 0
data = pd.DataFrame()

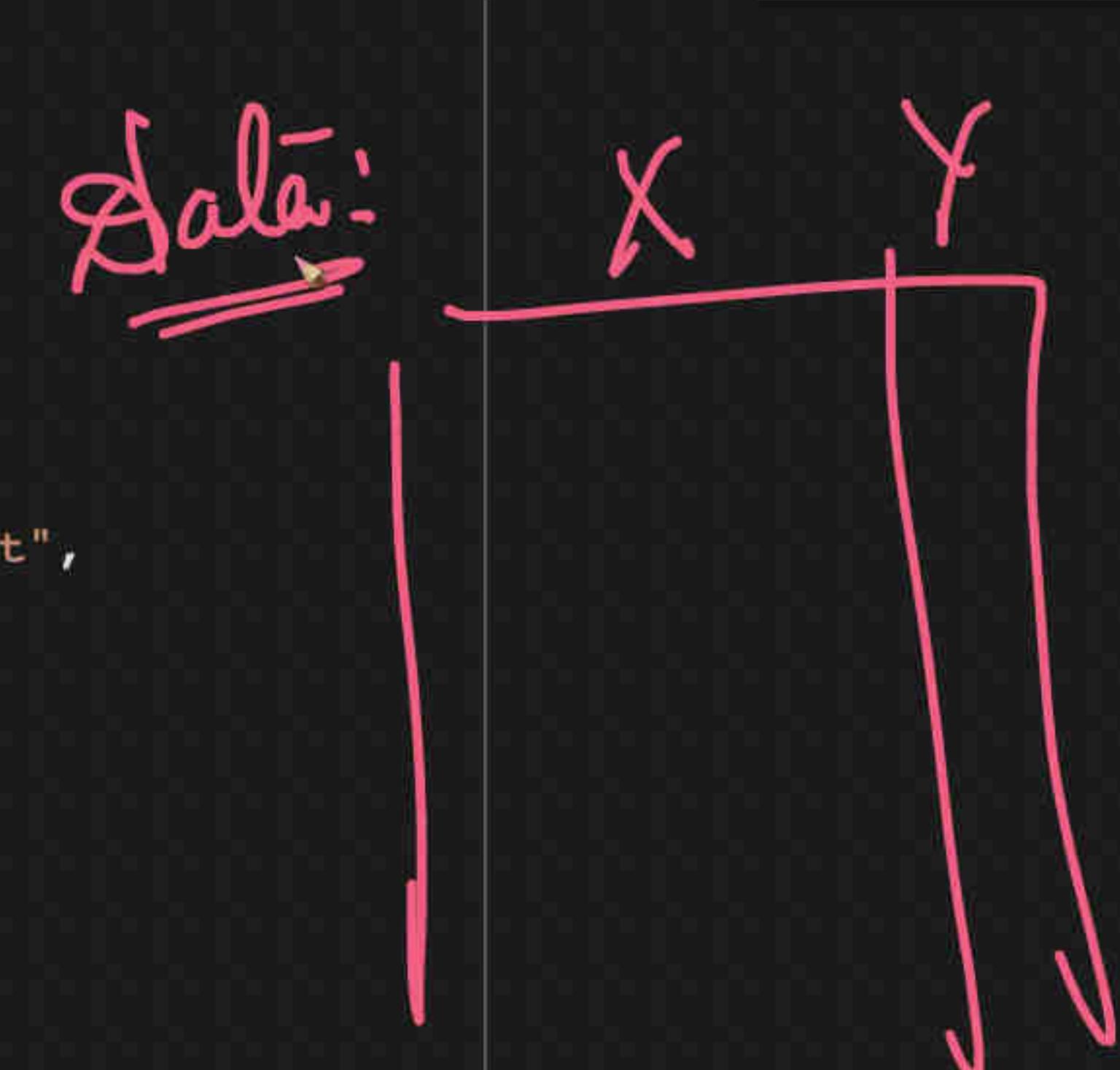
for dirs in data_dirs :

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 with open(os.path.join(dirs, files), "r") as f:

 temp = pd.read_csv(f.name,
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 header = None,
 names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels

Datal: X Y



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+ Code + Text RAM Disk

actions = {}

data_dirs = ["./EMG Physical Action Data Set/sub1/Aggressive/txt",
 "./EMG Physical Action Data Set/sub1/Normal/txt"]

ind = 0

data = pd.DataFrame()

for dirs in data_dirs :
 for files in os.listdir(dirs):
 with open(os.path.join(dirs, files), "r") as f:
 temp = pd.read_csv(f.name,
 sep = "\t",
 header = None,
 names = ["ch" + str(i) for i in range(1, 9)] # 8 input channels
)

chunking using Max of every 10 sequential values.
temp_chunked = pd.DataFrame()

for i in range(0, len(temp), 10):
 temp_chunked = temp_chunked.append(temp.iloc[i:i+10].max(), ignore_index = True)

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+ Code + Text RAM Disk

RAM Disk

Update

Code Editor:

```
for i in range(0, len(temp), 10):
    temp_chunked = temp_chunked.append(temp.iloc[i:i+10].max(), ignore_index = True)

{x}
labels = [files[:-4] for i in range(len(temp_chunked))] # remove the last 4 characters=".txt" from the filenames
actions[files[:-4]] = ind

temp_chunked["Action"] = labels

data = pd.concat([data, temp_chunked])

ind+=1

print(actions)
```

Output:

```
{'Frontkicking': 0, 'Slapping': 1, 'Elbowing': 2, 'Pulling': 3, 'Kneeing': 4, 'Hamerling': 5, 'Sidekicking': 6, 'Push': 7}
```

[] data.head()

	ch1	ch2	ch3	ch4	ch5	ch6	ch7	ch8	Action
0	328.0	433.0	533.0	210.0	3918.0	961.0	-3193.0	4000.0	Frontkicking
1	577.0	309.0	1550.0	-21.0	-4000.0	707.0	2297.0	3719.0	Frontkicking

Toolbar:

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+ Code + Text RAM Disk

RAM Disk

Update :

for i in range(0, len(temp), 10):
 temp_chunked = temp_chunked.append(temp.iloc[i:i+10].max(), ignore_index = True)

{x}
labels = [files[:-4] for i in range(len(temp_chunked))] # remove the last 4 characters=".txt" from the filenames
actions[files[:-4]] = ind

temp_chunked["Action"] = labels

data = pd.concat([data, temp_chunked])

ind+=1

print(actions)

{'Frontkicking': 0, 'Slapping': 1, 'Elbowing': 2, 'Pulling': 3, 'Kneeing': 4, 'Hamerling': 5, 'Sidekicking': 6, 'Push': 7}

[] data.head()

	ch1	ch2	ch3	ch4	ch5	ch6	ch7	ch8	Action
0	328.0	433.0	533.0	210.0	3918.0	961.0	-3193.0	4000.0	Frontkicking
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+ Code + Text RAM Disk

{'Frontkicking': 0, 'Slapping': 1, 'Elbowing': 2, 'Pulling': 3, 'Kneeing': 4, 'Hamerling': 5}

[] data.head()

1 NS → { 0 328.0 433.0 533.0 210.0 3918.0 961.0 -3193.0 4000.0 Frontkicking 1 577.0 309.0 1550.0 -21.0 -4000.0 707.0 2297.0 3719.0 Frontkicking 2 712.0 160.0 632.0 149.0 -3231.0 1515.0 3294.0 4000.0 Frontkicking 3 234.0 68.0 125.0 402.0 2972.0 2428.0 3009.0 1895.0 Frontkicking 4 2471.0 118.0 -263.0 -94.0 -4000.0 4000.0 -3592.0 613.0 Frontkicking

[] data.info()

```
<class 'pandas.core.frame.DataFrame'>
Int64Index: 19711 entries, 0 to 999
Data columns (total 9 columns):
 #   Column   Non-Null Count   Dtype  
--- 
 0   ch1      19711 non-null   float64
 1   ch2      19711 non-null   float64
```

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+ Code + Text RAM Disk

{'Frontkicking': 0, 'Slapping': 1, 'Elbowing': 2, 'Pulling': 3, 'Kneeing': 4, 'Hamerling': 5}

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3	234.0	68.0	125.0	402.0	2972.0	2428.0	3009.0	1895.0	Frontkicking
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```

averaging

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The main content shows a series of five vertically stacked EMG signal traces over time. From top to bottom, they are labeled: Raw (green), Filtration (red), Rectification (blue), Smoothing (purple), and RSM (root mean square) (black). Each trace is shown for three time intervals: 10 s, 30 s, and 60 s. A legend on the left identifies the colors: green for raw, red for filtration, blue for rectification, purple for smoothing, and black for RSM. Below the traces is a descriptive text about the recommended signal processing steps. To the right, there is a sidebar with an advertisement for JMP software.

Raw

Filtration

Rectification

Smoothing

RSM (root mean square)

10 s 30 s 60 s

EMG signal process recommended. Green: The raw signal, no treatment was applied until this moment; Red: Filtered signal, a limit was created for the signal, excluding everything out of it; Blue: Rectified signal, all negative values were transformed in positive ones and added; Purple: the smoothed signal, a linear enveloped was created and the extreme parts of the signal was excluded; Black: The RMS values after all the treatments.

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4 2471.0 118.0 -263.0 -94.0 -4000.0 4000.0 -3592.0 613.0 Frontkicking

✓ RAM Disk

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 3   ch4      19711 non-null    float64
 4   ch5      19711 non-null    float64
 5   ch6      19711 non-null    float64
 6   ch7      19711 non-null    float64
 7   ch8      19711 non-null    float64
 8   Action    19711 non-null    object 
dtypes: float64(8), object(1)
memory usage: 1.5+ MB
```

~20k रुपये

all 4 patients

```
[ ] data[ "Action" ].value_counts()
```

Seating 1000
Jumping 1000
Waving 1000

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[] `data["Action"].value_counts()`

{x} 

Seating	1000
Jumping	1000
Waving	1000
Kneeing	1000
Hamerling	1000
Clapping	1000
Headering	1000
Walking	1000
Running	997
Bowing	983
Sidekicking	983
Frontkicking	982
Slapping	979
Elbowing	978
Hugging	976
Standing	973
Pushing	968
Pulling	966
Punching	964
Handshaking	962
Name: Action, dtype: int64	

20-classes well-balanced

[] `Y = data["Action"]`

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+ Code + Text

RAM Disk

Handshaking 962
Name: Action, dtype: int64

{x} [] Y = data['Action']
X = data.drop(columns = ["Action"]) 

[] # Label encoding
Y = Y.map(actions)
Y.head()
print(Y.value_counts())

19	1000
11	1000
18	1000
4	1000
5	1000
14	1000
9	1000
12	1000
13	997
15	983
6	983
0	982
1	979
2	978

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RAM Disk

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19	1000
11	1000
18	1000
4	1000
5	1000
14	1000
9	1000
12	1000
13	997
15	983
6	983
0	982
1	979
2	978

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Handshaking 962
Name: Action, dtype: int64

{x} [] Y = data["Action"]
X = data.drop(columns = ["Action"])

[] # Label encoding ✓
Y = Y.map(actions)
Y.head()
print(Y.value_counts())

	Value
19	1000
11	1000
18	1000
4	1000
5	1000
14	1000
9	1000
12	1000
13	997
15	983
6	983
0	982
1	979
2	978

RAM Disk

Update

Code Text

Search

File

Actions

Help

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+ Code + Text

RAM Disk

[] 1 979
2 978
10 976
16 973
 $\{x\}$ 7 968
3 966
8 964
17 962
Name: Action, dtype: int64

Domain specific pre-processing
X = abs(X)
X.head()

	ch1	ch2	ch3	ch4	ch5	ch6	ch7	ch8
0	328.0	433.0	533.0	210.0	3918.0	961.0	3193.0	4000.0
1	577.0	309.0	1550.0	21.0	4000.0	707.0	2297.0	3719.0
2	712.0	160.0	632.0	149.0	3231.0	1515.0	3294.0	4000.0
3	234.0	68.0	125.0	402.0	2972.0	2428.0	3009.0	1895.0
4	2471.0	118.0	263.0	94.0	4000.0	4000.0	3592.0	613.0

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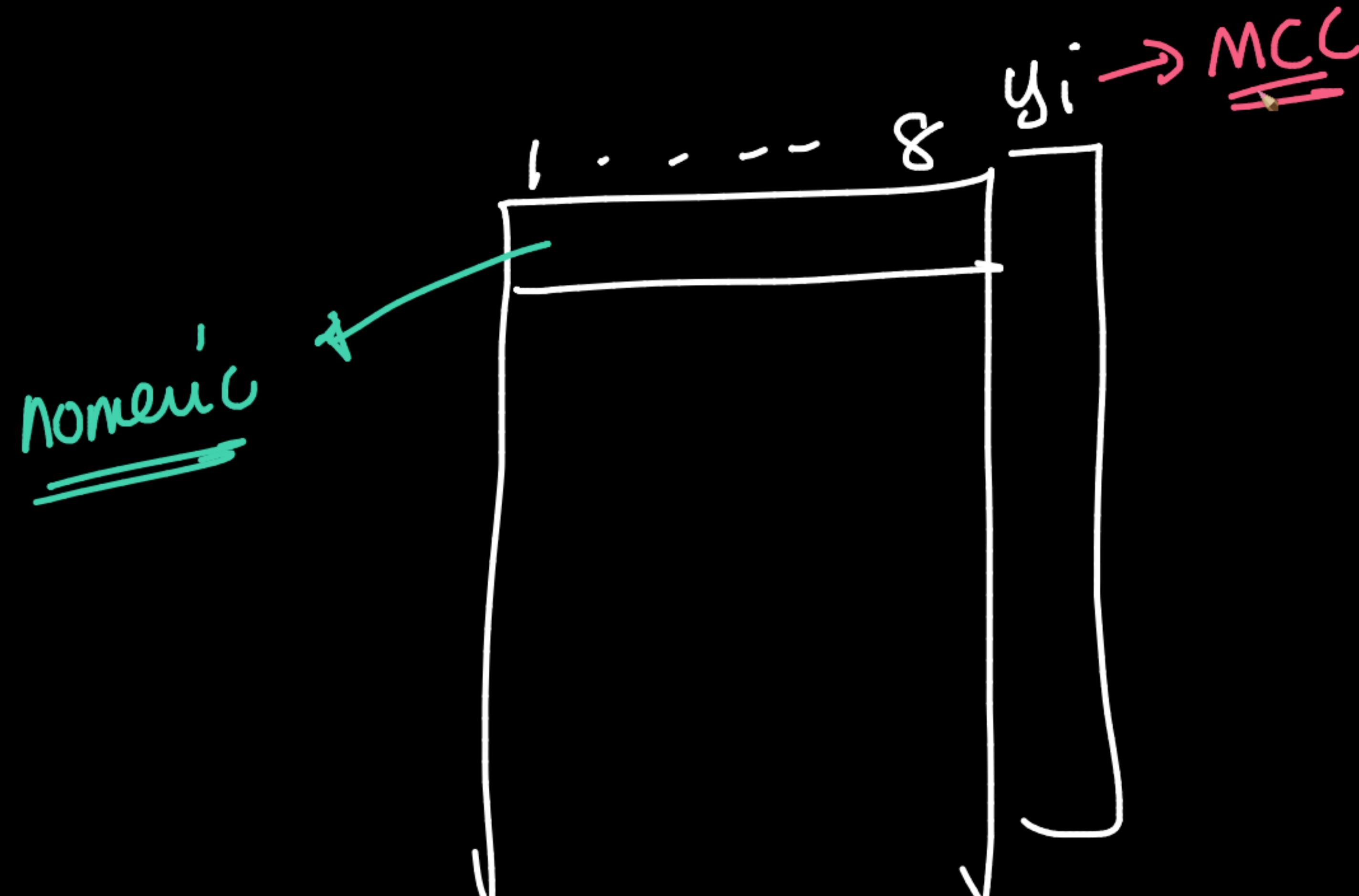
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METHODOLOGY FOR WLCSP
SIDEWALL CRACK DUE TO
CUSTOMER COMPLAINT
LM Shong, NXP Semiconductors
15 MAY 2012
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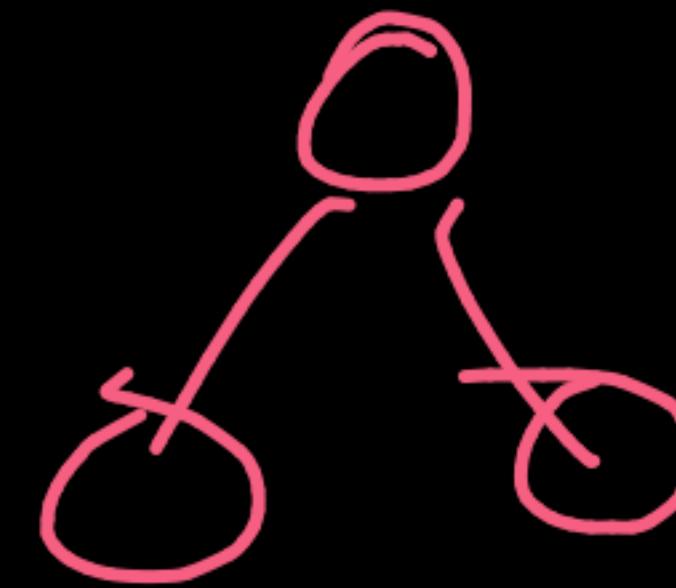
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✗ scaling (?)



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+ Code + Text RAM Disk

[] # Train, test split
no CV?
{x} from sklearn.model_selection import train_test_split

X = np.array(X.values.tolist())
Y = np.array(Y.values.tolist())
go. X_train, X_test, Y_train, Y_test = train_test_split(X, Y, test_size = 0.2, shuffle = True)
print(f"Sizes of the sets created are:\nTraining set:{X_train.shape[0]}\nTest set:{X_test.shape[0]}")

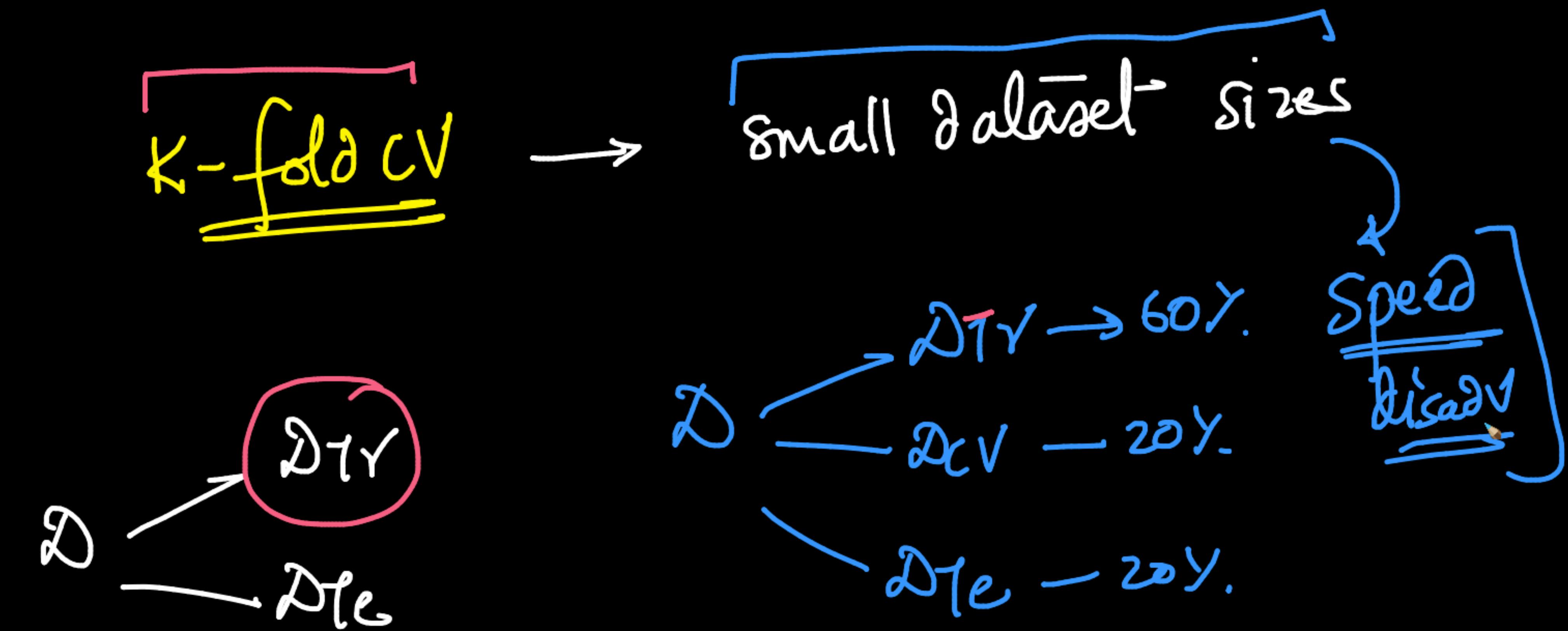
Sizes of the sets created are:

Training set:15768

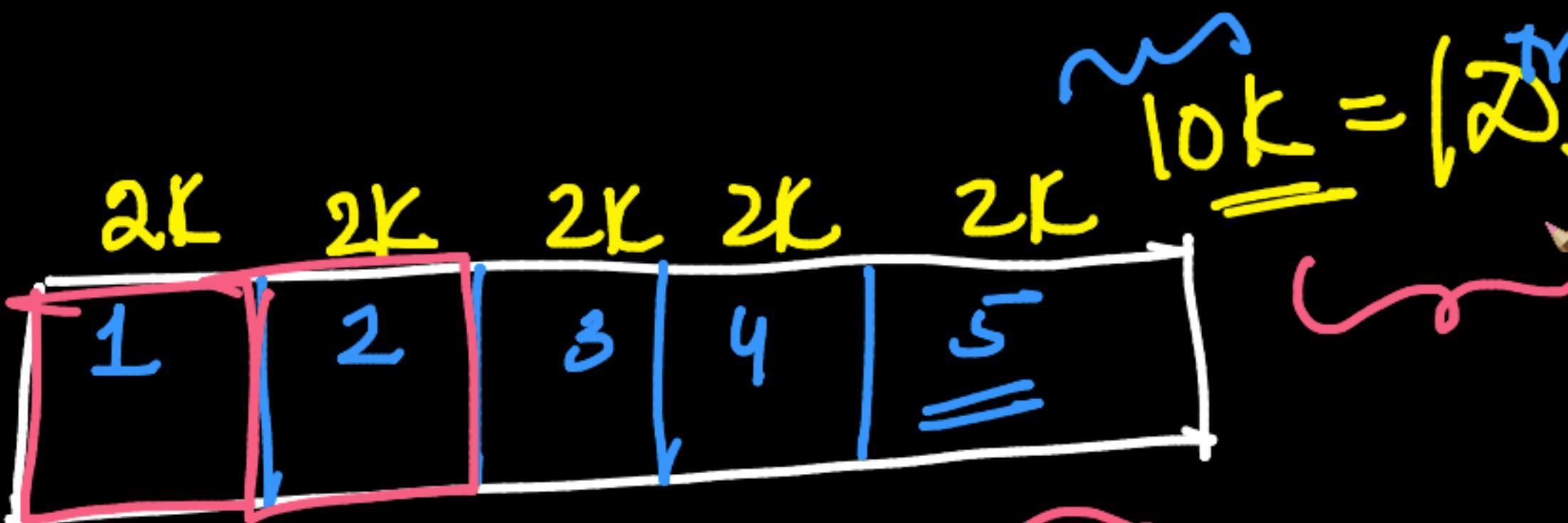
Test set:3943

Simple DT
5-fold CV
Grid Search for best hyper-param
from sklearn.tree import DecisionTreeClassifier as DTC
from sklearn import tree
from sklearn.model_selection import GridSearchCV

params = {



DT: Depth



$d=4$

i1: ✓ ✓ ✓ ✓ CV $\rightarrow CV_1$

i2: ✓ ✓ ✓ ✓ CV $\rightarrow CV_2$

i3: ✓ ✓ CV ✓ ✓ $\rightarrow CV_3$

i4: ✓ CV ✓ ✓ ✓ $\rightarrow CV_4$

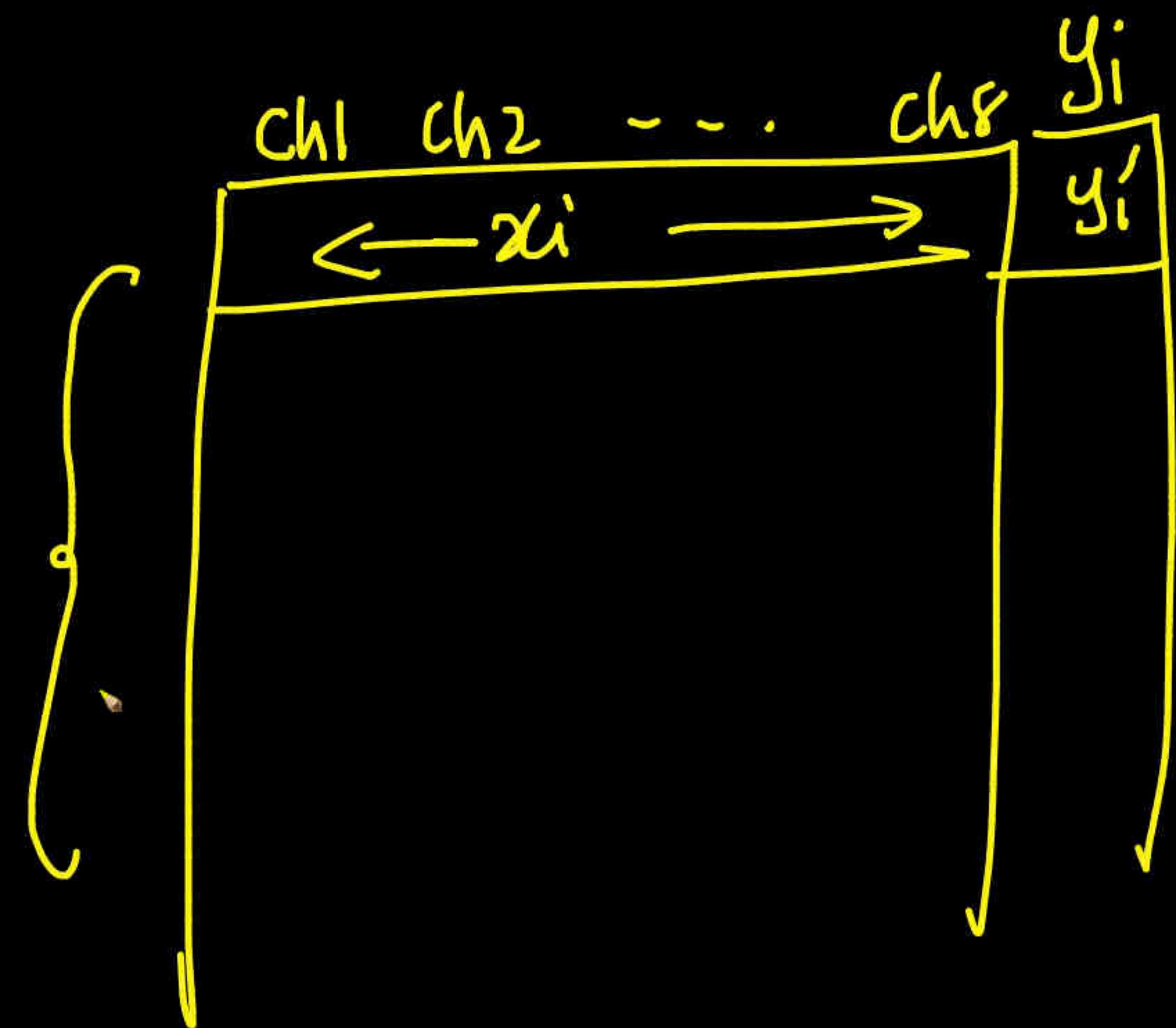
i5: CV ✓ ✓ ✓ $\rightarrow CV_5$

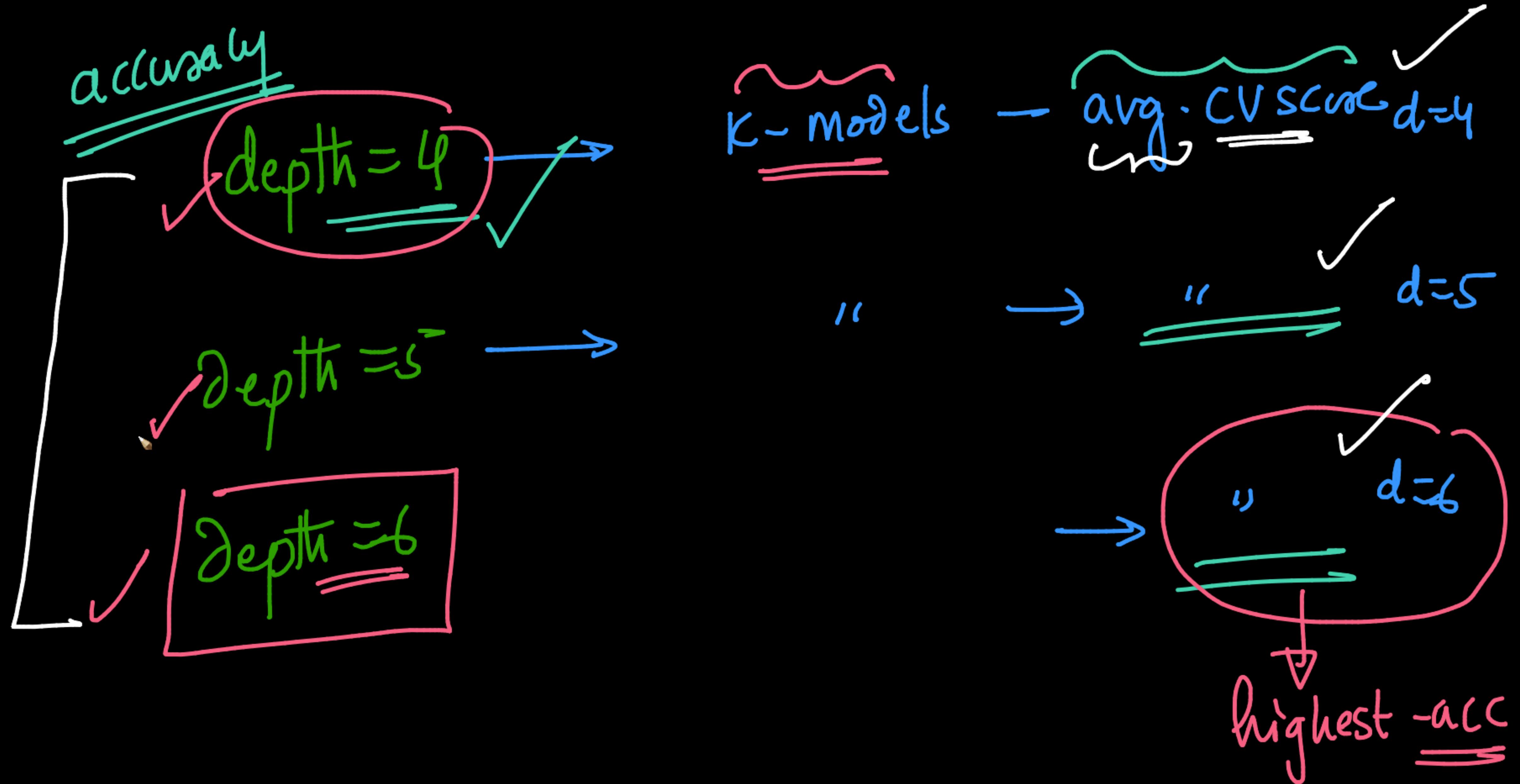
$K=5$ - fold CV

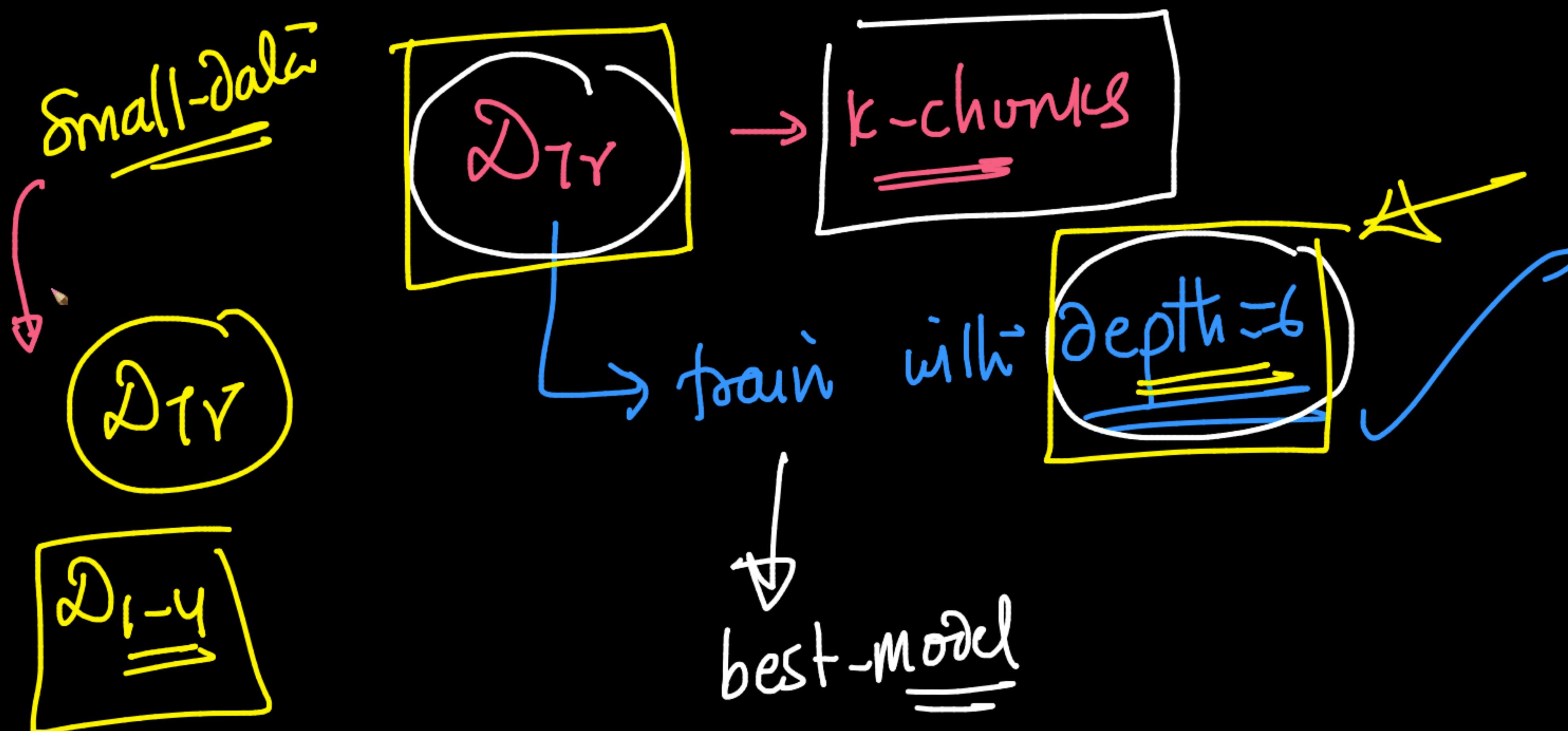
Depth = 4

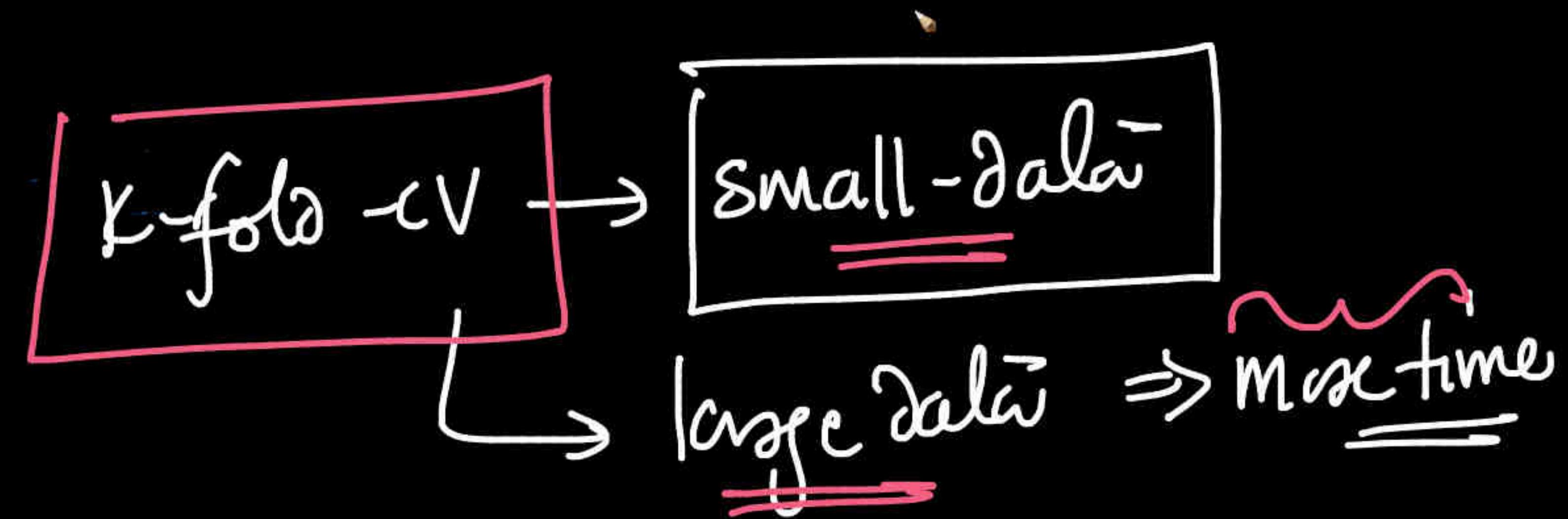
CV-Score

average









+ Code + Text

✓ RAM Disk

```
[ ] # Simple DT ✓  
# 5-fold CV  
# Grid Search for best hyper-param  
from sklearn.tree import DecisionTreeClassifier as DTC  
from sklearn import tree  
from sklearn.model_selection import GridSearchCV  
  
params = {  
    "max_depth" : [3, 5, 7],  
    "max_leaf_nodes" : [15, 20, 25]  
}  
  
modell = DTC()  
clf = GridSearchCV(modell, params, scoring = "accuracy", cv=5)  
  
clf.fit(X_train, Y_train)  
  
<>  
GridSearchCV(cv=5, estimator=DecisionTreeClassifier(),  
            param_grid={'max_depth': [3, 5, 7],  
                        'max_leaf_nodes': [15, 20, 25]},  
            scoring='accuracy')
```



+ Code + Text RAM Disk

RAM Disk

```
[ ] # Simple DT  
# 5-fold CV  
  
{x} # Grid Search for best hyper-param  
from sklearn.tree import DecisionTreeClassifier as DTC  
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K ↑ time ↑

+ Code + Text RAM Disk

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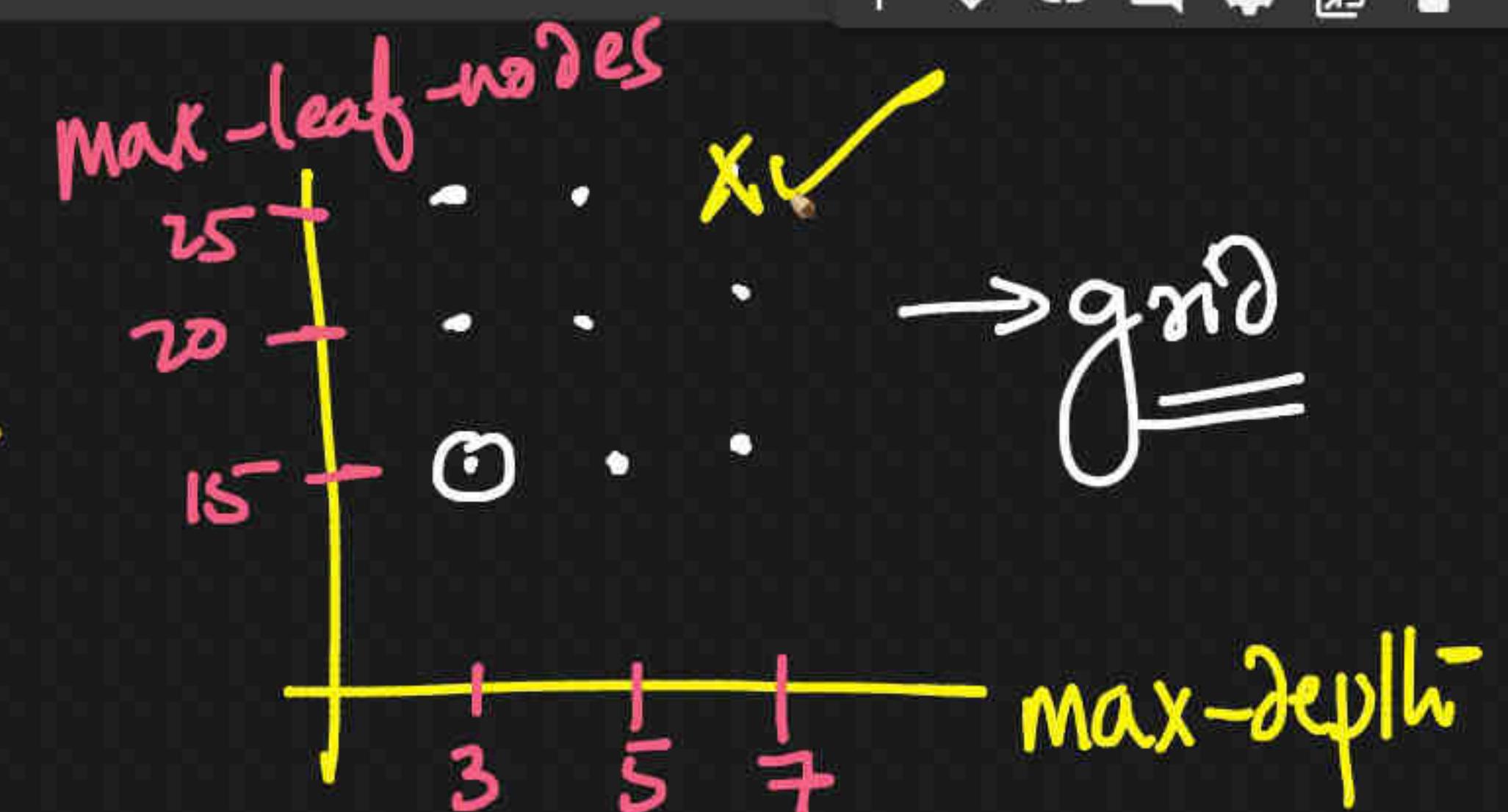
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```

```
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             param_grid={'max_depth': [3, 5, 7],
                         'max_leaf_nodes': [15, 20, 25]},
             scoring='accuracy')
```



colab.research.google.com/drive/1oOTcIDDRBX1mB3EZTsoYhv4S6Pk7TbjN#scrollTo=jlcjrE8dB1Gy

+ Code + Text

RAM Disk

A set of small, light-gray navigation icons located at the bottom of the page. From left to right, they include: an upward arrow, a downward arrow, a link icon (a circle with a line), a message icon (a speech bubble), a gear icon (a settings wheel), a refresh/circular arrow icon, a trash can icon, and three vertical dots indicating more options.

```
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}

modell = DTC()
clf = GridSearchCV(modell, params, scoring = "accuracy")

clf.fit(X train, Y train)
```

balanced

```
GridSearchCV(cv=5, estimator=DecisionTreeClassifier(),
             param_grid={'max_depth': [3, 5, 7],
                         'max_leaf_nodes': [15, 20, 25]},
             scoring='accuracy')
```

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```
[ ] # Simple DT
# 5-fold CV
{x} # Grid Search for best hyper-param
from sklearn.tree import DecisionTreeClassifier as DTC
from sklearn import tree
from sklearn.model_selection import GridSearchCV

params = {
    "max_depth" : [3, 5, 7],
    "max_leaf_nodes" : [15, 20, 25]
}

modell = DTC()
clf = GridSearchCV(modell, params, scoring = "accuracy", cv=5)
clf.fit(X_train, Y_train)

GridSearchCV(cv=5, estimator=DecisionTreeClassifier(),
            param_grid={'max_depth': [3, 5, 7],
                        'max_leaf_nodes': [15, 20, 25]},
            scoring='accuracy')
```

```
[ ] # Simple DT
# 5-fold CV
# Grid Search for best hyper-param
from sklearn.tree import DecisionTreeClassifier as DTC
from sklearn import tree
from sklearn.model_selection import GridSearchCV

params = {
    "max_depth" : [3, 5, 7],
    "max_leaf_nodes" : [15, 20, 25]
}

modell = DTC()
clf = GridSearchCV(modell, params, scoring = "accuracy")  
cv=5)  
clf.fit(X_train, Y_train)

GridSearchCV(cv=5, estimator=DecisionTreeClassifier(),
            param_grid={'max_depth': [3, 5, 7],
                        'max_leaf_nodes': [15, 20, 25]},
            scoring='accuracy')
```

Annotations:

- A handwritten note above the code block states: "9 combinations" with a bracket under the first two parameters and an arrow pointing to "5 fold CV".
- A circled "5" is next to the "cv=5" parameter in the GridSearchCV call.

+ Code + Tex

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```
[ ] GridSearchCV(cv=5, estimator=DecisionTreeClassifier(),
    param_grid={'max_depth': [3, 5, 7],
                'max_leaf_nodes': [15, 20, 25]}
    scoring='accuracy')
```

```
res = clf.cv_results_
for i in range(len(res["params"])):
    print(f"Parameters:{res['params'][i]} Mean score: {res['mean test score'][i]} Rank: {res['rank test score'][i]}")
```

```
Parameters: {'max_depth': 3, 'max_leaf_nodes': 15} Mean_score: 0.3192542617764362 Rank: 7
Parameters: {'max_depth': 3, 'max_leaf_nodes': 20} Mean_score: 0.3192542617764362 Rank: 7
Parameters: {'max_depth': 3, 'max_leaf_nodes': 25} Mean_score: 0.3192542617764362 Rank: 7
Parameters: {'max_depth': 5, 'max_leaf_nodes': 15} Mean_score: 0.4054414462899422 Rank: 5
Parameters: {'max_depth': 5, 'max_leaf_nodes': 20} Mean_score: 0.4360091072889887 Rank: 3
Parameters: {'max_depth': 5, 'max_leaf_nodes': 25} Mean_score: 0.44482467905574924 Rank: 2
Parameters: {'max_depth': 7, 'max_leaf_nodes': 15} Mean_score: 0.4054414462899422 Rank: 5
Parameters: {'max_depth': 7, 'max_leaf_nodes': 20} Mean_score: 0.42288167140996247 Rank: 4
Parameters: {'max_depth': 7, 'max_leaf_nodes': 25} Mean_score: 0.44552240712059515 Rank: 1
```

```
[ ] print(clf.best_estimator_)
```

```
DecisionTreeClassifier(max_depth=7, max_leaf_nodes=25)
```

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```
for i in range(len(res["params"])):
    print(f"Parameters:{res['params'][i]} Mean_score: {res['mean_test_score'][i]} Rank: {res['rank_test_score'][i]}")
```

{x}

Parameters:{'max_depth': 3, 'max_leaf_nodes': 15} Mean_score: 0.3192542617764362 Rank: 7
Parameters:{'max_depth': 3, 'max_leaf_nodes': 20} Mean_score: 0.3192542617764362 Rank: 7
Parameters:{'max_depth': 3, 'max_leaf_nodes': 25} Mean_score: 0.3192542617764362 Rank: 7
Parameters:{'max_depth': 5, 'max_leaf_nodes': 15} Mean_score: 0.4054414462899422 Rank: 5
Parameters:{'max_depth': 5, 'max_leaf_nodes': 20} Mean_score: 0.4360091072889887 Rank: 3
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Parameters:{'max_depth': 7, 'max_leaf_nodes': 20} Mean_score: 0.42288167140996247 Rank: 4
Parameters:{'max_depth': 7, 'max_leaf_nodes': 25} Mean_score: 0.44552240712059515 Rank: 1

```
[ ] print(clf.best_estimator_)
```

DecisionTreeClassifier(max_depth=7, max_leaf_nodes=25)

```
[ ] # Learning Curves
from sklearn.model_selection import learning_curve
```

```
<> def plot_learning_curve(estimator, X, Y, title):
```

```
train_sizes, train_scores, test_scores, _, _ = learning_curve(estimator,
```

x, 72/72

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param_grid={'max_depth': [3, 5, 7],
 'max_leaf_nodes': [15, 20, 25]},
scoring='accuracy')

{x} [] res = clf.cv_results_

[] for i in range(len(res["params"])):
 print(f"Parameters:{res['params'][i]} Mean_score: {res['mean_test_score'][i]} Rank: {res['rank_test_score'][i]}")

Parameters:{'max_depth': 3, 'max_leaf_nodes': 15} Mean_score: 0.3192542617764362 Rank: 7
Parameters:{'max_depth': 3, 'max_leaf_nodes': 20} Mean_score: 0.3192542617764362 Rank: 7
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Parameters:{'max_depth': 5, 'max_leaf_nodes': 25} Mean_score: 0.44482467905574924 Rank: 2
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Parameters:{'max_depth': 7, 'max_leaf_nodes': 25} Mean_score: 0.44552240712059515 Rank: 1

[] print(clf.best_estimator_)

<> DecisionTreeClassifier(max_depth=7, max_leaf_nodes=25)

[] # Learning Curves
from sklearn.model_selection import learning_curve



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```
# Simple DT
# 5-fold CV
# Grid Search for best hyper-param
from sklearn.tree import DecisionTreeClassifier as DTC
from sklearn import tree
from sklearn.model_selection import GridSearchCV

params = {
    "max_depth" : [3, 5, 7],
    "max_leaf_nodes" : [15, 20, 25]
}

modell = DTC()
clf = GridSearchCV(modell, params, scoring = "accuracy")

clf.fit(X train, Y train)
```

`GridSearchCV`
} → q combinations → 5-fold CV
= = mean-err

< >

2

```
NameError                                 Traceback (most recent call last)
<ipython-input-2-9851e8f8f4ca> in <module>()
      14 clf = GridSearchCV(model1, params, scoring = "accuracy", cv=5)
      15
----> 16 clf.fit(X_train, Y_train)
```

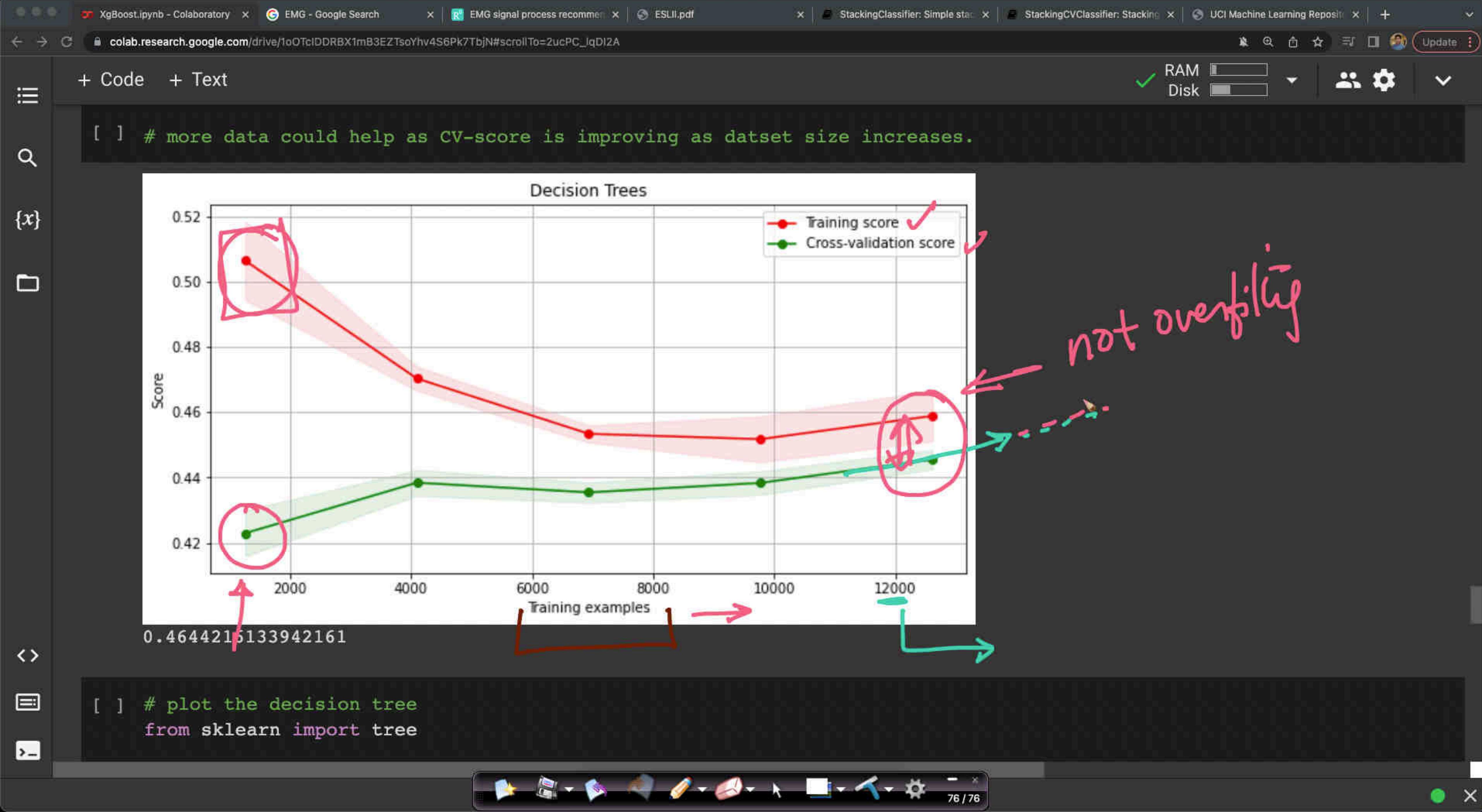
+ Code + Text

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[] # more data could help as CV-score is improving as dataset size increases.

0.4644216133942161
[] # plot the decision tree
from sklearn import tree

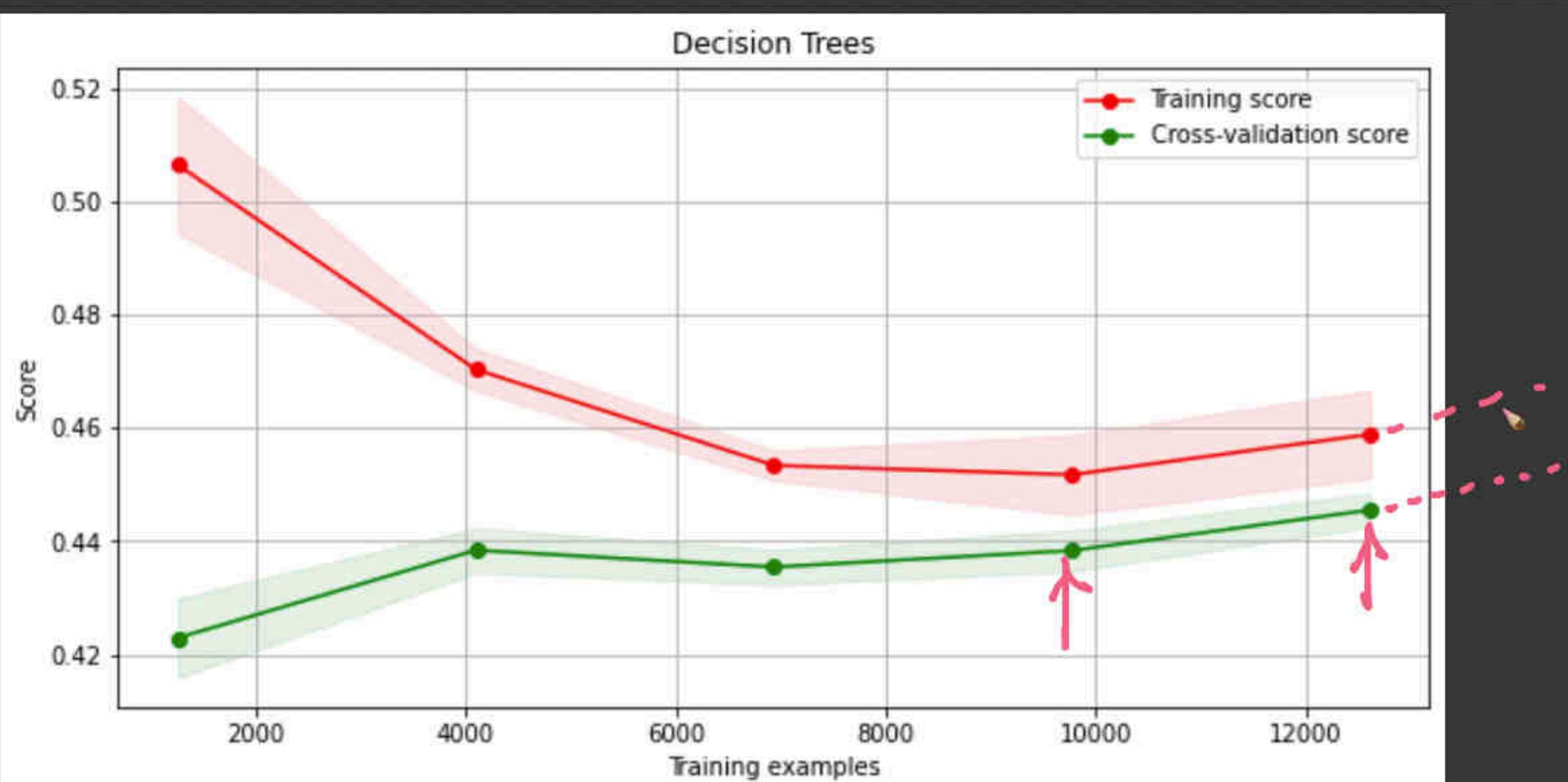


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[] # more data could help as CV-score is improving as dataset size increases.

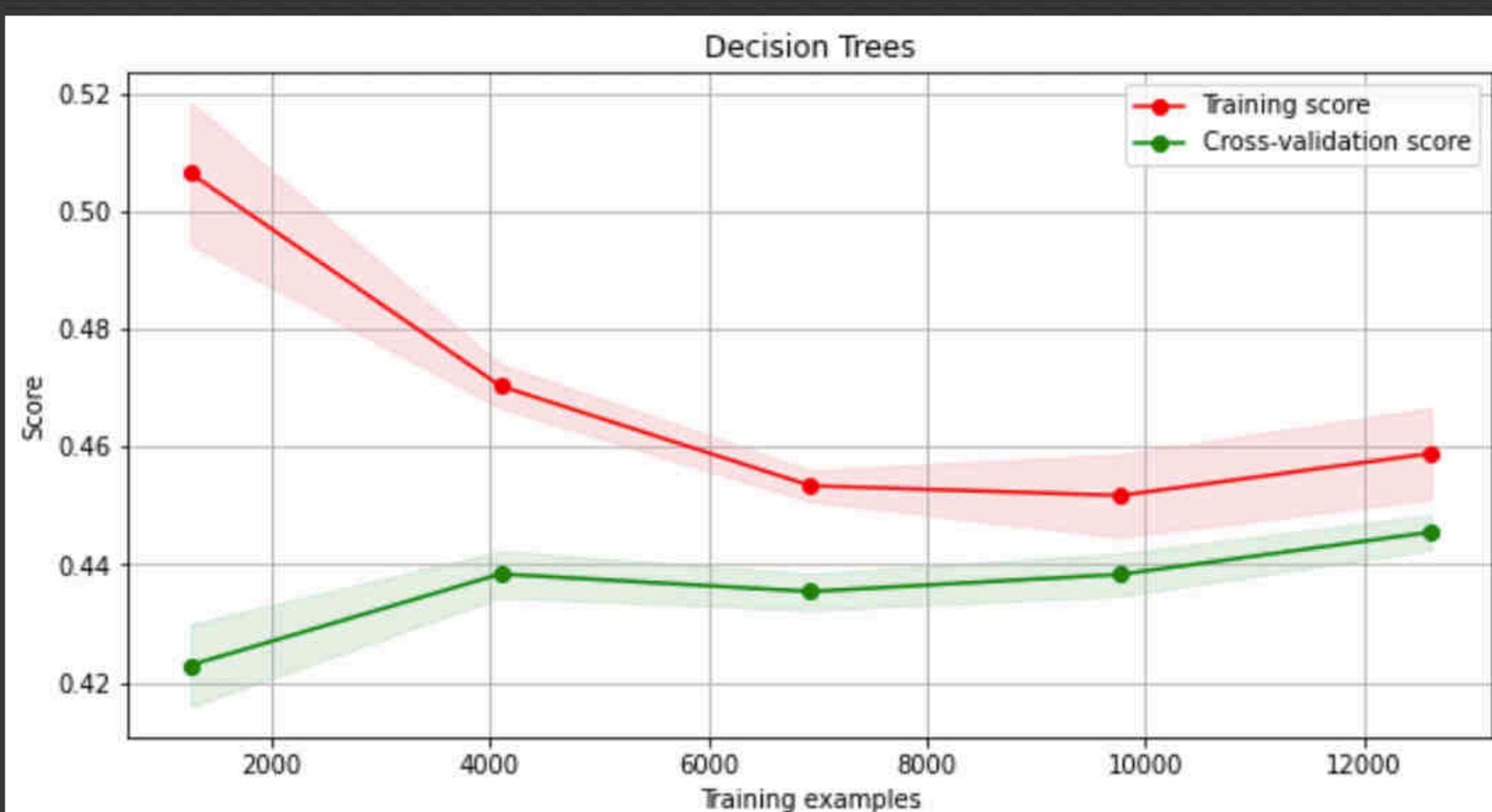


0.4644216133942161

[] # plot the decision tree
from sklearn import tree

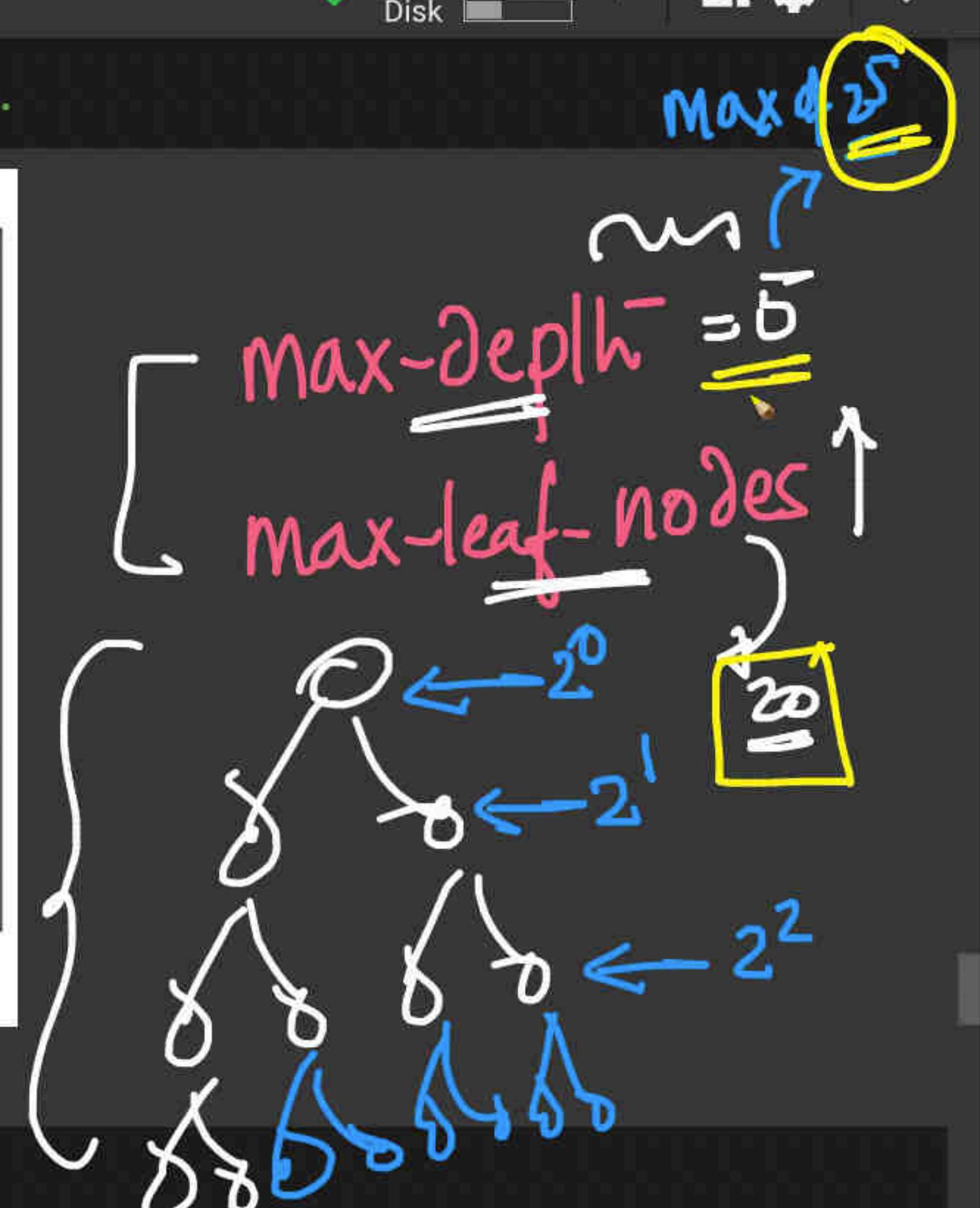
+ Code + Text

```
[ ] # more data could help as CV-score is improving as dataset size increases.
```



```
0.4644216133942161
```

```
[ ] # plot the decision tree  
from sklearn import tree
```



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```
# Learning Curves
from sklearn.model_selection import learning_curve

def plot_learning_curve(estimator, X, Y, title):

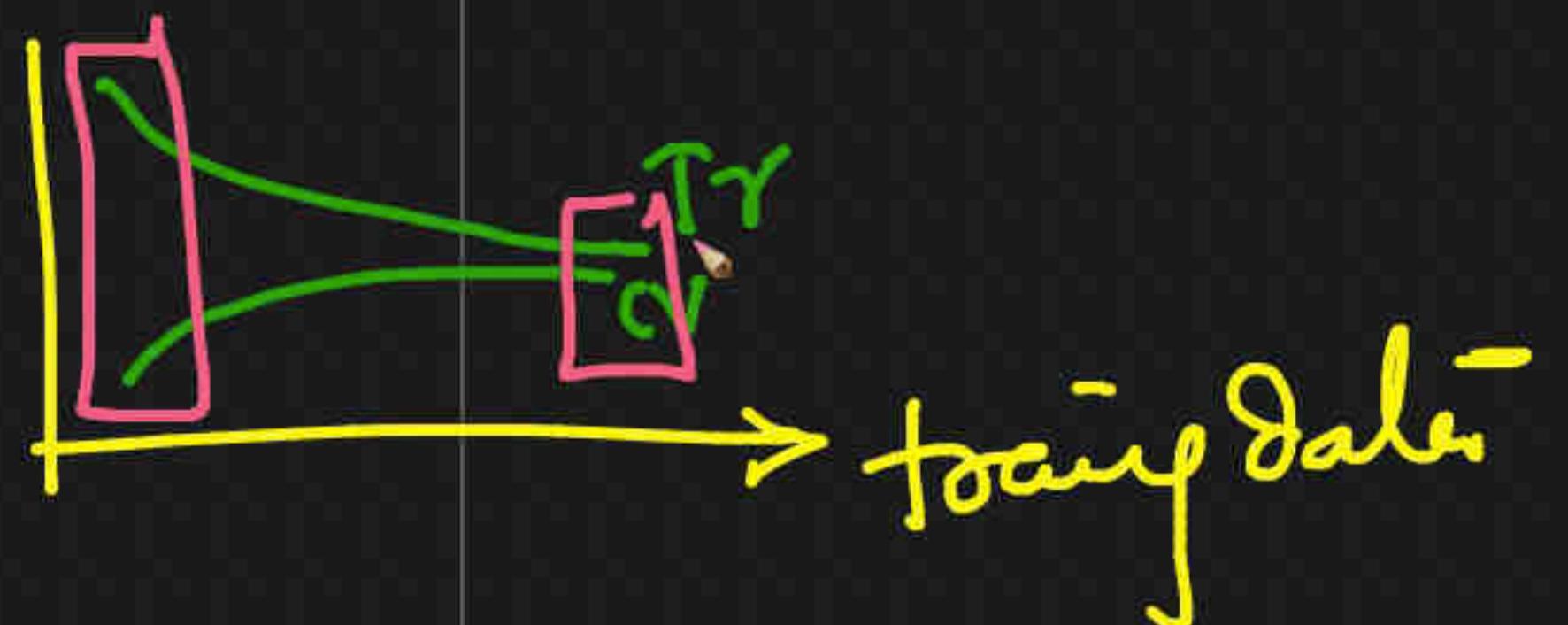
    train_sizes, train_scores, test_scores, _, _ = learning_curve(estimator,
                                                                X,
                                                                Y,
                                                                return_times=True
                                                                )

    fig, axes = plt.subplots(1, 1, figsize = (10, 5))

    axes.set_title(title)
    axes.plot
    axes.set_xlabel("Training examples")
    axes.set_ylabel("Score")

    train_scores_mean = np.mean(train_scores, axis=1)
    train_scores_std = np.std(train_scores, axis=1)
    test_scores_mean = np.mean(test_scores, axis=1)
    test_scores_std = np.std(test_scores, axis=1)


```



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Learning Curves

```
from sklearn.model_selection import learning_curve

def plot_learning_curve(estimator, X, Y, title):
    train_sizes, train_scores, test_scores, _, _ = learning_curve(estimator,
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                                                                Y,
                                                                return_times=True
                                                                )

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    train_scores_std = np.std(train_scores, axis=1)
    test_scores_mean = np.mean(test_scores, axis=1)
    test_scores_std = np.std(test_scores, axis=1)
```

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RAM Disk ✓

Parameters: {'max_depth': 7, 'max_leaf_nodes': 25} Mean_score: 0.44552240712059515 Rank: 1

[] print(clf.best_estimator_)

{x} DecisionTreeClassifier(max_depth=7, max_leaf_nodes=25)

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from sklearn.model_selection import learning_curve

def plot_learning_curve(estimator, X, Y, title):

 train_sizes, train_scores, test_scores, _, _ = learning_curve(estimator,
 X,
 Y,
 return_times=True
)

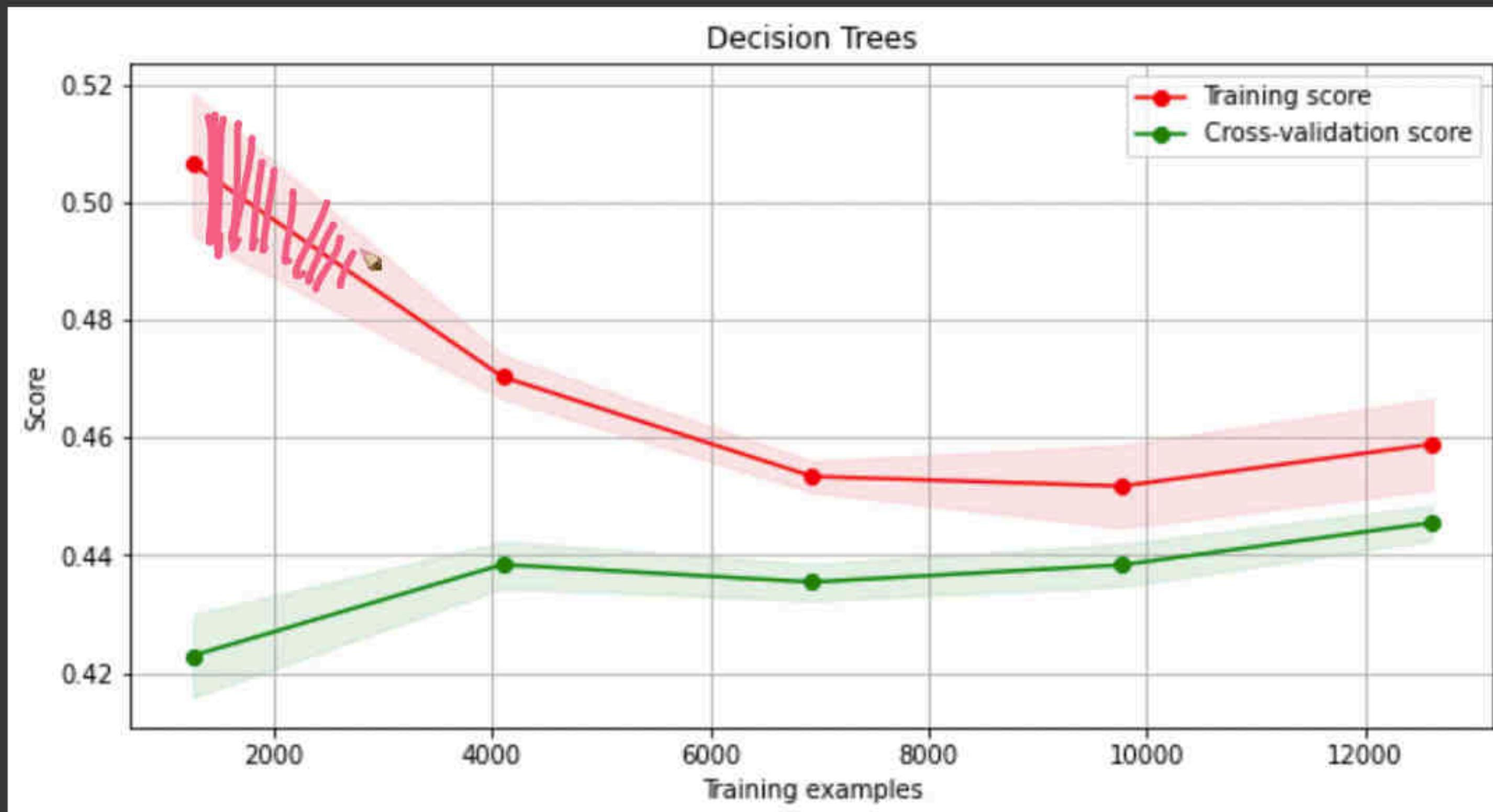
 fig, axes = plt.subplots(1, 1, figsize = (10, 5))

 axes.set_title(title)
 axes.plot
 axes.set_xlabel("Training examples")
 axes.set_ylabel("Score")

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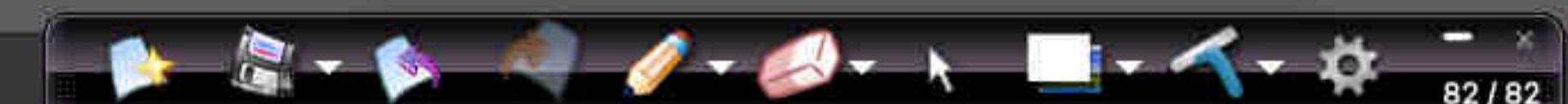
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more data could help as CV-score is improving as dataset size increases.



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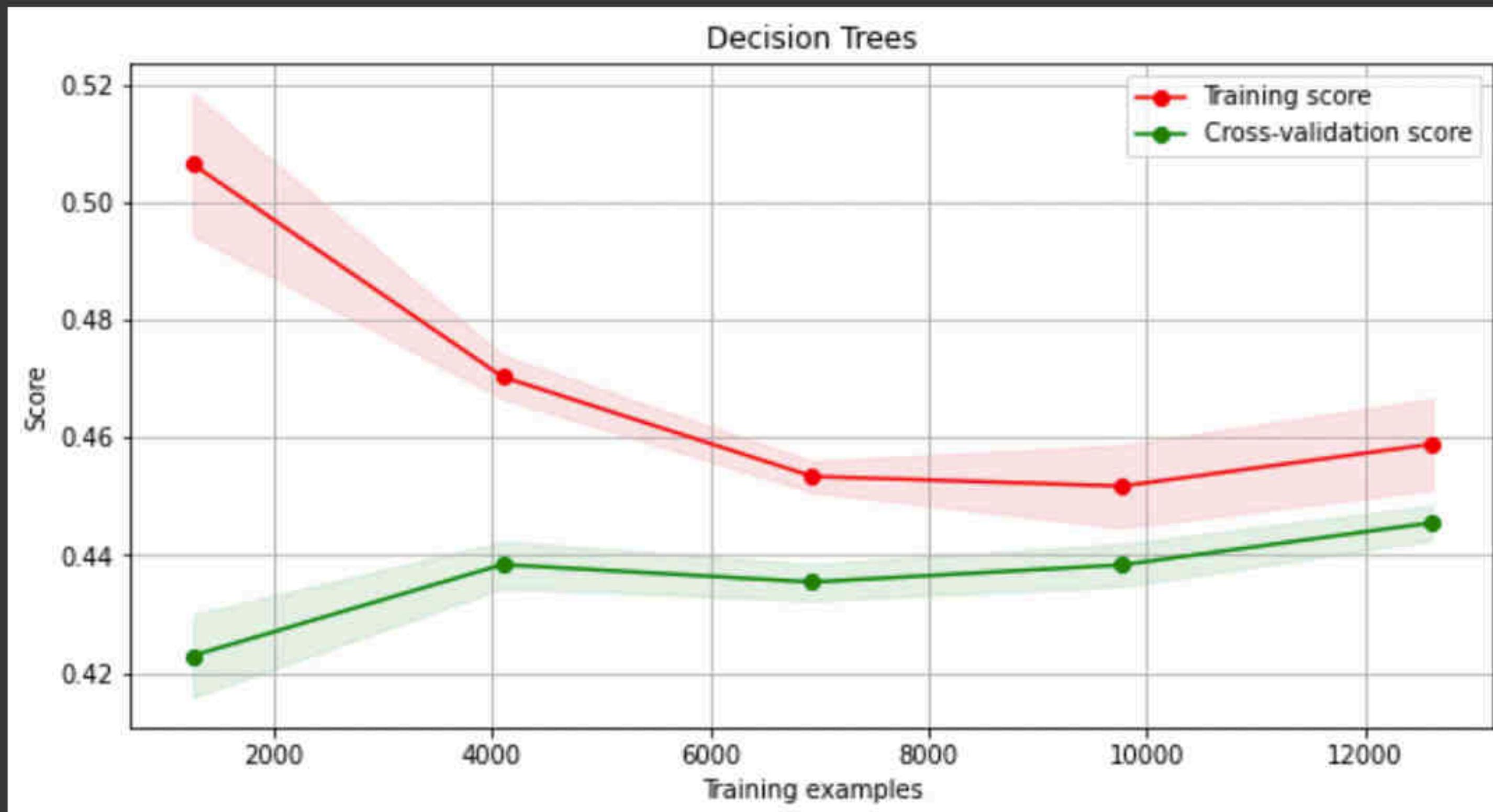
[] # plot the decision tree
from sklearn import tree



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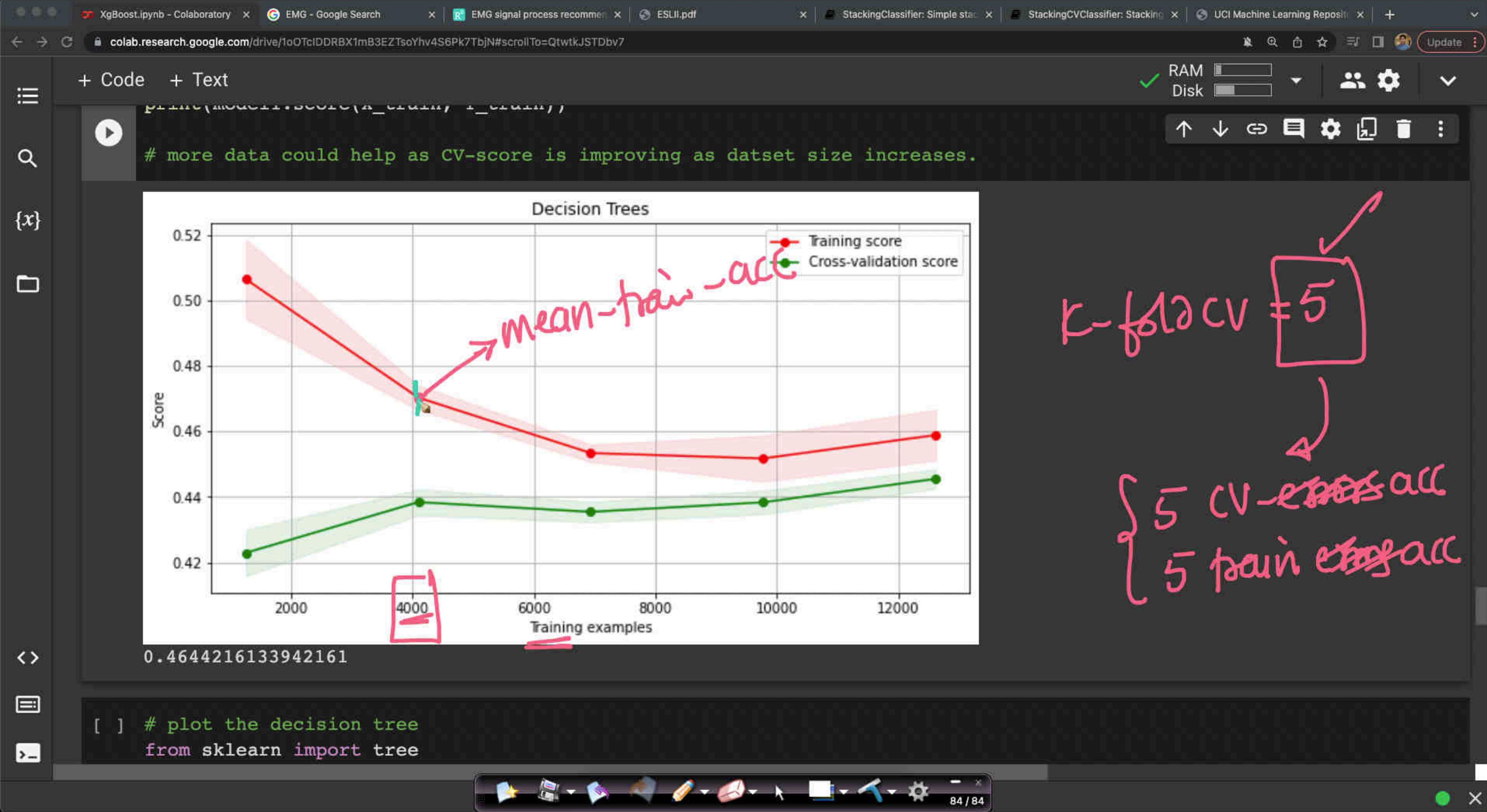
more data could help as CV-score is improving as dataset size increases.



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[] # plot the decision tree
from sklearn import tree

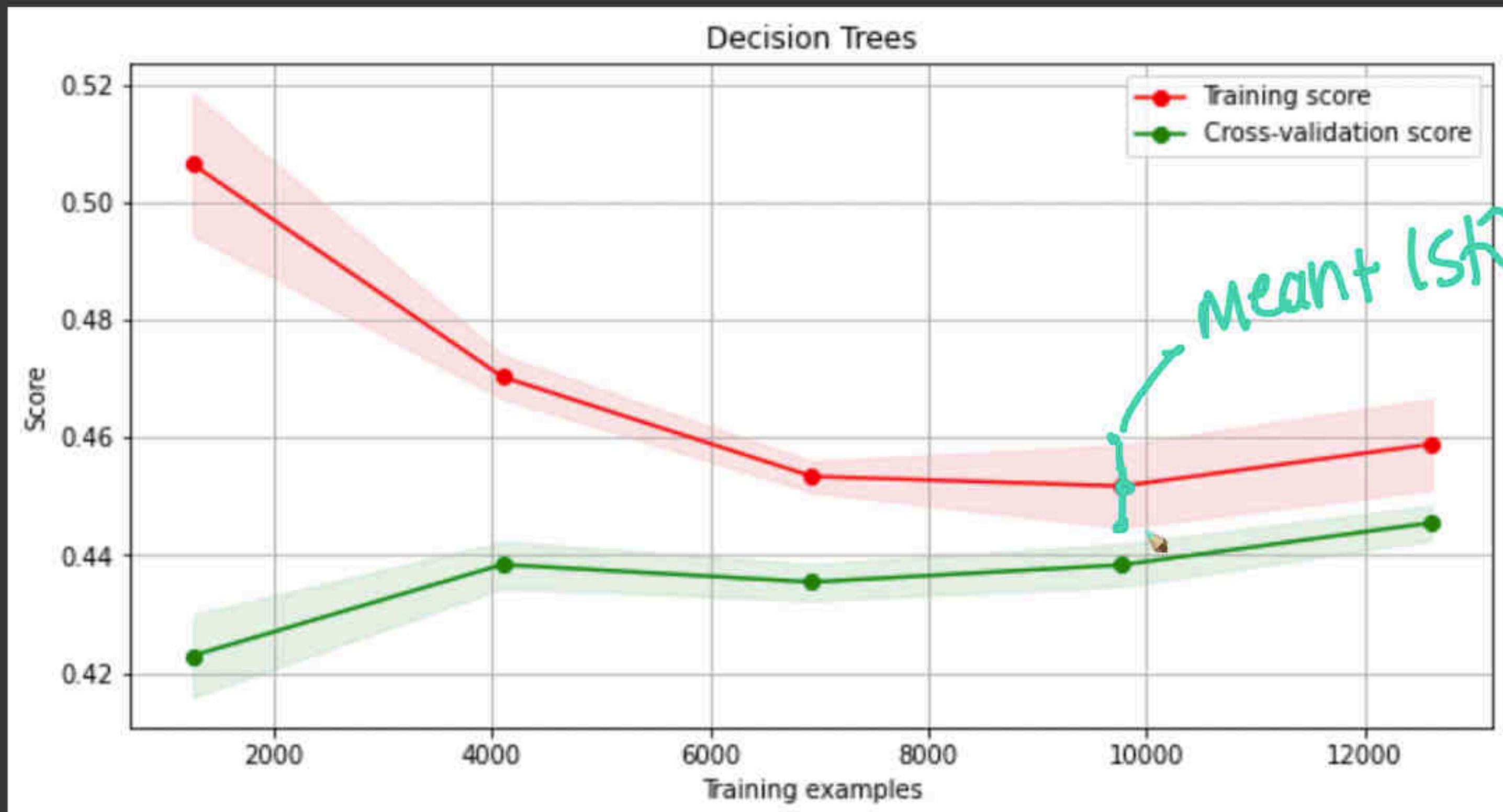




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more data could help as CV-score is improving as dataset size increases.



0.4644216133942161

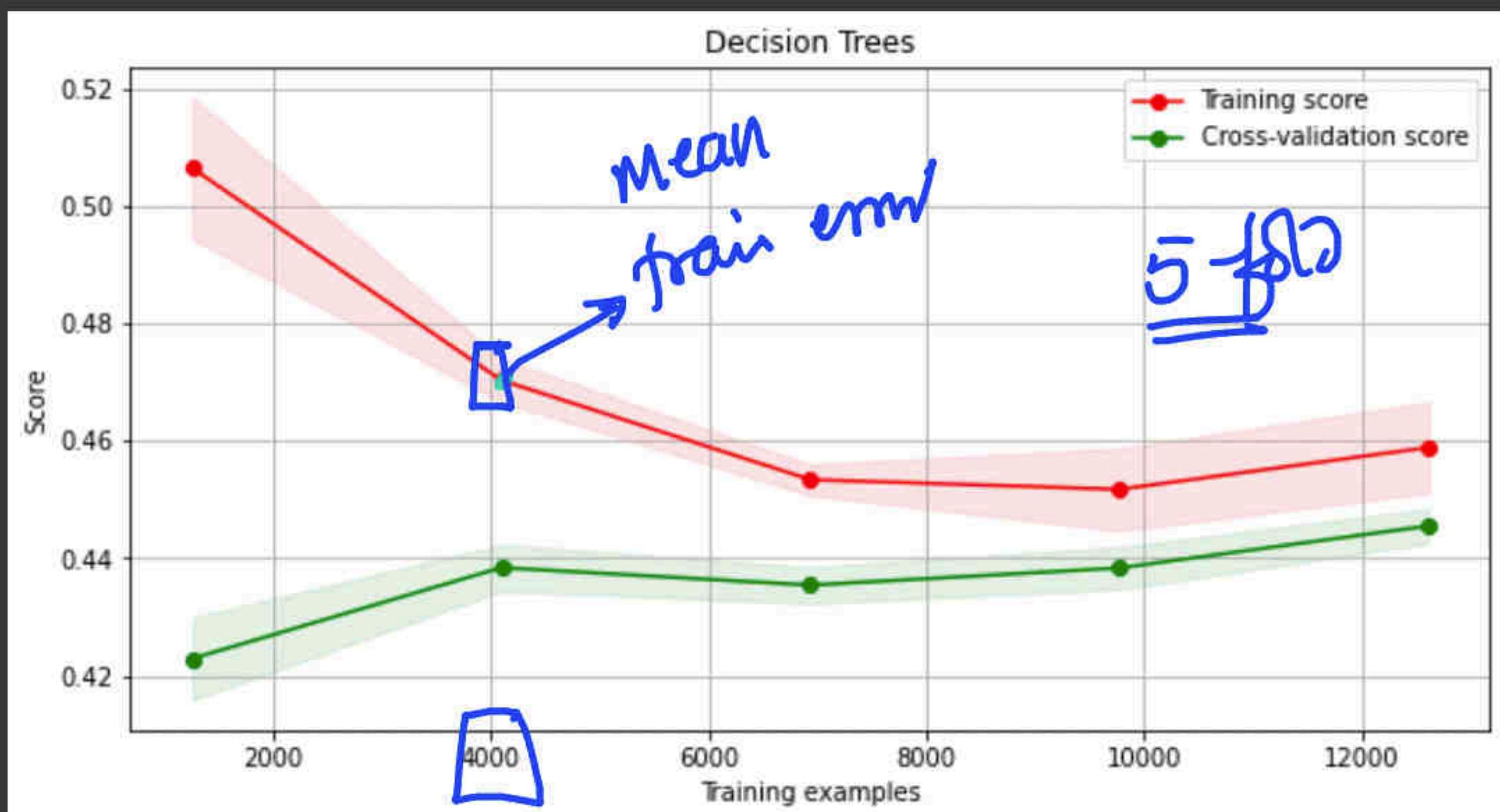
[] # plot the decision tree
from sklearn import tree

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RAM Disk



```
# more data could help as CV-score is improving as dataset size increases.
```



```
0.4644216133942161
```

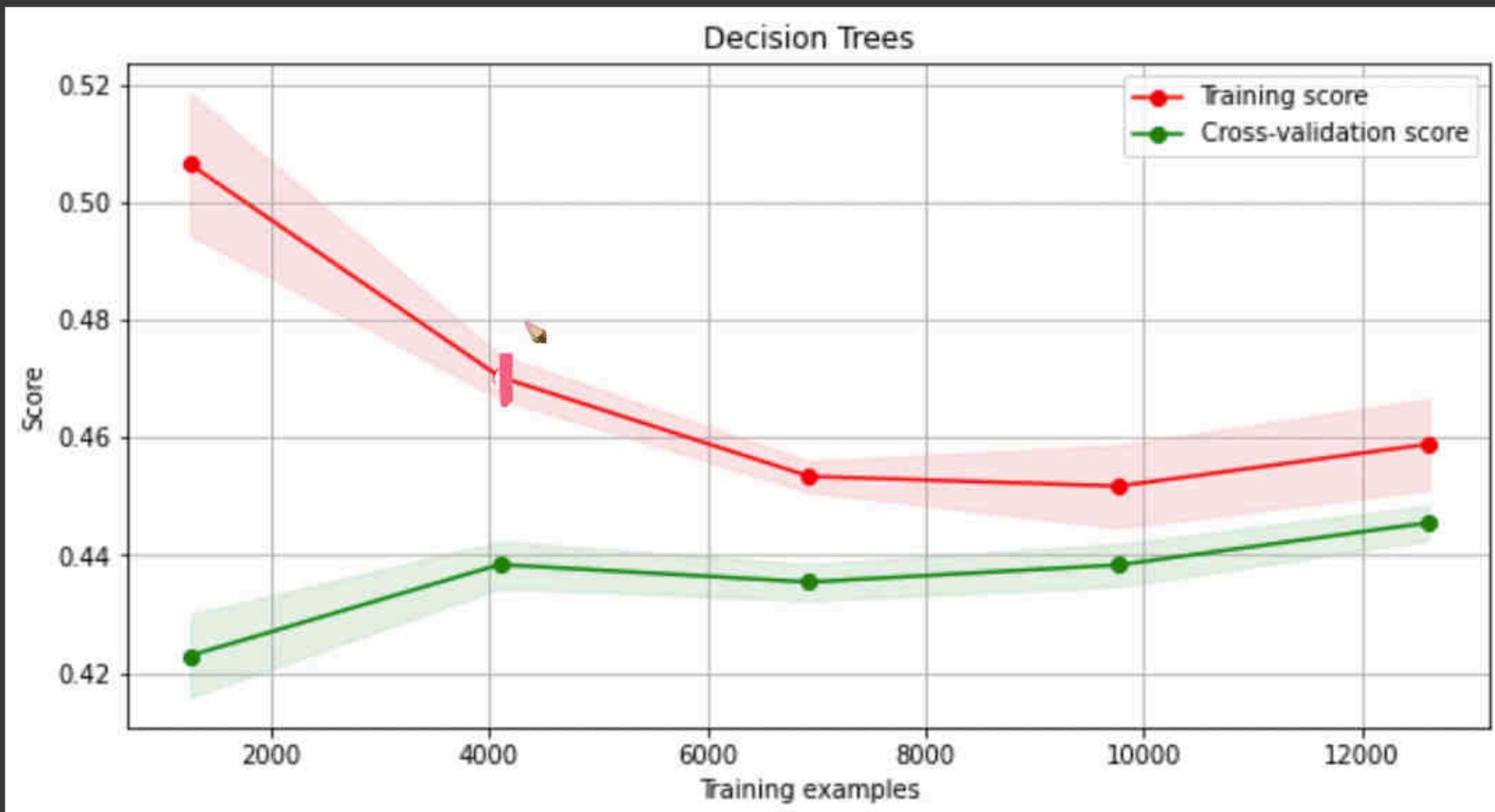
```
[ ] # plot the decision tree  
from sklearn import tree
```



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more data could help as CV-score is improving as dataset size increases.



0.4644216133942161

[] # plot the decision tree
from sklearn import tree

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```
[ ] from sklearn.model_selection import learning_curve

def plot_learning_curve(estimator, X, Y, title):
    train_sizes, train_scores, test_scores, _, _ = learning_curve(estimator,
        X,
        Y,
        return_times=True
    )

    fig, axes = plt.subplots(1, 1, figsize = (10, 5))

    axes.set_title(title)
    axes.plot
    axes.set_xlabel("Training examples")
    axes.set_ylabel("Score")

    train_scores_mean = np.mean(train_scores, axis=1)
    train_scores_std = np.std(train_scores, axis=1)
    test_scores_mean = np.mean(test_scores, axis=1)
    test_scores_std = np.std(test_scores, axis=1)

    # Plot learning curve
    axes.grid()
```

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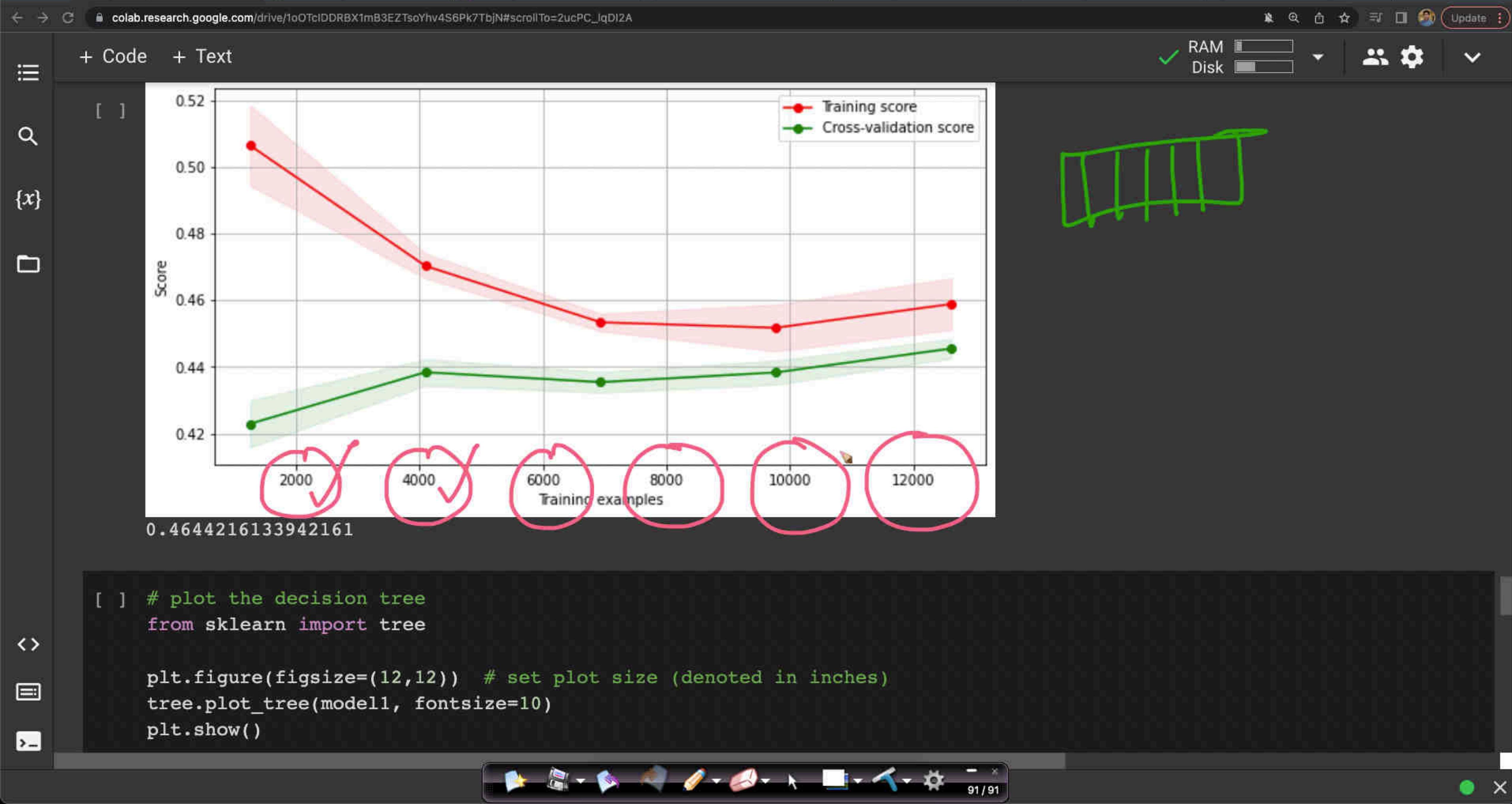


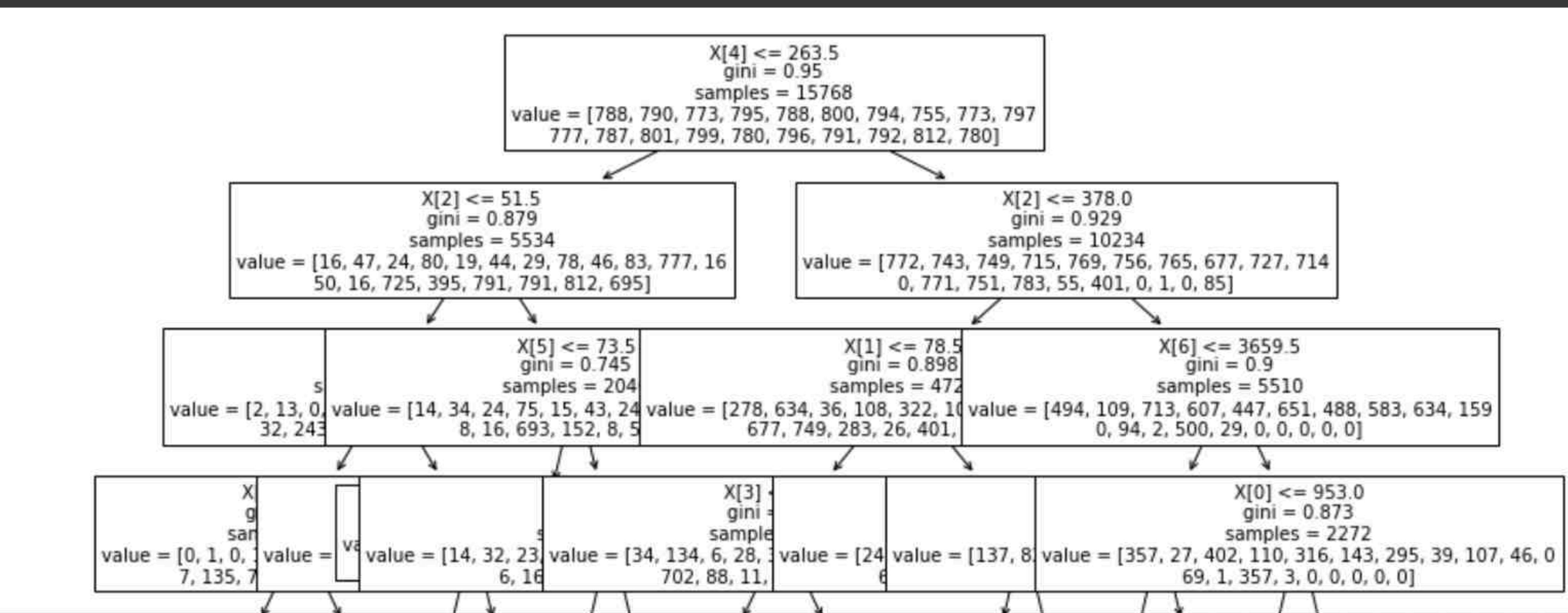
```
axes.set_ylabel( 'score' )  
[ ]  
✓ train_scores_mean = np.mean(train_scores, axis=1)  
✓ train_scores_std = np.std(train_scores, axis=1)  
test_scores_mean = np.mean(test_scores, axis=1)  
test_scores_std = np.std(test_scores, axis=1)  
  
# Plot learning curve  
axes.grid()  
axes.fill_between(  
    train_sizes,  
    train_scores_mean - train_scores_std,  
    train_scores_mean + train_scores_std,  
    alpha=0.1,  
    color="r",  
)  
axes.fill_between(  
    train_sizes,  
    test_scores_mean - test_scores_std,  
    test_scores_mean + test_scores_std,  
    alpha=0.1,  
    color="g",  
)  
axes.plot(  
    train_sizes, train_scores_mean, "o-", color="r", label="Training score"
```

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```
axes.set_ylabel( 'score' )  
[ ]  
  
train_scores_mean = np.mean(train_scores, axis=1)  
train_scores_std = np.std(train_scores, axis=1)  
test_scores_mean = np.mean(test_scores, axis=1)  
test_scores_std = np.std(test_scores, axis=1)  
  
# Plot learning curve  
axes.grid()  
axes.fill_between(  
    train_sizes,  
    ✓train_scores_mean - train_scores_std, ✓  
    train_scores_mean + train_scores_std,  
    alpha=0.1,  
    color="r",  
)  
axes.fill_between(  
    train_sizes,  
    test_scores_mean - test_scores_std,  
    test_scores_mean + test_scores_std,  
    alpha=0.1,  
    color="g",  
)  
axes.plot(  
    train_sizes, train_scores_mean, "o-", color="r", label="Training score"
```







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EMG - Google Search

EMG signal process recom

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x | StackingClassifier-Simple

StackingCVClassifier: StackingCVClassifier

IJCAI Machine Learning Report

Understanding the decision x

10

Code # Text

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```
# Xgboost
```

```
from xgboost import XGBClassifier
from sklearn.model_selection import RandomizedSearchCV, GridSearchCV
from sklearn.model_selection import StratifiedKFold
import datetime as dt

params = {
    'learning_rate': [0.1, 0.5, 0.8],
    'subsample': [0.6, 0.8, 1.0],
    'colsample_bytree': [0.6, 0.8, 1.0],
    'max_depth': [3, 4, 5]
}

xgb = XGBClassifier(n_estimators=100, objective='multi:softmax', n
```

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[]

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value	gini = 0.277 samples = 39 value = [0, 1, 0, 0, 0, 0, 0, 0, 0, 2, 0, 1, 33, 0, 0, 2, 0, 0, 0, 0]
-------	---

{x}

Xgboost

```
from xgboost import XGBClassifier
from sklearn.model_selection import RandomizedSearchCV, GridSearchCV
from sklearn.model_selection import StratifiedKFold

import datetime as dt

params = {
    'learning_rate': [0.1, 0.5, 0.8],
    'subsample': [0.6, 0.8, 1.0],
    'colsample_bytree': [0.6, 0.8, 1.0],
    'max_depth': [3, 4, 5]
}
xgb = XGBClassifier(Yn_estimators=100, objective='multi:softmax', num_class=20, silent=True)
```

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EMG - Google Search

EMG signal process recon

ESLII.pdf

StackingClassifier: Simple

StackingCVClassifier: St

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Update

Xgboost

```
from xgboost import XGBClassifier
from sklearn.model_selection import RandomizedSearchCV, GridSearchCV
from sklearn.model_selection import StratifiedKFold

import datetime as dt
```

params = {
 'learning_rate': [0.1, 0.5, 0.8], *0 ≤ γ ≤ 1*
 'subsample': [0.6, 0.8, 1.0],
 'colsample_bytree': [0.6, 0.8, 1.0],
 'max_depth': [3, 4, 5]
}

xgb = XGBClassifier(n_estimators=100, objective='multi:softmax', num_class=20, silent=True)

[] folds = 3

<> skf = StratifiedKFold(n_splits=folds, shuffle = True, random_state = 1001)

random_search = RandomizedSearchCV(xgb, param_distributions=params, n_iter=10, scoring='accuracy', n_jobs=4, cv=skf)

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ESLII.pdf

StackingClassifier: Simple

StackingCVClassifier: St

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Update

Xgboost

```
from xgboost import XGBClassifier
from sklearn.model_selection import RandomizedSearchCV, GridSearchCV
from sklearn.model_selection import StratifiedKFold

import datetime as dt

params = {
    'learning_rate': [0.1, 0.5, 0.8],
    'subsample': [0.6, 0.8, 1.0], 
    'colsample_bytree': [0.6, 0.8, 1.0],
    'max_depth': [3, 4, 5]
}
xgb = XGBClassifier(n_estimators=100, objective='multi:softmax', num_class=20, silent=True)
```

[] folds = 3

```
<> skf = StratifiedKFold(n_splits=folds, shuffle = True, random_state = 1001)

random_search = RandomizedSearchCV(xgb, param_distributions=params, n_iter=10, scoring='accuracy', n_jobs=4, cv=skf)
```

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XgBoost.ipynb - Colaboratory

EMG - Google Search

EMG signal process recon

ESLII.pdf

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StackingCVClassifier: St

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Update

Xgboost

```
from xgboost import XGBClassifier
from sklearn.model_selection import RandomizedSearchCV, GridSearchCV
from sklearn.model_selection import StratifiedKFold

import datetime as dt

params = {
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    'subsample': [0.6, 0.8, 1.0],
    'colsample_bytree': [0.6, 0.8, 1.0],
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xgb = XGBClassifier(n_estimators=100, objective='multi:softmax', num_class=20, silent=True)
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[] folds = 3

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<> skf = StratifiedKFold(n_splits=folds, shuffle = True, random_state = 1001)

random_search = RandomizedSearchCV(xgb, param_distributions=params, n_iter=10, scoring='accuracy', n_jobs=4, cv=skf)
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multi-class-classfn!

DL



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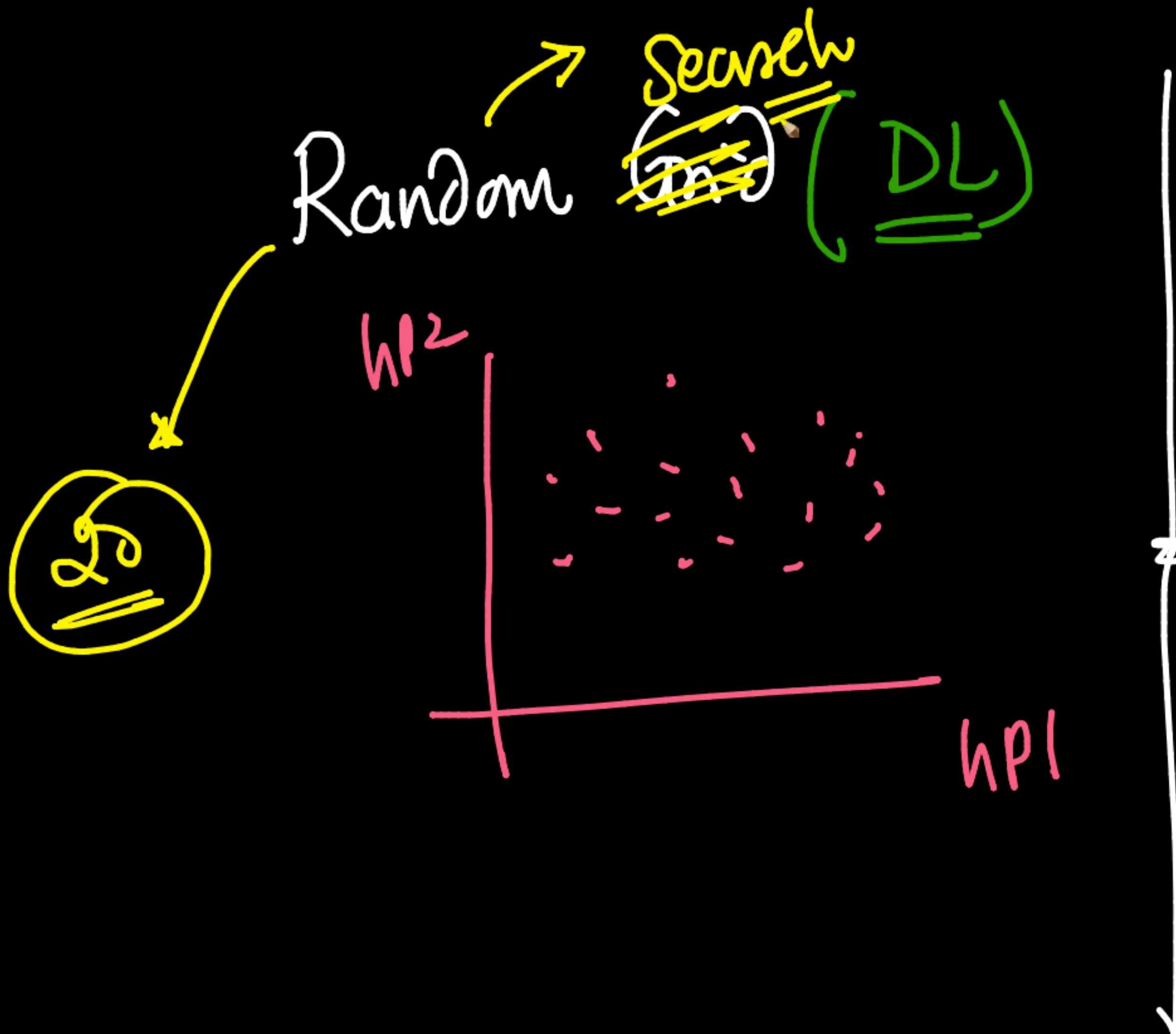
hi(\mathbf{z})



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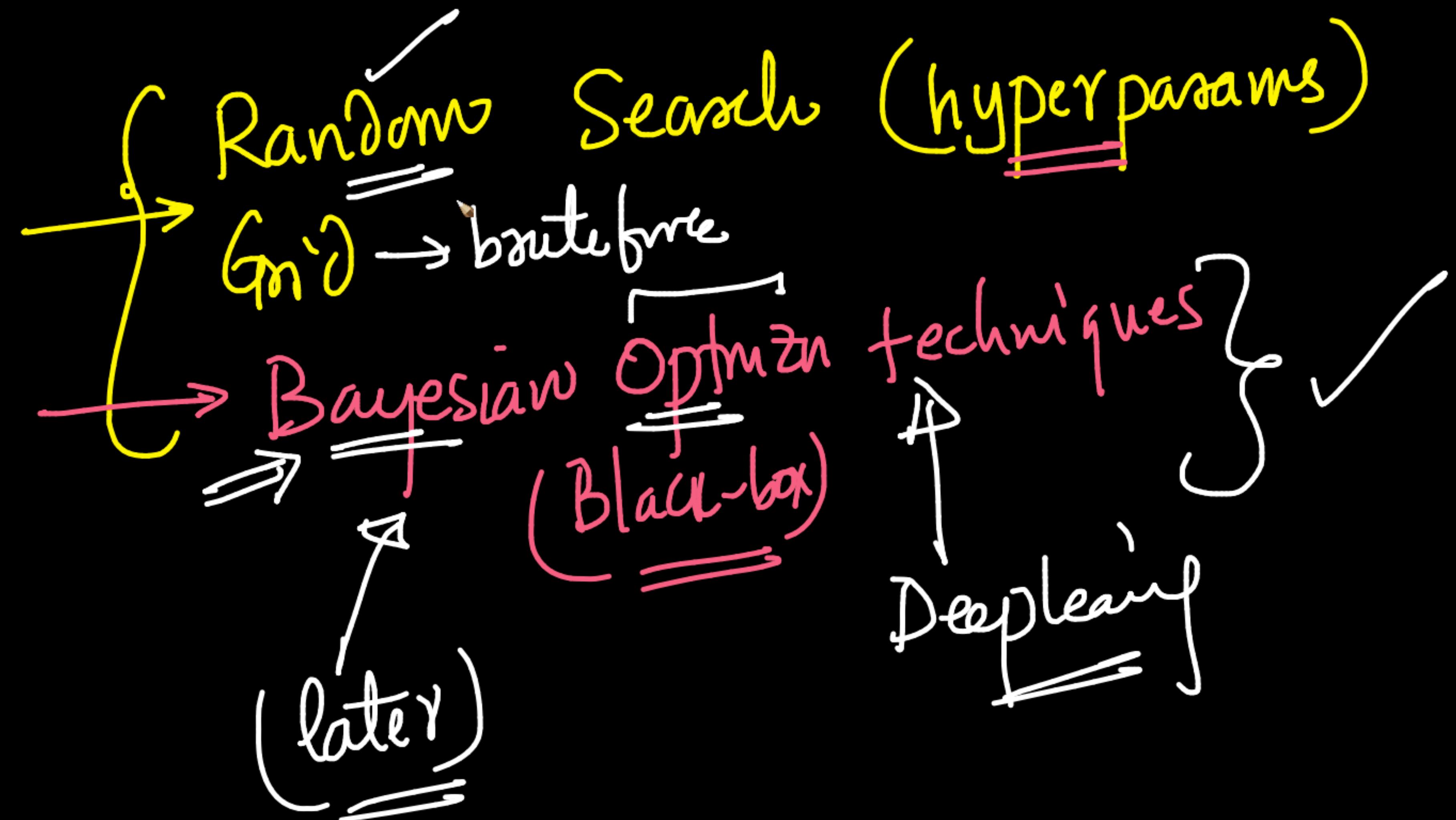
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243 GBDT
3-fold CV

RAM Disk

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Code

Text

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'learning_rate': [0.1, 0.5, 0.8],  
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start = dt.datetime.now()
random_search.fit(X_train, Y_train)
end = dt.datetime.now()

Fitting 3 folds for each of 10 candidates, totalling 30 fits

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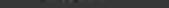
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<>

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Fitting 3 folds for each of 10 candidates, totalling 30 fits

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81: brute force

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```

Fitting 3 folds for each of 10 candidates, totalling 30 fits

```
[ ] print('\n Best hyperparameters: ')
print(random_search.best_params_)
```

```
+ Code + Text

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+ Code + Text RAM Disk Update

random_search = RandomizedSearchCV(xgb, param_distributions=params, n_iter=10, scoring='accuracy')

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Fitting 3 folds for each of 10 candidates, totalling 30 fits

[] print('\n Best hyperparameters: ')
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Best hyperparameters:
{'subsample': 0.6, 'max_depth': 3, 'learning_rate': 0.1, 'colsample_bytree': 1.0}

[] best_xgb = XGBClassifier(n_estimators=100, objective='multi:softmax', num_class=20, subsample=0.6, max_depth=3, learning_rate=0.1, colsample_bytree=1.0)
best_xgb.fit(X_train, Y_train)

XGBClassifier(colsample_bytree=1.0, num_class=20, objective='multi:softmax', silent=True, subsample=0.6)

[] print(f"Time taken for training : {end - start}\nTraining accuracy : {best_xgb.score(X_train, Y_train)}\nTest Accuracy : {best_xgb.score(X_test, Y_test)}")

accuracy

+ Code + Text

Fitting 3 folds for each of 10 candidates, totalling 30 fits

RAM Disk

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Best hyperparameters:

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XGBClassifier(colsample_bytree=1.0, num_class=20, objective='multi:softprob',
silent=True, subsample=0.6)

[] print(f"Time taken for training : {end - start}\nTraining accuracy:{best_xgb.score(X_train, Y_train)}\nTest Accurac

Time taken for training : 0:05:07.294350 ✓ ✓

Training accuracy:0.6747209538305429

Test Accuracy: 0.6114633527770733

[] print(best_xgb.feature_importances_)

[] plt.bar(range(len(best_xgb.feature_importances_)), best_xgb.feature_importances_)

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+ Code + Text RAM Disk  

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```

+ Code + Text

✓ RAM Disk

V

```
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```

$\{x\}$

Best hyperparameters:

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{'subsample': 0.6, 'max_depth': 3, 'learning_rate': 0.1, 'colsample_bytree': 1.0}
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XGBClassifier(colsample_bytree=1.0, num_class=20, objective='multi:softprob',  
              silent=True, subsample=0.6)
```

A set of small, light-gray navigation icons located at the bottom right of the screen. From left to right, they include: a double arrow for search, a magnifying glass for search, a circular arrow for refresh, a double arrow for zoom, a double arrow for scroll, a double arrow for scroll, a double arrow for scroll, and a double arrow for scroll.

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plt.bar(range(len(best_xgb.feature_importances_)), best_xgb.feature_importances_)
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```

```
[0.13315983 0.07298602 0.16566639 0.07955533 0.18605755 0.13500534  
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```

+ Code + Text

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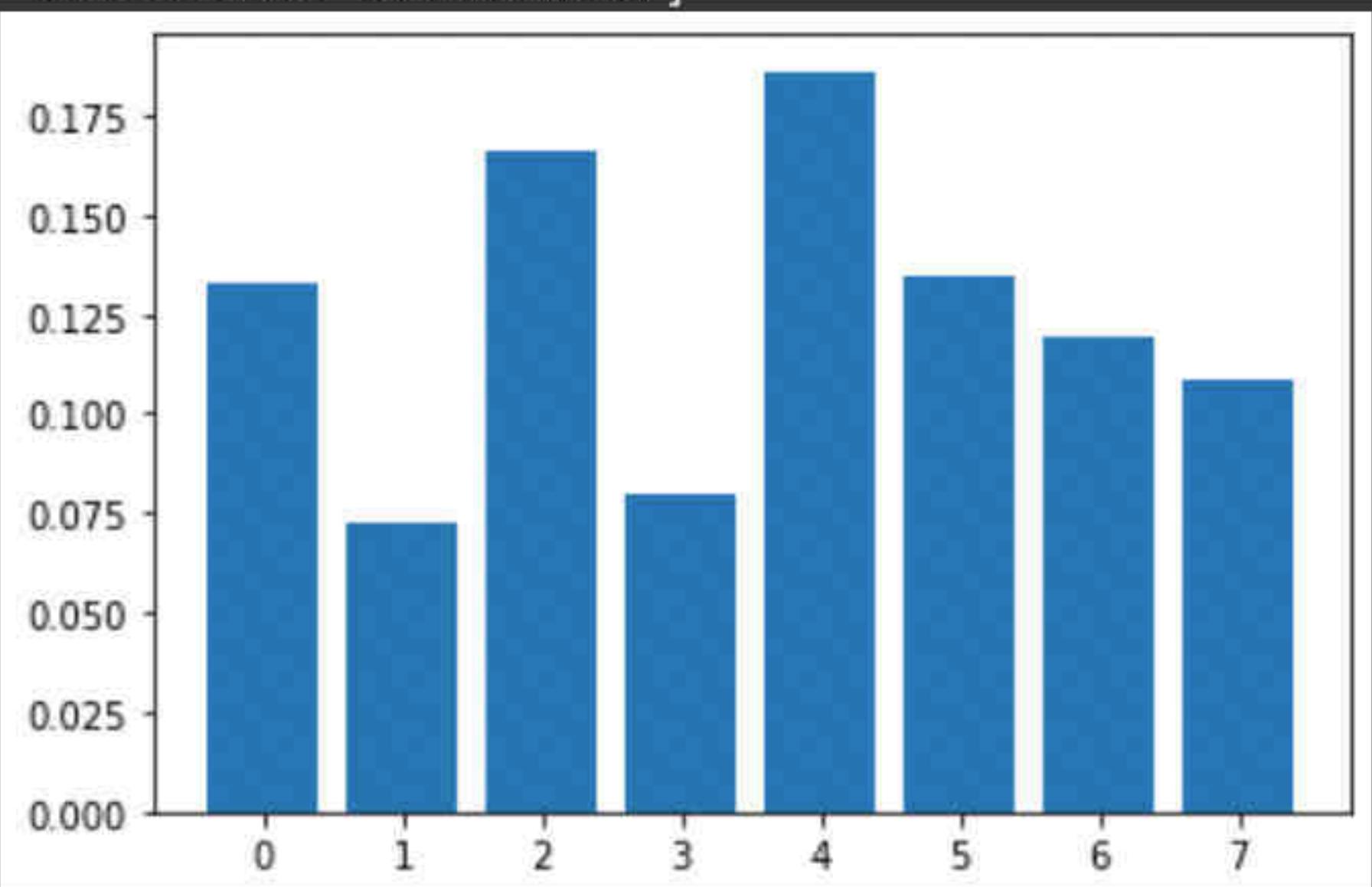
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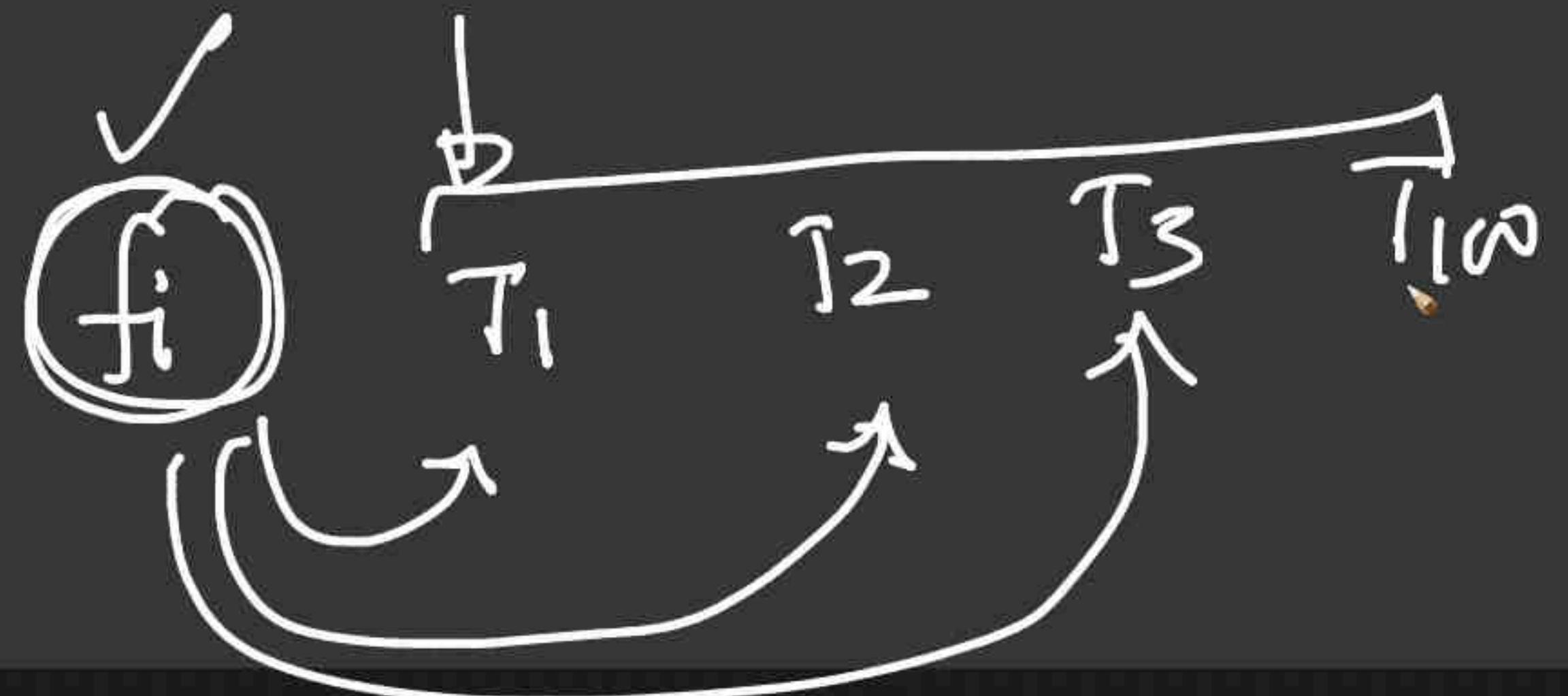
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100 base-learners



[] # Domain specific ideas to improve the results: Average data across time.

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Domain specific ideas to improve the results: Average data across time.

xgboost.readthedocs.io/en/stable/python/python_api.html#

GPU Support

XGBoost Parameters

Prediction

Tree Methods

Python Package

Python Package Introduction

Python API Reference

Callback Functions

Model

XGBoost Python Feature Walkthrough

XGBoost Dask Feature Walkthrough

R Package

JVM Package

Ruby Package

Swift Package

Julia Package

C Package

C++ Interface

CLI Interface

Contribute to XGBoost

feature_importances_ 3/30

results for all passed eval_sets. When eval_metric is also passed to the fit() function, evals_result will contain the eval_metrics passed to the fit() function.

The returned evaluation result is a dictionary:

```
{'validation_0': {'logloss': ['0.604835', '0.531479']},  
 'validation_1': {'logloss': ['0.41965', '0.17686']}}}
```

Return type: evals_result

property feature_importances_: numpy.ndarray

Feature importances property, return depends on importance_type parameter.

Returns:

- feature_importances_ (array of shape [n_features] except for multi-class)
- linear model, which returns an array with shape (n_features, n_classes)

property feature_names_in_: numpy.ndarray

Names of features seen during fit(). Defined only when X has feature names that are all strings.

```
fit(X, y, *, sample_weight=None, base_margin=None, eval_set=None, eval_metric=None,  
 early_stopping_rounds=None, verbose=True, xgb_model=None, sample_weight_eval_set=None,  
 bas
```

Read the Docs v: stable 115 / 115

TABLE 10.2. *Gradients for commonly used loss functions.*

Setting	Loss Function	$-\partial L(y_i, f(x_i))/\partial f(x_i)$
Regression	$\frac{1}{2}[y_i - f(x_i)]^2$	$y_i - f(x_i)$
Regression	$ y_i - f(x_i) $	$\text{sign}[y_i - f(x_i)]$
Regression	Huber	$y_i - f(x_i)$ for $ y_i - f(x_i) \leq \delta_m$ $\delta_m \text{sign}[y_i - f(x_i)]$ for $ y_i - f(x_i) > \delta_m$ where $\delta_m = \alpha\text{th-quantile}\{ y_i - f(x_i) \}$
Classification	Deviance	$k\text{th component: } I(y_i = \mathcal{G}_k) - p_k(x_i)$

boosting procedure, and top-down decision tree induction, are themselves approximation procedures. After constructing the tree (10.37), the corresponding constants in each region are given by (10.30).

Table 10.2 summarizes the gradients for commonly used loss functions. For squared error loss, the negative gradient is just the ordinary residual $-g_{im} = y_i - f_{m-1}(x_i)$, so that (10.37) on its own is equivalent standard least squares boosting. With absolute error loss, the negative gradient is the *sign* of the difference between the observed value y_i and the predicted value $f_{m-1}(x_i)$.

hastie.su.domains/Papers/ESLII.pdf

379 / 764 | - 175% + | [] []

360 10. Boosting and Additive Trees

TABLE 10.2. Gradients for commonly used loss functions.

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Classification	Deviance	kth component: $I(y_i = \mathcal{G}_k) - p_k(x_i)$

Yi - Pi

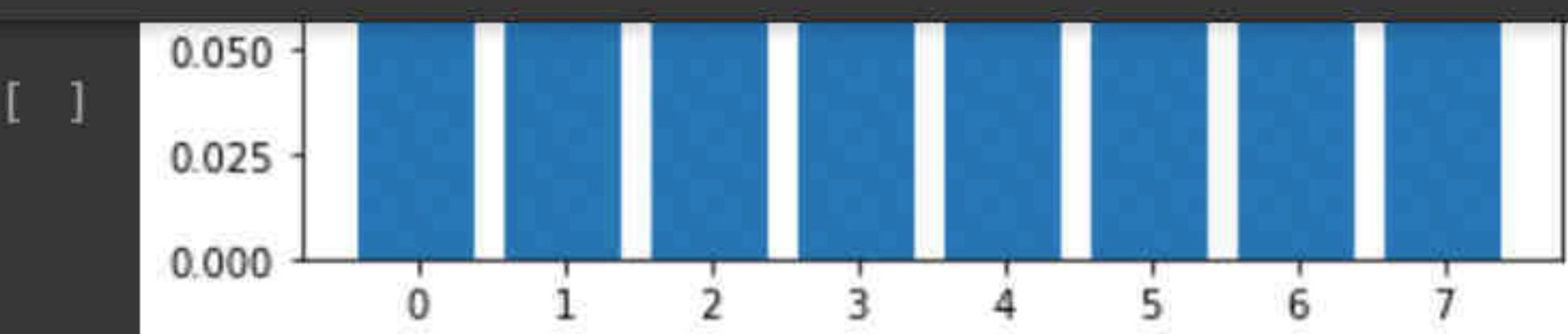
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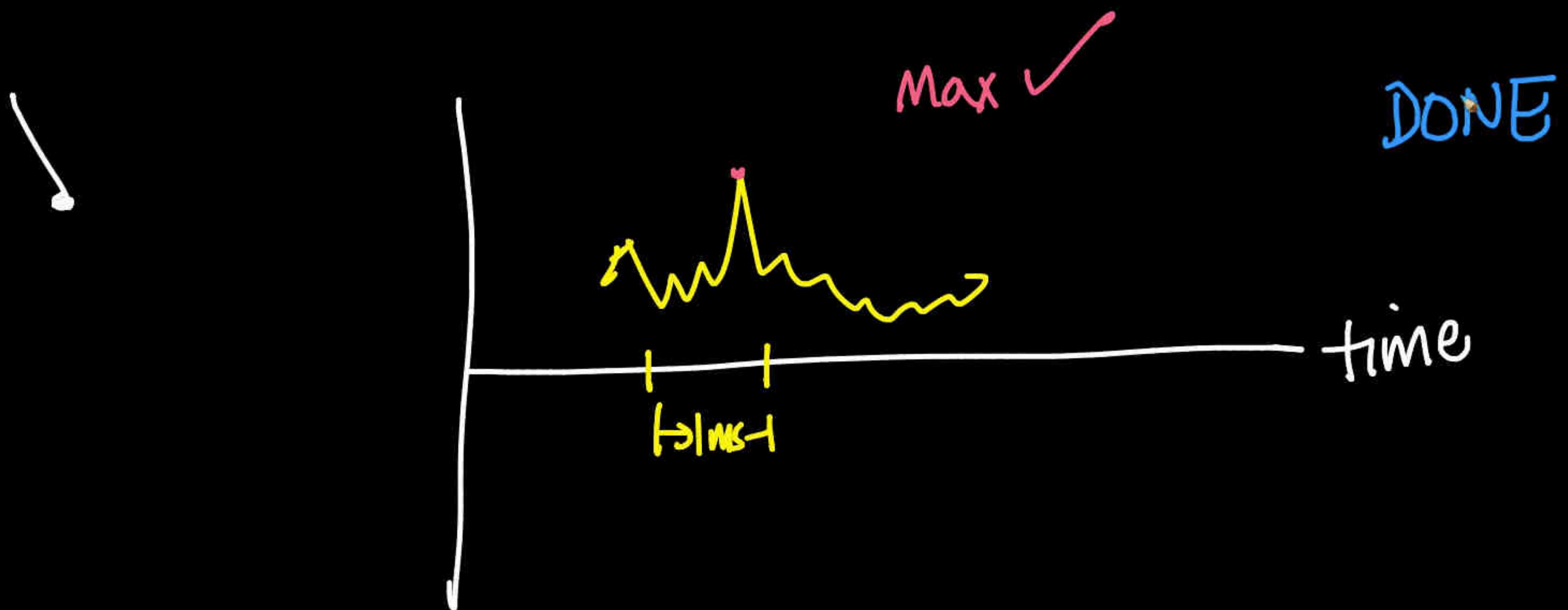
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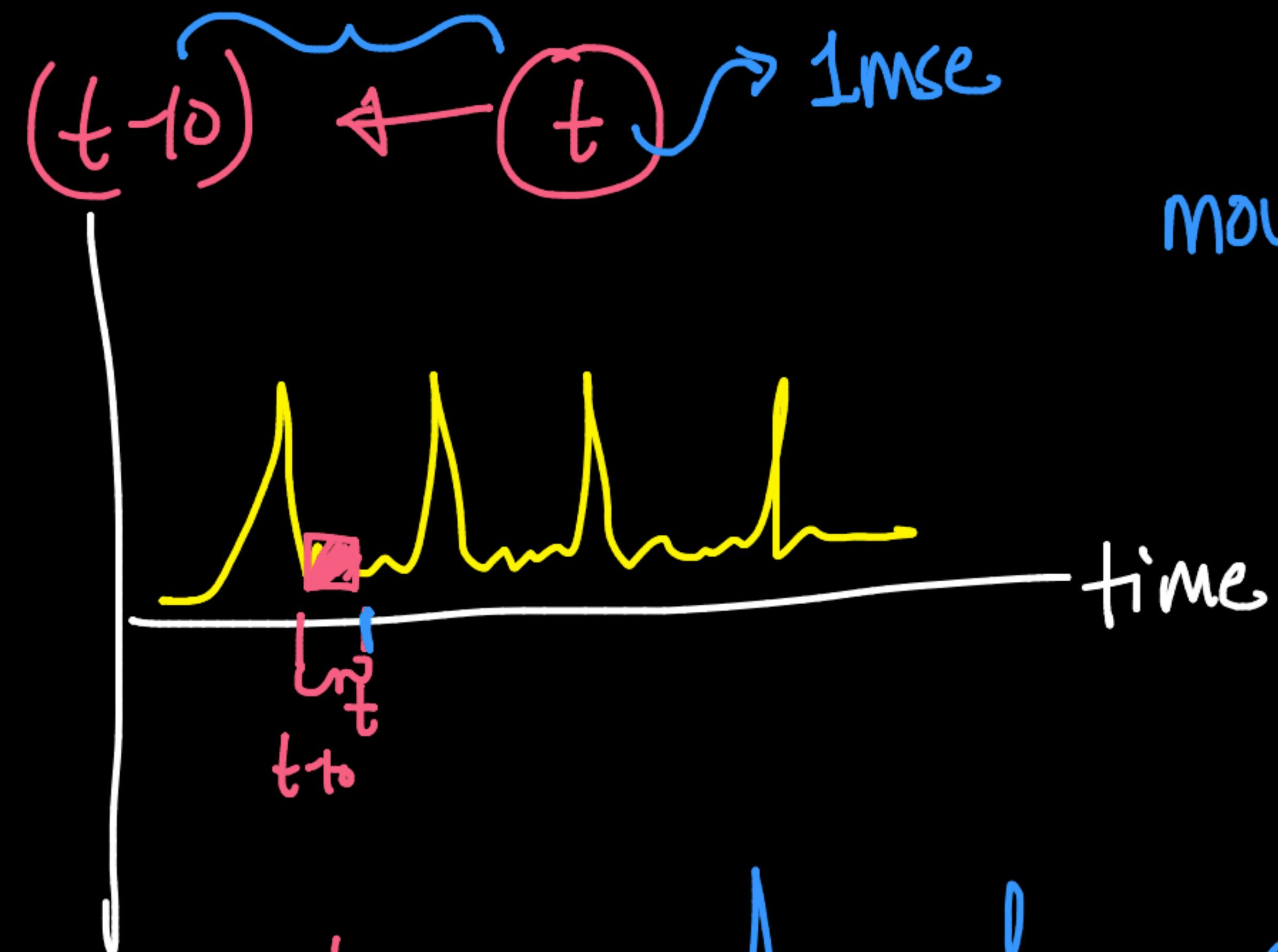
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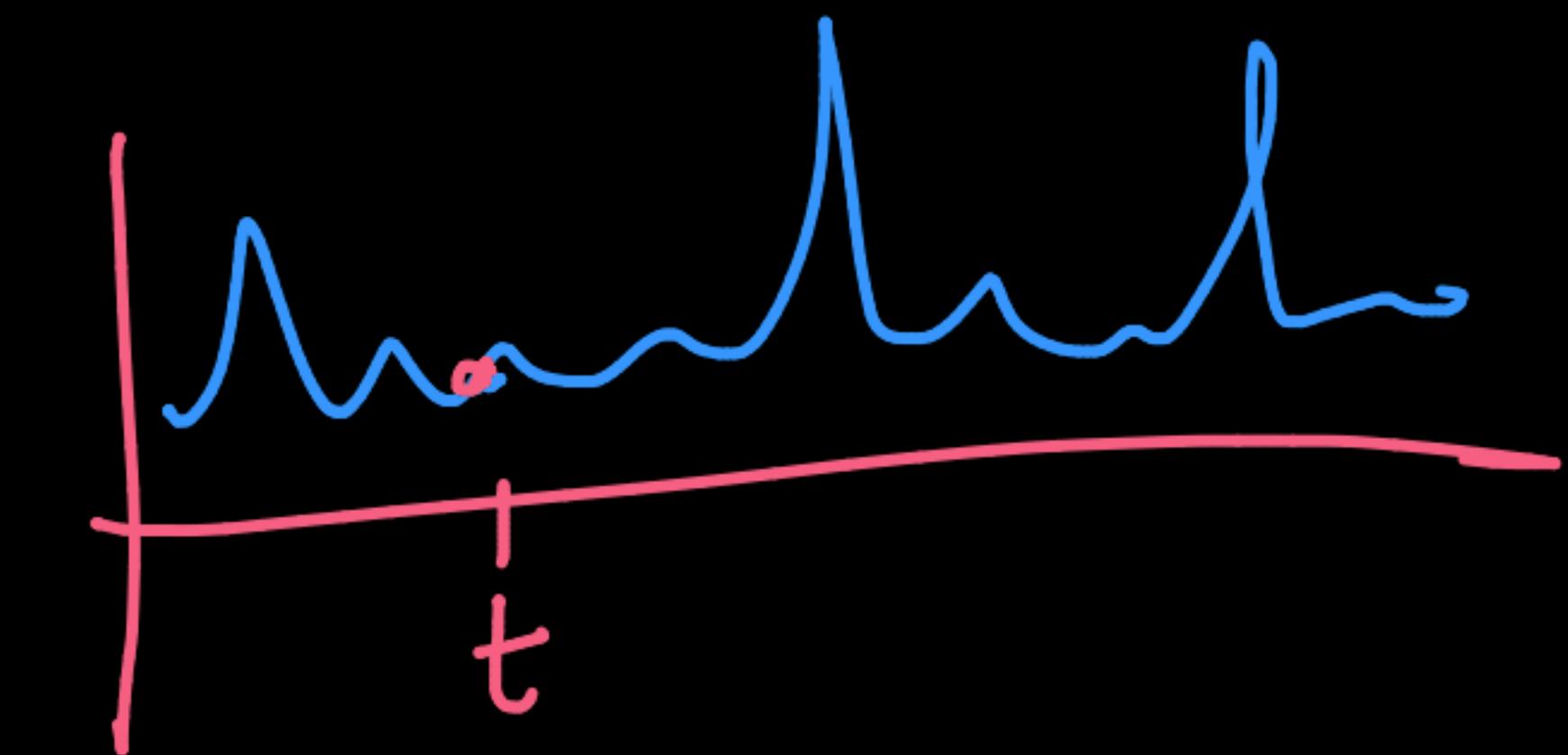


```
[ ] # Domain specific ideas to improve the results: Average data across time.  
## Source: https://www.researchgate.net/figure/EMG-signal-process-recommended-Green-The-raw-signal-no-treatment-was
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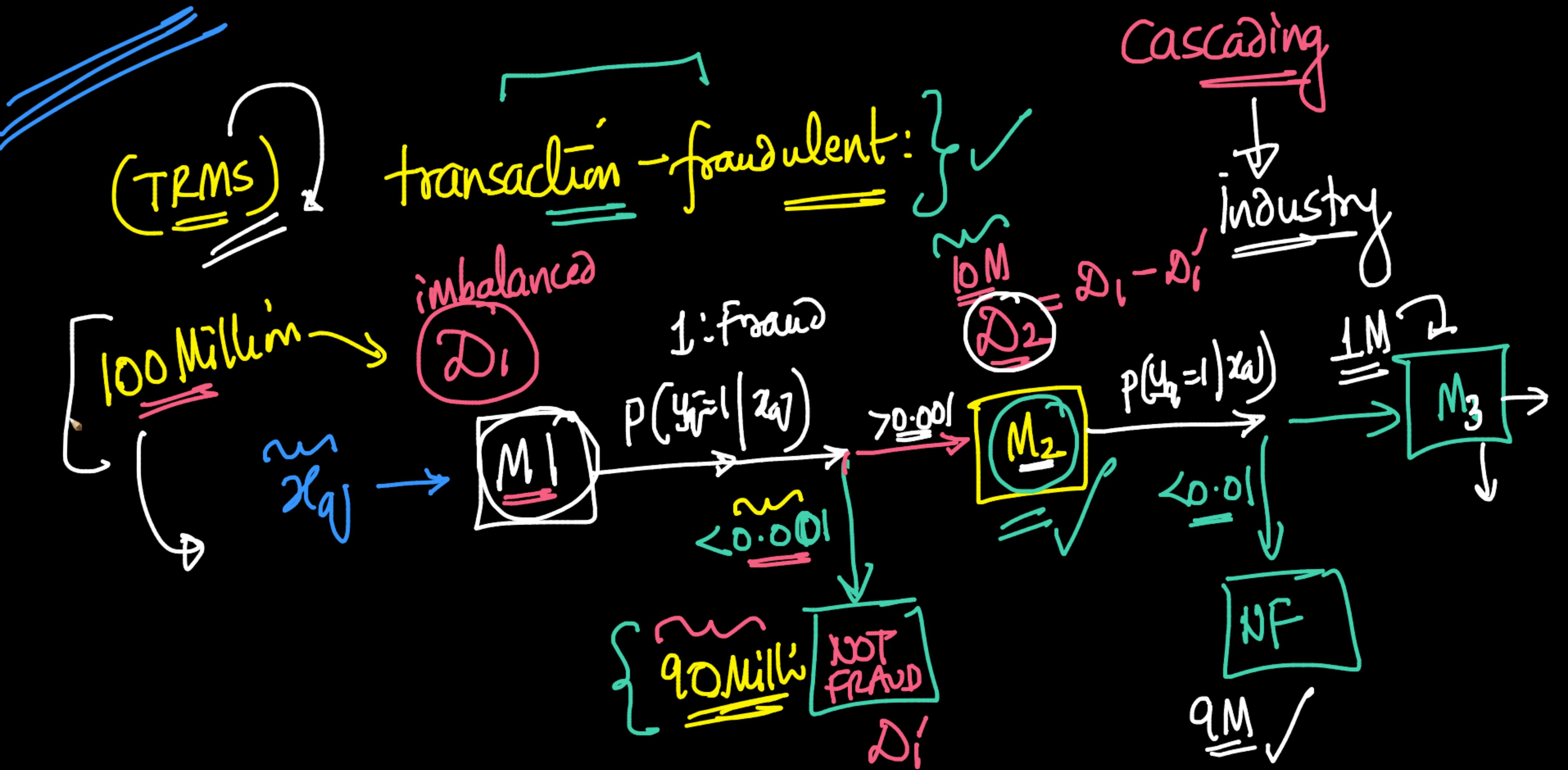


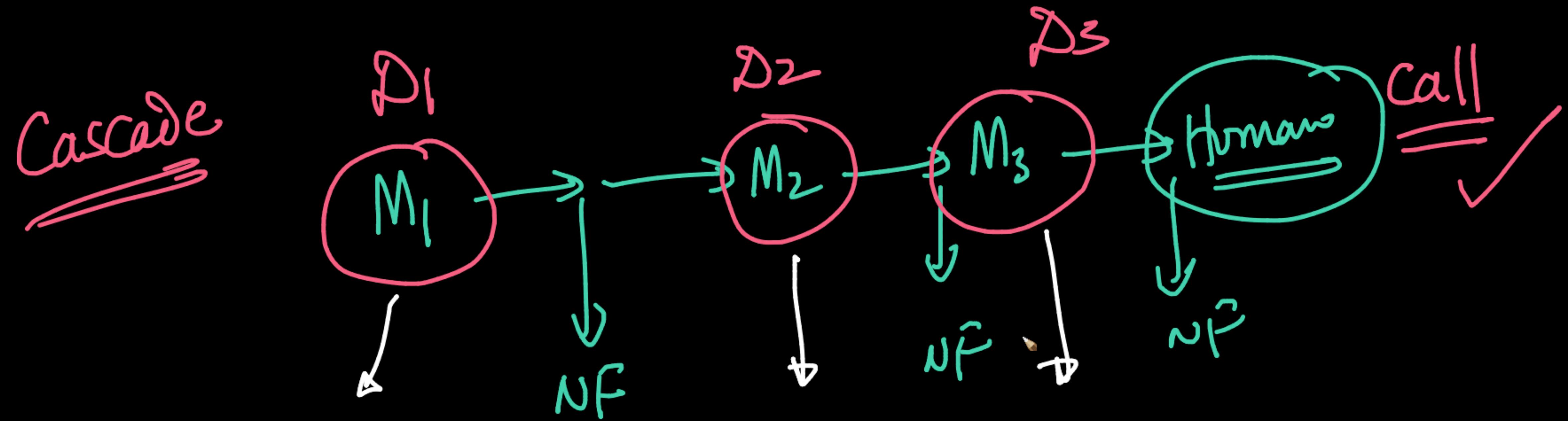


moving-average
↓
time-series



Smoothens
↓

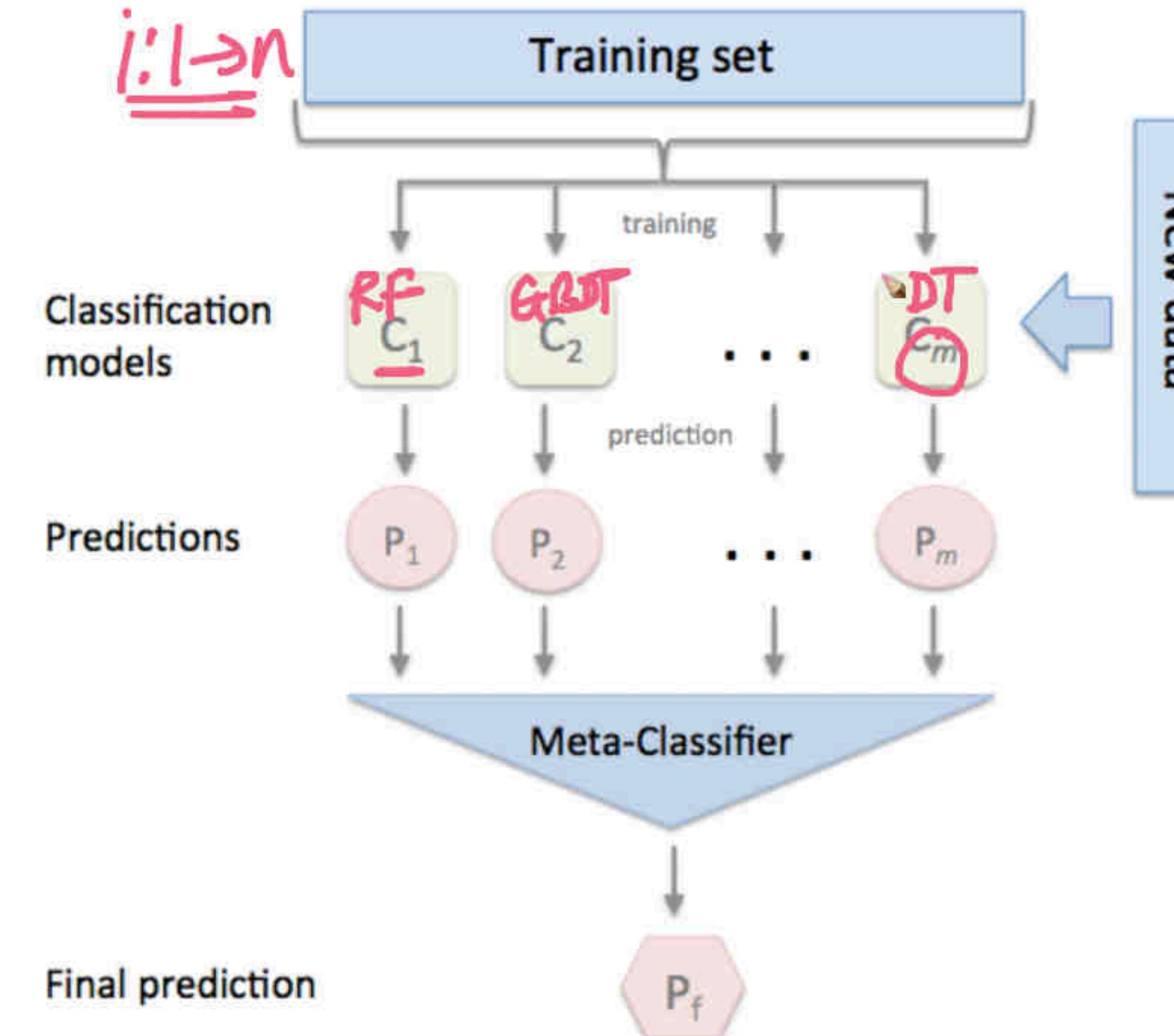




meta-classifier can either be trained on the predicted class labels or probabilities from the ensemble.

StackingClassifier: Simple stacking

- Overview
- References
- Example 1 - Simple Stacked Classification
- Example 2 - Using Probabilities as Meta-Features
- Example 3 - Stacked Classification and GridSearch
- Example 4 - Stacking of Classifiers that Operate on Different Feature Subsets
- Example 5 - Using Pre-fitted Classifiers
- Example 6 – ROC Curve with `decision_function`
- API

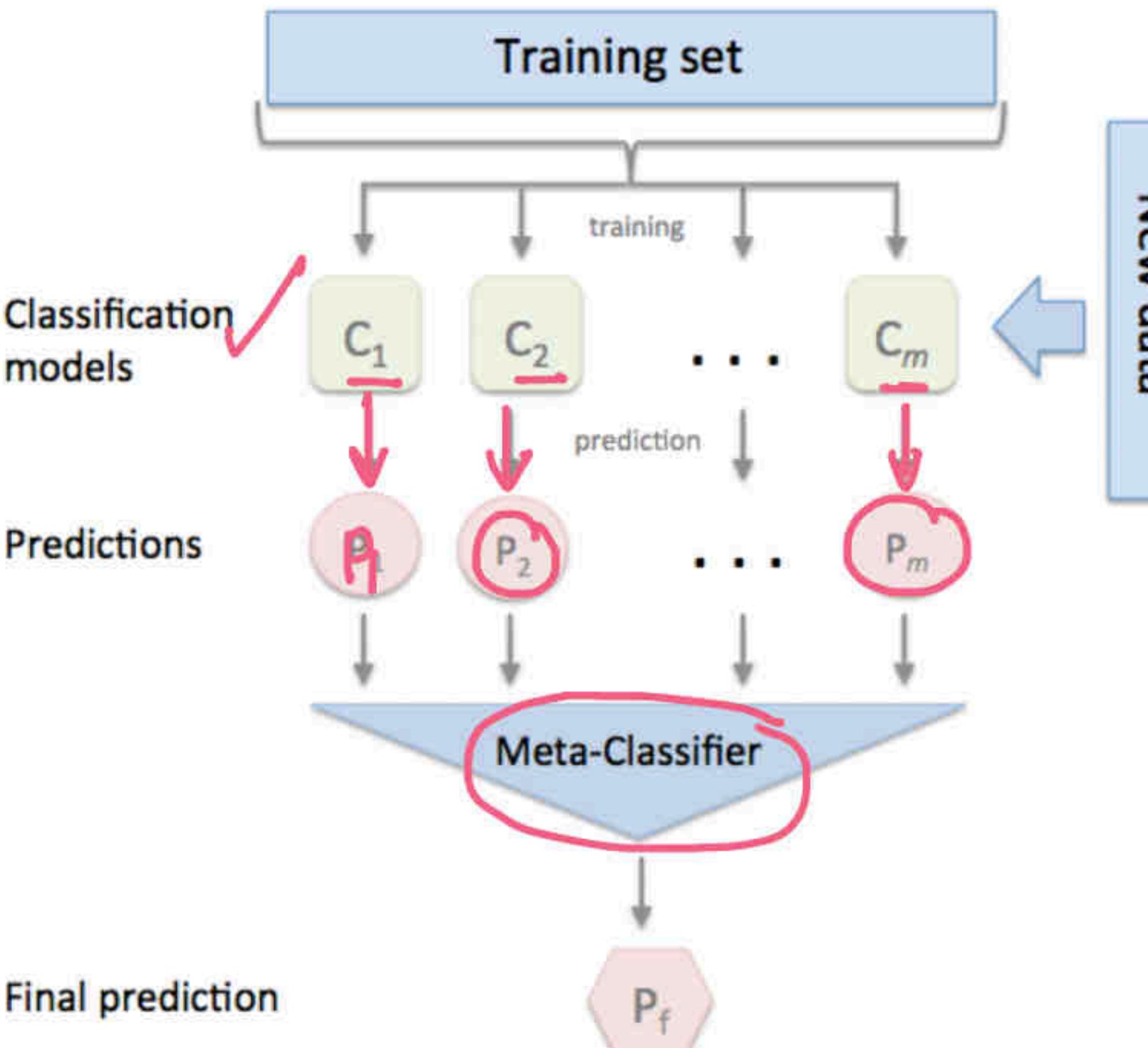


The algorithm can be summarized as follows (source: [1]):

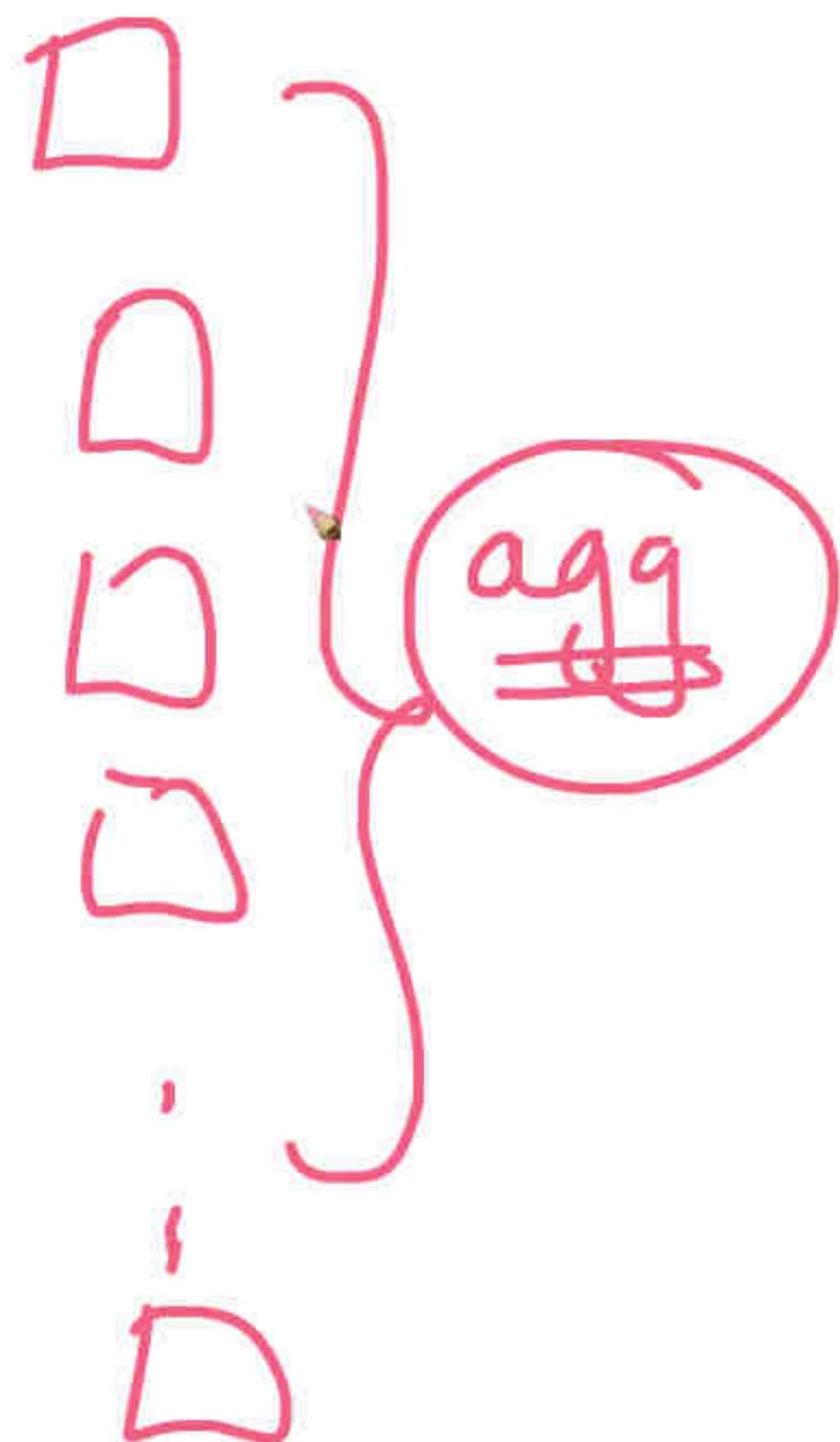
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- Example 6 – ROC Curve with `decision_function`
- API



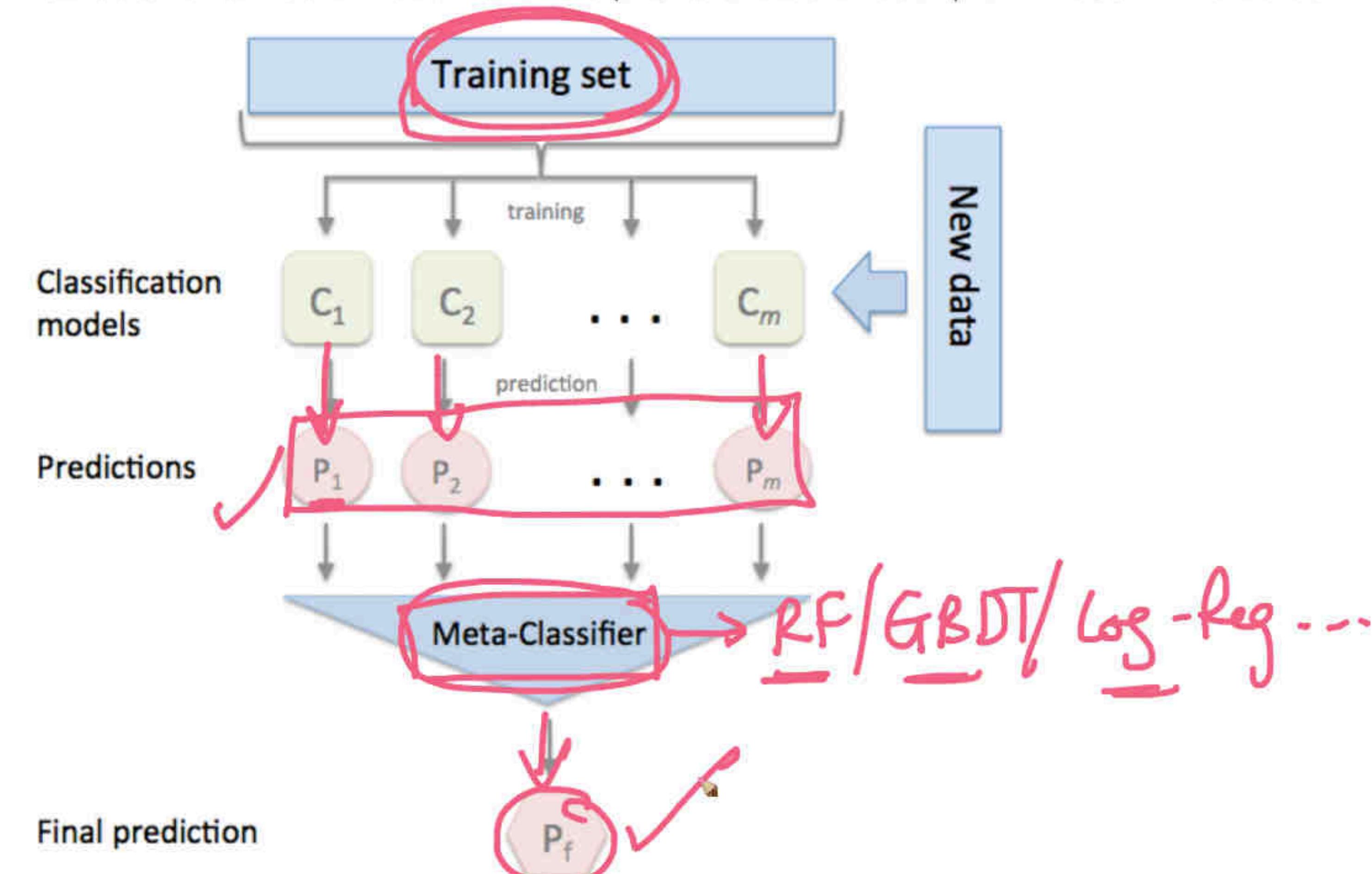
The algorithm can be summarized as follows (source: [1]):



StackingClassifier: Simple stacking

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- Example 3 - Stacked Classification and GridSearch
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meta-classifier can either be trained on the predicted class labels or probabilities from the ensemble.



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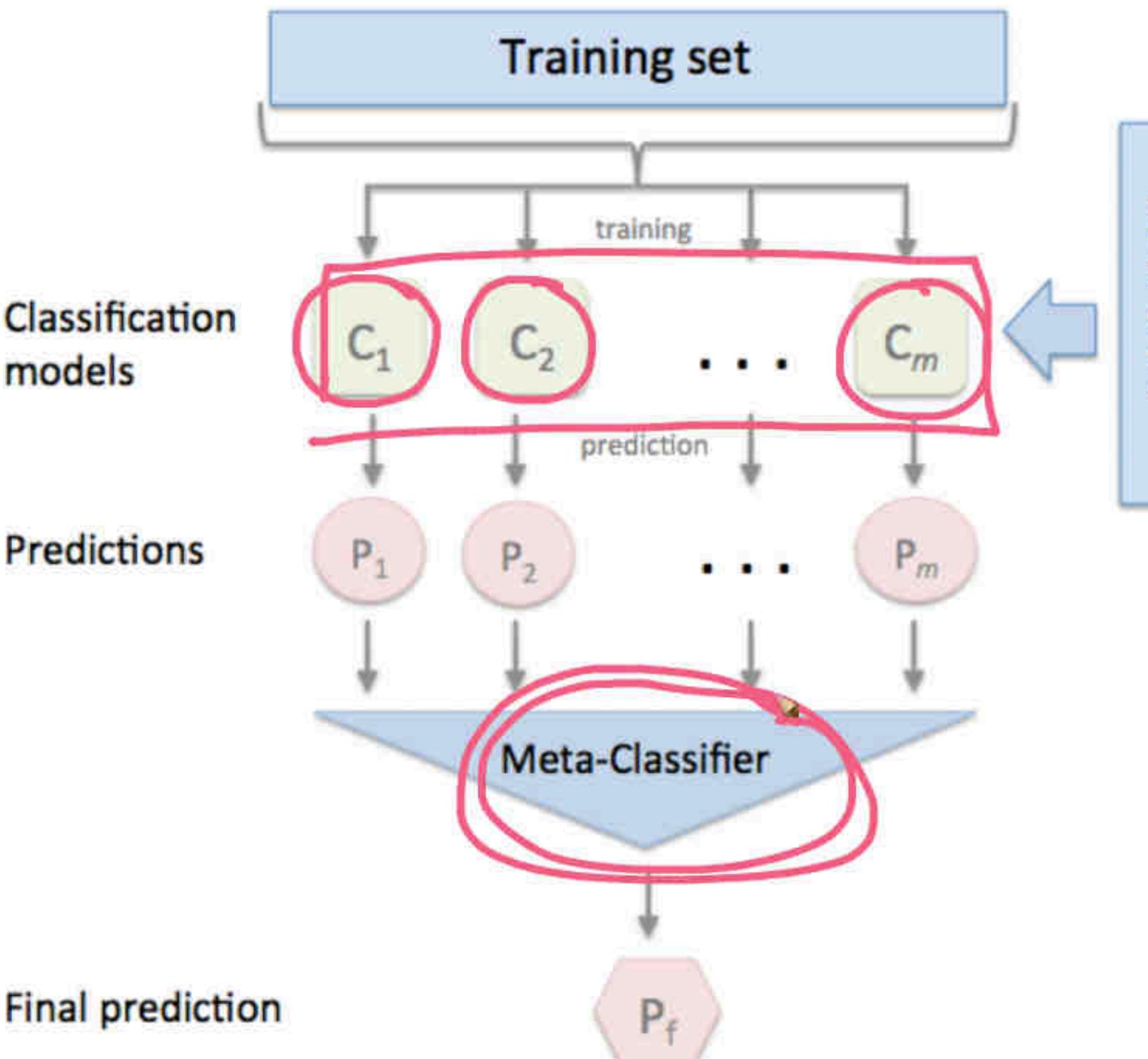
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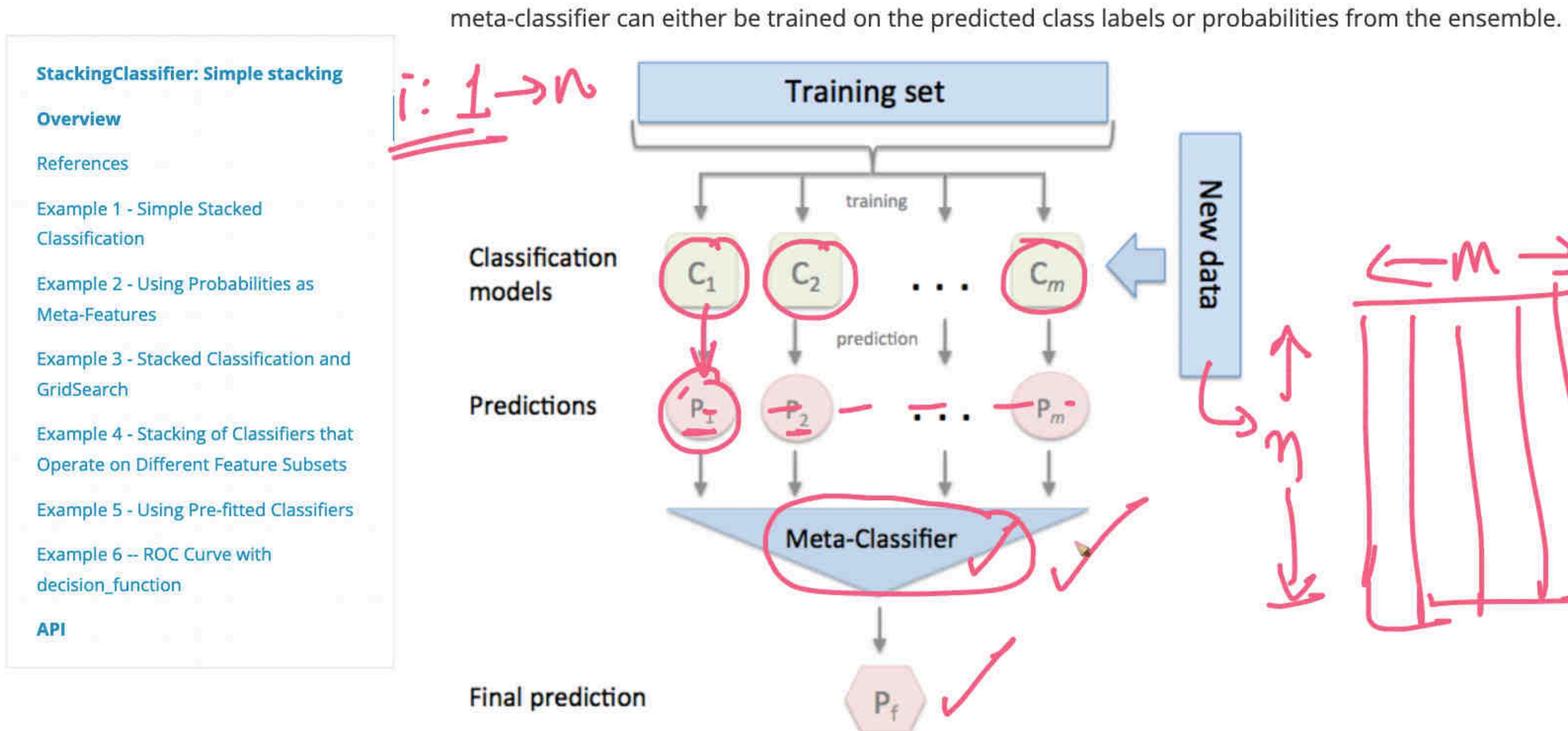
API

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~~Bagging:~~
Var \downarrow bias \rightarrow

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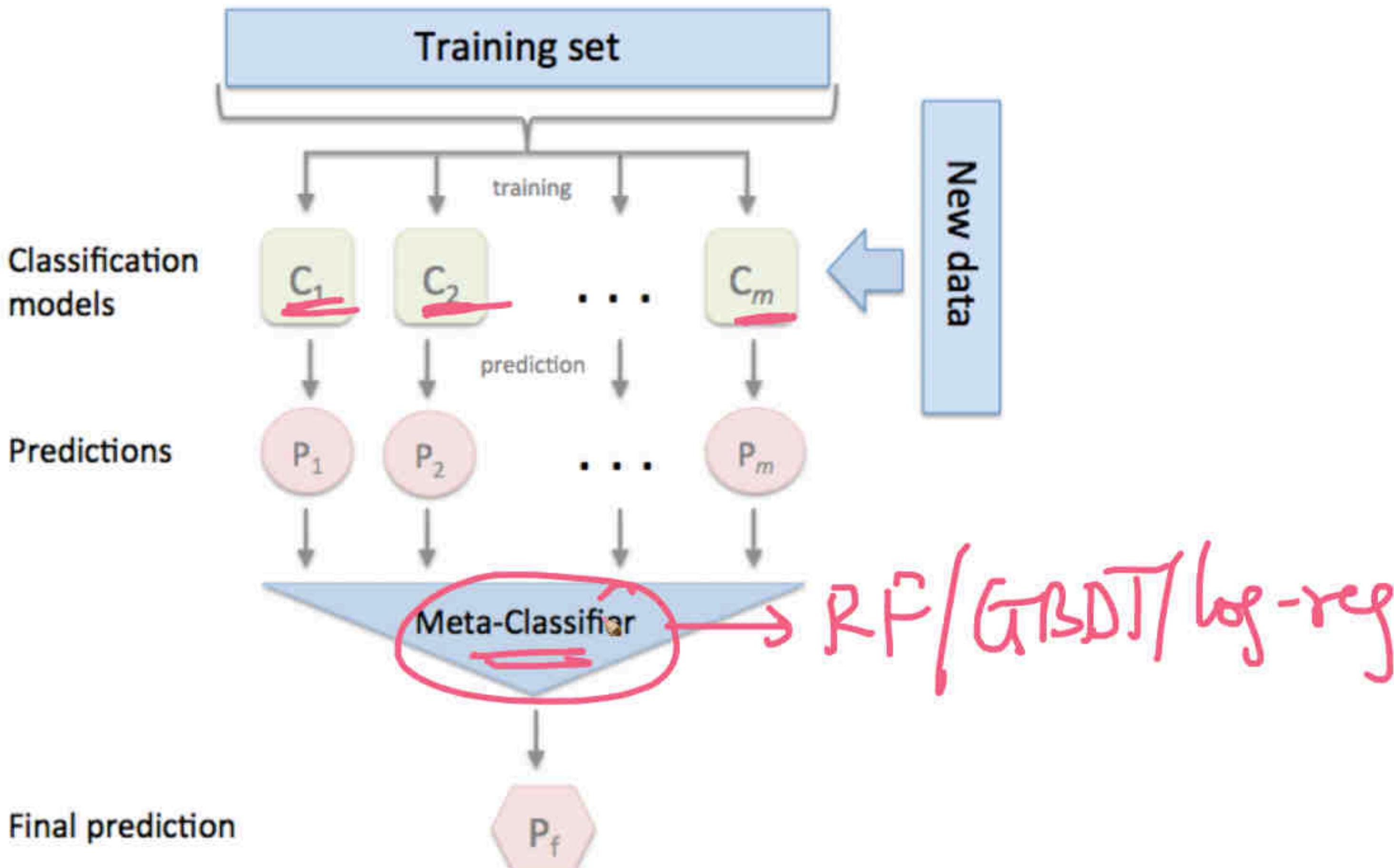


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API

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from sklearn.linear_model import LogisticRegression
from sklearn.neighbors import KNeighborsClassifier
from sklearn.naive_bayes import GaussianNB
from sklearn.ensemble import RandomForestClassifier
from mlxtend.classifier import StackingClassifier
import numpy as np
import warnings

warnings.simplefilter('ignore')

clf1 = KNeighborsClassifier(n_neighbors=1)
clf2 = RandomForestClassifier(random_state=1)
clf3 = GaussianNB()
lr = LogisticRegression()
sclf = StackingClassifier(classifiers=[clf1, clf2, clf3],
                           meta_classifier=lr)

print('3-fold cross validation:\n')

for clf, label in zip([clf1, clf2, clf3, sclf],
                      ['KNN',
                       'Random Forest',
                       'Naive Bayes',
                       'StackingClassifier']):

    scores = model_selection.cross_val_score(clf, X, y,
                                              cv=3, scoring='accuracy')
    print("Accuracy: %0.2f (+/- %0.2f) [%s]" % (scores.mean(), scores.std(), label))
```

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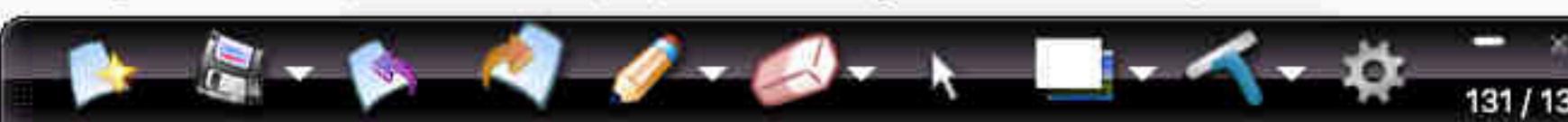
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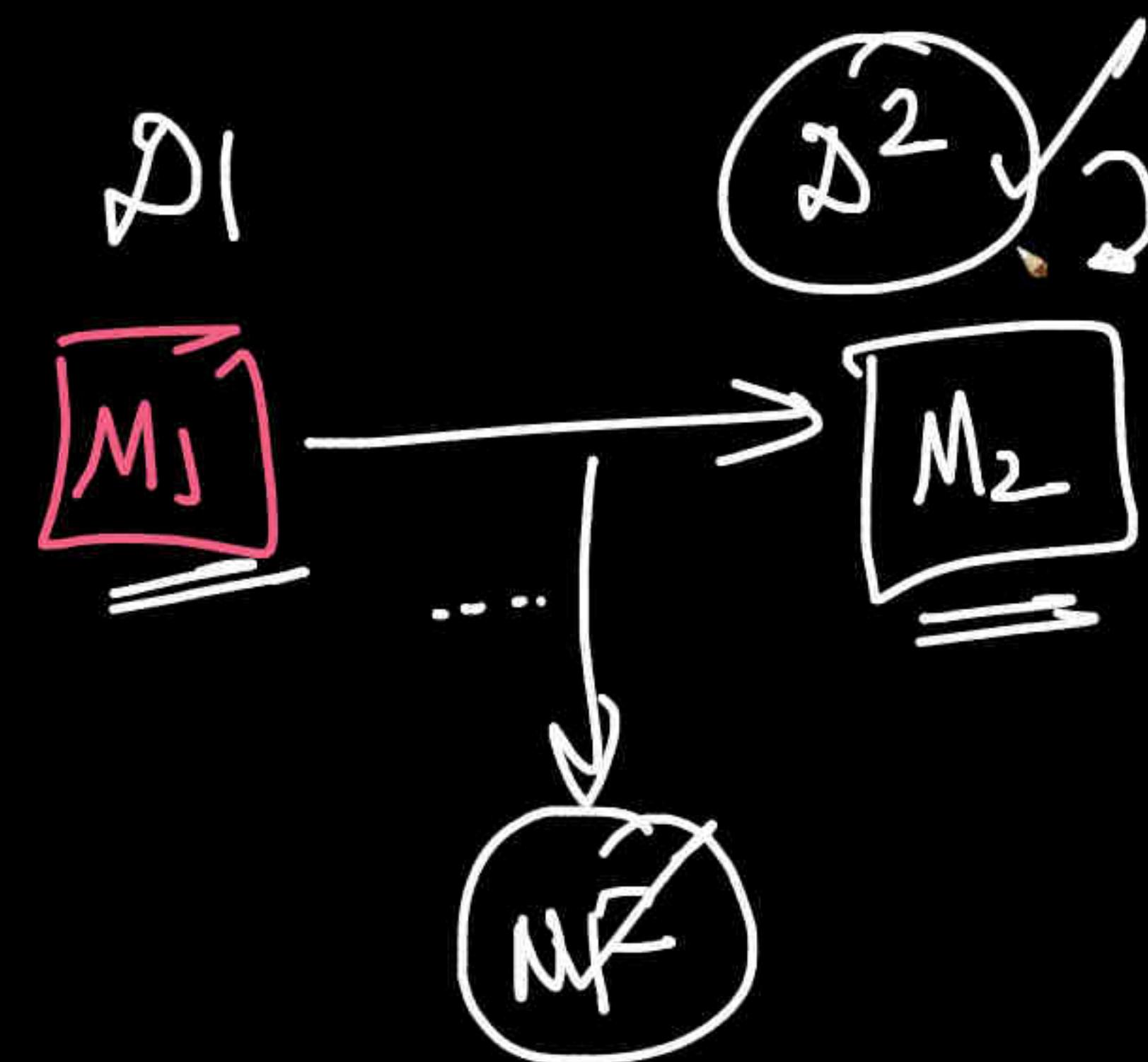
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    print("Accuracy: %0.2f (+/- %0.2f) [%s]"
          % (scores.mean(), scores.std(), label))
```

3-fold cross validation:

```
Accuracy: 0.91 (+/- 0.01) [KNN]
Accuracy: 0.95 (+/- 0.01) [Random Forest]
Accuracy: 0.91 (+/- 0.02) [Naive Bayes]
Accuracy: 0.95 (+/- 0.02) [StackingClassifier]
```



Cascade up



StackingClassifier: Simple stacking

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Example 6 – ROC Curve with decision_function

API

Example 1 - Simple Stacked Classification

```
from sklearn import datasets

iris = datasets.load_iris()
X, y = iris.data[:, 1:3], iris.target
```

```
from sklearn import model_selection
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```



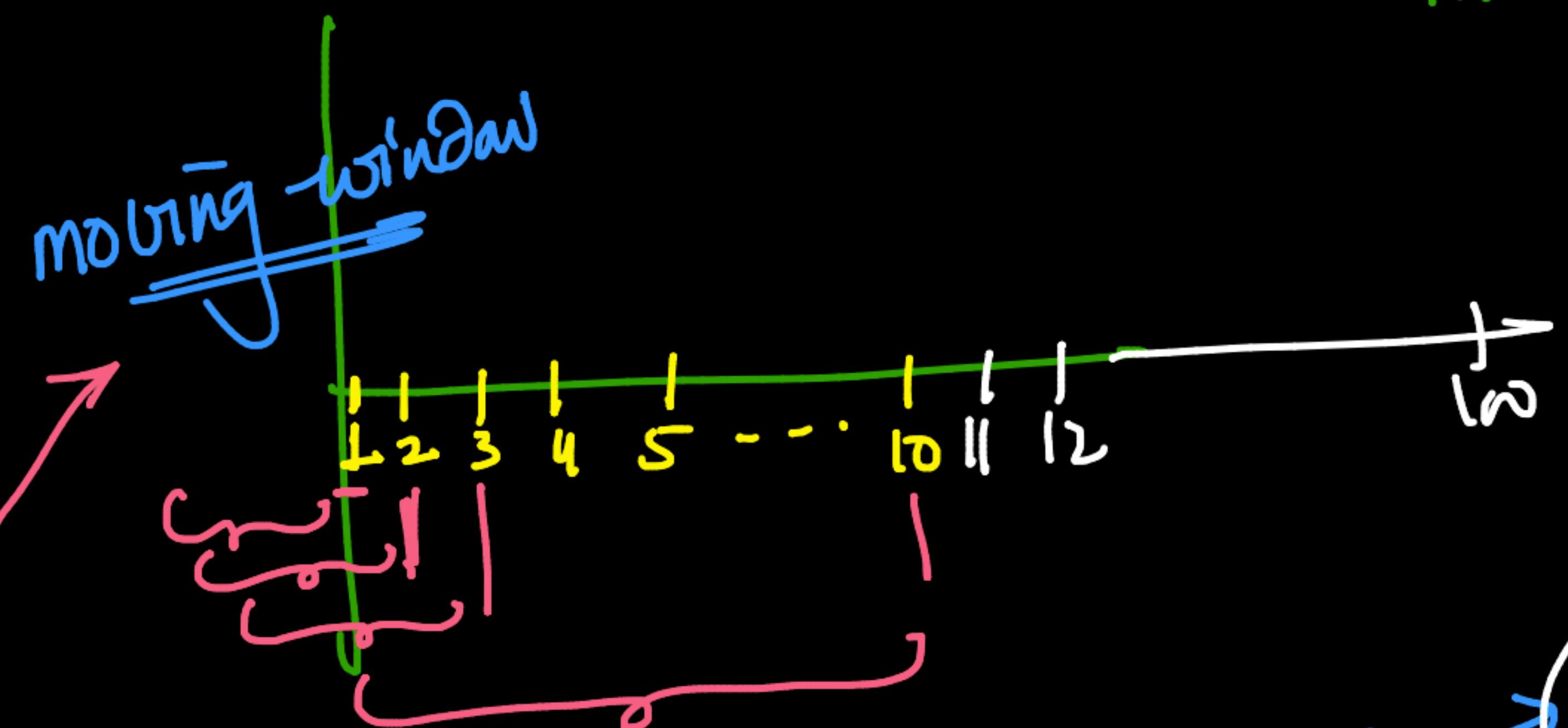
Next-class: → minor details (recap)

→ stacking, casted if
 p lagger

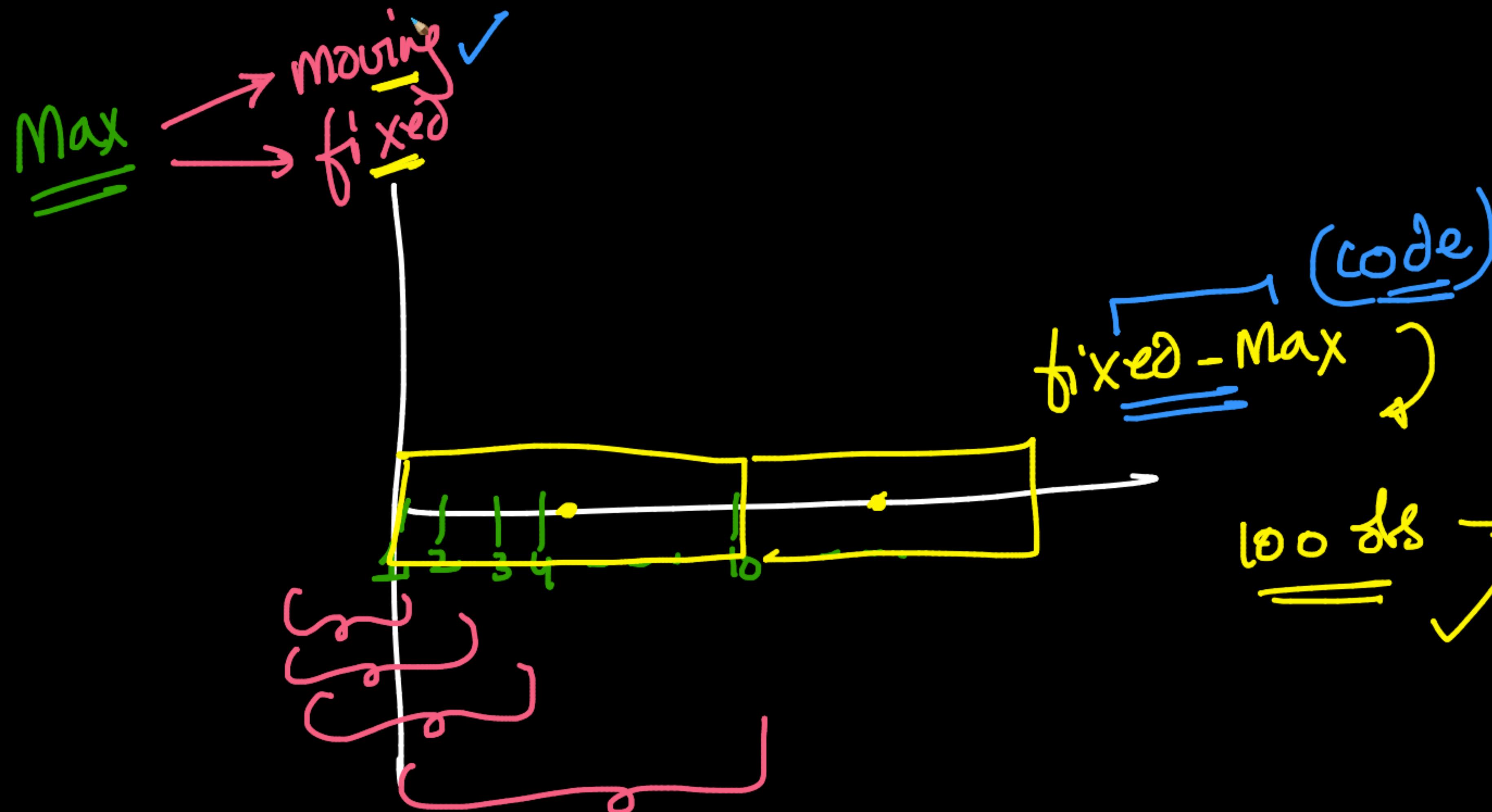
→ next - Model

Q & A

home-work



average → MW
→ FW

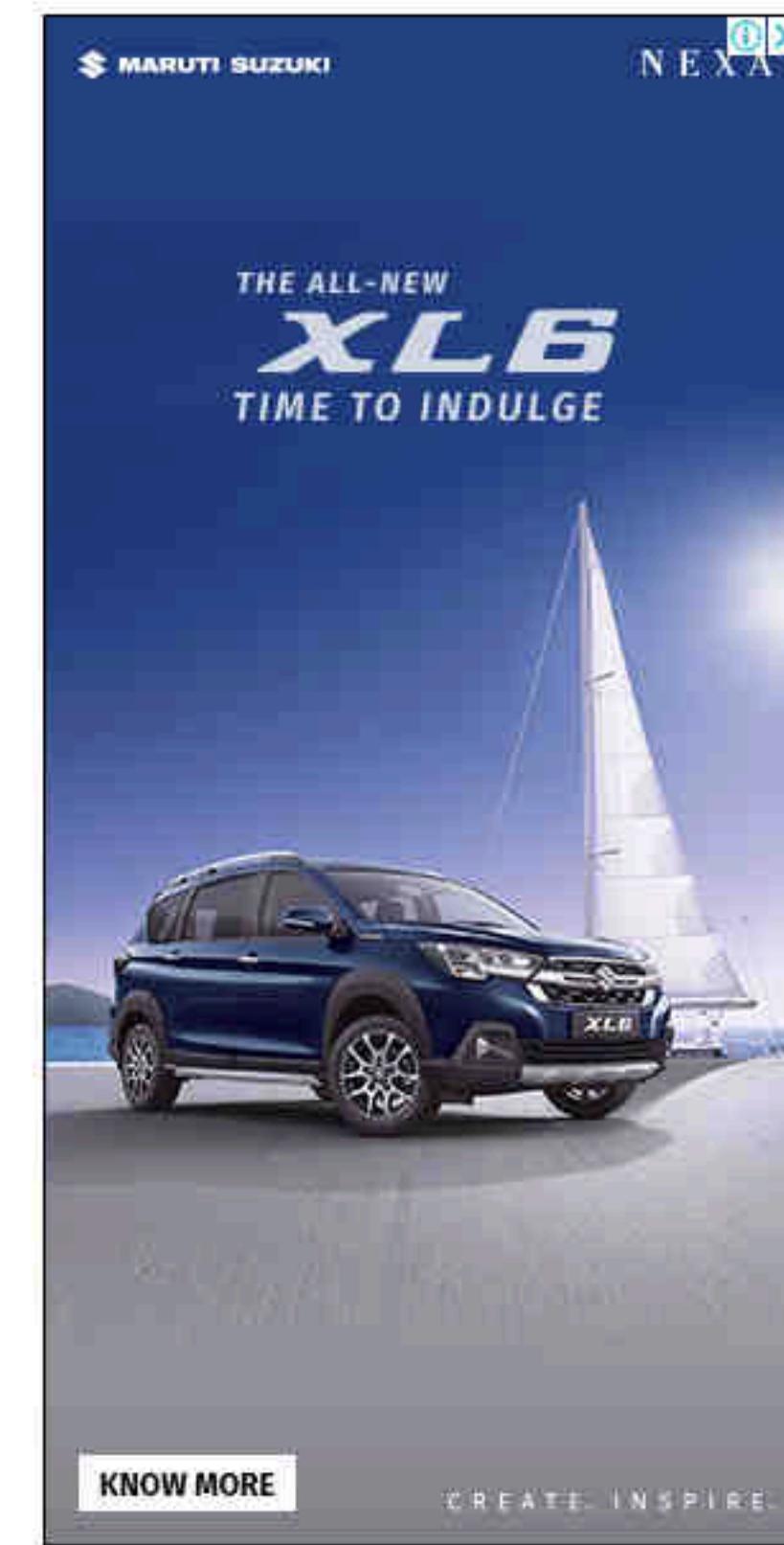


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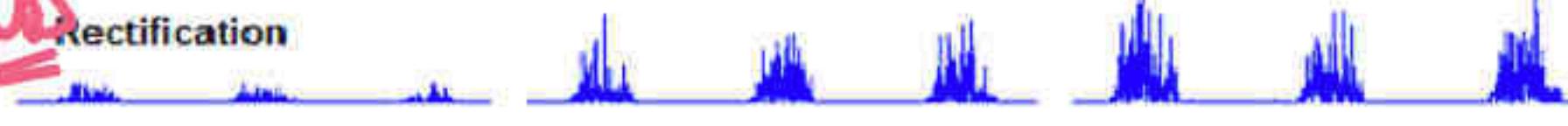
Raw



Filtration



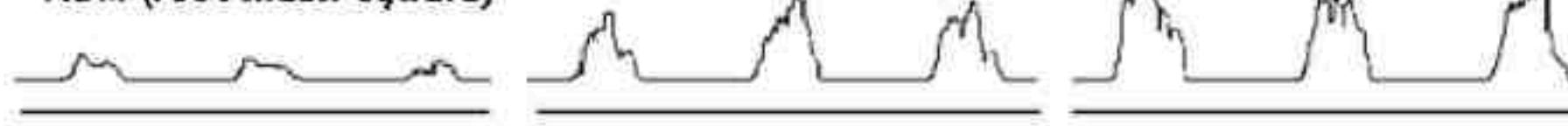
abs
Rectification



MWA
Smoothing



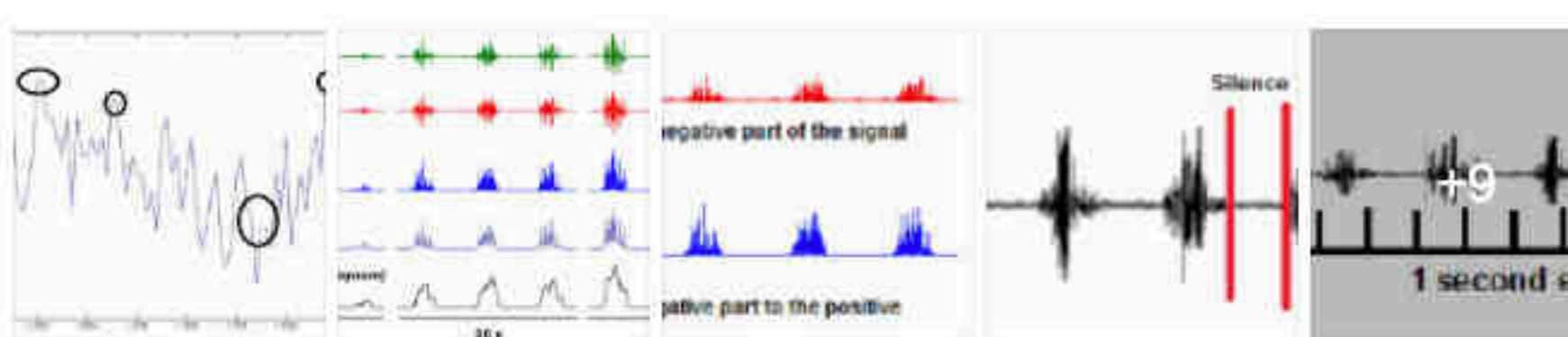
RSM (root mean square)



10 s 30 s 60 s

EMG signal process recommended. Green: The raw signal, no treatment was applied until this moment; Red: Filtrated signal, a limit was created for the signal, excluding everything out of it; Blue: Rectified signal, all negative values were transformed in positive ones and added; Purple: the smoothed signal, a linear enveloped was created and the extreme parts of the signal was excluded; Black: The RMS values after all the treatments.

Source publication



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$$L = y_i \cdot \log\left(\frac{1}{1 + e^{-\hat{y}_i}}\right) + (1 - y_i) \cdot \log\left(\frac{e^{-\hat{y}_i}}{1 + e^{-\hat{y}_i}}\right)$$

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After changing sign we have expression for gradient of logistic loss function:

$$p_i - y_i$$

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Ogurtsov

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- 4 What you're calling \hat{y} here is *not* a prediction of y , but a linear combination of predictors. In generalized linear modeling we use the notation v and call this term the "linear predictor". Your derivative of the loglikelihood (score) is wrong, there should be a squared term in the denominator, since bernoullis form an exponential likelihood. The score should be of the form $\frac{1}{p_i(1-p_i)}(y_i - p_i)$ – AdamO Jul 5, 2016 at 18:04

bicycles?

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y_i

$$-\frac{\partial L}{\partial F(a)} = \underbrace{\partial F(a)}_{L} \rightarrow p_i = \hat{y}_i$$

$$f_k(x) = \underline{\underline{p_i}} = \hat{y}_i$$

(log-loss(y_i, \hat{y}_i))

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360 10. Boosting and Additive Trees

TABLE 10.2. Gradients for commonly used loss functions.

Setting	Loss Function	$-\partial L(y_i, f(x_i))/\partial f(x_i)$
Regression	$\frac{1}{2}[y_i - f(x_i)]^2$	$y_i - f(x_i)$
Regression	$ y_i - f(x_i) $	$\text{sign}[y_i - f(x_i)]$
Regression	Huber	$y_i - f(x_i)$ for $ y_i - f(x_i) \leq \delta_m$ $\delta_m \text{sign}[y_i - f(x_i)]$ for $ y_i - f(x_i) > \delta_m$ where $\delta_m = \alpha\text{th-quantile}\{ y_i - f(x_i) \}$
Classification	Deviance	kth component: $I(y_i = \mathcal{G}_k) - p_k(x_i)$

boosting procedure, and top-down decision tree induction, are themselves approximation procedures. After constructing the tree (10.37), the corresponding constants in each region are given by (10.30).

Table 10.2 summarizes the gradients for commonly used loss functions. For squared error loss, the negative gradient is just the ordinary residual $-g_{im} = y_i - f_{m-1}(x_i)$, so that (10.37) on its own is equivalent standard least squares boosting. With absolute error loss, the negative gradient is the *sign* of the residual, so at each iteration (10.37) fits the tree to the sign of the current residuals by least squares. For Huber M-regression, the negative gradient is a compromise between these two (see the table).

For classification the loss function is the multinomial deviance (10.22), and K least squares trees are constructed at each iteration. Each tree T_{km} is fit to its respective negative gradient vector \mathbf{g}_{km} ,

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360 10. Boosting and Additive Trees

TABLE 10.2. Gradients for commonly used loss functions.

Setting	Loss Function	$-\partial L(y_i, f(x_i))/\partial f(x_i)$
Regression	$\frac{1}{2}[y_i - f(x_i)]^2$	$y_i - f(x_i)$
-Regression	$ y_i - f(x_i) $	$\text{sign}[y_i - f(x_i)]$
Regression	Huber	$y_i - f(x_i)$ for $ y_i - f(x_i) \leq \delta_m$ $\delta_m \text{sign}[y_i - f(x_i)]$ for $ y_i - f(x_i) > \delta_m$ where $\delta_m = \alpha\text{th-quantile}\{ y_i - f(x_i) \}$
Classification	Deviance	kth component: $I(y_i = \mathcal{G}_k) - p_k(x_i)$

boosting procedure, and top-down decision tree induction, are themselves approximation procedures. After constructing the tree (10.37), the corresponding constants in each region are given by (10.30).

Table 10.2 summarizes the gradients for commonly used loss functions. For squared error loss, the negative gradient is just the ordinary residual $-g_{im} = y_i - f_{m-1}(x_i)$, so that (10.37) on its own is equivalent standard least squares boosting. With absolute error loss, the negative gradient is the *sign* of the residual, so at each iteration (10.37) fits the tree to the sign of the current residuals by least squares. For Huber M-regression, the negative gradient is a compromise between these two (see the table).

For classification the loss function is the multinomial deviance (10.22), and K least squares trees are constructed at each iteration. Each tree T_{km} is fit to its respective negative gradient vector \mathbf{g}_{km} ,

dim

$$\left\{ \frac{-\partial L}{\partial F(x)} \right\} = \text{sensible take pseudo-dual} \approx \text{sensible residual}$$
$$f_{m+1}(x)$$

360 10. Boosting and Additive Trees

TABLE 10.2. *Gradients for commonly used loss functions*

Setting	Loss Function	$-\partial L(y_i, f(x_i))/\partial f(x_i)$
Regression	$\frac{1}{2}[y_i - f(x_i)]^2$	$y_i - f(x_i)$
Regression	$ y_i - f(x_i) $	$\text{sign}[y_i - f(x_i)]$
Regression	Huber	$y_i - f(x_i)$ for $ y_i - f(x_i) \leq \delta_m$ $\delta_m \text{sign}[y_i - f(x_i)]$ for $ y_i - f(x_i) > \delta_m$ where $\delta_m = \alpha\text{th-quantile}\{ y_i - f(x_i) \}$
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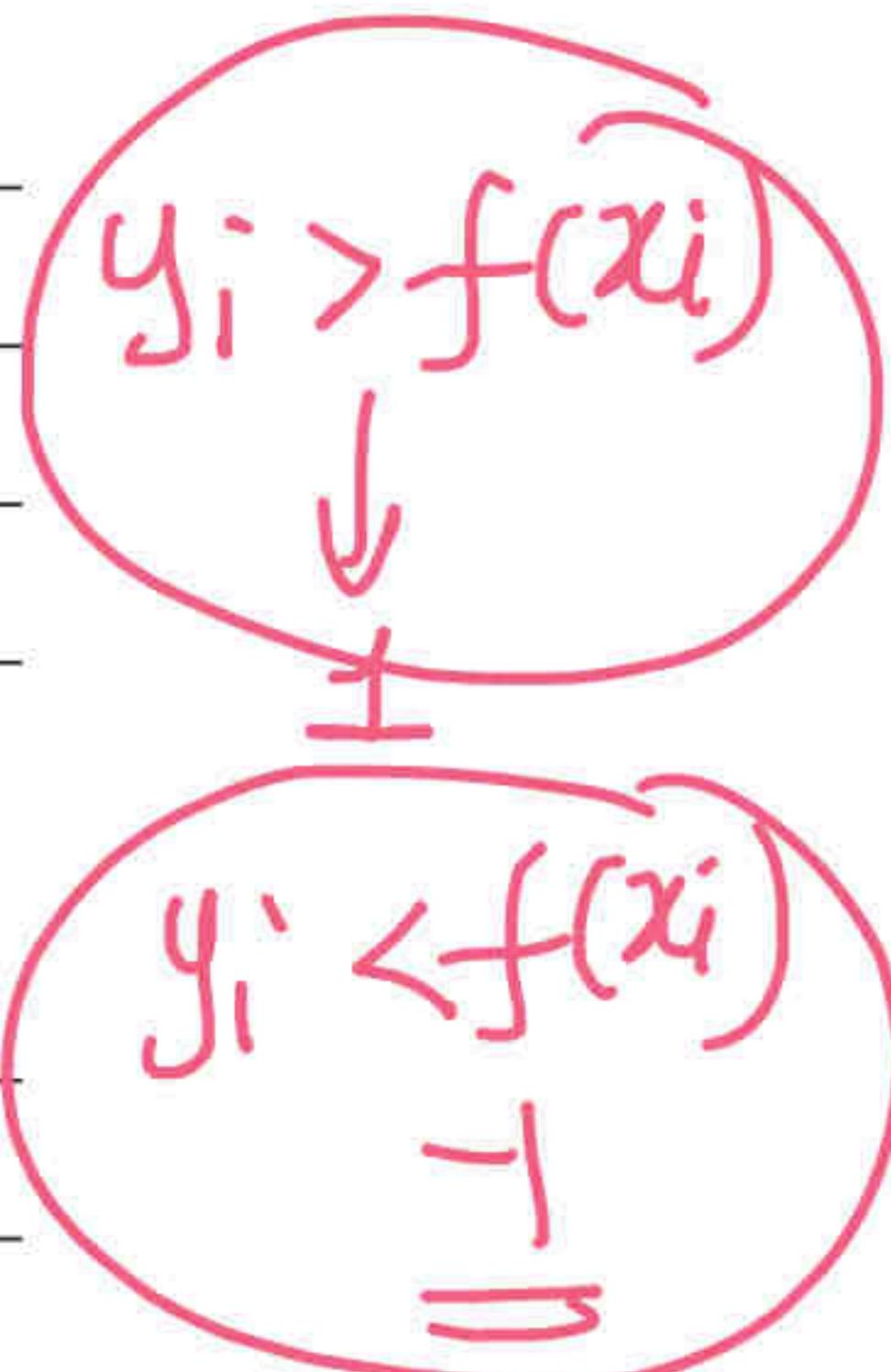
360 10. Boosting and Additive Trees

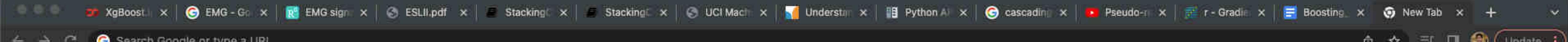
TABLE 10.2. Gradients for commonly used loss functions.

Setting	Loss Function	$-\partial L(y_i, f(x_i))/\partial f(x_i)$
Regression	$\frac{1}{2}[y_i - f(x_i)]^2$	$y_i - f(x_i)$
Regression	$ y_i - f(x_i) $	$\text{sign}[y_i - f(x_i)] \leftarrow \text{env}$
Regression	Huber	$y_i - f(x_i)$ for $ y_i - f(x_i) \leq \delta_m$ $\delta_m \text{sign}[y_i - f(x_i)]$ for $ y_i - f(x_i) > \delta_m$ where $\delta_m = \alpha\text{-quantile}\{ y_i - f(x_i) \}$
Classification	Deviance	kth component: $I(y_i = G_k) - p_k(x_i)$

boosting procedure, and top-down decision tree induction, are themselves approximation procedures. After constructing the tree (10.37), the corresponding constants in each region are given by (10.30).

Table 10.2 summarizes the gradients for commonly used loss functions. For square loss, the gradient is the ordinary residual





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