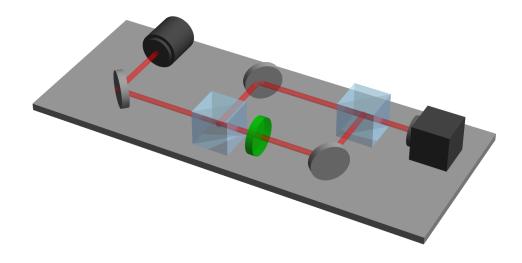
Optical component Library

This library is a free, open collection of designs for sketching diagrams related to laser optics. Each element is defined as a function that can placed in the working space

Mach-Zehnder Interferometer

```
In[185]:=
```

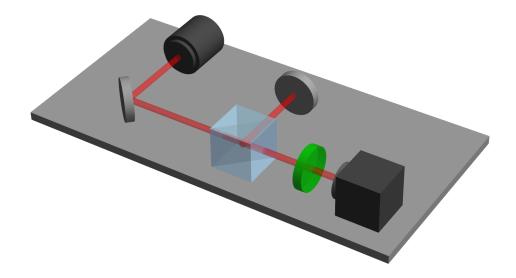
Out[186]=



Michelson Interferometer

```
In[187]:=
       Beam = Graphics3D[{{CapForm["Square"],
             Opacity[0.3], Red, Tube[{{1, 2, 0.5}, {1, 0, 0.5}, {7, 0, 0.5}}, 0.07]},
            {CapForm["Square"], Opacity[0.3], Red, Tube[{{4, 0, 0.5}, {4, 2, 0.5}}, 0.07]}}];
       Show [
        OpticalTable[{9, 4.5}],
        LaserCyl[\{1, 3, 0\}, -\pi/2],
        Beam,
        M[\{0.9, -0.1, 0\}, \pi/4],
        BS[\{4, 0, 0\}, \pi/2],
        QW[{5.5, 0, 0}],
        M[{7,0,0},-\pi/2],
        M[{4, 2.2, 0}, -\pi/2],
        CCD[{7, 0, 0}, \pi], ImageSize \rightarrow 500]
```

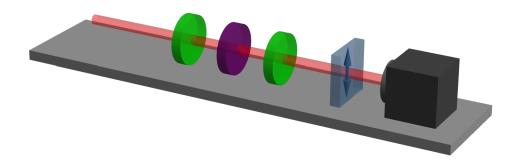
Out[188]=



Retardation measurement

```
In[189]:=
       Beam = Graphics3D[{{CapForm["Square"], Opacity[0.3],
              Red, Tube[\{\{0, 0, 0.5\}, \{6, 0, 0.5\}, \{7, 0, 0.5\}\}, 0.1]\}\}];
       Show [
        OpticalTable[{9, 2.}],
         Beam,
        QW[{2,0,0}],
        HW[{3, 0, 0}],
        QW[{4, 0, 0}],
        Pol[\{5.5, 0, 0\}, \pi/2, \pi/2],
        CCD[{7, 0, 0}, \pi], ImageSize \rightarrow 500]
```

Out[190]=



Functions

In[2]:=

(*Establishes the directory where the notebook is located as the default one*) SetDirectory@NotebookDirectory[];

Color definition

```
NiceBlue = RGBColor[2 / 5, 178 / 255, 1];
In[3]:=
      KnottyBlue = RGBColor[1 / 255, 89 / 255, 185 / 255];
      MexGreen = RGBColor[0, 104 / 255, 71 / 255];
      Pantone2459 = RGBColor[1 / 255, 181 / 255, 174 / 255];
      Pantone218 = RGBColor [206 / 255, 102 / 255, 161 / 255];
      Pantone199 = RGBColor[227 / 255, 56 / 255, 109 / 255];
      Pantone149 = RGBColor[243 / 255, 194 / 255, 66 / 255];
      PantoneProceBlue = RGBColor[63 / 255, 143 / 255, 205 / 255];
      Pantone7664 = RGBColor[104 / 255, 48 / 255, 120 / 255];
```

BasicTools

```
(*Cartesian Axes*)
In[12]:=
       AxisDe = Graphics3D[{(*X-Direction*)
           \{ Opacity [0.6], Blue, Arrowheads [0.1], Arrow [Tube [\{\{0,0,0\}\},\{2,0,0\}\},0.1]] \}, \\
                              (*Z-direction*)
           {Opacity[0.6], Red, Arrowheads[0.1], Arrow[Tube[{{0,0,0}, {0,0,2}}, 0.1]]},
                              (*Y-direction*)
           {Opacity[0.6], Green, Arrowheads[0.1], Arrow[Tube[{{0,0,0}, {0,2,0}}, 0.1]]}},
          ViewPoint → {0.8, 1.5, 0.4}, Boxed → False, Lighting → "Neutral"];
```

Basic Elements

```
(*Basic Plates*)
In[13]:=
       Options[PLATE] = {"Position" \rightarrow {0, 0, 0.5}, "Radius" \rightarrow 0.5,
           "Rotation" \rightarrow {0, 0}, "Length" \rightarrow 0.2, "Color" \rightarrow Gray, "Opacity" \rightarrow 1};
       PLATE[OptionsPattern[]] := Module[{Pos, Len, Col, Op, Rot, Rad},
           {Pos, Len, Col, Op, Rot, Rad} =
            OptionValue[{"Position", "Length", "Color", "Opacity", "Rotation", "Radius"}];
           Graphics3D[{Opacity[Op], EdgeForm[], Col, Cylinder[
               {Pos, Len * {Cos[Rot[2]] Sin[Rot[1]], Sin[Rot[1]] Sin[Rot[2]], Cos[Rot[1]]} + Pos},
               Rad]}, Lighting → "Neutral", Boxed → False]];
        (*Basic Rectangular Element: The entries should be *)
       Options [PRISM] = {"Position" \rightarrow {0, 0, 0}, "Dimensions" \rightarrow {1, 1, 1},
           "Color" \rightarrow Gray, "Opacity" \rightarrow 1, "Rotation" \rightarrow {\pi / 2, 0}};
       PRISM[OptionsPattern[]] := Module[{Pos, Dim, Col, Op, Rot, T},
          {Pos, Dim, Col, Op, Rot} =
           OptionValue[{"Position", "Dimensions", "Color", "Opacity", "Rotation"}];
          Show[Graphics3D[{{Opacity[Op], EdgeForm[], Col,
               T = (Dim[1] \{Cos[Rot[2]], Sin[Rot[2]], 0\} +
                    Dim[2] {-Sin[Rot[2]], Cos[Rot[2]], 0}) / 2;
               Parallelepiped[Pos - T, {Dim[3] {0, 0, 1},
                  Dim[[1] {Cos[Rot[[2]]], Sin[Rot[[2]]], 0}, Dim[[2]] {-Sin[Rot[[2]]], Cos[Rot[[2]]], 0}}]
              }}, Lighting → "Neutral", Boxed → False]]]
```

Basic Beam operations

```
In[17]:=
      Graphics3D[{Opacity[0.3], Darker@Red, EdgeForm[],
         Cone[{{0, -1.0, 0}, {0, -2, 0}}, 0.07]}], Graphics3D[
        {Opacity[0.3], Darker@Red, EdgeForm[], Cone[{{0, -3, 0}, {0, -1.8, 0}}, 0.07]}]
```

Basic Optical Elements

```
(*Optical Table*)
OpticalTable[A_, Thick_ : -.2] := Graphics3D[{EdgeForm[], Gray,
   Parallelepiped[{-1, -1, 0}, {Thick {0, 0, 1}, A[[1]] {1, 0, 0}, A[[2]] {0, 1, 0}}]},
  Lighting → "Neutral", Boxed → False]
(*Mirrors *) (*Still working on the proper alignment*)
M[Position_, Degree_ : 0 ] :=
 PLATE["Position" \rightarrow Position + {0, 0, 0.5}, "Rotation" \rightarrow {\pi / 2, Degree}]
(*Tubular Laser*)
```

```
LaserCyl[Position_, Degree_:0] :=
 Show[PLATE["Position" \rightarrow Position + {0, 0, 0.5}, "Length" \rightarrow 1,
    "Rotation" \rightarrow \{\pi / 2, Degree\}, "Color" \rightarrow Darker@Darker@Gray],
  PLATE["Position" → Position + {Cos[Degree], Sin[Degree], 0.5}, "Length" → 0.1,
    "Radius" \rightarrow 0.4, "Rotation" \rightarrow {\pi / 2, Degree}, "Color" \rightarrow Darker@Darker@Gray]]
(*BoxLaser*)
LaserSquare[Position_, Degree_:0] := Show[PRISM["Position" → Position,
    "Rotation" \rightarrow \{\pi / 2, Degree\}, "Color" \rightarrow Darker[Lighter@Cyan, 0.8]],
  PLATE["Position" → Position + 0.5 {Cos[Degree], Sin[Degree], 1}, "Color" →
     Darker@Darker@Cyan, "Radius" \rightarrow 0.4, "Length" \rightarrow 0.15, "Rotation" \rightarrow {\pi / 2, Degree}]]
(*Beam Splitter*)
BS[Position_, Degree_:0] := Module[{a, b, c, d},
  a = (RotationMatrix[Degree, {0, 0, 1}].#) & /@
     \{\{0.5, -0.5, 1\}, \{0.5, -0.5, 0\}, \{-0.5, 0.5, 0\}, \{-0.5, 0.5, 1\}\};
  b = (# + Position) & /@a;
  c = Graphics3D[{EdgeForm[], Gray, Opacity[0.3], Polygon[b]}];
  d = PRISM["Position" → Position, "Opacity" → 0.4,
     "Rotation" \rightarrow \{\pi / 2, Degree\}, "Color" \rightarrow Lighter@NiceBlue];
  Return[Show[c, d]]]
(*Camera*)
CCD[Position_, Degree_:0] := Show[PRISM["Position" → Position,
    "Rotation" \rightarrow \{\pi / 2, Degree\}, "Color" \rightarrow Darker@Darker@Gray],
  PLATE["Position" → Position + 0.5 {Cos[Degree], Sin[Degree], 1}, "Color" → Darker@Gray,
    "Radius" \rightarrow 0.4, "Length" \rightarrow 0.15, "Rotation" \rightarrow {\pi / 2, Degree}]]
(*Lens*)
Lens [Position_, \alpha_:0] := ParametricPlot3D[
  Position + \{0, 0, 0.5\} + \{0.1 \cos[\alpha] \cos[\theta] \cos[\phi] - 0.5 \cos[\phi] \sin[\alpha] \sin[\theta],
     0.1 \cos[\theta] \cos[\phi] \sin[\alpha] + 0.5 \cos[\alpha] \cos[\phi] \sin[\theta], 0.5 \sin[\phi],
  \{\Theta, 0, \pi\}, \{\phi, 0, 2\pi\}, \text{MaxRecursion} \rightarrow 1, \text{Mesh} \rightarrow \text{None}, \text{Boxed} \rightarrow \text{False},
  PlotStyle → {Lighter@NiceBlue, Opacity[0.5]}, PlotPoints → 50, Lighting → "Neutral"]
(*QWP*)
QW[Position_, Degree_ : 0] := PLATE["Position" → Position + {0, 0, .5},
    "Rotation" \rightarrow \{\pi / 2, Degree\}, "Color" \rightarrow Darker@Green, "Opacity" \rightarrow 0.7];
(*HWP*)
HW[Position_, Degree_ : 0] := PLATE["Position" → Position + {0, 0, .5},
    "Rotation" \rightarrow \{\pi/2, Degree\}, "Color" \rightarrow Darker@Purple, "Opacity" \rightarrow 0.7];
(*Iris*)
Iris[Position_, Degree_:0] :=
  Graphics3D[{Darker[Cyan, 0.8], EdgeForm[], Annulus3D[{Position + {0, 0, 0.5},
        Position + {-0.1 Sin[Degree], +0.1 Cos[Degree], 0.5}}, {0.05, 0.3}]}];
```

```
(*Phase Plate*)
PP[Position_, Degree_ : 0, Color_: Orange] := PLATE["Position" → Position + {0, 0, .5},
   "Rotation" \rightarrow \{\pi / 2, Degree\}, "Color" \rightarrow Darker@Color, "Opacity" \rightarrow 0.7];
(*Polarizer*)
Pol[Position_, \alpha_:0, Degree_:0] := Module[{A, B, C},
  A =
   With[{ra = .03, arhd = .25, arrowtip = Graphics3D[{EdgeForm[], Darker@Darker@NiceBlue,
          Cone[{{0, 0, 0}, {0.15, 0, 0}}, 0.03]}]}, Graphics3D[
      {Darker@Darker@NiceBlue, Arrowheads[{{-arhd, 0, arrowtip}, {arhd, 1, arrowtip}}],
       Arrow[Tube[\{0.15 \{-\cos[\alpha] \cos[\text{Degree}], -\cos[\alpha] \sin[\text{Degree}], -\sin[\alpha]\} +
            {0, 0, 0.5} + Position, Position +
            0.15 {Cos[\alpha] Cos[Degree], Cos[\alpha] Sin[Degree], Sin[\alpha] } + {0, 0, 0.5}}, ra]]}]];
  B = PRISM["Position" \rightarrow Position, "Opacity" \rightarrow 0.4, "Rotation" \rightarrow {\pi / 2, Degree},
     "Color" → Darker@Darker@NiceBlue, "Dimensions" → {1, 0.2, 1}];
  Show [B, A, PlotRange \rightarrow All, Boxed \rightarrow None]
 ]
F1[Position_, F1_] := Graphics3D[
  {Opacity[0.3], Darker@Red, EdgeForm[], Cone[{Position, Position + {F1, 0, 0}}, 0.07]}]
Focusing[Position_, F1_, F1F2_] := Graphics3D[
  {{Opacity[0.3], Darker@Red, EdgeForm[], Cone[{Position, Position + {F1, 0, 0}}, 0.07]},
   {Opacity[0.3], Darker@Red, EdgeForm[],
     Cone[{Position + {F1F2, 0, 0}, Position + {F1, 0, 0}}, 0.07]}}]
```

OptoMechanics

```
XStage[Position ] := Show[
In[30]:=
            PRISM["Position" \rightarrow Position + {0, 0, -0.3},
             "Dimensions" \rightarrow {4, 2.5, 0.1}, "Color" \rightarrow Gray],
            PRISM["Position" \rightarrow Position + {0, 0, -0.1},
             "Dimensions" \rightarrow {3.5, 0.7, 0.05}, "Color" \rightarrow Darker@Gray],
            PRISM["Position" \rightarrow Position + {0, 0, -0.05},
             "Dimensions" \rightarrow {3.5, 0.5, 0.05}, "Color" \rightarrow Darker@Gray],
           Graphics3D[{Lighter@Blue, Arrowheads[{-0.03, 0.03}],
              Arrow[Tube[\{Position + \{-1.5, 0.8, 0.3\}, Position + \{1.5, 0.8, 0.3\}\}, 0.03]\}\}]];
       YStage[Position_] := Show[
            PRISM["Position" \rightarrow Position + {0, 0, -0.3},
             "Dimensions" \rightarrow {2.5, 4, 0.1}, "Color" \rightarrow Gray],
            PRISM["Position" \rightarrow Position + {0, 0, -0.1},
             "Dimensions" → {0.7, 3.5, 0.05}, "Color" → Darker@Gray],
            PRISM["Position" \rightarrow Position + \{0, 0, -0.05\}, "Dimensions" \rightarrow \{0.5, 3.5, 0.05\},
             "Color" → Darker@Gray], Graphics3D[{Lighter@Blue, Arrowheads[{-0.03, 0.03}],
              Arrow[Tube[{Position + {0.8, -1.5, 0.3}, Position + {0.8, 1.5, 0.3}}, 0.03]]}]];
       ZStage[Position_] := Show[
            PRISM["Position" \rightarrow Position + {0, 0, -0.3},
             "Dimensions" \rightarrow {2.5, 4, 0.1}, "Color" \rightarrow Gray],
            PRISM["Position" \rightarrow Position + {0, 0, -0.1},
             "Dimensions" \rightarrow {1.7, 1.7, 0.05}, "Color" \rightarrow Darker@Gray],
            PRISM["Position" \rightarrow Position + \{0, 0, -0.05\}, "Dimensions" \rightarrow \{1.5, 1.5, 0.05\},
             "Color" → Darker@Gray], Graphics3D[{Lighter@Blue, Arrowheads[{-1, 1}],
              Arrow[Tube[{Position + {0.8, 1, 0}, Position + {0.8, 1, 1}}, 0.03]]}]];
       RotStage[Position_] := Graphics3D[{{Darker@Gray, EdgeForm[],
              Cylinder[{Position + {0, 0, 0.25}, Position + {0, 0, 0.15}}, 0.4]},
             {Gray, EdgeForm[], Cylinder[{Position + {0, 0, 0.}, Position + {0, 0, 0.15}}, 0.6]}}];
```

Annulus3D from the Repository

```
ClearAll[Annulus3D]
In[34]:=
      Annulus3D::invpt = "Invalid endpoint specification: ``.";
In[35]:=
      Annulus3D::invrad = "Invalid radius specification: ``.";
      Annulus3D::invang = "Invalid angle specification: ``.";
      Annulus3D::zeroh = "Endpoints coincide.";
      Annulus3D::inout = "The inner radius `` is larger than the outer radius ``.";
      Annulus3D::degdir = "The normal vector `` must
           have non-zero magnitude. Default setting {0,0,1} used instead.";
```

```
preprocessPoint[pt ] := If[TrueQ@Element[pt, Vectors[3, Reals]], N@pt,
In[41]:=
           ResourceFunction["ResourceFunctionMessage"][Annulus3D::invpt, pt];
           $Failed];
       preprocessRadius[rad_] := If[TrueQ@Element[rad, PositiveReals], N@rad,
           ResourceFunction["ResourceFunctionMessage"][Annulus3D::invrad, rad];
           $Failed];
       preprocessAngles [\Theta 1, \Theta 2] := Module [\{anginit = \Theta 1, dang = \Theta 2 - \Theta 1\}, 
           If [AnyTrue [\{\theta 1, \theta 2\}, NotElement [\#, Reals] &],
            ResourceFunction["ResourceFunctionMessage"][Annulus3D::invang, {θ1, θ2}];
            Return[{$Failed, $Failed}]];
           If [dang > 2\pi | | dang < -2\pi, dang = 2\pi];
           If [dang < 0, dang += 2\pi];
           {anginit, dang}
          ];
       annulus2D[rIn_, rOut_, k_, w_, coords_, z_, closed_:False] :=
In[44]:=
        BSplineSurface[Map[TranslationTransform[{0, 0, z}], {rIn coords, rOut coords}, {2}],
          SplineDegree \rightarrow {1, 2}, SplineKnots \rightarrow {{0, 0, 1, 1}, k},
          SplineWeights → {w, w}, SplineClosed → {False, closed}]
       roundSurface[coords_, k_, w_, closed_: False] :=
        BSplineSurface[coords, SplineDegree \rightarrow {1, 2}, SplineKnots \rightarrow {0, 0, 1, 1}, k},
          SplineWeights → {w, w}, SplineClosed → {False, closed}]
       getSpecs[dang_] := Module[{k, w, coords, segment, rest},
In[46]:=
          coords = \{\{1, 0, 0\}, \{1, 1, 0\}, \{0, 1, 0\}, \{-1, 1, 0\},
            \{-1, 0, 0\}, \{-1, -1, 0\}, \{0, -1, 0\}, \{1, -1, 0\}, \{1, 0, 0\}\};
          {segment, rest} = QuotientRemainder[dang, \pi / 2];
          If [segment \geq 4, {segment, rest} = {3, \pi / 2}];
          coords = Join[coords[;; 2 segment + 1], RotationTransform[segment \pi / 2, {0, 0, 1}] /@
              {{1, Tan[rest / 2], 0}, {Cos[rest], Sin[rest], 0}}];
         w = \left\{1, \frac{1}{\sqrt{2}}, 1, \frac{1}{\sqrt{2}}, 1, \frac{1}{\sqrt{2}}, 1, \frac{1}{\sqrt{2}}, 1\right\};
          w = Flatten[{w[;; 2 segment + 1]], Cos[rest / 2], 1}];
           Flatten[{0, 0, 0, Transpose[{Range[segment + 1], Range[segment + 1]}], segment + 1}];
          {k, w, coords}
```

```
In[47]:=
    Annulus3D[] := Annulus3D[\{\{0, 0, -1\}, \{0, 0, 1\}\}, \{1/2, 1\}, \{0, 2\pi\}]
    Annulus3D[r_?NumericQ] := Annulus3D[{{0, 0, -1}, {0, 0, 1}}, {r / 2, r}, {0, 2\pi}]
    Annulus3D[pts:{{__?NumericQ}, {__?NumericQ}}, r_?NumericQ] :=
     Annulus3D[pts, \{r/2, r\}, \{0, 2\pi\}]
    Annulus3D[pts:{{__?NumericQ}, {__?NumericQ}}, r:{_?NumericQ}]:=
     Annulus3D[pts, r, \{0, 2\pi\}]
```

```
Annulus3D[{pt1i:{ ?NumericQ}, pt2i:{ ?NumericQ}},
In[53]:=
          {rIni_?NumericQ, rOuti_?NumericQ}, {ang1i_?NumericQ, ang2i_?NumericQ}] :=
         Module[{pt1 = pt1i, pt2 = pt2i, rIn = rIni, rOut = rOuti, anginit, ann, baseL, baseH,
           circumI, circumO, faces, coords, height, k, w, segment, rest, dang, lastcc, l1, l2},
          (*preprocessing*)
          {pt1, pt2} = preprocessPoint /@ {pt1, pt2};
          {rIn, rOut} = preprocessRadius /@ {rIn, rOut};
          {anginit, dang} = preprocessAngles[ang1i, ang2i];
          If[! FreeQ[{pt1, pt2, rIn, rOut, anginit, dang}, $Failed], Return[{}]];
          height = Norm[pt2 - pt1];
          If[height == 0, ResourceFunction["ResourceFunctionMessage"] [Annulus3D::zeroh];
           Return[{}, Module]];
          If[rOut < rIn,</pre>
           ResourceFunction["ResourceFunctionMessage"][Annulus3D::inout, rIn, rOut]];
          (*weights, knots, coordinates*)
          {k, w, coords} = getSpecs[dang];
          lastcc = Last[coords];
          \{11, 12\} = coords[-1, ;; 2];
          (*net of annulus*)
          (*note: Reverse used to ensure proper normal orientation of all the faces*)
          baseL = annulus2D[rIn, rOut, k, Reverse@w, Reverse@coords, 0, dang = 2\pi];
          baseH = annulus2D[rIn, rOut, k, w, coords, height, dang == 2\pi];
          circumI = roundSurface[
            {rIn coords, TranslationTransform[{0, 0, height}][rIn coords]}, k, w, dang == 2\pi];
          circum0 = roundSurface[{rOut Reverse@coords, TranslationTransform[{0, 0, height}][
               rOut Reverse@coords]}, k, Reverse@w, dang == 2\pi];
          faces = If [dang < 2\pi, {
             Polygon[{{rIn, 0, 0}, {rOut, 0, 0}, {rOut, 0, height}, {rIn, 0, height}}],
             Polygon[{{rIn l1, rIn l2, height},
                {rOut l1, rOut l2, height}, {rOut l1, rOut l2, 0}, {rIn l1, rIn l2, 0}}]
            }];
          (*annulus*)
          ann = {baseL, baseH, circumI, circumO};
          If [dang < 2\pi, ann = Join[ann, faces]];
          MapAt[TranslationTransform[pt1]@*RotationTransform[{{0,0,1},pt2-pt1}]@*
            RotationTransform[anginit, {0, 0, 1}], ann, {All, 1, All}]
      ];
```

```
Annulus3D[pt:{_?NumericQ,_?NumericQ,_?NumericQ}] :=
In[54]:=
       Annulus3D[pt, \{0, 0, 1\}, \{1/2, 1\}, \{0, 2\pi\}]
      Annulus3D[pt: {_?NumericQ, _?NumericQ, _?NumericQ}, r_?NumericQ] :=
       Annulus3D[pt, \{0, 0, 1\}, \{r/2, r\}, \{0, 2\pi\}]
      Annulus3D[pt: {_?NumericQ, _?NumericQ}, _?NumericQ}, r: {_?NumericQ, _?NumericQ}] :=
       Annulus3D[pt, \{0, 0, 1\}, r, \{0, 2\pi\}]
      Annulus3D[pt:{ ?NumericQ, ?NumericQ},
        norm : { _ ?NumericQ, _ ?NumericQ} ] :=
       Annulus3D[pt, norm, \{1/2, 1\}, \{0, 2\pi\}]
      Annulus3D[pt:{_?NumericQ,_?NumericQ,,...?NumericQ},
        norm : {_?NumericQ, _?NumericQ}, r_?NumericQ] :=
       Annulus3D[pt, norm, \{r/2, r\}, \{0, 2\pi\}]
      Annulus3D[pt:{_?NumericQ,_?NumericQ,,...?NumericQ},
        norm : {_?NumericQ, _?NumericQ, _?NumericQ},
        r: \{ ?NumericQ, ?NumericQ \} ] := Annulus3D[pt, norm, r, \{0, 2\pi\}]
```

```
In[60]:=
      Annulus3D[pti:{ ?NumericQ, ?NumericQ}, ?NumericQ},
          normali: { _?NumericQ, _?NumericQ, _?NumericQ},
          {rIni_?NumericQ, rOuti_?NumericQ}, {ang1i_?NumericQ, ang2i_?NumericQ}] := Module[
          {pt = pti, normal = normali, rIn = rIni, rOut = rOuti, anginit, coords, k, w, dang, ann},
          (*preprocessing*)
          {pt, normal} = preprocessPoint /@ {pt, normal};
          {rIn, rOut} = preprocessRadius /@ {rIn, rOut};
          {anginit, dang} = preprocessAngles[ang1i, ang2i];
          If[! FreeQ[{pt, normal, rIn, rOut, anginit, dang}, $Failed], Return[{}, Module]];
          If[rOut < rIn,</pre>
           ResourceFunction["ResourceFunctionMessage"][Annulus3D::inout, rIn, rOut]];
          If [normal = \{0., 0., 0.\},
           ResourceFunction["ResourceFunctionMessage"][Annulus3D::degdir, normal];
           normal = \{0, 0, 1\},\
           normal = Normalize[normal];
          ];
          (*weights, knots, coordinates*)
          {k, w, coords} = getSpecs[dang];
          (*annulus*)
          Switch[normal,
           \{0., 0., 1.\},\
           Null,
           \{0., 0., -1.\},\
           {coords, w} = Reverse /@ {coords, w},
           coords = RotationTransform[{{0, 0, 1}, normal}][coords]
          ann = annulus2D[rIn, rOut, k, w, coords, 0, dang = 2\pi];
          MapAt [
           TranslationTransform[pt]@*RotationTransform[anginit, {0, 0, 1}], ann, {1, All}]
      ];
```