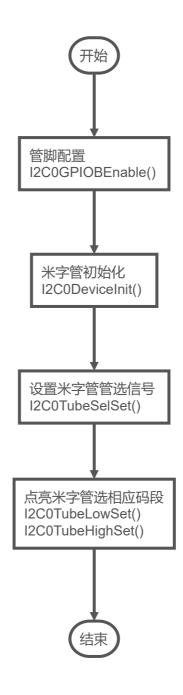
实验五

- 实验目的
 - 1. 了解 I2C 总线的特点和功能。
 - 2. 学会 C 语言模拟 I2C 时序。
 - 3. 学会用 I2C 总线对 PCA9557 芯片进行操作。
- 实验内容
 - 1. 能够点亮并且控制米字管.
 - 2. 能够使用ADC获得温度和电压.
- 实验流程图



• 实验代码

```
ui32SysClock = SysCtlClockFreqSet((SYSCTL_XTAL_25MHZ |
                                     SYSCTL_OSC_MAIN
                                     SYSCTL_USE_PLL |
                                     SYSCTL_CFG_VCO_480),
                                      1000000); //设置系统时间为1MHZ,不能太高,会
   SysCtlPeripheralEnable(SYSCTL_PERIPH_GPIOB);
   GPIOPinTypeI2C(GPIO_PORTB_BASE, GPIO_PIN_2 | GPIO_PIN_3);
   GPIOPinConfigure(GPIO PB2 I2C0SCL);
   GPIOPinConfigure(GPIO_PB3_I2C0SDA);
   GPIOPinTypeI2CSCL(GPIO_PORTB_BASE, GPIO_PIN_2);
   GPIOPinTypeI2C(GPIO_PORTB_BASE, GPIO_PIN_3);
void I2C0DeviceInit(void)
   char dataBuf[2] = {PCA9557_REG_CONFIG, 0x00};
   I2COSend(I2CO_ADDR_TUBE_SEL, dataBuf, 2); //U21管选
   I2COSend(I2CO_ADDR_TUBE_SEG_LOW, dataBuf, 2); //U22
   I2COSend(I2CO_ADDR_TUBE_SEG_HIGH, dataBuf, 2); //U23
void I2C0TubeSelSet(char data)
{
   char dataBuf[2] = {PCA9557_REG_OUTPUT, data};
   I2COSend(I2CO_ADDR_TUBE_SEL, dataBuf, 2);
void I2C0TubeLowSet(char data)
   char dataBuf[2] = {PCA9557_REG_OUTPUT, data};
   I2C0Send(I2C0_ADDR_TUBE_SEG_LOW, dataBuf, 2);
void I2C0TubeHighSet(char data)
{
   char dataBuf[2] = {PCA9557_REG_OUTPUT, data};
   I2C0Send(I2C0_ADDR_TUBE_SEG_HIGH, dataBuf, 2);
void PCA9557_Init(void)
{
   I2COPinConfig();
   I2C0MasterInit();
   I2CSlaveEnable(I2C0_MASTER_BASE);
   I2C0DeviceInit();
}
static const char tubeCodeTable[16][2]=
   {
      0x00, 0x18
                     },
      0x70, 0x2C
      0x70, 0x26 },
       0x60, 0x32
       0x70, 0x16
                       },
       0x70,
              0x1E
                       },
              0x26
       0x70, 0x3E
                      },
```

```
0x3E
        0x60,
        0x70, 0x3E
        0x10, 0x1C
       0x10, 0x3E
       0x60, 0x1C
};
void setnumber(int index,char value)
    switch(value) {
    case '0': {
       a[0]=tubeCodeTable[0][0];
        a[1]=tubeCodeTable[0][1];
       break;
    case '1': {
        a[0]=tubeCodeTable[1][0];
        a[1]=tubeCodeTable[1][1];
       break;
    }
    case '2': {
       a[0]=tubeCodeTable[2][0];
       a[1]=tubeCodeTable[2][1];
       break;
    }
    case '3': {
       a[0]=tubeCodeTable[3][0];
       a[1]=tubeCodeTable[3][1];
       break;
    case '4': {
       a[0]=tubeCodeTable[4][0];
       a[1]=tubeCodeTable[4][1];
       break;
    }
    case '5': {
       a[0]=tubeCodeTable[5][0];
        a[1]=tubeCodeTable[5][1];
       break;
       a[0]=tubeCodeTable[6][0];
       a[1]=tubeCodeTable[6][1];
       break;
    case '7': {
       a[0]=tubeCodeTable[7][0];
       a[1]=tubeCodeTable[7][1];
       break;
    }
    case '8': {
       a[0]=tubeCodeTable[8][0];
        a[1]=tubeCodeTable[8][1];
       break;
    case '9': {
       a[0]=tubeCodeTable[9][0];
       a[1]=tubeCodeTable[9][1];
       break;
    case 'A': {
        a[0]=tubeCodeTable[10][0];
```

```
a[1]=tubeCodeTable[10][1];
    break;
}
case 'B': {
   a[0]=tubeCodeTable[11][0];
   a[1]=tubeCodeTable[11][1];
   break;
case 'C': {
   a[0]=tubeCodeTable[12][0];
    a[1]=tubeCodeTable[12][1];
   break;
}
case 'D': {
   a[0]=tubeCodeTable[13][0];
   a[1]=tubeCodeTable[13][1];
   break;
}
case 'E': {
   a[0]=tubeCodeTable[14][0];
   a[1]=tubeCodeTable[14][1];
   break;
case 'F': {
   a[0]=tubeCodeTable[15][0];
    a[1]=tubeCodeTable[15][1];
   break;
}
case ' ': {
   a[0]=0x10;
   a[1]=0x3E;
   break;
}
}
switch(index)
case(1): {
   I2C0TubeSelSet(~0x20);
   I2C0TubeSelSet(~0x20);
   break;
case(2): {
   I2C0TubeSelSet(~0x02);
   I2C0TubeSelSet(~0x02);
   break;
case(3): {
   I2C0TubeSelSet(~0x04);
   I2C0TubeSelSet(~0x04);
   break;
}
case(4): {
   I2C0TubeSelSet(~0x08);
   I2C0TubeSelSet(~0x08);
   break;
default:
   break;
}
```

```
I2COTubeLowSet(a[0]);
I2COTubeHighSet(a[1]);
}

//测试函数

void PCA9557_Test()
{

while(1)
{

setnumber(1,'C');
delay();
setnumber(2,'D');
delay();
setnumber(3,'E');
delay();
setnumber(4,'F');
delay();
}

}
```

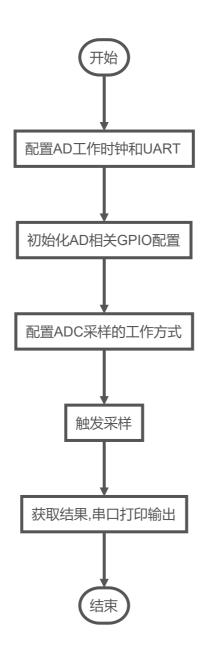
- 实验现象 数码管会依次显示C,D,E,F
- 思考题
 - 1. 以上代码以实现.
 - 2. 以上代码便是用库函数的方式实现的.

实验六

- 实验目的
 - 1. 理解 TM4C1294KCPDT 的 ADC 模块原理。
 - 2. 理解 ADC 如何启动,如何判断 ADC 转换结束。
 - 3. 学会 ADC 模块的设计
- 实验内容

控制ADC0分别从通道0和通道1读取数据,并转化成温度和电压值并输出.

• 实验流程图



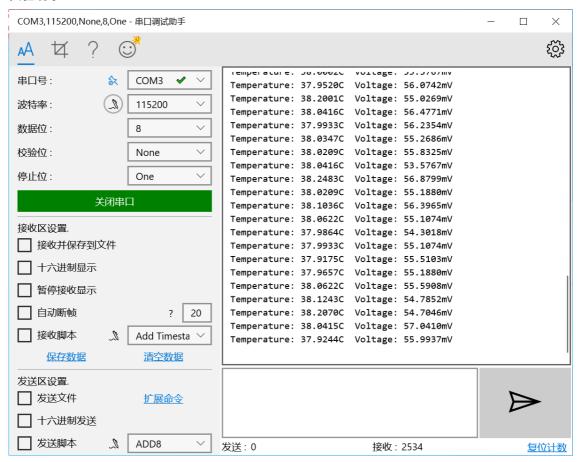
• 实验代码

```
void ADC0_Init()
{
    SysCtlPeripheralEnable(SYSCTL_PERIPH_ADC0);
    SysCtlPeripheralEnable(SYSCTL_PERIPH_GPIOE);
    GPIOPinTypeADC(GPIO_PORTE_BASE, GPIO_PIN_3);
    SysCtlPeripheralEnable(SYSCTL_PERIPH_GPIOD);
    GPIOPinTypeADC(GPIO_PORTD_BASE, GPIO_PIN_7);
    ADCSequenceConfigure(ADC0_BASE, 3, ADC_TRIGGER_PROCESSOR, 0);
    ADCSequenceStepConfigure(ADC0_BASE, 3, 0, ADC_CTL_CH0 | ADC_CTL_END |
ADC_CTL_IE);
    ADCSequenceEnable(ADC0_BASE, 3);
    ADCIntClear(ADC0_BASE, 3);
    ADCSequenceConfigure(ADC0_BASE, 2, ADC_TRIGGER_PROCESSOR, 0);
    ADCSequenceStepConfigure(ADC0_BASE, 2, 0, ADC_CTL_CH4 | ADC_CTL_END |
ADC_CTL_IE);
    ADCSequenceEnable(ADC0_BASE, 2);
    ADCIntClear(ADC0_BASE, 2);
```

```
uint16_t ADC0_Read(int channel)
    uint32_t v;
    switch(channel)
        case (0):
            {
                ADCProcessorTrigger(ADC0_BASE, 3);
                while(!ADCIntStatus(ADC0_BASE, 3, false));
                ADCIntClear(ADC0_BASE, 3);
                ADCSequenceDataGet(ADC0_BASE, 3, &v);
                break;
            }
        case (4):
            {
                ADCProcessorTrigger(ADC0_BASE, 2);
                while(!ADCIntStatus(ADCO_BASE, 2, false));
                ADCIntClear(ADC0_BASE, 2);
                ADCSequenceDataGet(ADC0_BASE, 2, &v);
                break;
            }
    return v;
void ADC0_Test()
    uint16_t adc_value[10];
    float v[10];
    char s[10];
    float temperature[10];
    float temperature_avg,v_avg;
    float temp_sum;
    while(1)
    {
        for(int i=0;i<10;i++)
        {
            adc_value[i] = ADC0_Read(0);
            temperature[i] = (1.8663-((adc_value[i]/4096.0)*3.3))*1000/11.69;
            adc_value[i] = ADC0_Read(4);
            v[i] = adc_value[i]/4096.0*3.3*1000;
        }
        for(int i=0;i<10;i++)
        {
            temp_sum+=temperature[i];
        temperature_avg = temp_sum/10;
        temp_sum = 0;
        for(int i=0;i<10;i++)</pre>
        {
            temp_sum+=v[i];
        v_avg = temp_sum/10;
        temp_sum = 0;
        sprintf(s,"Temperature: %.41fC Voltage:
%.41fmV\n",temperature_avg,v_avg);
        UARTprintf(s);
```

}

• 实验现象



• 思考题

温度的已经实现了,然后使用定时器中断定时采样温度,并用数码管显示的代码如下

```
void TimerOBIntHandler(void)
{ //volatile uint32_t i;
    unsigned long Status;
    TimerDisable(TIMER0_BASE, TIMER_B);
    Status=TimerIntStatus(TIMER0_BASE, true);
    if(Status==TIMER_TIMB_TIMEOUT)
            float v;
            char s[4];
            v = (1.8663-((ADCO_Read(0)/4096.0)*3.3))*1000/11.69*100;
            sprintf(s,"%4d",(int)v);
            int t = 20000000;
            SysCtlDelay(t);
            setnumber(1,s[0]);
            SysCtlDelay(t);
            setnumber(2,s[1]);
            SysCtlDelay(t);
            setnumber(3,s[2]);
            SysCtlDelay(t);
```

```
setnumber(4,s[3]);

SysCtlDelay(t);

}
TimerIntClear(TIMER0_BASE, Status);
TimerLoadSet(TIMER0_BASE, TIMER_B, g_ui32SysClock/10000 );
TimerEnable(TIMER0_BASE, TIMER_B);
}
```