

The background features a dark blue gradient with faint, light blue circular patterns. These patterns include concentric circles and arcs with degree markings (e.g., 40, 150, 160, 170, 180, 190, 210, 220, 230, 240, 250, 260) and arrows, suggesting a technical or engineering theme.

GNSS MEASUREMENT ENGINE SYSTEM DESIGN: COMMUNICATION ENGINEERING PERSPECTIVES

SHU WANG, FOUNDER

ERLANG NETWORK BRINGS A NEW DIMENSION INTO GNSS POSITIONING ENGINEERING

- We combine professional grade satellite positioning, DSP & Big Data techniques together with cloud computing.
 - High-performance satellite positioning based on cloud computing is fundamental for IoT location based services
- The salient features include:
 - **instant response (cold start less than 1s),**
 - **improved accuracy (10x),**
 - **increased sensitivity (10x),**
 - **reduced BOM (40%),**
 - **higher power efficiency (90%),**
 - **OTA upgradable**
 - And, of course, enhanced security and privacy.
- Our technology can replace or be complementary to existing device-based GPS solutions.
- All these are essential to and highly demanded by many 5G, logistic, IoT, children safety and senior care services

KEY GNSS MEASUREMENT ENGINE DESIGN PARAMETERS

1. **Sensitivity and Link Budget**

- a signal processing perspective. Link budget and mutual coupling between receiver and transmitter
- an information theory perspective. communication in low-SNR region.

2. **Accuracy (Error) Budget**

- spatial channel models

3. **Battery Life and Energy (Power) Budget**

- comprehensive energy modelling

LINK BUDGET AND EXAMPLES: GPS, LTE AND OTDOA

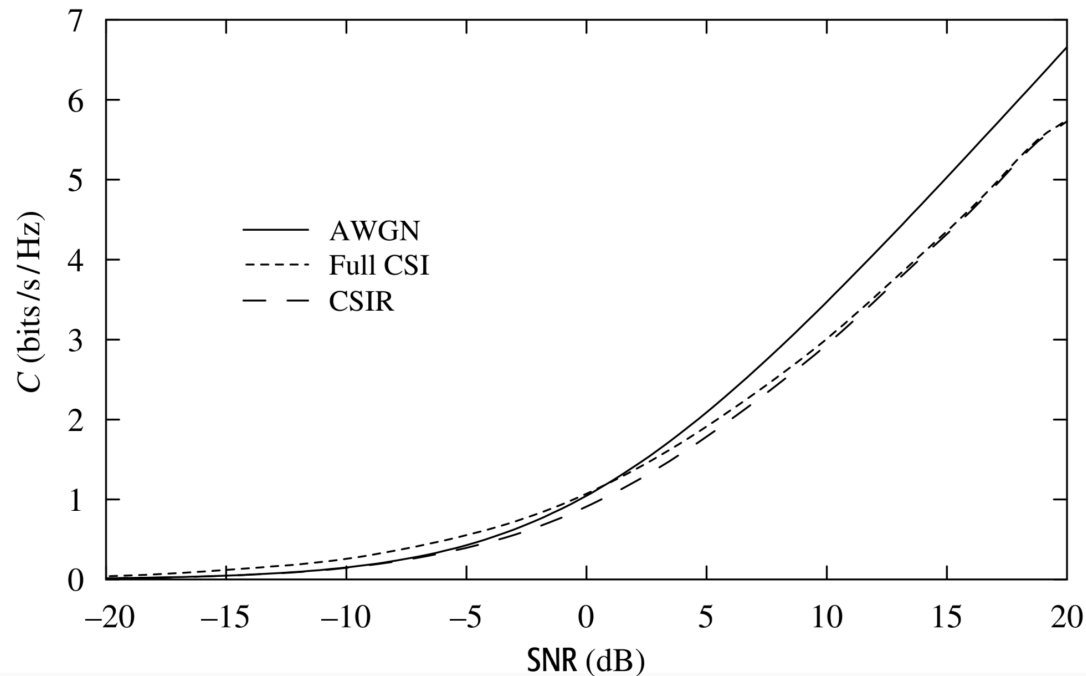
Parameter	GPS	LTE, 10MHz	LTE OTDOA	Comment
Transmitter Power	44.3 dBm	typical 46 dBm	additional power boost	
Transmitter Antenna Gain and Cable Loss	10.2~12.3 dBi	16 dBi		
Target Propagation Path-Loss	183 ~ 189.8 dB	e.g., 3GPP TS 25.996 modified COST231		
Cochannel Interference Margin		3 dB		Margin for inter-cell interference when the device is on the cell edge.
Fast Fading Margin		4 dB		Typically it is set to be about 4 dB.
Antenna Efficiency		4.7 dB		
RFIC Noise Figure		2.8 dB		
Thermal Noise Floor		107.3 dBm		
Body Loss				usage model dependent

GNSS MEASUREMENT ENGINE: A SIGNAL PROCESSING PERSPECTIVE

	Reference	ULPC Mode	HP Mode	
Signal Power at antenna port	-150			dBm
C/N0 at IF	23.9 = - 150 + 173.9			dB-Hz
IF Bandwidth	3.0			MHz
IF SNR	-40.9 = -150 - (-109.1)			dB
	Coherent Processing			
Sample Rate	2.046	4.092	4.092	MHz
Ideal Coherent Gain	43.5	46.5	54.7	dB
Implemt. Losses	-3.1	-3.5	-1.6	dB
Actual Coherent Gain	40.5	44.1	54.1	dB
SNR	-0.43	3.18	16.22	dB
	Non-Coherent Processing			
Squaring Loss	-1.69	0.93	5.1	dB
Processing Gain	45	45	25	
Non-coherent Gain	19.6	19.6	16.6	dB
Final SNR	14.3	16.5	22.0	dB

Shu Wang & Erlang Network, 2017~2019, All Rights Reserved

LOW SNR REGIME: A INFORMATION THEORY PERSPECTIVE (1/2)



$$C = \mathbb{E}[\log(1 + |h|^2 \text{SNR})] \approx \mathbb{E}[|h|^2 \text{SNR}] \log_2 e = \text{SNR} \log_2 e \approx C_{\text{awgn}}$$

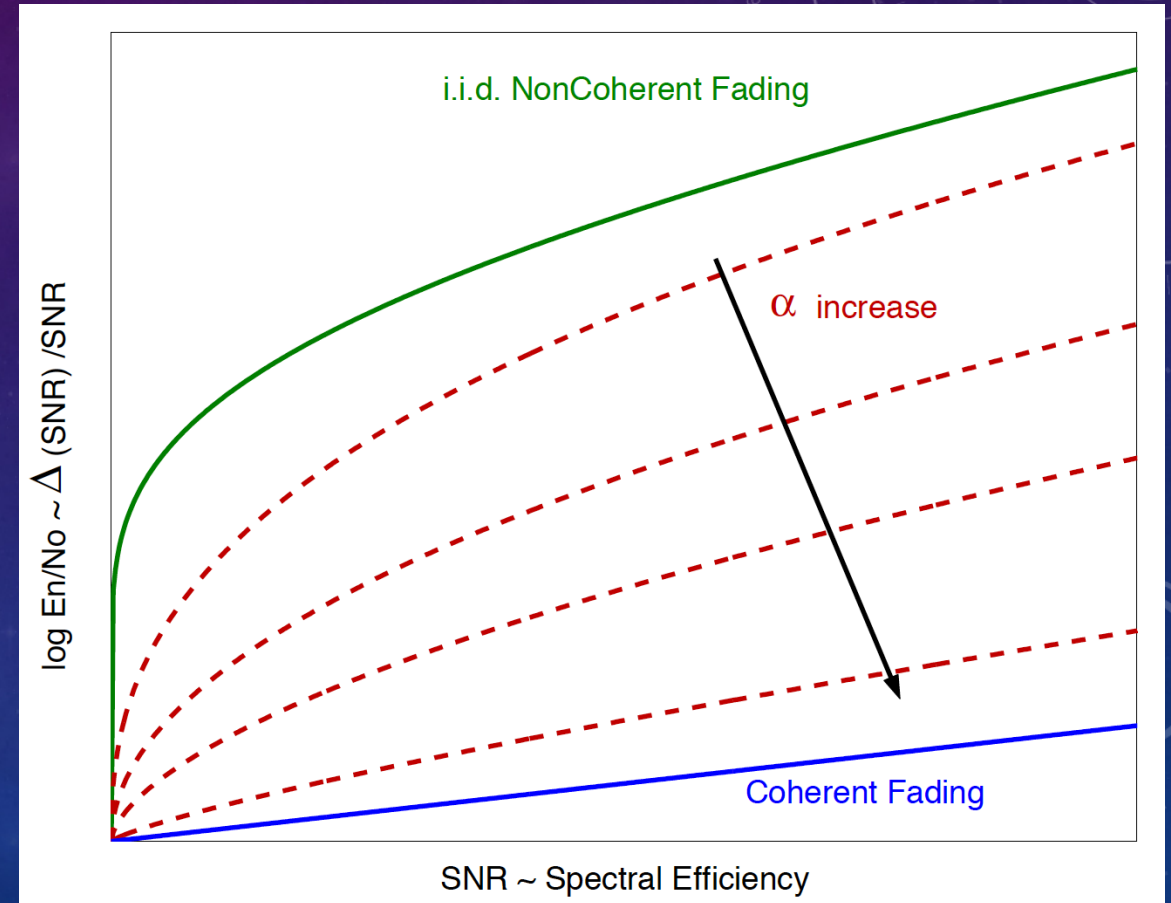
D. Tse and P. Viswanath, *Fundamentals of Wireless Communication*, Cambridge University Press, 2005

- At low SNR regime, the Jensen's loss becomes negligible and the capacities become approximately linear.
 - The reliable rate supported by the AWGN channel is much more sensitive to the received SNR at low SNR than at high SNR
- At low SNR regime, the impact of fading is very significant.
 - For reasonably small outage probabilities, the outage capacity is only a small fraction of the AWGN capacity at low SNR

LOW SNR REGIME: A INFORMATION THEORY PERSPECTIVE (2/2)

$$\lim_{\text{SNR} \rightarrow 0} \frac{C_{\text{fading}}(\text{SNR})}{\text{SNR}} = \lim_{\text{SNR} \rightarrow 0} \frac{C_{\text{AWGN}}(\text{SNR})}{\text{SNR}} = 1$$

- Bad News: “Channel capacity in the limit of vanishing SNR per degree of freedom is known to be linear in SNR for fading and non-fading channels, regardless of channel state information at the receiver (CSIR).”
- Good News: “although a near linear capacity can be achieved in both cases eventually at low enough SNR, this limit is approached much more slowly for the non-coherent case.”



ERROR SOURCES FOR OTDOA SYSTEMS

Error Sources	GNSS Positioning	LTE OTDOA
transmitter clock	1.5 m	15 m
transmitter antenna coordinate error or satellite orbit error	2.5 m	< 3 m
ionospheric & tropospheric delays	5.5 m	N/A
signal measurement accuracy	0.3 m	40 m when SINR > -13 dB
multipath excess delay	0.6 m	30 m in suburban
GDOP		0.9

ACCURACY BUDGET EXAMPLE

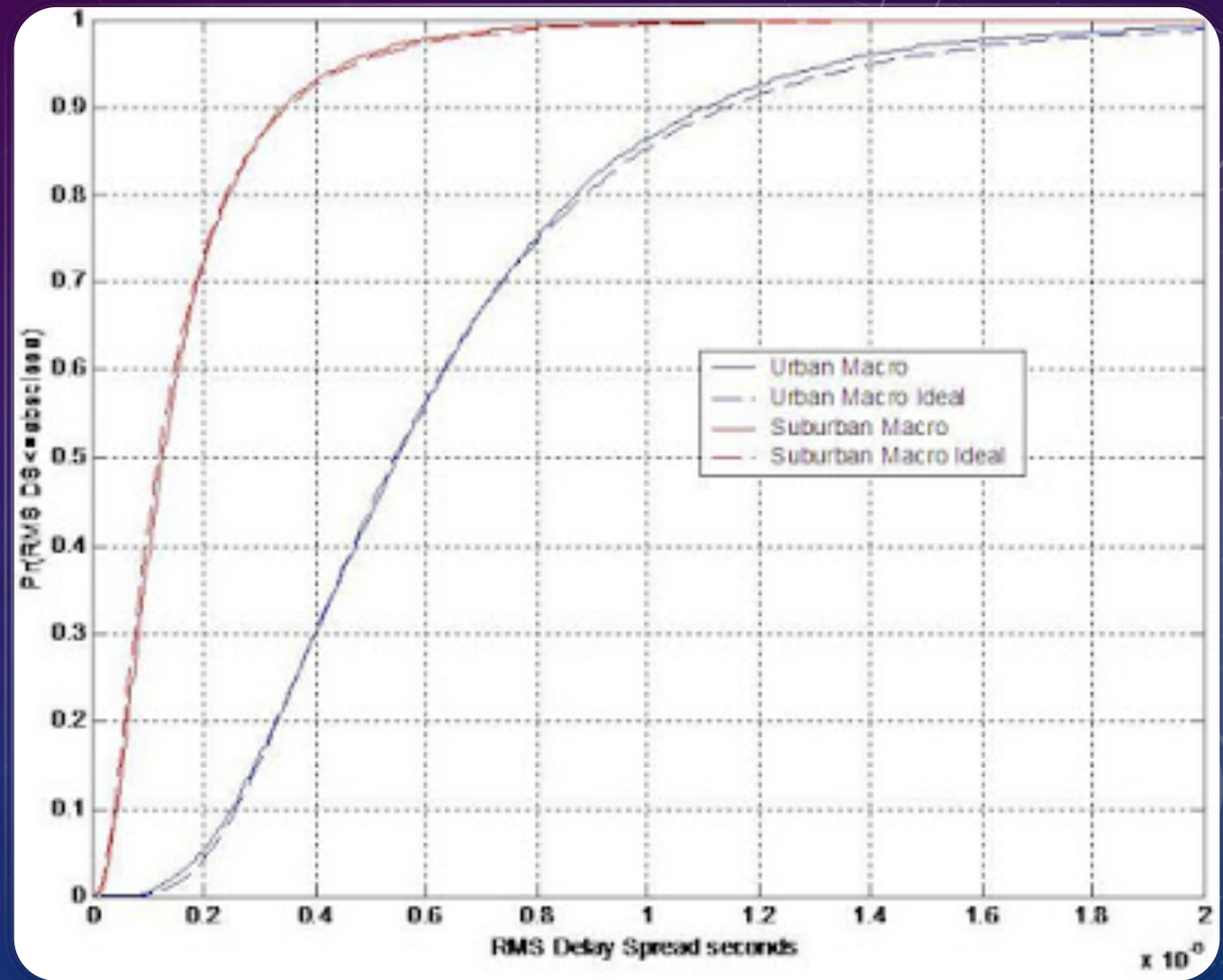
Error Sources	Absolute GPS		Differential GPS	
	P Code	L1 C/A Code	P Code	C/A Code
Satellite Clock & Ephemeris Errors	3.9	3.9	0	0
Ionospheric Delay	3.1	9	0	0
Tropospheric Delay	2.0	2.0	0.15	0.15
Receiver Noise and Resolution	1.1	11.1	1.1	11.1
Multipath	1.2	12	1.2	12
Other			0	0
*Selective Availability		30	0	0
Total System Error 1σ	5.6	35.6	1.3	16
Position Error PDOP = 2.92	16.3 m	104 m	3.8 m	48 m

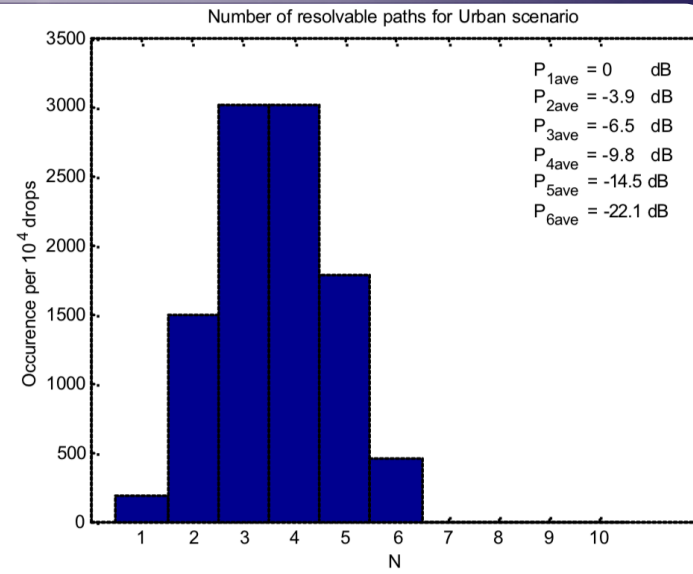
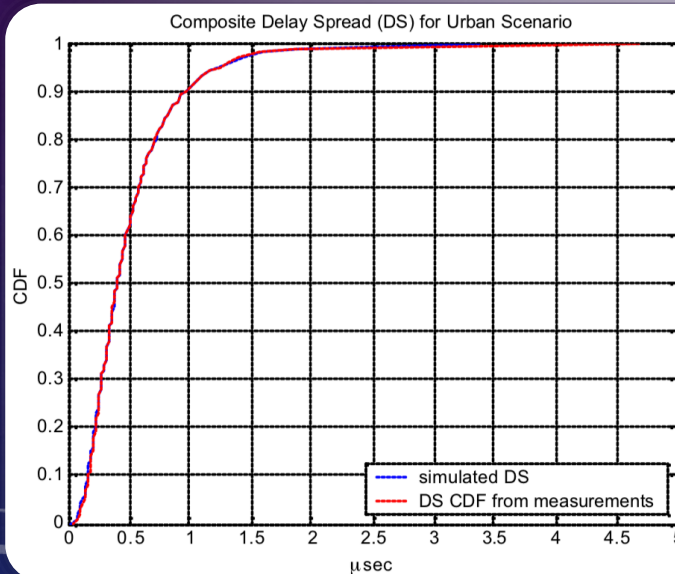
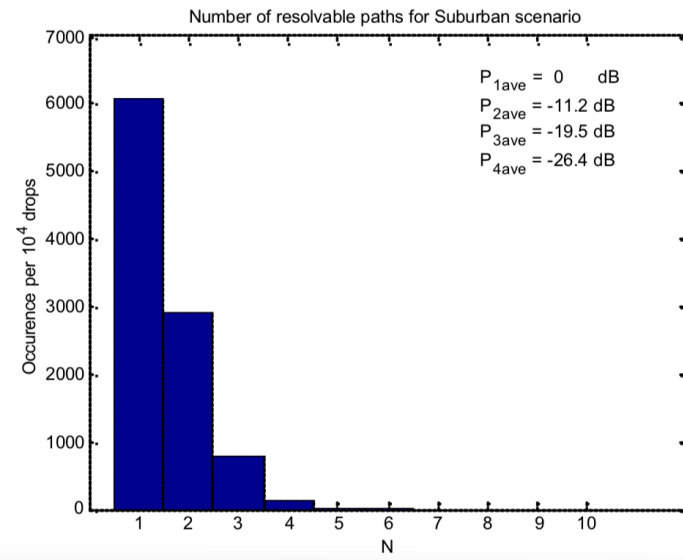
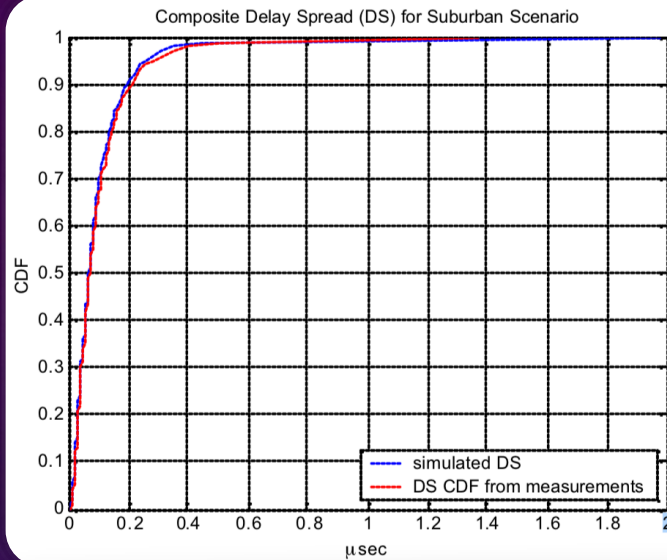
R. M. Kalafus, Vilcans, N. Knable, "Differential operation of Navstar GPS", Navigation Vol. 30, No. 3, 1983

MULTIPATH DELAY SPREAD

- In [1], Sousa, et. al., reported the 90th percent rms delay spread to be $1.2 \mu\text{s}$ in suburban Toronto.
- In [2], Ling, et. al. observed that the 90th percent rms delay spread was $1.7 \mu\text{s}$ in Lakehurst NAES, New Jersey.
- In [3], Baum reported the 77th percent rms delay spread was $1 \mu\text{s}$, the 94th percent rms delay spread was $2 \mu\text{s}$ in Rolling Meadows, Chicago.

- [1] E. Sousa, V. Jovanovic, C. Daigneault, "Delay spread measurements for the digital cellular channel in Toronto", IEEE Trans. on Vehicular Technology, Nov 1994
- [2] J. Ling, D. Chizhik, D. Samardzija, R. Valenzuela, "Wideband and MIMO measurements in wooded and open areas", Lucent Bell Laboratories,
- [3] K. Baum, "Frequency-Domain-Oriented Approaches for MBWA: Overview and Field Experiments", Motorola Labs, IEEE C802.20-03/19, March 2003



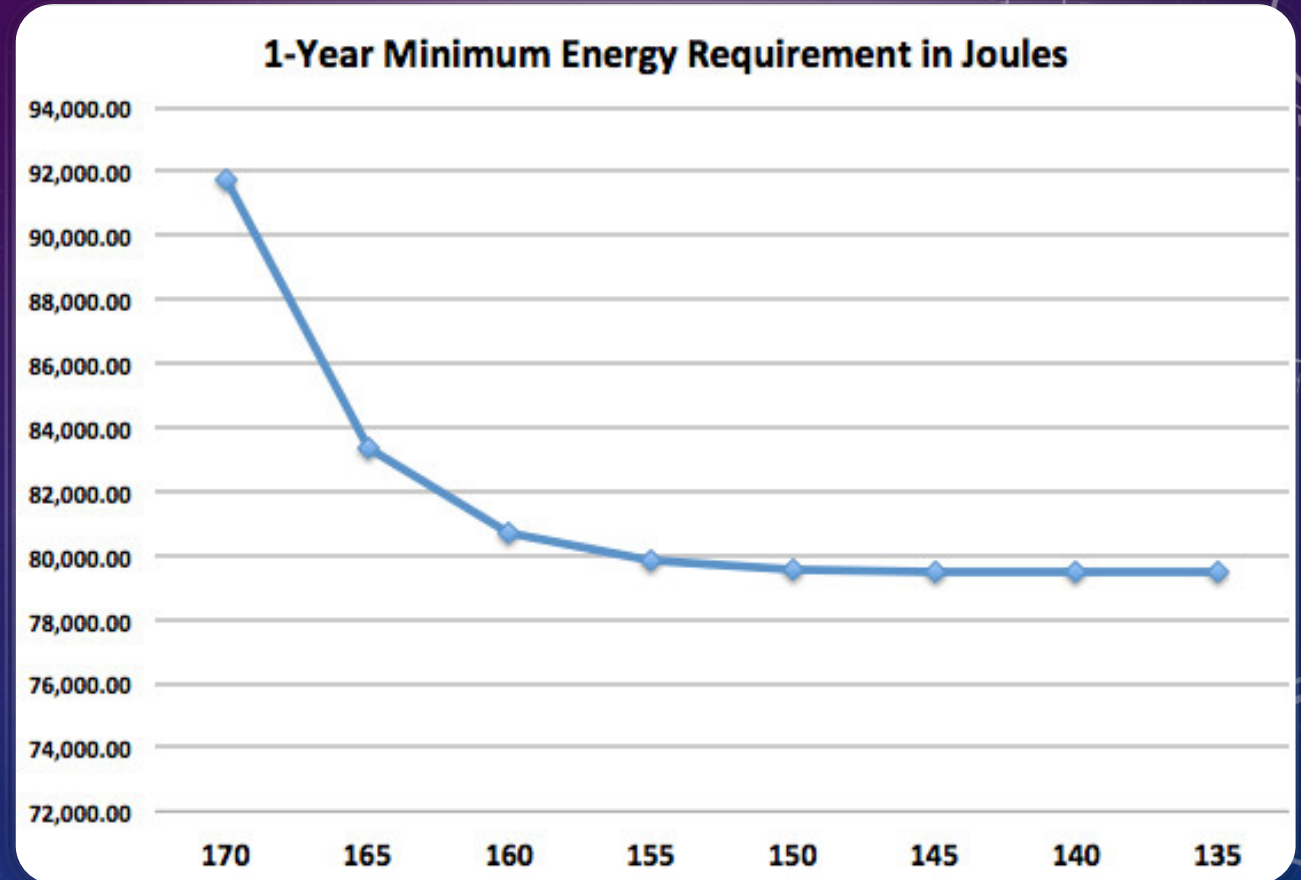


STATISTICS FOR 3GPP/3GPP2 MACRO CHANNELS

- 3GPP & 3GPP2 system level assumptions
- The Chip rate is 3.84Mcps.
- Only the paths with power higher than -15dB relative to the strongest path are recorded.
- The shown statistics are the non-power weighted ones

ENERGY BUDGET

- Energy Budget models how much energy is consumed in each stage of the total process, particularly considering L1 signal processing and L2 protocol stack.
- It is no surprising that for many wireless system, there are tradeoffs between energy budget and link budget, sensitivities, response time, battery life, etc.



EXAMPLE: LTE STATE MACHINE FOR ENERGY MODELLING AND BATTERY LIFE ESTIMATION



Parameters ▼	Values ▼	Unit
Number of PDSCH subpackets	3.00	
Transmission and Reception Time per PDSCH subpacket	1.00	mili-second;
PDSCH Decoding Time Per subpacket	0.0714	milli-second; 1 LTE subframe
ACK/NAK delay per subpacket	3.00	mili-second;
NAK/ACK Transmission Time per subpacket	1.00	mili-second;
Subsquential Subpack Transmission Delay	3.00	mili-second;
Total Reception, Decoding and Acknowledging Time	21.00	mili-second;
Energy Consumption per Paging Message (PDSCH) Reception, Decoding and Acknowledging	5,615.21	micro-joule;
Time interval Per PRS Power Measurement	2.00	subframes
Number of Cells	5.00	
Energy Consumption per OTDOA Measuremet	3,222.00	micro-joule; (XO+SX+RFIC+BB) x Measuring Interval
Total Energy Consumption per OTDOA Fix	54,260.00	micro-joule;

ENERGY MODELLING EXAMPLE

- GPS RF Power: 39.6 mw
- Deep-Sleep: 25 uw
- Micro-Sleep (XOSC+RSX+CLCKGEN): 44.6 mw
- Active (XOSC+RSX+CLCKGEN+1xRx): 101.4 mw
- BBIC PLL Power: 0.5 mw
- BBIC PLL warm-up: 3ms
- LTE Baseband: 200 mw
- Tx PA: 1000 mW in average
- Battery: shelf time, engineering loss, power supply efficiency, headroom, etc.



THANK YOU VERY MUCH FOR YOUR TIME!