



STEAM VR™

Tracking Training



STEAM®VR
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Extracting Sensor Data from 3D CAD

Introduction

- Creating a JSON file is an important part of the sensor placement process
- Manual creation of JSON files
 - Good for prototyping
 - Easy to use when the number of sensors is small
 - Time consuming
 - Error prone
- Automated creation of JSON files
 - Eliminates most human error
 - Fast
 - Difficult to work with universal file types (STEP, X_T, IGES, etc)
 - Program likely needs to be written for each CAD package

Creating a JSON for hmd_designer

- Location of sensor centroid
 - x, y, and z parameters determine position
 - Expressed in meters
- Sensor orientation
 - Vector that has a direction indicating the center of the sensor viewing area
 - Unit vector with length of 1
- Channel map not required. Can be added though if specific sensor identifiers are desired.

"modelPoints":

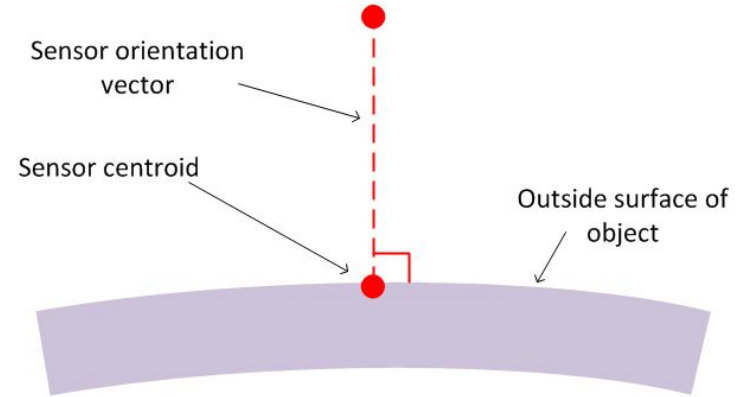
```
[0.08443813, -0.06550000, -0.06255000],  
[0.08443813, 0.00550000, -0.03507779],  
[-0.08443813, 0.00550000, -0.03507779],  
[0.03084635, 0.06003408, -0.03674775],  
[-0.03084635, 0.06003408, -0.03674775],  
[0.02082437, -0.11914293, -0.03720147],  
[-0.02082437, -0.11914293, -0.03720147],  
[0.09115339, -0.00009119, -0.01947069],  
[0.07734485, 0.00550000, -0.00362941],  
[0.07711887, 0.04135413, -0.00315314],  
[0.07711887, 0.04135413, -0.00315314]
```

"modelNormals":

```
[0.00000000, 0.00000000, -1.00000000],  
[0.54350384, 0.00000000, -0.83940668],  
[-0.54350384, 0.00000000, -0.83940668],  
[0.00000000, 0.45371886, -0.89114488],  
[0.00000000, 0.45371886, -0.89114488],  
[0.00000000, -0.45371886, -0.89114488],  
[0.00000000, -0.45371886, -0.89114488],  
[1.00000000, 0.00000000, 0.00000000],  
[0.54350384, 0.00000000, 0.83940668],  
[0.87857711, 0.44703810, 0.16810472],  
[0.87857711, 0.44703810, 0.16810472]
```

Manual Extraction from 3D CAD

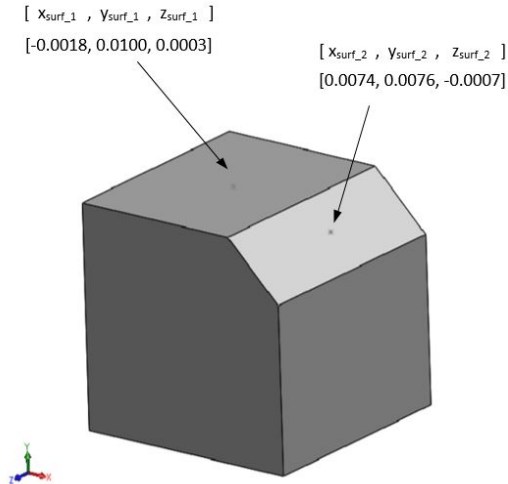
- Indicate the location of the sensor centroid
 - Need to be able to measure the absolute position of the centroid relative to the origin
 - A point usually works well
 - Usually on outside surface of part
- Indicate the direction the sensors are facing
 - Extend a line from the sensor centroid point in the desired direction
 - Line is usually perpendicular to the surface
 - Length of line not important



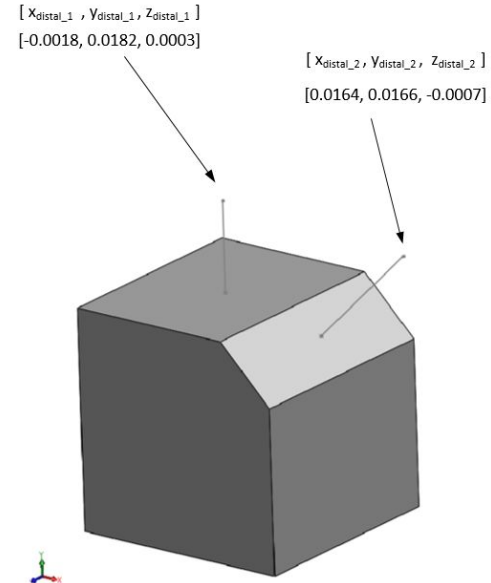
Manual Extraction from 3D CAD

- Measure the absolute positions

Sensor centroids



End of sensor orientation line



Manual Extraction from 3D CAD

- Calculate the normalized vector components for the orientation line

$$x_{normal} = \frac{x_{distal} - x_{surf}}{\sqrt{(x_{distal} - x_{surf})^2 + (y_{distal} - y_{surf})^2 + (z_{distal} - z_{surf})^2}}$$

$$y_{normal} = \frac{y_{distal} - y_{surf}}{\sqrt{(x_{distal} - x_{surf})^2 + (y_{distal} - y_{surf})^2 + (z_{distal} - z_{surf})^2}}$$

$$z_{normal} = \frac{z_{distal} - z_{surf}}{\sqrt{(x_{distal} - x_{surf})^2 + (y_{distal} - y_{surf})^2 + (z_{distal} - z_{surf})^2}}$$

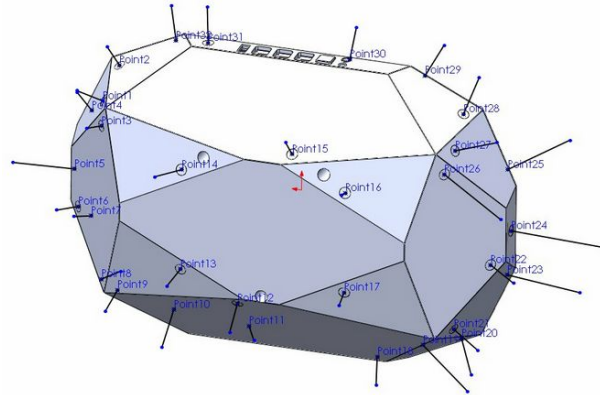
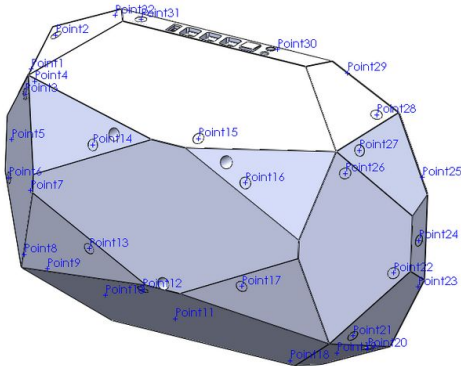
- Enter the centroid locations and normalized orientation vector components into JSON file

```
"modelPoints" : [  
  [ xsurf_1, ysurf_1, zsurf_1 ],  
  [ xsurf_2, ysurf_2, zsurf_2 ]  
]
```

```
"modelNormals" : [  
  [ xnormal_1, ynormal_1, znormal_1 ],  
  [ xnormal_2, ynormal_2, znormal_2 ]  
]
```

Automated Extraction from Solidworks

- Add macro to Solidworks
- Create a 3D Sketch
 - Indicate sensor centroid with sketch points
 - Indicate the sensor orientation with a sketch segment
 - Make the sketch segment normal to the face



Automated Extraction from Solidworks

- Save the Solidworks file
- Select 3D Sketch in the Feature Tree and run the macro
- A JSON file will be created with the same name as the Solidworks file and in the same directory

```
1 {
2   "modelNormals" : [
3     [0.851651, 0.39713126, -0.34202014],
4     [0.397131, 0.85165074, -0.34202014],
5     [0.707107, 0, -0.70710678],
6     [0.742404, 0.34618861, 0.57357644],
7     [0.396195, 0, -0.08715574],
8     [0.707107, 0, -0.70710678],
9     [0.742404, -0.34618861, 0.57357644],
10    [0.851651, -0.39713126, -0.34202014],
11    [0.397131, -0.85165074, -0.34202014],
12    [0.346189, -0.74240388, 0.57357644],
13    [0, -0.81915204, 0.57357644],
14    [0, -0.70710678, -0.70710678],
15    [0.11399, -0.22798078, -0.96696999],
16    [0.11399, 0.22798078, -0.96696999],
17    [0, 0.70710678, -0.70710678],
18    [-0.11399, 0.22798078, -0.96696999],
19    [-0.11399, -0.22798078, -0.96696999],
20    [0, -0.9961947, -0.08715574],
21    [-0.346189, -0.74240388, 0.57357644],
22    [-0.397131, -0.85165074, -0.34202014],
23    [-0.851651, -0.39713126, -0.34202014],
24    [-0.707107, 0, -0.70710678],
25    [-0.742404, -0.34618861, 0.57357644],
26    [-0.396195, 0, -0.08715574],
27    [-0.742404, 0.34618861, 0.57357644],
28    [-0.707107, 0, -0.70710678],
29    [-0.851651, 0.39713126, -0.34202014],
30    [-0.397131, 0.85165074, -0.34202014],
31    [-0.346189, 0.74240388, 0.57357644],
32    [0, 0.81915204, 0.57357644],
33    [0, 0.9961947, -0.08715574],
34    [0.346189, 0.74240388, 0.57357644]
35  ],
36  "modelPoints" : [
37    [0.099116, 0.05094458, -0.03741659],
38    [0.096753, 0.06424891, -0.01789139],
39    [0.09661, 0.04056914, -0.04681386],
40    [0.116967, 0.03007791, -0.00365902],
41    [0.122949, 0, -0.01464239],
42    [0.116037, -0.01576068, -0.02788716],
43    [0.116967, -0.03007791, -0.00365902],
44    [0.099116, -0.05094458, -0.03741659],
45    [0.096753, -0.06424891, -0.01789139],
46    [0.069937, -0.07703236, -0.00365997],
47    [0.027612, -0.08031133, -0.00368459],
48    [0.015, -0.04486129, -0.05856297],
49    [0.045931, -0.02837947, -0.06181439],
50    [0.04593, 0.02837947, -0.06181439],
51    [-0.015, 0.04486129, -0.05856297],
52    [-0.045931, 0.02837947, -0.06181439],
53    [-0.04593, -0.02837947, -0.06181439],
54    [-0.048124, -0.08297038, -0.01439971],
55    [-0.069937, -0.07703236, -0.00365997],
56    [-0.096753, -0.06424891, -0.01789139],
57    [-0.099116, -0.05094458, -0.03741659],
58    [-0.116995, -0.01569321, -0.02742963],
59    [-0.116967, -0.03007791, -0.00365902],
60    [-0.122949, 0, -0.01464239],
61    [-0.116967, 0.03007791, -0.00365902],
62    [-0.09661, 0.04056914, -0.04681428],
63    [-0.099116, 0.05094458, -0.03741659],
64    [-0.096753, 0.06424891, -0.01789139],
65    [-0.069937, 0.07703236, -0.00365997],
66    [-0.027612, 0.08031133, -0.00368459],
67    [-0.048124, 0.08297038, -0.01439971],
68    [0.069937, 0.07703236, -0.00365997]
69  ]
70 }
```

JSON File Verification

- Open the JSON to verify it was built correctly
 - Confirm there is a modelNormals section
 - Confirm there is a modelPoints section
 - Make sure there are no null vectors in the modelNormals array
 - Make sure the number of elements in each array is the same
- Visualize in hmd_designer
 - Export 3D object as an STL file
 - Load STL and JSON into hmd_designer
 - Confirm the sensors are in the correct position
 - Make sure the green sensor face is oriented outwards