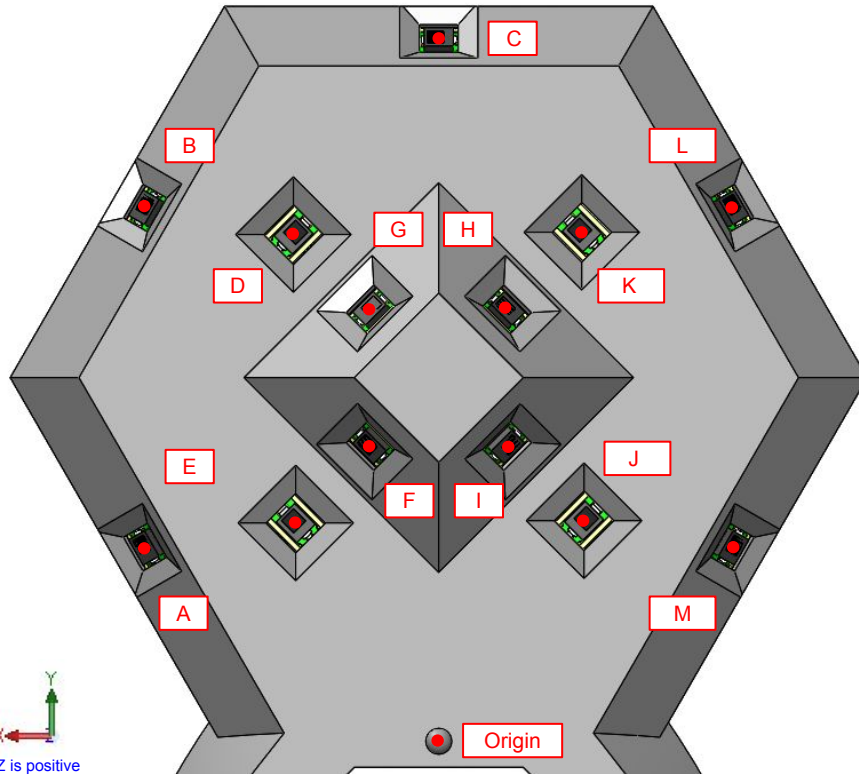
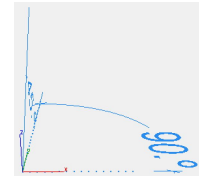


# Class Exercise

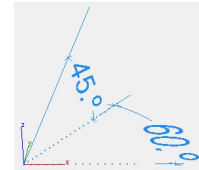


Point	X-location (mm)	Y-location (mm)	Z-location (mm)
Origin	0	0	0
A	45.245	29.8776	6.71967
B	45.245	82.1224	6.71967
C	0	108.2448	6.71967
D	22.386	78.03215	1.75
E	22.032	33.6143	1.75
F	10.523	45.47702	-3.85659
G	10.523	66.52298	-3.85659
H	-10.532	66.52298	-3.85659
I	-10.523	45.47702	-3.85659
J	-22.386	33.96785	1.75
K	-22.032	78.3857	1.75
L	-45.245	82.1224	6.71967
M	-45.245	29.8776	6.71967

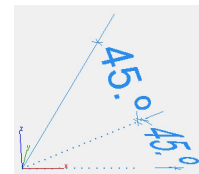
## Unit Vectors Reference



$$(0, \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$$



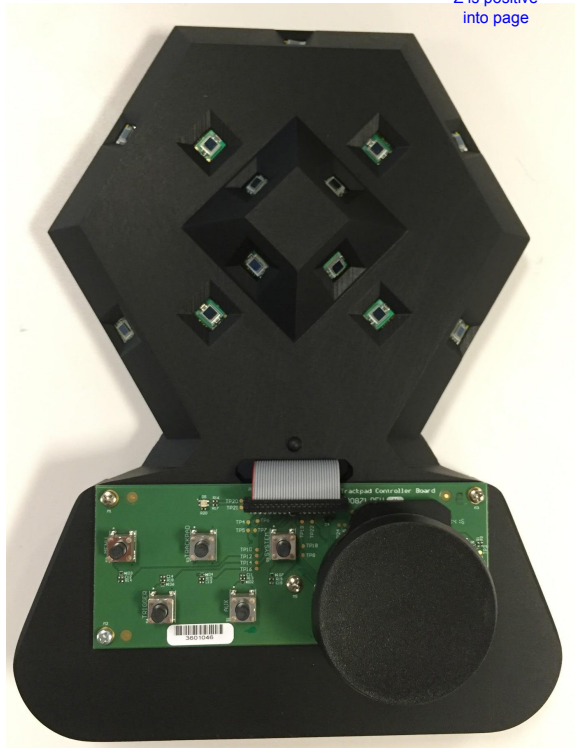
$$(\frac{\sqrt{3}}{2\sqrt{2}}, \frac{1}{2\sqrt{2}}, \frac{1}{\sqrt{2}})$$



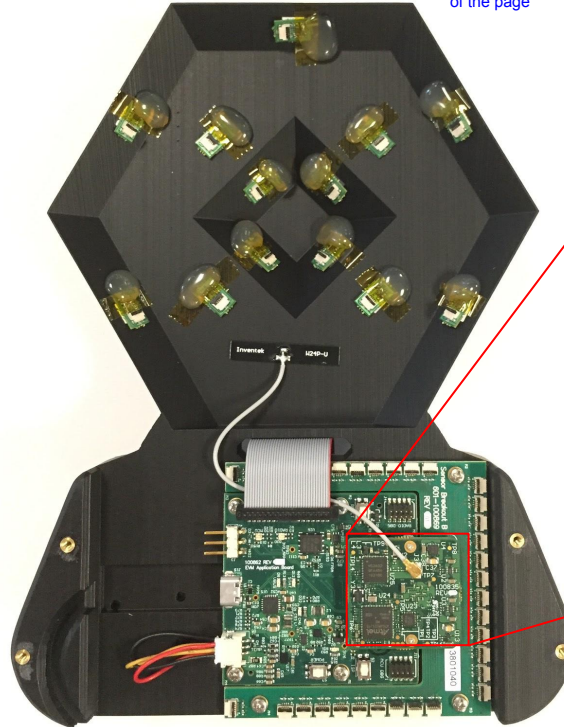
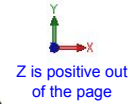
$$(\frac{1}{2}, \frac{1}{2}, \frac{1}{\sqrt{2}})$$

# Class Exercise

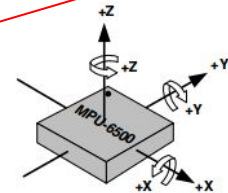
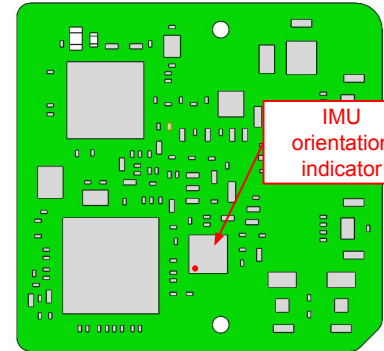
Top View



Bottom View



Point	X-location (mm)	Y-location (mm)	Z-location (mm)
IMU	28.385	-48.040	17.178



IMU orientation from Invensense MPU-6500 datasheet