

# Buildroot for cross-compiling GNU Radio to embedded boards

May 26, 2020

The Raspberry Pi{3,4} (RPI) is a single board computer designed – for the characteristics we are interested in for Software Defined Radio applications – around a quad-core ARM processor clocked at 1.5 GHz with 1, 2 or 4 GB random access memory. The operating system is stored on a microSD card and is hence easily updated from the host computer (never *ever* compile on the target embedded board). Generating a dedicated toolchain – as opposed to using a readily available binary distribution – allows for optimizing instructions for the chipset available on the targeted platform.

Our objective is to **execute GNU Radio on the RPi** in order to run some pre-processing on the embedded board before sending the processing result to the PC (e.g. receiving a broadcast FM station on the RPi and send the audio output to the PC through a Zero-MQ link).

## 1 Buildroot for RPi

Buildroot is a framework providing a consistent set of

- cross-compilation toolchain for the host (usually Intel x86/AMD64 processor)
- libraries and userspace applications for the ARM target,
- Linux kernel for the target,
- bootloader for embedded target board initialization in order to load the Linux kernel in charge of supervizing userspace applications.

This consistency avoids many pitfalls when cross-compiling target applications or kernel modules on the host. Obviously the low-computational power target is *not* designed for intensive computational load such as compiling GNU Radio, and `gcc` should actually not even be available on the target, neither is the SD card with its finite number of write cycles designed for large compilation (at least make `/tmp/` a RAM filesystem if trying such a compiltion on the target).

Installing the result of Buildroot cross-compilation on the Raspberry Pi4 is described at <https://github.com/buildroot/buildroot/tree/master/board/raspberrypi> but the documentation on this web page is not up to date (!):

1. `git clone https://git.busybox.net/buildroot`
2. `cd buildroot`
3. `make raspberrypi4_64.defconfig`

fetches the Buildroot archive, and configures for the Redpitaya4 in 64 bit mode (obviously for RPi3, select `raspberrypi3_64.defconfig`). Because Python support for GNU Radio will require the `glibc` library rather than the default `uClibc`, we must tune the default configuration

4. `make menuconfig`
5. Toolchain → C library (uClibc-ng) → glibc
6. Exit


Once the proper C-library has been selected

7. `make`

builds all tools needed for cross-compilation. This operation will take about 40 min on an 8-core 2.33 GHz Xeon CPU with fast internet connexion and require 7.4 GB of hard disk space. While compiling, Buildroot *only updates files stored* in the `output` directory. Thus, removing this directory (and sub-directories) will return to the original Buildroot configuration. All software related to the host computer – Intel x86/AMD64 architecture most of the time – is located in `output/host`, while all software related to the target (here ARM architecture) is stored in `output/target`. We shall not be interested in the


content of the directory in which source files are stored but might have to erase some of its content to force re-compilation: such files are stored in the `output/build` directory. Finally, the last compilation stage will result in a complete image including bootloader, kernel, libraries and userspace applications: this file is stored in `output/images`.

After completing buildroot compilation, we find in the `output/images` directory the file `sdcard.img` which holds the binary datastream (about 150 MB) to be stored on the microSD card holding the operating system to be run on the RPi. Here, “stored” does not mean copying since we must clone each byte from the binary file to the storage medium. Such an operation is achieved under GNU/Linux with the Disk Dump `dd` command.

 The following line might definitely **corrupt a hard disk** if the wrong storage medium is selected. Always **check** the name of the peripheral associated with the SD card (`dmesg | tail`) before running the `dd` command.

The image resulting from Buildroot compilation is transferred to the microSD card with `sudo dd if=output/images/sdcard.img of=/dev/sdc` where we have on purpose selected the `/dev/sdc` peripheral name in this example since it is ever hardly used. Usually, the microSD card is accessed as `/dev/sdb` (second hard disk storage medium compatible with the Linux SCSI driver) or `/dev/mmcblk0` (internal SD medium interface).

In case a Desktop Manager or a File Manager is used, make sure the SD card is unmounted before executing `dd`, as these tools will interfere with the cloning process.

 **Warning:** the content of the SD card, or any storage medium associated with the last argument of this command, will be **definitely** lost. Make sure, double check, the name of the peripheral on which the Buildroot image will be stored.

Once the image has been flashed on the SD card, we can see two partitions: the first one is a VFAT (format compatible with Microsoft Windows) with the devicetree, the Linux kernel and the bootloader, and a second one holding the GNU/Linux userspace filesystem (`rootfs`).

## 2 Adding custom packages (GNU Radio and PlutoSDR/UHD)

So far we have compiled a standard Buildroot image without dedicated GNU Radio support. Dedicated packages not selected in the default configuration can be activated. This is achieved from the Buildroot directory with `make menuconfig` and selecting **Target packages**. Searching (“/” command as in `vi`) allows for quickly finding the appropriate package, such as GNU Radio.

So far we have only worked with “official” Buildroot packages properly maintained by the Buildroot community. Some packages are not yet integrated in the official repository but can nevertheless be appended as external packages thanks to the `BR2_EXTERNAL` mechanism. As an example of supporting the PlutoSDR thanks to `gr-iio`, this support is available thanks to the `BR2_EXTERNAL` repository found at <https://github.com/oscimp/PlutoSDR> and most significantly its `for_next` branch. Hence, after going to a any directory out of the Buildroot source tree:

1. `git clone https://github.com/oscimp/PlutoSDR`
2. `cd PlutoSDR`
3. `git checkout for_next`
4. `source sourceme.ggm`

Now that the `BR2_EXTERNAL` has been cloned, the appropriate branch selected, and the environment variables set (last command), return in the Buildroot directory and `make menuconfig`. Running `make menuconfig` will now show a new menu named **External options** including `gr-iio`, `libuhd` or `gnss-sdr`.

1. `make menuconfig`
2. `/eudev`

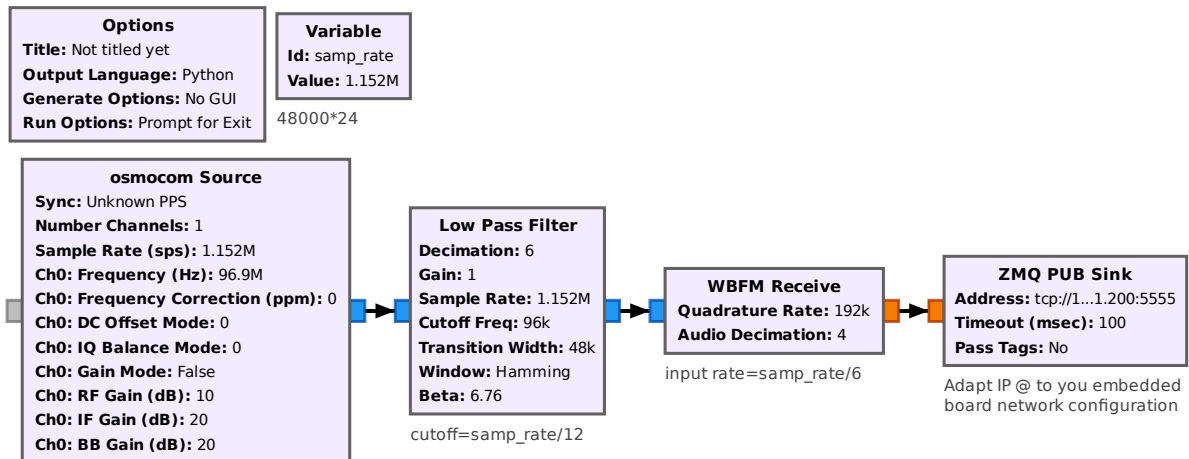
3. Select the last item indicating `BR2_ROOTFS_DEVICE_CREATION_DYNAMIC_EUDEV` and replace `/dev` management with `Dynamic` using `devtmpfs + eudev`
4. `/python3`
5. Select item (4) indicating `BR2_PACKAGE_PYTHON3`
6. `/gnuradio`
7. Select item (1) indicating `BR2_PACKAGE_GNURADIO`
8. Select additional GNU Radio functionalities as needed (we will need `gr-zeromq` support and `python` support)
9. `/osmosdr`
10. Select `BR2_PACKAGE_GR_OSMOSDR` (with Python support and Osmocom RTLSDR support)
11. in `External options` select `uhd` and for the `B210 b200` support and `python API` support,
12. in `External options` select `gr-iio` for PlutoSDR support.

The resulting file will be about 550 MB, requiring increasing the configuration in `.config` with `BR2_TARGET_ROOTFS_EXT2_SIZE="420M"`.

### 3 GNU Radio on RPi

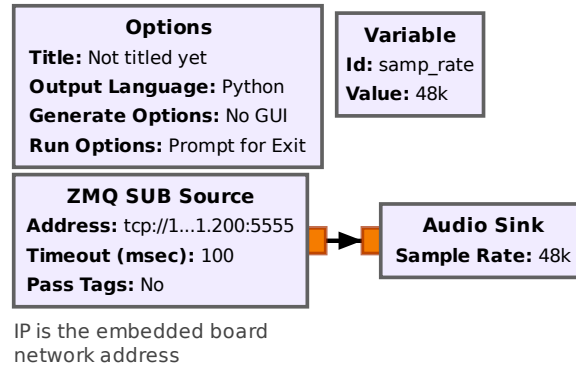
As a demonstration of the proper operation of GNU Radio on the embedded board, we generate using GNU Radio Companion a command line interface (“No GUI”) processing flow since obviously no graphical interface is running on the embedded target, and will execute the resulting Python3 script on the Raspberry Pi4. The audio stream resulting from broadcast FM demodulation will be streamed to the host PC for playing on the sound card.

On the host computer, run GNU Radio Companion (as part of GNU Radio 3.8) and generate the following chart:



### 4 Communication RPi to PC

Process signal collected from the FM broadcast band on the RPi, preprocess on the embedded target board, and send the audio stream to the PC.



## 5 Software development

We are interested in tuning the `gnss-sdr` functionalities. The source code of the software has been downloaded in the `output/build` directory. The build directory for the target system is found in `output/build/gnss-sdr-0.0.12/buildroot-build/` while a separate `output/build/gnss-sdr-0.0.12/build` allows for simultaneously testing source code modifications on the host PC. The output of compiling (`make`), either in `buildroot-build` (ARM target) or `build` (x86 target), is found in `src/main/gnss-sdr`.