

GOLDS-UFSC Documentation

GOLDS-UFSC Documentation SpaceLab, Universidade Federal de Santa Catarina, Florianópolis - Brazil

GOLDS-UFSC Documentation

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Introduction

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1.1 Mission Description

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1.2 Mission Objectives

- 1. To serve as a host platform for the EDC payload.
- 2. Validate the EDC payload in orbit.
- 3. Validate EDC functionality in orbit.
- 4. Validate core-satellite functions in orbit.
- 5. Evaluate the behavior of the core modules.
- 6. Perform experiments on radiation effects in electronic components in orbit.
- 7. Serve as relay for amateur radio communications.

Mission Requirements

- 1. The power system shall be able to harvest solar energy.
- 2. The power system shall be able to store energy for use when GOLDS-UFSC is eclipsed.
- 3. The power system shall supply energy to all other modules.
- 4. The data handling system shall communicate with the other modules and store their data.
- 5. The communications system shall send a beacon signal periodically using VHF radio.
- 6. The communications system shall send the CubeSat telemetry using UHF radio.
- 7. The communications system shall be able to receive telecommands and respond to them accordingly.
- 8. The attitude system shall be able to perform a 1-axis stabilization of the CubeSat.
- 9. GOLDS-UFSC shall have the capability to receive and execute a shutdown telecommand, therefore ceasing all transmissions.
- 10. The downlink transmissions shall be done once at a time, either telemetry or beacon.
- 11. The ground station shall operate under the proper radio frequency communication licenses.
- 12. GOLDS-UFSC shall comply with international and Brazilian radio license agreements and restrictions.
- 13. The team shall build and operate a ground station for full communication with GOLDS-UFSC.

Mission Schedule

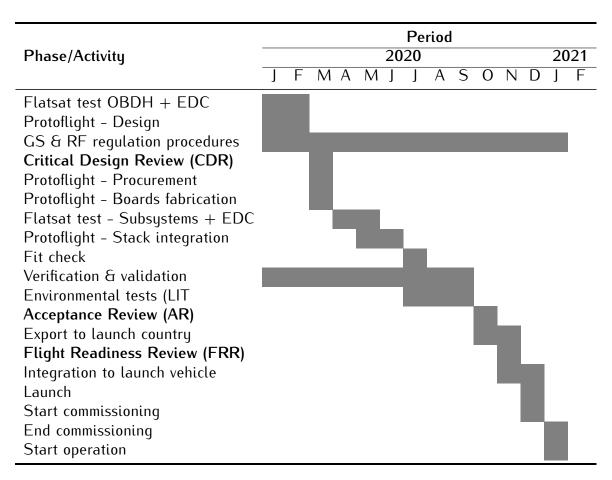


Table 3.1: Mission schedule.

Overall Description

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4.1 General Diagrams

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4.2 General Behaviour

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4.3 Power Budget

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4.4 Link Budget

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4.5 PC-104 Bus

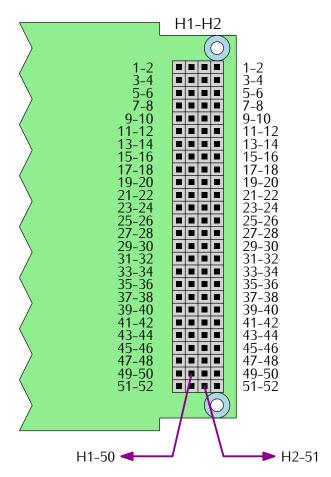


Figure 4.1: Reference diagram of the PC-104 bus.

Pin Row	H1 Odd	H1 Even	H2 Odd	H2 Even
1-2				
3-4	_	_	_	_
5-6	_	_	BE_UART_RX	_
7-8	_	_	BE_UART_TX	_
9-10	_	_		_
11-12	_	_	BE_SPI_MOSI	BE_SPI_CLK
13-14	_	_	BE_SPI_CS	BE_SPI_MISO
15-16	_	_	_	_
17-18	_	PLX_EN	-	-
19-20	_	_	-	-
21-22	_	_	_	_
23-24	_	_	_	_
25-26	EDC_UART_TX	_	-	_
27-28	EDC_UART_RX	_	-	_
29-30	GND	GND	GND	GND
31-32	GND	GND	GND	GND
33-34	-	_	_	-
35-36	RD_SPI_CLK	_	ANT_VCC	ANT_VCC
37-38	RD_SPI_MISO	_	-	_
39-40	RD_SPI_MOSI	RD_SPI_CS	-	_
41-42	PLX_I2C_SDA	_	-	_
43-44	PLX_I2C_SCL	_	-	_
45-46	OBDH_VCC	OBDH_VCC	BAT_VCC	BAT_VCC
47-48	EDC_VCC	EDC_VCC	-	-
49-50	RD_VCC	RD_VCC	EPS_I2C_SDA	-
51-52	BE_VCC	BE_VCC	EPS_I2C_SCL	_

Table 4.1: PC-104 bus pinout.

Signal	Din/c)	Used Ru	Description
Signal	Pin(s)	Used By	Description
GND	H1-29, H1-30,	All	Ground reference
	H1-31, H1-32,		
	H2-29, H2-30,		
	H2-31, H2-32		
BAT_VCC	H2-45, H2-46	EPS	Battery terminals (+)
ANT_VCC	H2-35, H2-36	EPS, ANT	Antenna power supply (3.3 V)
OBDH_VCC	H1-45, H1-46	EPS, OBDH	OBDH power supply (3.3 V)
EDC_VCC	H1-47, H1-48	EPS, EDC	EDC power supply (5 V)
RD_VCC	H1-49, H1-50	EPS, TTC	Main radio power supply (5 V)
BE_VCC	H1-51, H1-52	EPS, TTC	Beacon power supply (5 V)
RD_SPI_CLK	H1-35	OBDH, TTC	CLK signal of the main radio SPI bus
RD_SPI_MISO	H1-37	OBDH, TTC	MISO signal of the main radio
			SPI bus
RD_SPI_MOSI	H1-39	OBDH, TTC	MOS signal of the main radio
			SPI bus
RD_SPI_CS	H1-40	OBDH, TTC	CS signal of the main radio
			SPI bus
EPS_I2C_SDA	H2-49	OBDH, EPS	SDA signal of the EPS I2C
			bus
EPS_I2C_SCL	H2-51	OBDH, EPS	SCL signal of the EPS I2C bus
BE_UART_RX	H2-5	EPS, TTC	EPS TX, Beacon RX (UART
			bus)
BE_UART_TX	H2-7	EPS, TTC	EPS RX, Beacon TX (UART
			bus)
EDC_UART_TX	H1-25	OBDH, EDC	OBDH RX, EDC TX (UART
			bus)
EDC_UART_RX	H1-27	OBDH, EDC	OBDH TX, EDC RX (UART
			bus)
PLX_EN	H1-18	OBDH,	Payload X enable (GPIO)
		Payload X	
PLX_I2C_SDA	H1-41	OBDH,	SDA signal of the Payload X
DIV 10		Payload X	I2C bus
PLX_I2C_SCL	H1-43	OBDH,	SCL signal of the Payload X
		Payload X	I2C bus

Table 4.2: PC-104 bus signal description.

Subsystems

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5.1 On-Board Data Handling

OBDH

5.2 Telemetry, Tracking and Command Module

TTC

5.3 Electrical Power System

EPS

5.4 Attitude Determination and Control System

ADCS

5.5 Mechanical Structure

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- 5.6 Payloads
- 5.6.1 Environmental Data Collection

EDC

Ground Segment

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Operation Planning

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