

# LogiCORE™ IP FIFO Generator v6.1

## *User Guide*

UG175 April 19, 2010



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## Revision History

The following table shows the revision history for this document.

Date	Version	Revision
04/28/05	1.1	Initial Xilinx release.
8/31/05	2.0	Updated guide for release v2.2, added SP3 to ISE v7.1i, incorporated edits from engineering specific for this release, including FWFT, and Built-in FIFO flags, etc.
1/11/06	3.0	Updated for v2.3 release, ISE v8.1i.
7/13/06	4.0	Added Virtex-5 support, reorganized Chapter 5, added ISE v8.2i, version to 3.1
9/21/06	5.0	Core version updated to v3.2; support added for Spartan-3A.
2/15/07	6.0	Core version updated to 3.3; Xilinx tools updated to 9.1i.
4/02/07	6.5	Added support for Spartan-3A DSP devices.
8/8/07	6.6	Updated core to v4.1, ISE tools 9.2i, Cadence IUS v5.8.
10/10/07	7.0	Updated core to v4.2, IUS to v6.1, Xilinx trademark references.
3/24/08	8.0	Updated core to v4.3, ISE tools 10.1, Mentor Graphics® ModelSim® v6.3c.
9/19/08	9.0	Updated core to v4.4, ISE tools 10.1, SP3.
12/17/08	9.0.1	Early access documentation.
4/24/09	10.0	Updated core to v5.1, and ISE tools to v11.1.
6/24/09	10.5	Updated core to v5.2 and ISE tools to v11.2.
6/24/09	10.6	Updated <a href="#">Appendix A, “Performance Information.”</a>
9/16/09	11.0	Updated core to v5.3 and ISE tools to v11.3.
4/19/10	12.0	Updated core to v6.1 and ISE tools to v12.1.

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## **Appendix C: DOUT Reset Value Timing**

# About This Guide

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The *LogicCORE™ IP FIFO Generator User Guide* describes the function and operation of the FIFO Generator, as well as information about designing, customizing, and implementing the core.

## Guide Contents

The following chapters are included:

- [“Preface, About this Guide”](#) describes how the user guide is organized and the conventions used in this guide.
- [Chapter 1, “Introduction,”](#) describes the core and related information, including recommended design experience, additional resources, technical support, and submitting feedback to Xilinx.
- [Chapter 2, “Core Overview,”](#) describes the core configuration options and their interfaces.
- [Chapter 3, “Generating the Core,”](#) describes how to generate the core using the Xilinx CORE Generator Graphical User Interface (GUI).
- [Chapter 4, “Designing with the Core,”](#) discusses how to use the core in a user application.
- [Chapter 5, “Special Design Considerations,”](#) discusses specific design features that must be considered when designing with the core.
- [Chapter 6, “Simulating Your Design,”](#) provides instructions for simulating the design with either behavioral or structural simulation models.
- [Appendix A, “Performance Information,”](#) provides a summary of the core’s performance data.
- [Appendix B, “Core Parameters,”](#) provides a comprehensive list of the parameters set by the CORE Generator GUI for the FIFO Generator.
- [Appendix C, “DOUT Reset Value Timing,”](#) provides the timing diagram for DOUT reset value for various FIFO configurations.

## Additional Resources

To find additional documentation, see the Xilinx website at:

<http://www.xilinx.com/support/documentation/index.htm>.

To search the Answer Database of silicon, software, and IP questions and answers, or to create a technical support WebCase, see the Xilinx website at:

<http://www.xilinx.com/support/mysupport.htm>.

## Conventions

This document uses the following conventions. An example illustrates each convention.

### Typographical

The following typographical conventions are used in this document:

Convention	Meaning or Use	Example
Courier font	Messages, prompts, and program files that the system displays	<code>speed grade: - 100</code>
<b>Courier bold</b>	Literal commands that you enter in a syntactical statement	<b>ngdbuild</b> <i>design_name</i>
<b>Helvetica bold</b>	Commands that you select from a menu	<b>File → Open</b>
	Keyboard shortcuts	<b>Ctrl+C</b>
<i>Italic font</i>	Variables in a syntax statement for which you must supply values	<b>ngdbuild</b> <i>design_name</i>
	References to other manuals	See the <i>User Guide</i> for more information.
	Emphasis in text	If a wire is drawn so that it overlaps the pin of a symbol, the two nets are <i>not</i> connected.
Dark Shading	Items that are not supported or reserved	This feature is not supported
Square brackets [ ]	An optional entry or parameter. However, in bus specifications, such as <b>bus [7:0]</b> , they are required.	<b>ngdbuild</b> [ <i>option_name</i> ] <i>design_name</i>
Braces { }	A list of items from which you must choose one or more	<b>lowpwr</b> = { <b>on</b>   <b>off</b> }
Vertical bar	Separates items in a list of choices	<b>lowpwr</b> = { <b>on</b>   <b>off</b> }
Angle brackets < >	User-defined variable or in code samples	<directory name>
Vertical ellipsis . . .	Repetitive material that has been omitted	IOB #1: Name = QOUT' IOB #2: Name = CLKIN' . . .
Horizontal ellipsis ...	Repetitive material that has been omitted	<b>allow block</b> <i>block_name loc1 loc2 ... locn</i> ;

Convention	Meaning or Use	Example
Notations	The prefix '0x' or the suffix 'h' indicate hexadecimal notation	A read of address 0x00112975 returned 45524943h.
	An '_n' means the signal is active low	<b>usr_teof_n</b> is active low.

## Online Document

The following conventions are used in this document:

Convention	Meaning or Use	Example
Blue text	Cross-reference link to a location in the current document	See the section “ <a href="#">Additional Resources</a> ” for details. Refer to “ <a href="#">Title Formats</a> ” in <a href="#">Chapter 1</a> for details.
<a href="#">Blue, underlined text</a>	Hyperlink to a website (URL)	Go to <a href="http://www.xilinx.com">http://www.xilinx.com</a> for the latest speed files.



# Introduction

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The FIFO Generator core is a fully verified first-in first-out memory queue for use in any application requiring in-order storage and retrieval, enabling high-performance and area-optimized designs. This core can be customized using the Xilinx CORE Generator™ system as a complete solution with control logic already implemented, including management of the read and write pointers and the generation of status flags.

This chapter introduces the FIFO Generator and provides related information, including recommended design experience, additional resources, technical support, and submitting feedback to Xilinx.

## About the Core

The FIFO Generator is a Xilinx CORE Generator IP core, included in the latest IP Update on the Xilinx IP Center. The core is free of charge and no license is required. For detailed information about the core, see the [FIFO Generator product page](#).

### Windows

- Windows XP® Professional 32-bit/64-bit
- Windows Vista® Business 32-bit/64-bit

### Linux

- Red Hat® Enterprise WS 4.0 32-bit/64-bit
- Red Hat Enterprise Desktop 5.0 32-bit/64-bit (with Workstation option)
- SUSE Linux Enterprise (SLE) v10.1 32-bit/64-bit

### Software

- ISE® v11.3

## Recommended Design Experience

The FIFO Generator is a fully verified solution, and can be used by all levels of design engineers.

**Important:** When implementing a FIFO with independent write and read clocks, special care must be taken to ensure the FIFO Generator is correctly used. “[Synchronization Considerations](#),” [page 43](#) provides important information to help ensure correct design configuration.

Similarly, asynchronous designs should also be aware that the behavioral models do not model synchronization delays. See [Chapter 6, “Simulating Your Design”](#) for details.

## Technical Support

For technical support, visit [www.support.xilinx.com/](http://www.support.xilinx.com/). Questions are routed to a team of engineers with FIFO Generator expertise.

Xilinx will provide technical support for use of this product as described in the *LogiCORE FIFO Generator User Guide*. Xilinx cannot guarantee timing, functionality, or support of this product for designs that do not follow these guidelines.

## Feedback

Xilinx welcomes comments and suggestions about the FIFO Generator and the documentation supplied with the core.

### FIFO Generator

For comments or suggestions about the FIFO Generator, please submit a WebCase from [www.support.xilinx.com/](http://www.support.xilinx.com/). Be sure to include the following information:

- Product name
- Core version number
- Explanation of your comments

### Document

For comments or suggestions about this document, please submit a WebCase from [www.support.xilinx.com/](http://www.support.xilinx.com/). Be sure to include the following information:

- Document title
- Document number
- Page number(s) to which your comments refer
- Explanation of your comments



# Core Overview

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This chapter provides an overview of the FIFO Generator configuration options and interfaces.

## Feature Overview

### Clock Implementation Operation

The FIFO Generator enables FIFOs to be configured with either independent or common clock domains for write and read operations. The independent clock configuration of the FIFO Generator enables the user to implement unique clock domains on the write and read ports. The FIFO Generator handles the synchronization between clock domains, placing no requirements on phase and frequency relationships between clocks. A common clock domain implementation optimizes the core for data buffering within a single clock domain.

### Virtex-6 and Virtex-5 FPGA Built-in FIFO Support

The FIFO Generator supports the Virtex®-6 and Virtex-5 FPGA built-in FIFO modules, enabling the creation of large FIFOs by cascading the built-in FIFOs in both width and depth. The core expands the capabilities of the built-in FIFOs by utilizing the FPGA fabric to create optional status flags not implemented in the built-in FIFO macro. The built-in Error Injection and Correction Checking (ECC) feature in the built-in FIFO macro is also available.

### Virtex-4 FPGA Built-in FIFO Support

The FIFO Generator supports a single instantiation of the Virtex-4 FPGA built-in FIFO module. The core also implements a FIFO flag patch (“Solution 1: Synchronous/Asynchronous Clock Work-Arounds,” defined in the *Virtex-4 FPGA User Guide*), based on estimated clock frequencies. This patch is implemented in fabric. See [Appendix A, “Performance Information”](#) for resource utilization estimates.

### First-Word Fall-Through

The first-word fall-through (FWFT) feature provides the ability to look ahead to the next word available from the FIFO without having to issue a read operation. The FIFO accomplishes this by using output registers which are automatically loaded with data, when data appears in the FIFO. This causes the first word written to the FIFO to automatically appear on the data out bus (DOUT). Subsequent user read operations cause the output data to update with the next word, as long as data is available in the FIFO. The

use of registers on the FIFO DOUT bus improves clock-to-output timing, and the FWFT functionality provides low-latency access to data. This is ideal for applications that require throttling, based on the contents of the data that are read.

See [Table 2-2](#) for FWFT availability. The use of this feature impacts the behavior of many other features, such as:

- Read operations (see [“First-Word-Fall-Through FIFO Read Operation,”](#) page 53)
- Programmable empty (see [“Non-symmetric Aspect Ratio and First-Word Fall-Through,”](#) page 69)
- Data counts (see [“First-Word Fall-Through Data Count,”](#) page 64 and [“Non-symmetric Aspect Ratio and First-Word Fall-Through,”](#) page 69)

## Memory Types

The FIFO Generator implements FIFOs built from block RAM, distributed RAM, shift registers, or the built-in FIFOs for Virtex-6, Virtex-5 and Virtex-4 FPGAs. The core combines memory primitives in an optimal configuration based on the selected width and depth of the FIFO. [Table 2-1](#) provides best-use recommendations for specific design requirements.

**Table 2-1: Memory Configuration Benefits**

	Independent Clocks	Common Clock	Small Buffering	Medium-Large Buffering	High Performance	Minimal Resources
Built-in FIFO	✓	✓		✓	✓	✓
Block RAM	✓	✓		✓	✓	✓
Shift Register		✓	✓		✓	
Distributed RAM	✓	✓	✓		✓	

## Non-Symmetric Aspect Ratio

The core supports generating FIFOs whose write and read ports have different widths, enabling automatic width conversion of the data width. Non-symmetric aspect ratios ranging from 1:8 to 8:1 are supported for the write and read port widths. This feature is available for FIFOs implemented with block RAM that are configured to have independent write and read clocks.

## Embedded Registers in Block RAM and FIFO Macros

In Virtex-6 and Virtex-5 FPGA block RAM and FIFO macros and Virtex-4 FPGA block RAM macros, embedded output registers are available to increase performance and add a pipeline register to the macros. This feature can be leveraged to add one additional latency to the FIFO core (DOUT bus and VALID outputs) or implement the output registers for FWFT FIFOs. The embedded registers available in Virtex-6 FPGAs can be reset (DOUT) to a default or user programmed value for common clock built-in FIFOs. See [“Embedded Registers in Block RAM and FIFO Macros \(Virtex-6, Virtex-5 and Virtex-4 FPGAs\),”](#) page 70 for more information.

## Error Injection and Correction

The block RAM and FIFO macros are equipped with built-in Error Correction Checking (ECC) in the Virtex-5 FPGA architecture and built-in Error Injection and Correction Checking in the Virtex-6 FPGA architecture. Error Injection and Correction are available for both the common and independent clock block RAM or built-in based FIFOs.

## Core Configuration and Implementation

Table 2-2 provides a summary of the supported memory and clock configurations.

Table 2-2: FIFO Configurations

Clock Domain	Memory Type	Non-symmetric Aspect Ratios	First-Word Fall-Through	ECC Support	Embedded Register Support	Error Injection	Reset Option for Embedded Register (with/without DOUT Reset Value) <sup>a</sup>
Common	Block RAM		✓	✓	✓ <sup>b</sup>	✓	✓
Common	Distributed RAM		✓				
Common	Shift Register						
Common	Built-in FIFO <sup>c</sup>		✓ <sup>d</sup>	✓	✓ <sup>e</sup>	✓	✓
Independent	Block RAM	✓	✓	✓	✓ <sup>b</sup>	✓	
Independent	Distributed RAM		✓				
Independent	Built-in FIFO <sup>c</sup>		✓ <sup>d</sup>	✓		✓ <sup>f</sup>	

a. Available only if Embedded register option is selected.

b. Embedded register support is only available for Virtex-4, Virtex-5 and Virtex-6 FPGA block RAM-based FIFOs.

c. The built-in FIFO primitive is only available in the Virtex-6, Virtex-5 and Virtex-4 architectures.

d. FWFT is only supported for built-in FIFOs in Virtex-6 and Virtex-5 devices.

e. Only available for Virtex-6 and Virtex-5 FPGA common clock built-in FIFOs.

f. Available only if ECC option is selected.

## Common Clock: Block RAM, Distributed RAM, Shift Register

This implementation category allows the user to select block RAM, distributed RAM, or shift register and supports a common clock for write and read data accesses.

The feature set supported for this configuration includes status flags (full, almost full, empty, and almost empty) and programmable empty and full flags generated with user-defined thresholds. In addition, optional handshaking and error flags are supported (write acknowledge, overflow, valid, and underflow), and an optional data count provides the number of words in the FIFO. In addition, for the block RAM and distributed RAM implementations, the user has the option to select a synchronous or asynchronous reset for the core. For Virtex-6 and Virtex-5 FPGA designs, the block RAM FIFO configuration also supports ECC.

## Common Clock: Virtex-6, Virtex-5 or Virtex-4 FPGA Built-in FIFO

This implementation category allows the user to select the built-in FIFO available in the Virtex-6, Virtex-5 or Virtex-4 FPGA architectures and supports a common clock for write and read data accesses.

The feature set supported for this configuration includes status flags (full and empty) and optional programmable full and empty flags with user-defined thresholds. In addition, optional handshaking and error flags are available (write acknowledge, overflow, valid, and underflow). The Virtex-6 and Virtex-5 FPGA built-in FIFO configurations also support the built-in ECC feature.

## Independent Clocks: Block RAM and Distributed RAM

This implementation category allows the user to select block RAM or distributed RAM and supports independent clock domains for write and read data accesses. Operations in the read domain are synchronous to the read clock and operations in the write domain are synchronous to the write clock.

The feature set supported for this type of FIFO includes non-symmetric aspect ratios (different write and read port widths), status flags (full, almost full, empty, and almost empty), as well as programmable full and empty flags generated with user-defined thresholds. Optional read data count and write data count indicators provide the number of words in the FIFO relative to their respective clock domains. In addition, optional handshaking and error flags are available (write acknowledge, overflow, valid, and underflow). For Virtex-6 and Virtex-5 FPGA designs, the block RAM FIFO configuration also supports ECC.

## Independent Clocks: Built-in FIFO for Virtex-6, Virtex-5 or Virtex-4 FPGAs

This implementation category allows the user to select the built-in FIFO available in the Virtex-6, Virtex-5 or Virtex-4 FPGA architectures. Operations in the read domain are synchronous to the read clock and operations in the write domain are synchronous to the write clock.

The feature set supported for this configuration includes status flags (full and empty) and programmable full and empty flags generated with user-defined thresholds. In addition, optional handshaking and error flags are available (write acknowledge, overflow, valid, and underflow). The Virtex-6 and Virtex-5 FPGA built-in FIFO configurations also support the built-in ECC feature.

# FIFO Generator Features

Table 2-3 summarizes the FIFO Generator features supported for each clock configuration and memory type.

Table 2-3: FIFO Configurations Summary

FIFO Feature	Independent Clocks			Common Clock		
	Block RAM	Distributed RAM	Built-in FIFO <sup>a</sup>	Block RAM	DistributedRAM, Shift Register	Built-in FIFO <sup>a</sup>
Non-symmetric Aspect Ratios <sup>b</sup>	✓					
Symmetric Aspect Ratios	✓	✓	✓	✓	✓	✓
Almost Full	✓	✓		✓	✓	
Almost Empty	✓	✓		✓	✓	
Handshaking	✓	✓	✓	✓	✓	✓
Data Count	✓	✓		✓	✓	
Programmable Empty/Full Thresholds	✓	✓	✓ <sup>c</sup>	✓	✓	✓ <sup>c</sup>
First-Word Fall-Through	✓	✓	✓ <sup>d</sup>	✓	✓ <sup>e</sup>	✓ <sup>d</sup>
Synchronous Reset				✓	✓	
Asynchronous Reset	✓ <sup>f</sup>	✓ <sup>f</sup>	✓	✓ <sup>f</sup>	✓ <sup>f</sup>	✓
DOUT Reset Value	✓	✓		✓	✓	✓ <sup>g</sup>
ECC	✓ <sup>i</sup>		✓ <sup>h</sup>	✓ <sup>i</sup>		✓ <sup>i</sup>
Embedded Register	✓ <sup>i</sup>			✓ <sup>j</sup>		✓ <sup>j</sup>

- For Virtex-4 FPGA Built-in FIFO macro, the valid width range is 4, 9, 18 and 36 and the valid depth range automatically varies based on write width selection. For Virtex-6 and Virtex-5 FPGA Built-in FIFO macros, the valid width range is 1 to 1024 and the valid depth range is 512 to 4194304. Only depths with powers of 2 are allowed.
- For applications with a single clock that require non-symmetric ports, use the independent clock configuration and connect the write and read clocks to the same source. A dedicated solution for common clocks will be available in a future release. Contact your Xilinx representative for more details.
- For built-in FIFOs, the range of Programmable Empty/Full threshold is limited to take advantage of the logic internal to the macro.
- First-Word-Fall-Through is only supported for the Virtex-6 and Virtex-5 FPGA built-in FIFOs.
- First-Word-Fall-Through is supported for distributed RAM FIFO only.
- Asynchronous reset is optional for all FIFOs built using distributed and block RAM.
- DOUT reset value is supported only in Virtex-6 FPGA common clock built-in FIFOs with embedded register option selected.
- ECC is only supported for the Virtex-6 and Virtex-5 FPGA block RAM and built-in FIFOs.
- Embedded register option is only supported in Virtex-6, Virtex-5 and Virtex-4 FPGA block RAM FIFOs.
- Embedded register option is supported only in Virtex-6 and Virtex-5 FPGA common clock built-in FIFOs. See “Embedded Registers in Block RAM and FIFO Macros,” page 18.

## Using Block RAM FIFOs Instead of Built-in FIFOs

The Built-In FIFO solutions were implemented to take advantage of logic internal to the Built-in FIFO macro. Several features, for example, non-symmetric aspect ratios, almost full, almost empty, and so forth were not implemented because they are not native to the macro and require additional logic in the fabric to implement.

Benchmarking suggests that the advantages the Built-In FIFO implementations have over the block RAM FIFOs (for example, logic resources) diminish as external logic is added to implement features not native to the macro. This is especially true as the depth of the implemented FIFO increases. It is strongly recommended that users requiring features not available in the Built-In FIFOs implement their design using block RAM FIFOs.

## FIFO Interfaces

The following two sections provide definitions for the FIFO interface signals. [Figure 2-1](#) illustrates these signals (both the standard and optional ports) for a FIFO core that supports independent write and read clocks.

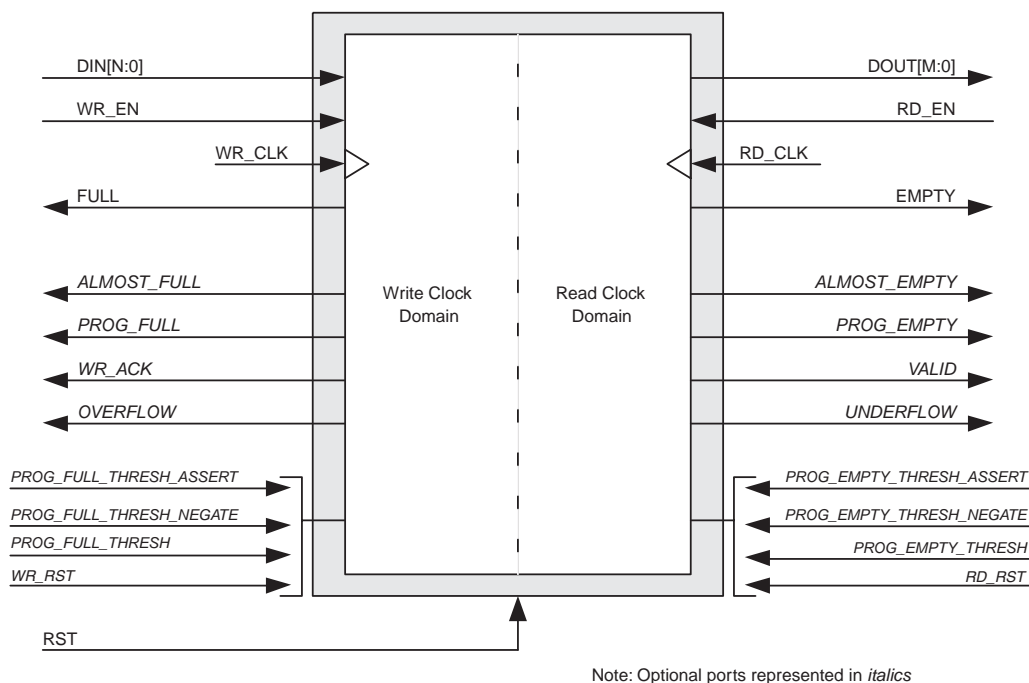


Figure 2-1: FIFO with Independent Clocks: Interface Signals

### Interface Signals: FIFOs With Independent Clocks

The RST signal, as defined in [Table 2-4](#), causes a reset of the entire core logic (both write and read clock domains). It is an asynchronous input which is synchronized internally in the core before being used. The initial hardware reset should be generated by the user. When the core is configured to have independent clocks, the reset signal should be High

for at least three read clock and write clock cycles to ensure all internal states are reset to the correct values.

**Table 2-4: Reset Signal for FIFOs with Independent Clocks**

Name	Direction	Description
RST	Input	Reset: An asynchronous reset signal that initializes all internal pointers, output registers and memory <sup>a</sup> .

a. Output of FIFO (DOUT) is reset and not the content of the memory.

[Table 2-5](#) defines the signals for the write interface for FIFOs with independent clocks. The write interface signals are divided into required and optional signals and all signals are synchronous to the write clock (WR\_CLK).

**Table 2-5: Write Interface Signals for FIFOs with Independent Clocks**

Name	Direction	Description
<b>Required</b>		
WR_CLK	Input	Write Clock: All signals on the write domain are synchronous to this clock.
DIN[N:0]	Input	Data Input: The input data bus used when writing the FIFO.
WR_EN	Input	Write Enable: If the FIFO is not full, asserting this signal causes data (on DIN) to be written to the FIFO.
FULL	Output	Full Flag: When asserted, this signal indicates that the FIFO is full. Write requests are ignored when the FIFO is full, initiating a write when the FIFO is full is non-destructive to the contents of the FIFO.
<b>Optional</b>		
WR_RST	Input	Write Reset: Synchronous to write clock. When asserted, initializes all internal pointers and flags of write clock domain.
ALMOST_FULL	Output	Almost Full: When asserted, this signal indicates that only one more write can be performed before the FIFO is full.
PROG_FULL	Output	Programmable Full: This signal is asserted when the number of words in the FIFO is greater than or equal to the assert threshold. It is deasserted when the number of words in the FIFO is less than the negate threshold.

Table 2-5: Write Interface Signals for FIFOs with Independent Clocks (Cont'd)

Name	Direction	Description
WR_DATA_COUNT [D:0]	Output	Write Data Count: This bus indicates the number of words written into the FIFO. The count is guaranteed to never under-report the number of words in the FIFO, to ensure the user never overflows the FIFO. The exception to this behavior is when a write operation occurs at the rising edge of WR_CLK, that write operation will only be reflected on WR_DATA_COUNT at the next rising clock edge.  If D is less than $\log_2(\text{FIFO depth}) - 1$ , the bus is truncated by removing the least-significant bits.
WR_ACK	Output	Write Acknowledge: This signal indicates that a write request (WR_EN) during the prior clock cycle succeeded.
OVERFLOW	Output	Overflow: This signal indicates that a write request (WR_EN) during the prior clock cycle was rejected, because the FIFO is full. Overflowing the FIFO is non-destructive to the contents of the FIFO.
PROG_FULL_THRESH	Input	Programmable Full Threshold: This signal is used to input the threshold value for the assertion and deassertion of the programmable full (PROG_FULL) flag. The threshold can be dynamically set in-circuit during reset.  The user can either choose to set the assert and negate threshold to the same value (using PROG_FULL_THRESH), or the user can control these values independently (using PROG_FULL_THRESH_ASSERT and PROG_FULL_THRESH_NEGATE).
PROG_FULL_THRESH_ASSERT	Input	Programmable Full Threshold Assert: This signal is used to set the upper threshold value for the programmable full flag, which defines when the signal is asserted. The threshold can be dynamically set in-circuit during reset.
PROG_FULL_THRESH_NEGATE	Input	Programmable Full Threshold Negate: This signal is used to set the lower threshold value for the programmable full flag, which defines when the signal is deasserted. The threshold can be dynamically set in-circuit during reset.



**Table 2-5: Write Interface Signals for FIFOs with Independent Clocks (Cont'd)**

Name	Direction	Description
INJECTSBITERR	Input	Injects a single bit error if the ECC feature is used on a Virtex-6 FPGA block RAM or built-in FIFO macro. For detailed information, see "Chapter 4, Designing with the Core," in the <i>FIFO Generator User Guide</i> .
INJECTDBITERR	Input	Injects a double bit error the ECC feature is used on a Virtex-6 FPGA block RAM or built-in FIFO macro. For detailed information, see "Chapter 4, Designing with the Core," in the <i>FIFO Generator User Guide</i> .

Table 2-6 defines the signals on the read interface of a FIFO with independent clocks. The read interface signals are divided into required signals and optional signals, and all signals are synchronous to the read clock (RD\_CLK).

**Table 2-6: Read Interface Signals for FIFOs with Independent Clocks**

Name	Direction	Description
<b>Required</b>		
RD_CLK	Input	Read Clock: All signals on the read domain are synchronous to this clock.
DOUT[M:0]	Output	Data Output: The output data bus is driven when reading the FIFO.
RD_EN	Input	Read Enable: If the FIFO is not empty, asserting this signal causes data to be read from the FIFO (output on DOUT).
EMPTY	Output	Empty Flag: When asserted, this signal indicates that the FIFO is empty. Read requests are ignored when the FIFO is empty, initiating a read while empty is non-destructive to the FIFO.
<b>Optional</b>		
RD_RST	Input	Read Reset: Synchronous to read clock. When asserted, initializes all internal pointers, flags and output registers of read clock domain.
ALMOST_EMPTY	Output	Almost Empty Flag: When asserted, this signal indicates that the FIFO is almost empty and one word remains in the FIFO.
PROG_EMPTY	Output	Programmable Empty: This signal is asserted when the number of words in the FIFO is less than or equal to the programmable threshold. It is deasserted when the number of words in the FIFO exceeds the programmable threshold.

Table 2-6: Read Interface Signals for FIFOs with Independent Clocks (Cont'd)

Name	Direction	Description
RD_DATA_COUNT [C:0]	Output	Read Data Count: This bus indicates the number of words available for reading in the FIFO. The count is guaranteed to never over-report the number of words available for reading, to ensure that the user does not underflow the FIFO. The exception to this behavior is when the read operation occurs at the rising edge of RD_CLK, that read operation will only be reflected on RD_DATA_COUNT at the next rising clock edge. If C is less than $\log_2(\text{FIFO depth})-1$ , the bus is truncated by removing the least-significant bits.
VALID	Output	Valid: This signal indicates that valid data is available on the output bus (DOUT).
UNDERFLOW	Output	Underflow: Indicates that the read request (RD_EN) during the previous clock cycle was rejected because the FIFO is empty. Underflowing the FIFO is not destructive to the FIFO.
PROG_EMPTY_THRESH	Input	Programmable Empty Threshold: This signal is used to input the threshold value for the assertion and deassertion of the programmable empty (PROG_EMPTY) flag. The threshold can be dynamically set in-circuit during reset.  The user can either choose to set the assert and negate threshold to the same value (using PROG_EMPTY_THRESH), or the user can control these values independently (using PROG_EMPTY_THRESH_ASSERT and PROG_EMPTY_THRESH_NEGATE).
PROG_EMPTY_THRESH_ASSERT	Input	Programmable Empty Threshold Assert: This signal is used to set the lower threshold value for the programmable empty flag, which defines when the signal is asserted. The threshold can be dynamically set in-circuit during reset.
PROG_EMPTY_THRESH_NEGATE	Input	Programmable Empty Threshold Negate: This signal is used to set the upper threshold value for the programmable empty flag, which defines when the signal is deasserted. The threshold can be dynamically set in-circuit during reset.
SBITERR	Output	Single Bit Error: Indicates that the ECC decoder detected and fixed a single-bit error on a Virtex-6 and Virtex-5 FPGA block RAMs or built-in FIFO macros. See <a href="#">“Built-in Error Correction Checking,”</a> page 71.
DBITERR	Output	Double Bit Error: Indicates that the ECC decoder detected a double-bit error on a Virtex-6 and Virtex-5 FPGA block RAMs or built-in FIFO macros and data in the FIFO core is corrupted. See <a href="#">“Built-in Error Correction Checking,”</a> page 71.

## Interface Signals: FIFOs with Common Clock

Table 2-7 defines the interface signals of a FIFO with a common write and read clock. The table is divided into standard and optional interface signals, and all signals (except reset) are synchronous to the common clock (CLK). Users have the option to select synchronous or asynchronous reset for the distributed or block RAM FIFO implementation.

Table 2-7: Interface Signals for FIFOs with a Common Clock

Name	Direction	Description
<i>Required</i>		
RST	Input	Reset: An asynchronous reset that initializes all internal pointers and output registers.
SRST	Input	Synchronous Reset: A synchronous reset that initializes all internal pointers and output registers.
CLK	Input	Clock: All signals on the write and read domains are synchronous to this clock.
DIN[N:0]	Input	Data Input: The input data bus used when writing the FIFO.
WR_EN	Input	Write Enable: If the FIFO is not full, asserting this signal causes data (on DIN) to be written to the FIFO.
FULL	Output	Full Flag: When asserted, this signal indicates that the FIFO is full. Write requests are ignored when the FIFO is full, initiating a write when the FIFO is full is non-destructive to the contents of the FIFO.
DOUT[M:0]	Output	Data Output: The output data bus driven when reading the FIFO.
RD_EN	Input	Read Enable: If the FIFO is not empty, asserting this signal causes data to be read from the FIFO (output on DOUT).
EMPTY	Output	Empty Flag: When asserted, this signal indicates that the FIFO is empty. Read requests are ignored when the FIFO is empty, initiating a read while empty is non-destructive to the FIFO.
<i>Optional</i>		
DATA_COUNT [C:0]	Output	Data Count: This bus indicates the number of words stored in the FIFO. If C is less than $\log_2(\text{FIFO depth})-1$ , the bus is truncated by removing the least-significant bits.
ALMOST_FULL	Output	Almost Full: When asserted, this signal indicates that only one more write can be performed before the FIFO is full.

Table 2-7: Interface Signals for FIFOs with a Common Clock (Cont'd)

Name	Direction	Description
PROG_FULL	Output	Programmable Full: This signal is asserted when the number of words in the FIFO is greater than or equal to the assert threshold. It is deasserted when the number of words in the FIFO is less than the negate threshold.
WR_ACK	Output	Write Acknowledge: This signal indicates that a write request (WR_EN) during the prior clock cycle succeeded.
OVERFLOW	Output	Overflow: This signal indicates that a write request (WR_EN) during the prior clock cycle was rejected, because the FIFO is full. Overflowing the FIFO is non-destructive to the contents of the FIFO.
PROG_FULL_THRESH	Input	Programmable Full Threshold: This signal is used to set the threshold value for the assertion and deassertion of the programmable full flag (PROG_FULL). The threshold can be dynamically set in-circuit during reset.  The user can either choose to set the assert and negate threshold to the same value (using PROG_FULL_THRESH), or the user can control these values independently (using PROG_FULL_THRESH_ASSERT and PROG_FULL_THRESH_NEGATE).
PROG_FULL_THRESH_ASSERT	Input	Programmable Full Threshold Assert: This signal is used to set the upper threshold value for the programmable full flag, which defines when the signal is asserted. The threshold can be dynamically set in-circuit during reset.
PROG_FULL_THRESH_NEGATE	Input	Programmable Full Threshold Negate: This signal is used to set the lower threshold value for the programmable full flag, which defines when the signal is deasserted. The threshold can be dynamically set in-circuit during reset.
ALMOST_EMPTY	Output	Almost Empty Flag: When asserted, this signal indicates that the FIFO is almost empty and one word remains in the FIFO.
PROG_EMPTY	Output	Programmable Empty: This signal is asserted after the number of words in the FIFO is less than or equal to the programmable threshold. It is deasserted when the number of words in the FIFO exceeds the programmable threshold.
VALID	Output	Valid: This signal indicates that valid data is available on the output bus (DOUT).

Table 2-7: Interface Signals for FIFOs with a Common Clock (Cont'd)

Name	Direction	Description
UNDERFLOW	Output	Underflow: Indicates that read request (RD_EN) during the previous clock cycle was rejected because the FIFO is empty. Underflowing the FIFO is not destructive to the FIFO.
PROG_EMPTY_THRESH	Input	<p>Programmable Empty Threshold: This signal is used to set the threshold value for the assertion and deassertion of the programmable empty flag (PROG_EMPTY). The threshold can be dynamically set in-circuit during reset.</p> <p>The user can either choose to set the assert and negate threshold to the same value (using PROG_EMPTY_THRESH), or the user can control these values independently (using PROG_EMPTY_THRESH_ASSERT and PROG_EMPTY_THRESH_NEGATE).</p>
PROG_EMPTY_THRESH_ASSERT	Input	Programmable Empty Threshold Assert: This signal is used to set the lower threshold value for the programmable empty flag, which defines when the signal is asserted. The threshold can be dynamically set in-circuit during reset.
PROG_EMPTY_THRESH_NEGATE	Input	Programmable Empty Threshold Negate: This signal is used to set the upper threshold value for the programmable empty flag, which defines when the signal is deasserted. The threshold can be dynamically set in-circuit during reset.
SBITERR	Output	Single Bit Error: Indicates that the ECC decoder detected and fixed a single-bit error on a Virtex-6 and Virtex-5 FPGA built-in FIFO macros. See <a href="#">"Built-in Error Correction Checking,"</a> page 71.
DBITERR	Output	Double Bit Error: Indicates that the ECC decoder detected a double-bit error on a Virtex-6 and Virtex-5 FPGA built-in FIFO macros, and data in the FIFO core is corrupted. See <a href="#">"Built-in Error Correction Checking,"</a> page 71.
INJECTSBITERR	Input	Injects a single bit error if the ECC feature is used on a Virtex-6 FPGA block RAM or built-in FIFO macro. For detailed information, see "Chapter 4, Designing with the Core," in the <i>FIFO Generator User Guide</i> .
INJECTDBITERR	Input	Injects a double bit error if the ECC feature is used on a Virtex-6 FPGA block RAM or built-in FIFO macro. For detailed information, see "Chapter 4, Designing with the Core," in the <i>FIFO Generator User Guide</i> .



## *Generating the Core*

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This chapter contains information and instructions for using the Xilinx CORE Generator system to customize the FIFO Generator.

### **CORE Generator Graphical User Interface**

The FIFO Generator GUI includes six configuration screens.

- [FIFO Implementation](#)
- [Performance Options and Data Port Parameters](#)
- [Optional Flags, Handshaking, and Initialization](#)
- [Initialization and Programmable Flags](#)
- [Data Count](#)
- [Summary](#)

## FIFO Implementation

The main FIFO Generator screen is used to define the component name and provides configuration options for the core.

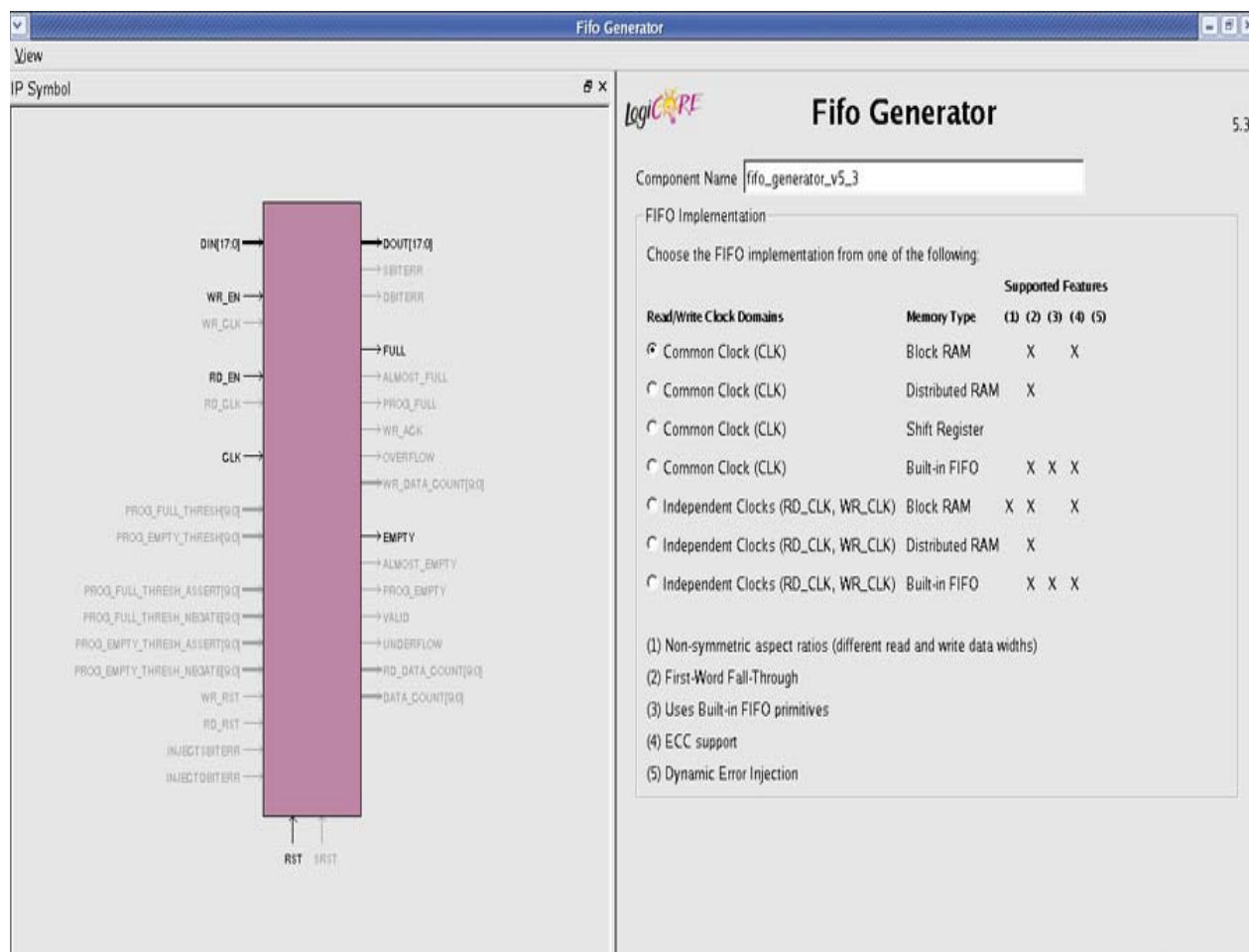


Figure 3-1: Main FIFO Generator Screen

### Component Name

Base name of the output files generated for this core. The name must begin with a letter and be composed of the following characters: a to z, 0 to 9, and “\_”.

### FIFO Implementation

This section of the GUI allows the user to select from a set of available FIFO implementations and supported features. The key supported features that are only available for certain implementations are highlighted by checks in the right-margin. The available options are listed below, with cross-references to additional information.



## Common Clock (CLK), Block RAM

For details, see [“Common Clock FIFO: Block RAM and Distributed RAM,” page 49](#). This implementation optionally supports first-word-fall-through (selectable in the second GUI screen, shown in [Figure 3-2](#)).

## Common Clock (CLK), Distributed RAM

For details, see [“Common Clock FIFO: Block RAM and Distributed RAM,” page 49](#). This implementation optionally supports first-word-fall-through (selectable in the second GUI screen, shown in [Figure 3-2](#)).

## Common Clock (CLK), Shift Register

For details, see [“Common Clock FIFO: Shift Registers,” page 49](#). This implementation is only available in Virtex-4 FPGA and newer architectures.

## Common Clock (CLK), Built-in FIFO

For details, see [“Common Clock: Built-in FIFO,” page 48](#). This implementation is only available when using the Virtex-6, Virtex-5 or Virtex-4 FPGA architectures. This implementation optionally supports first-word fall-through (selectable in the second GUI screen, shown in [Figure 3-2](#)).

## Independent Clocks (RD\_CLK, WR\_CLK), Block RAM

For details, see [“Independent Clocks: Block RAM and Distributed RAM,” page 45](#). This implementation optionally supports asymmetric read/write ports and first-word fall-through (selectable in the second GUI screen, shown in [Figure 3-2](#)).

## Independent Clocks (RD\_CLK, WR\_CLK), Distributed RAM

For more information, see [“Independent Clocks: Block RAM and Distributed RAM,” page 45](#). This implementation optionally supports first-word fall-through (selectable in the second GUI screen, shown in [Figure 3-2](#)).

## Independent Clocks (RD\_CLK, WR\_CLK), Built-in FIFO

For more information, see [“Independent Clocks: Built-in FIFO,” page 47](#). This implementation is only available when using Virtex-6, Virtex-5 or Virtex-4 FPGA architectures. This implementation optionally supports first-word fall-through (selectable in the second GUI screen, shown in [Figure 3-2](#)).

## Performance Options and Data Port Parameters

This screen provides performance options and data port parameters for the core.

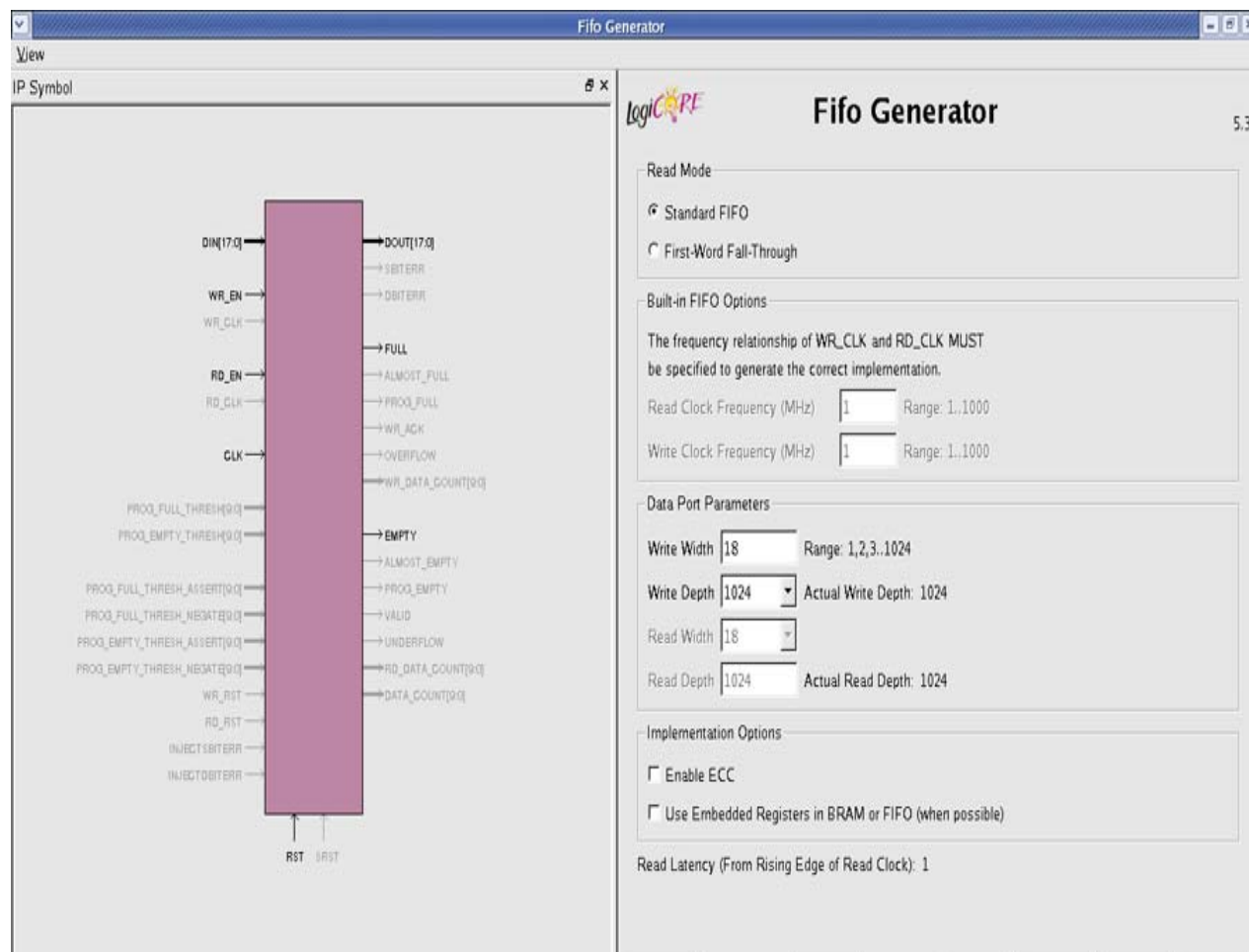


Figure 3-2: Performance Options and Data Port Parameters Screen

### Read Mode

Available only when block RAM or distributed RAM FIFOs are selected. Support for built-in FIFOs is only available for Virtex-6 and Virtex-5 FPGA implementations.

### Standard FIFO

Implements a FIFO with standard latencies, and without using output registers.

### First-Word Fall-Through FIFO

Implements a FIFO with registered outputs. For more information about FWFT functionality, see [“First-Word-Fall-Through FIFO Read Operation,” page 53](#).

## Built-in FIFO Options

### Read/Write Clock Frequencies

The Read Clock Frequency and Write Clock Frequency fields can be any integer from 1 to 1000. They are used to determine the optimal implementation of the domain-crossing logic in the core. This option is only available for built-in FIFOs with independent clocks. If the desired frequency is not within the allowable range, scale the read and write clock frequencies so that they fit within the valid range, while maintaining their ratio relationship.

**Important:** It is critical that this information is entered and accurate. If this information is not provided, it can result in a sub-optimal solution with incorrect core behavior.

## Data Port Parameters

### Write Width

For Virtex-4 FPGA Built-in FIFO macro, the valid range is 4, 9, 18 and 36. For other memory type configurations, the valid range is 1 to 1024.

### Write Depth

For Virtex-4 FPGA Built-in FIFO macro, the valid range automatically varies based on write width selection. For Virtex-6 and Virtex-5 FPGA Built-in FIFO macro, the valid range is 512 to 4194304. Only depths with powers of 2 are allowed.

For non Built-in FIFO, the valid range is 1 to 4194304. Only depths with powers of 2 are allowed.

### Read Width

Available only if independent clocks configuration with block RAM is selected. Valid range must comply with asymmetric port rules. See [“Non-symmetric Aspect Ratios,” page 66](#).

### Read Depth

Automatically calculated based on Write Width, Write Depth, and Read Width.

## Implementation Options

### Error Correction Checking in Block RAM or Built-in FIFO

The Error Correction Checking (ECC) feature enables built-in error correction in the Virtex-6 and Virtex-5 FPGA block RAM and built-in FIFO macros. When this feature is enabled, the block RAM or built-in FIFO is set to the full ECC mode, where both the encoder and decoder are enabled.

### Use Embedded Registers in Block RAM or FIFO

The block RAM macros available in Virtex-6, Virtex-5 and Virtex-4 FPGA, as well as built-in FIFO macros available in Virtex-6 and Virtex-5 FPGA, have built-in embedded registers that can be used to pipeline data and improve macro timing. This option enables users to

add one pipeline stage to the output of the FIFO and take advantage of the available embedded registers; however, the ability to reset the data output of the Virtex-5 FPGA built-in FIFO is disabled when this feature is used. For built-in FIFOs, this feature is only supported for synchronous FIFO configurations that have only 1 FIFO macro in depth. See “Embedded Registers in Block RAM and FIFO Macros (Virtex-6, Virtex-5 and Virtex-4 FPGAs),” page 70.

## Optional Flags, Handshaking, and Initialization

This screen allows you to select the optional status flags and set the handshaking options.

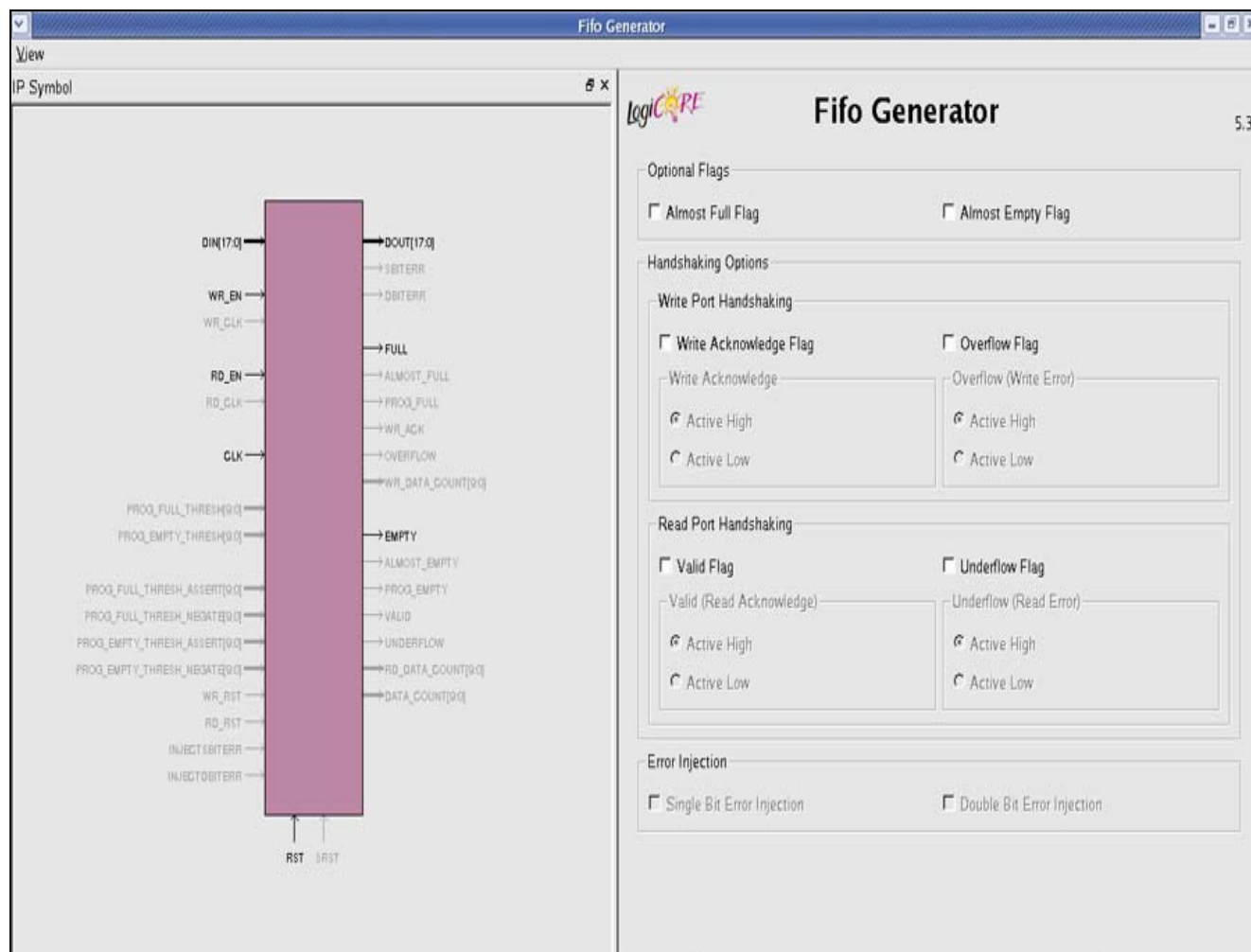


Figure 3-3: Optional Flags, Handshaking, and Error Injection Options Screen

### Optional Flags

#### Almost Full Flag

Available in all FIFO implementations except those using Virtex-6, Virtex-5 or Virtex-4 FPGA built-in FIFOs. Generates an output port that indicates the FIFO is almost full (only one more word can be written).

## Almost Empty Flag

Available in all FIFO implementations except in those using Virtex-6, Virtex-5 or Virtex-4 FPGA built-in FIFOs. Generates an output port that indicates the FIFO is almost empty (only one more word can be read).

## Handshaking Options

### Write Port Handshaking

#### Write Acknowledge

Generates write acknowledge flag which reports the success of a write operation. This signal can be configured to be active high or low (default active high).

#### Overflow (Write Error)

Generates overflow flag which indicates when the previous write operation was not successful. This signal can be configured to be active high or low (default active high).

### Read Port Handshaking

#### Valid (Read Acknowledge)

Generates valid flag which indicates when the data on the output bus is valid. This signal can be configured to be active high or low (default active high).

#### Underflow (Read Error)

Generates underflow flag to indicate that the previous read request was not successful. This signal can be configured to be active high or low (default active high).

## Error Injection

### Single Bit Error Injection

Available only in Virtex-6 FPGAs for both the common and independent clock block RAM or built-in FIFOs, with ECC option enabled. Generates an input port to inject a single bit error on write and an output port that indicates a single bit error occurred.

### Double Bit Error Injection

Available only in Virtex-6 FPGAs for both the common and independent clock block RAM or built-in FIFOs, with ECC option enabled. Generates an input port to inject a double bit error on write and an output port that indicates a double bit error occurred.

## Initialization and Programmable Flags

Use this screen to select the initialization values and programmable flag type when generating a specific FIFO Generator configuration.

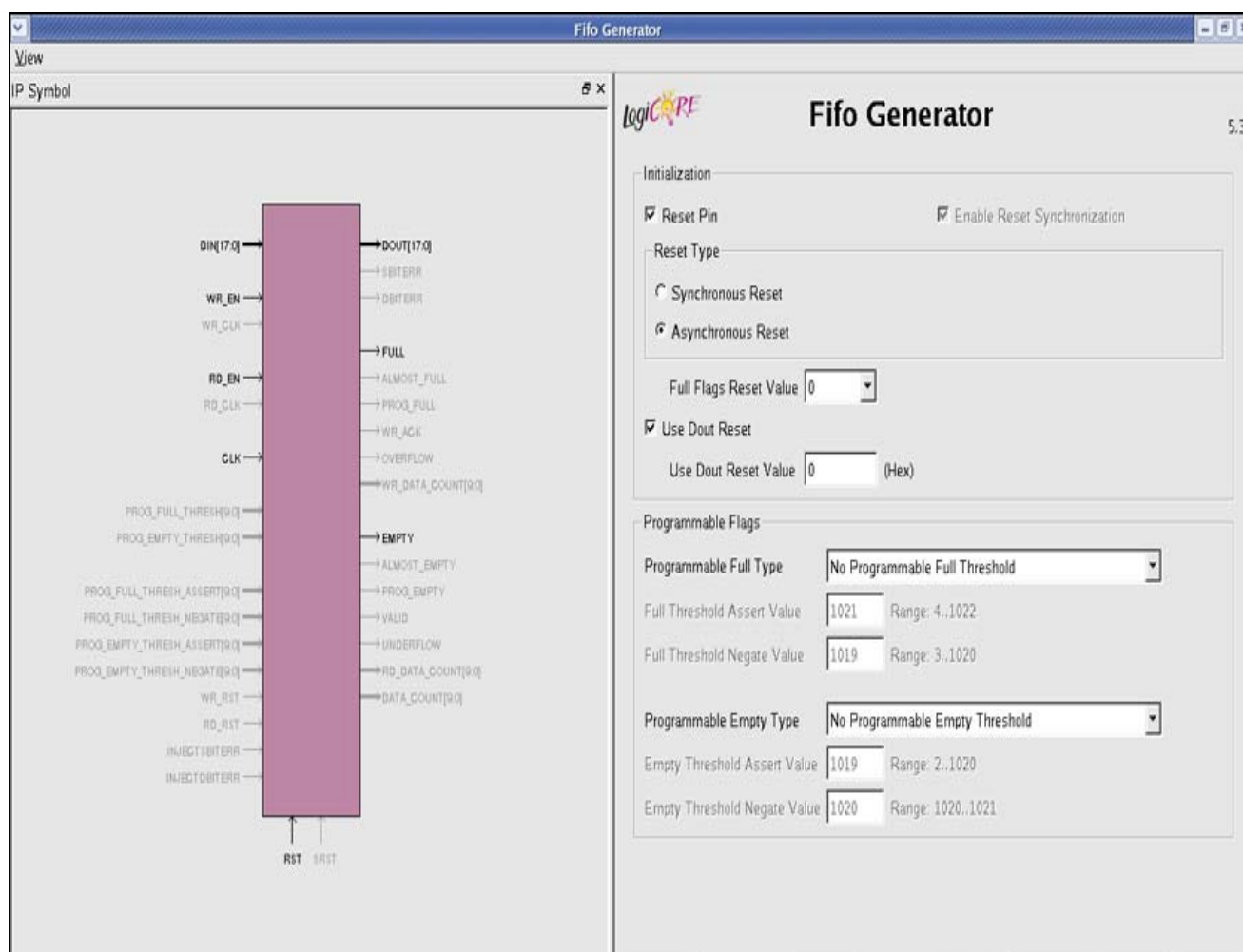


Figure 3-4: Programmable Flags and Reset Screen

### Initialization

#### Reset Pin

For FIFOs implemented with block RAM or distributed RAM, a reset pin is not required, and the input pin is optional.

- **Enable Reset Synchronization.** Optional selection only available for independent clock block RAM or distributed RAM FIFOs. When unchecked, WR\_RST/RD\_RST is available. See [“Reset Behavior” in Chapter 4](#) for details.
- **Asynchronous Reset.** Optional selection for a common-clock FIFO implemented using distributed or block RAM.
- **Synchronous Reset.** Optional selection for a a common-clock FIFO implemented using distributed or block RAM.

### Full Flags Reset Value

For block RAM, distributed RAM, and shift register configurations, the user can choose the reset value of the full flags (PROG\_FULL, ALMOST\_FULL, and FULL) during reset.

### Use Dout Reset

Available in Virtex-4 FPGA or newer architectures for all implementations using block RAM, distributed RAM, shift register or Virtex-6 common clock built-in with embedded register option. Only available if a reset pin option is selected. If selected, the DOUT output of the FIFO will reset to the defined DOUT Reset Value (below) when the reset is asserted. If not selected, the DOUT output of the FIFO will not be effected by the assertion of reset, and DOUT will hold its previous value.

Disabling this feature for Spartan®-3 devices may improve timing for the distributed RAM and shift register FIFO.

### Use Dout Reset Value

Available only when Use Dout Reset is selected, this field indicates the hexadecimal value asserted on the output of the FIFO when RST (SRST) is asserted. See [Appendix C, "DOUT Reset Value Timing"](#) for the timing diagrams for different configurations.

## Programmable Flags

### Programmable Full Type

Select a programmable full threshold type from the drop-down menu. The valid range for each threshold is displayed and varies depending on the options selected elsewhere in the GUI.

#### Full Threshold Assert Value

Available when Programmable Full with Single or Multiple Threshold Constants is selected. Enter a user-defined value. The valid range for this threshold is provided in the GUI. When using a single threshold constant, only the assert threshold value is used.

#### Full Threshold Negate Value

Available when Programmable Full with Multiple Threshold Constants is selected. Enter a user-defined value. The valid range for this threshold is provided in the GUI.

### Programmable Empty Type

Select a programmable empty threshold type from the drop-down menu. The valid range for each threshold is displayed, and will vary depending on options selected elsewhere in the GUI.

#### Empty Threshold Assert Value

Available when Programmable Empty with Single or Multiple Threshold Constants is selected. Enter a user-defined value. The valid range for this threshold is provided in the GUI. When using a single threshold constant, only the assert value is used.

## Empty Threshold Negate Value

Available when Programmable Empty with Multiple Threshold Constants is selected. Enter a user-defined value. The valid range for this threshold is provided in the GUI.

## Data Count

Use this screen to set data count options.

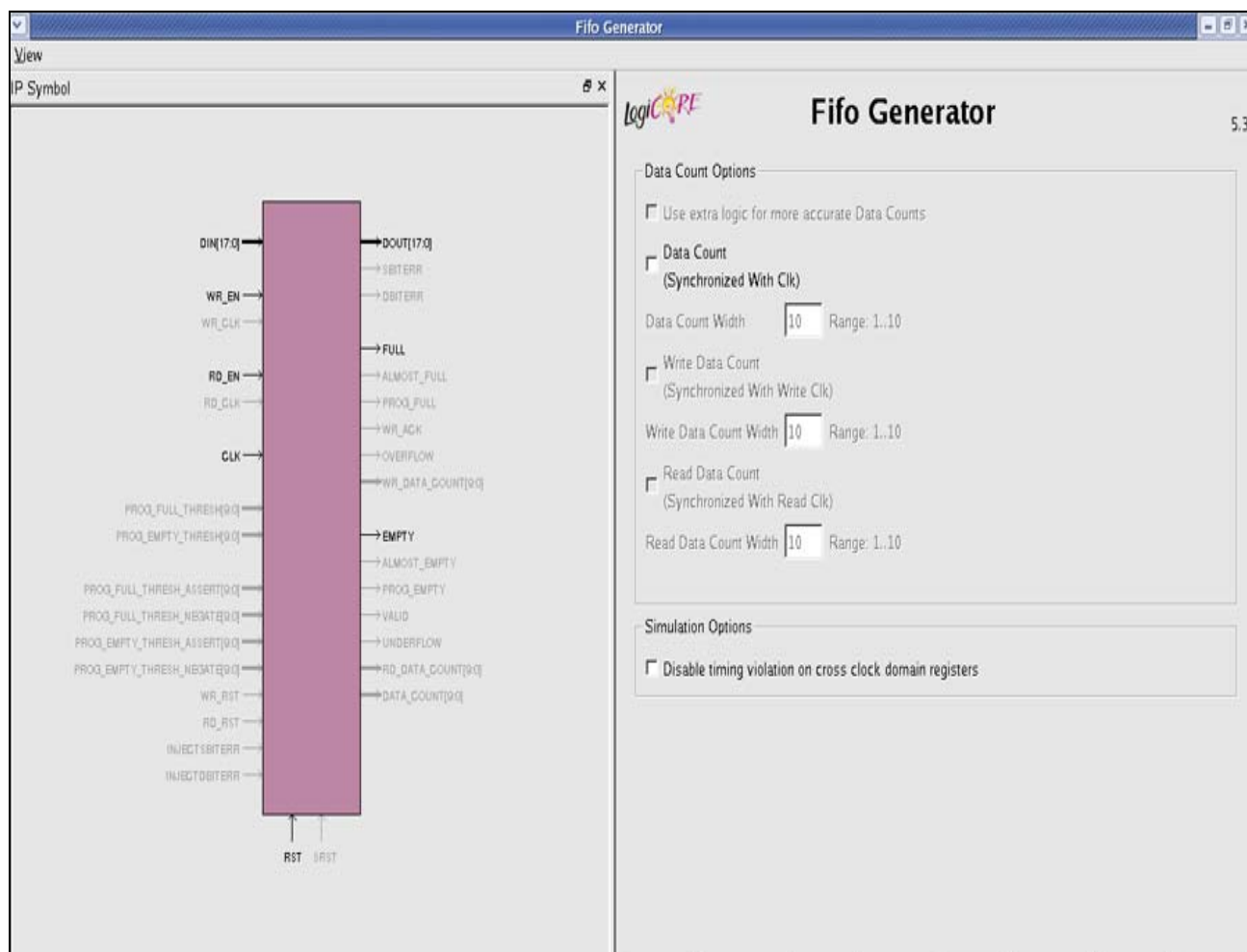


Figure 3-5: Data Count Screen

## Data Count Options

### Use Extra Logic For More Accurate Data Counts

Only available for independent clocks FIFO with block RAM or distributed RAM, and when using first-word fall-through. This option uses additional external logic to generate a more accurate data count. This feature is always enabled for common clock FIFOs with block RAM or distributed RAM and when using first-word-fall-through. See [“First-Word Fall-Through Data Count,”](#) page 64 for details.



### Data Count (Synchronized With Clk)

Available when a common clock FIFO with block RAM, distributed RAM, or shift registers is selected.

#### Data Count Width

Available when Data Count is selected. Valid range is from 1 to  $\log_2$  (input depth).

### Write Data Count (Synchronized with Write Clk)

Available when an independent clocks FIFO with block RAM or distributed RAM is selected.

#### Write Data Count Width

Available when Write Data Count is selected. Valid range is from 1 to  $\log_2$  (input depth).

### Read Data Count (Synchronized with Read Clk)

Available when an independent clocks FIFO with block RAM or distributed RAM is selected.

#### Read Data Count Width

Available when Read Data Count is selected. Valid range is from 1 to  $\log_2$  (output depth).

## Summary

This screen displays a summary of the selected FIFO options, including the FIFO type, FIFO dimensions, and the status of any additional features selected. In the Additional Features section, most features display either *Not Selected* (if unused), or *Selected* (if used).

**Note:** Write depth and read depth provide the actual FIFO depths for the selected configuration. These depths may differ slightly from the depth selected on screen 2 of the FIFO GUI.

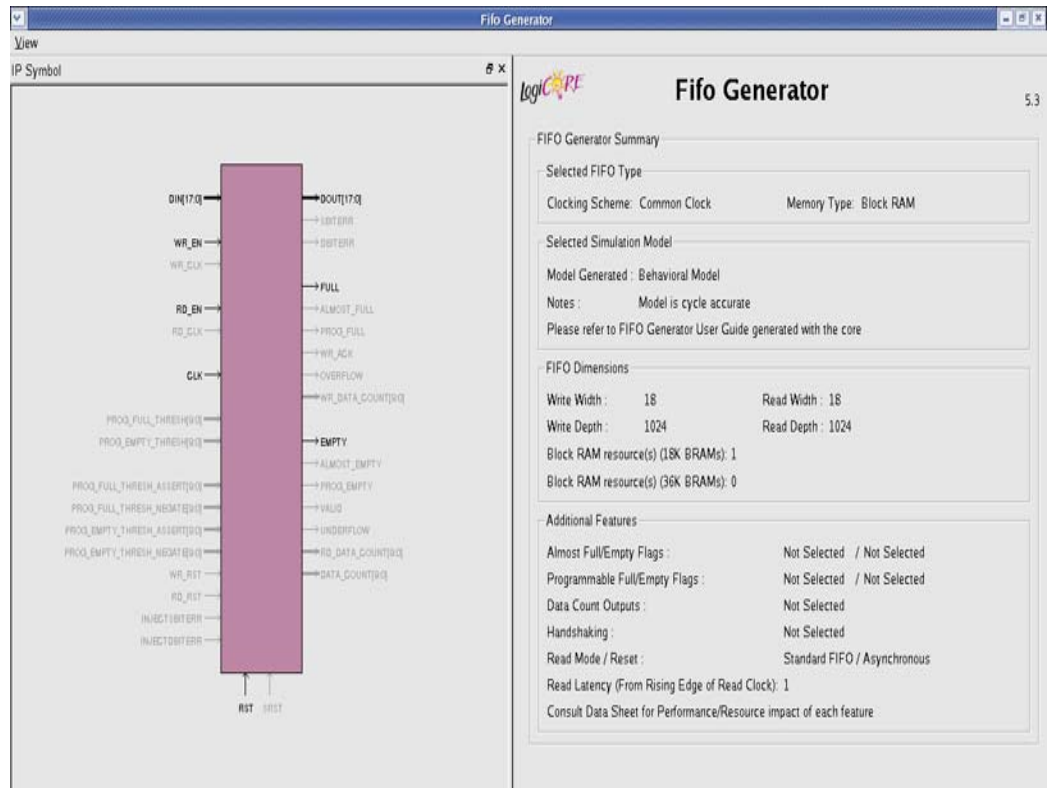


Figure 3-6: Summary Screen

# Designing with the Core

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This chapter describes the steps required to turn a FIFO Generator core into a fully functioning design integrated with the user application logic. It is important to note that depending on the configuration of the FIFO core, only a subset of the implementation details provided are applicable. For successful use of a FIFO core, the design guidelines discussed in this chapter must be observed.

## General Design Guidelines

### Know the Degree of Difficulty

A fully-compliant and feature-rich FIFO design is challenging to implement in any technology. For this reason, it is important to understand that the degree of difficulty can be significantly influenced by

- Maximum system clock frequency
- Targeted device architecture
- Specific user application

Ensure that design techniques are used to facilitate implementation, including pipelining and use of constraints (timing constraints, and placement and/or area constraints).

### Understand Signal Pipelining and Synchronization

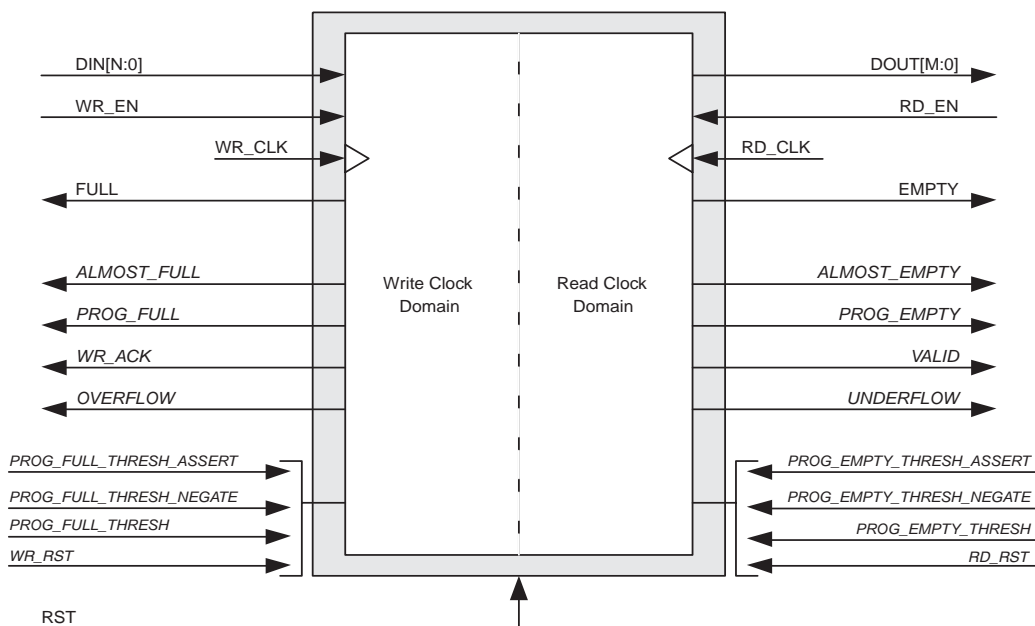
To understand the nature of FIFO designs, it is important to understand how pipelining is used to maximize performance and implement synchronization logic for clock-domain crossing. Data written into the write interface may take multiple clock cycles before it can be accessed on the read interface.

### Synchronization Considerations

FIFOs with independent write and read clocks require that interface signals be used only in their respective clock domains. The independent clocks FIFO handles all synchronization requirements, enabling the user to cross between two clock domains that have no relationship in frequency or phase.

**Important:** FIFO Full and Empty flags must be used to guarantee proper behavior.

Figure 4-1 shows the signals with respect to their clock domains. All signals are synchronous to a specific clock, with the exception of RST, which performs an asynchronous reset of the entire FIFO.



Note: Optional ports represented in *italics*

**Figure 4-1: FIFO with Independent Clocks: Write and Read Clock Domains**

For write operations, the write enable signal (`WR_EN`) and data input (`DIN`) are synchronous to `WR_CLK`. For read operations, the read enable (`RD_EN`) and data output (`DOUT`) are synchronous to `RD_CLK`. All status outputs are synchronous to their respective clock domains and can only be used in that clock domain. The performance of the FIFO can be measured by independently constraining the clock period for the `WR_CLK` and `RD_CLK` input signals.

The interface signals are evaluated on their rising clock edge (`WR_CLK` and `RD_CLK`). They can be made falling-edge active (relative to the clock source) by inserting an inverter between the clock source and the FIFO clock inputs. This inverter is absorbed into the internal FIFO control logic and does not cause a decrease in performance or increase in logic utilization.

## Initializing the FIFO Generator

When designing with the built-in FIFO or common clock shift register FIFO, the FIFO must be reset after the FPGA is configured and before operation begins. An asynchronous reset pin (`RST`) is provided, which is an asynchronous reset that clears the internal counters and output registers.

For FIFOs implemented with block RAM or distributed RAM, a reset is not required, and the input pin is optional. For common clock configurations, users have the option of asynchronous or synchronous reset. For independent clock configurations, users have the option of asynchronous reset (`RST`) or synchronous reset (`WR_RST`/`RD_RST`) with respect to respective clock domains.

When asynchronous reset is implemented (Enable Reset Synchronization option is selected), it is synchronized to the clock domain in which it is used to ensure that the FIFO initializes to a known state. This synchronization logic allows for proper reset timing of the core logic, avoiding glitches and metastable behavior. The reset pulse and synchronization delay requirements are dependent on the FIFO implementation types.

When WR\_RST/RD\_RST is implemented (Enable Reset Synchronization option is not selected), the WR\_RST/RD\_RST is treated as a synchronous reset to the respective clock domain. The write clock domain remains in reset state as long as WR\_RST is asserted, and the read clock domain remains in reset state as long as RD\_RST is asserted. See [“Reset Behavior,” page 73](#).

## FIFO Implementations

Each FIFO configuration has a set of allowable features, as defined in [Table 2-3, page 21](#).

### Independent Clocks: Block RAM and Distributed RAM

[Figure 4-2](#) illustrates the functional implementation of a FIFO configured with independent clocks. This implementation uses block RAM or distributed RAM for

memory, counters for write and read pointers, conversions between binary and Gray code for synchronization across clock domains, and logic for calculating the status flags.

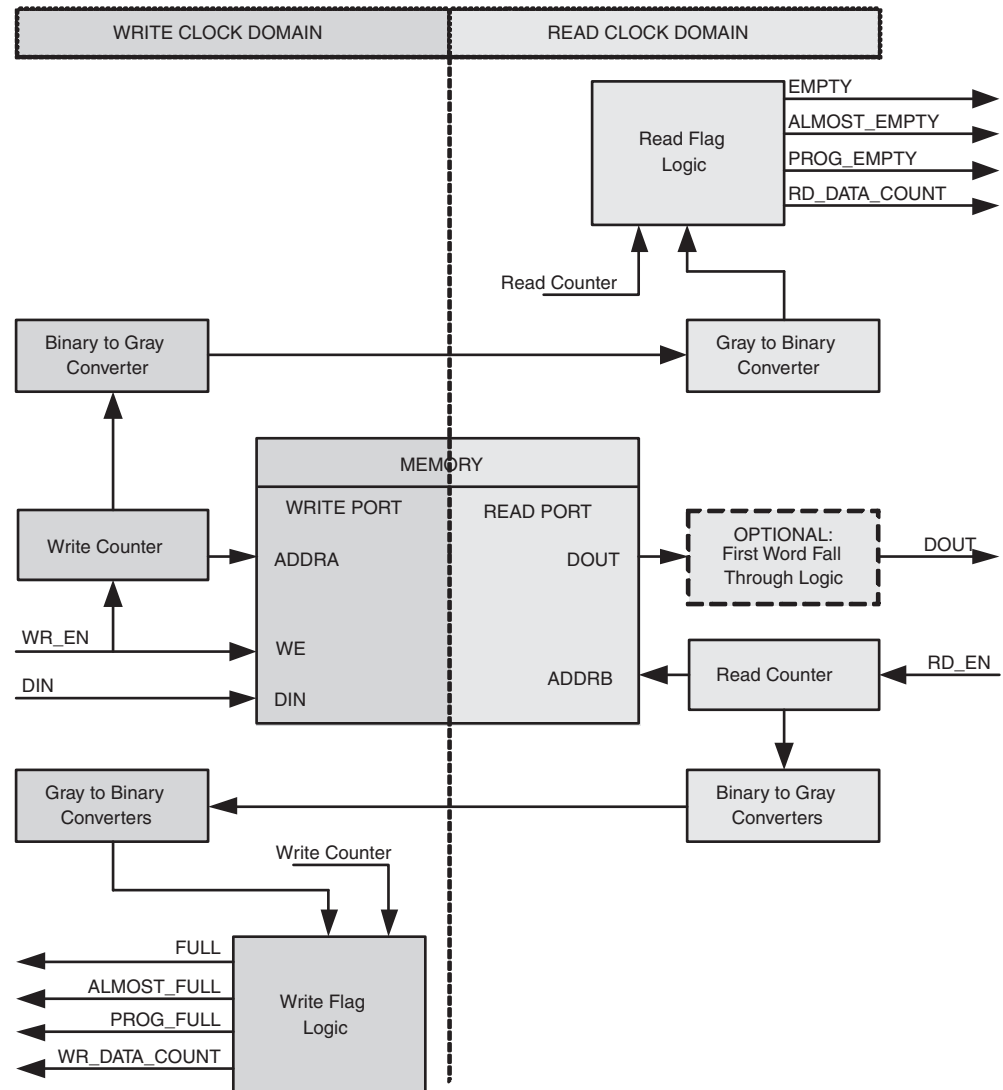


Figure 4-2: Functional Implementation of a FIFO with Independent Clock Domains

This FIFO is designed to support an independent read clock (RD\_CLK) and write clock (WR\_CLK); in other words, there is no required relationship between RD\_CLK and WR\_CLK with regard to frequency or phase. [Table 4-1](#) summarizes the FIFO interface signals, which are only valid in their respective clock domains.

**Table 4-1: Interface Signals and Corresponding Clock Domains**

WR_CLK	RD_CLK
DIN	DOUT
WR_EN	RD_EN
FULL	EMPTY
ALMOST_FULL	ALMOST_EMPTY
PROG_FULL	PROG_EMPTY
WR_ACK	VALID
OVERFLOW	UNDERFLOW
WR_DATA_COUNT	RD_DATA_COUNT
WR_RST	SBITERR
INJECTSBITERR	DBITERR
INJECTDBITERR	RD_RST

For FIFO cores using independent clocks, the timing relationship between the write and read operations and the status flags is affected by the relationship of the two clocks. For example, the timing between writing to an empty FIFO and the deassertion of EMPTY is determined by the phase and frequency relationship between the write and read clocks. For additional information refer to the [“Synchronization Considerations,”](#) page 43.

## Independent Clocks: Built-in FIFO

[Figure 4-3](#) illustrates the functional implementation of FIFO configured with independent clocks using the Virtex-6 and Virtex-5 FPGA built-in FIFO primitive. This design implementation consists of cascaded built-in FIFO primitives and handshaking logic. The number of built-in primitives depends on the FIFO width and depth requested.

The Virtex-4 FPGA built-in FIFO implementation allows generation of a single primitive. The generated core includes a FIFO flag patch (defined in "Solution 1: Synchronous/Asynchronous Clock Work-Arounds," in the *Virtex-4 FPGA User Guide*).

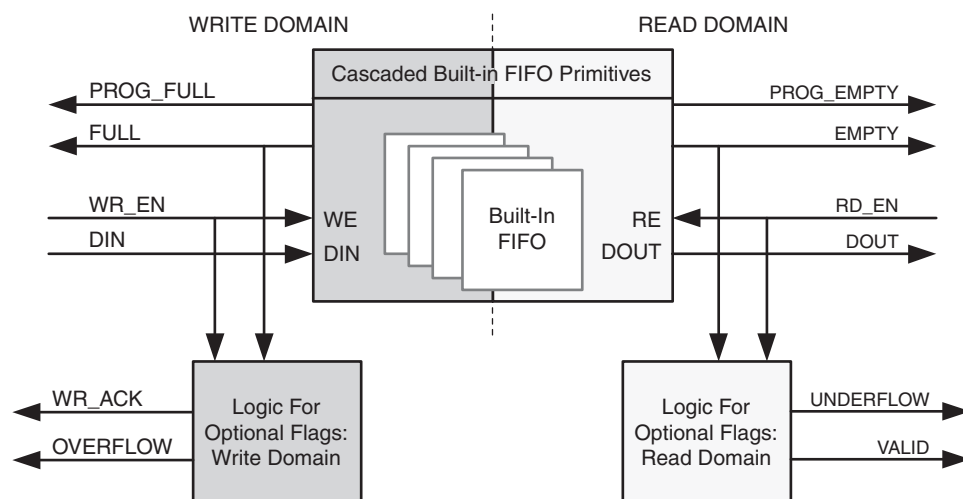


Figure 4-3: Functional Implementation of Built-in FIFO

This FIFO is designed to support an independent read clock (RD\_CLK) and write clock (WR\_CLK); in other words, there is no required relationship between RD\_CLK and WR\_CLK with regard to frequency or phase. Table 4-2 summarizes the FIFO interface signals, which are only valid in their respective clock domains.

Table 4-2: Interface Signals and Corresponding Clock Domains

WR_CLK	RD_CLK
DIN	DOUT
WR_EN	RD_EN
FULL	EMPTY
PROG_FULL	PROG_EMPTY
WR_ACK	VALID
OVERFLOW	UNDERFLOW
INJECTSBITERR	SBITERR
INJECTDBITERR	DBITERR

For FIFO cores using independent clocks, the timing relationship between the write and read operations and the status flags is affected by the relationship of the two clocks. For example, the timing between writing to an empty FIFO and the deassertion of EMPTY is determined by the phase and frequency relationship between the write and read clocks. For additional information, see [“Synchronization Considerations,”](#) page 43.

For Virtex-6 and Virtex-5 FPGA built-in FIFO configurations, the built-in ECC feature in the FIFO macro is provided. For more information, see [“Built-in Error Correction Checking,”](#) page 71.

## Common Clock: Built-in FIFO

The FIFO Generator supports FIFO cores using the built-in FIFO primitive with a common clock. This provides users the ability to use the built-in FIFO, while requiring only a single



clock interface. The behavior of the common clock configuration with built-in FIFO is identical to the independent clock configuration with built-in FIFO, except all operations are in relation to the common clock (CLK). See [“Independent Clocks: Built-in FIFO,”](#) page 47, for more information.

## Common Clock FIFO: Block RAM and Distributed RAM

Figure 4-4 illustrates the functional implementation of a FIFO configured with a common clock using block RAM or distributed RAM for memory. All signals are synchronous to a single clock input (CLK). This design implements counters for write and read pointers and logic for calculating the status flags. An optional synchronous (SRST) or asynchronous (RST) reset signal is also available.

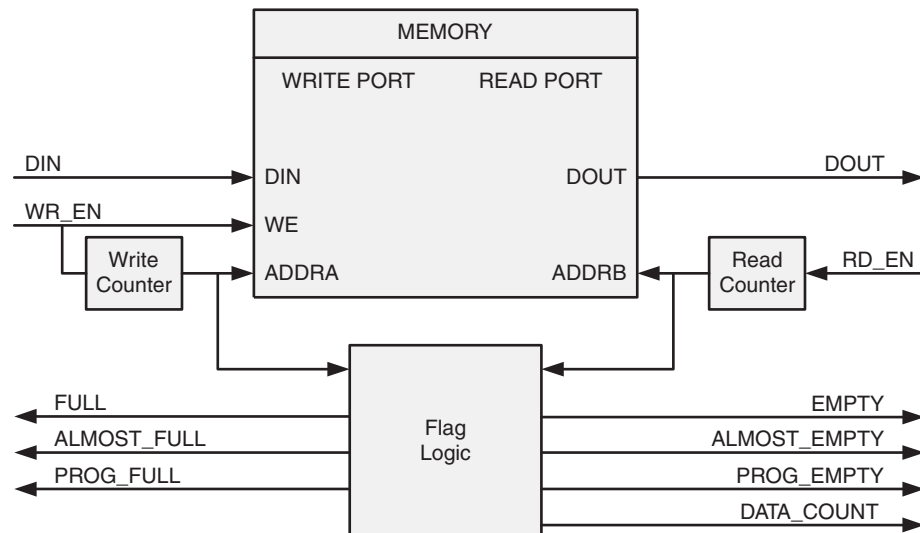


Figure 4-4: Functional Implementation of a Common Clock FIFO using Block RAM or Distributed RAM

## Common Clock FIFO: Shift Registers

Figure 4-5 illustrates the functional implementation of a FIFO configured with a common clock using shift registers for memory. All operations are synchronous to the same clock

input (CLK). This design implements a single up/down counter for both the write and read pointers and logic for calculating the status flags.

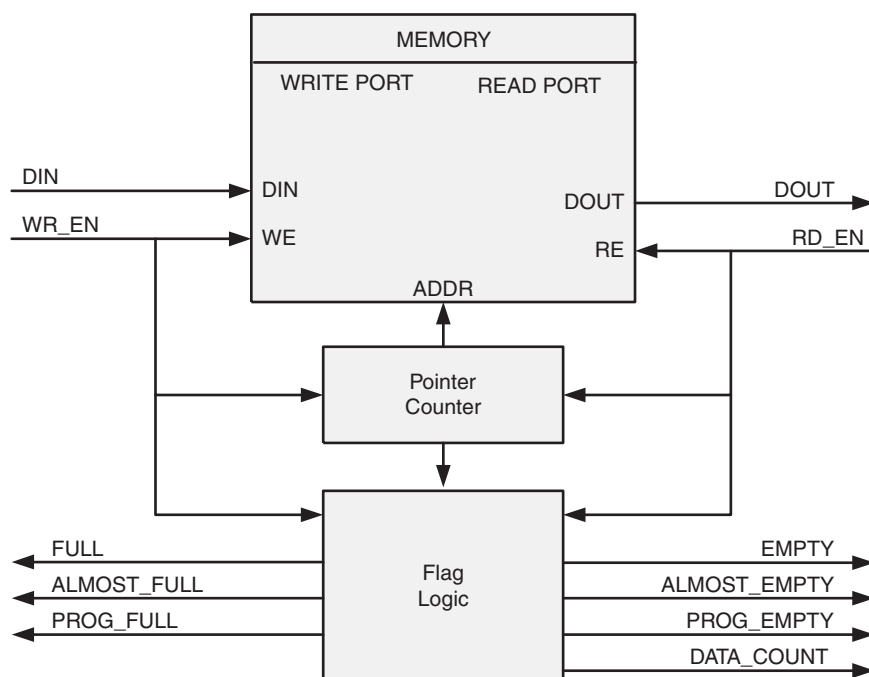


Figure 4-5: Functional Implementation of a Common Clock FIFO using Shift Registers

## FIFO Usage and Control

### Write Operation

This section describes the behavior of a FIFO write operation and the associated status flags. When write enable is asserted and the FIFO is not full, data is added to the FIFO from the input bus (DIN) and write acknowledge (WR\_ACK) is asserted. If the FIFO is continuously written to without being read, it fills with data. Write operations are only successful when the FIFO is not full. When the FIFO is full and a write is initiated, the request is ignored, the overflow flag is asserted and there is no change in the state of the FIFO (overflowing the FIFO is non-destructive).

### ALMOST\_FULL and FULL Flags

**Note:** The Built-in FIFO for Virtex-6, Virtex-5 and Virtex-4 FPGAs do not support the ALMOST\_FULL flag.

The almost full flag (ALMOST\_FULL) indicates that only one more write can be performed before FULL is asserted. This flag is active high and synchronous to the write clock (WR\_CLK).

The full flag (FULL) indicates that the FIFO is full and no more writes can be performed until data is read out. This flag is active high and synchronous to the write clock (WR\_CLK). If a write is initiated when FULL is asserted, the write request is ignored and OVERFLOW is asserted.

**Important:** For the Virtex-4 FPGA built-in FIFO implementation, the Full signal has an extra cycle of latency. Use Write Acknowledge to verify success or Programmable Full for an earlier indication.

## Example Operation

Figure 4-6 shows a typical write operation. The user asserts `WR_EN`, causing a write operation to occur on the next rising edge of the `WR_CLK`. Because the FIFO is not full, `WR_ACK` is asserted, acknowledging a successful write operation. When only one additional word can be written into the FIFO, the FIFO asserts the `ALMOST_FULL` flag. When `ALMOST_FULL` is asserted, one additional write causes the FIFO to assert `FULL`. When a write occurs after `FULL` is asserted, `WR_ACK` is deasserted and `OVERFLOW` is asserted, indicating an overflow condition. Once the user performs one or more read operations, the FIFO deasserts `FULL`, and data can successfully be written to the FIFO, as is indicated by the assertion of `WR_ACK` and deassertion of `OVERFLOW`.

**Note:** The Virtex-4 FPGA built-in FIFO implementation shows an extra cycle of latency on the `FULL` flag.

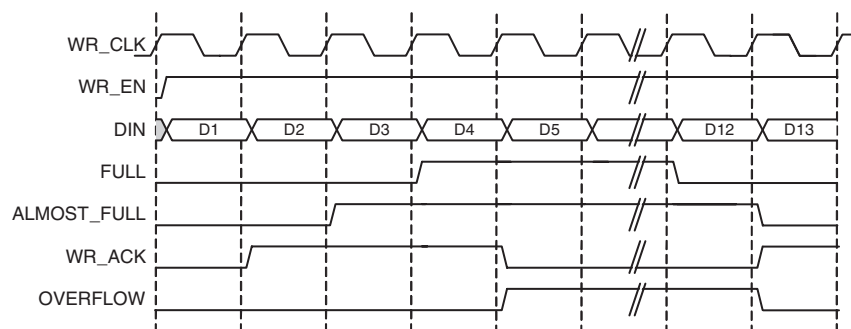


Figure 4-6: Write Operation for a FIFO with Independent Clocks

## Read Operation

This section describes the behavior of a FIFO read operation and the associated status flags. When read enable is asserted and the FIFO is not empty, data is read from the FIFO on the output bus (`DOUT`), and the valid flag (`VALID`) is asserted. If the FIFO is continuously read without being written, the FIFO empties. Read operations are successful when the FIFO is not empty. When the FIFO is empty and a read is requested, the read operation is ignored, the underflow flag is asserted and there is no change in the state of the FIFO (underflowing the FIFO is non-destructive).

## ALMOST\_EMPTY and EMPTY Flags

**Note:** The Virtex-6, Virtex-5 and Virtex-4 FPGAs built-in FIFO does not support the `ALMOST_EMPTY` flag.

The almost empty flag (`ALMOST_EMPTY`) indicates that the FIFO will be empty after one more read operation. This flag is active high and synchronous to `RD_CLK`. This flag is asserted when the FIFO has one remaining word that can be read.

The empty flag (`EMPTY`) indicates that the FIFO is empty and no more reads can be performed until data is written into the FIFO. This flag is active high and synchronous to the read clock (`RD_CLK`). If a read is initiated when `EMPTY` is asserted, the request is ignored and `UNDERFLOW` is asserted.

## Common Clock Note

When write and read operations occur simultaneously while `EMPTY` is asserted, the write operation is accepted and the read operation is ignored. On the next clock cycle, `EMPTY` is deasserted and `UNDERFLOW` is asserted.

## Modes of Read Operation

The FIFO Generator supports two modes of read options, standard read operation and first-word fall-through (FWFT) read operation. The standard read operation provides the user data on the cycle after it was requested. The FWFT read operation provides the user data on the same cycle in which it is requested.

Table 4-3 details the supported implementations for FWFT.

**Table 4-3: Implementation-Specific Support for First-Word Fall-Through**

FIFO Implementation		FWFT Support
Independent Clocks	Block RAM	✓
	Distributed RAM	✓
	Built-in	✓ <sup>(1)</sup>
Common Clock	Block RAM	✓
	Distributed RAM	✓
	Shift Register	
	Built-in	✓ <sup>(1)</sup>

### Notes:

1. Only supported in Virtex-6 and Virtex-5 FPGAs.

## Standard FIFO Read Operation

For a standard FIFO read operation, after read enable is asserted and if the FIFO is not empty, the next data stored in the FIFO is driven on the output bus (`DOUT`) and the valid flag (`VALID`) is asserted.

Figure 4-7 shows a standard read access. Once the user writes at least one word into the FIFO, `EMPTY` is deasserted—indicating data is available to be read. The user asserts `RD_EN`, causing a read operation to occur on the next rising edge of `RD_CLK`. The FIFO outputs the next available word on `DOUT` and asserts `VALID`, indicating a successful read operation. When the last data word is read from the FIFO, the FIFO asserts `EMPTY`. If the user continues to assert `RD_EN` while `EMPTY` is asserted, the read request is ignored, `VALID` is deasserted, and `UNDERFLOW` is asserted. Once the user performs a write operation, the FIFO deasserts `EMPTY`, allowing the user to resume valid read operations, as indicated by the assertion of `VALID` and deassertion of `UNDERFLOW`.

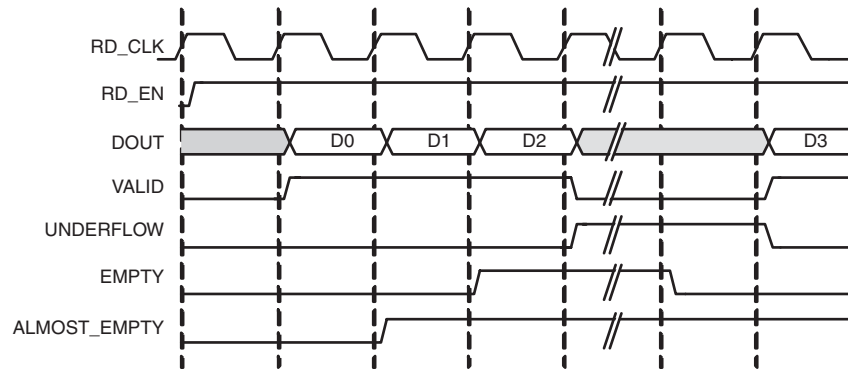


Figure 4-7: Standard Read Operation for a FIFO with Independent Clocks

### First-Word-Fall-Through FIFO Read Operation

The first-word-fall-through (FWFT) feature provides the ability to look-ahead to the next word available from the FIFO without issuing a read operation. When data is available in the FIFO, the first word falls through the FIFO and appears automatically on the output bus (DOUT). Once the first word appears on DOUT, `EMPTY` is deasserted indicating one or more readable words in the FIFO, and `VALID` is asserted, indicating a valid word is present on DOUT.

Figure 4-8 shows a FWFT read access. Initially, the FIFO is not empty, the next available data word is placed on the output bus (DOUT), and `VALID` is asserted. When the user asserts `RD_EN`, the next rising clock edge of `RD_CLK` places the next data word onto DOUT. After the last data word has been placed on DOUT, an additional read request by the user causes the data on DOUT to become invalid, as indicated by the deassertion of `VALID` and the assertion of `EMPTY`. Any further attempts to read from the FIFO results in an underflow condition.

Unlike the standard read mode, the first-word-fall-through empty flag is asserted after the last data is read from the FIFO. When `EMPTY` is asserted, `VALID` is deasserted. In the standard read mode, when `EMPTY` is asserted, `VALID` is asserted for 1 clock cycle. The FWFT feature also increases the effective read depth of the FIFO by two read words.

The FWFT feature adds two clock cycle latency to the deassertion of empty, when the first data is written into a empty FIFO.

**Note:** For every write operation, an equal number of read operations is required to empty the FIFO—this is true for both the first-word-fall-through and standard FIFO.

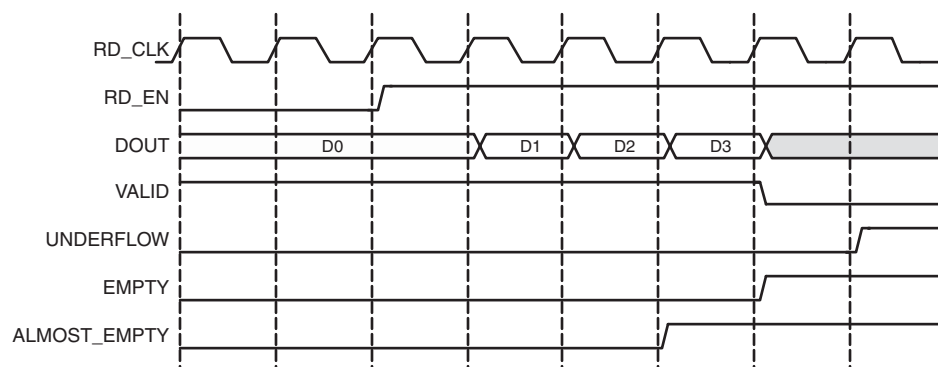


Figure 4-8: FWFT Read Operation for a FIFO with Independent Clocks

## Common Clock FIFO, Simultaneous Read and Write Operation

Figure 4-9 shows a typical write and read operation. A write is issued to the FIFO, resulting in the deassertion of the `EMPTY` flag. A simultaneous write and read is then issued, resulting in no change in the status flags. Once two or more words are present in the FIFO, the `ALMOST_EMPTY` flag is deasserted. Write requests are then issued to the FIFO, resulting in the assertion of `ALMOST_FULL` when the FIFO can only accept one more write (without a read). A simultaneous write and read is then issued, resulting in no change in the status flags. Finally one additional write without a read results in the FIFO asserting `FULL`, indicating no further data can be written until a read request is issued.

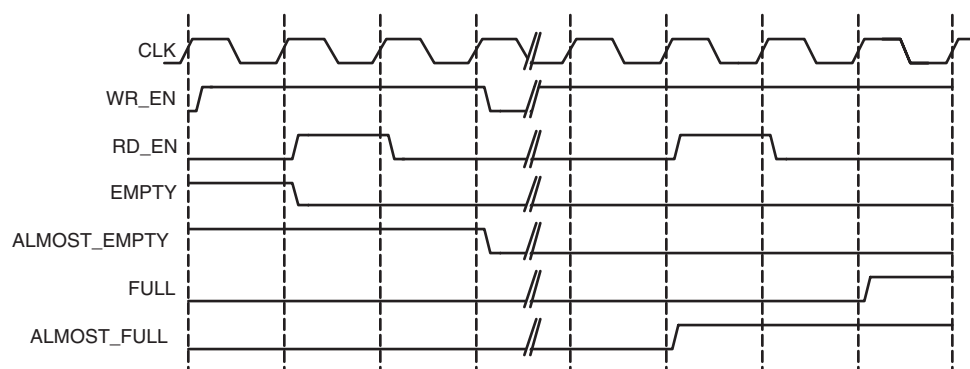


Figure 4-9: Write and Read Operation for a FIFO with Common Clocks

## Handshaking Flags

Handshaking flags (valid, underflow, write acknowledge and overflow) are supported to provide additional information regarding the status of the write and read operations. The handshaking flags are optional, and can be configured as active high or active low through the CORE Generator GUI (see Handshaking Options in Chapter 4 for more information). These flags (configured as active high) are illustrated in Figure 4-10.

### Write Acknowledge

The write acknowledge flag (`WR_ACK`) is asserted at the completion of each successful write operation and indicates that the data on the `DIN` port has been stored in the FIFO. This flag is synchronous to the write clock (`WR_CLK`).

### Valid

The operation of the valid flag (`VALID`) is dependent on the read mode of the FIFO. This flag is synchronous to the read clock (`RD_CLK`).

### Standard FIFO Read Operation

For standard read operation, the `VALID` flag is asserted at the rising edge of `RD_CLK` for each successful read operation, and indicates that the data on the `DOUT` bus is valid. When a read request is unsuccessful (when the FIFO is empty), `VALID` is not asserted.

### FWFT FIFO Read Operation

For FWFT read operation, the `VALID` flag indicates the data on the output bus (`DOUT`) is valid for the current cycle. A read request does not have to happen for data to be present and valid, as the first-word fall-through logic automatically places the next data to be read

on the DOUT bus. `VALID` is asserted if there is one or more words in the FIFO. `VALID` is deasserted when there are no more words in the FIFO.

## Example Operation

[Figure 4-10](#) illustrates the behavior of the FIFO flags. On the write interface, `FULL` is not asserted and writes to the FIFO are successful (as indicated by the assertion of `WR_ACK`). When a write occurs after `FULL` is asserted, `WR_ACK` is deasserted and `OVERFLOW` is asserted, indicating an overflow condition. On the read interface, once the FIFO is not `EMPTY`, the FIFO accepts read requests. In standard FIFO operation, `VALID` is asserted and `DOUT` is updated on the clock cycle following the read request. In FWFT operation, `VALID` is asserted and `DOUT` is updated prior to a read request being issued. When a read request is issued while `EMPTY` is asserted, `VALID` is deasserted and `UNDERFLOW` is asserted, indicating an underflow condition.

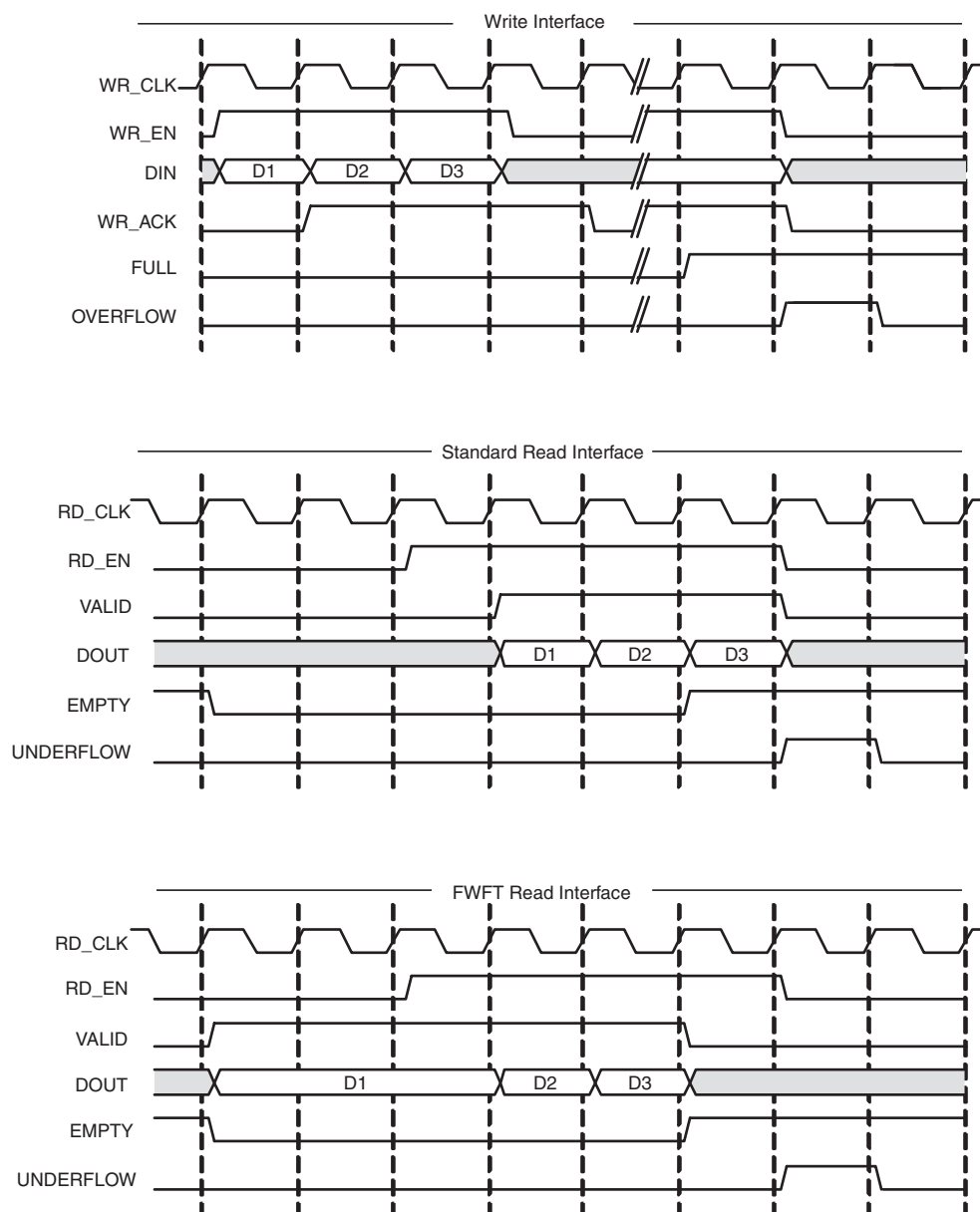


Figure 4-10: Handshaking Signals for a FIFO with Independent Clocks

## Underflow

The underflow flag (UNDERFLOW) is used to indicate that a read operation is unsuccessful. This occurs when a read is initiated and the FIFO is empty. This flag is synchronous with the read clock (RD\_CLK). Underflowing the FIFO does not change the state of the FIFO (it is non-destructive).



## Overflow

The overflow flag (**OVERFLOW**) is used to indicate that a write operation is unsuccessful. This flag is asserted when a write is initiated to the FIFO while **FULL** is asserted. The overflow flag is synchronous to the write clock (**WR\_CLK**). Overflowing the FIFO does not change the state of the FIFO (it is non-destructive).

## Example Operation

Figure 4-11 illustrates the Handshaking flags. On the write interface, **FULL** is deasserted and therefore writes to the FIFO are successful (indicated by the assertion of **WR\_ACK**). When a write occurs after **FULL** is asserted, **WR\_ACK** is deasserted and **OVERFLOW** is asserted, indicating an overflow condition. On the read interface, once the FIFO is not **EMPTY**, the FIFO accepts read requests. Following a read request, **VALID** is asserted and **DOUT** is updated. When a read request is issued while **EMPTY** is asserted, **VALID** is deasserted and **UNDERFLOW** is asserted, indicating an underflow condition.

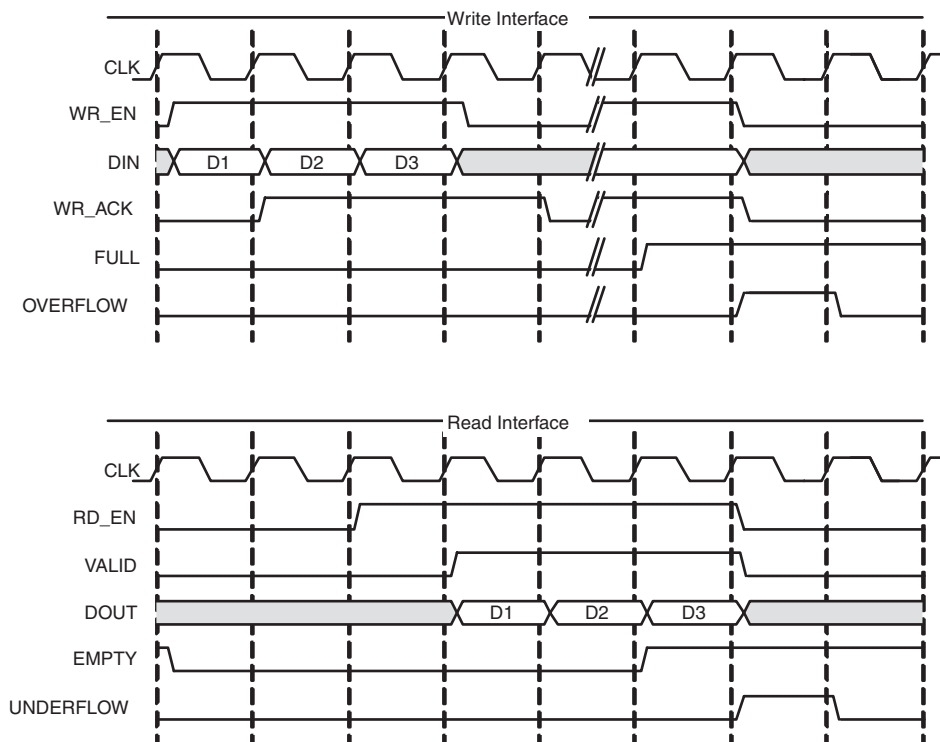


Figure 4-11: Handshaking Signals for a FIFO with Common Clocks

## Programmable Flags

The FIFO supports programmable flags to indicate that the FIFO has reached a user-defined fill level.

- Programmable full (**PROG\_FULL**) indicates that the FIFO has reached a user-defined full threshold.
- Programmable empty (**PROG\_EMPTY**) indicates that the FIFO has reached a user-defined empty threshold.

For these thresholds, the user can set a constant value or choose to have dedicated input ports, enabling the thresholds to change dynamically in circuit. Hysteresis is also optionally supported, by providing unique assert and negate values for each flag. Detailed information about these options are provided below. For information about the latency behavior of the programmable flags, see “Latency,” page 82.

## Programmable Full

The FIFO Generator supports four ways to define the programmable full threshold:

- Single threshold constant
- Single threshold with dedicated input port
- Assert and negate threshold constants (provides hysteresis)
- Assert and negate thresholds with dedicated input ports (provides hysteresis)

**Note:** The built-in FIFOs only support single-threshold constant programmable full.

These options are available in the CORE Generator GUI and accessed within the programmable flags window (Figure 3-4).

The programmable full flag (PROG\_FULL) is asserted when the number of entries in the FIFO is greater than or equal to the user-defined assert threshold. When the programmable full flag is asserted, the FIFO can continue to be written to until the full flag (FULL) is asserted. If the number of words in the FIFO is less than the negate threshold, the flag is deasserted.

**Note:** If a write operation occurs on a rising clock edge that causes the number of words to meet or exceed the programmable full threshold, then the programmable full flag will assert on the next rising clock edge. The deassertion of the programmable full flag has a longer delay, and depends on the relationship between the write and read clocks.

### Programmable Full: Single Threshold

This option enables the user to set a single threshold value for the assertion and deassertion of PROG\_FULL. When the number of entries in the FIFO is greater than or equal to the threshold value, PROG\_FULL is asserted. The deassertion behavior differs between built-in and non built-in FIFOs (block RAM, distributed RAM, and so forth).

For built-in FIFOs, the number of entries in the FIFO has to be less than the threshold value -1 before PROG\_FULL is deasserted. For non built-in FIFOs, if the number of words in the FIFO is less than the negate threshold, the flag is deasserted.

Two options are available to implement this threshold:

- **Single threshold constant.** User specifies the threshold value through the CORE Generator GUI. Once the core is generated, this value can only be changed by re-generating the core. This option consumes fewer resources than the single threshold with dedicated input port.
- **Single threshold with dedicated input port** (non-built-in FIFOs only). User specifies the threshold value through an input port (PROG\_FULL\_THRESH) on the core. This input can be changed while the FIFO is in reset, providing the user the flexibility to change the programmable full threshold in-circuit without re-generating the core.

**Note:** See the CORE Generator GUI screen for valid ranges for each threshold.

Figure 4-12 shows the programmable full flag with a single threshold for a non-built-in FIFO. The user writes to the FIFO until there are seven words in the FIFO. Because the programmable full threshold is set to seven, the FIFO asserts `PROG_FULL` once seven words are written into the FIFO. Note that both write data count (`WR_DATA_COUNT`) and `PROG_FULL` have one clock cycle of delay. Once the FIFO has six or fewer words in the FIFO, `PROG_FULL` is deasserted.

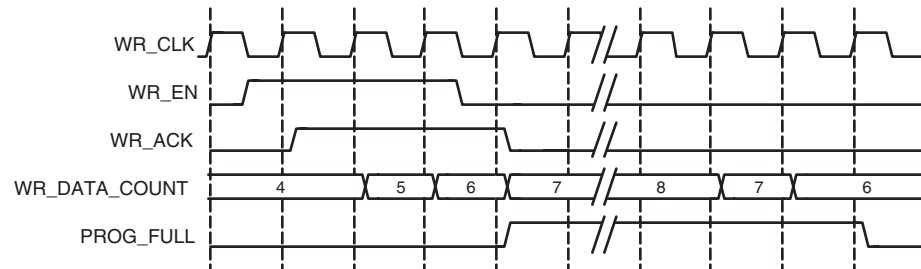


Figure 4-12: Programmable Full Single Threshold: Threshold Set to 7

### Programmable Full: Assert and Negate Thresholds

This option enables the user to set separate values for the assertion and deassertion of `PROG_FULL`. When the number of entries in the FIFO is greater than or equal to the assert value, `PROG_FULL` is asserted. When the number of entries in the FIFO is less than the negate value, `PROG_FULL` is deasserted. Note that this feature is not available for built-in FIFOs.

Two options are available to implement these thresholds:

- Assert and negate threshold constants: User specifies the threshold values through the CORE Generator GUI. Once the core is generated, these values can only be changed by re-generating the core. This option consumes fewer resources than the assert and negate thresholds with dedicated input ports.
- Assert and negate thresholds with dedicated input ports: User specifies the threshold values through input ports on the core. These input ports can be changed while the FIFO is in reset, providing the user the flexibility to change the values of the programmable full assert (`PROG_FULL_THRESH_ASSERT`) and negate (`PROG_FULL_THRESH_NEGATE`) thresholds in-circuit without re-generating the core.

**Note:** The full assert value must be larger than the full negate value. Refer to the CORE Generator GUI for valid ranges for each threshold.

Figure 4-13 shows the programmable full flag with assert and negate thresholds. The user writes to the FIFO until there are 10 words in the FIFO. Because the assert threshold is set to 10, the FIFO then asserts `PROG_FULL`. The negate threshold is set to seven, and the FIFO deasserts `PROG_FULL` once six words or fewer are in the FIFO. Both write data count (`WR_DATA_COUNT`) and `PROG_FULL` have one clock cycle of delay.

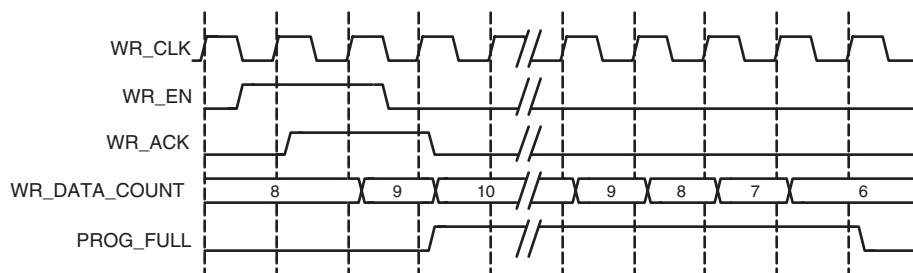


Figure 4-13: Programmable Full with Assert and Negate Thresholds: Assert Set to 10 and Negate Set to 7

### Programmable Full Threshold Range Restrictions

The programmable full threshold ranges depend on several features that dictate the way the FIFO is implemented, and include the following features:

- FIFO Implementation Type (Built-in FIFO or non Built-in FIFO, Common or Independent Clock FIFOs, and so forth)
- Symmetric or Non-symmetric Port Aspect Ratio
- Read Mode (Standard or First-Word-Fall-Through)
- Read and Write Clock Frequencies (Virtex-6, Virtex-5 and Virtex-4 FPGA Built-in FIFOs only)

The FIFO Generator GUI automatically parameterizes the threshold ranges based on these features, allowing you to choose only within the valid ranges. Note that for the Common or Independent Clock Built-in FIFO implementation type, you can only choose a threshold range within 1 primitive deep of the FIFO depth, due to the core implementation. If a wider threshold range is required, use the Common or Independent Clock Block RAM implementation type.

### Programmable Empty

The FIFO Generator supports four ways to define the programmable empty thresholds:

- Single threshold constant
- Single threshold with dedicated input port
- Assert and negate threshold constants (provides hysteresis)
- Assert and negate thresholds with dedicated input ports (provides hysteresis)

**Note:** The built-in FIFOs only support single-threshold constant programmable full.

These options are available in the CORE Generator GUI and accessed within the programmable flags window (Figure 3-4).

The programmable empty flag (PROG\_EMPTY) is asserted when the number of entries in the FIFO is less than or equal to the user-defined assert threshold. If the number of words in the FIFO is greater than the negate threshold, the flag is deasserted.

**Note:** If a read operation occurs on a rising clock edge that causes the number of words in the FIFO to be equal to or less than the programmable empty threshold, then the programmable empty flag will assert on the next rising clock edge. The deassertion of the programmable empty flag has a longer delay, and depends on the read and write clocks.

### Programmable Empty: Single Threshold

This option enables you to set a single threshold value for the assertion and deassertion of `PROG_EMPTY`. When the number of entries in the FIFO is less than or equal to the threshold value, `PROG_EMPTY` is asserted. The deassertion behavior differs between built-in and non built-in FIFOs (block RAM, distributed RAM, and so forth).

For built-in FIFOs, the number of entries in the FIFO must be greater than the threshold value + 1 before `PROG_EMPTY` is deasserted. For non built-in FIFOs, if the number of entries in the FIFO is greater than threshold value, `PROG_EMPTY` is deasserted.

Two options are available to implement this threshold:

- **Single threshold constant:** User specifies the threshold value through the CORE Generator GUI. Once the core is generated, this value can only be changed by re-generating the core. This option consumes fewer resources than the single threshold with dedicated input port.
- **Single threshold with dedicated input port:** User specifies the threshold value through an input port (`PROG_EMPTY_THRESH`) on the core. This input can be changed while the FIFO is in reset, providing the flexibility to change the programmable empty threshold in-circuit without re-generating the core.

**Note:** See the CORE Generator GUI for valid ranges for each threshold.

Figure 4-14 shows the programmable empty flag with a single threshold for a non-built-in FIFO. The user writes to the FIFO until there are five words in the FIFO. Because the programmable empty threshold is set to four, `PROG_EMPTY` is asserted until more than four words are present in the FIFO. Once five words (or more) are present in the FIFO, `PROG_EMPTY` is deasserted. Both read data count (`RD_DATA_COUNT`) and `PROG_EMPTY` have one clock cycle of delay.

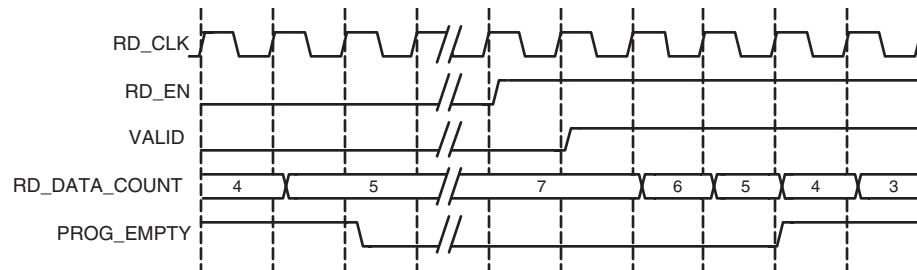


Figure 4-14: Programmable Empty with Single Threshold: Threshold Set to 4

### Programmable Empty: Assert and Negate Thresholds

This option lets the user set separate values for the assertion and deassertion of `PROG_EMPTY`. When the number of entries in the FIFO is less than or equal to the assert value, `PROG_EMPTY` is asserted. When the number of entries in the FIFO is greater than the negate value, `PROG_EMPTY` is deasserted. This feature is not available for built-in FIFOs.

Two options are available to implement these thresholds.

- **Assert and negate threshold constants.** The threshold values are specified through the CORE Generator GUI. Once the core is generated, these values can only be changed by re-generating the core. This option consumes fewer resources than the assert and negate thresholds with dedicated input ports.

- **Assert and negate thresholds with dedicated input ports.** The threshold values are specified through input ports on the core. These input ports can be changed while the FIFO is in reset, providing the user the flexibility to change the values of the programmable empty assert (`PROG_EMPTY_THRESH_ASSERT`) and negate (`PROG_EMPTY_THRESH_NEGATE`) thresholds in-circuit without regenerating the core.

**Note:** The empty assert value must be less than the empty negate value. Refer to the CORE Generator GUI for valid ranges for each threshold.

Figure 4-15 shows the programmable empty flag with assert and negate thresholds. The user writes to the FIFO until there are eleven words in the FIFO; because the programmable empty deassert value is set to ten, `PROG_EMPTY` is deasserted when more than ten words are in the FIFO. Once the FIFO contains less than or equal to the programmable empty negate value (set to seven), `PROG_EMPTY` is asserted. Both read data count (`RD_DATA_COUNT`) and `PROG_EMPTY` have one clock cycle of delay.

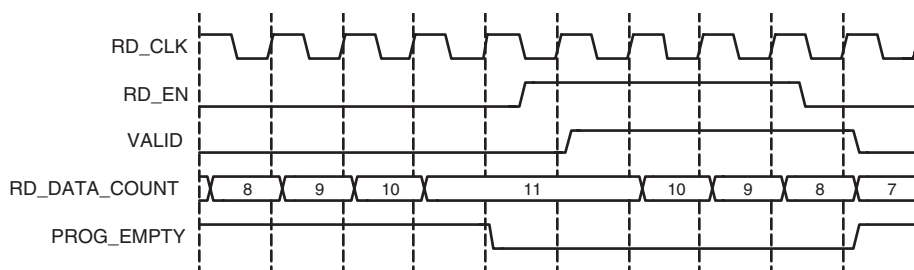


Figure 4-15: Programmable Empty with Assert and Negate Thresholds: Assert Set to 7 and Negate Set to 10

### Programmable Empty Threshold Range Restrictions

The programmable empty threshold ranges depend on several features that dictate the way the FIFO is implemented, including the following:

- FIFO Implementation Type (Built-in FIFO or non Built-in FIFO, Common or Independent Clock FIFOs, and so forth)
- Symmetric or Non-symmetric Port Aspect Ratio
- Read Mode (Standard or First-Word-Fall-Through)
- Read and Write Clock Frequencies (Virtex-6, Virtex-5, and Virtex-4 FPGA Built-in FIFOs only)

The FIFO Generator GUI automatically parameterizes the threshold ranges based on these features, allowing you to choose only within the valid ranges. Note that for Common or Independent Clock Built-in FIFO implementation type, you can only choose a threshold range within 1 primitive deep of the FIFO depth due to the core implementation. If a wider threshold range is needed, use the Common or Independent Clock Block RAM implementation type.

## Data Counts

`DATA_COUNT` tracks the number of words in the FIFO. You can specify the width of the data count bus with a maximum width of  $\log_2$  (FIFO depth). If the width specified is smaller than the maximum allowable width, the bus is truncated by removing the lower bits. These signals are optional outputs of the FIFO Generator, and are enabled through the CORE Generator GUI. Table 4-4 identifies data count support for each FIFO implementation. For information about the latency behavior of data count flags, see “Latency,” page 82.

Table 4-4: Implementation-specific Support for Data Counts

FIFO Implementation		Data Count Support
Independent Clocks	Block RAM	✓
	Distributed RAM	✓
	Built-in	
Common Clock	Block RAM	✓
	Distributed RAM	✓
	Shift Register	✓
	Built-in	

### Data Count (Common Clock FIFO Only)

Data Count output (DATA\_COUNT) accurately reports the number of words available in a Common Clock FIFO. You can specify the width of the data count bus with a maximum width of  $\log_2(\text{depth})$ . If the width specified is smaller than the maximum allowable width, the bus is truncated with the lower bits removed.

For example, you can specify to use two bits out of a maximum allowable three bits (provided a FIFO depth of eight). These two bits indicate the number of words in the FIFO with a quarter resolution, providing the status of the contents of the FIFO for read and write operations.

**Note:** If a read or write operation occurs on a rising edge of CLK, the data count port is updated at the same rising edge of CLK.

### Read Data Count (Independent Clock FIFO Only)

Read data count (RD\_DATA\_COUNT) pessimistically reports the number of words available for reading. The count is guaranteed to never over-report the number of words available in the FIFO (although it may temporarily under-report the number of words available) to ensure that the user design never underflows the FIFO. The user can specify the width of the read data count bus with a maximum width of  $\log_2(\text{read depth})$ . If the width specified is smaller than the maximum allowable width, the bus is truncated with the lower bits removed.

For example, the user can specify to use two bits out of a maximum allowable three bits (provided a FIFO depth of eight). These two bits indicate the number of words in the FIFO, with a quarter resolution. This provides a status of the contents of the FIFO for the read clock domain.

**Note:** If a read operation occurs on a rising clock edge of RD\_CLK, that read is reflected on the RD\_DATA\_COUNT signal following the next rising clock edge. A write operation on the WR\_CLK clock domain may take a number of clock cycles before being reflected in the RD\_DATA\_COUNT.

### Write Data Count (Independent Clock FIFO Only)

Write data count (WR\_DATA\_COUNT) pessimistically reports the number of words written into the FIFO. The count is guaranteed to never under-report the number of words in the FIFO (although it may temporarily over-report the number of words present) to ensure that the user never overflows the FIFO. The user can specify the width of the write data



count bus with a maximum width of  $\log_2$  (write depth). If the width specified is smaller than the maximum allowable width, the bus is truncated with the lower bits removed.

For example, you can only use two bits out of a maximum allowable three bits (provided a FIFO depth of eight). These two bits indicate the number of words in the FIFO, with a quarter resolution. This provides a status of the contents of the FIFO for the write clock domain.

**Note:** If a write operation occurs on a rising clock edge of `WR_CLK`, that write will be reflected on the `WR_DATA_COUNT` signal following the next rising clock edge. A read operation, which occurs on the `RD_CLK` clock domain, may take a number of clock cycles before being reflected in the `WR_DATA_COUNT`.

## First-Word Fall-Through Data Count

By providing the capability to read the next data word before requesting it, first-word fall-through (FWFT) implementations increase the depth of the FIFO by 2 read words. Using this configuration, the FIFO Generator enables the user to generate data count in two ways:

- Approximate Data Count
- More Accurate Data Count (Use Extra Logic)

### Approximate Data Count

Approximate Data Count behavior is the default option in the CORE Generator GUI for independent clock block RAM and distributed RAM FIFOs. This feature is not available for common clock FIFOs. The width of the `WR_DATA_COUNT` and `RD_DATA_COUNT` is identical to the non first-word-fall-through configurations ( $\log_2$  (write depth) and  $\log_2$  (read depth), respectively) but the data counts reported is an approximation because the actual full depth of the FIFO is not supported.

Using this option, you can use specific bits in `WR_DATA_COUNT` and `RD_DATA_COUNT` to approximately indicate the status of the FIFO, for example, half full, quarter full, and so forth.

For example, for a FIFO with a depth of 16, symmetric read and write port widths, and the first-word-fall-through option selected, the *actual* FIFO depth increases from 15 to 17. When using approximate data count, the width of `WR_DATA_COUNT` and `RD_DATA_COUNT` is 4 bits, with a maximum of 15. For this option, you can use the assertion of the MSB bit of the data count to indicate that the FIFO is approximately half full.

### More Accurate Data Count (Use Extra Logic)

This feature is enabled when Use Extra Logic for More Accurate Data Counts is selected in the CORE Generator GUI. In this configuration, the width of `WR_DATA_COUNT`, `RD_DATA_COUNT`, and `DATA_COUNT` is  $\log_2(\text{write depth})+1$ ,  $\log_2(\text{read depth})+1$ , and  $\log_2(\text{depth})+1$ , respectively to accommodate the increase in depth in the first-word-fall-through case and to ensure accurate data count is provided.

Note that when using this option, you *cannot* use any one bit of `WR_DATA_COUNT`, `RD_DATA_COUNT`, and `DATA_COUNT` to indicate the status of the FIFO, for example, approximately half full, quarter full, and so forth.

For example, for an independent FIFO with a depth of 16, symmetric read and write port widths, and the first-word-fall-through option selected, the *actual* FIFO depth increases from 15 to 17. When using accurate data count, the width of the `WR_DATA_COUNT` and `RD_DATA_COUNT` is 5 bits, with a maximum of 31. For this option, you must use the



assertion of both the MSB and MSB-1 bit of the data count to indicate that the FIFO is at least half full.

### Data Count Behavior

For FWFT implementations using More Accurate Data Counts (Use Extra Logic), DATA\_COUNT is guaranteed to be accurate when words are present in the FIFO, with the exception of when its near empty or almost empty or when initial writes occur on an empty FIFO. In these scenarios, DATA\_COUNT may be incorrect on up to two words.

Table 4-5 defines the value of DATA\_COUNT when FIFO is empty.

From the point-of-view of the write interface, DATA\_COUNT is always accurate, reporting the first word immediately once its written to the FIFO. However, from the point-of-view of the read interface, the DATA\_COUNT output may over-report by up to two words until ALMOST\_EMPTY and EMPTY have both deasserted. This is due to the latency of EMPTY deassertion in the first-word-fall-through FIFO (see Table 4-17). This latency allows DATA\_COUNT to reflect written words which may not yet be available for reading.

From the point-of-view of the read interface, the data count starts to transition from over-reporting to accurate-reporting at the deassertion to empty. This transition completes after ALMOST\_EMPTY deasserts. Before ALMOST\_EMPTY deasserts, the DATA\_COUNT signal may exhibit the following atypical behaviors:

- From the read-interface perspective, DATA\_COUNT may over-report up to two words.

### Write Data Count Behavior

Even for FWFT implementations using More Accurate Data Counts (Use Extra Logic), WR\_DATA\_COUNT will still pessimistically report the number of words written into the FIFO. However, the addition of this feature will cause WR\_DATA\_COUNT to further over-report up to two read words (and 1 to 16 write words, depending on read and write port aspect ratio) when the FIFO is at or near empty or almost empty.

Table 4-5 defines the value of WR\_DATA\_COUNT when the FIFO is empty.

The WR\_DATA\_COUNT starts to transition out of over-reporting two extra read words at the deassertion of EMPTY. This transition completes several clock cycles after ALMOST\_EMPTY deasserts. Note that prior to the transition period, WR\_DATA\_COUNT will always over-report by at least two read words. During the transition period, the WR\_DATA\_COUNT signal may exhibit the following strange behaviors:

- WR\_DATA\_COUNT may decrement although no read operation has occurred.
- WR\_DATA\_COUNT may not increment as expected due to a write operation.

**Note:** During reset, WR\_DATA\_COUNT and DATA\_COUNT value is set to 0.

Table 4-5: Empty FIFO WR\_DATA\_COUNT/DATA\_COUNT Value

Write Depth to Read Depth Ratio	Approximate WR_DATA_COUNT	More Accurate WR_DATA_COUNT	More Accurate DATA_COUNT
1:1	0	2	2
1:2	0	1	N/A
1:4	0	0	N/A
1:8	0	0	N/A
2:1	0	4	N/A

Table 4-5: Empty FIFO WR\_DATA\_COUNT/DATA\_COUNT Value (Cont'd)

Write Depth to Read Depth Ratio	Approximate WR_DATA_COUNT	More Accurate WR_DATA_COUNT	More Accurate DATA_COUNT
4:1	0	8	N/A
8:1	0	16	N/A

The RD\_DATA\_COUNT value at empty (when no write is performed) is 0 with or without Use Extra Logic for all write depth to read depth ratios.

## Example Operation

Figure 4-16 shows write and read data counts. When WR\_EN is asserted and FULL is deasserted, WR\_DATA\_COUNT increments. Similarly, when RD\_EN is asserted and EMPTY is deasserted, RD\_DATA\_COUNT decrements.

**Note:** In the first part of Figure 4-16, a successful write operation occurs on the third rising clock edge, and is not reflected on WR\_DATA\_COUNT until the next full clock cycle is complete. Similarly, RD\_DATA\_COUNT transitions one full clock cycle after a successful read operation.

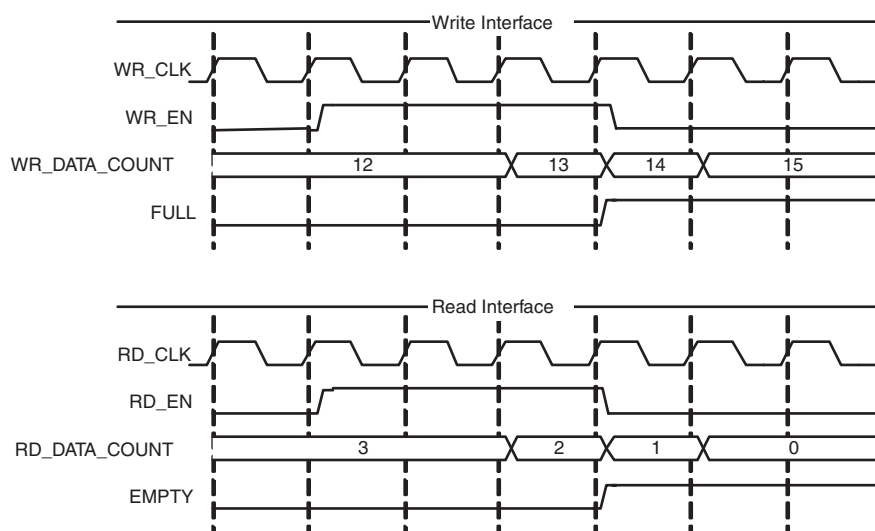


Figure 4-16: Write and Read Data Counts for FIFO with Independent Clocks

## Non-symmetric Aspect Ratios

Table 4-6 identifies support for non-symmetric aspect ratios.

Table 4-6: Implementation-specific Support for Non-symmetric Aspect Ratios

FIFO Implementation		Non-symmetric Aspect Ratios Support
Independent Clocks	Block RAM	✓
	Distributed RAM	
	Built-in	

Table 4-6: Implementation-specific Support for Non-symmetric Aspect Ratios

FIFO Implementation		Non-symmetric Aspect Ratios Support
Common Clock	Block RAM	
	Distributed RAM	
	Shift Register	
	Built-in	

This feature is supported for FIFOs configured with independent clocks implemented with block RAM. Non-symmetric aspect ratios allow the input and output depths of the FIFO to be different. The following write-to-read aspect ratios are supported: 1:8, 1:4, 1:2, 1:1, 2:1, 4:1, 8:1. This feature is enabled by selecting unique write and read widths when customizing the FIFO using the CORE Generator. By default, the write and read widths are set to the same value (providing a 1:1 aspect ratio); but any ratio between 1:8 to 8:1 is supported, and the output depth of the FIFO is automatically calculated from the input depth and the write and read widths.

For non-symmetric aspect ratios, the full and empty flags are active only when one complete word can be written or read. The FIFO does not allow partial words to be accessed. For example, assuming a full FIFO, if the write width is 8 bits and read width is 2 bits, the user would have to complete four valid read operations before full deasserts and a write operation accepted. Write data count shows the number of FIFO words according to the write port ratio, and read data count shows the number of FIFO words according to the read port ratio.

**Note:** For non-symmetric aspect ratios where the write width is smaller than the read width (1:8, 1:4, 1:2), the most significant bits are read first (refer to Figure 4-17 and Figure 4-18).

Figure 4-17 is an example of a FIFO with a 1:4 aspect ratio (write width = 2, read width = 8). In this figure, four consecutive write operations are performed before a read operation can be performed. The first write operation is 01, followed by 00, 11, and finally 10. The memory is filling up from the left to the right (MSB to LSB). When a read operation is performed, the received data is 01\_00\_11\_10.

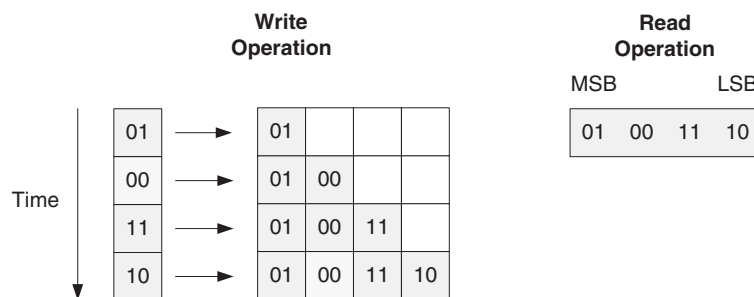


Figure 4-17: 1:4 Aspect Ratio: Data Ordering

Figure 4-18 shows DIN, DOUT and the handshaking signals for a FIFO with a 1:4 aspect ratio. After four words are written into the FIFO, EMPTY is deasserted. Then after a single read operation, EMPTY is asserted again.

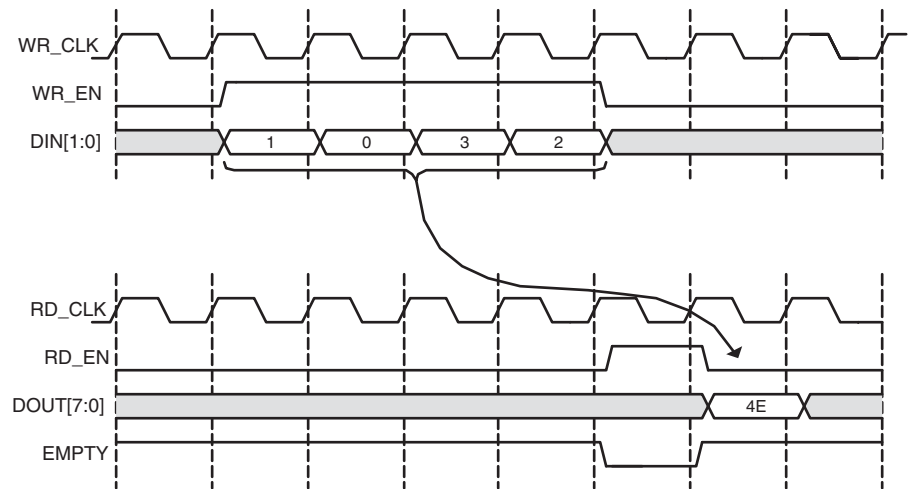


Figure 4-18: 1:4 Aspect Ratio: Status Flag Behavior

Figure 4-19 shows a FIFO with an aspect ratio of 4:1 (write width of 8, read width of 2). In this example, a single write operation is performed, after which four read operations are executed. The write operation is 11\_00\_01\_11. When a read operation is performed, the data is received left to right (MSB to LSB). As shown, the first read results in data of 11, followed by 00, 01, and then 11.

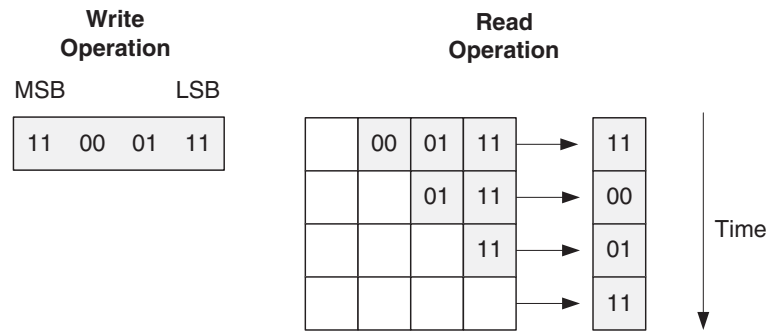


Figure 4-19: 4:1 Aspect Ratio: Data Ordering

Figure 4-20 shows DIN, DOUT, and the handshaking signals for a FIFO with an aspect ratio of 4:1. After a single write, the FIFO deasserts EMPTY. Because no other writes occur, the FIFO reasserts empty after four reads.

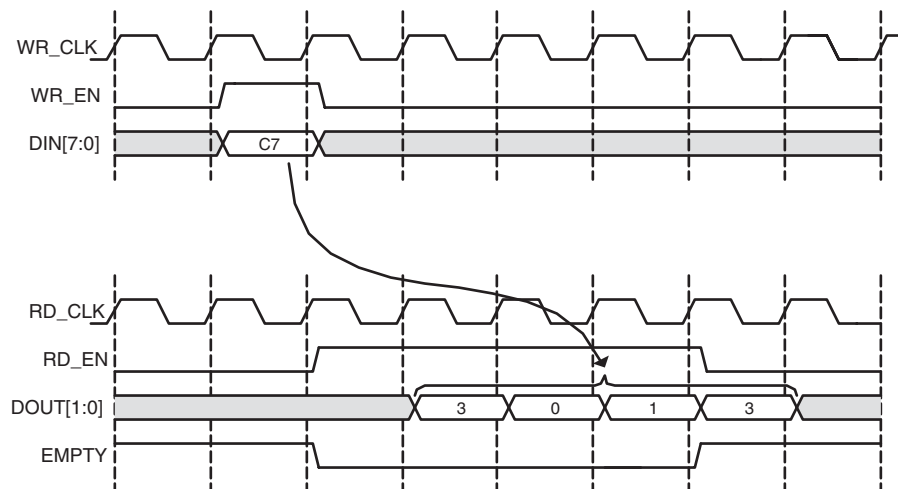


Figure 4-20: 4:1 Aspect Ratio: Status Flag Behavior

## Non-symmetric Aspect Ratio and First-Word Fall-Through

A FWFT FIFO has 2 extra read words available on the read port when compared to a standard FIFO. For write-to-read aspect ratios that are larger or equal to 1 (1:1, 2:1, 4:1, and 8:1), the FWFT implementation also increases the number of words that can be written into the FIFO by  $\text{depth\_ratio} \times 2$  ( $\text{depth\_ratio} = \text{write depth} / \text{read depth}$ ). For write-to-read aspect ratios smaller than 1 (1:2, 1:4 and 1:8), the addition of 2 extra read words only amounts to a fraction of 1 write word. The creation of these partial words causes the behavior of the PROG\_EMPTY and WR\_DATA\_COUNT signals of the FIFO to differ in behavior than as previously described.

## Programmable Empty

In general, PROG\_EMPTY is guaranteed to assert when the number of readable words in the FIFO is less than or equal to the programmable empty assert threshold. However, when the write-to-read aspect ratios are smaller than 1 (depending on the read and write clock frequency) it is possible for PROG\_EMPTY to violate this rule, but only while EMPTY is asserted. To avoid this condition, the user should set the programmable empty assert threshold to  $3 \times \text{depth\_ratio} \times \text{frequency\_ratio}$  ( $\text{depth\_ratio} = \text{write depth} / \text{read depth}$  and  $\text{frequency\_ratio} = \text{write clock frequency} / \text{read clock frequency}$ ). If the programmable empty assert threshold is set lower than this value, the user should assume that PROG\_EMPTY may or can be asserted when EMPTY is asserted.

## Write Data Count

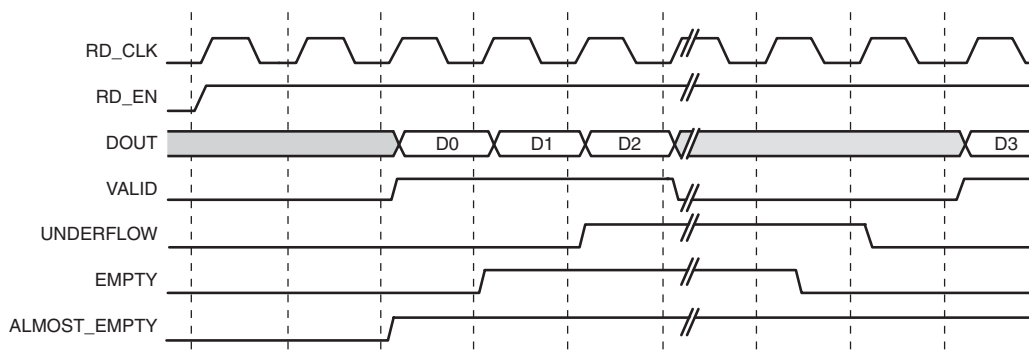
In general, WR\_DATA\_COUNT pessimistically reports the number of words written into the FIFO and is guaranteed to never under-report the number of words in the FIFO, to ensure that the user never overflows the FIFO. However, when the write-to-read aspect ratios are smaller than 1, if the read and write operations result in partial write words existing in the FIFO, it is possible to under-report the number of words in the FIFO. This behavior is most crucial when the FIFO is 1 or 2 words away from full, because in this state the WR\_DATA\_COUNT is under-reporting and cannot be used to gauge if the FIFO is full. In this configuration, you should use the FULL flag to gate any write operation to the FIFO.

## Embedded Registers in Block RAM and FIFO Macros (Virtex-6, Virtex-5 and Virtex-4 FPGAs)

The block RAM macros available in Virtex-6, Virtex-5 and Virtex-4 FPGA, as well as built-in FIFO macros available in Virtex-6 and Virtex-5 FPGA, have built-in embedded registers that can be used to pipeline data and improve macro timing. Depending on the configuration, this feature can be leveraged to add one additional latency to the FIFO core (DOUT bus and VALID outputs) or implement the output registers for FWFT FIFOs. For built-in FIFOs configuration, this feature is only available for common clock FIFOs.

### Standard FIFOs

When using the embedded registers to add an output pipeline register to the standard FIFOs, only the DOUT and VALID output ports are delayed by 1 clock cycle during a read operation. These additional pipeline registers are always enabled, as illustrated in Figure 4-21.



**Figure 4-21: Standard Read Operation for a Block RAM or built-in FIFO with Use Embedded Registers Enabled**

### Block RAM Based FWFT FIFOs

When using the embedded output registers to implement the FWFT FIFOs, the behavior of the core is identical to the implementation without the embedded registers.

### Built-in Based FWFT FIFOs (Common Clock Only)

When using the embedded output registers with a common clock built-in based FIFO with FWFT, the embedded registers add an output pipeline register to the FWFT FIFO. The DOUT and VALID output ports are delayed by 1 clock cycle during a read operation. These pipeline registers are always enabled, and the DOUT reset value feature is not supported in Virtex-4 and Virtex-5 FPGAs, as illustrated in Figure 4-22. For this configuration, the embedded output register feature is only available for FIFOs that use only 1 FIFO macro in depth.

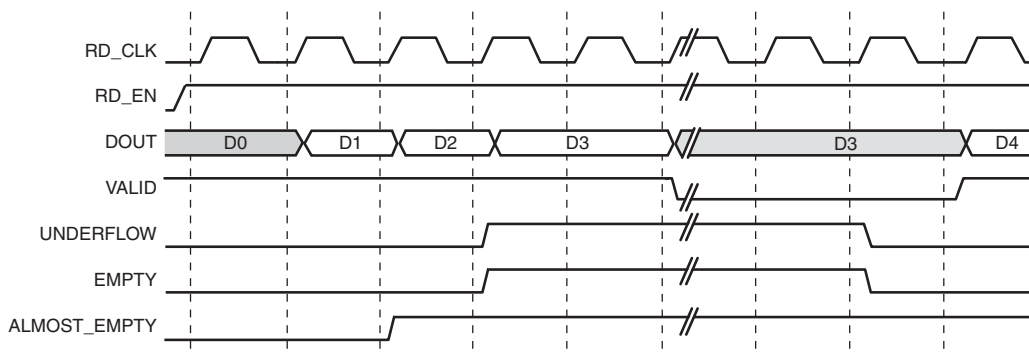


Figure 4-22: FWFT Read Operation for a Synchronous Built-in FIFO with User Embedded Registers Enabled

**Note:** Virtex-5 FPGA built-in FIFOs with independent clocks and FWFT always use the embedded output registers in the macro to implement the FWFT registers.

When using the embedded output registers with a common clock built-in FIFO in Virtex-6 FPGAs, the DOUT reset value feature is supported, as illustrated in Figure 4-23.

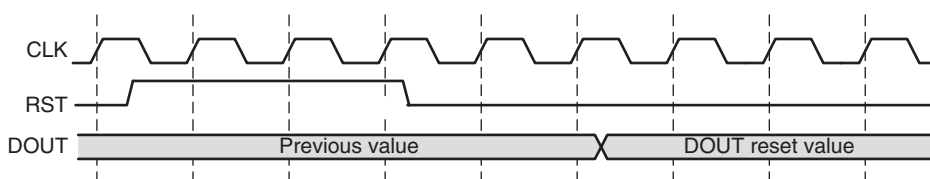


Figure 4-23: DOUT Reset Value for Virtex-6 Common Clock Built-in FIFO Embedded Register

## Built-in Error Correction Checking

Built-in ECC is supported for FIFOs configured with independent or common clock block RAM and built-in FIFOs targeting Virtex-5 and Virtex-6 FPGAs. In addition, error injection is supported for FIFOs configured with independent or common clock block RAM and built-in FIFOs targeting Virtex-6 FPGAs. When ECC is enabled, the block RAM and built-in FIFO primitive used to create the FIFO is configured in the full ECC mode (both encoder and decoder enabled), providing two additional outputs to the FIFO Generator core: SBITERR and DBITERR. These outputs indicate three possible read results: no error, single error corrected, and double error detected. In the full ECC mode, the read operation does not correct the single error in the memory array, it only presents corrected data on DOUT.

Figure 4-24 shows how the SBITERR and DBITERR outputs are generated in the FIFO Generator core. The output signals are created by combining all the SBITERR and DBITERR signals from the FIFO or block RAM primitives using an OR gate. Because the FIFO primitives may be cascaded in depth, when SBITERR or DBITERR is asserted, the error may have occurred in any of the built-in FIFO macros chained in depth or block RAM macros. For this reason, these flags are not correlated to the data currently being read from the FIFO Generator core or to a read operation. For this reason, when the DBITERR is flagged, the user should assume that the data in the entire FIFO has been corrupted and the user logic needs to take the appropriate action. As an example, when DBITERR is flagged, an appropriate action for the user logic is to halt all FIFO operation, reset the FIFO, and restart the data transfer.

The SBITERR and DBITERR outputs are not registered and are generated combinatorially. If the configured FIFO uses two independent read and write clocks, the SBITERR and DBITERR outputs may be generated from either the write or read clock domain. The signals generated in the write clock domain are synchronized before being combined with the SBITERR and DBITERR signals generated in the read clock domain.

Note that due to the differing read and write clock frequencies and the OR gate used to combine the signals, the number of read clock cycles that the SBITERR and DBITERR flags assert is not an accurate indicator of the number of errors found in the built-in FIFOs.

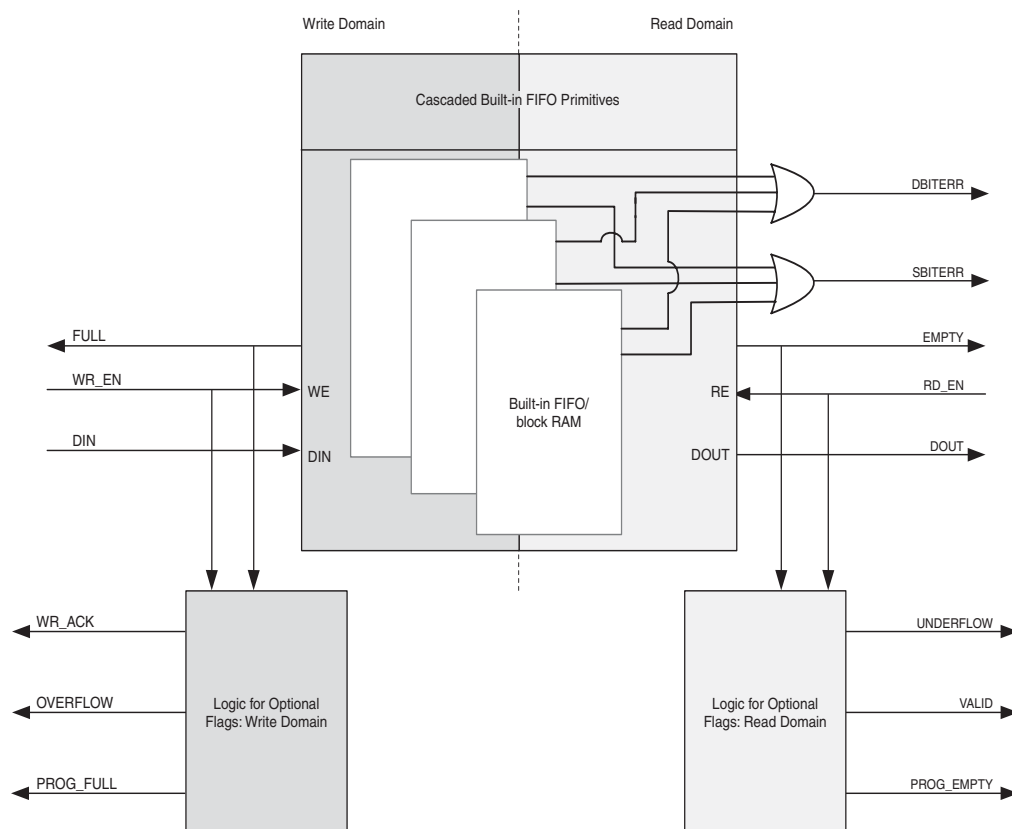


Figure 4-24: SBITERR and DBITERR Outputs in the FIFO Generator Core

## Built-in Error Injection

Built-in Error Injection is supported for FIFOs configured with independent or common clock block RAM and built-in FIFOs in Virtex-6 FPGAs. When ECC and Error Injection are enabled, the block RAM and built-in FIFO primitive used to create the FIFO is configured in the full ECC error injection mode, providing two additional inputs to the FIFO Generator core: INJECTSBITERR and INJECTDBITERR. These inputs indicate three possible results: no error injection, single bit error injection, or double bit error injection.

The ECC is calculated on a 64-bit wide data of Virtex-6 ECC primitive. If the data width chosen by the user is not an integral multiple of 64 (for example, there are spare bits in any ECC primitive), then a double bit error (DBITERR) may indicate that one or more errors have occurred in the spare bits. So, the accuracy of the DBITERR signal cannot be guaranteed in this case. For example, if the user's data width is 16, then 48 bits of the ECC primitive are left empty. If two of the spare bits are corrupted, the DBITERR signal would be asserted even though the actual user data is not corrupt.



When INJECTSBITERR is asserted on a write operation, a single bit error is injected and SBITERR is asserted upon read operation of a specific write. When INJECTDBITERR is asserted on a write operation, a double bit error is injected and DBITERR is asserted upon read operation of a specific write. When both INJECTSBITERR and INJECTDBITERR are asserted on a write operation, a double bit error is injected and DBITERR is asserted upon read operation of a specific write. Figure 4-25 shows how the SBITERR and DBITERR outputs are generated in the FIFO Generator core.

**Note:** Reset is not supported by the FIFO/BRAM macros when using the ECC option. Therefore, outputs of the FIFO core (DOUT, DBITERR and SBITERR) will not be affected by reset, and they hold their previous values. See “Reset Behavior” for more details.

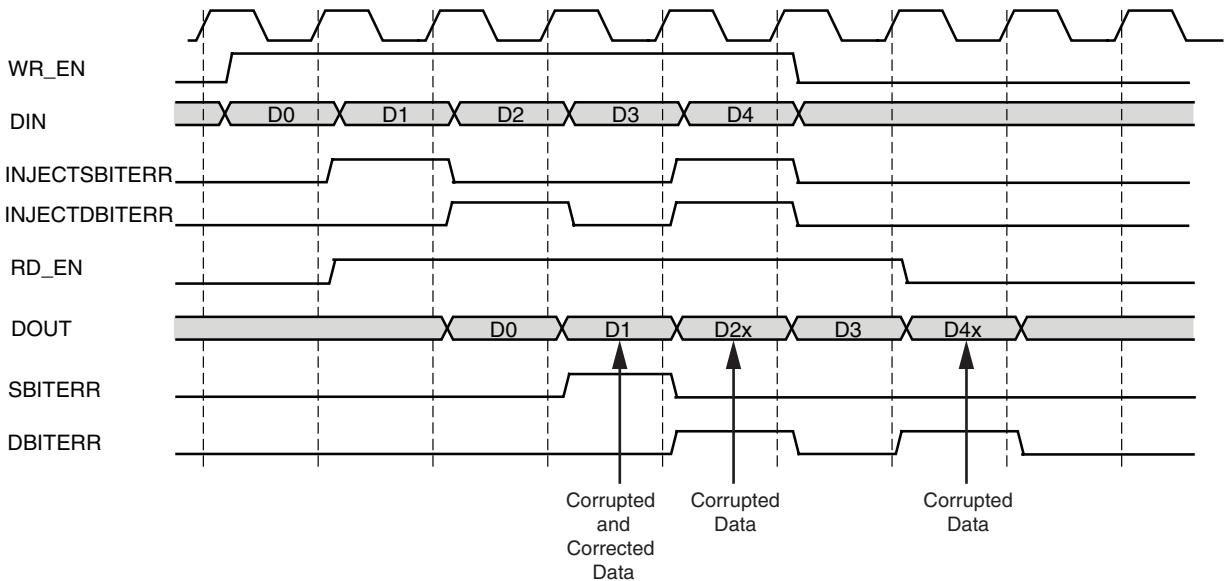


Figure 4-25: Error Injection and Correction in Virtex-6 FPGA

## Reset Behavior

The FIFO Generator provides a reset input that resets all counters, output registers, and memories when asserted. For block RAM or distributed RAM implementations, resetting the FIFO is not required, and the reset pin can be disabled in the FIFO. There are two reset options: asynchronous and synchronous.

### Asynchronous Reset (Enable Reset Synchronization Option is Selected)

The asynchronous reset (RST) input asynchronously resets all counters, output registers, and memories when asserted. When reset is implemented, it is synchronized internally to the core with each respective clock domain for setting the internal logic of the FIFO to a known state. This synchronization logic allows for proper timing of the reset logic within the core to avoid glitches and metastable behavior.

### Common/Independent Clock: Block RAM, Distributed RAM, and Shift RAM FIFOs

Table 4-7 defines the values of the output ports during power-up and reset state for block RAM, distributed RAM, and shift RAM FIFOs. Note that the underflow signal is dependent on RD\_EN. If RD\_EN is asserted and the FIFO is empty, underflow is asserted. The overflow signal is dependent on WR\_EN. If WR\_EN is asserted and the FIFO is full, overflow is asserted.

There are two asynchronous reset behaviors available for these FIFO configurations: Full flags reset to 1 and full flags reset to 0. The reset requirements and the behavior of the FIFO is different depending on the full flags reset value chosen.

**Note:** The reset is edge sensitive and not level sensitive. The synchronization logic looks for the rising edge of `RST` and creates an internal reset for the core. Note that the assertion of asynchronous reset immediately causes the core to go into a predetermine reset state - this is not dependent on any clock toggling. The reset synchronization logic is used to ensure that the logic in the different clock domains comes OUT of the reset mode at the same time - this is by synchronizing the deassertion of asynchronous reset to the appropriate clock domain. By doing this glitches and metastability can be avoided. This synchronization takes three clock cycles (write or read) after the asynchronous reset is detected on the rising edge read and write clock respectively. To avoid unexpected behavior, it is not recommended to drive/toggle `WR_EN/RD_EN` when `RST` or `FULL` is asserted/high.

**Table 4-7: FIFO Asynchronous Reset Values for Block RAM, Distributed RAM, and Shift RAM FIFOs**

Signal	Full Flags Reset Value of 1	Full Flags Reset Value of 0	Power-up Values
DOUT	DOUT Reset Value or 0	DOUT Reset Value or 0	Same as reset values
FULL	1 <sup>(1)</sup>	0	0
ALMOST FULL	1 <sup>(1)</sup>	0	0
EMPTY	1	1	1
ALMOST EMPTY	1	1	1
VALID	0 (active high) or 1 (active low)	0 (active high) or 1 (active low)	0 (active high) or 1 (active low)
WR_ACK	0 (active high) or 1 (active low)	0 (active high) or 1 (active low)	0 (active high) or 1 (active low)
PROG_FULL	1 <sup>(1)</sup>	0	0
PROG_EMPTY	1	1	1
RD_DATA_COUNT	0	0	0
WR_DATA_COUNT	0	0	0

**Notes:**

1. When reset is asserted, the FULL flags are asserted to prevent writes to the FIFO during reset.

### Full Flags Reset Value of 1

In this configuration, the FIFO requires a minimum asynchronous reset pulse of 1 write clock period (`WR_CLK/CLK`). After reset is detected on the rising clock edge of write clock, 3 write clock periods are required to complete proper reset synchronization. During this time, the FULL, ALMOST\_FULL, and PROG\_FULL flags are asserted. After reset is deasserted, these flags deassert after 3 clock period (`WR_CLK/CLK`) and the FIFO is now ready for writing.

The FULL and ALMOST\_FULL flags are asserted to ensure that no write operations occur when the FIFO core is in the reset state. After the FIFO exits the reset state and is ready for writing, the FULL and ALMOST\_FULL flags deassert; this occurs approximately three clock cycles after the deassertion of asynchronous reset. See [Figure 4-26](#) and [Figure 4-27](#) for

example behaviors. Note that the power-up values for this configuration are different from the reset state value.

Figure 4-26 shows an example timing diagram for when the reset pulse is one clock duration.

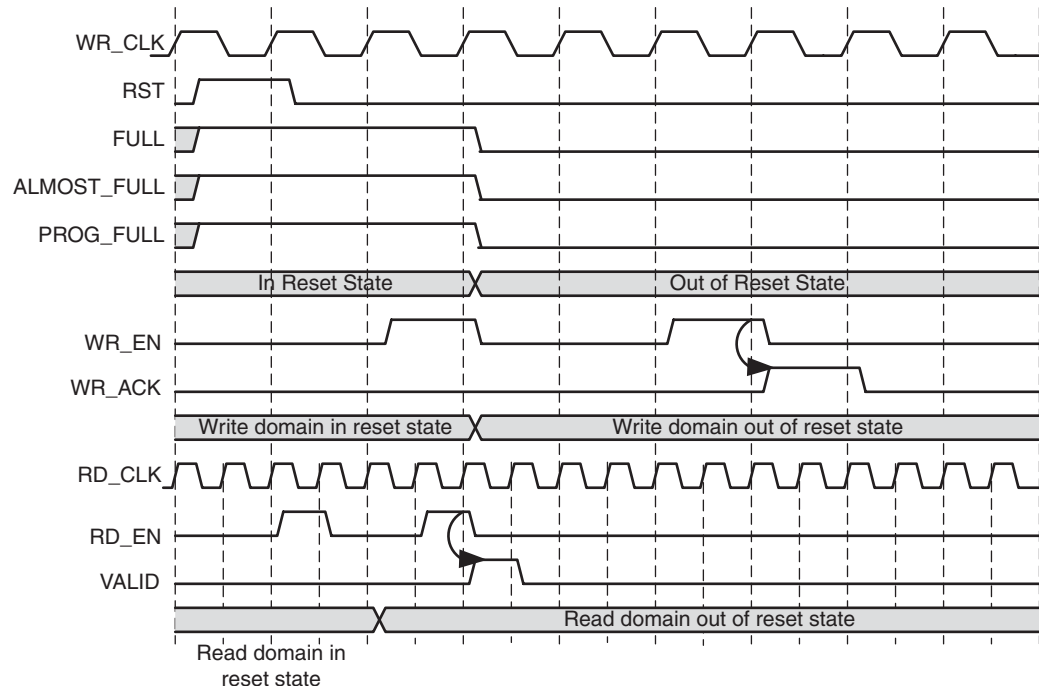


Figure 4-26: Block RAM, Distributed RAM, Shift RAM with Full Flags Reset Value of 1 for the Reset Pulse of One Clock

Figure 4-27 shows an example timing diagram for when the reset pulse is longer than one clock duration.

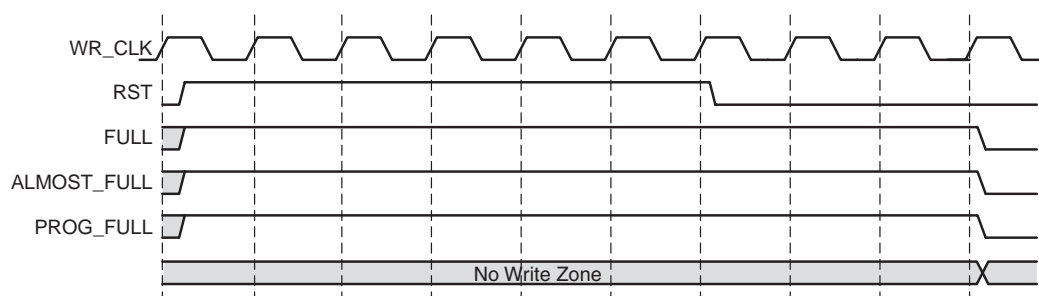
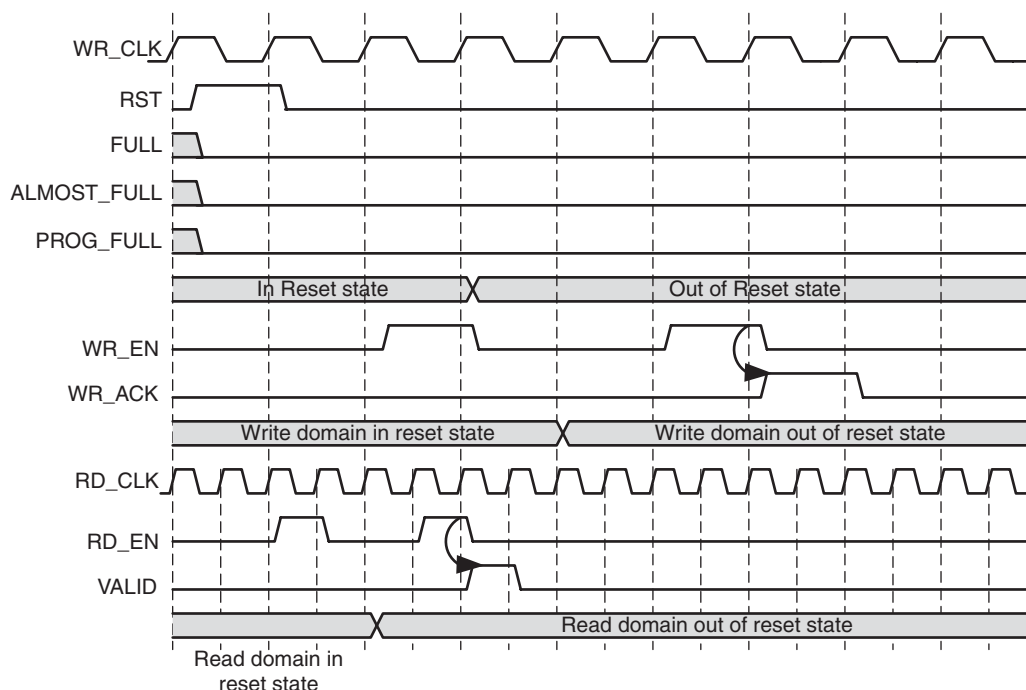


Figure 4-27: Block RAM, Distributed RAM, Shift RAM with Full Flags Reset Value of 1 for the Reset Pulse of More Than One Clock

### Full Flags Reset Value of 0

In this configuration, the FIFO requires a minimum asynchronous reset pulse of 1 write clock cycle to complete the proper reset synchronization. At reset, FULL, ALMOST\_FULL and PROG\_FULL flags are deasserted. After the FIFO exits the reset synchronization state, the FIFO is ready for writing; this occurs approximately three clock cycles after the assertion of asynchronous reset. See Figure 4-28 for example behavior.



**Figure 4-28: Block RAM, Distributed RAM, Shift RAM with Full Flags Reset Value of 0**

#### Common/Independent Clock: Built-in

Table 4-7 defines the values of the output ports during power-up and reset state for Built-in FIFOs. DOUT reset value is not supported for Virtex-4, Virtex-5, and Virtex-6 Built-in FIFOs, except Virtex-6 common clock Built-in FIFOs with embedded register option selected. The Built-In FIFOs require an asynchronous reset pulse of at least 3 read and write clock cycles. During reset, the RD\_EN and WR\_EN ports are required to be deasserted (no read or write operation can be performed). Assertion of reset causes the FULL and PROG\_FULL flags to deassert and EMPTY and PROG\_EMPTY flags to assert. After asynchronous reset is released, the core exits the reset state and is ready for writing. See Figure 4-29 for example behavior.

Note that the underflow signal is dependent on RD\_EN. If RD\_EN is asserted and the FIFO is empty, underflow is asserted. The overflow signal is dependent on WR\_EN. If WR\_EN is asserted and the FIFO is full, overflow is asserted.

Table 4-8: Asynchronous FIFO Reset Values for Built-in FIFO

Signal	Built-in FIFO Reset Values	Power-up Values
DOUT	Last read value	Content of memory at location 0
FULL	0	0
EMPTY	1	1
VALID	0 (active high) or 1 (active low)	0 (active high) or 1 (active low)
PROG_FULL	0	0
PROG_EMPTY	1	1

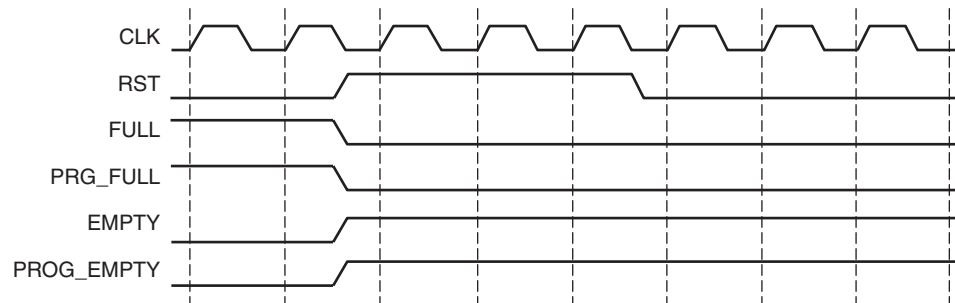


Figure 4-29: Built-in FIFO, Asynchronous Reset Behavior

## Synchronous Reset

The synchronous reset input (SRST or WR\_RST/RD\_RST synchronous to WR\_CLK/RD\_CLK domain) is only available for the block RAM, distributed RAM, or shift RAM implementation of the common/independent clock FIFOs.

### Common Clock Block, Distributed, or Shift RAM FIFOs

The synchronous reset (SRST) synchronously resets all counters, output registers and memories when asserted. Because the reset pin is synchronous to the input clock and there

is only one clock domain in the FIFO, no additional synchronization logic is necessary. Figure 4-32 illustrates the flags following the release of SRST.

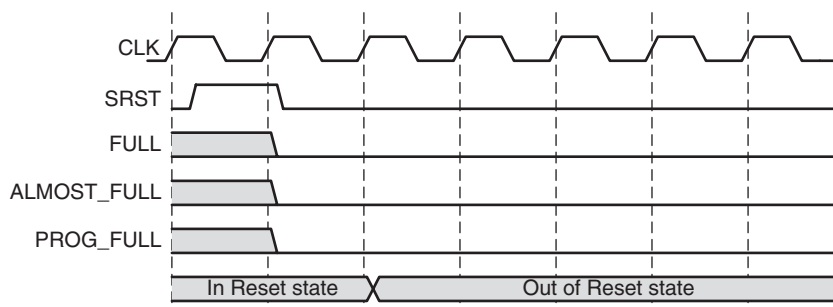


Figure 4-32: Synchronous Reset: FIFO with a Common Clock

#### Independent Clock Block and Distributed RAM FIFOs (Enable Reset Synchronization Option not Selected)

The synchronous reset (WR\_RST/RD\_RST) synchronously resets all counters, output registers of respective clock domain when asserted. Because the reset pin is synchronous to the respective clock domain, no additional synchronization logic is necessary.

If one reset (WR\_RST/RD\_RST) is asserted, the other reset must also be applied. The time at which the resets are asserted/de-asserted may differ, and during this period the FIFO outputs become invalid. To avoid unexpected behavior, it is not recommended to perform write or read operations from the assertion of the first reset to the de-assertion of the last reset.

**Note:** For the FIFOs built with First-Word-Fall-Through and ECC configurations, the SBITERR and DBITERR may be high until a valid read is performed after the de-assertion of both WR\_RST and RD\_RST.

Figure 4-33 and Figure 4-34 illustrate the rules to be considered.

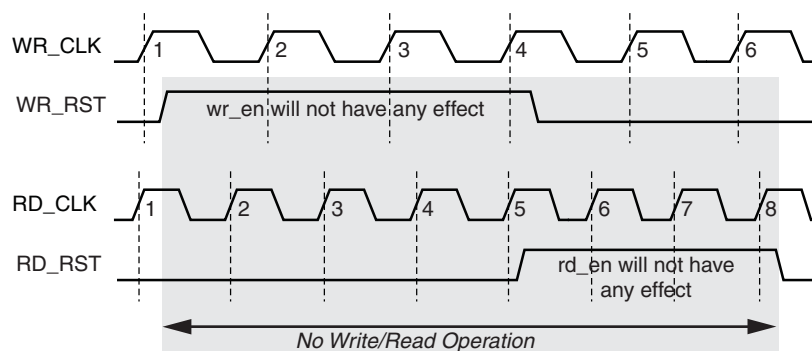
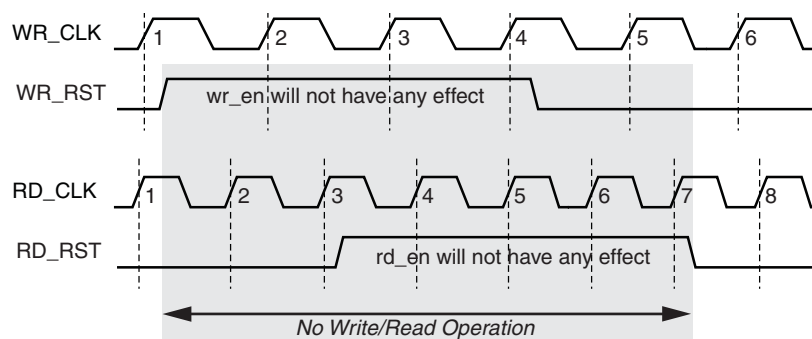
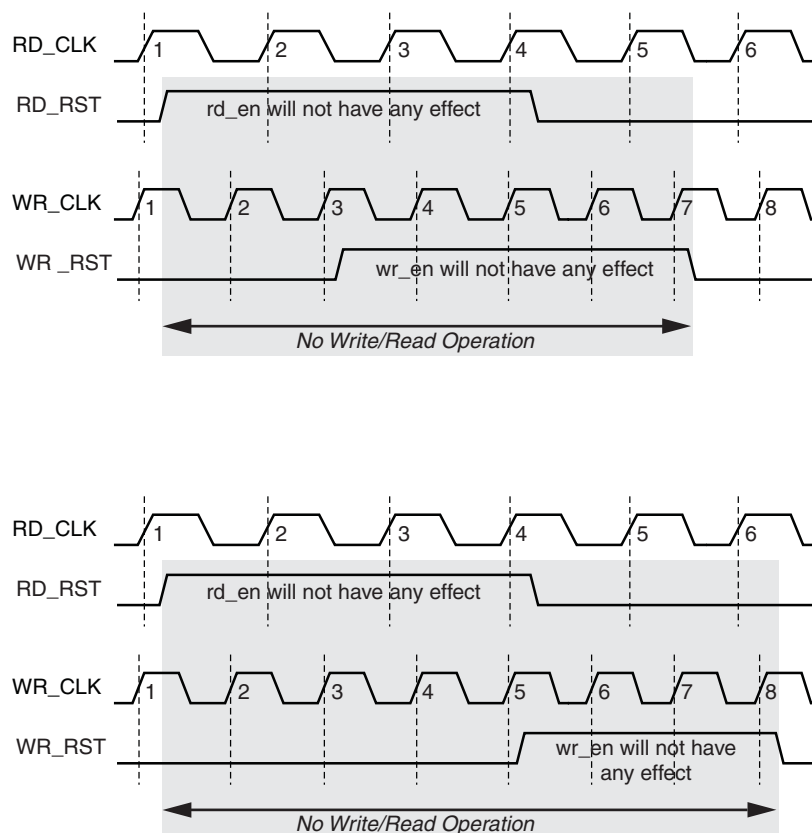


Figure 4-33: Synchronous Reset: FIFO with Independent Clock - WR\_RST then RD\_RST



**Figure 4-34: Synchronous Reset: FIFO with Independent Clock - RD\_RST then WR\_RST**

**Table 4-9** defines the values of the output ports during power-up and the reset state. If the user does not specify a DOUT reset value, it defaults to 0. The FIFO requires a reset pulse of only 1 clock cycle. The FIFOs are available for transaction on the clock cycle after the reset is released. The power-up values for the synchronous reset are the same as the reset state.

Note that the underflow signal is dependent on RD\_EN. If RD\_EN is asserted and the FIFO is empty, underflow is asserted. The overflow signal is dependent on WR\_EN. If WR\_EN is asserted and the FIFO is full, overflow is asserted.

**Table 4-9: Synchronous FIFO Reset and Power-up Values**

Signal	Block Memory and Distributed Memory Values of Output Ports During Reset and Power-up
DOUT	DOUT Reset Value or 0
FULL	0
ALMOST FULL	0
EMPTY	1
ALMOST EMPTY	1
VALID	0 (active high) or 1 (active low)



Table 4-9: Synchronous FIFO Reset and Power-up Values (Cont'd)

WR_ACK	0 (active high) or 1 (active low)
PROG_FULL	0
PROG_EMPTY	0
RD_DATA_COUNT	0
WR_DATA_COUNT	0

## Actual FIFO Depth

Of critical importance is the understanding that the *effective* or *actual* depth of a FIFO is *not necessarily* consistent with the *depth* selected in the GUI, because the actual depth of the FIFO depends on its implementation and the features that influence its implementation. In the FIFO Generator GUI, the actual depth of the FIFO is reported: the following section provides formulas or calculations used to report this information.

### Block RAM, Distributed RAM and Shift RAM FIFOs

The actual FIFO depths for the block RAM, distributed RAM, and shift RAM FIFOs are influenced by the following features that change its implementation:

- Common or Independent Clock
- Standard or FWFT Read Mode
- Symmetric or Non-symmetric Port Aspect Ratio

Depending on how a FIFO is configured, the calculation for the actual FIFO depth varies.

- Common Clock FIFO in Standard Read Mode

$$\text{actual\_write\_depth} = \text{gui\_write\_depth}$$

$$\text{actual\_read\_depth} = \text{gui\_read\_depth}$$

- Common Clock FIFO in FWFT Read Mode

$$\text{actual\_write\_depth} = \text{gui\_write\_depth} + 2$$

$$\text{actual\_read\_depth} = \text{gui\_read\_depth} + 2$$

- Independent Clock FIFO in Standard Read Mode

$$\text{actual\_write\_depth} = \text{gui\_write\_depth} - 1$$

$$\text{actual\_read\_depth} = \text{gui\_read\_depth} - 1$$

- Independent Clock FIFO in FWFT Read Mode

$$\text{actual\_write\_depth} = (\text{gui\_write\_depth} - 1) + (2 * \text{round\_down}(\text{gui\_write\_depth} / \text{gui\_read\_depth}))$$

$$\text{actual\_read\_depth} = \text{gui\_read\_depth} + 1$$

Notes

1. Gui\_write\_depth = actual write (input) depth selected in the GUI
2. Gui\_read\_depth = actual read (output) depth selected in the GUI
3. Non-symmetric port aspect ratio feature (gui\_write\_depth not equal to gui\_read\_depth) is only supported in block RAM based FIFOs.

## Virtex-6 and Virtex-5 FPGA Built-In FIFOs

The actual FIFO depths for the Virtex-6 and Virtex-5 FPGA built-in FIFOs are influenced by the following features, which change its implementation:

- Common or Independent Clock
- Standard or FWFT Read Mode
- Built-In FIFO primitive used in implementation (minimum depth is 512)

Depending on how a FIFO is configured, the calculation for the actual FIFO depth varies.

- Independent Clock FIFO in Standard Read Mode

$$\text{actual\_write\_depth} = (\text{primitive\_depth} + 2) * (N - 1) + (\text{primitive\_depth} + 1)$$

- Independent Clock FIFO in FWFT Read Mode

$$\text{actual\_write\_depth} = (\text{primitive\_depth} + 2) * N$$

- Common Clock FIFO in Standard Read Mode

$$\text{actual\_write\_depth} = (\text{primitive\_depth} + 1) * (N - 1) + \text{primitive\_depth}$$

- Common Clock FIFO in FWFT Read Mode

$$\text{actual\_write\_depth} = (\text{primitive\_depth} + 1) * N$$

Notes

1. `primitive_depth` = depth of the primitive used to implement the FIFO; this information is reported in the GUI
2. `N` = number of primitive cascaded in depth or roundup  

$$(\text{gui\_write\_depth} / \text{primitive\_depth})$$

## Virtex-4 FPGA Built-In FIFOs

The actual FIFO depths for the Virtex-4 FPGA Built-in FIFOs are influenced by the following features, which change its implementation:

- Read and Write Clock Frequencies
- Built-In FIFO primitive used in implementation (minimum depth is 512)

Depending on how a FIFO is configured, the calculation for the actual FIFO depth varies.

- Common/Independent Clock FIFO in Standard Read Mode and `RD_CLK` frequency > `WR_CLK` frequency

$$\text{actual\_write\_depth} = \text{primitive\_depth} + 17$$

- Common/Independent Clock FIFO in Standard Read Mode and `RD_CLK` frequency <= `WR_CLK` frequency

$$\text{actual\_write\_depth} = \text{primitive\_depth} + 17$$

**Note:** `primitive_depth` = depth of the primitive used to implement the FIFO. For more details, see [UG070](#), *Virtex-4 FPGA User Guide*.

## Latency

This section defines the latency in which different output signals of the FIFO are updated in response to read or write operations.

**Note:** Latency is defined as the number of clock edges after a read or write operation occur before the signal is updated. Example: if latency is 0, that means that the signal is updated at the clock edge in which the operation occurred, as shown in Figure 4-35 in which WR\_ACK is getting updated in which WR\_EN is high.

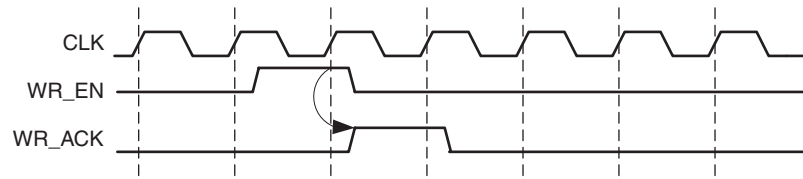


Figure 4-35: Latency 0 Timing

## Non-Built-in FIFOs: Common Clock and Standard Read Mode Implementations

Table 4-10 defines the write port flags update latency due to a write operation for non-Built-in FIFOs such as block RAM, distributed RAM, and shift RAM FIFOs.

Table 4-10: Write Port Flags Update Latency Due to Write Operation

Signals	Latency (CLK)
FULL	0
ALMOST_FULL	0
PROG_FULL	1
WR_ACK	0
OVERFLOW	0

Table 4-11 defines the read port flags update latency due to a read operation.

Table 4-11: Read Port Flags Update Latency Due to Read Operation

Signals	Latency (CLK)
EMPTY	0
ALMOST_EMPTY	0
PROG_EMPTY	1
VALID	0
UNDERFLOW	0
DATA_COUNT	0

Table 4-12 defines the write port flags update latency due to a read operation. Table 4-13

Table 4-12: Write Port Flags Update Latency Due to Read Operation

Signals	Latency (CLK)
FULL	0
ALMOST_FULL	0
PROG_FULL	1

**Table 4-12: Write Port Flags Update Latency Due to Read Operation (Cont'd)**

WR_ACK <sup>a</sup>	N/A
OVERFLOW <sup>a</sup>	N/A

a. Write handshaking signals are only impacted by a write operation.

Table 4-13 defines the read port flags update latency due to a write operation.

**Table 4-13: Read Port Flags Update Latency Due to Write Operation**

Signals	Latency (CLK)
EMPTY	0
ALMOST_EMPTY	0
PROG_EMPTY	1
VALID <sup>a</sup>	N/A
UNDERFLOW <sup>a</sup>	N/A
DATA_COUNT	0

a. Read handshaking signals are only impacted by a read operation.

## Non-Built-in FIFOs: Common CLock and FWFT Read Mode Implementations

Table 4-14 defines the write port flags update latency due to a write operation for non-Built-in FIFOs such as block RAM, distributed RAM, and shift RAM FIFOs.

**Table 4-14: Write Port Flags Update Latency due to Write Operation**

Signals	Latency (CLK)
FULL	0
ALMOST_FULL	0
PROG_FULL	1
WR_ACK	0
OVERFLOW	0

Table 4-15 defines the read port flags update latency due to a read operation.

**Table 4-15: Read Port Flags Update Latency due to Read Operation**

Signals	Latency (CLK)
EMPTY	0
ALMOST_EMPTY	0
PROG_EMPTY	1
VALID	0
UNDERFLOW	0
DATA_COUNT	0

Table 4-16 defines the write port flags update latency due to a read operation.

Table 4-16: Write Port Flags Update Latency Due to Read Operation

Signals	Latency (CLK)
FULL	0
ALMOST_FULL	0
PROG_FULL	1
WR_ACK <sup>a</sup>	N/A
OVERFLOW <sup>a</sup>	N/A

a. Write handshaking signals are only impacted by a write operation.

Table 4-17 defines the read port flags update latency due to a write operation.

**Table 4-17: Read Port Flags Update Latency Due to Write Operation**

Signals	Latency (CLK)
EMPTY	2
ALMOST_EMPTY	1
PROG_EMPTY	1
VALID <sup>a</sup>	N/A
UNDERFLOW <sup>a</sup>	N/A
DATA_COUNT	0

a. Read handshaking signals are only impacted by a read operation.

## Non-Built-in FIFOs: Independent Clock and Standard Read Mode Implementations

Table 4-18 defines the write port flags update latency due to a write operation.

**Table 4-18: Write Port Flags Update Latency Due to a Write Operation**

Signals	Latency (WR_CLK)
FULL	0
ALMOST_FULL	0
PROG_FULL	1
WR_ACK	0
OVERFLOW	0
WR_DATA_COUNT	1

Table 4-19 defines the read port flags update latency due to a read operation.

**Table 4-19: Read Port Flags Update Latency Due to a Read Operation**

Signals	Latency (RD_CLK)
EMPTY	0
ALMOST_EMPTY	0
PROG_EMPTY	1
VALID	0
UNDERFLOW	0
RD_DATA_COUNT	1

Table 4-20 defines the write port flags update latency due to a read operation.

**Table 4-20: Write Port Flags Update Latency Due to a Read Operation**

Signals	Latency
FULL	1 RD_CLK + 4 WR_CLK (+1 WR_CLK) <sup>a</sup>

**Table 4-20: Write Port Flags Update Latency Due to a Read Operation**

ALMOST_FULL	$1 \text{ RD\_CLK} + 4 \text{ WR\_CLK} (+1 \text{ WR\_CLK})^a$
PROG_FULL	$1 \text{ RD\_CLK} + 5 \text{ WR\_CLK} (+1 \text{ WR\_CLK})^a$
WR_ACK <sup>b</sup>	N/A
OVERFLOW <sup>b</sup>	N/A
WR_DATA_COUNT	$1 \text{ RD\_CLK} + 4 \text{ WR\_CLK} (+1 \text{ WR\_CLK})^a$

- a. The crossing clock domain logic in independent clock FIFOs introduces a 1 WR\_CLK uncertainty to the latency calculation.
- b. Write handshaking signals are only impacted by a write operation.

Table 4-21 defines the read port flags update latency due to a write operation.

**Table 4-21: Read Port Flags Update Latency Due to a Write Operation**

Signals	Latency
EMPTY	$1 \text{ WR\_CLK} + 4 \text{ RD\_CLK} (+1 \text{ RD\_CLK})^a$
ALMOST_EMPTY	$1 \text{ WR\_CLK} + 4 \text{ RD\_CLK} (+1 \text{ RD\_CLK})^a$
PROG_EMPTY	$1 \text{ WR\_CLK} + 5 \text{ RD\_CLK} (+1 \text{ RD\_CLK})^a$
VALID <sup>b</sup>	N/A
UNDERFLOW <sup>b</sup>	N/A
RD_DATA_COUNT	$1 \text{ WR\_CLK} + 4 \text{ RD\_CLK} (+1 \text{ RD\_CLK})^a$

**Note:** Read handshaking signals only impacted by read operation.

- a. The crossing clock domain logic in independent clock FIFOs introduces a 1 RD\_CLK uncertainty to the latency calculation.
- b. Read handshaking signals are only impacted by a read operation.

## Non-Built-in FIFOs: Independent Clock and FWFT Read Mode Implementations

Table 4-22 defines the write port flags update latency due to a write operation.

**Table 4-22: Write Port Flags Update Latency Due to a Write Operation**

Signals	Latency (WR_CLK)
FULL	0
ALMOST_FULL	0
PROG_FULL	1
WR_ACK	0
OVERFLOW	0
WR_DATA_COUNT	1

Table 4-23 defines the read port flags update latency due to a read operation.

Table 4-23: Read Port Flags Update Latency Due to a Read Operation

Signals	Latency (RD_CLK)
EMPTY	0
ALMOST_EMPTY	0
PROG_EMPTY	1
VALID	0
UNDERFLOW	0
RD_DATA_COUNT	1

Table 4-24 defines the write port flags update latency due to a read operation.

Table 4-24: Write Port Flags Update Latency Due to a Read Operation

Signals	Latency
FULL	1 RD_CLK + 4 WR_CLK (+1 WR_CLK) <sup>a</sup>
ALMOST_FULL	1 RD_CLK + 4 WR_CLK (+1 WR_CLK) <sup>a</sup>
PROG_FULL	1 RD_CLK + 5 WR_CLK (+1 WR_CLK) <sup>a</sup>
WR_ACK <sup>b</sup>	N/A
OVERFLOW <sup>b</sup>	N/A
WR_DATA_COUNT	1 RD_CLK + 4 WR_CLK (+1 WR_CLK) <sup>a</sup>

a. The crossing clock domain logic in independent clock FIFOs introduces a 1 WR\_CLK uncertainty to the latency calculation.

b. Write handshaking signals are only impacted by a write operation.

Table 4-25 defines the read port flags update latency due to a write operation.

Table 4-25: Read Port Flags Update Latency Due to a Write Operation

Signals	Latency
EMPTY	1 WR_CLK + 6 RD_CLK (+1 RD_CLK) <sup>a</sup>
ALMOST_EMPTY	1 WR_CLK + 6 RD_CLK (+1 RD_CLK) <sup>a</sup>
PROG_EMPTY	1 WR_CLK + 5 RD_CLK (+1 RD_CLK) <sup>a</sup>
VALID <sup>b</sup>	N/A
UNDERFLOW <sup>b</sup>	N/A
RD_DATA_COUNT	1 WR_CLK + 4 RD_CLK (+1 RD_CLK) <sup>a</sup> + [2 RD_CLK (+1 RD_CLK)] <sup>c</sup>

**Note:** Read handshaking signals only impacted by read operation.

a. The crossing clock domain logic in independent clock FIFOs introduces a 1 RD\_CLK uncertainty to the latency calculation.

b. Read handshaking signals are only impacted by a read operation.

c. This latency is the worst-case latency. The addition of the [2 RD\_CLK (+1 RD\_CLK)] latency depends on the status of the EMPTY and ALMOST\_EMPTY flags.



## Virtex-6 and Virtex-5 FPGA Built-in FIFOs: Common Clock and Standard Read Mode Implementations

**Note:** N is the number of primitives cascaded in depth; this can be calculated by dividing the GUI depth by the primitive depth.

Table 4-26 defines the write port flags update latency due to a write operation.

**Table 4-26: Write Port Flags Update Latency Due to Write Operation**

Signals	Latency (CLK)
FULL	0
PROG_FULL	1
WR_ACK	0
OVERFLOW	0

Table 4-27 defines the read port flags update latency due to a read operation.

**Table 4-27: Read Port Flags Update Latency Due to Read Operation**

Signals	Latency (CLK)
EMPTY	0
PROG_EMPTY	1
VALID	0
UNDERFLOW	0

Table 4-28 defines the write port flags update latency due to a read operation.

**Table 4-28: Write Port Flags Update Latency Due to Read Operation**

Signals	Latency (CLK)
FULL	(N-1)
PROG_FULL	N
WR_ACK <sup>a</sup>	N/A
OVERFLOW <sup>a</sup>	N/A

a. Write handshaking signals are only impacted by a write operation.

Table 4-29 defines the read port flags update latency due to a write operation.

**Table 4-29: Read Port Flags Update Latency Due to Write Operation**

Signals	Latency (CLK)
EMPTY	$(N-1)*2$
PROG_EMPTY	$(N-1)*2+1$
VALID <sup>a</sup>	N/A
UNDERFLOW <sup>a</sup>	N/A

**Note:** Read handshaking signals only impacted by read operation.

a. Read handshaking signals are only impacted by a read operation.

## Virtex-6 and Virtex-5 FPGA Built-in FIFOs: Common Clock and FWFT Read Mode Implementations

**Note:** N is the number of primitives cascaded in depth; this can be calculated by dividing the GUI depth by the primitive depth.

Table 4-30 defines the write port flags update latency due to a write operation.

**Table 4-30: Write Port Flags Update Latency Due to Write Operation**

Signals	Latency (CLK)
FULL	0
PROG_FULL	1
WR_ACK	0
OVERFLOW	0

Table 4-31 defines the read port flags update latency due to a read operation.

**Table 4-31: Read Port Flags Update Latency Due to a Read Operation**

Signals	Latency (CLK)
EMPTY	0
PROG_EMPTY	1
VALID	0
UNDERFLOW	0

Table 4-32 defines the write port flags update latency due to a read operation.

**Table 4-32: Write Port Flags Update Latency Due to a Read Operation**

Signals	Latency (CLK)
FULL	$(N-1)$
PROG_FULL <sup>a</sup>	N
WR_ACK <sup>a</sup>	N/A
OVERFLOW	N/A

- a. Write handshaking signals are only impacted by a write operation.

Table 4-33 defines the read port flags update latency due to a write operation

**Table 4-33: Read Port Flags Update Latency Due to a Write Operation**

Signals	Latency (CLK)
EMPTY	$((N-1)*2+1)$
PROG_EMPTY	$((N-1)*2+1)$
VALID <sup>a</sup>	N/A
UNDERFLOW <sup>a</sup>	N/A

- a. Read handshaking signals are only impacted by a read operation.

## Virtex-6 and Virtex-5 FPGA Built-in FIFOs: Independent Clocks and Standard Read Mode Implementations

**Note:** N is the number of primitives cascaded in depth; this can be calculated by dividing the GUI depth by the primitive depth. *Faster\_Clk* is the clock domain, either RD\_CLK or WR\_CLK, that has a larger frequency.

Table 4-34 defines the write port flags update latency due to a write operation.

**Table 4-34: Write Port Flags Update Latency Due to a Write Operation**

Signals	Latency (WR_CLK)
FULL	0
PROG_FULL	1
WR_ACK	0
OVERFLOW	0

Table 4-35 defines the read port flags update latency due to a read operation.

**Table 4-35: Read Port Flags Update Latency Due to a Read Operation**

Signals	Latency (RD_CLK)
EMPTY	0
PROG_EMPTY	1
VALID	0
UNDERFLOW	0

Table 4-36 defines the write port flags update latency due to a read operation.

**Table 4-36: Write Port Flags Update Latency Due to a Read Operation**

Signals	Latency
FULL	$(N-1) \cdot 5 \text{ faster\_clk} + 4 \text{ WR\_CLK}$
PROG_FULL	$(N-1) \cdot 4 \text{ faster\_clk} + 3 \text{ WR\_CLK}$
WR_ACK <sup>a</sup>	N/A
OVERFLOW <sup>a</sup>	N/A

a. Write handshaking signals are only impacted by a write operation.

Table 4-37 defines the read port flags update latency due to a write operation.

**Table 4-37: Read Port Flags Update Latency Due to a Write Operation**

Signals	Latency
EMPTY	$(N-1) \cdot 5 \text{ faster\_clk} + 3 \text{ RD\_CLK}$
PROG_EMPTY	$(N-1) \cdot 4 \text{ faster\_clk} + 3 \text{ RD\_CLK}$
VALID <sup>a</sup>	N/A
UNDERFLOW <sup>a</sup>	N/A

a. Read handshaking signals are only impacted by a read operation.

## Virtex-6 and Virtex-5 FPGA Built-in FIFOs: Independent Clocks and FWFT Read Mode Implementations

**Note:** N is the number of primitives cascaded in depth, which can be calculated by dividing the GUI depth by the primitive depth. *Faster\_Clk* is the clock domain, either RD\_CLK or WR\_CLK, that has a larger frequency.

Table 4-38 defines the write port flags update latency due to a write operation.

**Table 4-38: Write Port Flags Update Latency Due to a Write Operations**

Signals	Latency (WR_CLK)
FULL	0
PROG_FULL	1
WR_ACK	0
OVERFLOW	0

Table 4-39 defines the read port flags update latency due to a read operation.

**Table 4-39: Read Port Flags Update Latency Due to a Read Operation**

Signals	Latency (RD_CLK)
EMPTY	0
PROG_EMPTY	1
VALID	0
UNDERFLOW	0

Table 4-40 defines the write port flags update latency due to a read operation.

**Table 4-40: Write Port Flags Update Latency Due to a Read Operation**

Signals	Latency
FULL	$(N-1) \cdot 5 \text{ faster\_clk} + 4 \text{ WR\_CLK}$
PROG_FULL	$(N-1) \cdot 4 \text{ faster\_clk} + 3 \text{ WR\_CLK}$
WR_ACK <sup>a</sup>	N/A
OVERFLOW <sup>a</sup>	N/A

a. Write handshaking signals are only impacted by a write operation.

Table 4-41 defines the read port flags update latency due to a write operation.

**Table 4-41: Read Port Flags Update Latency Due to a Write Operation**

Signals	Latency
EMPTY	$(N-1) \cdot 5 \text{ faster\_clk} + 4 \text{ RD\_CLK}$
PROG_EMPTY	$(N-1) \cdot 4 \text{ faster\_clk} + 3 \text{ RD\_CLK}$
VALID <sup>a</sup>	N/A
UNDERFLOW <sup>a</sup>	N/A

a. Read handshaking signals are only impacted by a read operation.

## Virtex-4 FPGA Built-in FIFO

The Virtex-4 FPGA supports only one Built-in FIFO with a data width of 4, 9, 18 or 36. For more details for the write and read port flags update latency, see [UG070, Virtex-4 FPGA User Guide](#).



## Special Design Considerations

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This chapter provides additional design considerations for using the FIFO Generator core.

### Resetting the FIFO

The FIFO Generator must be reset after the FPGA is configured and before operation begins. Two reset pins are available, asynchronous (RST) and synchronous (SRST), and both clear the internal counters and output registers.

- For asynchronous reset, internal to the core, RST is synchronized to the clock domain in which it is used, to ensure that the FIFO initializes to a known state. This synchronization logic allows for proper reset timing of the core logic, avoiding glitches and metastable behavior. To avoid unexpected behavior, it is not recommended to drive/toggle WR\_EN/RD\_EN when RST is asserted/high.
- For common clock block and distributed RAM synchronous reset, because the reset pin is synchronous to the input clock and there is only one clock domain in the FIFO, no additional synchronization logic is needed.
- For independent clock block and distributed RAM synchronous reset, because the reset pin (WR\_RST/RD\_RST) is synchronous to the respective clock domain, no additional synchronization logic is needed. However, it is recommended to follow these rules to avoid unexpected behavior:
  - ♦ If WR\_RST is applied, then RD\_RST must also be applied and vice versa.
  - ♦ No write or read operations should be performed until both clock domains are reset.

The generated FIFO core will be initialized after reset to a known state. For details about reset values and behavior, see [“Reset Behavior” in Chapter 4](#) of this guide.

### Continuous Clocks

The FIFO Generator is designed to work only with free-running write and read clocks. Xilinx does not recommend controlling the core by manipulating RD\_CLK and WR\_CLK. If this functionality is required to gate FIFO operation, we recommend using the write enable (WR\_EN) and read enable (RD\_EN) signals.

### Pessimistic Full and Empty

When independent clock domains are selected, the full flag (FULL, ALMOST\_FULL) and empty flag (EMPTY, ALMOST\_EMPTY) are pessimistic flags. FULL and ALMOST\_FULL are synchronous to the write clock (WR\_CLK) domain, while EMPTY and ALMOST\_EMPTY are synchronous to the read clock (RD\_CLK) domain.

The full flags are considered pessimistic flags because they assume that no read operations have taken place in the read clock domain. `ALMOST_FULL` is guaranteed to be asserted on the rising edge of `WR_CLK` when there is only one available location in the FIFO, and `FULL` is guaranteed to be asserted on the rising edge of `WR_CLK` when the FIFO is full. There may be a number of clock cycles between a read operation and the deassertion of `FULL`. The precise number of clock cycles for `FULL` to deassert is not predictable due to the crossing of clock domains and synchronization logic. For more information see [“Simultaneous Assertion of Full and Empty Flag.”](#)

The `EMPTY` flags are considered pessimistic flags because they assume that no write operations have taken place in the write clock domain. `ALMOST_EMPTY` is guaranteed to be asserted on the rising edge of `RD_CLK` when there is only one more word in the FIFO, and `EMPTY` is guaranteed to be asserted on the rising edge of `RD_CLK` when the FIFO is empty. There may be a number of clock cycles between a write operation and the deassertion of `EMPTY`. The precise number of clock cycles for `EMPTY` to deassert is not predictable due to the crossing of clock domains and synchronization logic. For more information see [“Simultaneous Assertion of Full and Empty Flag.”](#)

See [Chapter 4, “Designing with the Core,”](#) for detailed information about the latency and behavior of the full and empty flags.

## Programmable Full and Empty

The programmable full (`PROG_FULL`) and programmable empty (`PROG_EMPTY`) flags provide the user flexibility in specifying when the programmable flags assert and deassert. These flags can be set either by constant value(s) or by input port(s). These signals differ from the full and empty flags because they assert one (or more) clock cycle *after* the assert threshold has been reached. These signals are deasserted some time after the negate threshold has been passed. In this way, `PROG_EMPTY` and `PROG_FULL` are also considered pessimistic flags. See [“Programmable Flags” in Chapter 4](#) of this guide for more information about the latency and behavior of the programmable flags.

## Simultaneous Assertion of Full and Empty Flag

For independent clock FIFO, there are delays in the assertion/deassertion of the full and empty flags due to cross clock domain logic. These delays may cause unexpected FIFO behavior like full and empty asserting at the same time. To avoid this, the following A and B equations must be true.

- A) Time it takes to update full flag due to read operation < time it takes to empty a full FIFO
- B) Time it takes to update empty flag due to write operation < time it takes to fill an empty FIFO

For example, assume the following configurations:

Independent clock (non built-in), standard FIFO

write clock frequency = 3MHz, `wr_clk_period` = 333 ns

read clock frequency = 148 MHz, `rd_clk_period` = 6.75 ns

write depth = read depth = 20

`actual_wr_depth` = `actual_rd_depth` = 19 (as mentioned in [“Actual FIFO Depth” in Chapter 4](#))



Apply equation A:

Time it takes to update full flag due to read operation < time it takes to empty a full FIFO  
 $= 1 \cdot \text{rd\_clk\_period} + 5 \cdot \text{wr\_clk\_period} < \text{actual\_rd\_depth} \cdot \text{rd\_clk\_period}$

$$1 \cdot 6.75 + 5 \cdot 333 < 19 \cdot 6.75$$

1671.75 ns < 128.5 ns --> Equation VIOLATED!

**Note:** Left side equation is the latency of full flag updating due to read operation as mentioned in [Table 4-20](#).

Conclusion: Violation of this equation proves that for this design, when a FULL FIFO is read from continuously, the empty flag asserts before the full flag deasserts due to the read operations that occurred.

Apply Equation B:

Time it takes to update empty flag due to write operation < time it takes to fill an empty FIFO

$$1 \cdot \text{wr\_clk\_period} + 5 \cdot \text{rd\_clk\_period} < \text{actual\_wr\_depth} \cdot \text{wr\_clk\_period}$$

$$1 \cdot 333 + 5 \cdot 6.75 < 19 \cdot 333$$

366.75 ns < 6327 ns --> Equation MET!

**Note:** Left side equation is the latency of empty flag updating due to write operation as mentioned in [Table 4-21](#).

Conclusion: Because this equation is met for this design, an EMPTY FIFO that is written into continuously has its empty flag deassert before the full flag is asserted.

## Write Data Count and Read Data Count

When independent clock domains are selected, write data count (WR\_DATA\_COUNT) and read data count (RD\_DATA\_COUNT) signals are provided as an indication of the number of words in the FIFO relative to the write or read clock domains, respectively.

Consider the following when using the WR\_DATA\_COUNT or RD\_DATA\_COUNT ports.

- The WR\_DATA\_COUNT and RD\_DATA\_COUNT outputs are not an instantaneous representation of the number of words in the FIFO, but can instantaneously provide an approximation of the number of words in the FIFO.
- WR\_DATA\_COUNT and RD\_DATA\_COUNT may skip values from clock cycle to clock cycle.
- Using non-symmetric aspect ratios, or running clocks which vary dramatically in frequency, will increase the disparity between the data count outputs and the actual number of words in the FIFO.

**Note:** The WR\_DATA\_COUNT and RD\_DATA\_COUNT outputs will always be correct after some period of time where RD\_EN=0 and WR\_EN=0 (generally, just a few clock cycles after read and write activity stops).

See [“Data Counts” in Chapter 4](#) of this guide for details about the latency and behavior of the data count flags.

## Setup and Hold Time Violations

When generating a FIFO with independent clock domains (whether a DCM is used to derive the write/read clocks or not), the core internally synchronizes the write and read clock domains. For this reason, setup and hold time violations are expected on certain registers within the core. In simulation, warning messages may be issued indicating these violations. If these warning messages are from the FIFO Generator core, they can be safely ignored. The core is designed to properly handle these conditions, regardless of the phase or frequency relationship between the write and read clocks.

Alternatively, there are two ways to disable these expected setup and hold time violations due to data synchronization between clock domains:

- Add the following constraint to your design—this constraint sets a timing constraint to the synchronization logic by requiring a maximum set of delays. The maximum delays used is defined by 2x of the slower clock period.

```
NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/wr_pntr_gc<0> MAXDELAY = 12
ns;
NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/wr_pntr_gc<1> MAXDELAY = 12
ns;
...
NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/wr_pntr_gc<9> MAXDELAY = 12
ns;

NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/rd_pntr_gc<0> MAXDELAY = 12
ns;
NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/rd_pntr_gc<1> MAXDELAY = 12
ns;
...
NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/rd_pntr_gc<9> MAXDELAY = 12
ns;
```

- Add the following constraint to your design—this constraint directs the tool to ignore the appropriate paths that are part of the synchronization logic:

```
NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/wr_pntr_gc<0> TIG;
NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/wr_pntr_gc<1> TIG;
...
NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/wr_pntr_gc<9> TIG;

NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/rd_pntr_gc<0> TIG;
NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/rd_pntr_gc<1> TIG;
...
NET fifo_instance/BU2/U0/grf.rf/gcx.clkx/rd_pntr_gc<9> TIG;
```

- If distributed RAM FIFO is used, the following constraints may also be required to improve the timing.

```
INST "fifo_instance/BU2/U0/grf.rf/mem/gdm.dm/Mram*" TNM= RAMSOURCE;
INST "fifo_instance/BU2/U0/grf.rf/mem/gdm.dm/dout*" TNM= FFDEST;
TIMESPEC TS_RAM_FF= FROM "RAMSOURCE" TO "FFDEST" <<one read clock
period>> DATAPATHONLY;
```

## Simulating Your Design

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The FIFO Generator is provided as a Xilinx technology-specific netlist, and as a behavioral or structural simulation model. This chapter provides instructions for simulating the FIFO Generator in your design.

### Simulation Models

The FIFO Generator supports two types of simulation models based on the Xilinx CORE Generator system project options. The models are available in both VHDL and Verilog®. Both types of models are described in detail in this chapter.

To choose a model:

1. Open the CORE Generator.
2. Select Options from the Project drop-down list.
3. Click the Generation tab.
4. Choose to generate a behavioral model or a structural model.

#### Behavioral Models

**Important!** The behavioral models provided do not model synchronization delay, and are designed to reproduce the behavior and functionality of the FIFO Generator. The models maintain the assertion/deassertion of the output signals to match the FIFO Generator.

The behavioral models are functionally correct, and will represent the behavior of the configured FIFO. The write-to-read latency and the behavior of the status flags will accurately match the actual implementation of the FIFO design.

To generate behavioral models, select Behavioral and VHDL or Verilog in the Xilinx CORE Generator project options. Behavioral models are the default project options.

The following considerations apply to the behavioral models.

- Write operations always occur relative to the write clock (WR\_CLK) or common clock (CLK) domain, as do the corresponding handshaking signals.
- Read operations always occur relative to the read clock (RD\_CLK) or common clock (CLK) domain, as do the corresponding handshaking signals.
- The delay through the FIFO (write-to-read latency) will match the VHDL model, Verilog model, and core.
- The deassertion of the status flags (full, almost full, programmable full, empty, almost empty, programmable empty) will match the VHDL model, Verilog model, and core.

**Note:** If independent clocks or common clocks with built-in FIFO is selected, the user must use the structural model, as the behavioral model does not support the built-in FIFO configurations.

## Structural Models

The structural models are designed to provide a more accurate model of FIFO behavior at the cost of simulation time. These models will provide a closer approximation of cycle accuracy across clock domains for asynchronous FIFOs. No asynchronous FIFO model can be 100% cycle accurate as physical relationships between the clock domains, including temperature, process, and frequency relationships, affect the domain crossing indeterminately.

To generate structural models, select Structural and VHDL or Verilog in the Xilinx CORE Generator project options.

**Note:** Simulation performance may be impacted when simulating the structural models compared to the behavioral models

# *Performance Information*

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## **Resource Utilization and Performance**

Performance and resource utilization for a FIFO varies depending on the configuration and features selected during core customization. The following tables show resource utilization data and maximum performance values for a variety of sample FIFO configurations.

See "Resource Utilization and Performance" in [FIFO Generator Data Sheet](#) for the performance and resource utilization numbers.



## Core Parameters

### FIFO Parameters

Table B-1 describes the FIFO core parameters, including the XCO file value and the default settings.

Table B-1: FIFO Parameter Table

Parameter Name	XCO File Values	Default GUI Setting
Component_Name	instance_name ASCII text starting with a letter and using the following character set: a-z, 0-9, and _	fifo_generator_v4_4
FIFO Implementation	Common_Clock_Block_RAM Common_Clock_Distributed_RAM Common_Clock_Shift_Register Common_Clock_Builtin_FIFO Independent_Clocks_Block_RAM Independent_Clocks_Distributed_RAM Independent_Clocks_Builtin_FIFO	Common_Clock_Block_RAM
Input Data Width <sup>a</sup>	Integer in range 1 to 1024	18
Output Data Width <sup>1</sup>	Integer in range 1 to 1024	18
Input Depth <sup>1</sup>	2 <sup>N</sup> where N is an integer 4 to 24	1024
Output Depth <sup>1</sup>	2 <sup>M</sup> where M is an integer 4 to 24	1024
Data Count Width	Integer in range 1 to log <sub>2</sub> (Output Depth)	10
Read Clock Frequency	Integer 1 to 1000 (MHz)	1
Write Clock Frequency	Integer 1 to 1000 (MHz)	1
Almost Full Flag	true, false	false
Almost Empty Flag	true, false	false
Enable ECC	true, false	false
Programmable Full Type	No_Programmable_Full_Threshold Single_Programmable_Full_Threshold_Constant Multiple_Programmable_Full_Threshold_Constants Single_Programmable_Full_Threshold_Input_Port Multiple_Programmable_Full_Threshold_Input_Ports	No_Programmable_Full_Threshold

Table B-1: FIFO Parameter Table (Cont'd)

Parameter Name	XCO File Values	Default GUI Setting
Full Threshold Assert Value	See range under Programmable Flags.	1022
Full Threshold Negate Value	See range under “Programmable Flags,” page 57.	1021
Programmable Empty Type	No_Programmable_Empty_Threshold Single_Programmable_Empty_Threshold_Constant Multiple_Programmable_Empty_Threshold_Constants Single_Programmable_Empty_Threshold_Input_Ports Multiple_Programmable_Empty_Threshold_Input_Ports	No_Programmable_Empty_Threshold
Empty Threshold Assert Value	See range under “Programmable Flags,” page 57.	2
Empty Threshold Negate Value	See range under “Programmable Flags,” page 57.	3
Write Acknowledge Flag	true, false	false
Write Acknowledge Sense	Active_High, Active_Low	Active_High
Overflow Flag	true, false	false
Overflow Sense	Active_High, Active_Low	Active_High
Valid Flag	true, false	false
Valid Sense	Active_High, Active_Low	Active_High
Underflow Flag	true, false	false
Underflow Sense	Active_High, Active_Low	Active_High
Use Dout Reset	true, false	true
Dout Reset Value	Hex value in range of 0 to output data width - 1	0
Primitive Depth	512, 1024, 2048, 4096	1024
Read Data Count	true, false	false
Read Data Count Width	Integer in range 1 to $\log_2(\text{output depth})$	10
Write Data Count	true, false	false
Write Data Count Width	Integer in range 1 to $\log_2(\text{input depth})$	10
Data Count	true, false	false
Performance Options	First_Word_Fall_Through, Standard_Fifo	Standard_Fifo
Read Latency	integer range 0 to 1	1
Reset Pin	true, false	true
Use Embedded Registers	true, false	false
Full Flags Reset Value	1, 0	1

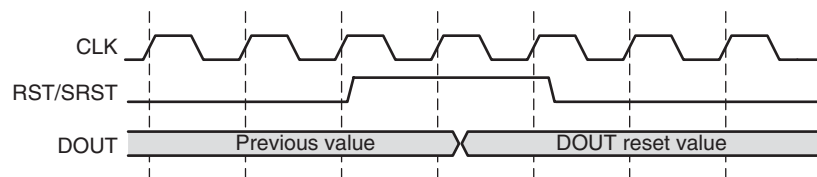


- a. A user-customized core should not exceed the number of shift registers, built-in FIFOs, block RAM, or distributed RAM primitives available in the targeted architecture; it is the user's responsibility to know the resource availability in the targeted device.



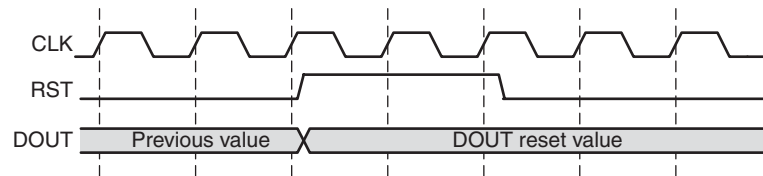
# DOUT Reset Value Timing

Figure C-1 shows the DOUT reset value for common clock block RAM, distributed RAM and Shift Register based FIFOs for synchronous reset (SRST), and common clock block RAM FIFO for asynchronous reset (RST).



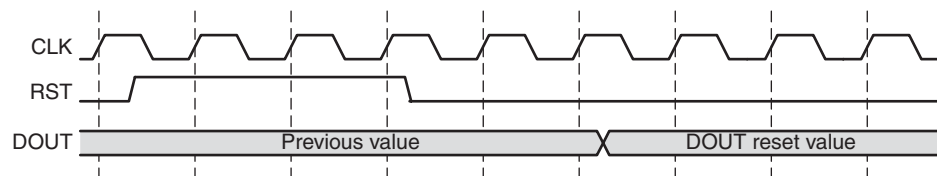
**Figure C-1: DOUT Reset Value for Synchronous Reset (SRST) and for Asynchronous Reset (RST) for Common Clock Block RAM Based FIFO**

Figure C-2 shows the DOUT reset value for common clock distributed RAM and Shift Register based FIFOs for asynchronous reset (RST).



**Figure C-2: DOUT Reset Value for Asynchronous Reset (RST) for Common Clock Distributed/Shift RAM Based FIFO**

Figure C-3 shows the DOUT reset value for Virtex-6 FPGA common clock Built-in FIFO with Embedded register for asynchronous reset (RST).



**Figure C-3: DOUT Reset Value for Common Clock Built-in FIFO**

Figure C-4 shows the DOUT reset value for independent clock block RAM based FIFOs (RD\_RST).

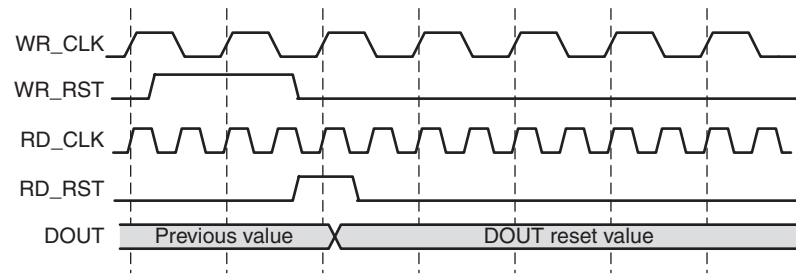


Figure C-4: DOUT Reset Value for Independent Clock Block RAM Based FIFO

Figure C-5 shows the DOUT reset value for independent clock distributed RAM based FIFOs (RD\_RST).

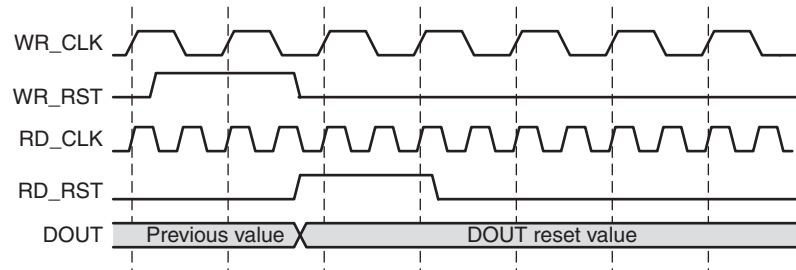


Figure C-5: DOUT Reset Value for Independent Clock Distributed RAM Based FIFO