APPM 5600 — HOMEWORK # 5

- 1. (15 points) Consider the problem of solving Ax = b where A is a nonsingular matrix. Determine an upper bound for the condition number of solving for x when there is a pertubation in b.
- 2. (15 points) Consider solving $\mathbf{A}\boldsymbol{x} = \boldsymbol{b}$ where $\mathbf{A} = \frac{1}{2}\begin{bmatrix} 1 & 1 \\ 1 + 10^{-10} & 1 10^{-10} \end{bmatrix}$ and $\boldsymbol{b} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$. The exact solution is $\boldsymbol{x} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and the inverse of \mathbf{A} is $\begin{bmatrix} 1 10^{10} & 10^{10} \\ 1 + 10^{10} & -10^{10} \end{bmatrix}$. In this problem we will investigate a perturbation in \boldsymbol{b} of $\begin{bmatrix} \Delta b_1 \\ \Delta b_2 \end{bmatrix}$ and the numerical effects of the condition number.
 - (a) Find an exact formula for the change in the solution between the exact problem and the perturbed problem Δx .
 - (b) What is the condition number of A?
 - (c) Let Δb_1 and Δb_2 be of magnitude 10^{-5} . What is the relative error in the solution? How does the number of accurate digits match with the condition number of A?
- 3. (30 points) Let $A \in \mathbb{R}^{n \times n}$ be a tridiagonal matrix where the diagonal entries are given by a_j for j = 1, ..., n, the lower diagonal entries are b_j for j = 2, ..., n and the upper diagonal entries are c_j for j = 1, ..., n 1.
 - (a) (10 points) For n=3, derive the LU factorization of the matrix A.
 - (b) (10 points) What is the extension of the LU factorization for general n?
 - (c) (10 points) Theorem 8.2 in Atkinson states that Gaussian Elimination applied to a tridiagonal matrix satisfying certain diagonal-dominance conditions does not require pivoting. What is the operation count (give an exact formula) when applying Gaussian Elimination to a tridiagonal system without pivoting? You must explain how you derive the operation count.
- 4. (15 points) Consider the linear system

$$6x + 2y + 2z = -2$$
$$2x + 2/3y + 1/3z = 1$$
$$x + 2y - z = 0$$

- (a) (3 points) Verify that (x, y, z) = (2.6, -3.8, -5) is the exact solution.
- (b) (5 points) Using 4 digit floating point arithmetic with rounding, solve the system via Gaussian elimination without pivoting.

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- (c) (5 points) Repart part (a) with partial pivoting.
- (d) (2 points) Which method is more accurate? i.e. stable.

(Remember to do the rounding to 4 significant digits as the machine would.)

5. (25 points) Consider the system Ax = b where

$$\mathsf{A} = \begin{bmatrix} 4 & -1 & 0 & -1 & 0 & 0 \\ -1 & 4 & -1 & 0 & -1 & 0 \\ 0 & -1 & 4 & -1 & 0 & -1 \\ -1 & 0 & -1 & 4 & -1 & 0 \\ 0 & -1 & 0 & -1 & 4 & -1 \\ 0 & 0 & -1 & 0 & -1 & 4 \end{bmatrix} \quad \text{and } \boldsymbol{b} = \begin{bmatrix} 2 \\ 1 \\ 2 \\ 2 \\ 1 \\ 2 \end{bmatrix}.$$

Use the ones vector as x_0 . (i.e. $x_0 = [1 \ 1 \ 1 \ 1 \ 1]^T$)

- (a) (5 points) Use Gauss-Jacobi iteration to approximate the solution to this problem with $\epsilon = 1e 7$.
- (b) (5 points) Use Gauss-Siedel iteration to approximate the solution to this problem with $\epsilon = 1e 7$.
- (c) (5 points) Use SOR iteration with $\omega = 1.6735$ to approximate the solution to this problem with $\epsilon = 1e 7$.
- (d) (2 points) Which method converges faster? Do you expect this to always be true?
- (e) (5 points) Set $c = \rho(B)$ (spectral radius). Use the following to error estimate to derive error bounds for the last computed approximations with all methods.

$$\|\boldsymbol{x}_{k+1} - \boldsymbol{x}\| \le \frac{c}{1-c} \|\boldsymbol{x}_{k+1} - \boldsymbol{x}_k\|$$

(f) (3 points) What happens if you change the parameter ω for SOR?