Impact of Systematic Measurement Error on Inference: Sensitivity Analysis Using Beliefs*

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Abstract

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1 Introduction

2 Theory

Suppose we have an observed variable $\mathbf{x}$ with elements x_i, where $i = 1, \ldots, n$. It is believed that this variable has some systematic measurement error for one of the reasons described above. Denote the true but unknown values of $\mathbf{x}$ with $\mathbf{t}$. We suspect that variable $\mathbf{w}$ systematically influences how close the elements x_i are to t_i. We call $\mathbf{w}$ the "corrupting variable". The relationship between $\mathbf{w}$, $\mathbf{x}$ and $\mathbf{t}$ is unknowable, but researchers can formulate beliefs about it. In this section, we present a hierarchical model approach that allows researchers to assess what their conclusions about the substantive inference they are interested in should be, give the beliefs they hold about how $\mathbf{w}$ corrupts the true values $\mathbf{t}$ to produce the observed variable $\mathbf{x}$. Both $\mathbf{x}/\mathbf{t}$ and $\mathbf{w}$ can be continuous or non-continuous. For each of the four possible combinations a somewhat different approach is necessary. We discuss them in turn.

2.1 Both Corrupting and True/Observed Variable are Continuous

Suppose $x_i \in \mathbb{R}$ is an element of $\mathbf{x}$ and $t_i \in \mathbb{R}$ is an element of $\mathbf{t}$. We specify the following hierarchical model describing the relationship between w_i, t_i, and x_i:

$$\begin{aligned} t_i &= x_i \cdot m_i \\ m_i &= \alpha_0 + \textstyle\sum_{j=1}^{J} \alpha_k w_i^j \\ \alpha_0 &\overset{\text{iid}}{\sim} F_0 \\ &\vdots \\ \alpha_K &\overset{\text{iid}}{\sim} F_K \end{aligned} \tag{1}$$

The term m_i is a constant with which the observed value x_i is multiplied to give the true value t_i. If $m_i = 1$ then x_i measures t_i correctly, if $m_i < 1$ then x_i is larger than t_i and if $m_i > 1$ then x_i is smaller than t_i.

The value of m_i depends on w_i and the relationship is modeled through a polynomial of order j where α_0 is the intercept and α_1 is the first-order coefficient of w_i on m_i and so on. The intercept and coefficients are draws from independent and identically distributed random variables with density $F_1, \dots F_k$. It is through these distributions that the researcher quantifies her beliefs how w_i influences the difference between t_i and x_i. In the most simple case they are just constants – but this is only appropriate if the researcher is absolutely sure about the data generating process. More appropriately, they are standard distributions such as the Normal or more complex mixture distributions. We describe prior elicitation in more detail in section 4.

2.2 True/Observed Variable is Continuous, Corrupting Variable is Non-Continuous

Now suppose x_i is still continuous but w_i is non-continuous (nominal or ordinal) with L categories. In this case we specify the following hierarchical model describing the relationship between w_i, t_i, and x_i:

$$\begin{aligned} t_i &= x_i \cdot m_i \\ m_i &= \textstyle\sum_{l=1}^{L} \alpha_l \mathbb{I}_{w_i = l} \\ \alpha_1 &\overset{\text{iid}}{\sim} F_1 \\ &\vdots \\ \alpha_L &\overset{\text{iid}}{\sim} F_L \end{aligned} \tag{2}$$

The term m_i, is still a constant with which the observed value x_i is multiplied to give the true value t_i. The value of m_i depends on which of the L categories w_i is. There is an α_l, which is an i.i.d. draw from a distribution F_l, for each of the L categories ($\mathbb{I}$ is an indicator function that take the value of unity if the condition specified is fulfilled and zero otherwise). In essence, the researcher specifies her beliefs about how $\mathbf{w}$ influences the difference between $\mathbf{t}$ and $\mathbf{x}$ for each category separately.

$$\begin{array}{c} \\ x_i = 1 \\ x_i = 2 \\ \vdots \\ x_i = k \end{array} \begin{bmatrix} t_i = 1 & t_i = 2 & \dots & t_i = k \\ p_{11} & p_{12} & \dots & p_{1k} \\ p_{21} & p_{22} & \dots & p_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ p_{k1} & p_{k2} & \dots & p_{kk} \end{bmatrix}$$

Figure 1: Probabilities for each level of observed value (x_i)and true value (t_i)

2.3 True/Observed Variable is Non-Continuous, Corrupting Variable is Continuous

When dealing with how a continuous confounding variable effects a categorical response, we need to look at odds ratios. If a categorical variable can take on k possible values, we are interested in the k probabilities that the true value is one of those values, given the observed value. Further, we have a continuous variable, w_1 that impats these probabilities. To determine the effect of the confounding variable, we enumerate certain prior beliefs about the relative odds of each possible true value, and use a logit transformation to fit a curve:

$$log \frac{Pr(\text{True Category is i}|x_i, w_i)}{Pr(\text{True Category is j}|x_i, w_i)} = a_0 + \sum_{j=1}^{J} a_j \cdot w_i^j \tag{3}$$

Fitting this curve will give estimated probabilities for each value of x_i, w_i, and allow us to use a multinomial distribution to correct for perceived measurement error.

2.4 Both Corrupting and True/Observed Variable are Non-Continuous

In the case of a categorical variable, given the observed value x_i, which can take on k values, we are interested in the true value t_i, which also has k values. There is a given joint probability for each possible level of observed and true value which for a given $x_i = x, t_i = t$ we call p_{xt}.

Once we observe $x_i = x$, and given the vector of probabilities $(p_{x1}, p_{x2}...p_{xk}) \equiv \Delta(p_x)$ we can estimate t_i using the following hierarchical model:

$$t_i|\Delta(p_x) \sim Multinomial(\Delta(p_x), 1) \tag{4}$$

$$\Delta p_x | w_i, \alpha \sim Dirichlet(\alpha) \tag{5}$$

We determine the values of $\Delta(p_x)$ by choosing a prior where α is a vector of k values $(a_0, a_1 \ldots a_{k-1})$ based on prior beliefs about the likelihood of observing certain values of the variable of interest given the true value. This can be done by elicitation of values for the expected values of $\Delta(p_x)$, as well as the overall level of uncertainty about these beliefs. This must be done for each level of the observed value.

This covers the likelihood of incorrect data conditional on the values of the observed data, but there is also a possibility that the error in the data is conditioned on a different categorical variable w_i. In that case, we enumerate the multinomial, dirichlet hierarchical distribution for each value of w_i based on beliefs about the likelihood and direction of error at each level of the corrupting variable.

3 Simulation Study

In this section we evaluate the performance of the belief-based sensitivity analysis using Monte Carlo studies. The data generating process for the n observations is:

$$y_i = \beta_1 x_{1i} + \beta_2 x_{2i} + \beta_3 x_{3i} + \varepsilon_i \tag{6}$$

where $\varepsilon_i \overset{\text{iid}}{\sim} N(0, 1)$. The first two independent variables are continuous and the third one has three categories (we assume for now that they are ordered). They are drawn from a multivariate normal distribution with varying covariance structure Σ. The non-continuous variable is generated by dividing the draws from the multivariate Normal into terciles. We set $\beta_1 = \beta_2 = \beta_3 = 1$.

4 Empirical Examples

5 Discussion