

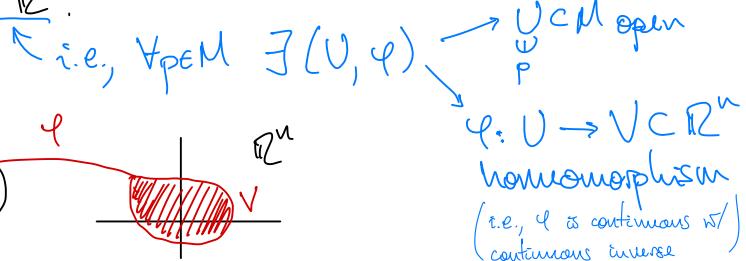
# LECTURE 1

Sep 5<sup>th</sup>, 2024

## INTRODUCTION

### TOPOLOGICAL MANIFOLDS

Def: (Topological Manifolds) A real  $n$ -dimensional topological manifold is a Hausdorff, 2<sup>nd</sup> countable topological space that is locally homeomorphic to  $\mathbb{R}^n$ .



Such  $(U, \varphi)$  is called a coordinate chart around  $p$  b/c the "standard fcts"  $x^1, \dots, x^n: \mathbb{R}^n \rightarrow \mathbb{R}$  define "coordinates".

Ex:  $\emptyset, \mathbb{R}^n$

Ex: Any open subset of  $\mathbb{R}^n$  or any another top. manifold.

$\text{Mat}(n, \mathbb{R}) := \{n \times n \text{ matrices w/ real entries}\} \simeq \mathbb{R}^{n^2}$ .

$\cup$

$\text{GL}(n, \mathbb{R}) = \{X \in \text{Mat}(n, \mathbb{R}) : \det X \neq 0\}$

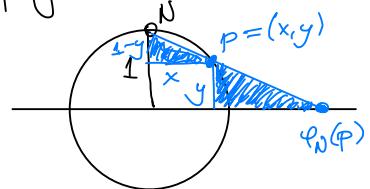
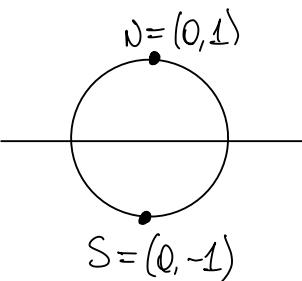
polynomial in the entries of  $X$   
i.e.,  $\det^{-1}(\mathbb{R}^n \setminus \{0\})$  is open  
open

Ex: Check  $S^1 = \{(x,y) \in \mathbb{R}^2 : x^2 + y^2 = 1\} \subset \mathbb{R}^2$ .

Define an atlas for  $S^1$  via stereographic projection

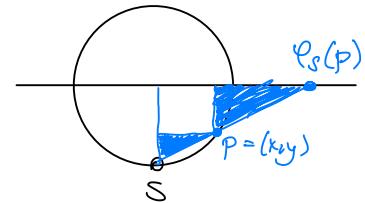
$$S^1 \supset U_N := S^1 \setminus \{N\}$$

open



$$S^1 \supset U_S := S^1 \setminus \{S\}$$

open



Homomorphisms:

(stereographic projection)

$$\begin{cases} \varphi_N: U_N \rightarrow \mathbb{R}, \quad \varphi_N(x, y) = \frac{x}{1-y} \\ \varphi_S: U_S \rightarrow \mathbb{R}, \quad \varphi_S(x, y) = \frac{x}{1+y} \end{cases}$$

Ex: Cartesian products: If  $M^n, N^m$  are manifolds, then  $M \times N$  (in the product top.) is a manifold as well.

$$\{(U_\alpha, \varphi_\alpha)\} \rightarrow \text{Atlas for } M$$

$$\{(V_\beta, \psi_\beta)\} \rightarrow \text{Atlas for } N$$

Result: manifold of dim  $n+m$

$$\Rightarrow \{(U_\alpha \times V_\beta, \varphi_\alpha \times \psi_\beta)\}$$

$$(\varphi_\alpha \times \psi_\beta)(p, q) = (\varphi_\alpha(p), \psi_\beta(q))$$

$$\mathbb{R}^n \times \mathbb{R}^m$$

Ex:  $T^n := \underbrace{S^1 \times \dots \times S^1}_{n \text{ times}}$

$$\begin{array}{c} \rightarrow \\ \rightarrow \\ T^2 \end{array}$$

Ex:  $S^n = \{x \in \mathbb{R}^{n+1} : \|x\|^2 = 1\}$ .

$$\sum_{i=0}^n x_i^2 = \|x\|^2$$

Atlas:  $\{(U_N, \varphi_N), (U_S, \varphi_S)\}$

$$N := (1, 0, \dots, 0)$$
$$S := (-1, 0, \dots, 0)$$

$$U_N := S^n \setminus \{N\}$$

$$U_S := S^n \setminus \{S\}$$

$$\varphi_N: U_N \rightarrow \mathbb{R}^n$$

$$\varphi_S: U_S \rightarrow \mathbb{R}^n$$

$$\varphi_N(x) = \frac{(x^1, \dots, x^n)}{1 - x^0}$$

$$\varphi_S(x) = \frac{(x^1, \dots, x^n)}{1 + x^0}$$

stereographic  
proj.

Obs: If  $M^n, N^n$  are  $n$ -mflds then  $M \sqcup N$  is an  $n$ -mfld.

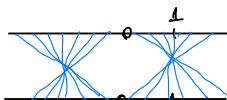
Ex: (Why Hausdorff?) Consider

$$R =: R_1 \supset R_1^* := R_1 \setminus \{0\}$$

$$R =: R_2 \supset R_2^* := R_2 \setminus \{0\}$$

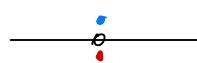
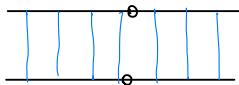
Glue  $R_1$  to  $R_2$  along gluing region  $R_1^*, R_2^*$ . To do this, we need a homeomorphism  $R_1^* \rightarrow R_2^*$ .

Option 1: use  $R_1^* \xrightarrow{\varphi} R_2^*$   
 $t \mapsto t^{-1}$



Then  $R_1 \sqcup R_2 / R^* \ni x \sim \varphi(x) \in R_2^* = S^1$ .

Option 2: Use  $R_1^* \xrightarrow{\varphi} R_2^*$ . Then  $R_1 \sqcup R_2 /_{\substack{x \sim \varphi(x) \\ \cap \\ R_1^* \cap R_2^*}} = B$



Line with 2 origins

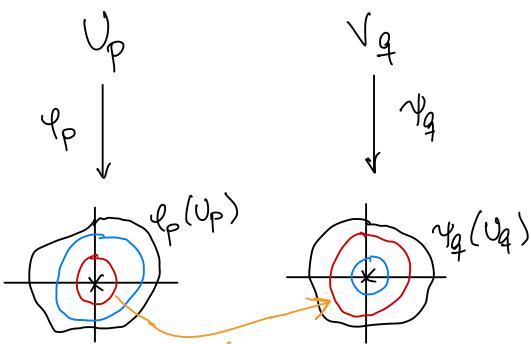
PROBLEM: Is b.c. homeom to Euclidean space  
but has this exotic behavior that can be problematic.

WARNING: When building manifolds via gluing, really need to pay attention to whether the Hausdorff condition is satisfied (b/c it is not inherited by quotient topology) !

CONNECTED SUM:  $M^n, N^n$  manifolds  
 $p \downarrow \psi_q \downarrow q$

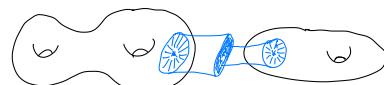


Charts:  $(U_p, \varphi_p)$  and  $(V_q, \psi_q)$   
s.t.  $\varphi_p(p) = 0$  and  $\psi_q(q) = 0$ .



$$\phi(x) := \frac{z\varepsilon^2}{\|x\|^2} x$$

$$M \# N := \frac{(M \setminus \overline{\varphi^{-1}(B_\varepsilon)}) \sqcup (N \setminus \overline{\psi^{-1}(B_\varepsilon)})}{x \sim \psi^{-1}(\phi(\varphi(x))) \quad \forall x \in \varphi^{-1}(B_{2\varepsilon})}$$



Choose balls of radius  $2\varepsilon$  and annulus of radius  $\varepsilon$ .

Define

# LECTURE 2

## PROJECTIVE SPACES, ETC.

Sep 6th, 2024

REMARK: Topological manifolds are objects in the category  $\text{TOP}$ . The morphisms  $X \rightarrow Y$  in  $\text{TOP}$  are continuous maps.

## Isomorphisms in $\text{TOP}$ :

$X \xrightarrow{f} Y$      $f, g$  are morphisms s.t.  $fg = 1_Y$  and  $gf = 1_X$ .  
 $\xleftarrow{g}$      $f, g$  are called homomorphisms.

(actually, TOP is a subcategory of topological spaces)

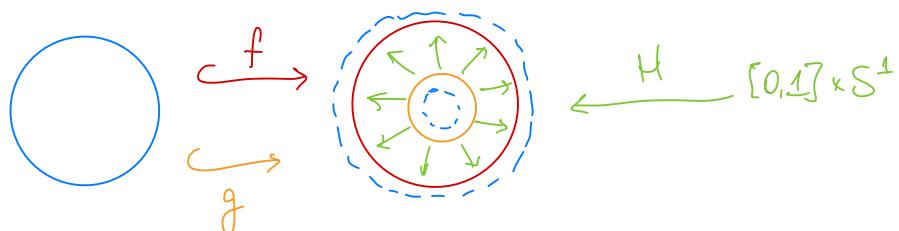
Feature of top-spaces: In top-spaces, two continuous maps may be related (equiv. relation) by a homotopy; i.e.:

$X \xrightarrow{f} Y$      $f, g$  are homotopic if we can continuously  
interpolate them; i.e.:

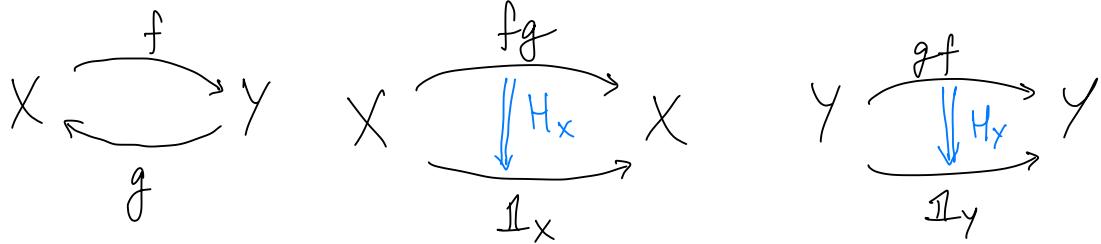
$$\exists H: [0,1] \times X \longrightarrow Y \quad \text{continuous s.t.} \quad H_0(x) = f(x)$$

$$(t, x) \mapsto H_t(x) \quad H_1(x) = g(x)$$

e.g.: circle embedded in an annulus



Def: Top. spaces  $X, Y$  are HOMOTOPY EQUIVALENT when :



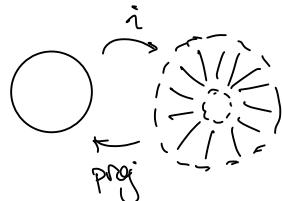
$$H_X: [0,1] \times X \rightarrow X$$

$$H_Y: [0,1] \times Y \rightarrow Y$$

i.e.,  $fg$  is homotopic to  $\text{Id}_X$  and  $(\text{not equal to})$   
 $gf$  is homotopic to  $\text{Id}_Y$  ( $\text{identity but very close to}$ )

i.e.,  $f$  and  $g$  are inverses to each other up to homotopy.

Ex:



are homotopy equivalent but not homeomorphic.

(Top. Poincaré)

CONJECTURE: Is it possible for an  $n$ -dim top. mfld  $X$  to be

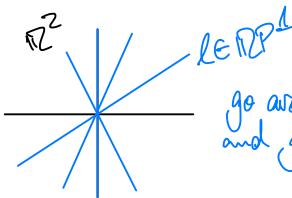
- Homotopy equiv. to  $S^n$
- not homeo. to it ?

A: No.

- $n \geq 5$  Smale 60-70
- $n = 4$  Freedman 80-90
- $n = 3$  Hamilton-Perelman 00s
- $n = 1, 2$  conse<sup>q</sup>. of classification thus

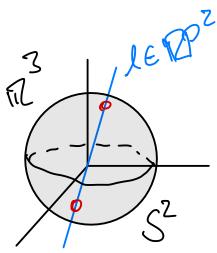
## \* PROJECTIVE SPACES:

Over  $\mathbb{R}$ :  $\mathbb{RP}^n = \text{space of lines through } 0 \text{ in } \mathbb{R}^{n+1}$



go around  $180^\circ$   
and go back to  $l$

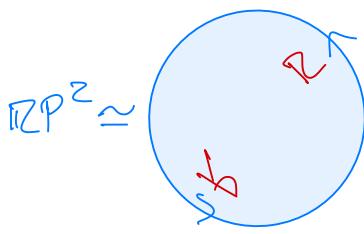
$$\mathbb{RP}^1 = [0, \pi] /_{0 \sim \pi} \cong S^1$$



$\mathbb{RP}^2 \times S^2$  (the antipodal pt. in the sphere  
produces the same line through 0)

$$\mathbb{RP}^2 \cong S^2 /_{x \sim -x}$$

Another way of doing this  
is just considering the upper  
hemisphere of  $S^2$ . Then  
the problematic pts. are on  
the bdy of the hemisphere



Identify the antipodal pts on the  
bdy of this disk (which represents the upper)  
hemisphere

Obs: because we never get the  
"same  $\mathbb{R}$ " going around, we say  $\mathbb{RP}^2$  is non-orientable.

Def: ( $\mathbb{RP}^n$ ) Start with  $X = \mathbb{R}^{n+1} \setminus \{0\}$ . Define an  
equivalence relation

$$X \ni x \sim y \in X \iff \exists \lambda \in \mathbb{R} \text{ st. } \lambda x = y \quad (\text{i.e., pts. are equiv if they are colinear})$$

Then, define

$$\mathbb{RP}^n := X / \sim \text{ with the quotient topology.}$$

Claim:  $\mathbb{R}P^n$  is an  $n$ -dim. manifold.

Pf: Let  $\pi: X = \mathbb{R}^{n+1} \setminus \{0\} \rightarrow \mathbb{R}P^n$  be the projection map.  
Want to show that  $\pi$  is open (i.e.,  $\bigcup_{\text{open}} U \subset X \Rightarrow \pi(U) \subset \mathbb{R}P^n$ ),

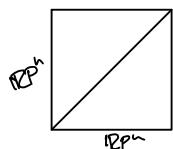
This is true b/c

$\bigcup_{\text{open}} U \subset X \Rightarrow \pi^{-1}(\pi(U))$  is open. Why? B/c  $\pi^{-1}(\pi(U)) = \bigcup_{x \in U} \pi^{-1}(x)$

Thus:  $\mathbb{R}P^n$  is 2nd countable.

NTS:  $\mathbb{R}P^n$  is Hausdorff.  $\Leftrightarrow$  Diagonal in  $\mathbb{R}P^n \times \mathbb{R}P^n$  is closed

$$\Delta_{\mathbb{R}P^n} := \{(x, x) : x \in \mathbb{R}P^n\}$$



But since we have  $\pi: X \times X \rightarrow \mathbb{R}P^n \times \mathbb{R}P^n$

$$\{(x, y) \in X \times X : x \sim y\} =: \tilde{\Gamma}_\sim = \text{preimage of } \Delta_{\mathbb{R}P^n}$$

To show  $\mathbb{R}P^n \times \mathbb{R}P^n \setminus \Delta_{\mathbb{R}P^n}$  is open, we can just use that  $\pi$  is open and that

$$\mathbb{R}P^n \times \mathbb{R}P^n \setminus \Delta_{\mathbb{R}P^n} = (\pi \times \pi)(X \times X \setminus \tilde{\Gamma}_\sim)$$

So,

$\mathbb{R}P^n$  is Hausdorff  $\Leftrightarrow \tilde{\Gamma}_\sim \subset X \times X$  is closed.

How to show  $\tilde{\Gamma}_\sim$  is closed? Express  $\tilde{\Gamma}_\sim$  as the zero set/preimage of a pt. of a continuous map.

Have  $\mathbb{R}^{n+1} \setminus \{0\} \ni x \sim y \in \mathbb{R}^{n+1} \setminus \{0\}$ . Need to define a map that detects whether  $x$  and  $y$

$$(x^i)_{i=0}^n$$

$$(y^i)_{i=0}^n$$

are lin. dependent or not.

$$\mathbb{P} = M^{-1}(0)$$

where  $M(x, y) = x^n y$ .

Atlas for  $\mathbb{R}P^n$ :  $U_i := \pi(\tilde{V}_i)$ , where

$$\tilde{V}_i := \left\{ (x^0, \dots, x^n) \in \mathbb{R}^{n+1} \setminus \{0\} : x_i \neq 0 \right\}$$

$\leftarrow n+1$  hyperplane complements

$\leftarrow$  deleting the  $i$ -th hyperplane.

$$\varphi_i: U_i \rightarrow \mathbb{R}^n$$

$$[(x^0, \dots, \overset{\text{at } i}{x^i}, \dots, x^n)] \longmapsto \left( \frac{x^0}{x^i}, \frac{x^1}{x^i}, \dots, \widehat{\frac{x^i}{x^i}}, \dots, \frac{x^n}{x^i} \right)$$

- $\varphi_i$  well-defined ✓

- $\varphi_i$  continuous ✓

- $\varphi_i$  invertible ✓ / inverse  $(y^1, \dots, y^n) \longmapsto [(y^1, \dots, \overset{\text{at } i}{1}, \dots, y^n)]$

is the  
 inverse  
 of  $\varphi_i$   
 and clearly  
 continuous

Upshot:  $\{(U_0, \varphi_0), \dots, (U_n, \varphi_n)\}$  is an atlas for  $\mathbb{R}P^n$  since

$$\mathbb{R}P^n = \bigcup_{i=0}^n U_i$$

Same for  $\mathbb{C}P^n$ ... but complex

# LECTURE 3

## FLAGS & GLINES

Sep 12th, 2024

$S^n, \mathbb{RP}^n, \mathbb{CP}^n, \text{Gr}_k(\mathbb{V}) = \text{space of } k\text{-dim subspaces}$   
 $\text{of } n\text{-dim vec. space}$

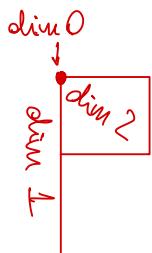
$\text{Gr}_1(\mathbb{R}^{n+1}) \quad \text{Gr}_1(\mathbb{C}^{n+1})$



"FLAG MANIFOLDS"  $\rightarrow \text{Fl}_{\mathbb{R}}(n) = \text{space of "full" flags in } \mathbb{R}^n$



$\left\{ \{0\} \subset V_1 \subset V_2 \subset \dots \subset V_{n-1} \subset \mathbb{R}^n \right\}$   
 $\dim V_i = i$



Ex:  $\text{Fl}(3) = \left\{ \{0\} \subset V_1 \subset V_2 \subset \mathbb{R}^3 \right\}$ .

forget  $V_1 \subset \mathbb{R}^3$

$$\text{Gr}_2(\mathbb{R}^3) \simeq \mathbb{RP}^2$$

forget  $V_2$

$$\mathbb{RP}^2$$

inclusion  $V_2 \xrightarrow{\cong} \mathbb{R}^3$

Fix  $V_2 \subset \mathbb{R}^3$  and consider  $\pi_1^{-1}(V_2)$

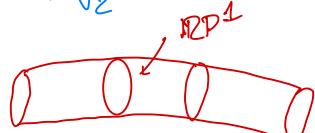
Annihilator( $V_2$ )

$$= K_{V_2}$$

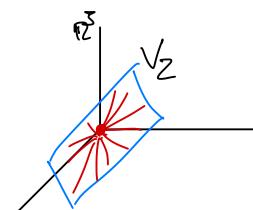
kernel of  $a^*$

Have:  $\pi_1^{-1}(V_2) = \left\{ V_1 \text{ 1-dim subspace of } V_2 \right\}$

$$\simeq \mathbb{RP}^1$$



$\text{Fl}(3) \simeq 8 \text{ dim}$



  $\Rightarrow \text{Fl}(3)$  is a bundle of  $\text{RP}^1$  over base  $\text{RP}^2$  with  $\pi_1$  as the bundle projection.

Ex: (FIBER BUNDLES) Let  $F$  be a top. space (the FIBER). A fiber bundle with fiber  $F$  is  $(E, \pi, B)$  where

- $E$  (TOTAL SPACE) and  $B$  (BASE SPACE) are top. spaces
- $\pi: E \rightarrow B$  continuous surjective (BUNDLE PROJECTION MAP)

SUCH THAT:  $\forall p \in B \exists$  a neighborhood  $U \ni p$  and a homeo.

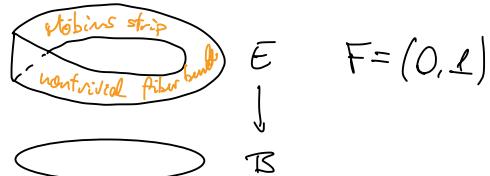
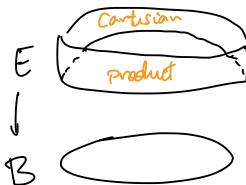
$$\Phi: \pi^{-1}(U) \longrightarrow U \times F \quad (\text{LOCAL TRIVIALITY})$$


  
 that commutes with  $\pi$   $\downarrow \pi_1$   
 the projections.

i.e., locally, the bundle  
 is a Cartesian product.  
 We just don't want it to  
 be globally trivial...

Claim: If  $F, B$  are top. spaces then so is  $E$ .

Rmk: There are many fiber bundles with the same base & fiber



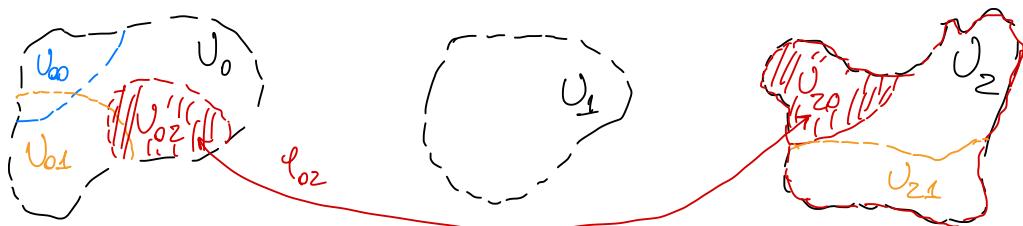
# Gluing Construction of Manifolds

Begin with: a countable collection of open sets  $\mathcal{U} = \{U_i\}_{i \in I}$

Idea: Quotient  $\bigsqcup_{i \in I} U_i$  by an equiv. relation to get

$$M = \bigsqcup_{i \in I} U_i / \sim$$

Gluing:  $\forall i$  choose finitely many opens  $U_{ij} \subset U_i$



and gluing maps  $\varphi_{ij}: U_{ij} \xrightarrow{\sim} U_{j|i}$  (homeos.).

Gluing maps define an equivalence relation  $\sim$ :

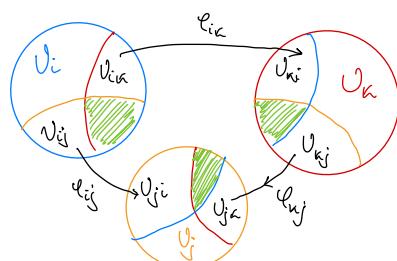
$$(i) \quad \varphi_{ij} \circ \varphi_{ji} = \text{id}_{U_{ji}} \quad \begin{matrix} U_{ji} & \xleftarrow{\varphi_{ij}} & U_{ij} & \xleftarrow{\varphi_{ji}} & U_{ji} \\ & & \swarrow \text{id}_{U_{ij}} & & \end{matrix}$$

(reflexivity)

$$(ii) \quad \varphi_{ij}(U_{ij} \cap U_{ik}) = U_{ji} \cap U_{jk} \quad \forall k$$

(transitivity)

$$\varphi_{ki} \Big|_{U_{ki} \cap U_{kj}} \circ \varphi_{jk} \Big|_{U_{ji} \cap U_{jk}} \circ \varphi_{ij} \Big|_{U_{ik} \cap U_{ij}} = \text{id}_{U_{ij} \cap U_{jk}}$$



This defines an equiv. relation on  $\bigsqcup_{i \in I} U_i$

$$\Rightarrow M = \bigsqcup_{i \in I} U_i / \sim$$

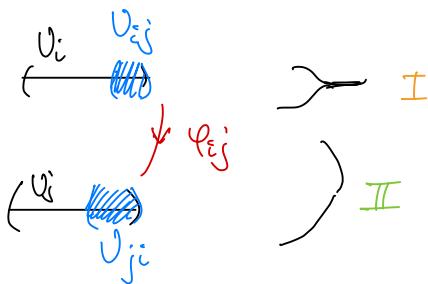
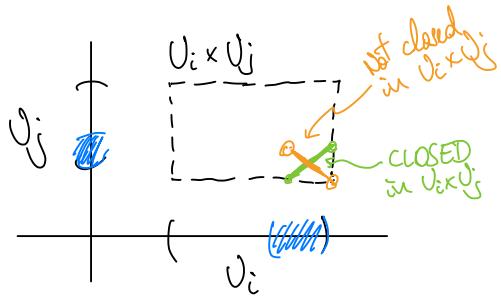
• top space  
 • 2nd countable  
 • locally homeo to  $\mathbb{R}^n$

& Hausdorff under an additional assumption:

(iii) Graph of  $\varphi_{ij} = \{(x, \varphi_{ij}(x)) : x \in U_{ij}\} \subset U_{ij} \times U_{ji}$

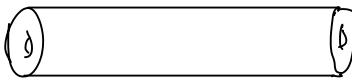
needs to be CLOSED in  $U_i \times U_j$ .

$$U_i \times U_j$$



Ex: (MAPPING TORUS)  $M$  top. manifold and  $\phi: M \rightarrow M$

First:  $M \times \mathbb{R}$



$$\mathbb{Z} \wr t \sim t+1 \xrightarrow{\pi} S^1 = \mathbb{R}/\sim$$

Quotient:  $M_\phi := M \times \mathbb{R} / \sim$ , where  $(x, t) \sim (\phi(x), t+1)$

Upshot: The resulting mapping torus  $M_\phi$  is a fiber bundle over  $S^1$  with fiber  $M$ .

# LECTURE 4

## DIFFERENTIAL STRUCTURES

Sup 13<sup>th</sup>, 2024

We say  $f: U \subset V \rightarrow W$ ,  $V, W$  finite dim vector spaces, is differentiable at  $p \in U$  if there exists a linear map

$Df(p): V \rightarrow W$  that approximates  $f$  at  $p$ :

$$\lim_{\substack{x \rightarrow 0 \\ x \neq 0}} \frac{|f(p+x) - f(p) - Df(p)(x)|}{|x|} = 0.$$

$Df(p)$  uniquely characterized by this limit.

$$Df(p) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} \Big|_p & \cdots & \frac{\partial f_1}{\partial x_n} \Big|_p \\ \vdots & & \vdots \\ \frac{\partial f_m}{\partial x_1} \Big|_p & \cdots & \frac{\partial f_m}{\partial x_n} \Big|_p \end{pmatrix};$$

Def:  $f$  is continuously differentiable if

$$Df: U \rightarrow \text{Hom}(V, W)$$

is continuous. In this case,  $f \in C^1(U, W)$ .

Note:  $C^\infty(U, W) := \bigcap_n C^n(U, W)$

Def: A smooth manifold is a topological manifold equipped with an equivalence class of smooth atlases.

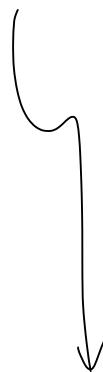
Def: An atlas  $\mathcal{A} = \{(U_i, \varphi_i)\}$  for a topological manifold is smooth when all transition functions

$$\varphi_j \circ \varphi_i^{-1} : \varphi_i(U_{ij}) \longrightarrow \varphi_j(U_{ij})$$

are smooth maps; i.e., lie in  $C^\infty(\varphi_i(U_{ij}), \mathbb{R}^n)$ .

Two atlases  $\mathcal{A}, \mathcal{A}'$  are equivalent if  $\mathcal{A} \cup \mathcal{A}'$  is itself a smooth atlas.

Rmk: these transition maps only need to be smooth on an open subset  $\varphi_i(U_i \cap U_j) \subset \mathbb{R}^n$  (not necessarily the whole  $\mathbb{R}^n$ ).



# LECTURE 5

Sep 19th, 2024

Category: collection of objects  $\mathcal{C}$  and arrows  $A$ . There are two natural maps source and target telling us what is the beginning and end of each arrow:

$$A \xleftarrow{\quad s \quad} \mathcal{C} \xrightarrow{\quad t \quad}$$

Also, there must be an identity  $1_X$ :

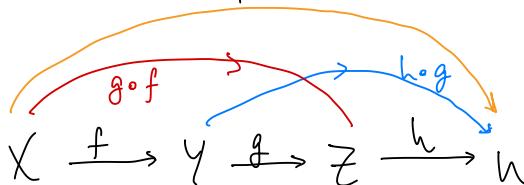
$$X \xrightarrow{\quad} 1_X$$

Plus, an associative composition of arrows.

If  $X, Y$  are objects, define

$A \supset \text{Hom}(X, Y) = \text{morphisms (arrows) from } X \text{ to } Y$ .

Associative composition:  $\text{Hom}(X, Y) \times \text{Hom}(Y, Z) \rightarrow \text{Hom}(X, Z)$ .



$$(h \circ g) \circ f = h \circ (g \circ f)$$

Ex: (i)  $\mathcal{C} = \text{sets}$ ,  $A = \text{maps of sets}$

(ii)  $\mathcal{C} = \text{groups}$ ,  $A = \text{group homomorphisms}$

(iii)  $\mathcal{C} = \text{Vec-space over } F$ ,  $A = \text{linear maps}$

(iv)  $\mathcal{C} = \text{top. spaces}$ ,  $A = \text{continuous maps}$

\* MORPHISMS BETWEEN  $C^\infty$  MANIFOLDS: If  $M, N$  are  $C^\infty$  manifolds, a map  $f: M \rightarrow N$  is smooth when it is continuous and  $C^\infty$  in charts; i.e., for any charts  $(U, \varphi)$  and  $(V, \psi)$  on  $M, N$  in the smooth atlas, we require

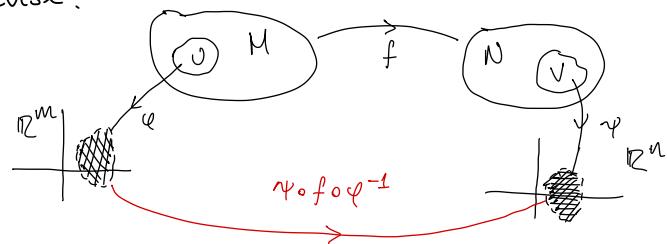
$$f_U^V := \psi \circ f \circ \varphi^{-1}: \varphi(U) \subset \mathbb{R}^m \longrightarrow \psi(V) \subset \mathbb{R}^n$$

to be  $C^\infty$  in the usual sense.

e.g.: for 1<sup>st</sup> derivative,

$$f_U^V = \left( (f_U^V)^1, \dots, (f_U^V)^n \right)$$

$$\left[ \frac{\partial}{\partial x^i} (f_U^V)^j \right]_{n \times m} \text{ matrix.}$$



- The set of  $C^\infty$  maps  $M \rightarrow N$  is denoted

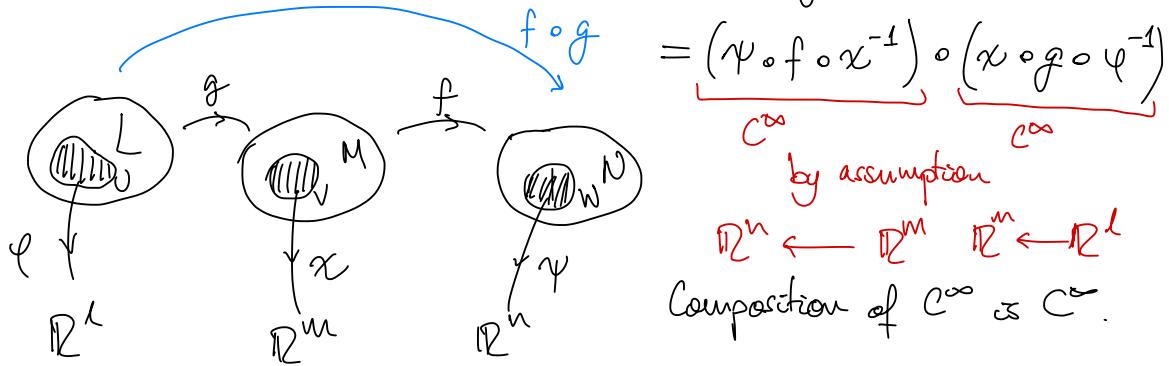
$$\text{Hom}_{C^\infty}(M, N) = C^\infty(N, M).$$

WARNING:  $(\text{Id}_M)_U^V = \psi \circ \text{Id}_M \circ \varphi^{-1}$  need not be  $\text{Id}_{\mathbb{R}^n}$ . It's only going to look like  $\text{Id}_{\mathbb{R}^n}$  if we use  $(\text{Id}_M)_U^V$ .

- Associative composition: we already have a continuous associative composition inherited from the topological aspect of  $C^\infty$ -manifolds. We only need to check that this composition is smooth:

Prop: If  $L \xrightarrow{g} M$  and  $M \xrightarrow{f} N$  are  $C^\infty$  maps, then  $f \circ g$  is also  $C^\infty$ .

Pf: Check on the charts:  $(f \circ g)^N = \psi \circ (f \circ g) \circ \varphi^{-1}$



KEY: Chain rule for differentiation of maps  $\mathbb{R}^l \rightarrow \mathbb{R}^m$  i.e.,

$$D_p(\psi f g \varphi^{-1}) = D_{\overset{n \times l \text{ matrix}}{x(g(\varphi^{-1}(p))}}} (\psi f x^{-1}) \underset{n \times m \text{ matrix}}{D_p(x g \varphi^{-1})} \underset{m \times l \text{ matrix}}{D_p(g \varphi^{-1})}$$

### ISOMORPHISMS in $C^\infty$ MANIFOLDS:

i.e., arrows  $f$  with inverses  $g$

$\xrightarrow{\text{Hom}}(X,Y)$

$$f \circ g = \text{Id}_Y$$

$\xrightarrow{\text{Hom}}(Y,X)$

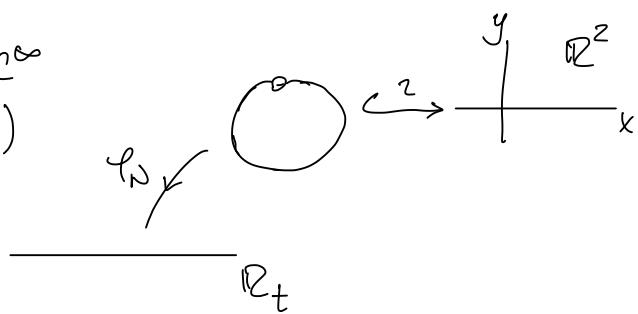
$$g \circ f = \text{Id}_X$$

Such smooth maps  $f$  w/ smooth inverse  $g$  are DIFFEOMORPHISMS

Ex:  $S^1 \hookrightarrow \mathbb{R}^2$  inclusion is smooth

i.e.,  $\varphi_N^{-1}: \mathbb{R} \rightarrow \mathbb{R}^2$  is  $C^\infty$

$$t \mapsto (x(t), y(t))$$



Ex:  $S^1 \times S^1 \xrightarrow{\text{inclusion}} \mathbb{R}^2 \times \mathbb{R}^2$  inclusion of  $T^2$  into  $\mathbb{R}^4$ .  
 $(z_1, z_2) \mapsto \left( \frac{z_1}{\sqrt{2}}, \frac{z_2}{\sqrt{2}} \right)$  so that it has length 1

$\Rightarrow S^1 \times S^1$  includes first through  $S^3$  and then it includes into  $\mathbb{R}^4$  via  $S^3 \hookrightarrow \mathbb{R}^4$ .

$$S^1 \times S^1 \xrightarrow{\quad} \mathbb{R}^4$$

$\hookdownarrow$

Cf: We defined a  $\varphi \in C^\infty(T^2, S^3)$

Pf: This involves 4 charts in domain  $T^2$  (products of charts of  $S^1$ )  
 2 charts in codomain  $S^3$

$\Rightarrow$  Check 8 components.



Ex: (Lie Group) Group  $G$  is a set w/ associative multiplication  $m: G \times G \rightarrow G$  and identity  $e \in G$ , and inversion  $i: G \rightarrow G$   
 $g \mapsto g^{-1}$

If we endow  $G$  with a  $C^\infty$  structure (i.e., an equivalence class of smooth atlases) and we require  $m \in C^\infty(G \times G, G)$  and  $i \in C^\infty(G, G)$   $\implies G$  is a Lie Group

E.g.: •  $(\mathbb{R}, +, 0, i(t) = -t)$  is a Lie group  $(x, y) \mapsto x+y$   $t \mapsto -t$   
 $\mathbb{R}^2 \xrightarrow{C^\infty} \mathbb{R}$

•  $(\mathbb{R}^k, +, 0, -1)$  is a Lie group

•  $\mathbb{R}/\mathbb{Z} = S^1$  is a Lie group  $z_1 = e^{i\theta_1}, z_2 = e^{i\theta_2} \rightsquigarrow z_1 \cdot z_2 = e^{i(\theta_1 + \theta_2)}$

- $\text{GL}(n, \mathbb{R}) \subset \mathbb{R}^{n^2}$  is a Lie group. Matrix multiplication is smooth b/c it is just a polynomial in the entries of the matrices.

- If  $G$  is a Lie group and  $g \in G$  is fixed, we can define natural  $C^\infty$  maps  $R_g: G \rightarrow G$  and  $L_g: G \rightarrow G$
- $\uparrow$   
 $x \mapsto xg$        $x \mapsto gx$   
 since multiplication is  $C^\infty$

Inverses:  $R_{g^{-1}}$  and  $L_{g^{-1}}$  (both  $C^\infty$ )

$\Rightarrow R_g, L_g$  are DIFFEOMORPHISMS.

**⚠ WARNING:** Do not confuse DIFFEO with EQUIV. OF ATLAS.

E.g.:

$$\frac{(\mathbb{R}, \alpha)}{(\mathbb{R}, \beta)}$$

$\alpha(x) = x$        $\beta(x) = x^3$   
 $\mathbb{R}$                    $\mathbb{R}$

$\alpha$  is a valid  $C^\infty$  atlas on  $\mathbb{R}$   
 $\beta$  is also a valid  $C^\infty$  atlas on  $\mathbb{R}$

$\left. \begin{array}{l} \alpha, \beta \text{ represent two } C^\infty \\ \text{structures on } \mathbb{R}. \end{array} \right\}$

Is  $[\alpha] = [\beta]$ ? No ←

Check:  $\beta \alpha^{-1}: x \mapsto x^3$   $C^\infty$  ✓

$\alpha \beta^{-1} : t \mapsto t^{1/3}$  is not  $C^\infty$

$\Rightarrow (\mathbb{R}, \alpha)$  and  $(\mathbb{R}, \beta)$  are two different  $C^\infty$  manifolds.

But this is still acceptable b/c they are ISOMORPHIC:

$$(\mathbb{R}, \alpha) \xrightarrow{\lambda} (\mathbb{R}, \beta)$$
$$\lambda^{-1}$$

Define  $\lambda$  as:  $\lambda(x) = x^{1/3}$  ← doesn't look smooth but it is

$$(\mathbb{R}, x) \xrightarrow{\lambda} (\mathbb{R}, y)$$

smooth with this structure  
and is invertible.

$$\begin{array}{ccc} & \downarrow \alpha & \\ \mathbb{R} & \xrightarrow{\lambda} & x \\ & \downarrow \beta & \\ & \mathbb{R} & y^3 \end{array}$$

Obs:  $S^7$  has 28 non-isomorphic  $C^\infty$  structures löl (Kervaire-Milnor)

$\mathbb{R}^4$  has uncountably many non-iso.  $C^\infty$

$\mathbb{R}^n$   $n \neq 4$  has only 1

# LECTURE 6

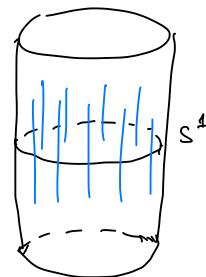
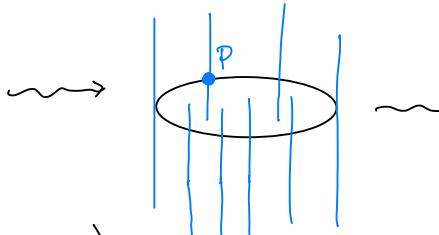
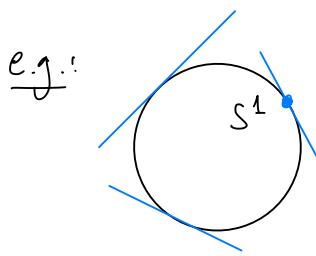
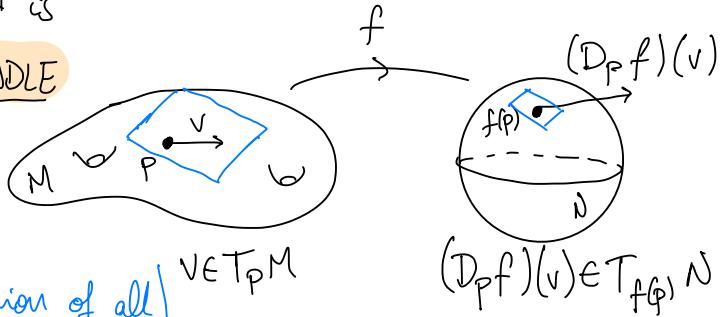
## DERIVATIVES

Sep 20th, 2024

To define  $Df$ , the derivative of a  $C^\infty$  map  $f$ , we need to build the space where it is defined: the TANGENT BUNDLE

$$TM = \bigsqcup_{p \in M} T_p M$$

(union of all tangent spaces)



$$TS^1 \simeq S^1 \times \mathbb{R} \text{ (cylinder)}$$

2d manif

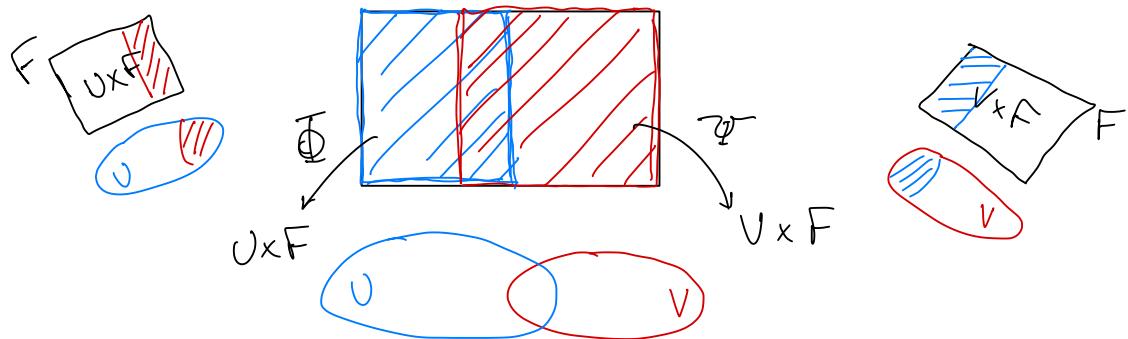
REMARK: In general  $TM \neq M \times \mathbb{R}^n$  but it is a  $2n$ -dim. manif. Moreover,  $TM$  has the following structure

(Bundle Projection)  $\pi: TM \rightarrow M$   
 $(p, v) \mapsto p$

$TM \xrightarrow{\pi} M$  is a FIBER BUNDLE with fiber  $\mathbb{R}^n$  (often nontrivial)

REMARK: Fiber bundles have charts

$$U, V \subset B \quad \pi^{-1}(U) \xrightarrow[\sim]{\Phi} U \times F, \quad \pi^{-1}(V) \xrightarrow[\sim]{\Psi} V \times F$$



Transition map:  $\Psi \circ \Phi^{-1}: (U \cap V) \times F \longrightarrow (U \cap V) \times F$

is a family of homeomorphisms  $F \rightarrow F$  parametrized by  $U \cap V$ .

- If  $F = \mathbb{R}^n$  we can ask that  $\Psi \circ \Phi^{-1}$  respect the vec. space structure of the fiber, i.e., require

$$\Psi \circ \Phi^{-1}: U \cap V \longrightarrow GL(n, \mathbb{R}).$$

With this additional constraint, the fiber bundle is called a **VECTOR BUNDLE**.

GOAL: 1) Any  $C^\infty$  manifol M has a natural vector bundle

$$TM \xrightarrow{\pi} M.$$

2) Any smooth map  $f: M \rightarrow N$  has natural **DERIVATIVE**  $Df$

$$(TM)^{2m} \xrightarrow{Df} (TN)^{2n}$$

which is a linear map  
of vector bundles.

$$\begin{array}{ccc} \pi_M & & \downarrow \pi_N \\ \downarrow & & \\ M^m & \xrightarrow{f} & N^n \end{array}$$

Obs: This association

$$M \xrightarrow{\quad} TM$$

$$f \downarrow \xrightarrow{\quad} \downarrow Df = Tf$$

$$N \xrightarrow{\quad} TN$$

Tangent functor

$$\text{Smooth Manifolds} \xrightarrow{T} \text{Smooth Vector Bundles}$$

Tangent Functor

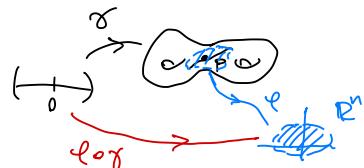
\* Construct the Tangent Bundle:

Def:  $T_p M$  = equivalence classes of paths through  $p$ .

Def: Let  $I \subset \mathbb{R}$  open interval containing 0. A PATH in  $M$  through  $p$  is

$$\gamma: I \rightarrow M \text{ smooth}$$

$$\gamma(0) = p$$



Def: Two paths are equivalent  $\gamma_1 \sim \gamma_2$  when they have the same velocity at zero. (in any fixed chart)  
i.e., in any chart  $(U, \varphi)$  about  $p$

$$\frac{d}{dt} \Big|_{t=0} (\varphi \circ \gamma: I \rightarrow \mathbb{R}^n) \in \mathbb{R}^n \quad ] \text{Velocity of } \gamma \text{ in chart } (U, \varphi)$$

Note: This definition is independent of chart.

$\implies T_p M$  is a vector space identified with  $\mathbb{R}^n$  by a chart

Changing coordinates  $\psi \circ \varphi^{-1}: \varphi(U \cap V) \rightarrow \psi(U \cap V)$  implies

$$D_{\varphi(p)}(\psi \circ \varphi^{-1}) \frac{d}{dt} \Big|_{t=0} (\varphi \circ \gamma) = D_{\psi(p)}(\psi \circ \varphi^{-1} \circ \varphi \circ \gamma)$$

*velocity relative to  $\varphi$*

$\mathbb{R}^n \leftarrow \mathbb{R}^n \leftarrow \mathbb{R}^n$

*Chain rule for  
vector valued fcts.*

$= \frac{d}{dt} \Big|_{t=0} (\psi^{-1} \gamma)$

*velocity relative to  $\psi$*

*Jacobian linear map*

SUMMARY: Def: Let  $(U, \varphi), (V, \psi)$  smooth charts on  $M$  containing  $p \in M$

$$u \in T_{\varphi(p)} \varphi(U) = \varphi(U) \times \mathbb{R}^n$$

$$v \in T_{\psi(p)} \psi(V) = \psi(V) \times \mathbb{R}^n$$

$$((U, \varphi), u) \sim ((V, \psi), v)$$

$$\text{when } D_{\varphi(p)}(\psi \circ \varphi^{-1})(u) = v$$

The space of equivalence classes is  $T_p M$

Def:  $TM \stackrel{\text{set}}{=} \bigsqcup_{p \in M} T_p M$  equipped with  
 (TM as a set)  $\pi: TM \longrightarrow M$

$$(p, [(U, \varphi), u]) \longmapsto p$$

Vector Bundle

Prop:  $TM$  is equipped with a smooth (mfld) structure.

Pf: Any chart  $(U, \varphi)$  for  $M$  defines a bijection  
 (TM as a  $C^\infty$  mfld)  $T\varphi(U) := \varphi(U) \times \mathbb{R}^n \longrightarrow \pi^{-1}(U)$ .

In this way, each chart  $(U, \varphi)$  endows  $\pi^{-1}(U)$  with topology and  
 chart into  $\mathbb{R}^n \times \mathbb{R}^n$

$$\pi^{-1}(U) \xrightarrow{\Phi} \mathbb{R}^{2n}$$

Given another chart  $(V, \psi)$  on  $M$ , if lifts to

$$\pi^{-1}(V) \xrightarrow{\Psi} \mathbb{R}^{2n}$$

Transition:

$$\begin{aligned} \Psi \circ \Phi^{-1}: \varphi(U \cap V) \times \mathbb{R}^n &\longrightarrow \psi(U \cap V) \times \mathbb{R}^n \\ (p, u) &\longmapsto (\underbrace{\psi \varphi^{-1}(p)}_{C^\infty \text{ by assumption}}, \underbrace{D_p(\psi \varphi^{-1})(u)}_{\text{smooth}}) \end{aligned}$$

TM inherits:

- Topology:  $W \subset TM$  open  $\iff W \cap \pi^{-1}(U)$  open  $\forall U$  chart on  $M$

- Hausdorff: separate  $p, q \in TM$ 
  - if  $p, q$  lie in same chart ✓
  - if  $p, q$  don't lie in same chart,  
separate by charts ✓

\* MORE USEFUL CONSTRUCTION OF  $\underline{TM}$  ALONG w/  $\underline{M}$ :

Choose a countable atlas  $\{(U_i, \varphi_i)\}_{i \in I}^{\Rightarrow A}$  for  $M^n$ . Then

$$TM = \bigsqcup_{i \in I} (\varphi_i(U_i) \times \mathbb{R}^n) / \begin{array}{l} (x, u) \sim (y, v) \\ \Leftrightarrow y = \varphi_j \varphi_i^{-1}(x) \text{ &} \\ v = D_x(\varphi_j \varphi_i^{-1})(u) \end{array}$$

Can verify that the general gluing construction holds.

- While this depends on the atlas, if another atlas  $\{\tilde{U}_i, \tilde{\varphi}_i\}_{i \in I}^{\text{smoothly equivalent}}$  is used, then there is a canonical diffeomorphism between the tangent bundles coming from the different atlases:

$$(\varphi_j^{-1} \circ (\varphi_i^{-1})^{-1}, D(\varphi_j^{-1} \circ (\varphi_i^{-1})^{-1}))$$

# LECTURE 7

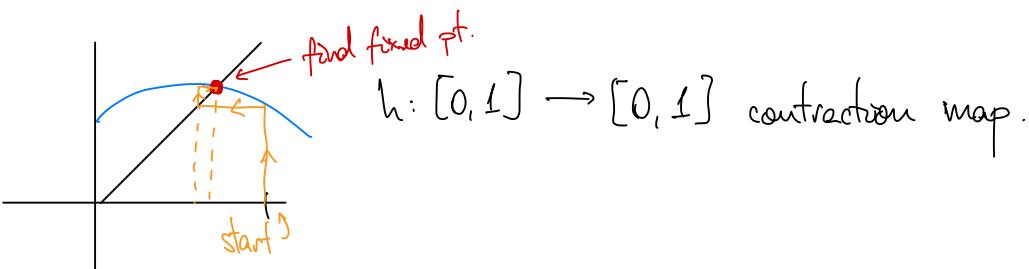
## INVERSE FUNCTION & CONSTANT RANK THEOREMS

\* INVERSE FUNCTION THEOREM:

Thm: (IFT) If  $f: (M, p) \rightarrow (N, q)$  is a smooth map of  $n$ -manifolds such that  $Df(p): T_p M \rightarrow T_q N$  is invertible, then  $f$  has a local smooth inverse.

i.e.,  $\exists$  open neighborhoods  $U \ni p$  and  $V \ni q$  and a smooth  $g: U \rightarrow V$  s.t.  $fg = \text{Id}_V$  and  $gf = \text{Id}_U$

Pf: Step 0 (BANACH FIXED PT THM) If  $h: X \rightarrow X$  is s.t.  $d(h(x), h(y)) \leq \frac{1}{2} d(x, y)$  and  $X$  is complete, then  $\exists!$  fixed pt.



Setup: Reduce to case  $M = \text{open in } \mathbb{R}^n$ ,  $N = \mathbb{R}^n$ ,  $p = q = 0$   
also WLOG  $Df(0) = \text{Id}: \mathbb{R}^n \rightarrow \mathbb{R}^n$  (can replace  $f$  by  $Df(0)^{-1} \circ f$ ).

Step 1: (DEFINE INVERSE MAP) For each  $y$  suff. small <sup>close to zero as above.</sup> we want  $x$  s.t.  $f(x)=y$  to be the fixed pt of a contraction map.

$$f(x) = \underset{\text{linear}}{\downarrow} x + \underset{\substack{\text{nonlinear} \\ \text{part of } f}}{\curvearrowleft} \kappa(x) \Rightarrow x + \kappa(x) = y \text{ as a fixed pt.}$$

$$y - \kappa(x) = x$$

for any  $y$ , defined map

$$h_y : x \longmapsto y - \kappa(x)$$

fixed pt of this map would be an inverse; i.e.,  $x$  s.t.  $f(x)=y$ .

- Check  $h$  is a contraction map:

$$Dh_y(0) = 0 \Rightarrow |Dh_y| \leq \frac{1}{2} \text{ in some ball } B_r(0).$$

$$\text{MVT} \Rightarrow |h_y(x) - h_y(x')| \leq \frac{1}{2}|x - x'| \text{ for } x, x' \in B_r(0).$$

- $h_y$  acts on a complete vector space :

$$\begin{aligned} |h_y(x)| &= |h_y(x) - h_y(0) + h_y(0)| \leq |h_y(x) - h_y(0)| + |h_y(0)| \\ &\leq \frac{1}{2}|x| + |y|. \end{aligned}$$

So, as long as  $y$  is chosen in  $B_{\frac{r}{2}}(0)$ ,  $\overline{B_r(0)} \xrightarrow{h_y} \overline{B_{\frac{r}{2}}(0)}$ .

BFPT  $\Rightarrow \exists!$  fixed pt. of  $h_y$  in  $\overline{B_r(0)}$  for each  $y \in B_{\frac{r}{2}}(0)$   
so we define:

$$g : B_{\frac{r}{2}}(0) \longrightarrow \overline{B_r(0)}$$

$$y \longmapsto \text{fixed pt. of } h_y$$

Inverse

Upshot:  $f \circ g = \text{Id}_{B_{\frac{r}{2}}(0)} \rightarrow \text{since } h_y(g(y)) = g(y)$

$$g \circ f = \text{Id}_{f^{-1}(B_{\frac{r}{2}}(0))} \cap \overline{B_r(0)} \rightarrow \text{since fixed pt. in } \overline{B_r(0)} \text{ is unique}$$

but  $f^{-1}(B_{\frac{r}{2}}(0)) \cap \overline{B_r(0)}$  may not be open in  $M$ ! So, we need to shrink  $B_{\frac{r}{2}}(0)$ .

### Step 2: (CONTINUITY OF INVERSE)

$$\begin{aligned} |g(y) - g(y')| &= |h_y(g(y)) - h_{y'}(g(y'))| \\ &\leq |y - y'| + |\kappa(g(y)) - \kappa(g(y'))| \\ &\leq |y - y'| + \frac{1}{2} |g(y) - g(y')| \end{aligned}$$

$$\Rightarrow |g(y) - g(y')| \leq 2|y - y'| \Rightarrow g \text{ is continuous.}$$

### Step 3: ( $f$ IS LOCAL HOMEO.)

$g(0) = 0$  and continuous  $\Rightarrow$  lt  $U \subset B_r(0)$  nbhd of zero and lt  $V = g^{-1}(0)$ .

then  $\begin{cases} f \circ g = \text{Id}_V \text{ as before} \\ g \circ f = \text{Id}_U \text{ by uniqueness of fixed pt.} \end{cases}$

Step 4: ( $g$  IS DIFFERENTIABLE AT  $y$ ) If  $g$  is smooth,  $Dg(y)$  must be  $Df(g(y))^{-1}$  by chain rule. Now  $Df$  will be invertible on some nbhd of  $0$   $\Rightarrow$  for this to make sense we should have chosen  $r$  small enough s.t.  $Df(x)$  invertible for  $x \in B_r(0)$ .

Step 5: ( $g$  IS  $C^\infty$ )  $Dg(y) = Df(g(y))^{-1}$  since inversion is  $C^\infty$   $g$  has as many derivatives as  $f$  does.

---

\* CONSTANT RANK THEOREM

Thm: (CRT) If  $f: M^m \rightarrow N^n$  is smooth and  $Df$  has constant rank  $r$  in a neighborhood of  $p \in M$ , then  $\exists$  charts  $(U, \varphi) \ni p$  and  $(V, \psi) \ni f(p)$  s.t.

$$\psi \circ f \circ \varphi^{-1}: (x_1, \dots, x_m) \mapsto (x_1, \dots, x_r, 0, \dots, 0)$$

# LECTURE 8

## EMBEDDINGS

Oct 2<sup>nd</sup>, 2024

### \* REGULAR (or EMBEDDED) SUBMANIFOLDS

Def: Let  $M^n$  be a manifold. An embedded (or regular) submanifold of codimension  $\kappa$  is a subspace  $S \subset M$  such that every  $p \in S$  is contained in a chart  $(U, \varphi)$  of the ambient manifold  $M$  such that

$$\varphi(U \cap S) = \left\{ x \in \varphi(U) : \underbrace{x_{n-\kappa+1} = \dots = x_n = 0}_{\text{last } \kappa \text{ coordinates}} \right\}.$$

Rmk: (i) We call charts above "adapted" to  $S$ .

(ii) If the codimension  $\kappa = 1$ , we say  $S$  is a hypersurface.

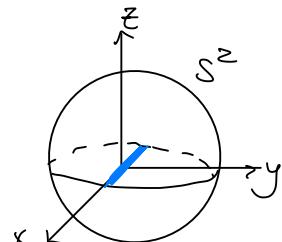
Ex:  $M = S^2$ ,  $S := \{(x, y, z) \in S^2 : y = 0\} \cong S^1$

$$U := \{z > 0\} \subset S^2, \quad \varphi(x, y, z) = (x, y)$$

$$\Rightarrow \varphi(U) = B_1(0) \text{ and } \varphi(U \cap S) = \{(x, y) \in B_1(0) : y = 0\}$$

Using  $\{z < 0\}$  or  $x$  instead of  $z$ , we can cover  $S$  by adapted charts.

Alternative: stereographic projection.



Ex:  $M = \mathbb{R}P^n$  and  $S = \{[x_0, \dots, x_n] \in \mathbb{R}P^n : x_n = 0\} \cong \mathbb{R}P^{n-1}$ .

$$U_i = \{x_i \neq 0\} \subset \mathbb{R}P^n, \quad \varphi_i([x_0, \dots, x_n]) = \frac{1}{x_i} (x_1, \dots, \hat{x}_i, \dots, x_n)$$

$$\Rightarrow \varphi(U_i) = \mathbb{R}^n \text{ and } \varphi(U_i \cap S) = \{x \in \mathbb{R}^n : x_n = 0\},$$

Repeat for all  $i=0, \dots, n$  and thus get adapted chart covering  $S$ .

Prop: Let  $S^{n-k} \subset M^n$  be an embedded submfld. The adapted charts  $(U, \varphi)$  induce charts for  $S$  given by

$$U \cap S \xrightarrow[\varphi]{\simeq} \varphi(U) \cap (\mathbb{R}^{n-k} \times \{0\}) \xrightarrow{\simeq} \begin{matrix} \text{open set} \\ \text{in } \mathbb{R}^{n-k} \end{matrix} \\ (x_1, \dots, x_n) \mapsto (x_1, \dots, x_{n-k}).$$

These give  $S$  a mfld structure.

### \* FIBERS & IMAGES OF MAPS

Prop: If  $f: M \rightarrow N$  is a smooth map and  $Df(x): T_x M \rightarrow T_{f(x)} N$  has constant rank  $k$  on  $M$ , then  $f^{-1}(q) \subset M$  is an embedded submanifold of codim  $k$  ( $\forall q \in f(M)$ ).

Pf: Given  $x \in f^{-1}(q)$ , by the Constant Rank Thm, there exists charts  $(U, \varphi)$  around  $x$  and  $(V, \psi)$  around  $q$  such that

(i)  $f(U) \subset V$  and  $\varphi(x) = 0$  and  $\psi(q) = 0$

Can assume  
they are centered

(ii)  $\psi \circ f \circ \varphi^{-1}: \varphi(U) \rightarrow \psi(V)$  is of the form

$$(x_1, \dots, x_m) \mapsto (x_1, \dots, x_k, 0, \dots, 0)$$

Then  $\varphi(U \cap f^{-1}(q)) = \{x \in \varphi(U) : x_1 = \dots = x_k = 0\}$

0 is the <sup>↑</sup> image of q under  $\varphi$

So, up to permutations of coordinates

(which is a diffeo of  $\mathbb{R}^m$ ...),  $(U, \varphi)$  is an adapted chart.

Ex:  $f: \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $(x_1, \dots, x_n) \mapsto \sum_i x_i^2 = q = r^2$

Then  $Df(x) = (2x_1, \dots, 2x_n)$  has rank 1 everywhere except at zero; i.e.,  $\forall x \in \mathbb{R}^n \setminus \{0\} = \mathbb{R}^n \setminus f^{-1}(0)$ .

So,  $f|_{\mathbb{R}^n \setminus f^{-1}(0)}$  has constant rank 1

$\Rightarrow f^{-1}(q) \simeq S^{n-1}(\sqrt{q})$  is an embedded submfld  $\forall q > 0$ .

Dif: Let  $f: M \rightarrow N$  be a smooth map. A point  $x \in M$  is

- regular point (of  $f$ ) if  $Df(x)$  is surjective (i.e., if  $\text{rank } Df(x) = \dim N$ )
- critical point (of  $f$ ) otherwise

If all points in the fiber  $f^{-1}(q)$  are regular, then

we say  $q$  is a regular value. Otherwise, we say  $q$  is a critical value.

FACT: If  $f: M \rightarrow N$  is a smooth map and  $q \in f(M)$  is a regular value, then  $f^{-1}(q) \subset M$  is an embedded submanifold of  $\text{codim} = \dim N$ .

PF: B/c of the fact that

$$\text{rank } Df(x) = k \Rightarrow \text{rank } Df(y) \geq k \quad \forall y \text{ in an open neighborhood of } x$$

So,  $\cup := \{x \in M : Df(x) \text{ is surjective}\}$  is open in  $M$  around  $f^{-1}(q)$ . So we can apply the prop. from two pages ago.  $\square$



Def: A smooth map  $f: M \rightarrow N$  with constant rank is called

- a smooth SUBMERSION iff  $Df(x)$  is surjective  $\forall x \in M$   
i.e., iff  $\text{rank } Df(x) = \dim N$  at all points  $x \in M$ .
- a smooth IMMERSION iff  $Df(x)$  is injective  $\forall x \in M$   
i.e., iff  $\text{rank } Df(x) = \dim M$  at all points  $x \in M$ .
- a smooth EMBEDDING iff  $f$  is an injective immersion and it is a homeomorphism onto  $f(M)$  (w.r.t. to the subspace topology of  $f(M) \subset N$ ).

**Prop:** If  $f: M \rightarrow N$  is a smooth embedding, then  $f(M) \subset N$  is an embedded submanifold.

**Pf:** Let  $x \in M$ . By the Constant Rank Thm, there exists charts

$$x \in (U, \varphi) \text{ and } (V, \psi) \ni f(x)$$

s.t.

$$(i) \quad f(U) \subset V \text{ and } \psi \circ f \circ \varphi^{-1}(y_1, \dots, y_m) = (y_1, \dots, y_m, 0, \dots, 0)$$

$$(ii) \quad \psi(f(U)) = \{y \in \psi(V) : y_{m+1} = \dots = y_n = 0\}$$

$$\psi(f(\varphi^{-1}(\psi(U))))$$

Since  $f: M \xrightarrow{\cong} N$  is a homeo.,  $f(U) = f(M) \cap W$ , where  $W \subset N$  open. Set  $V' := W \cap V$ . Then  $(V', \psi|_{V'})$  is a chart around  $f(x)$  s.t.

$$\psi(V' \cap f(M)) = \psi(f(U))$$

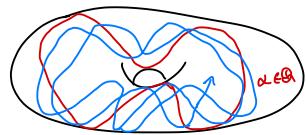
$$= \{y \in \psi(V') : y_{m+1} = \dots = y_n = 0\}$$

**EXAMPLES:** (for what can fail if  $f: M \rightarrow f(M)$  is not homeo.)



"figure eight"  $\subset \mathbb{R}^2$ ,  $f(t) := (\sin 2t, t)$

$f$  is an injective immersion but not a homeo  $M \rightarrow f(M)$



$f: \mathbb{R} \rightarrow S^1 \times S^1$ ,  $f(t) = (e^{it}, e^{i\alpha t})$   
with  $\alpha \in \mathbb{R}$  fixed.

$\alpha \in \mathbb{Q} \Rightarrow f(\mathbb{R})$  is an embedded  $S^1$

$\alpha \notin \mathbb{Q} \Rightarrow f(\mathbb{R})$  is dense and not open in  $S^1 \times S^1$ , so  
it is not an embedded submfld.

## LECTURE 9

at 4<sup>th</sup>, 2024

## COBORDISMS

Facts: (1) If  $S \subset N$  is an embedded submfld, then  $\exists!$  smooth structure on  $S$  making the inclusion map  $S \hookrightarrow N$  an emb.

(2) If  $f: M \rightarrow N$  is an embedding, then  $f(M) =: S \subset N$  is an embedded submfld and  $f: M \rightarrow f(M) \subset N$  is a diffeo.  
w.r.t. the smooth structure on  $f(M)$  as in (1).

————— //

\* MANIFOLDS w/ BOUNDARY

Def: A mfld w/ boundary is the same as a mfld but that is locally modelled on  $H^m := \{(x_1, \dots, x_m) \in \mathbb{R}^m : x_m \geq 0\}$ .

$\Rightarrow$  Can make sense of a smooth atlas here

$H^m$

Duf: Let  $M$  be a smooth mfld w/ boundary, then

- $x \in \text{int } M$  if  $\varphi(x)_m > 0$  for some (or equiv. any) chart  $(U, \varphi)$ .  
 $m$ -th coordinate
- $x \in \partial M$  if  $\varphi(x)_m = 0$  for some (or equiv. any) chart  $(U, \varphi)$ .

Prop: Charts for  $M^m$  restrict to charts for  $\partial M$  making  $\partial M$  an  $(m-1)$ -dimensional mfld w/out boundary.  $\partial^2 = 0$ .

Ex:  $M = \text{Möbius band}$ ,  $\partial M = S^1$ .



$S^1$  is a nontrivial fiber bundle

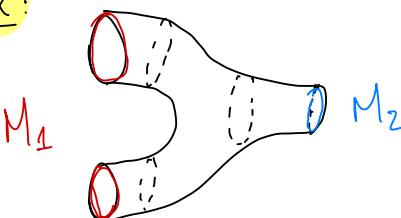
If it were, it would be  $S^1 \times [0, 1]$ .

But  $\partial(S^1 \times [0, 1]) = S^1 \sqcup S^1$  ↪ ↪ ↪  
 $\partial M = S^1$ .

\* COBORDISMS:

Duf: Compact  $n$ -mflds (without boundary)  $M_1$  and  $M_2$  are cobordant iff  $\exists$  a compact  $(n+1)$ -mfld  $N$  st.  $\partial N \cong M_1 \sqcup M_2$  essential

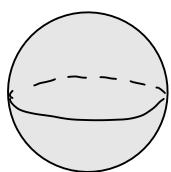
Ex:



$M_1$        $M_2$   
" "      " "  
 $S^1 \sqcup S^1$  and  $S^1$   
are cobordant.

Ex:  $M_1 := \partial B$

$M_2 := \emptyset$



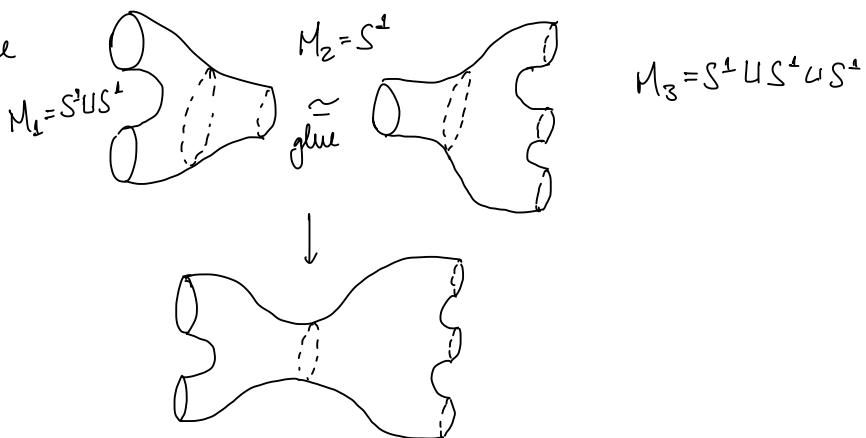
$\Rightarrow S^2$  and  $\emptyset$  are cobordant

We say  $S^2$  is NULL-COBORDANT

Prop: Cobordance is an equivalence relation.

Pf: • Reflexive ✓

• Transitive



NOTATION:  $\mathcal{Q}^n$  := cobordism classes of compact  $n$ -mfds.

Group STRUCTURE:  $[M_1] + [M_2] := [M_1 \sqcup M_2]$ .

Well-defined:  $\partial N_1 \simeq M_1 \sqcup M'_1$  and  $\partial N_2 \simeq M_2 \sqcup M'_2$ , thus take  $\partial(N_1 \sqcup N_2) = \partial N_1 \sqcup \partial N_2 \simeq (M_1 \sqcup M'_1) \sqcup (M_2 \sqcup M'_2)$   
 $\simeq (M_1 \sqcup M_2) \sqcup (M'_1 \sqcup M'_2)$ .

Prop:  $x + x = 0 \quad \forall x \in \Omega^n$ .

Pf:  $x = [M] \Rightarrow x + x = [\underbrace{M \sqcup M}_{\partial(M \times [0,1])}] = [\emptyset] = 0$

Note:  $\Omega^* := \bigoplus_{n \geq 0} \Omega^n$  becomes a graded ring with multiplication given by:  $[M_1] \cdot [M_2] = [M_1 \times M_2]$

Well-defined:  $\partial N_1 \cong M_1 \sqcup M'_1, \quad \partial N_2 \cong M_2 \sqcup M'_2$

$$[M_1 \times M_2] = [M'_1 \times M_2] \text{ since } \partial(N_1 \times M_2) = (\partial N_1) \times M_2$$

$$\text{Same for } [M'_1 \times M_2] = [M'_1 \times M_2] \simeq M_1 \times M_2 \sqcup M'_1 \times M_2$$

Commutative ring: b/c  $M_1 \times M_2 \cong M_2 \times M_1$

Unital: unit =  $[*]$  one-point space

Thm: (Rene Thom) The cobordism ring is a countably generated polynomial ring over  $\mathbb{F}_2$  with generators in every degree  $n \neq 2^k - 1, k \in \mathbb{N}$ .

$$\hookrightarrow \Omega^* = \mathbb{F}_2[x_2, x_4, \underset{\substack{\uparrow \\ \text{deg of generator}}}{x_5}, x_6, x_8, \dots]$$

↔ dimension

NOTE: (1)  $\mathbb{Q}^0 = \mathbb{Z}/2\mathbb{Z}$  consisting of  $0 = [\emptyset]$  and  $1 = [*]$ .

(2)  $\mathbb{Q}^1 = 0$  ← Classification of 1-dim compact manifolds w/out bdry ⇒ only have  $S^1$  which is the bdry of the disk ⇒ null-cobordant.

(3)  $\mathbb{Q}^2 = \mathbb{Z}/2\mathbb{Z} = \langle x_2 \rangle$ ,  $x_2 = [\mathbb{RP}^2]$ .

Rmk:  $[\Sigma] = 0$  ∀ Σ oriented surface.

Classification:



NOTE:  $\mathbb{Q}^4 = \{x_2^2, x_4, x_2^2 + x_4, 0\}$ .

$$x_2^2 + x_4 = [\mathbb{RP}^2 \times \mathbb{RP}^2 \sqcup \mathbb{RP}^4] = [\mathbb{RP}^2 \times \mathbb{RP}^2 \# \mathbb{RP}^4].$$

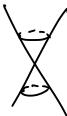
\* MAPS BETWEEN MANIFOLDS w/ BOUNDARY:

Prop: Let  $M$  be a manifold ( $\partial M = \emptyset$ ) and  $f: M \rightarrow \mathbb{R}$  smooth and  $a \leq b$  both regular values of  $f$ . Then  $f^{-1}([a, b])$  is a smooth  $n$ -manifold embedded in  $M$  and with boundary  $= f^{-1}(a) \sqcup f^{-1}(b)$ .

Ex:  $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ ,  $(x, y, z) \mapsto x^2 + y^2 - z^2$ . Apply proposition to find that  $f^{-1}([-1, 1])$  is a manifold with boundary given by  $f^{-1}(-1) \sqcup f^{-1}(1) = \{x^2 + y^2 = z^2 - 1\} \sqcup \{x^2 + y^2 = z^2 + 1\}$ .



Note  $f^{-1}(0) =$  singularity.



Q:  $[M_1 \sqcup M_2] = [M_1 \# M_2]$ .

Pf:  $M_1 \sqcup M_2 =$   $\stackrel{\text{prop.}}{=} \#$

## LECTURE 10

Oct 10<sup>th</sup>, 2024

Smooth maps  $f: M^m \rightarrow N^n$  are modeled on  $\mathbb{R}^m \xrightarrow{\text{linear}} \mathbb{R}^n$  if the rank  $Df$  is constant.

If it's not constant near  $p \in M$ , then we cannot classify the form of the maps  $\Rightarrow$  classification problem

Ex: (MORSE LEMMA) Let  $f: M \rightarrow \mathbb{R}$  be  $C^\infty$  s.t.  $\begin{cases} (i) Df(p) = 0 \\ (ii) \left[ \frac{\partial^2 f}{\partial x_i \partial x_j} \right] \text{ is nondegenerate at } p \end{cases}$

Then  $\exists$  coords  $(x^1, \dots, x^n)$  about  $p$  s.t.

$$f(x^1, \dots, x^n) = f(p) + \sum_{i=1}^k (x^i)^2 - \sum_{j=k+1}^n (x^j)^2.$$

$\begin{cases} (ii) \left[ \frac{\partial^2 f}{\partial x_i \partial x_j} \right] \text{ is nondegenerate at } p \text{ of signature } (k, n-k) \\ \uparrow \quad \# \text{ of } + \\ \# \text{ of } - \quad \text{in the Hessian} \end{cases}$

$\hookrightarrow$  Allows us to infer the behavior of a fct. at the nbhd of a point  $p$ .

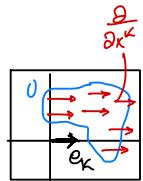
\* VECTOR FIELDS: A vec. field on some  $U \subset V$  ( $V$  is a  $\mathbb{R}$ -vec. space) is just  $X: U \rightarrow V$  vector valued fct.

- If we choose a basis  $(e_1, \dots, e_n)$  for  $V$ , it induces a dual basis  $(x^1, \dots, x^n)$  coord. syst. on  $U$ .

- Then we have constant vec. fields

$$\begin{array}{ccc} U & \longrightarrow & V \\ p & \longmapsto & e_k \end{array}$$

These constant vec. fields are denoted  $\frac{\partial}{\partial x^k}$



- Reason for notation: can identify  $\frac{\partial}{\partial x^k}$  with the directional derivative of functions.

$$\left\{ \begin{array}{l} \text{Vector fields} \\ \text{on } U \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} \text{Derivations} \\ \text{of } C^\infty(U, \mathbb{R}) \end{array} \right\}$$

Def: A derivation of an algebra  $A$  is a linear map  $D: A \rightarrow A$  st.  $D(ab) = (Da)b + aDb$  (Liebniz Rule)

- Giving: Under what conditions does

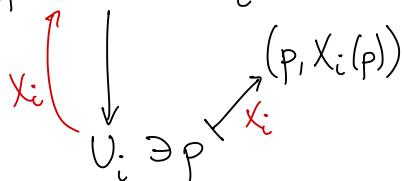
$$V = \sum_{i=1}^n v^i(x^1, \dots, x^n) \frac{\partial}{\partial x^i} \text{ glue to } W = \sum_{i=1}^n w^i(y^1, \dots, y^n) \frac{\partial}{\partial y^i}$$

$$\begin{array}{c} (x^1, \dots, x^n) \\ \downarrow \phi_{ij} \\ U_i \supset U_{ij} \end{array} \quad \begin{array}{c} (y^1, \dots, y^n) \\ \downarrow \phi_{ij} \\ U_j \supset U_{ij} \end{array} \quad \begin{array}{c} \mathbb{R}^n \supset U_i \\ \downarrow \phi_{ij} \\ U_{ij} \end{array} \quad \begin{array}{c} \mathbb{R}^n \supset U_j \\ \downarrow \phi_{ij} \\ U_{ij} \end{array} \quad \begin{array}{c} W = \sum_{i=1}^n w^i(y^1, \dots, y^n) \frac{\partial}{\partial y^i} \\ \text{using } \phi_{ij} \\ \text{change bases: } \frac{\partial}{\partial y^i} = \sum_j \frac{\partial x^j}{\partial y^i} \frac{\partial}{\partial x^j} \end{array}$$

$\Rightarrow$  Condition is that we can write:

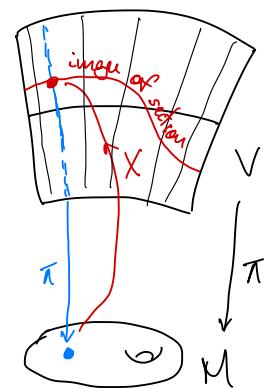
$$V^i(x^1, \dots, x^n) = \sum_{\kappa=1}^n W^\kappa(y^1(x^1, \dots, x^n), \dots, y^n(x^1, \dots, x^n)) \frac{\partial x^i}{\partial y^\kappa}(x^1, \dots, x^n)$$

Upshot: The vector field  $X_i: U_i \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$  is a "section" of  $TU_i = U_i \times \mathbb{R}^n$



Def: A section of a tangent bundle  $\pi: V \rightarrow M$  is a  $C^\infty$  map  $X: M \rightarrow V$  s.t.  $\pi \circ X = \text{Id}_M$ .

Section hits each fiber  
precisely at 1 point



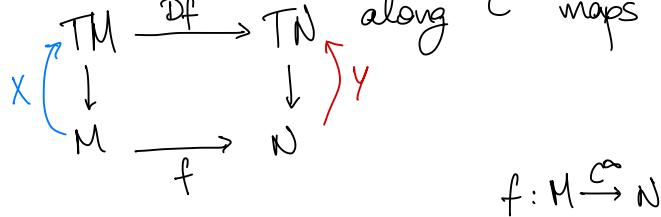
Thus: given vector fields  $X_i, X_j$  on  $U_i, U_j$ , these glue to a global section iff  $D(\phi_{ij})_{p \in U_{ij}}(X_i(p)) = X_j(\phi_{ij}(p))$

$$\begin{array}{ccccc} TU_i & \supset & TU_{ij} & \xrightarrow{\cong} & TU_{ji} \subset TU_j \\ \pi_i \downarrow & & \downarrow & & \downarrow \pi_j \\ U_i & \supset & U_{ij} & \xrightarrow{\cong} & U_{ji} \subset U_j \end{array}$$

A commutative diagram showing the gluing of local sections. At the top,  $TU_i$  contains  $TU_{ij}$ , which is isomorphic ( $\cong$ ) to  $TU_{ji}$  via the map  $(\phi_{ij}, D\phi_{ij})$ . Below,  $U_i$  contains  $U_{ij}$ , which is isomorphic ( $\cong$ ) to  $U_{ji}$  via the map  $\phi_{ij}$ . Red arrows indicate the inclusion  $X_i \rightarrow X_{ij}$  and  $X_{ij} \rightarrow X_j$ .

Def: A vector field on a  $C^\infty$  manifold  $M$  is a  $C^\infty$  section of  $TM$ .  
 The space of all vec. fields on  $M$  is  $\Gamma(TM) = \mathcal{X}(M)$

Annoying Remark: Vector fields may not be pushed or pulled  
 $\pi: TM \xrightarrow{Df} TN$  along  $C^\infty$  maps (unless  $f$  is invertible)



Def:  $X \in \mathcal{X}(M)$  is "f-related" to  $Y \in \mathcal{X}(N)$  when

$$Df \circ X = Y \circ f.$$

In the special case of  $f$  being a diffeomorphism, we can push and pull via

$$f_* X := Df \circ X \circ f^{-1}, \quad f^* Y := (Df)^{-1} \circ Y \circ f$$

Ex: (Vector field on  $S^1$ ) Take  $X_0 = \frac{\partial}{\partial x}$  const. vec field on  $U_0$

$$X_0 = \frac{\partial}{\partial x} \underset{\substack{\text{const.} \\ \text{vac field}}}{\longrightarrow} U_0 = R_x > R_{f_0}$$

$$\phi: x \mapsto x^{-1}$$

$$U_1 = \mathbb{R}_y > \mathbb{R}_{\neq 0} \quad \text{Gluing: } x \neq 0 \sim y \neq 0 \quad \text{iff } y = x^{-1}$$

$$\begin{aligned}\phi : x &\mapsto x^{-1} \\ D\phi : v &\mapsto \left[ \frac{\partial \phi}{\partial x} \right] v \\ &\quad \stackrel{!!}{=} [-x^{-2}] v\end{aligned}$$

By the gluing construction for vec fields above,

$$(\mathbb{D}\phi_{ij})_{p \in V_j}(x_i(p)) = x_j(\phi_{ij}(p)) \rightsquigarrow [-x^{-2}]_1 = x_1$$

$$X_0 = 1 \cdot \frac{\partial}{\partial x}$$

$$\Rightarrow X_1 = -x^{-2} \frac{\partial}{\partial y} = -y^2 \frac{\partial}{\partial y}$$

Since smooth, we can extend it to all of  $U_1$  (could be non-smooth and then we only have it on the gluing region and not on all of  $S^1$ )

## LECTURE 11

Oct 11, 2024

## \* Flow of A Vector Field

$I = (a, b)$  including  $(a, \infty)$   
 $\downarrow$   $(-\infty, b)$   
 $(-\infty, \infty)$

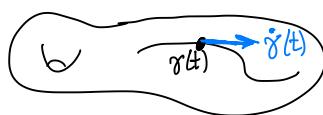
Def: A path or curve on  $M$  is a map  $\gamma: I \subset \mathbb{R} \rightarrow M$ .

The velocity of this path at time  $t = T$  is

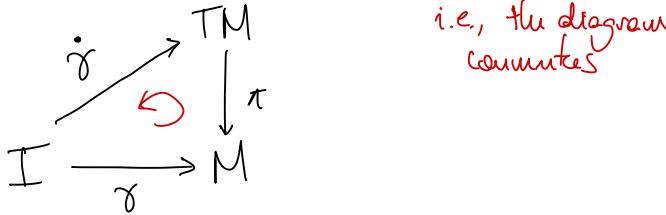
$$(D_\gamma)_t : T_t I \rightarrow T_{\gamma(t)} M$$

11  
12

$$\stackrel{\psi}{\underline{1}} =: \frac{d}{dt} \longmapsto Df_t \left( \frac{d}{dt} \right) = \dot{f}(t)$$



Note: The velocity defines a lift of  $\gamma$  to a path on  $TM$



Def. Let  $X \in \mathcal{X}(M)$ . The path  $\gamma$  is called an integral curve of  $X$  if its velocity coincides with  $X$ ; i.e.,

$$\dot{\gamma}(t) = X(\gamma(t)). \quad (*)$$

In coordinates:  $(0, t) (x^1, \dots, x^n),$

$$X = X^1 \frac{\partial}{\partial x^1} + \dots + X^n \frac{\partial}{\partial x^n}, \quad X^i = X^i(x^1, \dots, x^n) \text{ smooth}$$

$$\varphi \circ \gamma = (\gamma^1(t), \dots, \gamma^n(t))$$

So, we can write  $(*)$  as:

$$\begin{aligned} \frac{d}{dt} \gamma^1(t) &= X^1(\gamma^1(t), \dots, \gamma^n(t)) \\ &\vdots \\ \frac{d}{dt} \gamma^n(t) &= X^n(\gamma^1(t), \dots, \gamma^n(t)) \end{aligned} \quad (*)$$

System of  $n$   
coupled 1st  
order nonlinear  
ODEs

Thm: (Existence and uniqueness of solutions to ODEs)

Let  $X \in \mathcal{X}(V)$ ,  $V \subset_{\text{open}} \mathbb{R}^n$ . For each  $x_0 \in V$ , if a nbhd  $U$ ,  $x_0 \in U \subset V$ , and  $\varepsilon > 0$  and a smooth map

$$\Phi : (-\varepsilon, \varepsilon) \times U \longrightarrow V$$

implies solution depends smoothly on initial conditions

$$(t, x) \longmapsto \varphi_t(x)$$

such that  $\forall x \in U$ , the curve  $t \mapsto \varphi_t(x)$  is an integral curve of  $X$  with initial condition  $x$ ; i.e.,  $\varphi_0(x) = x$ .

Uniqueness: if  $(U', \varepsilon', \Phi')$  is another tuple satisfying the above, then  $\Phi = \Phi'$  on a common domain.

Corollary: Let  $X \in \mathcal{X}(M)$ . Then, there exists a nbhd  $U$ ,  $\{0\} \times M \subset U \subset \mathbb{R} \times M$ , and a  $C^\infty$  map

$$\Phi : U \longrightarrow M$$

such that

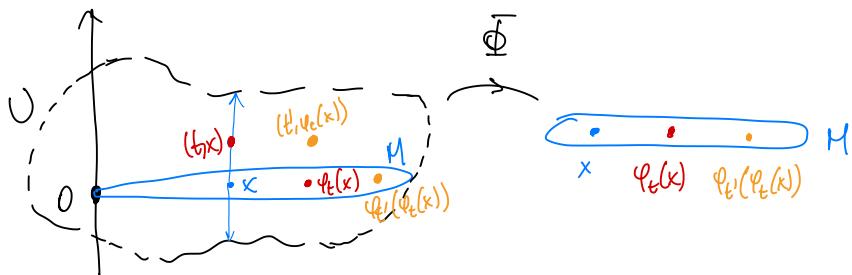
(i)  $(\mathbb{R} \times \{x\}) \cap U$  is an interval about 0 in  $\mathbb{R}$ . (measures  $U$   
is connected)

(ii)  $t \mapsto \varphi_t(y) = \Phi(t, y)$  is an integral curve of  $X$

(iii)  $\varphi_0(y) = y$  starting at  $y$

(iv) if  $(t, x)$  and  $(t', \varphi_t(x))$  and  $(t+t', x)$  are in  $U$ ,  
then  $\varphi_{t+t'}(x) = \varphi_{t'}(\varphi_t(x))$ .

Uniqueness: if  $(U, \Phi')$  satisfies the above and satisfies (i), (ii), (iii), then it must satisfy (iv) and  $\Phi = \Phi'$  on a common domain.



Pf: Using Exist. & Uniq. of ODEs, find an open cover  $(U_i)_{i \in I}$  of  $M$ ,  $\varepsilon_i > 0$   $i \in I$ , and maps  $\Phi_i : (-\varepsilon_i, \varepsilon_i) \rightarrow M$  as in thm.

By uniqueness  $\Phi_i$  must agree with  $\Phi_j$  on

$$((- \varepsilon_i, \varepsilon_i) \times U_i) \cap ((-\varepsilon_j, \varepsilon_j) \times U_j).$$

Then, we get a well-def. map on the union:

$$\Phi : \bigcup_{i \in I} (-\varepsilon_i, \varepsilon_i) \times U_i \xrightarrow{\text{def}} M$$

By construction,  $\Phi$  satisfies (i), (ii), (iii).

Verify (iv), note that we can compare

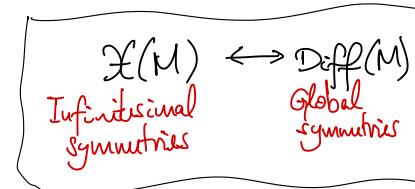
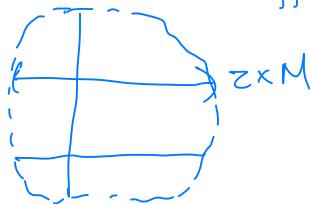
$$\begin{aligned} \tau &\mapsto \varphi_\tau(\varphi_t(x)) \\ \tau &\mapsto \varphi_{\tau+t}(x) \end{aligned} \quad \begin{matrix} \leftarrow & \text{Both are integral curves w/ initial condition } \varphi_t(x). \text{ Thus,} \\ & \text{by uniqueness, they must coincide.} \end{matrix}$$

Similar analysis gives uniqueness of flows.

□

Proposition: There exists a maximal flow (constructed by taking the union of all possible flows). This flow is called: maximal local 1-parameter group of diffeomorphisms (bad terminology...)

Note: if  $t \in \mathbb{R}$ ,  $x \in M$  then  $\varphi_t: M \rightarrow M$  is defined and is a diffeomorphism (smooth inverse is  $\varphi_{-t}: M \rightarrow M$ ).



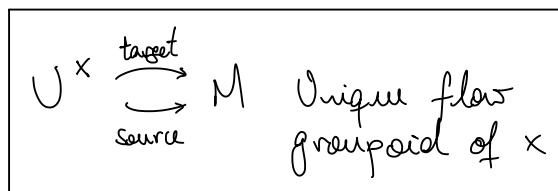
Def: A groupoid is a category in which every arrow has an

$$\begin{array}{ccc} & g & \\ y & \xrightarrow{\hspace{2cm}} & x \\ & g^{-1} & \end{array}$$

inverse  $g^{-1}$

For maximal flow: view elements of  $\cup$  as arrows, where

$\cup \ni (t, x)$	$\text{source}(t, x) = x$	$\text{inverse}(t, x) = (-t, \varphi_t(x))$
$\varphi_t(x)$	$\xleftarrow{\hspace{2cm}}$	$\text{target}(t, x) = \varphi_t(x)$
	$\text{Id}_x = (0, x)$	<u>Composition</u> :
		$(t', \varphi_t(x))(t, x) = (t' + t, x)$



## SPECIAL CASE:

Def: If  $U^x = \mathbb{R} \times M$  then  $X$  is called a COMPLETE vector fields and we obtain a 1-parameter <sup>(sub)</sup>group of diff. eqs.

$$\mathbb{R} \ni t \longmapsto \varphi_t^X \in \text{Diff}(M)$$

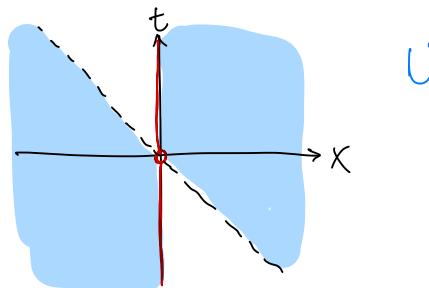
$$t + t' \longmapsto \varphi_{t+t'}^X = \varphi_t^X \circ \varphi_{t'}^X = \varphi_{t'}^X \circ \varphi_t^X$$

Solutions written  $\varphi_t^X = e^{tX}$  ← 1-param. group of diff. eqs.  
of complete vector fields

Ex: Constant vector field  $X = \frac{\partial}{\partial x}$  is complete in  $\mathbb{R}$

with flow  $\varphi_t^X(y) = t + y$ .

But  $X = \frac{\partial}{\partial x}$  is incomplete in  $\mathbb{R} \setminus \{0\}$



Thm: If  $M$  is compact (w/out bdy), then all  $X \in \mathcal{X}(M)$  are complete.

# LECTURE 12

Oct 17<sup>th</sup>, 2024

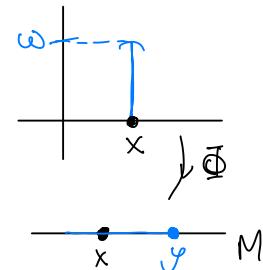
Thm: On a compact manifold, any  $X \in \mathcal{X}(M)$  is complete.

Pf: By contradiction, assume  $\Phi$  is the maximal flow of  $X$ . If  $X$  is not complete, then

$\exists x \in M$  and wlog  $w > 0$  s.t.

$U \cap (\mathbb{R} \times \{x\}) = \text{open interval } w \text{ / upper boundary } w$

WTS: this contradicts maximality.



1. By compactness, as  $t \rightarrow w$ ,  $\Phi(t, x) - y$  is an accumulation point.

(Idea: flow is defined at  $y$ ! Extend flow at  $x$  by flowing almost to  $w$ , continue using flow near  $y$ .)

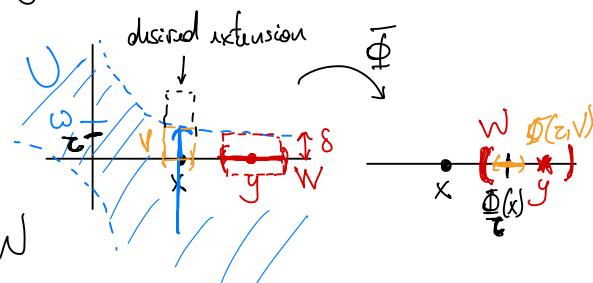
2.  $\exists \delta > 0$  and a nbhd of  $y$  st.  $(-\delta, \delta) \times W \subset U$ .

Since  $W$  is open,  $\exists z \in (w - \delta, w)$

s.t.  $\Phi(z, x) \in W$ . Moreover,

$\exists$  nbhd  $V$  of  $x$  s.t.

$\{z\} \times V \subset U$  and  $\Phi(z, V) \subset W$



3. Given these choices, enlarge  $U$  by doing:

$$\tilde{U} = U \cup ((z-\delta, z+\delta) \times V)$$

$$\tilde{\Phi}(t, z) = \begin{cases} \Phi(t, z), & \text{if } (t, z) \in U \\ \Phi(t-z, \Phi(z, z)) & \text{if } (t, z) \in \underbrace{(z-\delta, z+\delta) \times V}_{\text{Extension of } U \text{ since } z+\delta > \omega} \end{cases}$$

//

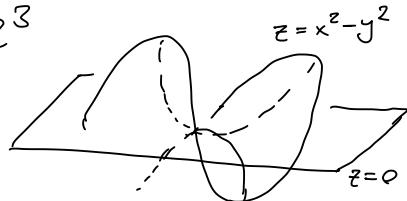
\* TRANSVERSALITY: Unlike in the linear category, where  $U_1, U_2 \subset V$  intersect in a linear subspace  $U_1 \cap U_2$ , for manifolds, this fails! ← Unless we require a special relationship between submanifolds

↳ Manifolds are not "closed under intersection".

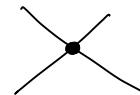
Ex:  $\{z = x^2 - y^2\} \cap \{z = 0\}$  in  $\mathbb{R}^3$

surface  
codim 1

surface  
codim 1



Intersection:



← Not  
a manifold

Note:  $\{z^2 = x^2 - y^2\} \cap \{z = t\}$

$t = 0$  : singular

$t = 1$  : Hyperbola

$t = -1$  : Hyperbola

$\left. \begin{array}{l} \text{smooth 1-d} \\ \text{submanifolds} \\ (\text{codim 2}) \end{array} \right\}$  (Transverse intersections)

Thm: If  $K, L$  are smooth submanifolds of  $M^n$  of codim  $\kappa + l$  are TRANSVERSE, then  $K \cap L$  is either empty or a submanifold of codim  $\kappa + l$ .

Idea: submfld of codim  $\kappa = \kappa$  indp constraints in  $M$   
 $" " "$        $l = l$      $" " "$      $" " "$

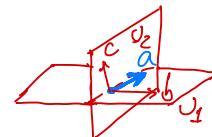
If  $\kappa$ -constraints and  $l$ -constraints are independent (transversality), then  $K \cap L$  imposes all  $\kappa + l$  constraints gives a submfld of codim  $\kappa + l$ .

Def:  $K, L$  submflds of  $M$  are transverse if  $\forall p \in K \cap L$ ,  $T_p K$  and  $T_p L$  are transverse in  $T_p M$ .

From linear algebra: two linear subspaces  $U_1, U_2 \subset V$  are transverse if  $U_1 + U_2 = V$ .

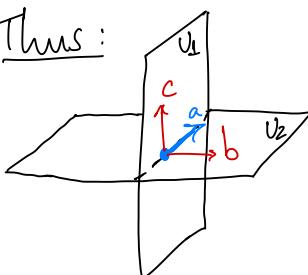
e.g.:  $V + V = V$   
 $\curvearrowright$  transverse

$\curvearrowleft$  not direct sum  
 (intersection need)  
 not be zero



$$\begin{aligned} \dim U_1 \cap U_2 &= a = (a+b) + (a+c) - (a+b+c) \\ &= \dim U_1 + \dim U_2 - \dim V \end{aligned}$$

Thus:  $\dim U_1 \cap U_2 = \dim U_1 + \dim U_2 - \dim V$

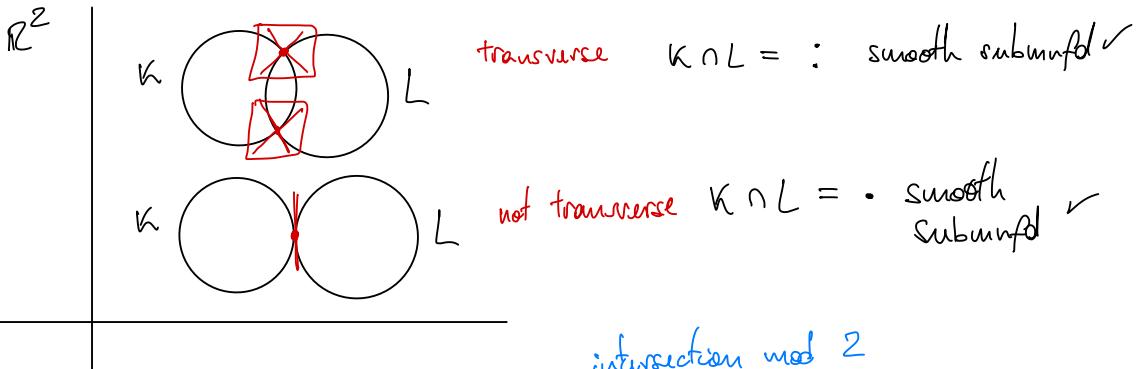


$$\text{codim } U_1 \cap U_2 = b + c = \text{codim } U_1 + \text{codim } U_2$$

# constraints def.  $U_1 \cap U_2$       # constraints def.  $U_1$       # constraints def.  $U_2$

$\Rightarrow$  "dimension of transverse intersection & the expected dim."

⚠ **WARNING:**  $K \cap L$  may be a smooth submfld even if intersection is not transverse.



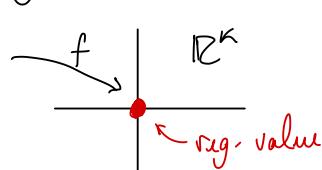
$\Rightarrow$  "Transversality gives [control] over intersection # in the case  $\dim K \cap L = 0$ ".

Note: in order for two closed loops in the plane to be transverse they must intersect in an even # of pts.

**Pf:** (of thm)  $K, L$  are submflds of codim  $k, l$ . So,  $\exists$  submfld charts  $U(x^1, \dots, x^n)$  and  $V(y^1, \dots, y^n)$  in  $M$  s.t.  $K = \{x^1 = \dots = x^k = 0\}$ ,  $L = \{y^1 = \dots = y^l = 0\}$ .

In other words,  $\exists f: U \rightarrow \mathbb{R}^k$  s.t. 0 is a regular value

$$g: V \rightarrow \mathbb{R}^l \quad K \cap U = f^{-1}(0)$$



$$L \cap V = g^{-1}(0)$$

Now, on  $U \cap V$ , combine the constraint functions

$$(f, g): U \cap V \rightarrow \mathbb{R}^k \times \mathbb{R}^l.$$

d:  $(K \cap L) \cap (U \cap V) = (f, g)^{-1}(0, 0)$  and  $(f, g)$  is a submersion, so  $K \cap L$  is a submfld.

Only remains to show that  $(0, 0) \in \mathbb{R}^{k+l}$  is a reg. value of  $(fg)$ .

WTS:  $D_x(f, g)$  is onto for all  $x \in U \cap V \cap K \cap L$

$$D_x(f, g): T_x M \xrightarrow{\cong \mathbb{R}^n} \mathbb{R}^{k+l}$$

$$\ker D_x(f, g) = \underbrace{(\ker D_x f)}_{T_x K} \cap \underbrace{(\ker D_x g)}_{T_x L}$$

$$\text{Transversality} \Rightarrow \dim \text{im}(D_x(f, g)) = \text{codim } \ker(D_x(f, g))$$

$$\begin{aligned} &= \text{codim}(\ker D_x f) \\ &\quad + \text{codim}(\ker D_x g) \\ &= k + l \end{aligned}$$

## LECTURE 13

Oct 18, 2024

Thm:  $K, L \subset M$  are transverse, then either  $K \cap L$  is empty or a submfld of  $\text{codim}(K \cap L) = \text{codim } K + \text{codim } L$ .

Ex: In  $\mathbb{R}^6$

K	L
0	0
1	1
2	2
3	3
4	4
5	5
6	6

\* nonempty  $\cap$

Ex:  $\mathbb{R}^{10} \setminus \{0\} = \mathbb{C}^5 \setminus \{0\} =: M$

$$K := S^4 = \left\{ (z_1, \dots, z_5) : \sum_{i=1}^5 |z_i|^2 = 1 \right\} \text{ hypersurface (codim 1)}$$

$$L_k := \left\{ (z_1, \dots, z_5) : \underbrace{z_1^2 + z_2^2 + z_3^2 + z_4^2 + z_5^{6k-1}}_0 = 0 \right\}, k \in \mathbb{N}$$

(think of  $f: \mathbb{R}^{10} \rightarrow \mathbb{R}^2$ ,  $f^{-1}(0)$  is a reg.  $f$  value)

C:  $K \pitchfork L$  (transverse intersection)

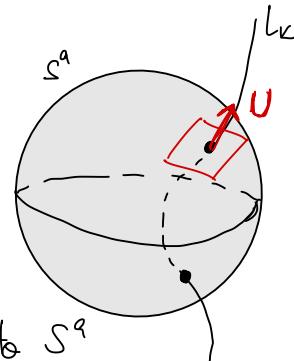
$$\begin{aligned} U &= \frac{1}{2} z_1 \partial_{z_1} + \frac{1}{2} z_2 \partial_{z_2} + \frac{1}{2} z_3 \partial_{z_3} \\ &\quad + \frac{1}{3} z_4 \partial_{z_4} + \frac{1}{6k-1} z_5 \partial_{z_5} \end{aligned}$$

Now,  $Re(U)$  is tangent to  $L_k$  but not to  $S^4$



Apply it to the fcts that define  $L_k$  and  $S^4$

Note:  $z = x + iy \rightarrow dz = dx + i dy \rightarrow \frac{\partial}{\partial z} = \frac{1}{2} \left( \frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right)$ .



Brieskorn (60s):  $K \cap L_\kappa$  for  $\kappa = 1, \dots, 28$  are homeomorphic to  $S^7$ .

Kervaire-Milnor: these are all the different smooth structures on  $S^7$ . The smooth structures on  $S^7$  form a group by connected sums

$$S_{\text{top}}^7 \# S_{\text{top}}^7 = S_{\text{top}}^7.$$

$$\text{In this case } C^\infty\text{-str}(S^7) = \mathbb{Z}/28\mathbb{Z}$$

$$(K \cap L_1) \# (K \cap L_1) \stackrel{C^\infty}{=} K \cap L_2$$

We can rephrase transversality of  $K, L \subset M$  in terms of the embeddings

$$\iota_K : K \hookrightarrow M \longleftrightarrow L : \iota_L$$

(embedding  
injective  
immersion  
homeo onto image)

Need to map the tangent spaces to  $K$  and  $L$  to  $M$ .  
 $\forall (k, l) \in K \times L$  s.t.  $\iota_K(k) = \iota_L(l) =: p \in M$

$(k, l)$  is  
an "intersection point"

$$T_k K$$

$$T_l L$$

are transverse; i.e.,

$$D_k \iota_K$$

$$D_l \iota_L$$

$$\text{im } D_k \iota_K + \text{im } D_l \iota_L = T_p M$$

$$T_p M$$

Transversality in terms of maps now (instead of submanifolds)

Duf: Two maps  $f: K \rightarrow M$  and  $g: L \rightarrow M$  of manifolds are TRANSVERSE if  $\forall$  intersection pts.

i.e.,  $(a, b) \in K \times L$  s.t.  $f(a) = g(b) =: p$

we have  $D_a f, D_b g$  are transverse

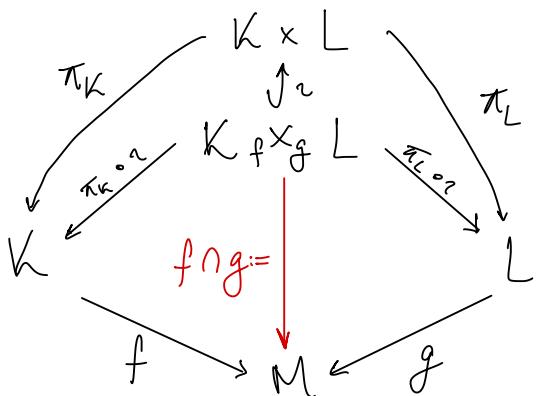
i.e.,  $\text{im } D_a f + \text{im } D_b g = T_p M$ .

{ slightly improved this

Thm: If  $f \in C^\infty(K, M)$  and  $g \in C^\infty(L, M)$  are transverse, then their intersection, called the fiber product,

$$K_f \times_g L = \left\{ (k, l) \in K \times L : f(k) = g(l) \right\}$$

is a smooth submanifold of  $K \times L$  equipped with commuting maps



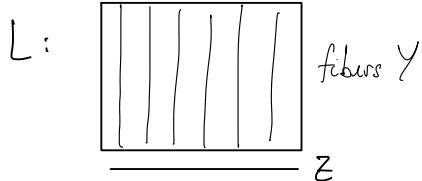
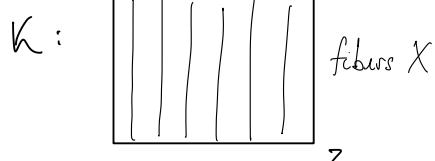
When maps  $g, f$  are understood, we write  $K_f \times_g L = K \times_M L$

$$\text{Ex: } K = \mathbb{Z} \times X \quad X, Y, Z \in C^\infty\text{-mfld}$$

$$L = \mathbb{Z} \times Y$$

$$\begin{array}{ccc} K & \times_{\mathbb{Z}} & L \\ \searrow & & \downarrow \\ K & & L \\ \pi_Z \searrow & & \swarrow \pi_Z \\ & Z & \end{array}$$

$\pi_Z$  is a submersion  
(i.e.,  $D\pi_Z$  is onto) so  
it is transverse to  
any map to  $Z$



$$K \times_{\mathbb{Z}} L = \left\{ (z, x), (\tilde{z}, y) : z = \tilde{z} \right\} = \mathbb{Z} \times X \times Y.$$

$$K \times_{\mathbb{Z}} L$$

fibers are  $X \times Y$

$$\text{Ex: } \pi: S^3 \rightarrow S^2 \text{ Hopf fibration (} S^1 \text{ fiber bundle)}$$

$$\begin{array}{ccc} S^3 \times_{S^2} S^3 \\ \searrow & & \downarrow \\ S^3 & & S^3 \\ \pi \searrow & & \swarrow \pi \\ \text{fiber dim 1} & & \text{fiber dim 1} \end{array}$$

Since  $\pi$  is continuous,  
we have that  $\pi \pitchfork \pi$ .

This gives a fiber bundle with fiber  $T^2 = S^1 \times S^1$

$$\begin{array}{ccc} S^3 \times_{S^2} S^3 & \downarrow & \\ \text{fiber dim 1+1} & \xrightarrow{\pi \pitchfork \pi} & S^2 \\ \text{Z} & & \end{array}$$

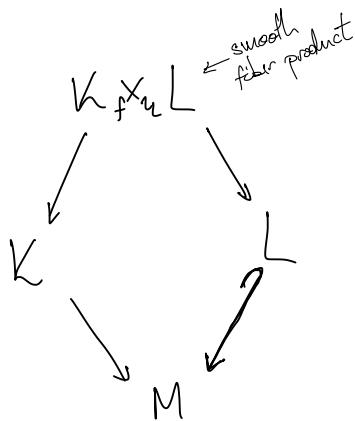
4d mfld.

Ex:  $L \hookrightarrow M$  submfld

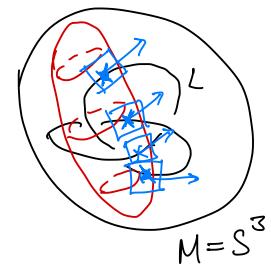
$K \xrightarrow{f} M$  smooth map

transverse to L

e.g., if  $f$  is a submersion but this is not always the case



In order for  $f$  to be transverse, it needs to provide the tangent directions that are missing from  $L$  to complete into  $T_p M$ .



$$K_f x_{z_L} L = \{(k, l) : K \times L \text{ s.t. } f(k) = z_L(l)\}$$

$$= f^{-1}(L)$$

Generalizes the regular value theorem.

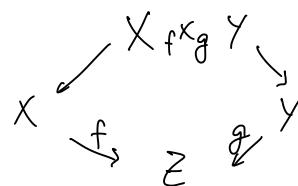
## LECTURE 14

Oct 24th, 2024

Transversality • of manifolds:

• of  $C^\infty$  maps:

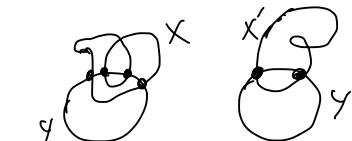
$$X, Y \subset Z \quad X \pitchfork Y$$



INTERSECTION NUMBER  $(\text{mod } 2)$ : the intersection # of two submanifolds  $X, Y$  in  $Z$  should be " $= \#$  of intersec. pts."

- want  
X  
Y  
to  
be  
this
- Want  $X, Y$  to have  $\cap$  intersec. in 0-dim submanifds  
i.e., want  $X, Y$  to have complementary dim:  $\dim X + \dim Y = \dim Z$
  - Want  $X, Y$  compact so the # is finite.

PROBLEM: # not well-def. but it is mod 2.

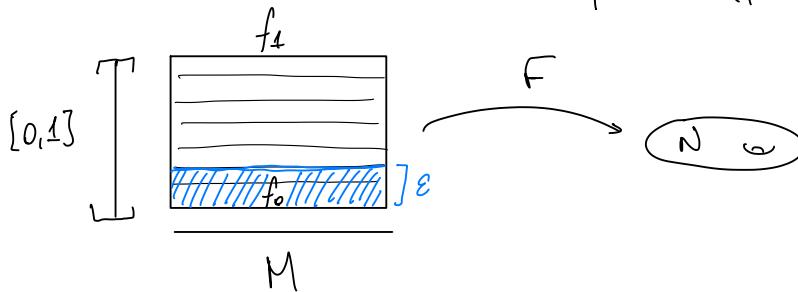


"CL: # mod 2 is independent of perturbations of  $X, Y$ ." (i.e., it's stable)

Def: (1) A smooth map  $F: M \times [0, 1] \rightarrow N$  is a smooth homotopy from  $f_0$  to  $f_1$ , where

$$f_t = F \circ j_t \quad j_t: M \longrightarrow M \times [0, 1]$$

$$p \mapsto (p, t)$$



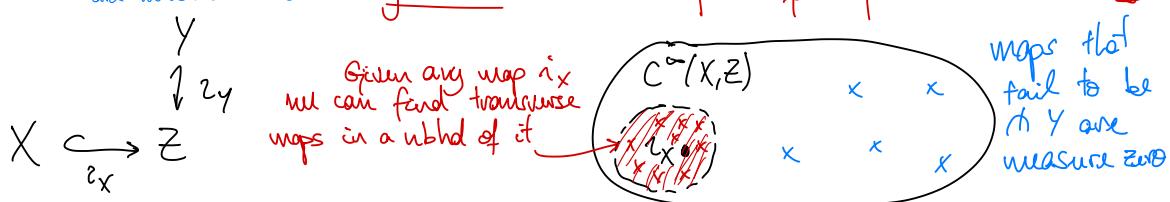
(2) A property of smooth maps  $f \in C^\infty(M, N)$  is STABLE under perturbations if ∀ smooth homotopies  $f_t$ ,  $t \in [0, 1]$ , we have

property holds for  $f_0 \Rightarrow$  property holds for  $f_t$  for some  $\epsilon > 0$ ,  $0 \leq t < \epsilon$ .

Def: (INTERSECTION #) Actual definition of  $I_Z(X, Y)$  removes the requirement of  $X, Y$  being transverse.

Strategy: 1. If  $X, Y$  compact are given and are s.t.  $\dim X + \dim Y = \dim Z$ , deform  $X$  via a smooth homotopy until it becomes transverse to  $Y$ .

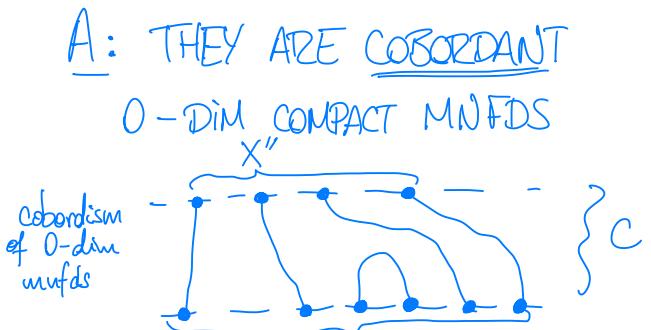
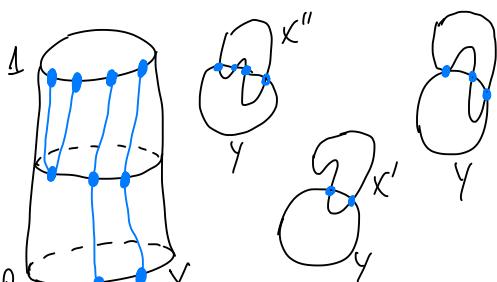
This depends on the fact that  $\pitchfork$  is [SARD'S THM] generic in the space of maps



Exm: the set of maps  $\pitchfork Y$  are dense and have full measure.

After deformation from  $X$  to  $X'$ ,  $\#(X' \cap Y) \in \mathbb{Z}$  is well-defined. But this depends on the deformation.

2. Given two deformations  $X', X''$  of  $X$ , each  $\pitchfork Y$ , what is the relation between  $X' \cap Y$  and  $X'' \cap Y$ ?



$C$  = compact 1-manifol w/  
boundary

$O \cup O \cup \dots \cup O$

$[0,1] \cup [0,1] \cup \dots \cup [0,1] \Rightarrow \# \text{bdry pts. of } C \Rightarrow \#X' = \#X'' \pmod{2}$

How to produce such cobordism? We need a  $C^\infty$  homotopy

$$J: X \times [0,1] \longrightarrow Z$$

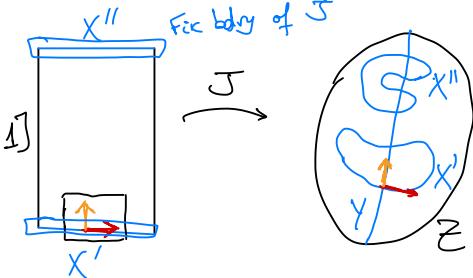
$$J_0 = \gamma_{X'}, \text{ and } J_1 = \gamma_{X''}$$

$$\begin{array}{ccc} (X \times [0,1])_{J \times \gamma_Y} Y & \longrightarrow & Y \\ \downarrow & & \downarrow \gamma_Y \\ X \times [0,1] & \xrightarrow[J]{} & Z \end{array}$$

Hope:  $(X \times [0,1])_{J \times \gamma_Y} Y$  is a cobordism.

Problem: We don't know that  $(X \times [0,1])_{J \times \gamma_Y} Y$  is smooth  
(e.g., it would be of  $J \pitchfork Y$  but we have no guarantee  
of that). BUT:  $J_0, J_1$  are  $\pitchfork Y$ .

$J \pitchfork Y$  along the boundary  $[0,1]$   
of the cylinder



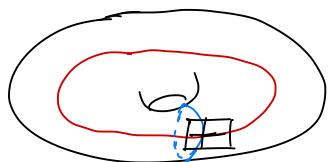
Solution: Same strategy using genericity of  $\mathcal{A}$ .

Modify  $J$ : find a homotopy from  $J$  to  $J'$  s.t.  
 $J' \not\pitchfork \gamma$ .

But: domain of  $J$  is a manifold w/  $\partial$  and we  
want to fix  $J|_{\partial(M \times [0,1])}$  (version of genericity)  
allows us to do that

[ SARD II ] Thm: Existence of  $\mathcal{A}$  perturbation w/  
bdry condition

Ex:  $T^2$



$$X := S^1 \times \{1\} \subset S^1 \times S^1$$

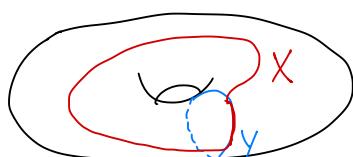
$$Y := S^1 \times \{1\} \subset$$

$$X \cap Y = \{(1,1)\}$$

But  $X \pitchfork Y$  since  $T_{(1,1)} X + T_{(1,1)} Y = T_{(1,1)} (T^2)$

$$\Rightarrow I_2(X, Y) = 1 \text{ mod } 2.$$

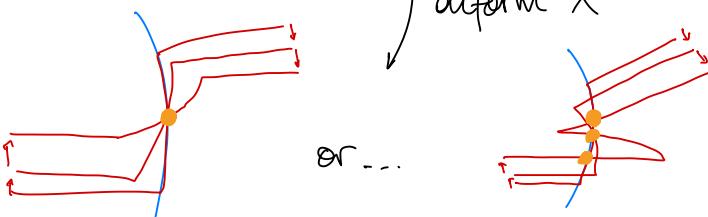
$T^2$



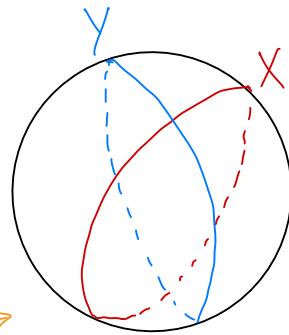
$X \cap Y$  not transverse,  $\infty$ -many intersection pts.

} Apply construction above

deform  $X$



Ex:  $S^2$



$X, Y$  great circles

$$I_2(X, Y) = 2 = 0 \bmod 2$$

or deform  $X$  to a point by smooth homotopy until

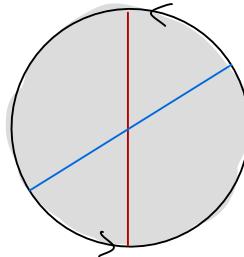
$$X' \cap Y = \emptyset.$$

Same  
works for any embedded  
circles



Ex:  $\mathbb{RP}^2$  image of distinct great circles give paths

$$\# X \pitchfork Y = 1 \bmod 2$$



## LECTURE 15

Oct 25<sup>th</sup>, 2024

Def: (INTERSECTION #)  $X, Y$  compact  $f, g$  smooth s.t.  $X \xrightarrow{f} Z \xrightarrow{g} Y$   
 $\dim X + \dim Y = \dim Z$ . Then

not necessarily  
transverse

$$I_2(f, g) := \#(X_f \times_g Y) \bmod 2,$$
 where

$f'$  is any map smoothly homotopic to  $f$  and transverse to  $g$ .

$$\begin{array}{ccc} X \times Y & \supset & X_{f' \times g} Y \\ \text{smooth} \\ \text{submfld} & \downarrow & \downarrow g \\ & & X \xrightarrow{f'} Z \end{array}$$

Run:  $\dim X + \dim Y = \dim Z$

$$\dim(X_{f' \times g} Y) = 0$$

Need to prove:

Claim 1: It is always possible to find  $f' \sim f$  ( $C^0$  homotopy)

Claim 2: For  $f' \sim f$  and  $f'' \sim f$ ,  $X_{f' \times g} Y$  is cobordant to  $X_{f'' \times g} Y$

so that the definition is valid.

Obs: Both claims follow from Sard's theorem.

Ex: A pt  $p \in S^1$  can be seen as a map

$$\begin{array}{ccccc} & \{p\} & & S^1 & \\ h^*\{ & \swarrow & \searrow & & \\ & p & & & \text{Id} \\ & \searrow & \swarrow & S^1 & \end{array}$$

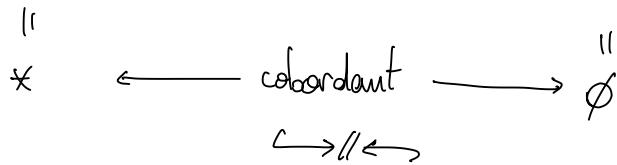
Note:  $\text{Id}$  is a submersion, hence  $\text{Id} \pitchfork \left( \begin{smallmatrix} \text{any map} \\ X \rightarrow S^1 \end{smallmatrix} \right)$ .

So, we have a single point of intersection.

$\Rightarrow \text{Id}$  is not smoothly homotopic to any constant map.

If  $\text{Id} \sim \text{const. map } g: x \mapsto q \in S^1$ ,  $q \neq p$ .

$\Rightarrow *_{p \times_{\text{Id}} S^1} S^1$  is cobordant to  $*_{p \times_q S^1} S^1 = \emptyset$



SAME HOLDS FOR ANY COMPACT MANIFOLD!  $\longrightarrow \blacktriangleleft$

WEIERSTRASS APPROXIMATION: Any continuous function  $f: [0, 1] \rightarrow \mathbb{R}$  can be approximated by polynomials in the sup norm  $\|f\|_\infty = \sup_{x \in [0, 1]} |f(x)|$ .

(Generalize)

STONE - WEIERSTRASS: for any compact Hausdorff top. space  $X$  (e.g., compact manifolds), if  $A \subset C^0(X, \mathbb{R})$  is a subalgebra s.t.

1.  $A$  separates pts

2.  $A$  contains at least one nonzero continuous function

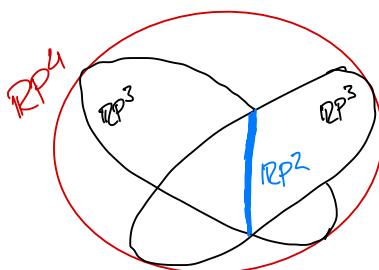
Then  $A$  is dense in the sup norm.

$\hookrightarrow$  Since we can approximate all homotopies by smooth homotopies, the example above gives us that

COMPACT MANIFOLDS ARE NOT CONTRACTIBLE!

Ex:  $\mathbb{R}P^4 = (\mathbb{R}^5 \setminus \{0\})/\sim$ . In  $\mathbb{R}^5$ , choose two hyperplanes  $H_1$  and  $H_2$  s.t.  $H_1 \pitchfork H_2$  (i.e.,  $H_1 + H_2 = \mathbb{R}^5$ ). Then

$$\begin{array}{ccc} \text{↑ 4-dim} & \text{Projectivization} & \text{3-dim} \\ P(H_1) \pitchfork P(H_2) & = P(H_1 \cap H_2) & \simeq \mathbb{R}P^2 \\ \text{RP}^3 \curvearrowleft & & \curvearrowright \text{RP}^3 \end{array}$$



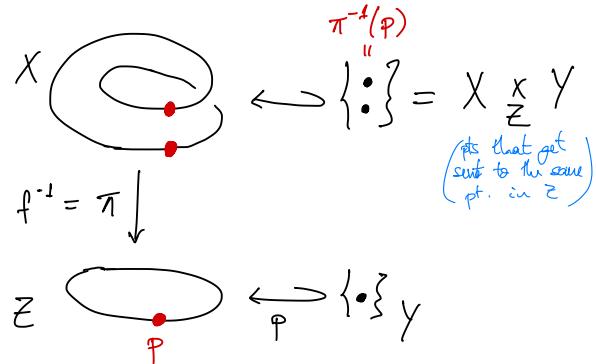
Q: Is it possible to remove intersection by deforming  $2\text{RP}^3$ ?

A: No! Since  $\mathbb{R}P^2$  is not null-cobordant.

If we remove this intersection,  $\mathbb{R}P^2$  would be cobordant to  $\emptyset$ . Thom's classification of cobordism ring gives that  $\mathbb{R}P^2$  is a generator in dim-2, hence cannot be null-cobordant.

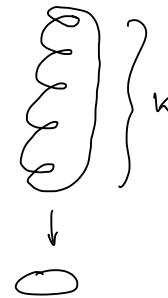
Def: (DEGREE OF MAP) Let  $f: M^d \rightarrow N^d$  be smooth and  $\dim M = \dim N$  with  $M$  compact and  $N$  connected, then the degree of  $f$  is

$$\deg_Z(f) := \mathbb{Z}_2(\varphi_p, f), \quad p \in N$$

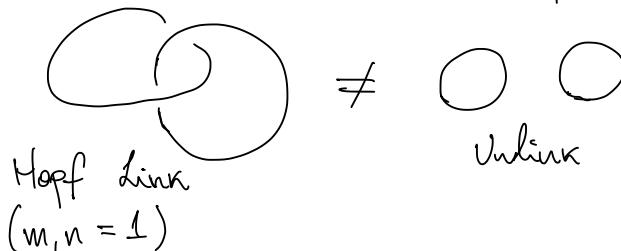


Ex:  $f: S^1 \rightarrow S^1$      $k$ -fold cover  
 $z \mapsto z^k$

$$\deg_z f = k \bmod 2.$$



Ex: Use intersection #/degree to study manifolds that don't intersect. Say  $M^m, N^n$  are manifolds of dim  $m, n$  and they sit inside  $\mathbb{R}^{m+n+1}$ . Example: 2 circles in  $\mathbb{R}^3$



Q: Can we detect if manifolds are linked or not?

Strategy: Convert this into an intersection problem in an auxiliary space. Define

$$\lambda: M \times N \longrightarrow S^{m+n} \quad \text{sphere at } \infty \text{ in } \mathbb{R}^{m+n}$$

$$(x, y) \longmapsto \frac{x-y}{\|x-y\|} \quad \begin{matrix} \text{direction of } x \text{ from } y \\ \dim = m+n \end{matrix}$$

will-dif. b/c  $M, N$  don't intersect

$\Rightarrow$  Can compute the degree of  $\lambda$

For Hopf link,  $\deg_z \lambda = 1$ ,  $\lambda: S^1 \times S^1 \rightarrow S^2$

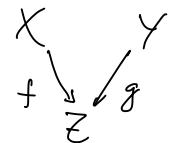
$$\Rightarrow \text{Unlink} \neq \text{Hopf link}$$

# LECTURE 16

Nov 14<sup>th</sup>, 2024

SARD'S THEOREM: Transversality is generic.

Almost all pairs  $(f, g) \in \text{Hom}(X, Z) \times \text{Hom}(Y, Z)$



Rmk: Transversality may be expressed as the existence of regular value of a map.  $X, Y \subset Z$  submfds

$$X \pitchfork Y \iff 0 \text{ reg. value of}$$

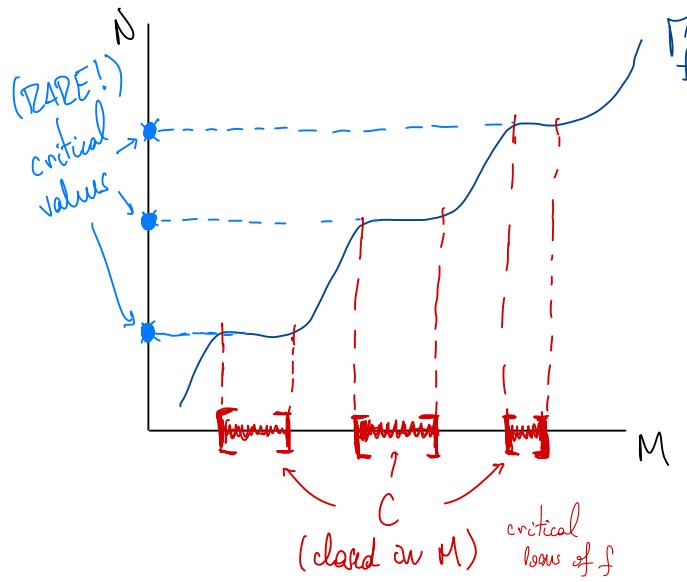
$$(f, g): Z \rightarrow \mathbb{R}^{\text{codim } X + \text{codim } Y}$$

Ex:

$$\begin{array}{ccc} M & & N \\ f \downarrow & & \leftarrow p = \gamma_p \\ & f: M \rightarrow N & \\ & p \in N \text{ is reg. value} \iff f \pitchfork p. & \end{array}$$



Sard's Theorem: Let  $f \in C^\infty(M, N)$  and let  $C \subset M$  be the set of critical points of  $f$ . Then  $f(C) \subset N$  has measure 0.



Rmk: if  $f$  is not smooth, we need  $f \in C^k(M, N)$  where  $k > \dim M - \dim N + 1$

Def: A subset  $X \subset M$  of a mfld  $M$  has measure 0 if, in each chart  $(U, \varphi)$ ,  $\varphi(X \cap U)$  has Lebesgue measure 0 in  $\mathbb{R}^n$ . → that's why we need mflds to be 2nd countable...

i.e.,  $\forall \varepsilon > 0$ ,  $\varphi(X \cap U)$  can be covered by a countable seq. of balls w/ total volume  $< \varepsilon$ .

Guarantees that the def. above is indep. of charts

Lemma: Let  $I^m = [0, 1]^m$  and  $f: I^m \rightarrow \mathbb{R}^n$  be  $C^1$ .

(a) If  $m < n$ , then  $f(I^m)$  has measure 0

(b) If  $m = n$  and  $A \subset I^m$  has measure 0 then  $f(A)$  has measure zero

$$A = I^m \times \{0\} \xrightarrow{\text{C}_m \text{ has } 0} I^m \times I^{n-m} \xrightarrow{\tilde{f}} \mathbb{R}^n \quad f(I^m) = \tilde{f}(A)$$

Pf: (b)  $A$  meas. 0  $\Rightarrow \forall \varepsilon > 0 \exists$  sq. of balls  $B_k$  w/ radius  $r_k$  covering  $A$  s.t.

$$C_m \sum_{k \in \mathbb{N}} (r_k)^m < \varepsilon$$

Idea: Cover  $f(A)$  w/  $f(B_k)$ . So, find balls  $B'_k \subset \mathbb{R}^n$  s.t.  $f(B_k) \subset B'_k$  w/  $\sum_{k \in \mathbb{N}} \text{vol}(B'_k) < \varepsilon$ .

Need: Estimate for expansion factor of  $f$

If  $f \in C^1(I^m, \mathbb{R}^n)$ ,  $I^m$  compact  $\Rightarrow$  derivative is bounded

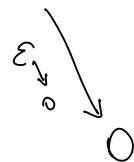
LIPSCHITZ  
CONSTANT  
OF  $f$

$$\forall x, y \in I^m, \|f(x) - f(y)\| \leq K \|x - y\|.$$

$\exists K > 0$

$\Rightarrow f(A)$  covered by balls of radius  $K r_k$

$$\Rightarrow \text{volume} \leq C_m \sum_k (K r_k)^m < K^m \varepsilon$$



$\Rightarrow$

$\Rightarrow f(A)$  is measure zero.

Corollary: 1)  $f: M \rightarrow N$   $C^1$   $\dim M = \dim N$

(uses 2nd count.)

then  $A$  meas. zero  $\Rightarrow f(A)$  meas. zero

2) (Baby Sard) If  $\dim M < \dim N$ ,  $C = \text{crit. pts.} = M$ ,  $f \in C^1$

then  $f(C) = f(M) \subset N$  has meas. zero (uses 2nd countable)

Thm: (Equidimensional Sard)  $f: M \rightarrow N \in C^1$   
 $\dim M = \dim N$ ,  $C = \text{crit. pts. of } f \subset M$ ,  $f(C) \subset N$   
 has meas. zero.

Pf: Suffices to prove for  $I^n \rightarrow \mathbb{R}^n$ .

(1) Let  $K$  be the Lipschitz const. of  $f$

$$\|f(x) - f(y)\| \leq K\|x - y\|.$$

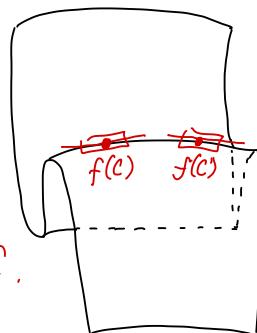
(2) Critical Vol. Comparison:  $c \in I^n$  critical  $\Rightarrow$  im  $Df_c$  is

critical locus

proper subspace  
of  $\mathbb{R}^n$ .



Comparison of volume  
along critical pts of  $f$ .



Choose hyperplane  
 $H_c$  centered at  
 $f(c)$  containing  
image.

Then  $d(f(x), H_c) \leq \|f(x) - f_c^{\text{lin}}(x)\|$ ,

where  $f_c^{\text{lin}}(x) = f(c) + D_c f(x - c)$

By def. of derivative:  $\forall \varepsilon > 0 \exists \delta > 0$  s.t.

$$\|f(x) - f_c^{\text{lin}}(x)\| < \varepsilon \|x - c\| \quad \forall x \text{ s.t. } \|x - c\| < \delta$$

Use  $I^n$  compact  $f \in C^1 \Rightarrow$  unif  $\uparrow \delta$  in  $c$  for any  $\varepsilon$   
 $\delta$  indep. of  $c$

Combining (1) + (2):  $\|x - c\| < \delta \Rightarrow f(x)$  is within  $\varepsilon\delta$  of  $H_c$ .

$$d(f(x), H_c) \leq \|f(x) - f_c^{\text{lin}}(x)\| < \varepsilon \|x - c\| < \varepsilon \delta.$$

and within  $K\delta$  of  $f(c)$

$\Rightarrow f(x)$  lies in a parallelepiped of volume  $(2\varepsilon\delta)(2K\delta)^{n-1}$

Finally: Need to cover crit. locus  $C$  w/ countably many balls/cubes s.t. we can use above est. in each one.

Easy: Subdivide cube into  $N^n$  small boxes s.t.

$$\text{diam}(\text{small cubes}) < \delta \quad \text{i.e., } \sqrt{n} \frac{1}{N} < \delta$$

$\Rightarrow$  covered critical locus of  $f$  w/ boxes of  $\text{diam} < \delta$ .

So,

$$\begin{aligned} \text{vol}(f(\text{small cubes} \cap C)) &\leq \left(2\varepsilon \frac{\sqrt{n}}{N}\right) \left(2K \frac{\sqrt{n}}{N}\right)^{n-1} N^n \\ &= (2\varepsilon \sqrt{n}) (2K \sqrt{n})^{n-1} \xrightarrow{\varepsilon \rightarrow 0} 0. \end{aligned}$$



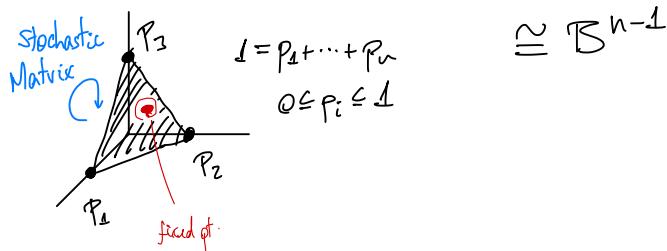
# LECTURE 17

Nov 15<sup>th</sup>, 2024

## \* APPLICATIONS OF SARD:

Thm: (Brouwer Fixed Point) Any continuous map  $f: \mathbb{B}^n \rightarrow \mathbb{B}^n$ ,  
 $\mathbb{B}^n = \{x \in \mathbb{R}^n : \|x\| \leq 1\}$  has a fixed point.  
↳ Manifold w/ boundary

Rmk: Space of prob. distrib. on  $n$  outcomes  $\{1, 2, \dots, n\}$   
is an  $n$ -simplex  $\Delta^{n-1} = \{(p_1, \dots, p_n) : \sum p_i = 1, 0 \leq p_i \leq 1\}$



Lemma: Let  $M$  be a compact manfd w/ bdry. Then  
is no smooth retract to  $\partial M$ ; i.e., there are no  
 $f: M \rightarrow \partial M$   
s.t.  $f|_{\partial M} = \text{Id}_{\partial M}$ .

Regular Value Thm for manfds w/ bdry:  $q \in N$  is reg. val.

$M // / / / / \not\pitchfork f$  and  $\partial f \Rightarrow f^{-1}(q)$  is a submanfd  
w/ bdry given by  
 $\partial f^{-1}(q) = f^{-1}(q) \cap \partial M$

Pf: (Lemma) By contradiction assume such  $f$  exists.

By Sard's Thm,  $\exists$  a reg. value  $q \in \partial M$  for  $f$   
(since  $f|_{\partial M} = \text{Id}_{\partial M}$   $q$  is also reg. val. for  $\partial f$ )

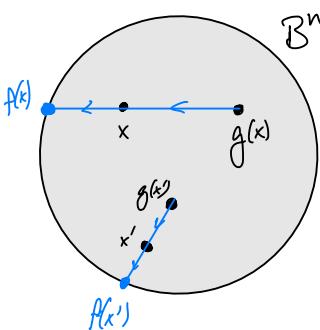
$\Rightarrow f^{-1}(q)$  is a submfld w/ bdry of  $B^n$  s.t.  $\xrightarrow{\text{single point}}$   
 $\partial(f^{-1}(q)) = f^{-1}(q) \cap \partial B^n = f^{-1}(q) \cap S^{n-1} = \{*\}$

But  $\dim f^{-1}(q) = 1 \Rightarrow$  we built a compact 1-dim  
mfld w/ bdry  $\cong \{q\}$   $\hookrightarrow // \hookleftarrow$

□

Smooth Brower Fixed Pt. Thm:  $\forall g \in C^0(B^n, B^n)$ ,  $\exists p$   $g(p) = p$

Pf: Contradiction: suppose  $g$  has no fixed points.



Extend the line  $g(x) \mapsto x$  to  $\partial B^n$

and obtain

$$f: x \longmapsto \overrightarrow{g(x)x} \cap \partial B^n$$

which is a smooth retraction.  $\hookrightarrow // \hookleftarrow$

$$f(x) = x + tu \text{ where } u = \frac{x - g(x)}{\|x - g(x)\|}$$

} since  $g$  is smooth  
and  $f$  is given by  
this smooth formula  
 $f$  is smooth

$t = \text{positive solution to a quadratic eq. w/ positive discriminant.}$

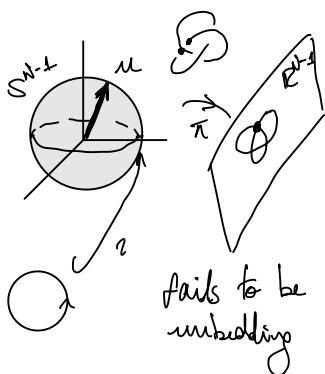
□

Pf: (BFPT) Weierstrass approx. of continuous  $\mathcal{B}^n$  by smooth maps, scaled slightly to fit in  $\mathbb{R}^n$ . □

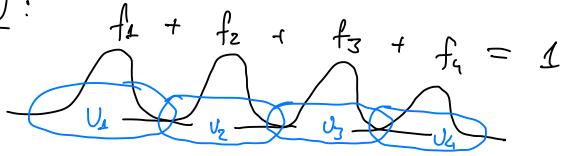
### APPLICATION OF SARD:

Thm: (Whitney Embedding Theorem) Any  $n$ -manifold can embed in  $\mathbb{R}^{2n+1}$ .

Idea of Pf: Construct  $N$  w/ partition of unity and get the dimensions down by studying when projections fail to give embeddings.



POU:



Thm: (Partitions of Unity) Given a regular covering of  $M$   $\{(V_i, \varphi_i)\}$ , if  $\{f_i\}$  partition of unity subordinate to this covering s.t.  $f_i > 0$  on  $V_i \subset \varphi_i^{-1}(B_\circ(1))$  and  $\text{supp } f_i \subset \overline{\varphi_i^{-1}(B_\circ(2))}$ .

Def: A regular covering is a <sup>locally finite (i.e., each  $x \in M$  covered by finitely many charts)</sup> open cover  $\{(U_i, \varphi_i)\}$  of  $M$  by coord. charts s.t.  $\varphi_i(U_i) = \mathbb{B}_o(3)$  and  $V_i = \varphi_i^{-1}(B_o(1))$  also form a covering.

Def: A POU subordinated to cover  $\{(U_i, \varphi_i)\}$  is a collection  $(f_i : M \xrightarrow{\text{C}} [0,1])$  s.t. (1)  $\text{Supp } f_i = \overline{\varphi_i^{-1}(B_o(3))} \subset \varphi_i^{-1}(B_o(2))$

only makes sense on the loc. finite case since only finitely many  $f_i$ 's are  $\neq 0$

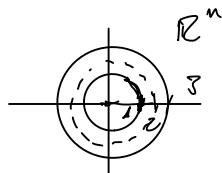
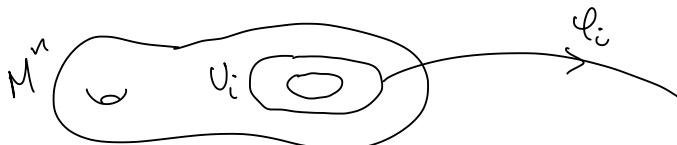
## LECTURE 18

Nov 21<sup>st</sup>, 2024

same idea for non-compact  
but more bookkeeping.

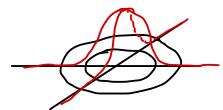
\* WHITNEY EMBEDDING: Let  $M^n$  be compact mfld.

Idea: Start w/ P.O.U. :



Adapted POU  
 $f_i$

Regular covering of  $M^n$ :  $U_i \rightarrow \mathbb{B}_o(3)$   
 $V_i \rightarrow \mathbb{B}_o(1)$



1. Extend charts  $\cup_i \cap_M U_i \xrightarrow{\varphi_i} \mathbb{R}^n$  to maps  $M \rightarrow \mathbb{R}^n$  by doing

$$f_i \varphi_i := \begin{cases} f_i \varphi_i, & \text{for } x \in U_i \\ 0, & \text{else} \end{cases}$$

This map is going to be an embed. on  $U_i$  but not anywhere else.

2. If we exit  $U_i$  and enter  $U_j$ , pass below to  $f_j \varphi_j$ .

i.e.: for a covering  $\{U_i\}_{i=1}^N$ , define

$$\begin{aligned} M &\longrightarrow \mathbb{R}_1^n \times \mathbb{R}_2^n \times \dots \times \mathbb{R}_N^n \\ x &\longmapsto (f_1 \varphi_1(x), f_2 \varphi_2(x), \dots, f_N \varphi_N(x)) \end{aligned}$$

3. But to make this into an embedding, we need more information: define  $\Phi: M \rightarrow (\mathbb{R}^n)^N \times \mathbb{R}^N = \mathbb{R}^{N(n+1)}$

$$\Phi(x) := (f_1 \varphi_1(x), \dots, f_N \varphi_N(x), \underbrace{f_1(x), \dots, f_N(x)}_{\text{Bookkeeping information}})$$

Bookkeeping information  
to track in which open set  $x$  lies in.

Claim:  $\Phi$  is injective

Pf: If  $\Phi(x) = \Phi(y) \Rightarrow$  for some  $i$ ,  $f_i(x) = f_i(y) \neq 0$   
 $\Rightarrow x, y \in U_i$  and  $f_i \varphi_i(x) = f_i \varphi_i(y)$   
 $\Rightarrow x = y$  b/c  $\varphi_i$  is injective (coor. map)  $\square$

Claim:  $\Phi$  is an immersion

Pf: Check  $D\Phi: T_p M \rightarrow \mathbb{R}^{N(n+1)}$  is injective

$$D_x \Phi(v) = \left( D_x f_1(v) \varphi_i(x) + f_1(x) D_x \varphi_i(x), \dots, D_x f_n(v), \dots \right)$$

If  $D_x \Phi(v) = 0$ , must have  $D_x f_i(v) = 0 \ \forall i$ . Plugging this into the first part  $\Rightarrow f_i(x) D_x \varphi_i(v) = 0 \ \forall i$

$\Rightarrow$  for some  $i$ ,  $f_i(x) \neq 0 \quad x \in U_i$

$\Rightarrow D_x \varphi_i(v) = 0 \Rightarrow v = 0$

$\uparrow$   
 $\varphi_i$  coord. charts

□

Claim:  $\Phi$  embedding

Pf:  $\Phi$  injective immersion.

$\Phi$  homo. b/c it's injective on a compact Hausdorff space.

Upshot: Can embed  $\mathbb{RP}^2 \xrightarrow{\text{emb.}} \mathbb{R}^9 \xleftarrow{\substack{(2+1) \cdot (2+1) \\ \# \text{ of charts on atlas for } \mathbb{RP}^2}}$  as above

Actually can reduce  $\mathbb{RP}^2 \xrightarrow{\text{emb.}} \mathbb{R}^5$

$\xrightarrow{\text{emb.}}$   
Surgery theory  $\xrightarrow{\text{emb.}} \mathbb{R}^4$

Thm: Any manifold  $M$  embeds into  $\mathbb{R}^{2 \dim M + 1}$  ( $\mathbb{R}^{2 \dim M}$  actually)

Pf: Here, assume  $M$  is compact (see notes for generalization)

Strategy: 1. Embed  $M \hookrightarrow \mathbb{R}^N$  using previous result

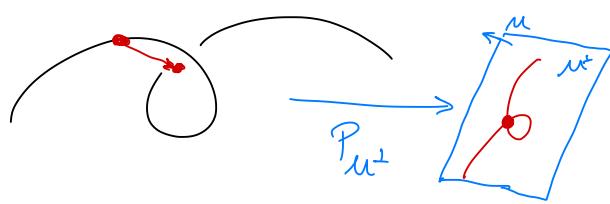
2. Show that, if  $N > 2\dim M + 1$ ,  $\exists$  directions  $\mu \in S^{N-1}$  s.t. projections to  $\perp \mu$  is an embedding. Use Sard's Thm to show that the bad directions are measure  $0$ .

Q: What makes a direction bad?

- (i) Failure of injectivity of  $P_{\mu^\perp} \circ \Phi : M \rightarrow \mathbb{R}^{N-1}$
- (ii) Failure of injectivity of the derivative

WTS: Both these failures only occur on sets of measure  $0$  in the sphere  $S^{N-1}$ .

(i) This failure occurs when  $\exists (x, y) \in M \times M \setminus \Delta$  s.t.



$$\frac{\Phi(y) - \Phi(x)}{\|\Phi(y) - \Phi(x)\|} = \mu$$

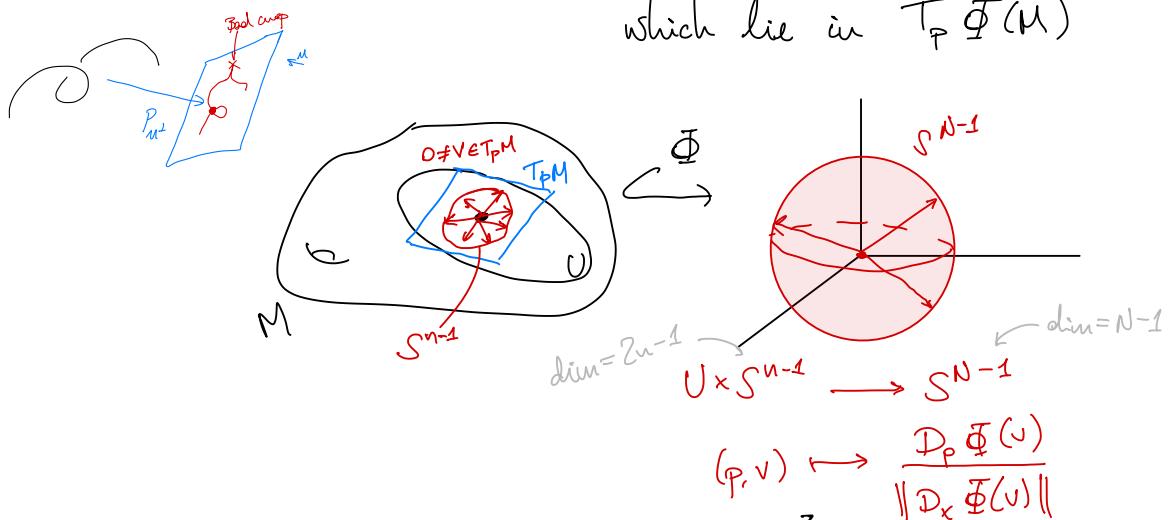
i.e.:  $P_{\mu^\perp} \circ \Phi$  fails injectivity when  $\mu \in S^{N-1}$  is in the image of the map:

$$\begin{aligned} M \times M \setminus \Delta &\longrightarrow S^{N-1} && \text{← } N-1 \text{ dim} \\ (x, y) &\longmapsto \frac{\Phi(y) - \Phi(x)}{\|\Phi(y) - \Phi(x)\|} \end{aligned}$$

Sard: Image has measure of  $2n < N-1$

$\Rightarrow$  Embedding into  $N = \mathbb{S}^{n+1}$  is the best we can do here.

(ii) Failure of injectivity of  $D(P_{M^{\perp}} \circ \Phi)$  occurs for  $u \in S^{N-1}$  which lie in  $T_p \Phi(M)$



Immersion fails on image of this  $\rightarrow$

Sard: immersion fails on a measure zero set if

$$2n - l < N - 1 ; \text{ i.e., } 2n < N$$

Upshot :  $\begin{cases} \text{Embed into } \mathbb{R}^{2\dim M + 1} \\ \text{Immense into } \mathbb{R}^{2\dim M} \end{cases}$

□

————— 1 —————

\* TUBULAR NEIGHBORHOODS (for embeddings  $M \hookrightarrow \mathbb{R}^N$ )

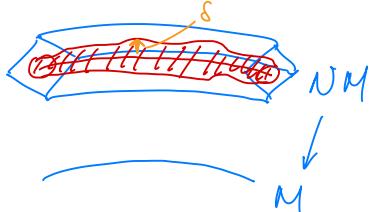
Thm: Every submanifold  $M$  of  $\mathbb{R}^N$  has a tubular nbhd.

i.e.,  $U$  open nbhd of  $M$  which is diffeom. to the

image of a solid cylinder in NM (normal bundle)

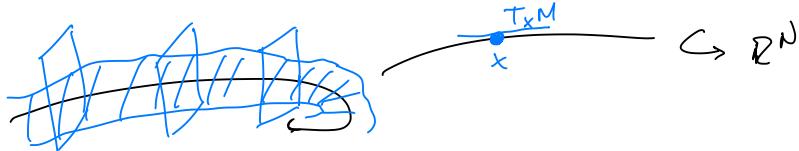
- Each point  $x \in M$  has a normal space  $N_x = \mathbb{R}^N / T_x M = T_x M^\perp$

$\Rightarrow$  Form a vector bundle  $NM$   
called the NORMAL BUNDLE



- Solid cylinder: Given  $\delta: M \rightarrow \mathbb{R}_{>0}$

$$V = \{(v, y) \in NM : \|v\| < \delta\}$$



Map  $V \rightarrow \mathbb{R}^N$       Since  $V \cong$  cylinder

$$(y, v) \mapsto \Phi(y) + v$$

$$V \xrightarrow[r]{\text{retraction}} M$$

$$(y, v) \mapsto y$$

$$V \xleftarrow[\text{inclusion}]{i} M$$

$$(y, 0) \leftarrow y$$

$$r \circ i = \text{Id}_M$$

### Importance of this:

\*  $f: M \rightarrow N$  may not be transverse to  $g: K \rightarrow N$ .

To modify  $f$  into a map which is transverse to  $g$ ,  
need to put  $f$  in a family of maps

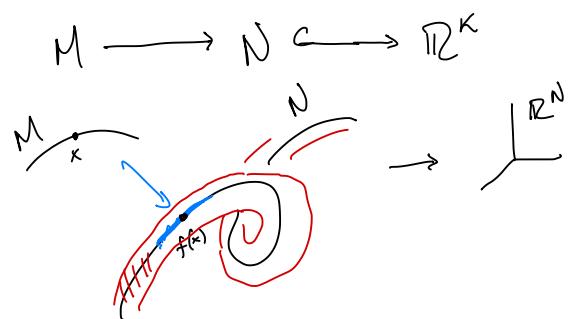
tangent space of  $f(M)$  in  $N$  not enough for  
 $d_f$ , but we can add more directions by

$F: M \times S \rightarrow N$  s.t.  $F|_{M \times \{0\}}: M \rightarrow N = f$   
 $s_0 \in S$  and  $F \pitchfork g$ .  $\Leftrightarrow \exists s \in S$  for which  $f_s \pitchfork g$ .

Q: How to deform  $f$  in this family  $F: M \times S \rightarrow N$  to make it

transverse to  $g$ ?

A: Given  $f: M \rightarrow N$ , embed  $N$  in  $\mathbb{R}^k$



$S = B^k$  open ball in  $\mathbb{R}^k$   
use this to translate  
 $F(x, s) = r(f(x) + s)$   
retraction of tubular nbhd

## LECTURE 19

Nov 22<sup>nd</sup>, 2024

\* VECTOR BUNDLES ( $\subseteq$  fiber bundles)

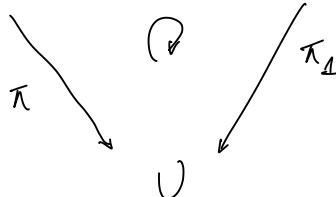
Def:

$E$   $\pi =$  bundle projection submersion

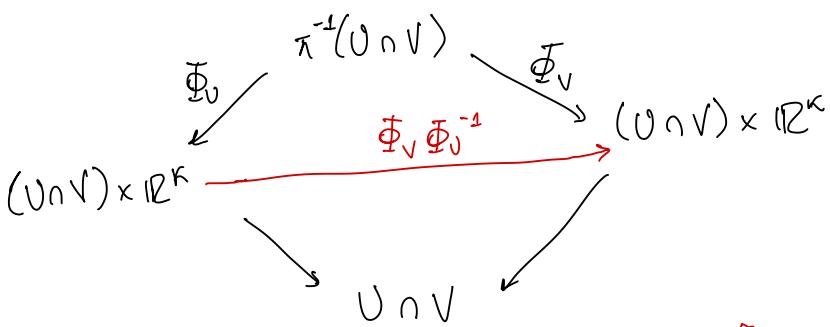
$\pi \downarrow$  st.  $\forall p \in M \exists$  nbhd  $U$  and  $\Phi$  homeo s.t. the

$M$

$\pi^{-1}(U) \xrightarrow{\Phi} U \times \mathbb{R}^k$  diagram commutes



Overlap: if  $U, V$  are such nbhds w/  $\Phi_U, \Phi_V$  resp. Then



$\Phi_U \Phi_V^{-1}$  = "transition function":  $U \cap V \xrightarrow{C^\infty} GL(n, \mathbb{R})$

Construction: To build a vector bundle over  $M$

1. Build  $M$  from opens  $\{U_i \subset \mathbb{R}^k\}$  via gluing maps  $(U_j \xrightarrow{\Phi_{ij}} U_i)$  diffo.

2. Provide  $g_{ij}: U_i \cap U_j \rightarrow GL(n, \mathbb{R})$  and define

$$E := \bigcup_{i \in I} (U_i \times \mathbb{R}^k) / \left\{ \begin{array}{l} (x, u) \sim (y, v) \\ y = g_{ij}(x) \\ v = g_{ij}(x)u \end{array} \right.$$

Equiv.-relation b/c  
we have  $g_{ik} g_{kj} = g_{ik}$   
and  
 $g_{jk} g_{kj} = g_{jk}$

cocycle condition  
(nonabelian 1-cocycle)

Ex:  $S^2 = U_0 \cup U_1$ . A vector bundle over  $S^2$



is obtained by choosing

$$g_{01}: U_0 \cap U_1 \rightarrow GL(2, \mathbb{R})$$

$$U_0 \cap U_1 = \mathbb{R}^2 \text{ for } = \mathbb{C}^*$$



$$\text{e.g.: } g_{01}(z \in \mathbb{C}^*) = r^n \begin{pmatrix} \cos n\theta & -\sin n\theta \\ \sin n\theta & \cos n\theta \end{pmatrix} = [z^n]$$

$n = \# \text{ of times this* plane turns as it goes around}$

$$\overset{\star}{GL}(2, \mathbb{R})$$

$$GL(1, \mathbb{C})$$

the intersection before it's identified w/ the bottom plane

$\Rightarrow \mathbb{Z}$ -family of rank-2 vector bundles over  $S^2$ .

Rank: FB vs. VB



- FB: fiber type  $F$        $U_i \cap U_j \xrightarrow{g_{ij}} \text{Homeo}(F)$
- VB: fiber type  $\mathbb{R}^k$        $U_i \cap U_j \xrightarrow{g_{ij}} GL(k, \mathbb{R})$

Variants:

- Affine bundle: fiber type  $\mathbb{R}^k$  (as affine space)

$$U_i \cap U_j \xrightarrow{g_{ij}} \text{Aff}(\mathbb{R}^k) = GL(k, \mathbb{R}) \times \mathbb{R}^k$$

Right

• Principal  $G$ -bundle: fiber type  $G$  Lie group viewed as a right  $G$ -space

$$U_i \cap U_j \xrightarrow{g_{ij}} G \text{ (acting on the left)}$$

\* OPERATIONS ON VECTOR BUNDLES: "Any functor involving vec. spaces can be upgraded to  $VB \rightarrow M$ ".

e.g.: Duals

$$V \text{ finite-dim. } \mathbb{R}\text{-vec. space} \quad V^* \text{ dual} \quad V^* = \text{Hom}(V, \mathbb{R})$$

$$V \xrightarrow[\text{linear}]{} W \quad V^* \xleftarrow{f^*} W^* \quad (\text{contravariant functor})$$

If  $E$  is built from  $U_i \times \mathbb{R}^k$  and  $g_{ij}: U_i \cap U_j \longrightarrow GL(k, \mathbb{R})$

$$\pi \downarrow M$$

$$\downarrow U_i$$

Apply functor to

Inference is  
a conseq. of  
the contra-  
variance of  
dual functor

$$U_i \times (\mathbb{R}^k)^* \xrightarrow{(g_{ij}^*)^{-1}} U_j \times (\mathbb{R}^k)^*$$

get ↘

$\downarrow$                                      $\downarrow$   
 $U_i$                                      $U_j$

$$g_{ij} \longleftrightarrow E$$

$$(g_{ij}^*)^{-1} \longleftrightarrow E^*$$

dual VB

e.g.: Sum  $V, W \mapsto V \oplus W$

$$\begin{array}{ccc} f: V \rightarrow V' & \rightsquigarrow & f \oplus g: V \oplus W \rightarrow V' \oplus W' \\ g: W \rightarrow W' & & (v, w) \mapsto (f(v), g(w)) \end{array}$$

rank- $k$	rank- $l$
$E$	$E$
$\downarrow$	$\downarrow$
$M$	$M$
$g_{ij}$	$h_{ij}$
$U_i \rightarrow GL(n, \mathbb{R})$	$U_j \rightarrow GL(l, \mathbb{R})$

Direct sum VB

$E \oplus F$

$\downarrow$

$M$

$G_{ij} = \left( \begin{array}{c|c} g_{ij} & 0 \\ \hline 0 & h_{ij} \end{array} \right)$

e.g.: Tensor product  $V, W \mapsto V \otimes W$

$f: V \rightarrow V$   $\dim V = k$   $f \otimes g: V \otimes W \longrightarrow V \otimes W$

$g: W \rightarrow W$   $\dim W = l$   $\sum_{i,j} v_i \otimes w_j \mapsto \sum_{i,j} f(v_i) \otimes g(w_j)$

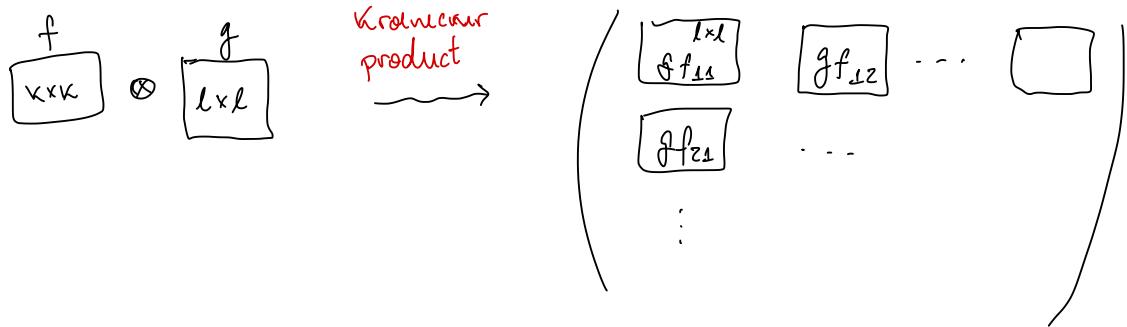
Bases  $(e_i^V), (e_i^W)$

for  $V, W$ .

as matrices  $f \otimes g$  "Kronecker product".

Basis for  $V \otimes W: (e_1^V \otimes e_1^W, e_1^V \otimes e_2^W, \dots, e_1^V \otimes e_l^W, e_2^V \otimes e_1^W, \dots)$

$$\dim V \otimes W = (\dim V)(\dim W) = k l$$



\* ASSOCIATED VB TO THE TANGENT BUNDLE

$M$   $C^\infty$  mfld  $\Rightarrow TM$  tangent bundle w/ transition fcts

$$U_i \times \mathbb{R}^n \longrightarrow U_j \times \mathbb{R}^n$$

$$(x, u) \longmapsto (q_{ij}(x), D_x q_{ij}(u))$$

$TM$  has many associated VBs:

Ex: COTANGENT BUNDLE

$T^* M$

$$g_{ij} = \left( (\partial_x \varphi_{ij})^* \right)^{-1}$$

Element of  $T_x^* M$  is a linear ft. on  $T_x M$ .

Ex:  $\underbrace{TM \otimes \cdots \otimes TM}_{k} \otimes \underbrace{T^* M \otimes \cdots \otimes T^* M}_{l} \leftarrow \text{rank } n^{k+l}$

$$g_{ij} = (\partial_x \varphi_{ij}) \otimes \cdots \otimes (\partial_x \varphi_{ij}) \otimes ((\partial_x \varphi_{ij})^*)^{-1} \otimes \cdots \otimes ((\partial_x \varphi_{ij})^*)^{-1}$$

[This is the bundle of  $(k, l)$ -tensors  
k - covariant  
l - contravariant]

Interpretation:  $\omega \in T_x^* M \otimes T_x^* M$  is a bilinear ft. on  $T_x M$

$$\begin{array}{c} \parallel \\ \Lambda^2 T_x^* M \oplus \underline{\text{Sym}^2 T_x^* M} \\ \text{skew-symmetric} \\ \text{bilinear forms} \qquad \qquad \qquad \text{symmetric bilinear} \\ \qquad \qquad \qquad \qquad \qquad \text{forms} \end{array}$$

Def: A section of VB  $E \xrightarrow{\pi} M$  is a  $C^\infty$  map  
 $s: M \rightarrow E$  s.t.  $\pi s = \text{Id}_M$

e.g.: Riem. manfolds - M  $C^\infty$  manfd

- g sym. bilinear form, positive def. on each tangent space varying over M

$g \in C^\infty(M, \text{Sym}^2 T^* M)$   $\longrightarrow$   $g$  is a  $(0, 2)$ -tensor

$\text{Sym}^2 T^* M = \text{VB}$  of symmetric 2-tensors  
 $\cap$

$T^* M \otimes T^* M$

$X, Y$  vec. fields  $\Rightarrow g(X, Y) \in C^\infty(M, \mathbb{R})$

$$g(X, Y)_x = g_x(X_x, Y_x).$$

E.g.: Symplectic Manifold

-  $M$   $C^\infty$  manfd

only possible when  $\dim M = \text{even}$

-  $\omega \in C^\infty(M, \Lambda^2 T^* M)$  nondegenerate skew-symmetric  
bilinear form on each tangent space (and  $\text{vol } d\omega = 0$ ).  
 $\uparrow$

E.g.: Complex Manifold

-  $M$   $C^\infty$  manfd

- Complex structure on each tangent space. Need to define  
multiplication by  $i$  to define this structure:

$I: T_x M \longrightarrow T_x M$  i.e.,  $I \in T_x^* M \otimes T_x M$

$I^2 = -\text{id}$  i.e.,  $I \in C^\infty(M, T^* M \otimes TM)$

only possible when  $\dim M = \text{even}$

s.t.  $I^2 = -\text{id}_{TM}$ .

(also need involutivity needed  
get complex coordinates on  $\mathbb{C}^n$ )

Ex: • Tensor algebra

$$\dim \otimes^* V = \infty$$

Non-commutative  
↓

Tautological product:

$$(a_1 \otimes \dots \otimes a_k) \cdot (b_1 \otimes \dots \otimes b_\ell) = a_1 \otimes \dots \otimes a_k \otimes b_1 \otimes \dots \otimes b_\ell$$

• Exterior algebra:  $\Lambda^* V = \otimes^* V$

$$\left/ \langle x \otimes x : x \in V \rangle \right.$$

↑

i.e., expressions w/  $a \otimes a$   
always get killed

$$(x+y) \otimes (x+y) = x \otimes x + x \otimes y + y \otimes x + y \otimes y = 0$$

$$\Rightarrow x \otimes y = -y \otimes x$$

↓

That's why we call  $\Lambda^* V$  a graded commutative algebra (b/c it's almost commutative except for a minus sign).

$$\dim V = n$$

$$\Lambda^* V = (\mathbb{R} = \Lambda^0 V) \oplus V \oplus \Lambda^2 V \oplus \Lambda^3 V \oplus \dots \oplus \Lambda^n V \oplus 0 \oplus 0 \oplus \dots$$

$$\begin{array}{cccc} 1 & e_1 & e_1 \wedge e_2 & e_1 \wedge e_2 \wedge e_3 \\ e_n & e_1 \wedge e_3 & i < j < k & e_1 \wedge \dots \wedge e_n \\ & & & 1-\text{dim} \end{array}$$

$$\begin{array}{c}
 e_2 \wedge e_3 \\
 e_2 \wedge e_4 \\
 \vdots \\
 e_3 \wedge e_4 \\
 \vdots \\
 \downarrow \\
 e_i \wedge e_j \\
 i < j
 \end{array}
 \quad \dim \Lambda^{\bullet} V = 2^n$$

$\mathbb{Z}$ -Graded b/c  $\Lambda^{\bullet} V = \bigoplus_{k \in \mathbb{Z}} \Lambda^k V$  and

commutative

algebra

$$\alpha, \beta \text{ deg } \kappa, l \rightarrow \deg(\kappa \wedge l) = \kappa + l$$

$$\alpha \wedge \beta = (-1)^{(\deg \alpha)(\deg \beta)} \beta \wedge \alpha$$

## LECTURE 20

Nov 28<sup>th</sup>, 2024

\* Differential Forms:  $M$   $C^\infty$  manifold.

diff.  $k$ -forms

Differential graded commutative algebra:  $\Omega^{\bullet}(M) = \bigoplus_{k \geq 0} \Omega^k(M)$

$$\text{where } \Omega^k(M) = C^\infty(M, \Lambda^k T^* M).$$

The product in this algebra is the wedge product:  $\alpha \wedge \beta$ .

non zero only for  
 $k=0, 1, \dots, \dim M$

$$\text{Note: } \alpha \wedge \beta = (-1)^{(\deg \beta)(\deg \alpha)} \beta \wedge \alpha$$

\* **THE DIFFERENTIAL**: In degree-0, we have

$$\Omega^0(M) = C^\infty(M, \Lambda^0 T^*M) = C^\infty(M, \mathbb{R})$$

ψ

$$f: M \rightarrow \mathbb{R}$$

$$Df: TM \rightarrow T\mathbb{R} = \mathbb{R} \times \mathbb{R}$$

$$(x, v) \mapsto (f(x), D_x f(v))$$

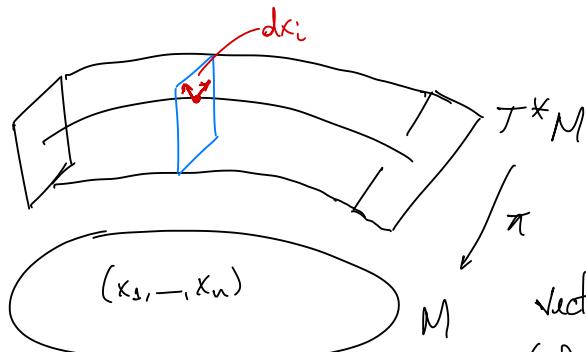
$v \mapsto D_x f(v)$  is a linear ft. on  $T_x M$

Def:  $\pi_2 \circ Df =: df$  is a smooth section of  $T^*M$   
i.e.,  $df \in \Omega^1(M) = C^\infty(M, \Lambda^1 T^*M)$ .

$$\Omega^0(M) \xrightarrow{d} \Omega^1(M) \text{ de Rham operator (exterior derivative)}$$

In local coordinates:  $(x_1, \dots, x_n)$  coords  $(x_i: M \rightarrow \mathbb{R})$

have derivatives  $(dx_1, \dots, dx_n)$ ,  $dx_i \in \Omega^1(M)$ .



For  $f \in \Omega^0(M)$ ,

$$df = a_1 dx_1 + \dots + a_n dx_n,$$

$$a_i \in \Omega^0(M)$$

How to find these  $a_i$ ? Use vector fields! They have a basis  $\left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n}\right)$  (sections of TM).

Duality pairing:  $df \left( \frac{\partial}{\partial x_k} \right) = a_k$

$$\frac{\partial f}{\partial x_k}$$

Upshot: In coordinates,

$$df = \sum_{k=1}^n \left( \frac{\partial f}{\partial x_k} \right) dx_k$$

Cor:  $df = 0 \Rightarrow f$  is constant on each connected component of  $M$ .

From this, can define the general exterior derivative.

Def:  $d: \Omega^\bullet(M) \rightarrow \Omega^\bullet(M)$  is the unique graded derivation of deg + 1 s.t.  $df$  is as above (i.e.,  $df(X) = X(f)$ ) for  $f \in \Omega^0(M)$ ; and  $d(df) = 0$   $\forall f \in \Omega^0(M)$ .

$$0 \xrightarrow{d} \Omega^0(M) \xrightarrow{d} \Omega^1(M) \xrightarrow{d} \Omega^2(M) \xrightarrow{d} \dots \xrightarrow{d} \Omega^n(M) \xrightarrow{d} 0$$

Graded Derivation: Leibniz rule  $\text{deg } d = +1 \text{ always}$

$$d(\alpha \wedge \beta) = (d\alpha) \wedge \beta + (-1)^{|d||\alpha|} \alpha \wedge (d\beta)$$

To show this exists, we can explicitly compute it in coordinates: let  $\rho = \sum_{k=1}^n \xi_k dx_k \in \Omega^1(M)$ ,  $\xi_k \in \mathcal{L}^0(M)$ .

then

$$\begin{aligned} d\rho &= d\left(\sum_{k=1}^n \xi_k dx_k\right) \\ &= \sum_{k=1}^n \left( (d\xi_k) \wedge dx_k + \underbrace{\xi_k d(dx_k)}_{\stackrel{(-1)^k}{=} (-1)^{k+0} = +1} \right) \\ &= \sum_{k=1}^n \left( \sum_{j=1}^n \frac{\partial \xi_k}{\partial x_j} dx_j \right) \wedge dx_k \end{aligned}$$

$$d\rho = \sum_{j < k} \left( \frac{\partial \xi_k}{\partial x_j} - \frac{\partial \xi_j}{\partial x_k} \right) dx_j \wedge dx_k$$

Now, take a general  $n$ -form  $\rho \in \Omega^n(U)$ , where the coords. in  $U$  are  $(x_1, \dots, x_n)$ . Then we can write

$$\rho = \sum_{i_1 < i_2 < \dots < i_n} \rho_{i_1, \dots, i_n}^{e \mathcal{L}^0(M)} dx_{i_1} \wedge \dots \wedge dx_{i_n}$$

$$d\rho = \sum_{l=1}^n \left( \sum_{i_1 < \dots < i_n} \frac{\partial \rho_{i_1, \dots, i_n}}{\partial x_l} dx_l \wedge dx_{i_1} \wedge \dots \wedge dx_{i_n} \right) \in \Omega^{n+1}(M)$$

In order for the df. of  $d: \mathcal{Q}^*(M) \rightarrow \mathcal{Q}^*(M)$  to be well-defined, we need to check that the proposed operator (\*) satisfies ① + ② + ③.

② Clear

$$\begin{aligned}
 ③ d(df) &= d\left(\sum_n \frac{\partial f}{\partial x_n} dx_n\right) = \sum_n \left(d\left(\frac{\partial f}{\partial x_n} dx_n\right)\right) \\
 &= \sum_n \left(d\left(\frac{\partial f}{\partial x_n}\right) \wedge dx_n + \overset{\text{1. D. } (\text{1st})}{\left(\frac{\partial f}{\partial x_n}\right)} \wedge d(dx_n) \overset{=0}{\longrightarrow}\right) \\
 &= \sum_n \sum_{k < l} \frac{\partial^2 f}{\partial x_k \partial x_l} dx_k \wedge dx_l \\
 &= \sum_{n < l} \left(\frac{\partial^2 f}{\partial x_n \partial x_l} - \frac{\partial^2 f}{\partial x_l \partial x_n}\right) dx_n \wedge dx_l = 0.
 \end{aligned}$$

① For  $f, g \in \mathcal{Q}^*(M)$ ,

$$\begin{aligned}
 d\left((f dx_{i_1} \wedge \dots \wedge dx_{i_p}) \wedge (g dx_{j_1} \wedge \dots \wedge dx_{j_q})\right) \\
 = d(fg) dx_{i_1} \wedge \dots \wedge dx_{i_p} \wedge dx_{j_1} \wedge \dots \wedge dx_{j_q}
 \end{aligned}$$

use fact:  $d(fg) = (df)g + f(dg)$  (old Liebniz rule)

$$\begin{aligned}
&= f dg \wedge dx_{i_1} \wedge \dots \wedge dx_p \wedge dx_{j_1} \wedge \dots \wedge dx_q \\
&\quad + g df \wedge dx_{i_1} \wedge \dots \wedge dx_p \wedge dx_{j_1} \wedge \dots \wedge dx_q \\
&= d(f dx_{i_1} \dots dx_{i_p}) \wedge g dx_{j_1} \dots dx_{j_q} \\
&\quad + (-1)^P f dx_{i_1} \dots dx_{i_p} \wedge d(g dx_{j_1} \dots dx_{j_q})
\end{aligned}$$

Thm:  $d^2 = 0$ .

Pf:  $d$  graded derivation  $\Rightarrow d \in \text{Der}^4(\Omega^\bullet, \wedge)$ .  
 Derivations are closed under commutator (i.e., they form a Lie algebra).

$$D_1 \in \text{Der}^{d_1}, D_2 \in \text{Der}^{d_2}$$

$$[D_1, D_2] := D_1 \circ D_2 - (-1)^{d_1 d_2} D_2 \circ D_1 \quad (\text{Graded commutator})$$

Exercise:  $[D_1, D_2] \in \text{Der}^{d_1+d_2}$ .

Pf: Take  $\alpha, \beta$ ,  $[D_1, D_2](\alpha \wedge \beta) = D_1 D_2(\underbrace{\alpha \wedge \beta}_{\text{Liebniz}}) - (-1)^{d_1 d_2} D_2 D_1(\alpha \wedge \beta)$

$$[d, d] = d \circ d - (-1)^{1 \cdot 1} d \circ d = 2d^2$$

$\Rightarrow d^2$  is a graded derivation of degree 2.

$\Rightarrow$  Suffices to check

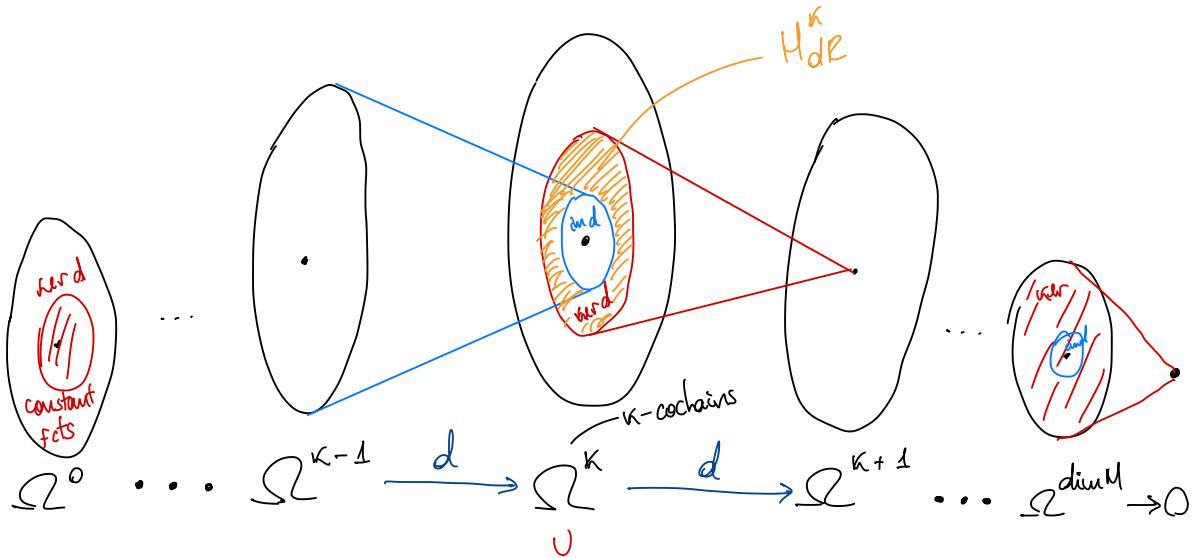
$d^2 = 0$  on forms of type  $f \in \Omega^0$   
 $dg, g \in \Omega^0$ .

local generators for  $\Omega^0$

But  $d^2 f = 0$  by def. (\*)

$$d^2(dg) = d(d^0g) = d(0) = 0.$$

CONSEQUENCE OF  $d^2 = 0$ :  $\text{im } d \subset \ker d$  b/c  $d^2 = 0$



dual terminology  
to  $\partial$  boundary for  
mfds, and sing. homology

$$\begin{aligned} (\ker d) \cap \Omega^k &= k\text{-cocycles} \\ (\text{im } d) \cap \Omega^k &= k\text{-coboundaries} \end{aligned}$$

↳  
Leads to definition



Def: The de Rham cohomology is the graded algebra given by

$$H_{dR}^{\bullet}(M) := \bigoplus_{k=0}^{\dim M} \left( \frac{\ker d \cap \Omega^k}{\text{im } d \cap \Omega^k} \right) \cong H_{dR}^k(M)$$

Topological invariant of spaces.

## LECTURE 21

Nov 29<sup>th</sup>, 2024

Differential forms:  $\rho \in \Omega^k(M)$  can be written locally as

$$\rho_{loc} = \sum p_{i_1, \dots, i_k} dx^{i_1} \wedge \dots \wedge dx^{i_k}$$

$M \rightsquigarrow$  diff. commutative graded algebra  $(\Omega^{\bullet}(M), \wedge, d)$

$M \rightarrow C^{\infty}(M, \mathbb{R})$  comm. alg.

$$F^*(f) = f \circ F$$

Pull-back:  $N \longmapsto C^{\infty}(N, \mathbb{R})$

$$F \uparrow \qquad \downarrow F^*$$

$$M \longmapsto C^{\infty}(M, \mathbb{R})$$

$$\begin{array}{ccc} \mathbb{R} & & \mathbb{R} \\ \uparrow & & \uparrow \\ M & \xrightarrow{F} & N \\ C^{\infty}(M, \mathbb{R}) & \xleftarrow{F^*} & C^{\infty}(N, \mathbb{R}) \end{array}$$

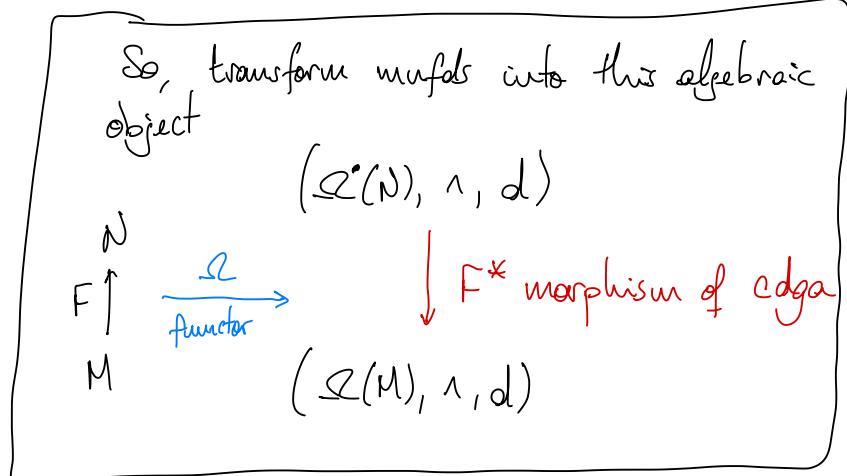
$$\begin{array}{ccc}
 \Lambda^k T^* M & \leftarrow & \Lambda^k T^* N \\
 \downarrow & & \downarrow \\
 M & \xrightarrow{F} & N
 \end{array}$$

$F^* p$   
 pullback  
 of  $p$

$\rho \in \mathcal{Q}^k(N)$

$$TM \xrightarrow{DF} TN$$

$$T^*M \xleftarrow{DF^*} T^*N$$



In local coordinates:

$$\begin{array}{ccc}
 M & \xrightarrow{F} & N \xrightarrow{R} y = F(x) \\
 x_i & & y_j \\
 & & \text{basis } dy_i \text{ for } \mathcal{Q}^1(N)
 \end{array}$$

$$F^* dy_i = \sum_{j=1}^n \frac{\partial F_i}{\partial x_j} dx_j$$

↑  
 entries of Jacobian of  $F$   
 (i.e., of  $DF$ );  $F_i = y_i \circ F$

So, for  $\rho \in \mathcal{Q}^k(N)$ ,

$$F^*(\rho_{j_1 \dots j_k}(y) dy_{j_1} \wedge \dots \wedge dy_{j_k})$$

$$= (\rho_{j_1 \dots j_k} \circ F)(x) \sum_{i_1} \dots \sum_{i_k} \left( \frac{\partial y_{j_1}}{\partial x_{i_1}} \dots \frac{\partial y_{j_k}}{\partial x_{i_k}} \right) dx_{i_1} \wedge \dots \wedge dx_{i_k}$$

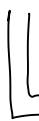
$$dy_{j_s} = \frac{\partial F_{j_s}}{\partial x_1} dx_1 + \dots + \frac{\partial F_{j_s}}{\partial x_n} dx_n$$

$$= \sum_{i_1 < \dots < i_k} \begin{pmatrix} k \times k \text{ minor} \\ \text{of } DF \end{pmatrix} dx_{i_1} \wedge \dots \wedge dx_{i_k} \quad dy_{j_s} = \frac{\partial F_{j_s}}{\partial x_1} dy_1 + \dots + \frac{\partial F_{j_s}}{\partial x_n} dy_n$$

Remark: If  $F$  is a diff. map,  $DF$  is  $n \times n$ , then

$$F^*(dy_1 \wedge \dots \wedge dy_n) = (\det DF) \underbrace{dx_1 \wedge \dots \wedge dx_n}_{\text{top degree}}$$

Jacobian determinant



Integration is well-defined on manifolds !

Recall: Change of Variables Formula

$$\int f(y) dy_1 \wedge \dots \wedge dy_n \stackrel{y=y(x)}{=} \int f(y(x)) \left| \det \frac{\partial y_i}{\partial x_j} \right| dx_1 \wedge \dots \wedge dx_n$$

For these 2 formulas to agree, need  $F$  to "preserve orientation" i.e., need  $\det DF > 0$ .



Def: Let  $M$  be an  $n$ -dim manifold. It is orientable when the line bundle  $\Lambda^n T^* M \cong M \times \mathbb{R}$ .

An orientation is an equivalence class of nonvanishing section  $v \in \Omega^n(M)$  where  $v' \sim v$  if  $v' = e^f v$ , for  $f \in C^\infty(M, \mathbb{R})$ .

$M$  is oriented when it's endowed w/ orientation  $(M, [v])$ .

Cor: If  $M$  is oriented, we can cover  $M$  with charts  $U_i$  s.t. the gluing maps  $\varphi_{ij}$  have positive Jac. det.

Pf: For each chart  $\varphi_i: U_i \rightarrow \mathbb{R}^n$

$\varphi_i^*(dx_1 \wedge \dots \wedge dx_n)$  — if this is in  $[v]$  OK ✓

↖ if this is in  $[-v]$ , change the sign of first entry of  $\varphi_i$ :

$$\begin{pmatrix} -1 & 1 & 0 \\ 0 & 1 & \dots \\ 0 & 0 & 1 \end{pmatrix} \circ \varphi_i .$$

Upshot: For  $M$  oriented, have a well-defined INTEGRAL

Def: Let  $(M^{(j)})$  be an oriented  $n$ -mfld. The integral is the unique linear map  $\int: \Omega_c^n(M) \xrightarrow{\text{compact supported forms}} \mathbb{R}$  s.t. it

is compatible with the usual Lebesgue integral in  $\mathbb{R}^n$  i.e., if  $h: V \subset \mathbb{R}^n \xrightarrow{\text{diff}} U \subset M$  is orientation preser-

vary (i.e.,  $h^* v \sim [\mathrm{d}x_1 \wedge \cdots \wedge \mathrm{d}x_n]$ ) and if  $\alpha \in \Omega_c^n(M)$  with support in  $U$ , then  $\int_M \alpha = \int_{\mathbb{R}^n} h^* \alpha$

\* We cannot integrate functions on manifolds. □  
We can only integrate top-degree forms □

Pf: Idea: • Use property to write unique expression for  $\int$   
• Prove it satisfies claim

If  $\alpha \in \Omega_c^n(M)$  choose oriented atlas  $(U_i, \varphi_i)$   
" P.O.U.  $\psi_i$  subordinate to  $(U_i, \varphi_i)$

$$\alpha = \left( \sum_i \psi_i \right) \alpha = \sum_i \psi_i \alpha$$

$$\int \alpha = \sum_i \int \psi_i \alpha = \sum_i \int_{\varphi_i(U_i)} (\varphi_i^{-1})^* \psi_i \alpha$$

Prove this satisfies the properties.

□

- Each nonvanishing element  $v \in \Omega^n(M)$  defines a measure (or volume form) on  $M$

$$\Omega^0(M) \ni f \mapsto \int_M f v \quad \text{makes sense}$$

e.g.: if a Riemannian metric is chosen on an oriented  $M \Rightarrow$  obtain a canonical  $\nu \in \mathcal{L}^n(M)$  "volume" measure (usually called vol)

STOKES' THEOREM: Let  $M$  be an  $n$ -mfld with boundary  $\partial M$ . Let  $[v]$  be an orientation on  $M$ , which induces an orientation on  $\partial M$  using outward convention.

Let  $\rho \in \mathcal{L}^{n-1}(M)$ , then

Make precise:  $\imath_0: \partial M \hookrightarrow M$  submfld

$$\int_M d\rho = \int_{\partial M} \overset{\leftarrow}{\rho} = \int_{\partial M} \imath_0^* \rho$$

Rmk: This shows the duality between  $d \leftrightarrow \partial$ .

Cor 1: If  $\partial M = \emptyset$ , then  $\int_M d\rho = 0 \quad \forall \rho \in \mathcal{L}^{n-1}(M)$ .

Cor 2: If  $\partial M = \emptyset$  and  $v$  is a volume form,  $v \in \mathcal{L}^n(M)$ , then, using orientation  $[v]$ ,  $\int_M v > 0$

$\Rightarrow v$  cannot be in the image of  $d$

$\Rightarrow [v] \neq 0$  in  $H_{dR}^n(M)$ .

Philosophy: may think of  $\mathcal{L}^k(M)$  as follows:

$\mathcal{L}^0$  evaluate on points (functions on pts)

$\mathcal{L}^1$  function on 1-dimension embedded submanifolds

e.g., 1-form on  $M$  can  
be pulled back to, say, a circle  
and we can integrate it there  
b/c, there, it's a top form



$\vdots$   
 $\mathcal{L}^k$  functions on maps from  $k$ -dim. domains

$\vdots$   
 $\mathcal{L}^n$

\* MAYER - VÉTOZIS: Method for computing  $H_{dR}^*(M)$   
(local-to-global)

Main Input      Partition of unity

Poincaré Lemma:  $H_{dR}^k(\mathbb{R}^n) = \begin{cases} \mathbb{R}, & k=0 \\ 0, & \text{else} \end{cases}$

$k=0, H_{dR}^0(\mathbb{R}^n)$   
is just cont. fcts.  
 $\mathbb{R}^n$  is convex

Lemma: If  $f, g: M \rightarrow N$  are homotopic i.e.,  $\exists H: [0,1] \times M \xrightarrow{\text{C}^\infty} N$   
then the pullback morphisms  $f^*, g^*$  are  $H(0, -) = f, H(1, -) = g$   
chain homotopic i.e.,  $\exists$  homotopy  $K$  between them

$$\begin{array}{ccccc}
 \mathcal{Q}^{k-1}(M) & \xrightarrow{d} & \mathcal{Q}^k(M) & \xrightarrow{d} & \mathcal{Q}^{k+1}(M) \\
 f^* \uparrow \quad \uparrow g^* & \nearrow K & f^* \uparrow \quad \uparrow g^* & \nearrow K & f^* \uparrow \quad \uparrow g^* \\
 \mathcal{Q}^{k-1}(N) & \xrightarrow{d} & \mathcal{Q}^k(N) & \xrightarrow{d} & \mathcal{Q}^{k+1}(N)
 \end{array}$$

i.e.,  $K: \mathcal{Q}^k(N) \rightarrow \mathcal{Q}^{k-1}(M)$   
(degree  $k = -1$ )  
s.t.  
 $f^* - g^* = Kd + dK$

e.g.: if  $\alpha \in \mathcal{Q}^k(N)$ ,  $d\alpha = 0$ , then  $f^*\alpha, g^*\alpha$  are closed  
 $d(f^*\alpha) = d(g^*\alpha) = 0$ . But note:

$$(f^* - g^*) = (Kd + dK)\alpha = d(K\alpha)$$

$\Rightarrow f^* - g^*$  is exact

$$\Rightarrow [f^*\alpha] = [g^*\alpha] \text{ in } H_{dR}^k(M)$$

Cor: If  $f, g$  are homotopic  $\Rightarrow$  induced maps  $f^*, g^*$  on  $H_{dR}^\bullet$  agree

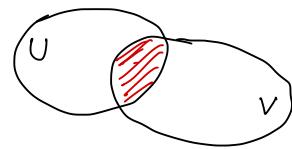
Cor: If  $M, N$  are homotopic  $\Rightarrow H_{dR}^\bullet(M) \cong H_{dR}^\bullet(N)$ .

$$\begin{array}{ccc}
 M & \xrightarrow{\text{functor}} & (\mathcal{Q}^\bullet(M), \wedge, d) & \xrightarrow{\text{functor}} & (H_{dR}^\bullet(M), \wedge) \\
 \text{mfds} & & \text{cdga} & & \text{cga} \\
 & & & \downarrow & \\
 & & & d=0 \text{ here...} &
 \end{array}$$

MAYER - VIETORIS SEQUENCE: Suppose  $M = U \cup V$  (e.g.:  $S^n = U_N \cup U_S$ )

$$\begin{array}{ccc} U & \xleftarrow{\partial_U} & U \cap V \\ \downarrow \imath_U & & \downarrow \partial_V \\ M & \xleftarrow{\imath_W} & V \end{array}$$

Apply  $\mathcal{Q}^\bullet$



$$\begin{array}{ccc} \mathcal{Q}^\bullet(U) & \xrightarrow{\partial_U^*} & \mathcal{Q}^\bullet(U \cap V) \\ \imath_U^* \uparrow & & \uparrow \partial_V^* \\ \mathcal{Q}^\bullet(M) & \xrightarrow{\imath_W^*} & \mathcal{Q}^\bullet(V) \end{array}$$

①

②

③

$$0 \xrightarrow{0} \mathcal{Q}^\bullet(M) \xrightarrow{(\imath_U^*, \imath_V^*)} \mathcal{Q}^\bullet(U) \oplus \mathcal{Q}^\bullet(V) \xrightarrow{\partial_V^* - \partial_U^*} \mathcal{Q}^\bullet(U \cap V) \xrightarrow{0} 0$$

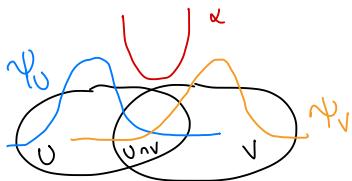
Note: 0. complex ( $d^2 = 0$ )

1.  $(\imath_U^*, \imath_V^*)$  is injective ( $\ker = \text{im}$  at ①) so we say the seq. is exact at ①

2.  $\ker(\partial_V^* - \partial_U^*) = \text{im}(\imath_U^*, \imath_V^*)$  b/c if they agree on  $U \cap V$  they glue to a form of  $U \cup V$ .  $\Rightarrow$  Exact at ②

3. Seq. is exact at ③ i.e.,  $\partial_V^* - \partial_U^*$  is surjective.

Not trivial to show  $\rightarrow$  if  $\alpha \in \mathcal{Q}^k(U \cap V)$  use P.O.U.



$$\alpha = \underbrace{\psi_U \alpha}_{\text{well-def. in } U} - \underbrace{(-\psi_V \alpha)}_{\text{well-def. in } V}$$

□

Def.: Such a 3-term exact sequence

$$0 \rightarrow (A^\bullet, d_A) \rightarrow (B^\bullet, d_B) \rightarrow (C^\bullet, d_C) \rightarrow 0$$

is called a short exact sequence of complexes.

Upshot: de Rham complexes of  $M$ ,  $U \cup V$ ,  $U \cap V$  are related by a short exact sequence.

Thm: Any short exact sequence  $0 \rightarrow A^\bullet \xrightarrow{f} B^\bullet \xrightarrow{g} C^\bullet \rightarrow 0$  induces a long exact sequence on  $H^*(A)$ ,  $H^*(B)$ ,  $H^*(C)$ :

Mayr-Vietoris

sequence

$$\begin{array}{ccccccc} & H^{k+1}(A) & \rightarrow & H^{k+1}(B) & \rightarrow & H^{k+1}(C) & \dots \\ \curvearrowleft & & & & & & \\ & H^k(A) & \xrightarrow{f_*} & H^k(B) & \xrightarrow{g_*} & H^k(C) & \dots \\ & & & & & & \delta \text{ connecting homomorphism} \\ & & & & & & \\ & & & & & & \dots \rightarrow H^{k-1}(C) \end{array}$$