

# SOLVING THE FERMAT-WEBER PROBLEM

## A NUMERICAL AND GEOMETRIC APPROACH

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# Abstract:

“Given three points in a plane, find a fourth point such that the sum of its distances to the three given points is as small as possible.” This historical problem from the 17th century was put by the

French mathematician Fermat to the Italian physicist Torricelli. A modern formulation of this problem could be: “To find a best location for a power plant between three cities in such a way that the sum of the connections between the power plant and the cities is minimal”. Torricelli

found several mathematical proofs, which can be nicely presented by GeoGebra. A generalization of the original problem leads to a geometric median – the problem of minimizing the sum of weighted distances.

Finding a geometric median is an optimization problem, which has no analytical solution for more than four points. We will present an interactive numerical solution with GeoGebra using the Weiszfeld algorithm and the programming language Python. Our GeoGebra Materials calculate the geometric median in real-time, this allows dynamic observations of the solution and the convergence behavior of the Weiszfeld algorithm.

# OUTLOOK

- Introduction
- Mathematical exploration with GeoGebra
- Theory around the Fermat-Weber Problem
- Implementation of the Weiszfeld algorithm

# FERMAT'S PROBLEM FOR TORRICELLI

*Given three points in a plane, find a fourth point such that the sum of its distances to the three given points is as small as possible.*

This historical problem was put by the French mathematician Fermat to the Italian physicist Torricelli.

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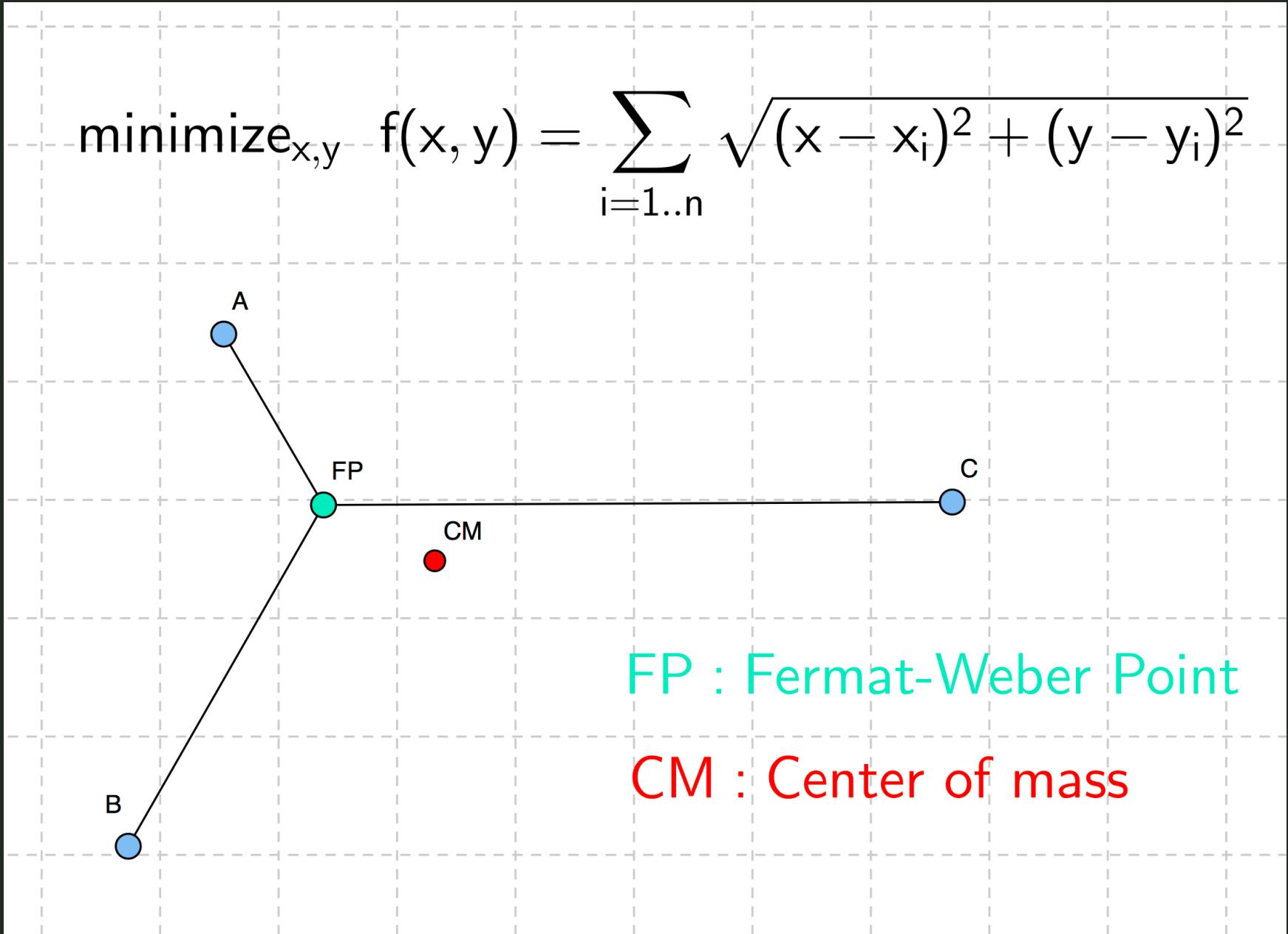
Dorrie, H. (1965). 100 Great problems of elementary mathematics. Dover Publications.

# SOME OF MANY NAMES

The long history and the interdisciplinary application have given several names to the problem and its variations: the Fermat problem, the generalized Fermat problem, the Fermat-Torricelli problem, the Steiner problem, the generalized Steiner problem, the Steiner-Weber problem, the Weber problem, the generalized Weber problem, the Fermat-Weber problem, the one median problem, the median center problem, the spatial median problem, the bivariate median problem, the minimum aggregate travel point problem

# MINIMIZE THE SUM OF DISTANCES

$$\text{minimize}_{x,y} \quad f(x, y) = \sum_{i=1..n} \sqrt{(x - x_i)^2 + (y - y_i)^2}$$

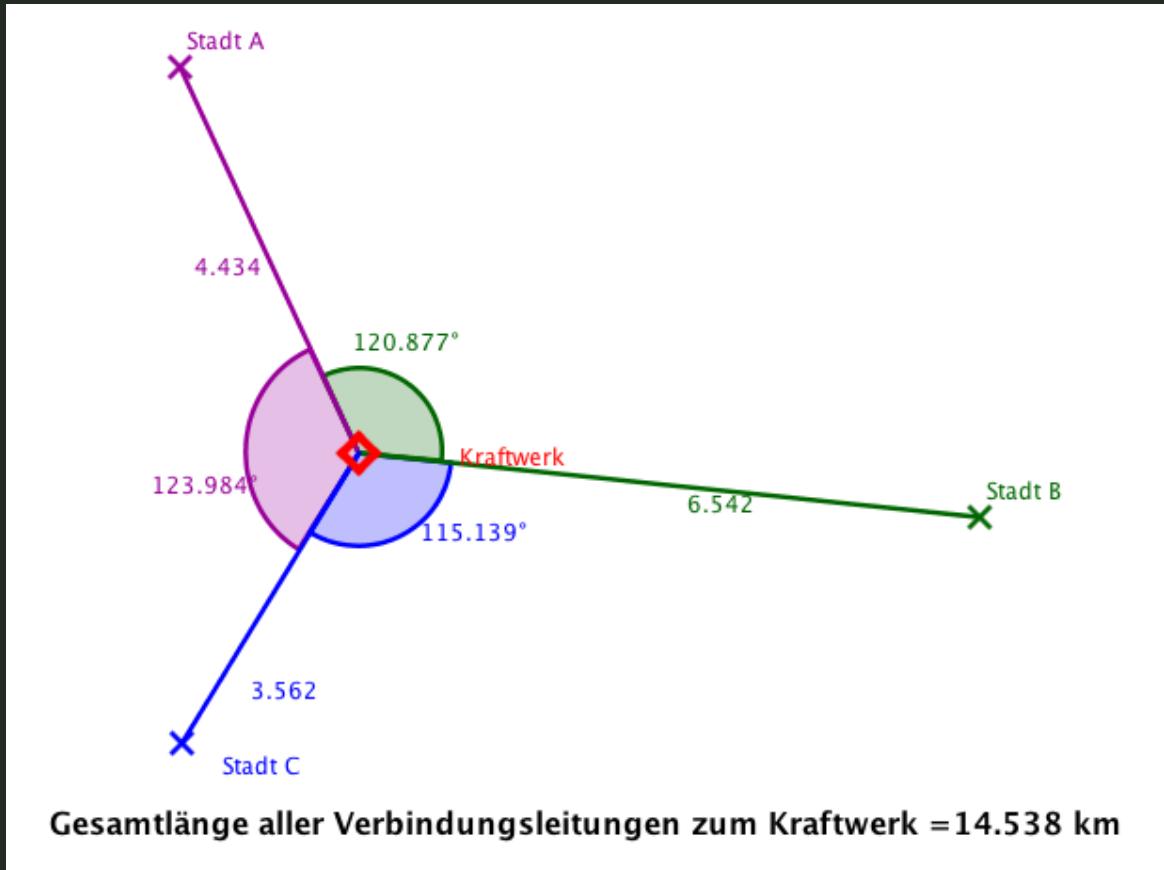


# MODERN FORMULATION

The Weber problem finds the point in a plane which minimises the sum of weighted Euclidean distances to a set of fixed points.

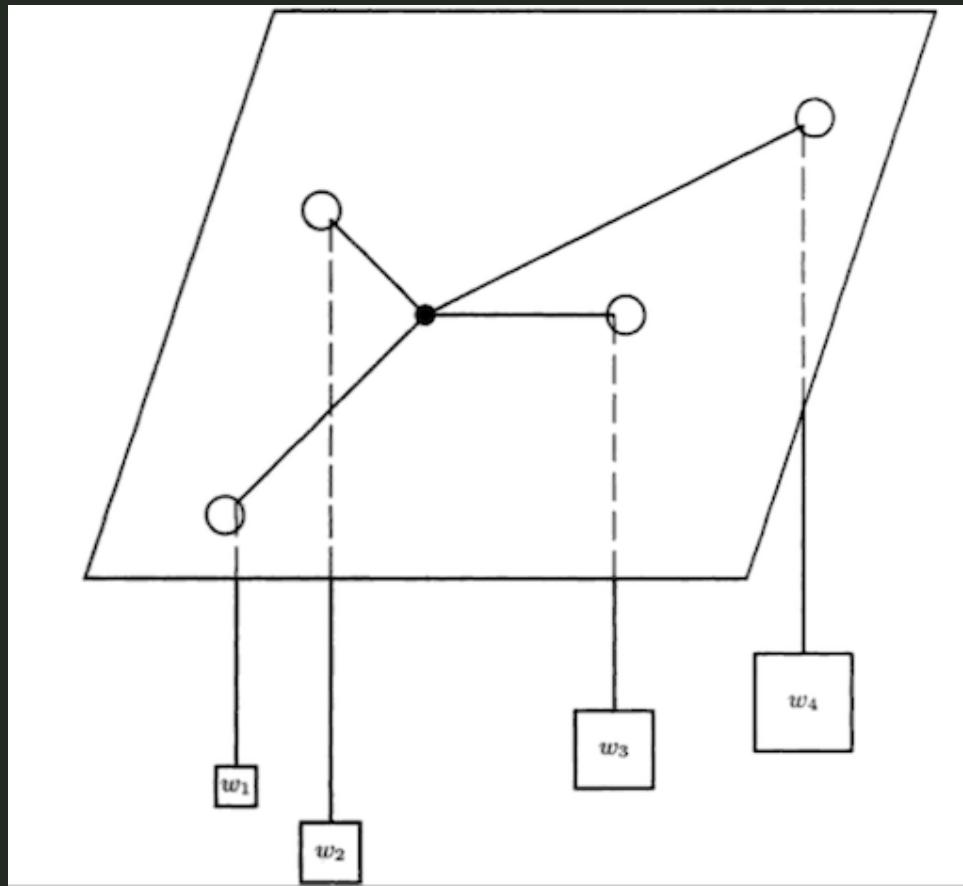
This is interpreted as finding the factory location which minimises the total weighted distances from suppliers and customers, where weights represent relative volumes of interactions, e.g. weight of material to be transported from a supplier, or volume of finished products for a customer.

# MODERN FORMULATION



[Link to GeoGebra Material](#)

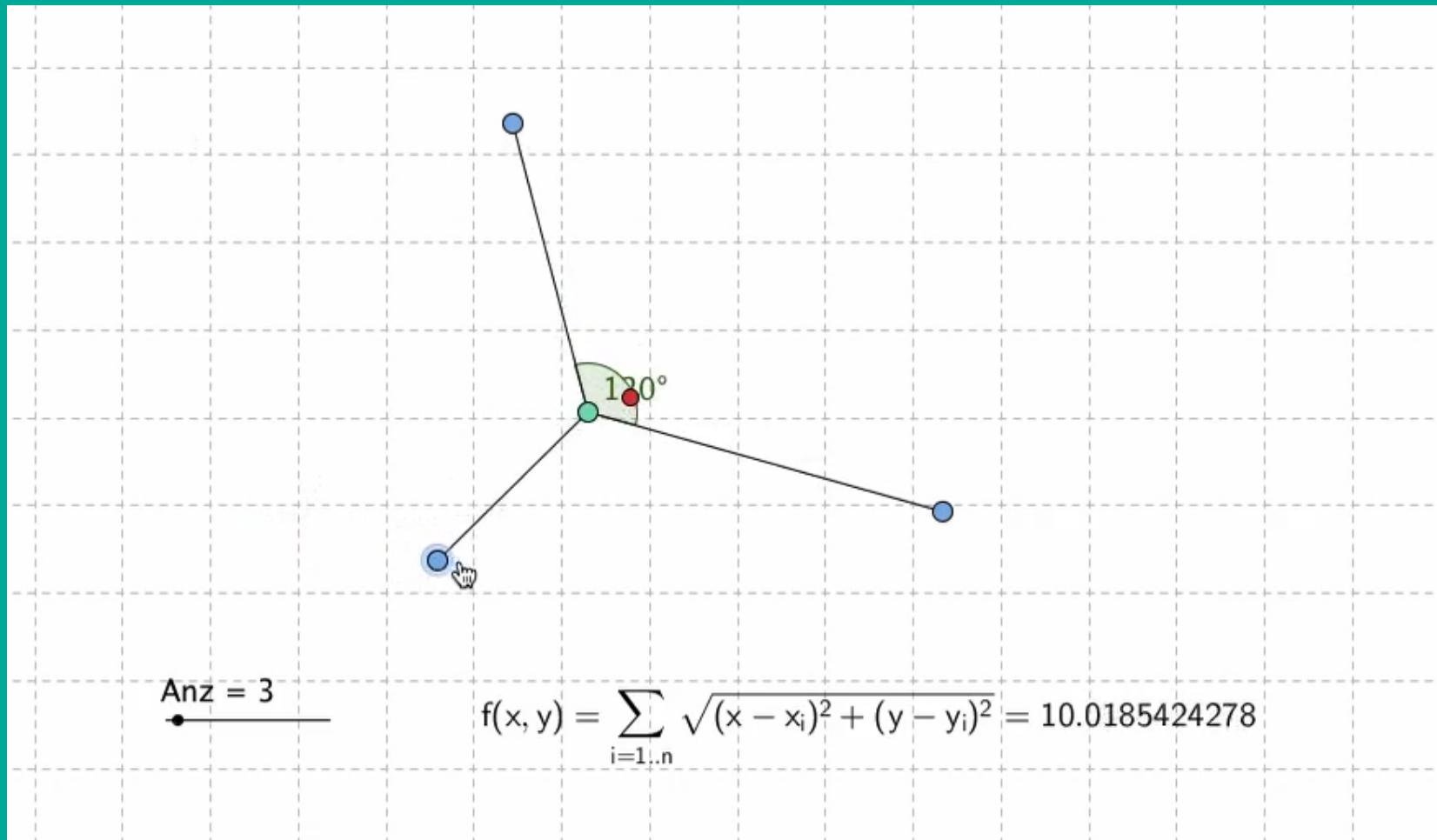
# VARIGNON FRAME



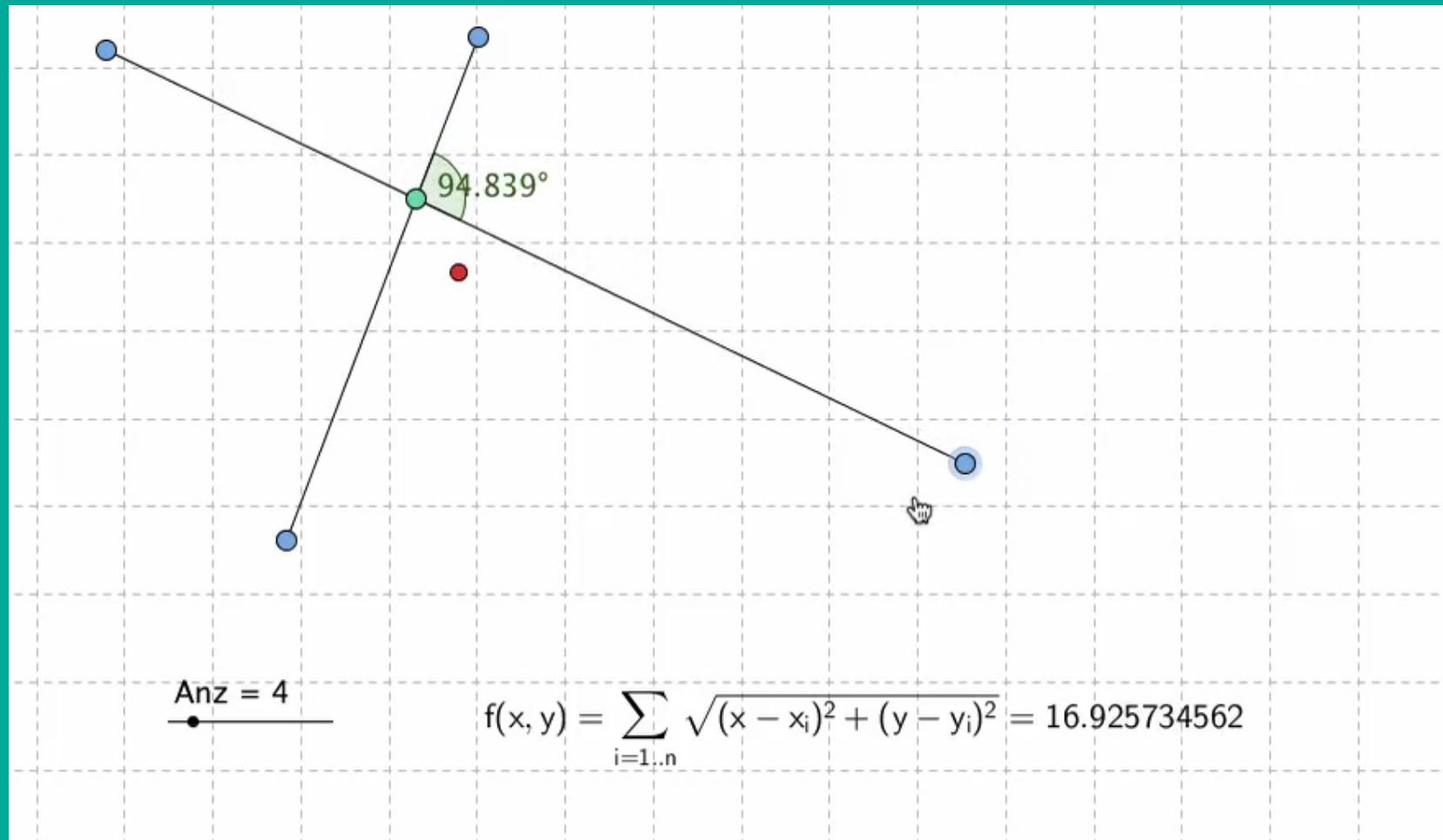
Varignon proposed a mechanical analogue device which has actually been used in practice

# MATHEMATICAL EXPLORATION

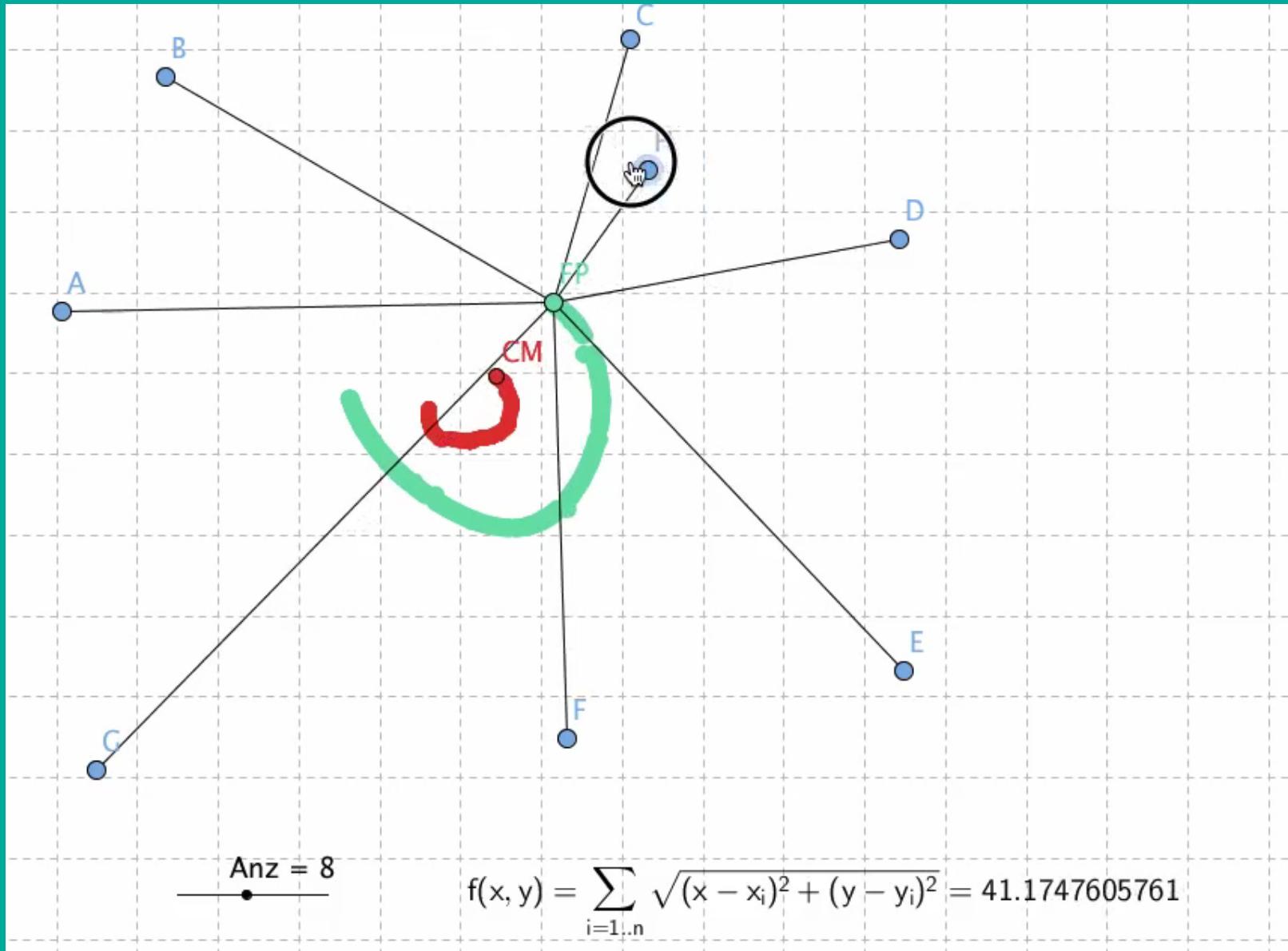
# FOR N=3 THE ANGLE 120° CAN BE OBSERVED



# NO ANGLE DEPENDENCY FOR MORE THAN 3 POINTS

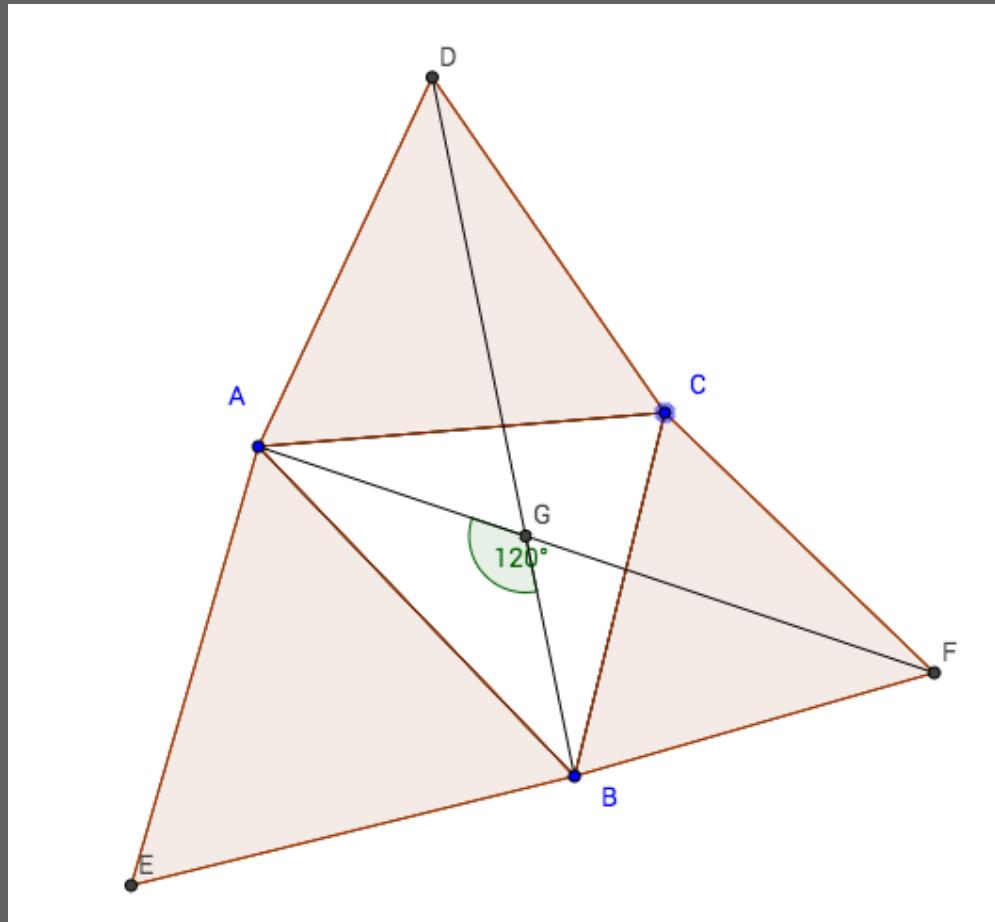


# FERMAT POINT SNAP TO INTERNAL POINT



# THEORY AROUND THE FERMAT-WEBER PROBLEM

# GEOMETRIC SOLUTION FOR 3 LOCATION

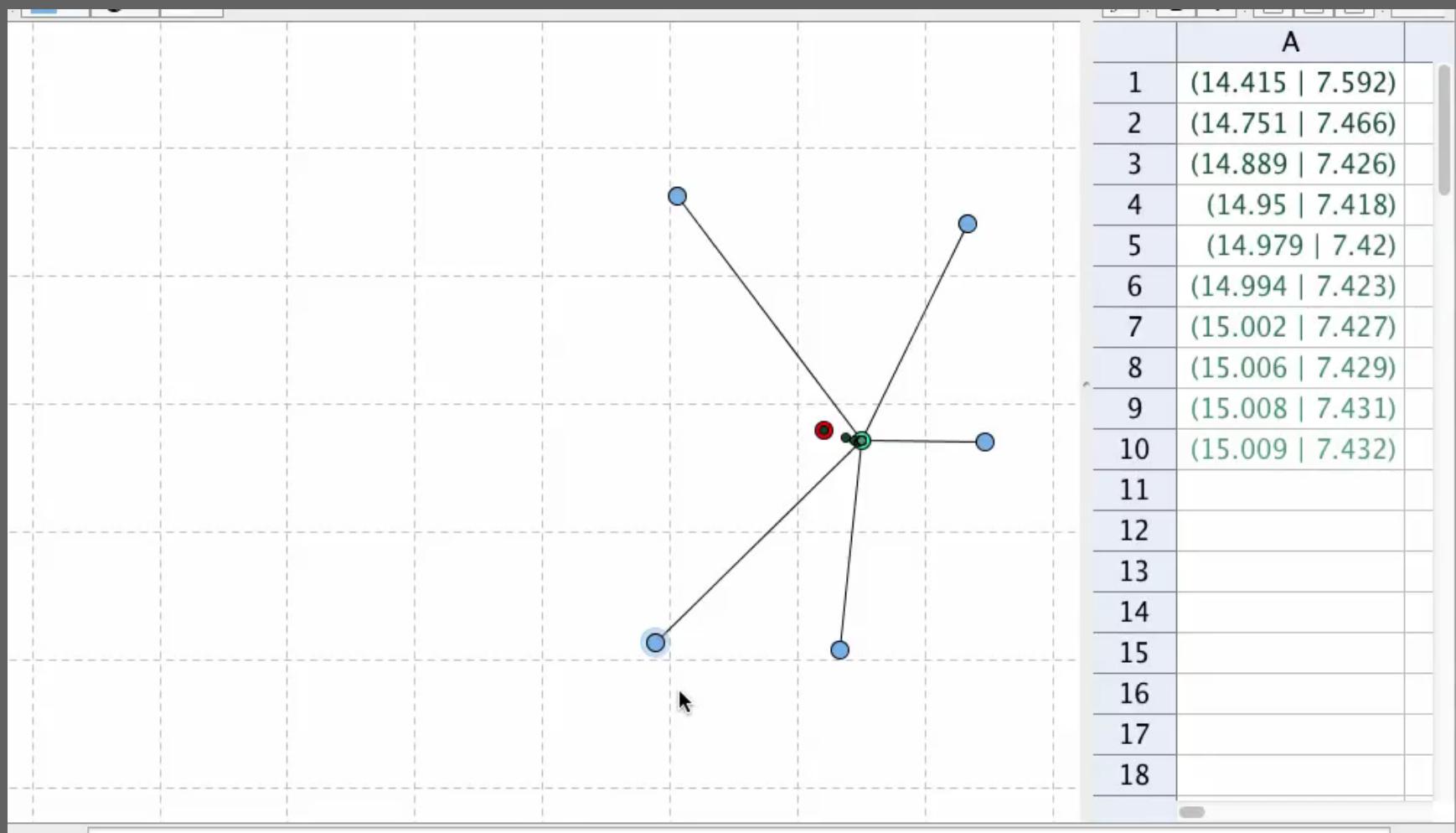


[Link to Geogebra Material](#)

# WEISZFELD ALGORITHM

by Endre Weiszfeld, alias Andrew Vázsonyi (1916–2003), born in Budapest

# CONVERGENCE OF THE WEISZFELD ALGORITHM



# ALGORITHM

IMPLEMENTATION WITH THE  
PROGRAMMING LANGUAGE PYTHON

# PROGRAMMING WITH PYTHON IN GEOGEBRA (BETA)

The screenshot shows a Geogebra interface with a coordinate system. A set of points labeled A, B, C, D, E, and F are plotted. Point BP is the blue point representing the geometric median. Point CM is a red dot representing the centroid. A slider labeled "Anz = 6" is shown, and a formula  $f(x, y) = \sum_{i=1..n} \sqrt{(x - x_i)^2 + (y - y_i)^2} = 12.9689839271$  is displayed.

```
46 $Länge=sum(segs)
47
48
49 def distance(self,A, B):
50     return sqrt((A[0]-B[0])**2+(A[1]-B[1])**2).value
51
52 def schwerpunkt(self):
53     x0=y0=0
54     n = len(self.mypoints)
55     for P in self.mypoints:
56         x0=x0+P.x.value
57         y0=y0+P.y.value
58     return (x0/n,y0/n)
59
60 def drawSchwerPunkt(self):
61     tmp = self.schwerpunkt()
62     $CM.x=tmp[0]
63     $CM.y=tmp[1]
64
65 def median_approx(self,P, points):
66     """
67     Return a new approximation to the geometric median of 'points' by
68     applying one iteration of Weiszfeld's algorithm to the old
69     appromixation P.
70     """
71     W = x = y = 0.0
72     for Q in points:
73         d = self.distance(P, Q)
74         if d != 0:
75             w = 1.0 / d
76             W += w
77             x += Q[0] * w
78             y += Q[1] * w
79     return x / W, y / W
80
```

[Download Material \(Geogebra 5 Beta\)](#)

# WEISZFELD CLASS

```
class Weiszfeld(object):
    mypoints = None
    text1 = None
    def __init__(self):
        ...
    def drawPoints(self):
        ...
    def distance(self,A, B):
        ...
    def schwerpunkt(self):
        ...
    def median_approx(self,P, points):
        ...
    def geometric_median(self,points, epsilon):
        ...
    def update(self):
        ...
```

# DRAW RANDOM POINTS

## SET EVENTLISTENER

```
class Weiszfeld(object):  
    def drawPoints(self):  
        N = int($Anz.value)  
        xcoords = [random.uniform(3, 17) for i in range(N)]  
        ycoords = [random.uniform(3, 10) for i in range(N)]  
        self.mypoints = [Point(x, y, point_size=6, \  
                               color=Color(118,175,236), label_visible=True) \  
                         for x, y in zip(xcoords, ycoords)]  
        ...  
        for p in Point.all:  
            p.onupdate=refresh  
        ...  
    ...
```

```
def init(self):  
    alg.drawPoints()  
    alg.drawSchwerPunkt()  
    alg.drawFermatPunkt()
```

# GLOBAL FUNCTION

```
# UPDATE CM AND FP
def refresh(self):
    alg.drawSchwerPunkt()
    alg.drawFermatPunkt()
```

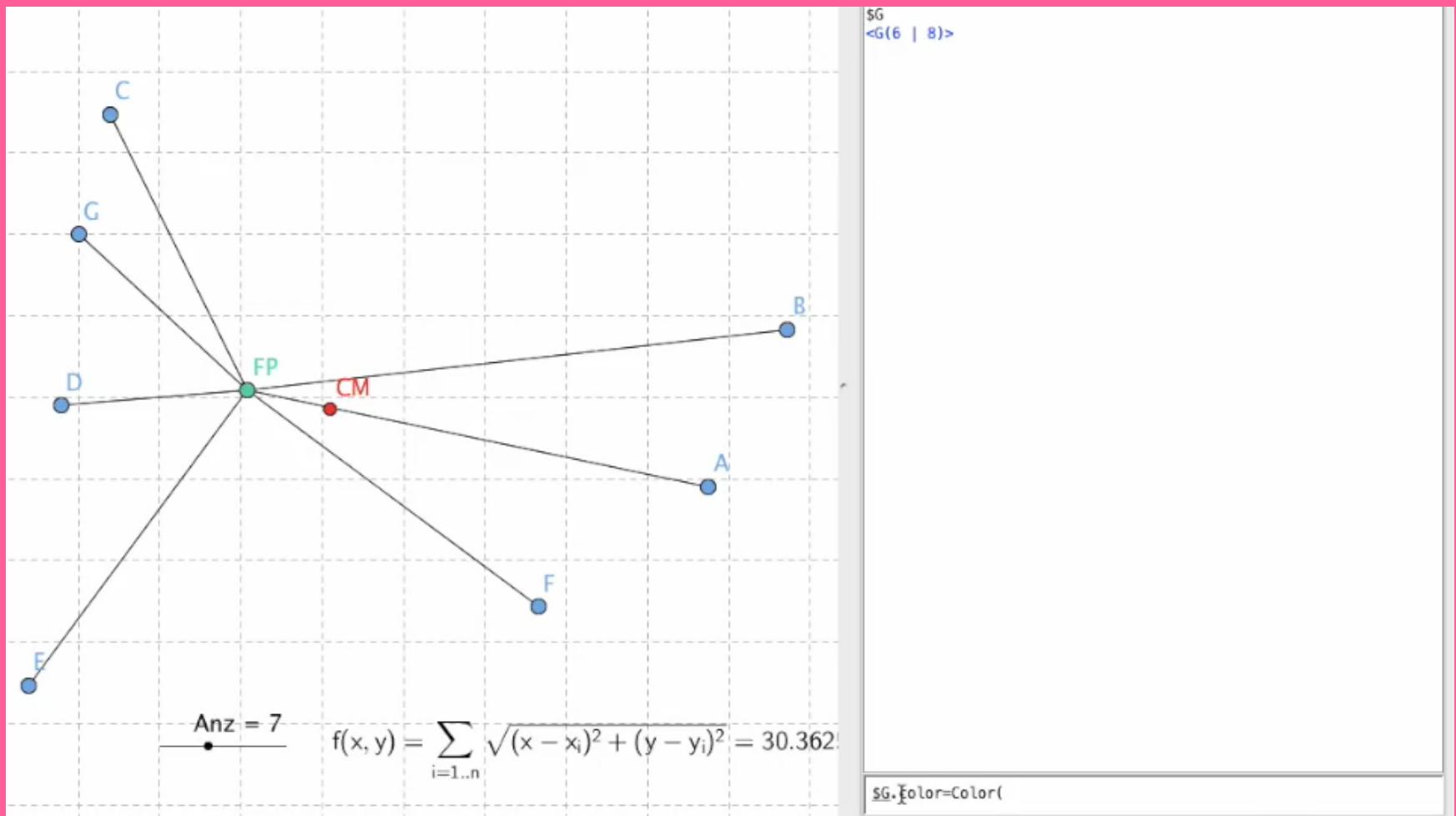
# GLOBAL INITIALIZATION

```
# GLOBAL VAR
global alg
alg = Weiszfeld()
alg.drawPoints()
alg.update()
$Anz.onupdate=init
```

# CALCULATE NEXT INTERATION POSITION OF FP

```
def median_approx(self, P, points):
    """
    Return a new approximation to the geometric median
    of `points` by applying one iteration of Weiszfeld's
    algorithm to the old appromixation P.
    """
    W = x = y = 0.0
    for Q in points:
        d = self.distance(P, Q)
        if d != 0:
            w = 1.0 / d
            W += w
            x += Q[0] * w
            y += Q[1] * w
    return x / W, y / W
```

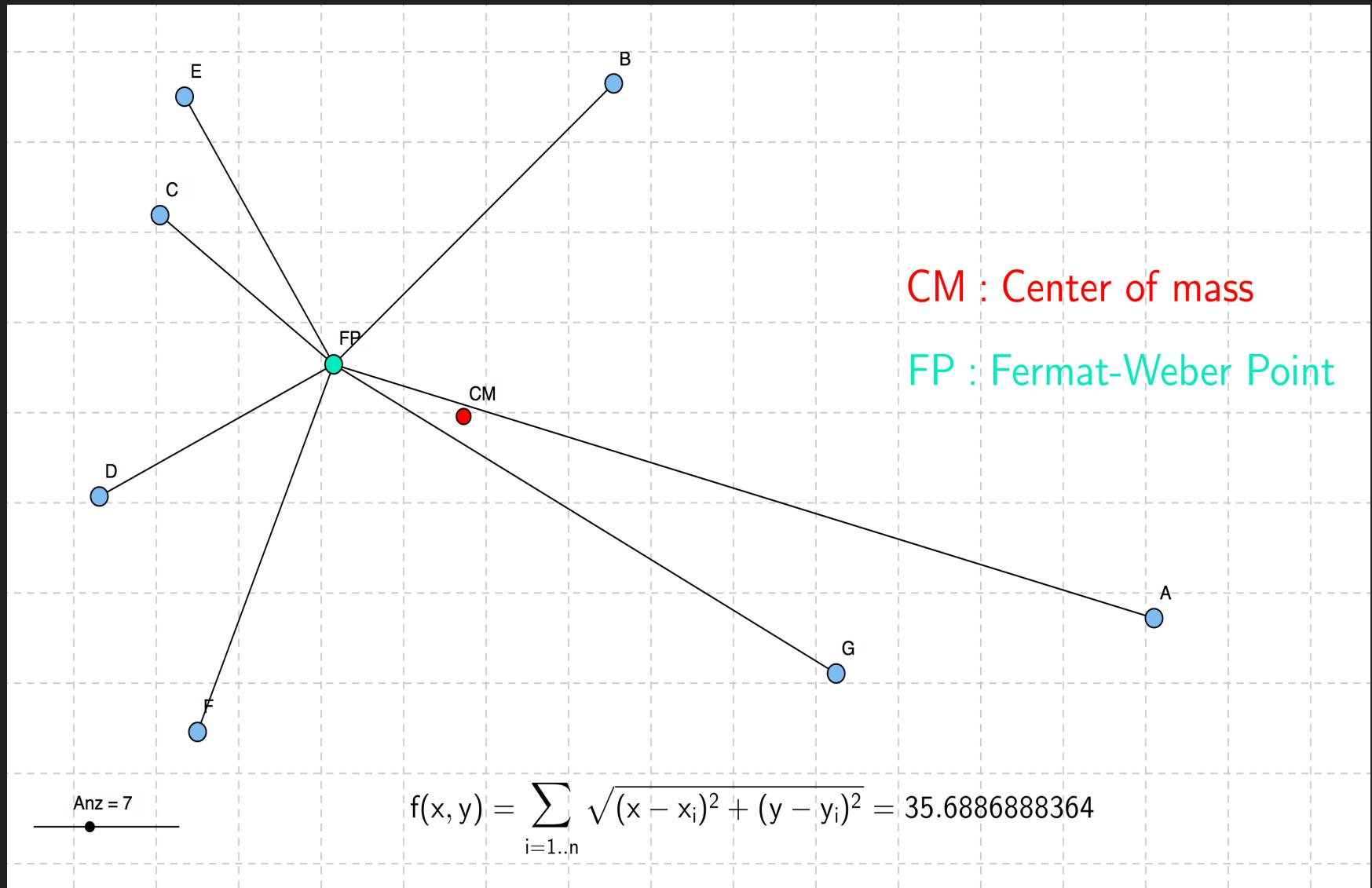
# INTERACTIVE PYTHON



# CONCLUSION

# INTERACTIVE DEMO (JAVASCRIPT)

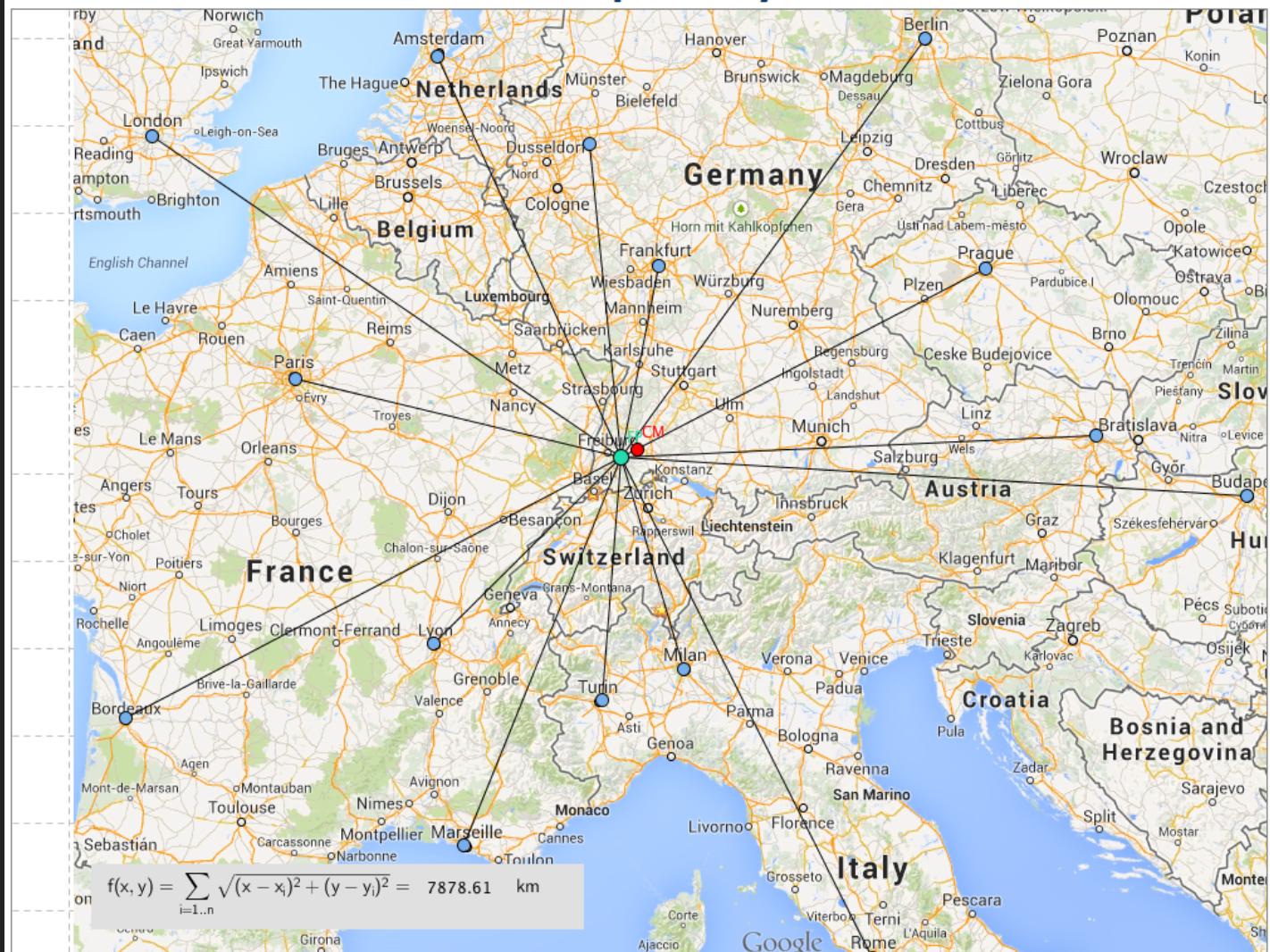
GeoGebra Materials : <http://www.geogebraTube.org/material/show/id/66049>



# DEMO 2

GeoGebra Materials : <http://www.geogebraTube.org/student/m66688>

## Fermat Weber Point of European Cities



# SUMMARY

- We presented the historical fermat-weber problem
- The use of GeoGebra to solve this problem
- A python implementation of the Weiszfeld algorithm

This presentation and all interactive material are published on github.

<http://mgie.github.io/presentations/>

# USING JAVASCRIPT

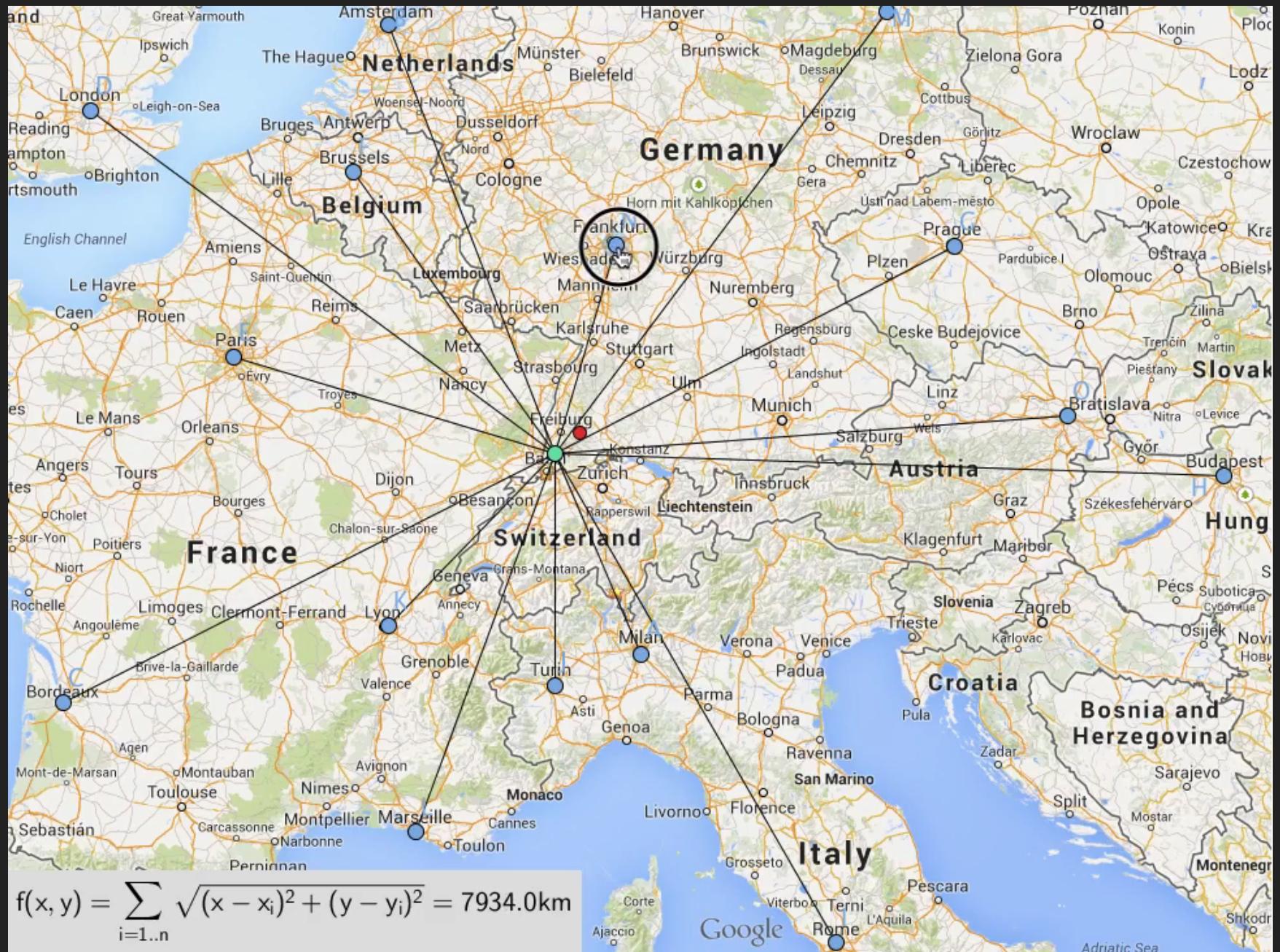
Demo Runs on the web an standard Geogebra4.4

THANKS FOR YOUR ATTENTION

# FINDING THE FERMAT-WEBER POINT FOR

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AMSTERDAM, BERLIN, BORDEAUX,  
BRUSSELS, BUDAPEST, FRANKFURT,  
LONDON, LYON, MARSEILLE, MILAN,  
PARIS, PRAGUE, ROME, TURIN AND  
VIENNA



THE END

QUESTIONS ?

THANKS TO HAKIM EL HATTAB / HAKIM.SE  
FOR REVEAL.JS